

Week 2: Change of coordinates/basis, Eigenvalues and Eigenvectors
 (textbook § 2.5 and § 5.1)

Change of basis

Recall: Once we picked ordered bases β and γ for V and W respectively, we have a 1-1 correspondence:

$$\left(\begin{array}{l} \text{matrix representation} \\ \text{of } T \\ \text{w.r.t. } \beta \text{ and } \gamma \end{array} \right) : \quad \begin{array}{ccc} L(V, W) & \longleftrightarrow & M_{m \times n}(IF) \\ \Downarrow & & \Downarrow \\ T & \longleftrightarrow & [T]_{\beta}^{\gamma} \end{array}$$

To actually compute the matrix $[T]_{\beta}^{\gamma}$:

let $\beta = \{v_1, v_2, \dots, v_n\} \subset V$ be the ordered bases.

$$\gamma = \{w_1, w_2, \dots, w_m\} \subset W$$

there exist unique $a_{ij} \in IF$, $i=1, \dots, m$, $j=1, \dots, n$ s.t. (Q: Why?)

$$(*) \quad \left\{ \begin{array}{l} T(v_1) = a_{11}w_1 + a_{12}w_2 + \dots + a_{1n}w_m \\ T(v_2) = a_{21}w_1 + a_{22}w_2 + \dots + a_{2n}w_m \\ \vdots \\ T(v_n) = a_{n1}w_1 + a_{n2}w_2 + \dots + a_{nn}w_m \end{array} \right. \quad \text{then,}$$

$$[T]_{\beta}^{\gamma} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} = \begin{pmatrix} | & | & | & | \\ [T(v_1)]_{\gamma} & [T(v_2)]_{\gamma} & \cdots & [T(v_n)]_{\gamma} \\ | & | & | & | \end{pmatrix}$$

$m \times n$ matrix Caution: This is somewhat the "transpose"
of the ordering in (*)

Notation: When $V = W$ and $\beta = \gamma$, we simply write $[T]_{\beta}$.

Example: Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the projection onto x-axis:

$$T(a_1, a_2) = (a_1, 0).$$

Let $\beta = \{e_1, e_2\} = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$ be the standard basis.

$$\begin{cases} T(e_1) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 1 \cdot e_1 + 0 \cdot e_2 \\ T(e_2) = \begin{pmatrix} 0 \\ 0 \end{pmatrix} = 0 \cdot e_1 + 0 \cdot e_2 \end{cases} \Rightarrow [T]_{\beta} = \begin{pmatrix} T(e_1) & T(e_2) \\ \begin{pmatrix} 1 \\ 0 \end{pmatrix} & \begin{pmatrix} 0 \\ 0 \end{pmatrix} \end{pmatrix}.$$

Now, let $\beta' = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix} \right\}$ be another ordered basis.

$$\begin{cases} T(1) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix} \\ T(-1) = \begin{pmatrix} 0 \\ 0 \end{pmatrix} = -\frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix} \end{cases} \Rightarrow [T]_{\beta'} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{pmatrix}.$$

- Since both matrices $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ and $\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{pmatrix}$ represent the same linear transformation T , they should have some properties in common and be "similar" in some sense.

Defⁿ: Let $A, B \in M_{n \times n}(IF)$. We say that B is **similar** to A

if \exists invertible $Q \in M_{n \times n}(IF)$ s.t. $B = Q^{-1}AQ$.

Ex: "similar" is an equivalence relation.

Prop: If A and B are similar matrices, then $\boxed{\text{tr } A = \text{tr } B}$ and $\boxed{\det A = \det B}$.

Proof: Exercise! Recall that $\text{tr}(AB) = \text{tr}(BA)$ and

$$\det(AB) = \det(BA).$$

$$\begin{array}{c} // \\ \det(A) \cdot \det(B) \end{array}$$

The reason why we define similar matrices as above is that they should represent the same linear transformation (just w.r.t. different basis). It follows from the following theorem.

Thm A : Let $T: V \rightarrow V$ be a linear transformation ($\dim V < +\infty$).

Suppose β and β' are two ordered basis for V . Then,

$$[T]_{\beta'} = Q^{-1} [T]_{\beta} Q$$

where $Q := [I_V]_{\beta'}^{\beta}$ is the change of coordinate matrix (from β' to β). Hence, $[T]_{\beta}$ and $[T]_{\beta'}$ are similar matrices.

Example : As before, we take $V = \mathbb{R}^2$ and,

$$\beta = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} \quad \text{and} \quad \beta' = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix} \right\}.$$

To compute $Q := [I_V]_{\beta'}^{\beta}$, note that

$$\left. \begin{array}{l} I_V \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 1 \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 1 \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ I_V \begin{pmatrix} -1 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} = -1 \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 1 \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{array} \right\} \Rightarrow Q = \begin{pmatrix} | & | \\ 1 & -1 \\ | & | \\ 1 & 1 \end{pmatrix}$$

One can check by direct calculation that

$$[T]_{\beta'} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = Q^{-1} [T]_{\beta} Q$$



How to find Q^{-1} ? $[Q | I] \rightarrow [I | Q^{-1}]$

$$\begin{pmatrix} 1 & -1 & | & 1 & 0 \\ 1 & 1 & | & 0 & 1 \end{pmatrix} \xrightarrow{\text{Row } 2 \leftrightarrow \text{Row } 1} \begin{pmatrix} 1 & -1 & | & 1 & 0 \\ 0 & 2 & | & -1 & 1 \end{pmatrix} \xrightarrow{\text{Row } 2 \rightarrow \text{Row } 2 / 2} \begin{pmatrix} 1 & -1 & | & 1 & 0 \\ 0 & 1 & | & -\frac{1}{2} & \frac{1}{2} \end{pmatrix} \xrightarrow{\text{Row } 1 \rightarrow \text{Row } 1 - \text{Row } 2} \begin{pmatrix} 1 & 0 & | & \frac{1}{2} & \frac{1}{2} \\ 0 & 1 & | & -\frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

so $(1 \ -1)^{-1} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{pmatrix}$.

Properties of $Q = [I_v]_{\beta'}^{\beta}$:

(a) Q is invertible

(b) $[v]_{\beta} = Q [v]_{\beta'}$ $\forall v \in V$

(i.e. the coordinate vectors of v relative to β and β' are related by the change of coordinate matrix Q)



By defⁿ, if $T: V_{\beta} \rightarrow W_{\gamma}$, then $[T(v)]_{\gamma} = [T]_{\beta}^{\gamma} [v]_{\beta}$

Moreover, if

$$V_{\alpha} \xrightarrow{T} W_{\beta} \xrightarrow{U} Z_{\gamma} \quad \text{then} \quad [U \circ T]_{\gamma}^{\alpha} = [U]_{\beta}^{\gamma} [T]_{\alpha}^{\beta}$$

Proof: (a) $I_v = I_v \circ I_v \Rightarrow I = [I_v]_{\beta}^{\beta} = [I_v]_{\beta'}^{\beta} [I_v]_{\beta}^{\beta'}$

Therefore, $Q = [I_v]_{\beta'}^{\beta}$ is invertible with $Q^{-1} = [I_v]_{\beta}^{\beta'}$.

(b) By defⁿ with $I_v: V_{\beta'} \rightarrow V_{\beta}$. Exercise!

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Proof of Thm A:

Consider the compositions:

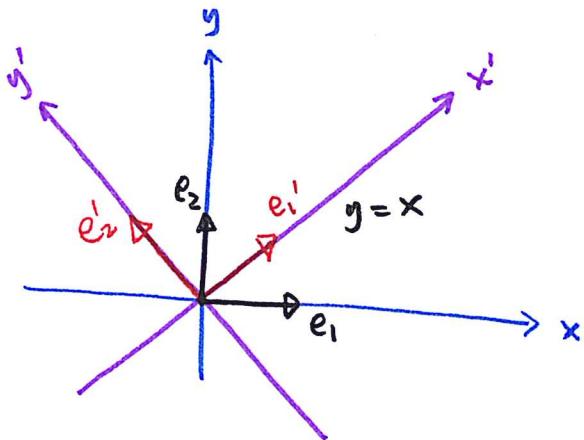
$$V_{\beta'} \xrightarrow{I_v} V_{\beta} \xrightarrow{T} V_{\beta} \xrightarrow{I_v} V_{\beta'}$$

$$\Rightarrow [T]_{\beta'} = [I_v]_{\beta}^{\beta'} [T]_{\beta}^{\beta} [I_v]_{\beta}^{\beta'} = Q^{-1} [T]_{\beta} Q$$

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Thm A can often help us compute $[T]_{\beta}$ by a "clever" choice of a new basis β' so that $[T]_{\beta'}$ is easier to compute (this is basically just doing a change of variables!)

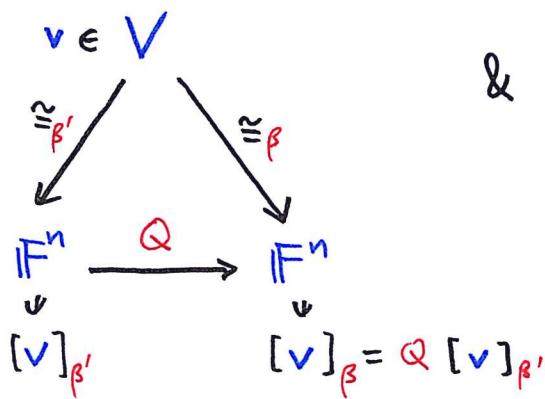
Example: Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the linear transformation which is the projection onto the line $\{y=x\} \subseteq \mathbb{R}^2$. Find $[T]_{\beta}$ where $\beta = \{e_1, e_2\}$ is the standard basis for \mathbb{R}^2 .



Apply Thm A:

$$\begin{aligned}[T]_{\beta} &= Q [T]_{\beta'} Q^{-1} \\ &= \underbrace{\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}}_{\left(\begin{array}{cc} 1 & 0 \\ 0 & 0 \end{array}\right)} \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}}_{\left(\begin{array}{cc} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{array}\right)}^{-1} = \left(\begin{array}{cc} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{array}\right).\end{aligned}$$

Diagrams



consider the basis

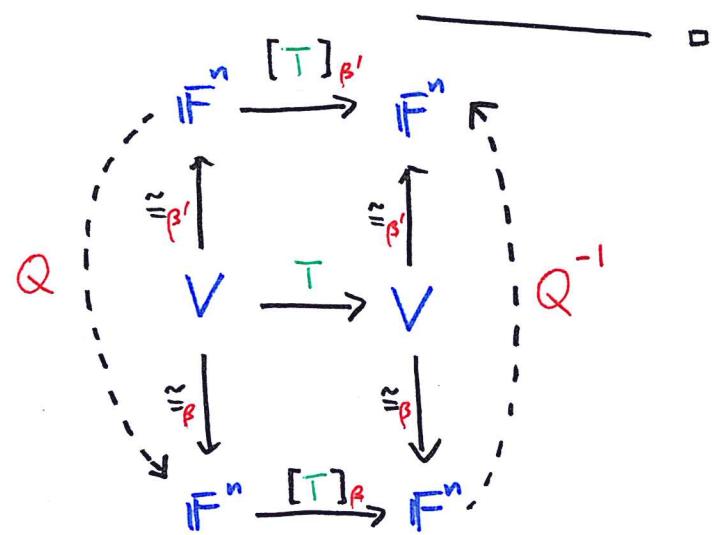
$$\beta' = \{e_1', e_2'\} = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix} \right\}.$$

in the basis β' .

$$[T]_{\beta'} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

Change of coordinate matrix:

$$Q = [I_{\mathbb{R}^2}]_{\beta'}^{\beta} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$



A (slightly) more complicated example:

Let $T = L_A : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the linear map given by the left multiplication by the matrix

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{pmatrix},$$

find $[T]_{\beta'}$ where $\beta' = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} \right\}$.

Solution: let $\beta = \{e_1, e_2, e_3\}$ be the standard basis of \mathbb{R}^3 .

change of
coordinate
matrix :

$$Q = \left(\begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right) \quad \left. \begin{array}{l} \text{Just putting the vectors} \\ \text{in } \beta' \text{ as column vectors} \\ \text{why is it?} \end{array} \right)$$

It is easy to see that $[L_A]_{\beta} = A$. Therefore, by Thm A.

$$[T]_{\beta'} = Q^{-1} [T]_{\beta} Q$$

$$= \underbrace{\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix}}_{\text{red}}^{-1} \underbrace{\begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{pmatrix}}_{\text{blue}} \underbrace{\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix}}_{\text{blue}}$$

$$= \begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 1 & 2 & 3 \\ 0 & 2 & 6 \\ 0 & 0 & 3 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix} \quad \text{diagonal matrix?}$$

A Natural Question: Given A , a square matrix, can we find a "good" basis β' s.t. $[L_A]_{\beta'}$ is diagonal?

Ans: look for eigenvalues / eigenvectors!



Eigenvalues and Eigenvectors

Defⁿ: (i) A linear operator $T: V \rightarrow V$, where $\dim V < +\infty$, is diagonalizable if \exists ordered basis β for V s.t.

$[T]_{\beta}$ is diagonal.

(ii) A square matrix A is diagonalizable if the linear operator $L_A: \mathbb{F}^n \rightarrow \mathbb{F}^n$ is diagonalizable.

Note: By Thm.A, A is diagonalizable $\Leftrightarrow \exists$ invertible matrix Q s.t.

$$Q^{-1}AQ \text{ is diagonal.}$$

Let $\beta = \{v_1, v_2, \dots, v_n\}$ be an ordered basis s.t. $[T]_{\beta}$ is diagonal, i.e.

$$[T]_{\beta} = \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots & \\ & & & \lambda_n \end{pmatrix} \Leftrightarrow \boxed{Tv_i = \lambda_i v_i}$$

The vector v_i just gets rescaled by the scalar λ_i after transformed by the linear map T .

Defⁿ: Let $T: V \rightarrow V$ be linear. If $v \in V$ is a nonzero vector s.t.

$$\boxed{Tv = \lambda v}$$

then v is an eigenvector of T with eigenvalue λ .

Similarly, we say that $v \in \mathbb{F}^n$ is an eigenvector of a matrix $A \in M_{n \times n}(\mathbb{F})$ with eigenvalue λ if $v \neq \bar{0}$ and

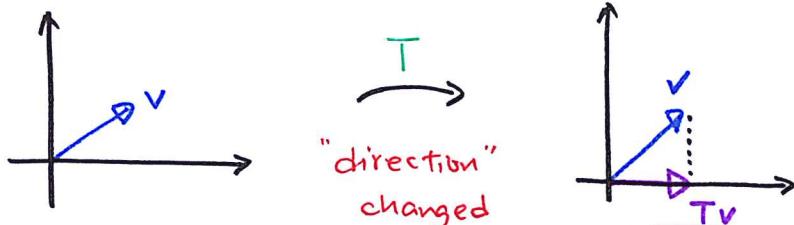
$$\boxed{Av = \lambda v}$$

Note: Since $T(0_v) = 0_v$ for any $T: V \rightarrow V$ linear, we do not consider 0_v as eigenvector. However, 0 can be an eigenvalue!

Using the geometric interpretation that an eigenvector simply gets rescaled by a factor under the linear transformation, one can sometimes "see" the eigenvectors / eigenvalues directly from geometry.

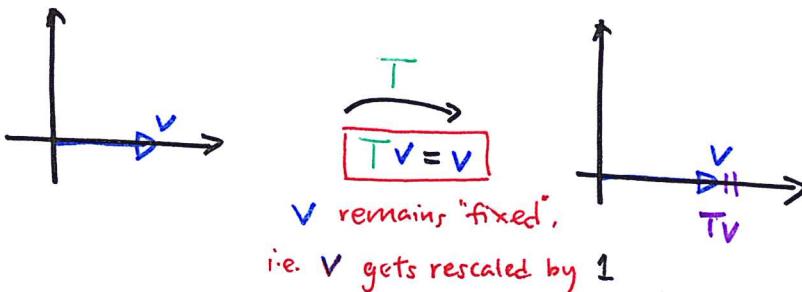
Example: Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the projection onto the x-axis.

for a general vector v :

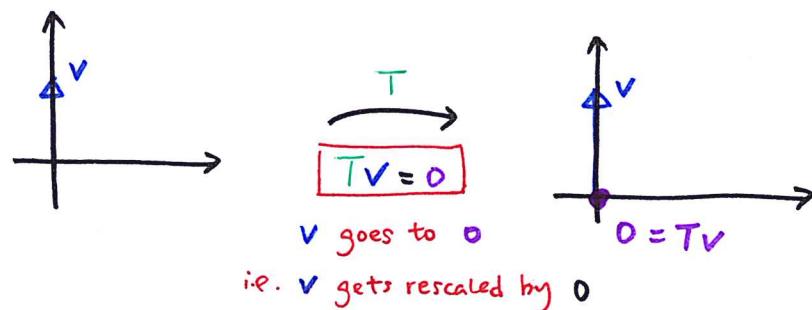


However, if v lies in the x-axis / y-axis:

$v \parallel e_1$:



$v \parallel e_2$:



Therefore, for any $a \neq 0$,

(a) $\begin{pmatrix} 0 \\ a \end{pmatrix}$ is an eigenvector of T with eigenvalue $\lambda = 1$.

(b) $\begin{pmatrix} 0 \\ a \end{pmatrix}$ is an eigenvector of T with eigenvalue $\lambda = 0$. (allowed to have zero eigenvalue, but not zero eigenvector!)

[Q: Is T diagonalizable?] Yes! $[T]_{\beta}^{\beta} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$

Two easy observations:

(1) $0 \neq v \in N(T) \Leftrightarrow v$ is an eigenvector of T with eigenvalue 0.

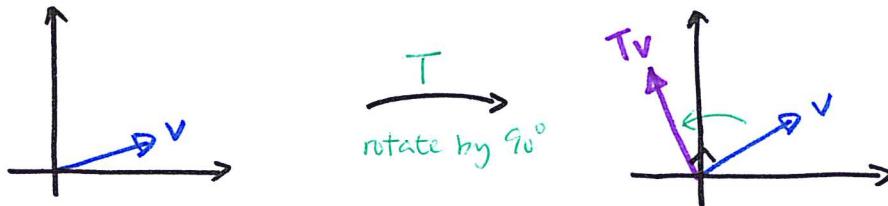
(2) v is an eigenvector of $T \Leftrightarrow a \cdot v$ is an eigenvector $\forall a \neq 0 \in \mathbb{F}$.

(with the same eigenvalue)

⑨

• Eigenvalues may not exist (over \mathbb{R})

For example, let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be rotation (counter-clockwise) by 90° .



Obviously, no vector v stays in the same direction under T .

Therefore, T has no eigenvalues/eigenvectors (over \mathbb{R})

Equivalently, the matrix

$\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ has no real eigenvalues

BUT, it has complex eigenvalues:

$$\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ -i \end{pmatrix} = \begin{pmatrix} i \\ 1 \end{pmatrix} = i \cdot \begin{pmatrix} 1 \\ -i \end{pmatrix}$$

So, i is a complex eigenvalue.

[Q: Can you find another?]

• Infinite dimensional case:

Let $C^\infty(\mathbb{R}) = \{f: \mathbb{R} \rightarrow \mathbb{R} \mid f \text{ infinitely differentiable}\}$. Consider the linear operator: (Note: $\dim C^\infty(\mathbb{R}) = +\infty$).

$$T: C^\infty(\mathbb{R}) \rightarrow C^\infty(\mathbb{R}) \quad T(f) := f'$$

If $0 \neq f \in C^\infty(\mathbb{R})$ is an eigenvector of T with eigenvalue $\lambda \in \mathbb{R}$, then $T(f) = \lambda f$, i.e. f satisfies the ODE

$$f' = \lambda f$$

which we know the solutions are $f(t) = Ce^{\lambda t}$ for any $0 \neq C \in \mathbb{R}$.

Therefore, any $\lambda \in \mathbb{R}$ is an eigenvalue of T .

Q: How to find eigenvalues / eigenvectors?

Thm: Let $A \in M_{n \times n}(\mathbb{F})$. Why? $\exists v \neq 0$ st $Av = \lambda v = \lambda I v \Leftrightarrow (A - \lambda I)v = 0$

(i) $\lambda \in \mathbb{F}$ is an eigenvalue of $A \Leftrightarrow \det(A - \lambda I_n) = 0$

Defⁿ: $f(\lambda) = \det(A - \lambda I_n)$

characteristic polynomial of A

characteristic equation.

I_n = identity matrix

(ii) $0 \neq v \in \mathbb{F}^n$ is an eigenvector with eigenvalue λ of A

$\Leftrightarrow 0 \neq v \in N(A - \lambda I_n)$.

Steps to compute eigenvalues/eigenvectors of a matrix $A \in M_{n \times n}(\mathbb{F})$

(1) Solve the characteristic equation:

$f(\lambda) = \det(A - \lambda I) = 0 \quad \leftarrow$ degree n polynomial equation in λ

(2) For each solution $\lambda \in \mathbb{F}$ to the characteristic equation, find all the eigenvectors with eigenvalue λ by computing the null space $N(A - \lambda I)$.



Example: Find all the eigenvalues/ eigenvectors of

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix} \quad (\mathbb{F} = \mathbb{R})$$

Is A diagonalizable?

Solution: Find characteristic polynomial of A

$$f(\lambda) = \det(A - \lambda I) = \det \begin{pmatrix} 1-\lambda & 2 \\ 3 & 2-\lambda \end{pmatrix}$$

$$= (1-\lambda)(2-\lambda) - 6 = \lambda^2 - 3\lambda - 4$$

Solve characteristic equation

$$f(\lambda) = \lambda^2 - 3\lambda - 4 = 0 \Rightarrow \lambda_1 = 4, \lambda_2 = -1$$

(2 distinct real eigenvalues)

Find eigenvectors for $\lambda_1 = 4$: i.e. $\vec{0} \neq v \in N(A - 4I)$

$$N(A - 4I) = N\left(\begin{pmatrix} -3 & 2 \\ 3 & -2 \end{pmatrix}\right) = \text{span}\left\{\left(\begin{pmatrix} 2 \\ 3 \end{pmatrix}\right)\right\}, \text{ i.e. } v = a\left(\begin{pmatrix} 2 \\ 3 \end{pmatrix}\right), a \neq 0.$$

For $\lambda_2 = -1$,

$$N(A + I) = N\left(\begin{pmatrix} 2 & 2 \\ 3 & 3 \end{pmatrix}\right) = \text{span}\left\{\left(\begin{pmatrix} 1 \\ -1 \end{pmatrix}\right)\right\}, \text{ i.e. } v = a\left(\begin{pmatrix} 1 \\ -1 \end{pmatrix}\right), a \neq 0.$$

A is diagonalizable since if we take $B = \left\{\left(\begin{pmatrix} 2 \\ 3 \end{pmatrix}\right), \left(\begin{pmatrix} 1 \\ -1 \end{pmatrix}\right)\right\}$, then for

$$Q = \left(\begin{pmatrix} 2 & 1 \\ 3 & -1 \end{pmatrix}\right), \text{ we have } Q^{-1}AQ = \left(\begin{pmatrix} 4 & 0 \\ 0 & -1 \end{pmatrix}\right).$$

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Example: Find all the eigenvalues/eigenvectors of

$$A = \left(\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}\right)$$

Is A diagonalizable?

Solution: Solve characteristic equation:

$$0 = f(\lambda) = \det(A - \lambda I) = \det\left(\begin{pmatrix} 1-\lambda & 1 \\ 0 & 1-\lambda \end{pmatrix}\right) = (1-\lambda)^2$$

$$\Rightarrow \lambda = 1 \quad (\text{only 1 eigenvalue - "multiplicity 2"})$$

Find eigenvectors for $\lambda = 1$, i.e. $\vec{0} \neq v \in N(A - I)$.

$$N(A - I) = N\left(\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}\right) = \text{span}\left\{\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right)\right\} \quad \underline{1\text{-dimensional!!}}$$

Therefore, A is NOT diagonalizable because if it were,

then \exists basis $B = \{\vec{v}_1, \vec{v}_2\}$ consisting of eigenvectors.

but \exists only 1 eigenvalue $\lambda = 1$ so both \vec{v}_1, \vec{v}_2 must have eigenvalue 1, i.e. $\vec{v}_1, \vec{v}_2 \in N(A - I)$ and thus

$B = \{\vec{v}_1, \vec{v}_2\}$ must be linearly dependent

as $\dim N(A - I) = 1$.

This contradicts that B is a basis.

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Sometimes, eigenvalues/eigenvectors exist or not depends on the field $\mathbb{F} = \mathbb{R}$ or \mathbb{C} .

Example: Find all the eigenvalues of

$$A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

Is A diagonalizable?

Solution: The characteristic equation is

$$f(\lambda) = \det(A - \lambda I) = \det \begin{pmatrix} -\lambda & -1 \\ 1 & -\lambda \end{pmatrix} = \lambda^2 + 1 = 0$$

$\exists \underline{\text{no}}$ real solutions \Rightarrow NO \mathbb{R} eigenvalues

so, NUT diagonalizable over \mathbb{R} .

BUT, \exists two complex eigenvalues $\lambda_1 = i$, $\lambda_2 = -i$.

Eigenvectors for $\lambda_1 = i$:

$$N(A - iI) = N \begin{pmatrix} -i & -1 \\ 1 & -i \end{pmatrix} = \text{span}_{\mathbb{C}} \left\{ \begin{pmatrix} i \\ 1 \end{pmatrix} \right\}$$

Eigenvectors for $\lambda_2 = -i$:

$$N(A + iI) = N \begin{pmatrix} i & -1 \\ 1 & i \end{pmatrix} = \text{span}_{\mathbb{C}} \left\{ \begin{pmatrix} i \\ -1 \end{pmatrix} \right\}$$

So, A is diagonalizable over \mathbb{C} , ie if we take

$$\beta = \left\{ \begin{pmatrix} i \\ 1 \end{pmatrix}, \begin{pmatrix} i \\ -1 \end{pmatrix} \right\} \text{ or equivalently, } Q = \begin{pmatrix} i & i \\ 1 & -1 \end{pmatrix}$$

$$\text{then } Q^{-1}AQ = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}.$$

Fundamental Theorem of Algebra: \mathbb{C} is "algebraically closed", ie.

any degree n polynomials over \mathbb{C} , $P(t)$, splits:

$$P(t) = C \underset{\mathbb{C}}{\underbrace{(t-a_1)}} \underset{\mathbb{C}}{\underbrace{(t-a_2)}} \underset{\mathbb{C}}{\underbrace{(t-a_3)}} \dots \underset{\mathbb{C}}{\underbrace{(t-a_n)}}$$

(Some a_i 's could be the same)

$\Rightarrow \mathbb{C}$ eigenvalues always exist (But \nRightarrow always diagonalizable over \mathbb{C}) e.g.?

How to find eigenvalues / eigenvectors of $T: V \rightarrow V$? ($\dim V = n$)

(1) Fix ANY basis β to obtain $A = [T]_{\beta} \in M_{n \times n}(F)$.

(2) Find eigenvalues / eigenvectors for the matrix A .

⇒ (3) These are the eigenvalues and the coordinate representation of the eigenvectors (w.r.t. β) for T .

Exercise: Why does it work?



Example: Let $T: M_{2 \times 2}(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$ be $T(A) = A^t$.

Find all eigenvalues / eigenvectors of T .

Is T diagonalizable?

Solution: Take a standard basis for $M_{2 \times 2}(\mathbb{R})$:

$$\beta = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$$

$$\begin{array}{cccc} T \downarrow & T \downarrow & T \downarrow & T \downarrow \\ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} & \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} & \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} & \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \end{array}$$

Therefore,

$$A = [T]_{\beta} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{Char. eq": } \det(A - \lambda I) = \det \begin{pmatrix} 1-\lambda & 0 & 0 & 0 \\ 0 & -\lambda & 1 & 0 \\ 0 & 1 & -\lambda & 0 \\ 0 & 0 & 0 & 1-\lambda \end{pmatrix}$$

$$= (1-\lambda)^2 (\lambda^2 - 1) = (\lambda-1)^3 (\lambda+1) = 0$$

eigenvalues $\lambda_1 = 1, \lambda_2 = -1$.

Eigenvectors: $\boxed{\lambda_1 = 1} \quad T(A) = 1 \cdot A \Leftrightarrow A^t = A$ "symmetric matrices"

$\boxed{\lambda_2 = -1} \quad T(A) = -1 \cdot A \Leftrightarrow A^t = -A$ "skew-symmetric matrices"

(14)

$$\left\{ \begin{array}{l} \text{symmetric} \\ \text{matrices} \end{array} \right\} = \left\{ A \in M_{2 \times 2}(\mathbb{R}) \mid A^t = A \right\} = \text{span} \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right\}.$$

$$\left\{ \begin{array}{l} \text{skew-symmetric} \\ \text{matrices} \end{array} \right\} = \left\{ A \in M_{2 \times 2}(\mathbb{R}) \mid A^t = -A \right\} = \text{span} \left\{ \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \right\}.$$

Hence, T is diagonalizable: if $\beta' = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \right\}$

then

$$[T]_{\beta'} = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & -1 \end{pmatrix}.$$

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