



Project Seminar on Energy-Aware Computing in Heterogeneous Data Centers

Introduction: Motivation, Organization, Hardware, Project Topics

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Operating Systems and Middleware Group

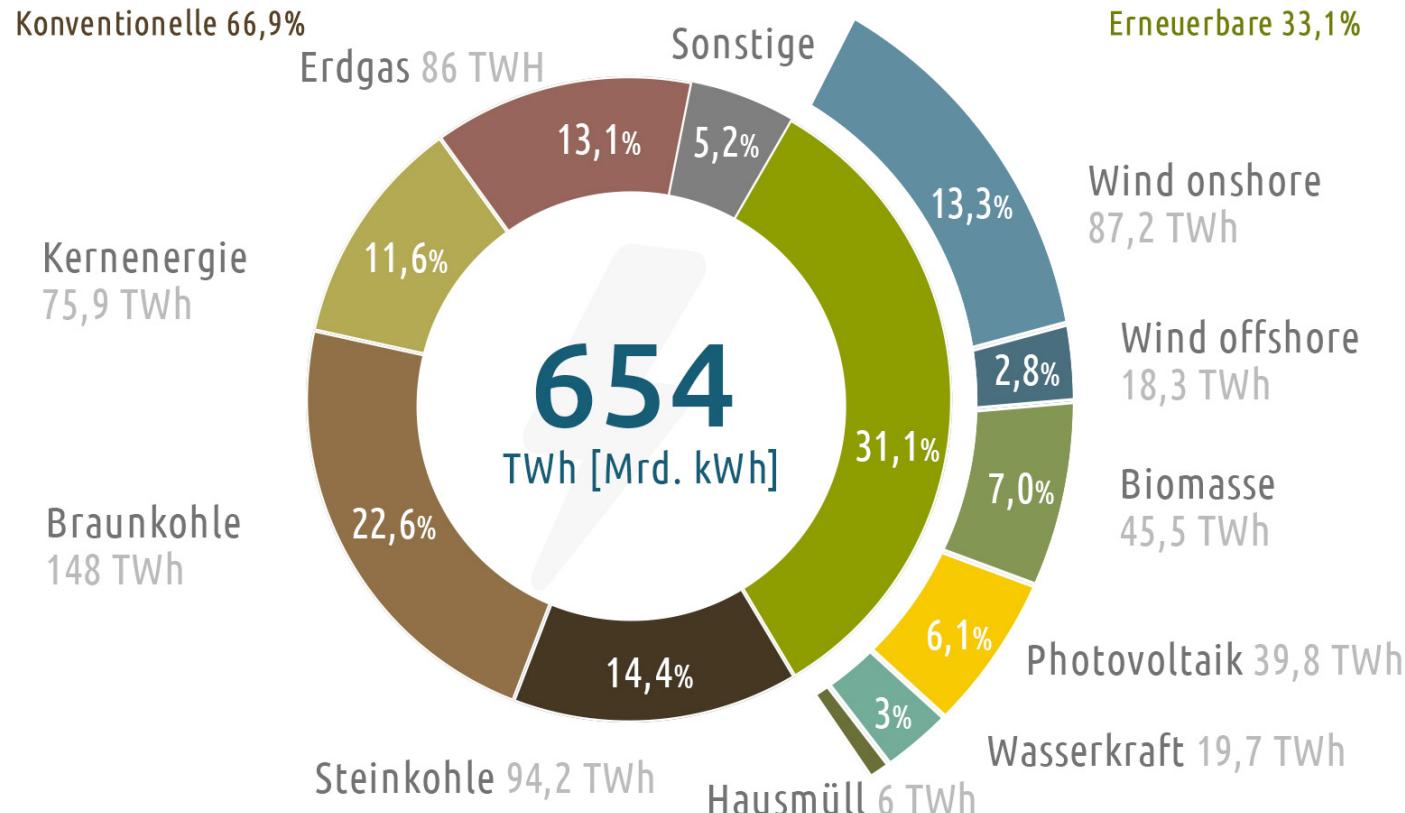
1 Motivation

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Chart 2

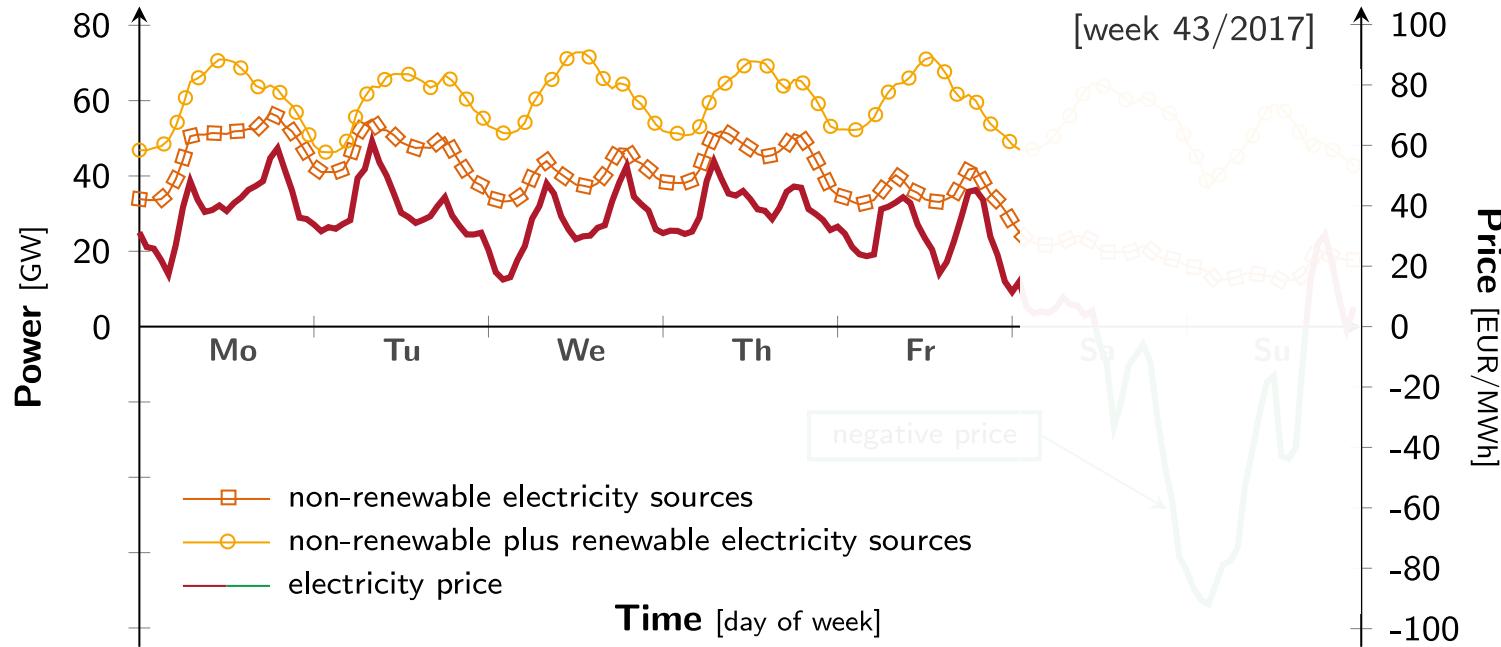
DER STROMMIX IN DEUTSCHLAND 2017 [BRUTTO]

Anteil der Energieträger an der Bruttostromerzeugung in Deutschland



1. Motivation

Energy Price Over Time



Fluctuating energy supply leads to
highly variable energy prices

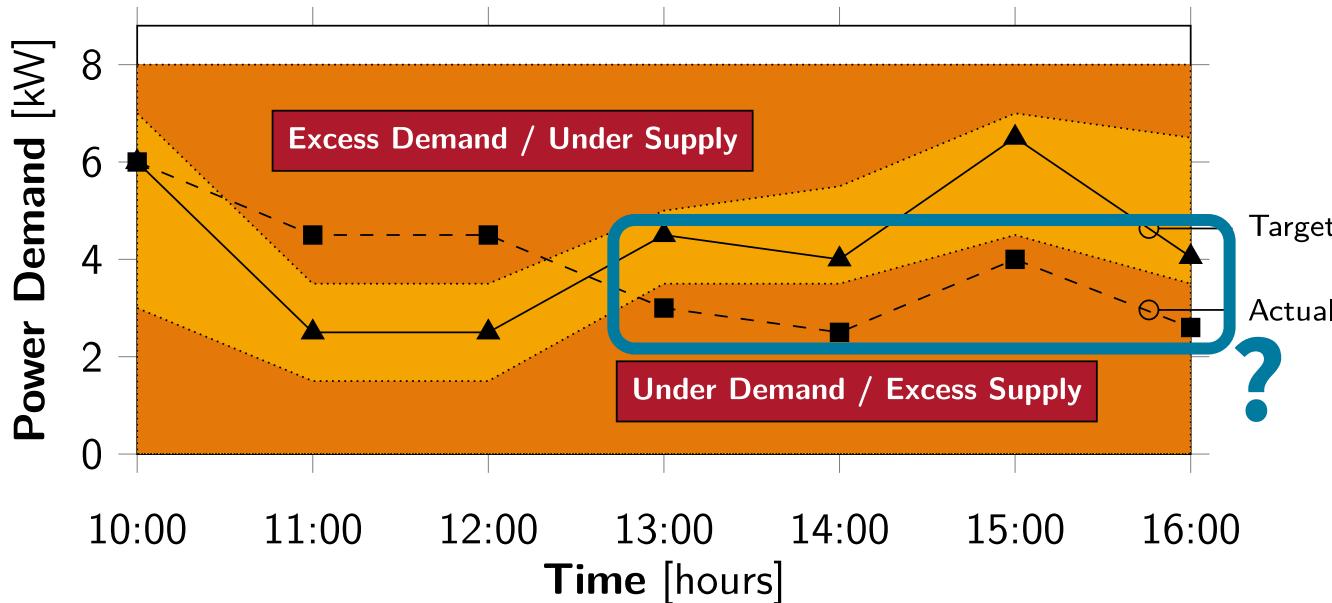
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Chart 4

1. Motivation

Energy Management in Data Center Operation



Variable power-target and penalty zones must be considered in computing laboratory operation

1. Motivation

Energy Management in Data Center Operation

How to control power consumption of computing lab operation?

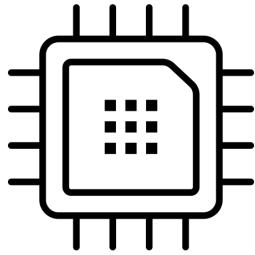
- 1. Work another time:** Defer/pick jobs with matching energy profile
(popular research in embedded systems,
requires known and deferrable jobs)
- 2. Work less/more:** Use additional hardware components
(commonly used to scale depending
on operation requirements)
- 3. Work elsewhere:** Use other hardware components

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This project seminar

1. Motivation

Different Hardware Classes



CPU

Intel

AMD

Power

ARM

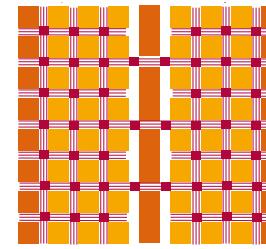


GPU

AMD

NVIDIA

Mali



FPGA

Zynq SOC

Xilinx via CAPI

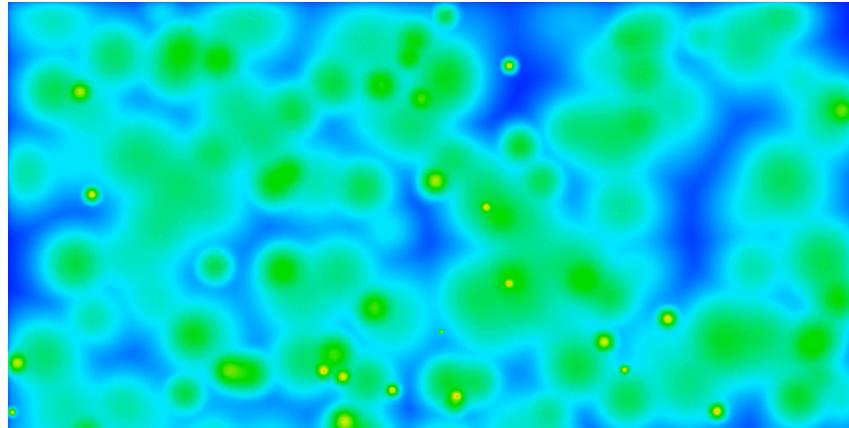
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Chart 7

1. Motivation

Recap: Parallel Programming Assignments ST 2019



Device	Problem Size (MCells)	Cell Type	Throughput (MCells/s)	Power Consumption (W)	Power Efficiency (MCells/Ws)
NVidia Tesla K20Xm	256	float (32bit)	1127,88	60	18,80
Intel E5-2630 v4	256	float (32bit)	1435,48	85	16,89
Intel E5-2630 v4	256	char (8bit)	1420,29	85	16,71
Xilinx XCKU060	1024	char (8bit)	2209,35	9,5	232,56

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Chart 8

1. Motivation

Goal of This Project Seminar

In this project seminar we want you to learn:

1. How to target different hardware platforms
2. How to assess the current power consumption of your algorithm
3. Finding the preferred hardware platform for your given algorithm class

Organization

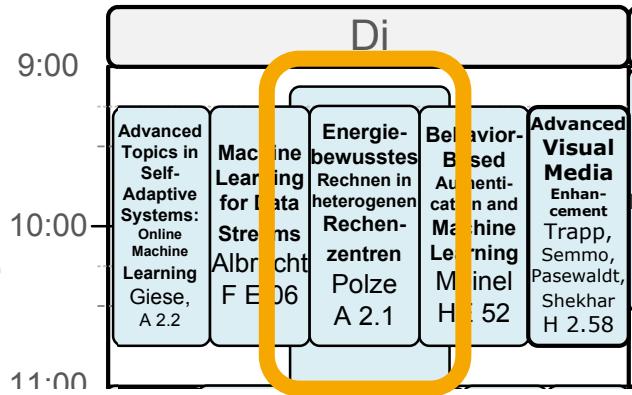
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Chart 10

2. Organization Time Slots

- **Project Seminar** (= *Not a lecture*)
- **6 ECTS** credits (4 SWS)
- **Each Tuesday** (start of the semester):
 - Announcements
 - Heterogeneous Programming Course
 - Profiling Course
 - Exchange with fellow students
- No regular Tuesday meetings later in the semester.
Use the time to work on your projects :)



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2. Organization Your project focus

Each team (1-3 persons) can choose to focus on:

mastering 2+ hardware platforms in depth

or

optimizing 2+ algorithm classes on multiple platforms

or

developing new profiling tools

speak to your project mentor

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2. Organization

Mentoring Team (PhD Students)



- Max Plauth
 - GPU Accelerators
 - Virtualization of Accelerators
 - Bandwidth Compression



- Felix Eberhardt
 - NUMA Topologies
 - Dynamic Scaling
 - Profiling



- Sven Köhler
 - On-Core Accelerators
 - Programming Models for Accelerators
 - Hardware Performance Counters



- Lukas Wenzel
 - FPGA Accelerators
 - Near-Storage Computing
 - FPGA-OS integration

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Chart 13

Requirements for each team to successfully pass this course:

- Meet regularly with your project mentor
 - 10 minute presentation in November
 - 30 minute presentation at end of semester
 - 5-10 pages technical report
-
- **Grading:** 50 % project, 50 % presentations and report

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3 Potential Hardware Targets

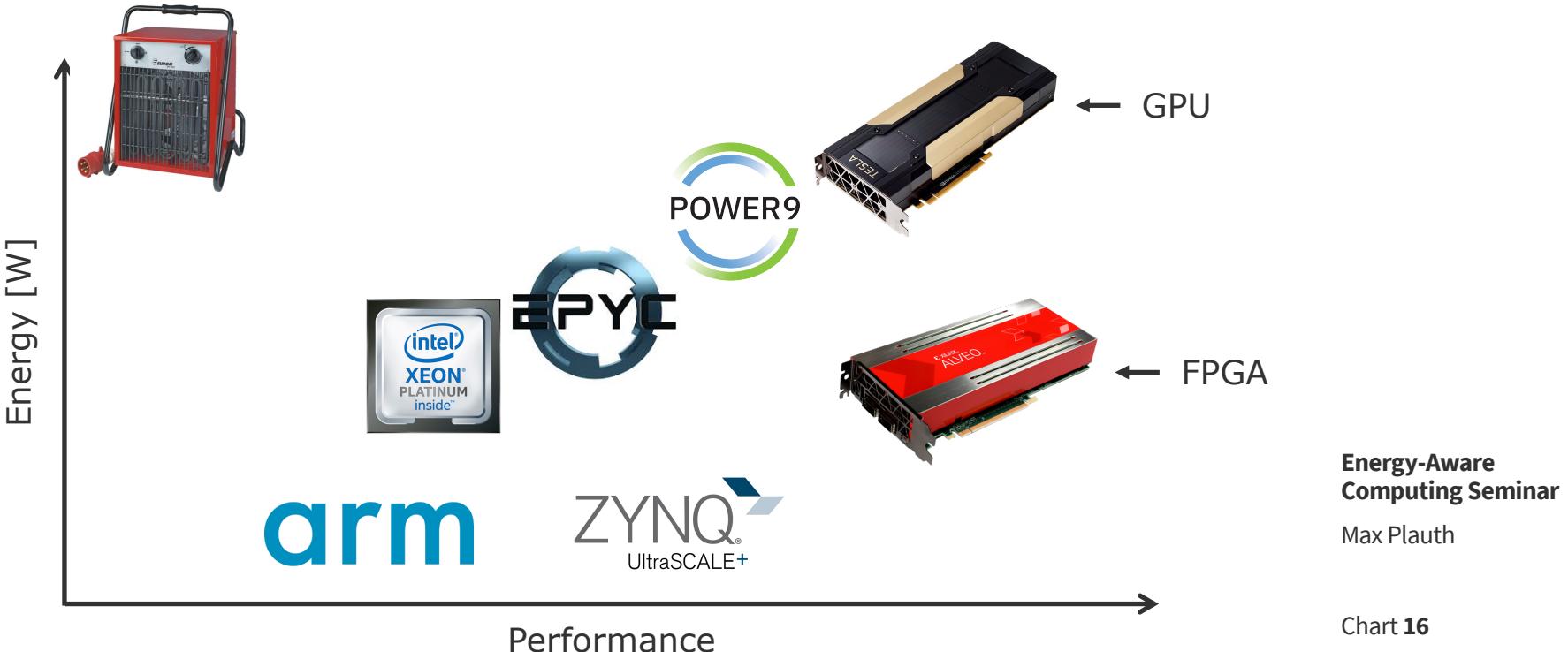
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Chart 15

3. Potential Hardware Targets

Energy vs. Performance



3. Potential Hardware Targets

Low-Power Systems

■ Odroid N2

- 4x ARM A73 / 2x ARM A53 CPUs
 - ISA: aarch64
- 1x Mali-G52 GPU
- ~6.5 Watt under load



■ Ultra96

- 4x ARM Cortex-A53 CPU
 - ISA: aarch64
- 1x Xilinx UltraScale+ FPGA
- ~5.5 Watt under load



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3. Potential Hardware Targets

Mid-Power Systems

- HPE m710p Moonshot Cartridge (up to 10 machines available)
 - Intel Xeon E3-1284Lv4
(4 Cores / 8 Threads)
 - ISA: x86_64
 - 1x Iris Pro P6300 GPU
 - RoCE-enabled NIC
 - ~30 Watt under load



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3. Potential Hardware Targets: High-Power Systems (CPU-only)

- HPE ProLiant DL580 Gen9
 - 4x Intel Xeon E3-1284Lv4
(18 Cores / 36 Threads)
 - >1kW Watt under load



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3. Potential Hardware Targets

High-Power Systems (with Accelerators)

■ HPE ProLiant DL380 Gen9

- 2x Intel Xeon E5-2630v4 (10C/20T)
 - ISA: x86_64
- 2x NVIDIA Tesla K20Xm GPU
- >1kW under load



■ IBM Power System S824L

- 2x IBM POWER8 (10C/80T)
 - ISA: ppc64le
- 1x NVIDIA Tesla K80 GPU
- 1x Nallatech 250S FPGA
- >1kW under load



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3. Potential Hardware Targets

High-Power Systems („Accelerator-only“)

- NVIDIA DGX-1
 - 2x Intel Xeon E5-2698v4 (20C/40T)
 - ISA: x86_64
 - 8x NVIDIA Tesla V100 GPU
 - ~3.5 kW under load



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Potential Algorithms

The Landscape of Parallel Computing Research: A View from Berkeley



*Krste Asanovic
Ras Bodik
Bryan Christopher Catanzaro
Joseph James Gebis
Parry Husbands
Kurt Keutzer
David A. Patterson
William Lester Plishker
John Shalf
Samuel Webb Williams
Katherine A. Yelick*

Electrical Engineering and Computer Sciences
University of California at Berkeley

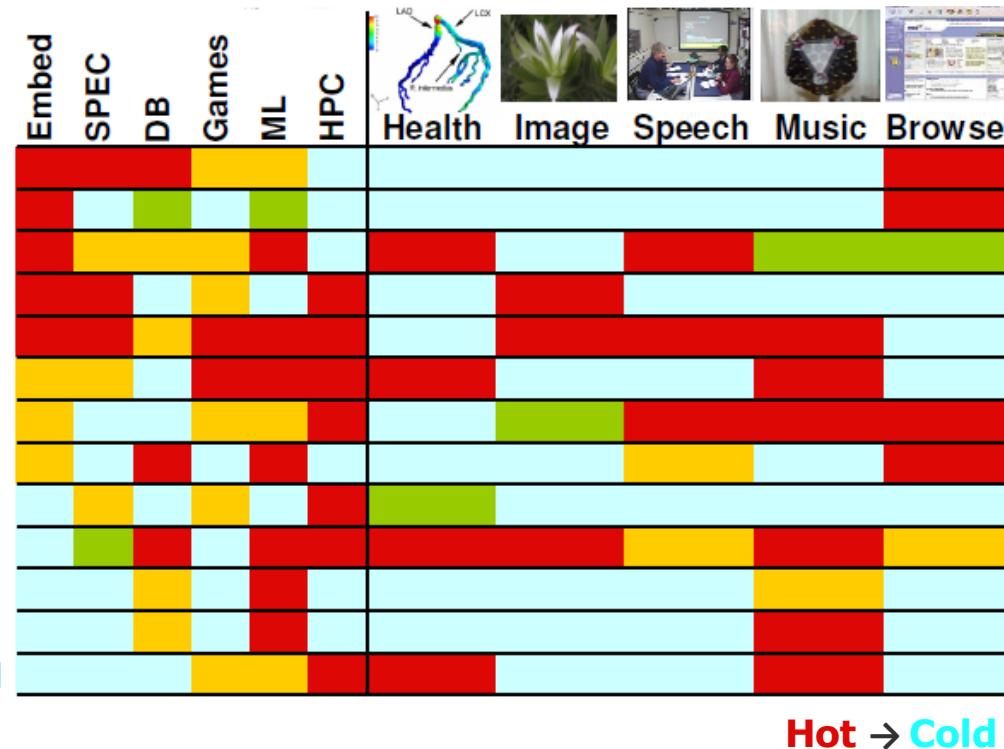
Technical Report No. UCB/EECS-2006-183
<http://www.eecs.berkeley.edu/Pubs/TechRpts/2006/EECS-2006-183.html>

December 18, 2006

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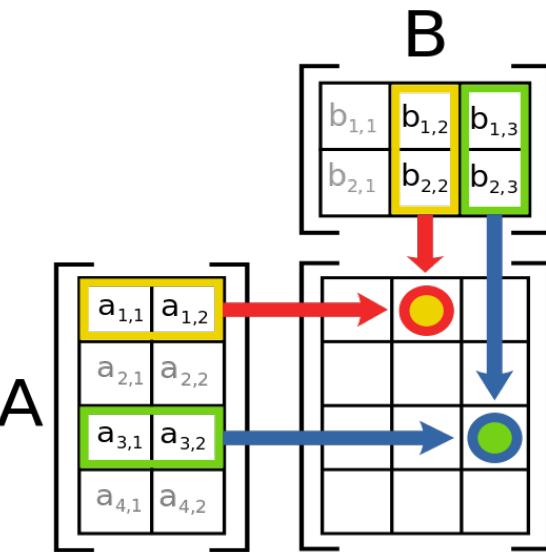
Chart 22



* added later

4. Potential Algorithms

Dwarf 1: Dense Linear Algebra



Classic vector and matrix operations

```
do i=1,n  
  do j=1,n  
    do k=1,n  
      a(i,j) = a(i,j) + b(i,k)*c(k,j)
```

Frequent operation in computer graphics
and as training step in machine learning

$$C = AxB$$

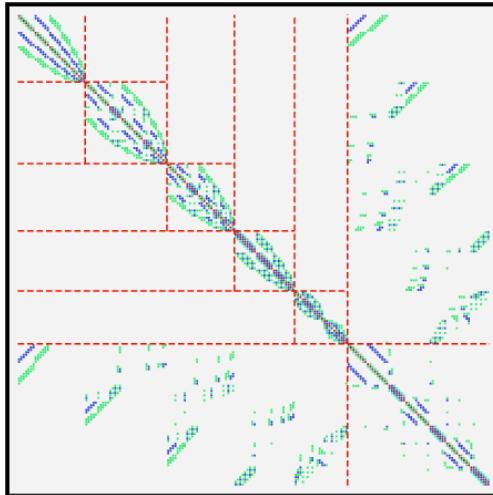
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Chart 24

4. Potential Algorithms

Dwarf 2: Sparse Linear Algebra



Operations on a sparse matrix (lots of zeros)

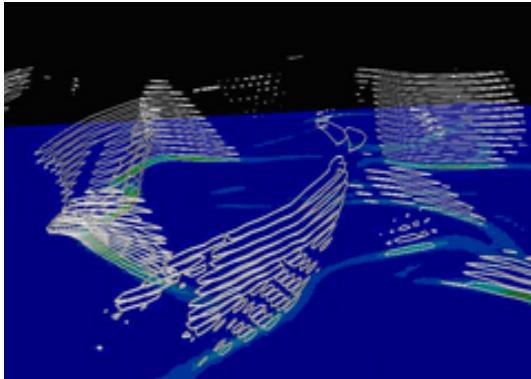
```
do i=1,n
    do j=row_start(i),row_start(i+1)-1
        y(i) = y(i) + val(j)*x(col_index(j))
```

Complex data-dependency structure
Common in e.g. in graph problems.

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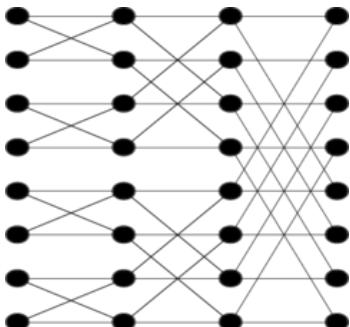
4. Potential Algorithms

Dwarf 3: Spectral Methods



Data is converted into other domains, which means multiple stages with inter-dependent data access patterns.

Common ML data preparation step, or used in signal processing.

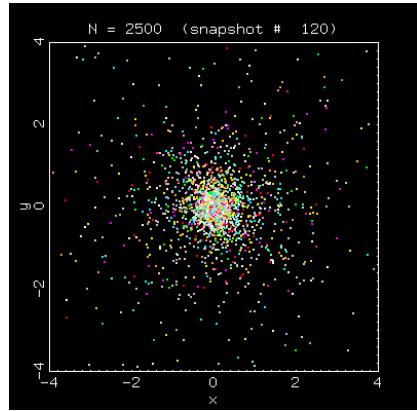


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Chart 26

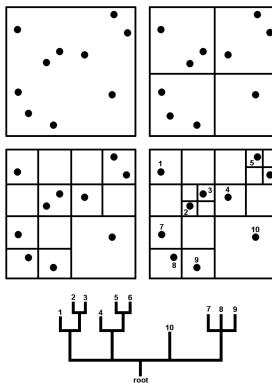
4. Potential Algorithms

Dwarf 4: N-Body Methods



Calculations on interactions between
Many discrete points.

Large number of independent calculations
in a time step, followed by wide communication.

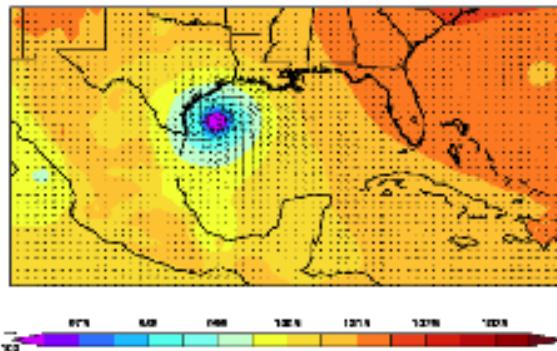


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Chart 27

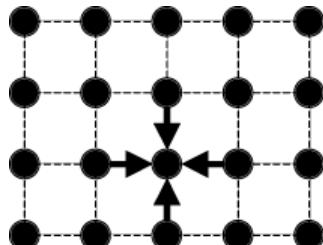
4. Potential Algorithms

Dwarf 5: Structured Grid



Data as a regular multidimensional grid:
access is regular and statically
determinable (strided).

Computation is sequence of grid updates
(all points are updated using values from a
small neighborhood).



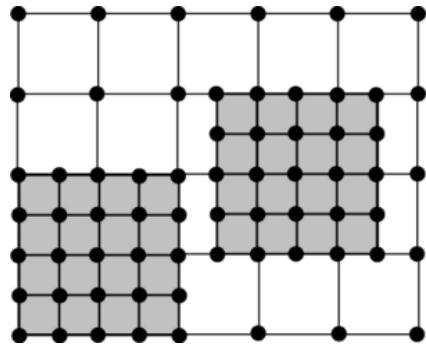
Typical Application: Weather simulations

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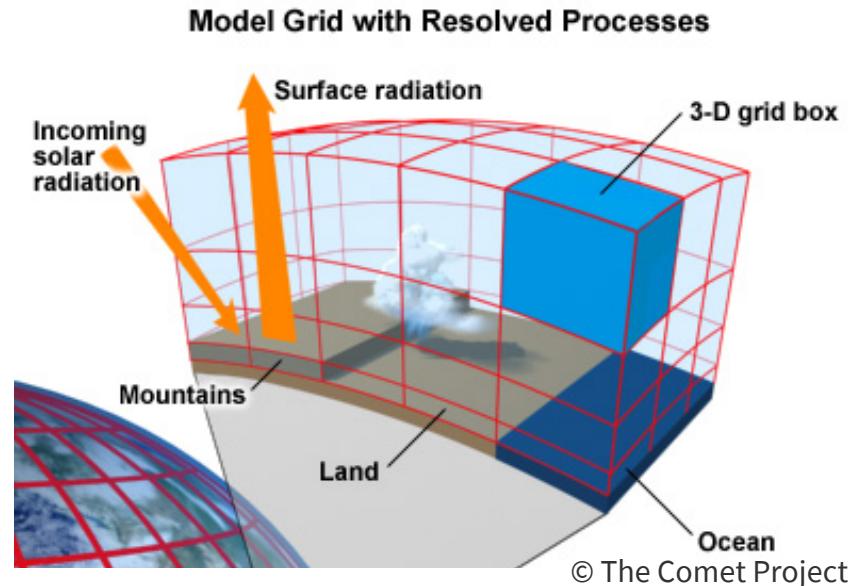
Mandatory warm-up for all teams

4. Potential Algorithms

Dwarf 5 Variant: Adaptive Mesh Refinement



Overlaying higher-resolution grids across areas of interest. Requires complex indexing and difficult communication across nodes.



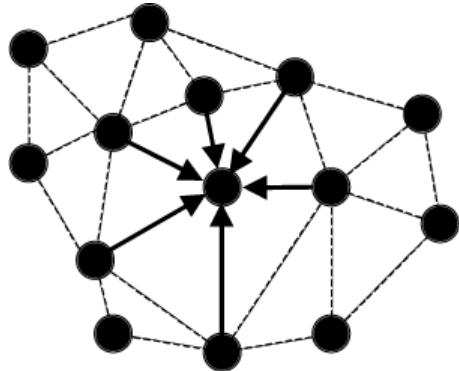
Example:
Modular Ocean Model

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4. Potential Algorithms

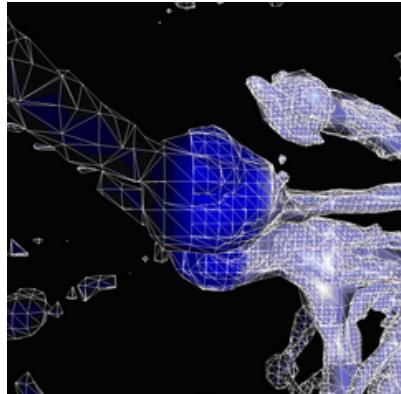
Dwarf 6: Unstructured Grid



Elements update neighbors in irregular mesh/grid with static or dynamic structure

Problematic data distribution and access requirements, usually indirection by tables.

$$A'[B[C[i]]] = f(A[B[C[i + 1]]] + A[B[C[i + 2]]] + A[B[C[i + 3]]])$$



Modelling domain (e.g. physics engine)

- Mesh represents surface or volume
- Entities are points, edges, faces, volumes, ...
- Applying tension, temperature, pressure

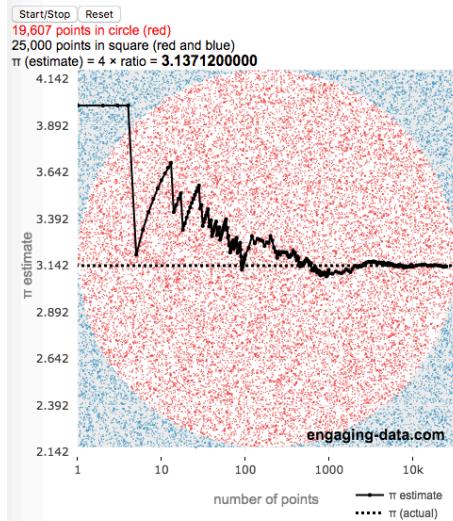
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Chart 30

4. Potential Algorithms

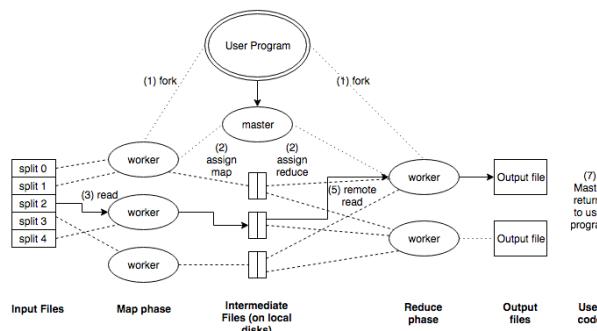
Dwarf 7: MapReduce (= “Monte Carlo”)



Repeated independent execution of a function
(e.g. RNG, map function), results aggregated.

Examples:

Monte Carlo Pi, BOINC (SETI@home),
Optimization Protein Structure Prediction



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4. Potential Algorithms

Dwarf 10(*): Dynamic Programming

Dynamic programming matrix:

		(sequence y)									
		0	1	2	3	4	5	6	7	8 = N	
		T	G	C	T	C	G	T	A		
i	0	0	-6	-12	-18	-24	-30	-36	-42	-48	
	1	T	-6	5	-1	-7	-13	-19	-25	-31	-37
	2	T	-12	-1	3	-3	-2	-8	-14	-20	-26
	3	C	-18	-7	-3	8	2	3	-3	-9	-15
	4	A	-24	-13	-9	2	6	0	1	-5	-4
	5	T	-30	-19	-15	-4	7	4	-2	6	0
M = 6	A	-36	-25	-21	-10	1	5	2	0	11	

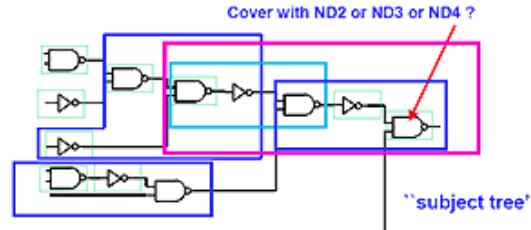
Optimum alignment scores 11:

T	-	-	T	C	A	T	A
T	G	C	T	C	G	T	A
+5	-6	-6	+5	+5	-2	+5	+5

Compute optimal solutions by combining optimal, yet simpler overlapping subproblem solutions (typically use a table to avoid recomputation)

Examples:

circuit design, DNA sequence matching
(Needleman–Wunsch), Viterbi, Knapsack, ...



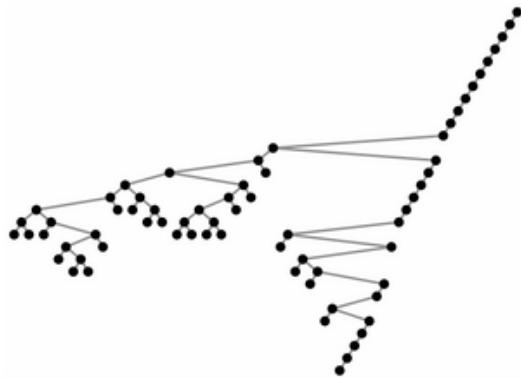
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Chart 32

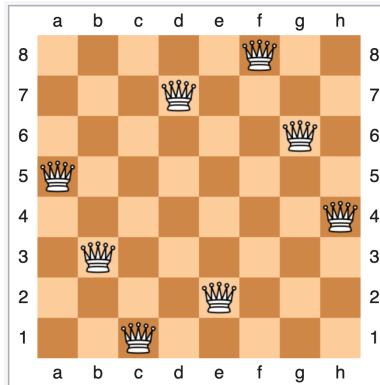
4. Potential Algorithms

Dwarf 11(*): Branch-and-Bound



Global optimization problem in very large search space:

- Branches into subdivisions
- Rules out infeasible regions to optimize execution time and energy consumption



Examples:

Integer Linear Programming, Boolean Satisfiability, Combinatorial Optimization, Traveling Salesman, Constraint Programming, N-Queens



A
D
end

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Chart 34

1. Motivation

Vision: Hardware Agnostic Job Format

