

Pratyush Varshney

<https://pratyusv.github.io/>

GitHub: <https://github.com/pratyusv>

Email : pratyushvarshney91@gmail.com

Mobile : +91 9532365394

EDUCATION

- **Indian Institute Technology, Kanpur** Kanpur, India
Master of Science by Research in Computer Science and Engineering; CPI: 9.00/10.00 *Jan'17 - Present*
- **Kamla Nehru Institute of Technology** Sultanpur, India
Bachelor of Technology in Computer Science and Engineering; 75.92 % *Sep'09 - Jul'13*

RESEARCH WORK

- **Formal Verification of Controllers for UAVs** VERIMAG Institute, France
Prof. Thao Dang & Prof. Indranil Saha *Jun'19 - Present*
Developing frameworks to verify the tight bounds of a Neural Network controller for UAVs in a closed loop system with nonlinear plant dynamics.
- **DeepControl: Energy-Efficient Control of a Quadrotor using a Deep Neural Network** IIT Kanpur
Prof. Indranil Saha *Jun'18 - Mar'19*
Synthesized controllers for a real-world quadrotor by approximating Model Predictive Controller (MPC) using Deep Neural Networks (DNN). The controller synthesized using the DNN required low computation hardware but is able to perform the trajectory tracking close to the MPC.
- **Reducing Policy Search Space using Guide-Actor-Critic Algorithm** IIT Kanpur
Prof. Indranil Saha *Jan'18 - Jun'18*
Developed a Reinforcement Learning based algorithm to synthesize a controller for Quadrotor. The algorithm uses Actor Critic setup of Reinforcement Learning and reduces the vast policy search space using a guide network.

PUBLICATION

- **DeepControl: Energy-Efficient Control of a Quadrotor using a Deep Neural Network**
Pratyush Varshney, Gajendra Nagar, Indranil Saha
In Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2019)
IEEE, Macau, China, November 4-8, 2019

PROJECTS

- **Neural Network Based Modeling and Control of Quadcopters** IIT Kanpur
Prof. Indranil Saha *Jan-2017 - Jun-2017*
Learned the non-linear dynamics of a Quadrotor using Deep Neural Networks via supervised learning. The framework used px4 as the autopilot and Gazebo as the simulator. The DNN could predict the next state of the quadrotor with high accuracy given its previous state and control.
- **Formal Verification of Artificial Neural Networks: A Survey** Computer Aided Verification
Prof. Indranil Saha *Jul 2017 - Nov 2017*
Performed an in-depth survey of formal verification strategies for Neural Networks. Analyzed and compared verification strategies including Abstract Refinement, Integer Constraint Programming and SMT-based techniques.
- **Playing Atari Games using Reinforcement Learning** Neural Networks
Prof. Laxmidher Behera *Jan 2017 - Mar 2017*
Developed a reinforcement learning based application in python that could play the Atari pong game with human level expertise using policy gradient techniques.

- **Aayush: Online Medical Assistance Portal**

B.Tech Project

Prof. Abhay Kumar Agarwal

Jul 2012 - Mar 2013

Created a Java-based web application for medical assistance. The users could locate and seek appointments from doctors, access medical reports, migrate to doctors with specializations, etc. The platform also enabled the communication between doctors seeking medical advice from their peers.

EXPERIENCE

- **Indian Farmers Fertilizer Cooperative**

New Delhi, India

Senior Engineer

Mar 2014 - Dec 2016

- **Document Management System (DMS):** Developed a DMS using J2EE-struts framework to store documents in the Oracle database, provide quick access and an access control mechanism to the users. This reduced a lot of overhead of maintaining and securing the valuable documents manually.
- **Management Information System :** Implemented the module of Employee Leaves Management in the Management Information System (MIS). The module was developed using the Oracle Application Development Framework (ADF).
- **Oracle ERP :** Created and deployed new forms and reports for the Oracle ERP system as per the users requirements.

- **Nokia (Formerly Alcatel-Lucent)**

Gurgaon, India

Software Engineer

Nov 2013 - Mar 2014

- **SIP Protocol Testing:** Part of a team that developed a tool for testing the Session Initiation Protocol (SIP). The tool could simulate SIP calls and interact with the CAMEL stack as well as creating logs that were used for debugging.
- **Instant Convergent Charging System (ICC):** Implemented new functional requirements in the flexible and configurable convergent payment system - ICC. Developed new services for SMS and SIP, as per the clients requirements.

- **Aditya Birla Nuvo Limited**

Jagdishpur, India

Internship Trainee

Jun 2012 - Jul 2012

- **Conversion of Excel reports to online project:** Developed an online Excel converter in Java for a web application. The converter generated formatted Excel reports based on the data queried from the web interface of the application.

RESEARCH POSITIONS

- **Visiting Research Scholar**

VERIMAG Institute, France

Formal Verification of Autopilot Software for UAVs

Jun 2019-Jul 2019

- **Senior Student Research Associate**

IIT Kanpur

A framework for synthesizing robust motion primitives for UAVs

Jan 2017-Present

POSITIONS OF RESPONSIBILITY

- Reviewer for Indian Control Conference (ICC) 2018, 2019
- Training and Placement Coordinator, KNIT Sultanpur.
- Served as Senior Executive Coordinator for Indian Society for Technical Education (ISTE), KNIT Sultanpur.
- Served as Senior Executive Coordinator for Cultural Council, KNIT Sultanpur.
- Served as Co-Executive coordinator for Computer Society of India, KNIT Sultanpur.
- Taught Programming in C, to the first year students, KNIT Sultanpur.

ACHIEVEMENTS

- Secured All India Rank 653 in GATE 2015 among the 115425 shortlisted candidates..
- IBM Certified Academic Professional for DB2.
- A+ Certification in J2EE- Struts with Hibernate from Hewlett-Packard Education Services.
- IBM ‘The Great Mind Challenge’ participation for the project on Smart City.
- Institute Merit Scholarship from UPTU consecutively for 3 years.

AWARDS AND RECOGNITION

- Secured Ist position in Programming competition organized by Computer Society of India.
- Secured Ist position in IT-BHU Robo-opus 2010 organized by Robosapiens.
- Secured IIIrd position in the Embedded Security Challenge at CSAW’18 at IIT Kanpur.

STUDENTS MENTORED

- Mrinal Dogra (B.Tech CSE, IIT Kanpur)
Project: Neural Network Based Modeling and Control of Quadrotors
- Amit Yadav (B.Tech CSE, IIT Kanpur)
Project: Reinforcement Learning based control of Quadrotors
- Gajendra Nagar (B.Tech AE, IIT Kanpur)
Project: Model-Predictive Control of Quadrotors

TECHNICAL SKILLS

- **Languages:** C/C++, Python, Java, SQL, MATLAB, Bash
- **Libraries/Technologies:** Tensorflow, Oracle Application Development Framework(ADF), J2EE-Struts, Oracle Forms and Reports, Eigen, Numpy
- **Robotics:** Robot Operating System (ROS), Gazebo, RotorS, px4-autopilot

REFERENCES

- Dr. Indranil Saha
Department of Computer Science and Engineering
Indian Institute of Technology Kanpur
Email: isaha@cse.iitk.ac.in
- Dr. Thao Dang
VERIMAG Research Lab
Universite Grenoble Alpes, France
Email: thao.dang@univ-grenoble-alpes.fr
- Dr. Nikolaos Kekatos
VERIMAG Research Lab
Universite Grenoble Alpes, France
Email: nikolaos.kekatos@univ-grenoble-alpes.fr