

# ADC14V155, LMK02000, LMK03000

*Application Note 1721 High Speed ADCs with Interfacing, Driving and  
Clocking Schemes*



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# High Speed ADCs with Interfacing, Driving and Clocking Schemes

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## Introduction

The performance of integrated high-speed pipeline Analog-to-Digital Converters (ADCs) is reaching new heights. Resolution, sampling speed, and dynamic performance have pushed to new limits. The ADC14V155 is amongst the best-in-class converters, delivering 57 percent higher full-power bandwidth than competing 14-bit ADCs. The challenge is to keep the static and especially dynamic performance at the levels that are given in the datasheet. Designers must select components around the converter very carefully. This application note will discuss how the performance of high-speed pipeline ADCs can be optimized by designing the right clock circuitry, a good analog input network, as well as how to get the data at these high speeds undistorted from the ADC onto an FPGA or ASIC.

One application example is the ADC14V155 which has a resolution of 14 bits and samples at up to 155 MSPS. It uses differential pipeline architecture and its unique low jitter sample-and-hold stage yields a full power bandwidth of 1.1 GHz. This high input bandwidth makes it a very good candidate for all types of communication receivers, but especially for undersampling. The device can sample signals up to 450 MHz bandwidth, providing flexibility for the system frequency planning and allowing migration from single carrier architectures to a multi-carrier approach where a single ADC digitizes several carriers.

Another area where this ADC can be used is for fast test and measurement equipment. Data leaves the chip on a parallel Low Voltage Differential Signaling (LVDS) interface in a Dual Data Rate (DDR) format to allow clean data transmission onto modern FPGAs. To further reduce noise and power the device features a separate power supply for the output interface (1.8V) and the analog section (3.3V). Typically the device uses under one Watt power. At input frequencies of 70 MHz, the part typically performs with a signal-to-noise ratio (SNR) of 71.7dBFS and spurious free dynamic range (SFDR) of 86.9dBFS.

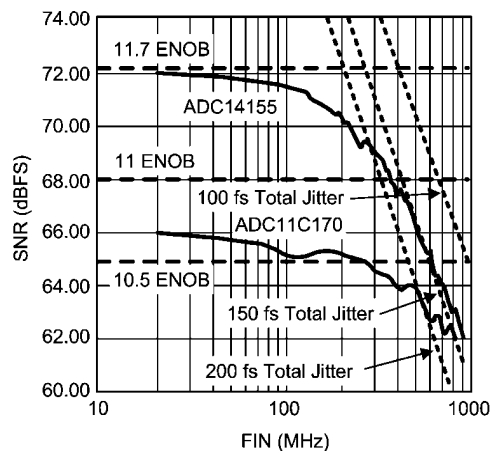
## Clock Jitter — the Enemy to SNR Performance

At high input frequencies and resolution, clock jitter/data jitter becomes one of the biggest limitations to ADC SNR performance. The maximum jitter without degrading SNR must be below the quantization noise (1/2LSB) and can be calculated as:

$$T_{j(rms)} = (V_{in(p-p)} / V_{INFSR}) * (1 / (2^{(N+1)} * \pi * f_{in}))$$

When the input voltage swing  $V_{in(p-p)}$  is optimized to swing full scale the first term becomes one and jitter is only dependant

on resolution (N) and input frequency ( $f_{in}$ ). Measurements of SNR performance on ADCs with 11-14 bit resolution shows that for input frequencies above 100 MHz the total system jitter should be no more than 200 fs for the 11-bit ADC and around 100 fs for the ADC14V155 (11.5 ENOB).

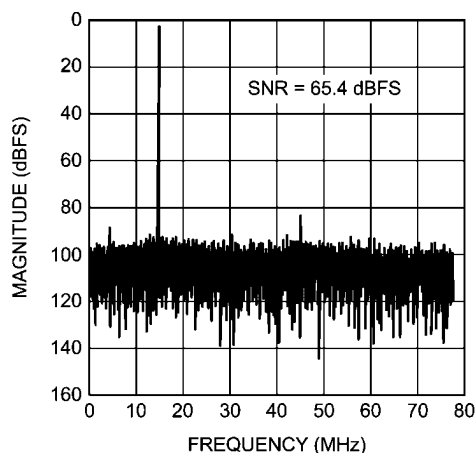


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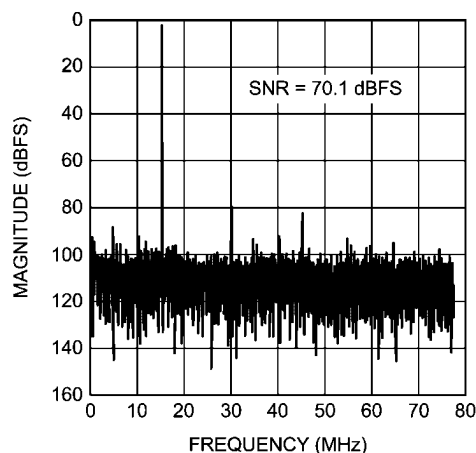
FIGURE 1. 11-14 bit ADC SNR Performance and Jitter Limits

Using that information can help target what the clock source specification and design to implement. Most clock products are defined by their frequency and phase noise, found in their respective datasheets plots. Phase noise and jitter are describing the same phenomenon or problem where phase noise is represented in the frequency domain and jitter is derived from it by integrating the phase noise plot. Consequently, it provides a good insight on what causes jitter on the ADC clock, which then can be addressed and eliminated by subsequent circuit design. A good start is to divide the diagram into the two areas: close-in phase noise and broadband noise. Broadband noise can easily be filtered out, so we have to concentrate on the close-in phase noise. A clock source is needed which has low close-in noise and it should roll off as steeply as possible at the lowest offset.

The reason why broadband noise has to be filtered out is that the signal on the ADC clock input is convolved with the analog input. The very high input bandwidth of 1.1 GHz of the ADC14V155 is matched with a very high clock input bandwidth. That means that a lot of the broadband noise from the clock source, if not filtered away, will alias back into the first Nyquist zone and may degrade SNR.



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**FIGURE 2. The Effect on SNR with and without a Bandpass Filter on the Clock Source (Using a BP Filter Reduces the Noise Floor by 4.7 dB)**

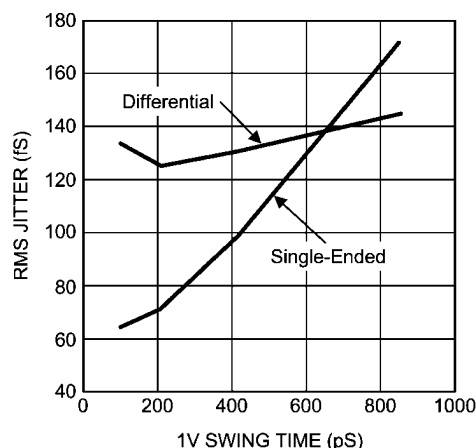
## Subsampling Pitfalls

If subsampling is used, you might even be caught by another trap. Subsampling refers to the situation where the clock frequency is more than twice the signal frequency, which violates the Nyquist theorem of  $f_s$  should be greater than two times  $f_{in}$  to avoid aliasing. Subsampling causes the signal and its harmonics to alias back into the first Nyquist band, but as long as we know which frequencies they are aliased to, a frequency plan can be laid out in a way such that the signal of interest is not corrupted by aliased harmonic spurs.

One popular frequency plan is to use an input frequency that aliases to  $f_s/4$ . In this frequency plan, all of the harmonics will alias to DC,  $f_s/4$  or  $f_s/2$ . The benefit of this plan is that it gives the biggest separation between harmonic distortion spurs, which simplifies filtering and it centers the fundamental frequency in the Nyquist band. However, this frequency plan also masks all of the ADC's harmonic spurs by overlapping them and makes the ADC output spectrum look much better than it actually is. To see the true performance you have to offset the input frequency by 0.1-1 MHz, which un masks overlapping spurs.

## ADC Clock Receiver

Unfortunately, even the clock receiver circuitry inside the ADC itself will generate some jitter. The reason for this is that any supply noise will change the clock receiver's tripping point slightly and this noise will be converted into phase noise when a clock signal with finite slope is applied. This is an analogy of AM (Amplitude Modulation) to PM (Phase Modulation), where AM is the supply noise converted to PM clock noise, which then is jitter in the time domain view. The longer the transition time of the clock, the more jitter will be added. Applying a high slew rate clock will minimize this effect. Consequently, a square wave clock input with fast transition times is the best choice and gives the best SNR.



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**FIGURE 3. Swing Time vs rms Jitter of a Differential Clock and Single-Ended Clock**

In the lab and for testing concepts, high quality signal generators are the best option offering frequency agility. Once the frequency plan is fixed, a crystal oscillator will provide the purest clock. If multiple clocks are required on the PCB then one of the LMK03000/2000 series precision clock conditioners from National is a good choice.

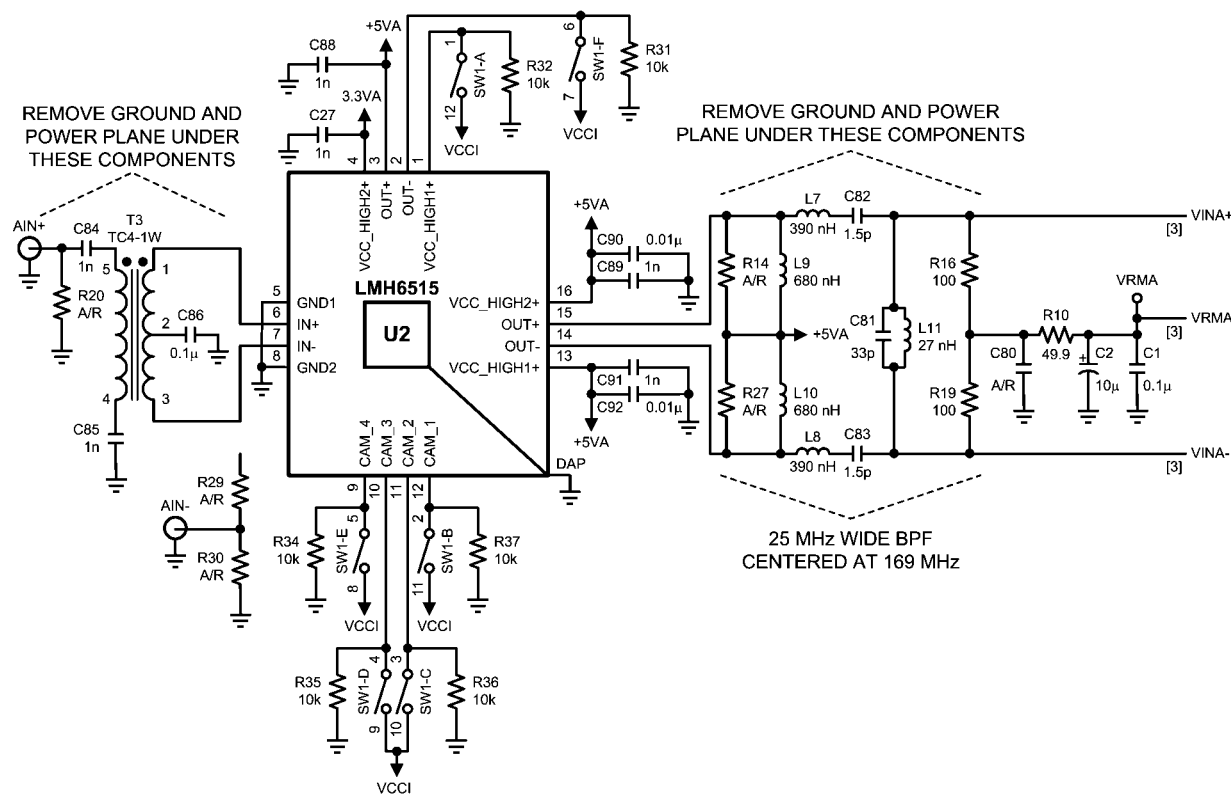
## The Input Network

In the selection and testing phase of an ADC, signal generators are used to drive the input. Clearly, the measured ADC performance will be no better than the purity of the signal applied to its inputs. That means filtering of the signal generator output is mandatory to limit the generator's harmonic distortion and noise from reaching the ADC inputs. A typical synthesizer second harmonic distortion (H2) will be between -40 dBc and -50 dBc while the ADC14V155 H2 at 238 MHz can be as low as -85 dBFS. It is recommended to use tunable bandpass filters like Trilithic VF series filters providing 90 dB 2<sup>nd</sup> and 3<sup>rd</sup> harmonic attenuation.

Filtering the input signal is certainly critical in the final product application. The ADC14V155 has an extremely wide input bandwidth of 1.1 GHz, which means it will sample the entire of spectrum including all unwanted noise components like described in the sampling pitfalls section. Even if the ADC samples only at 155 MHz, noise above this frequency will be aliased back into the first Nyquist band, which has a negative effect on SNR, but if we bandpass filter the input signal around its center frequency, the problem can be avoided.

In most practical examples, the ADC will be coupled to the input signal via a transformer and/or amplifier. Figure 4 shows

a circuit example to drive the ADC14V155 using a DVGA LMH6515. Between the ADC and the amplifier a 4<sup>th</sup> order filter with 25 MHz bandwidth centered around 169 MHz is used. The resistors R16 and R19 provide input common mode bias to the ADC and set the load impedance of the filter. Be careful not to have the impedance too high, even though that reduces the filter attenuation, it also degrades SFDR. The best trade-off between ADC and amplifier distortion has been found to be 500Ω.



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FIGURE 4. Example Circuit to Drive the Input of the ADC14V155

To maximize SFDR performance an additional RC network can be used and tuned to the applications input frequency. The network consists of two serial resistors connected to the input pins of the ADC and a shunt capacitor. These resistors and the capacitor affect settling time due to disturbances from the sample and hold circuitry at the ADC input. The RC com-

ination provides also a last lowpass filter before the ADC and the cutoff frequency will impact noise rejection and harmonic attenuation. A higher value shunt capacitor will lower the cut-off frequency of the lowpass filter and will improve low frequency distortion (at the expense of input bandwidth.)

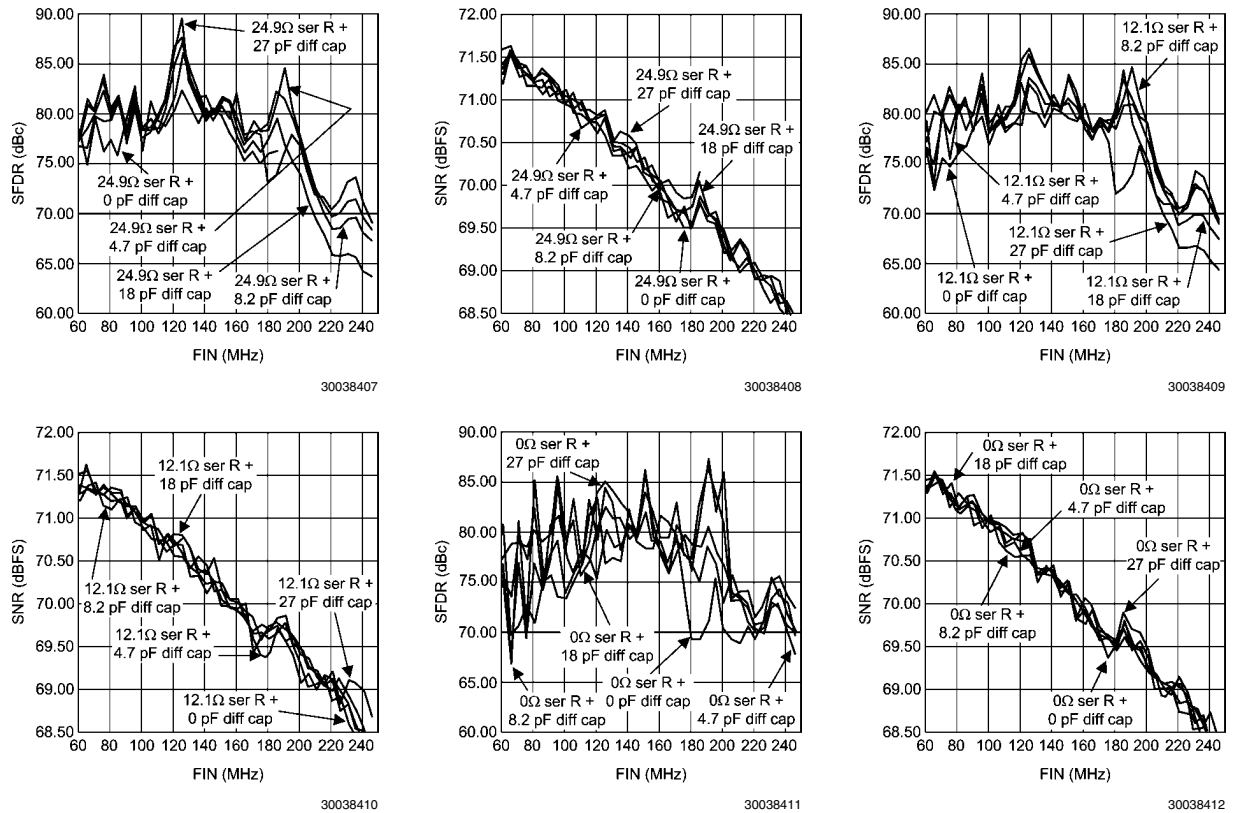


FIGURE 5. Frequency Sweeps Illustrating SFDR Performance with Different Filter Settings

The datasheet of the ADC14V155 shows 12.1Ω resistors and a 15 pF capacitor which exhibit a good compromise over a wide fin range.

## Decoupling

After selecting the right low jitter clock and providing a clean, filtered signal to the input of the ADC, there is one more area of focus. Noise can also couple into the ADC through its reference and supply pins. The best practices are to place the decoupling capacitors as close as possible to the ADC package and pins as possible. Every millimeter counts! At least two different capacitor values for decoupling must be used: 0.1 uF and 0.01 uF, and they have to be connected to the power and ground planes directly. Long traces introduce parasitic resistance and inductance must be avoided.

While measuring SNR and SFDR performance of the ADC14155 in both LLP and TQFP packages, lead length can be problematic if not addressed. Testing showed that with the leads length of the TQFP package, the decoupling caps must be placed on the back of the board directly under the reference and supply pin for optimal performance. SNR degraded almost 3 dB with top side decoupling and SFDR degraded over 3 dB.

## Output Interface

Once we have converted our analog signal, we can present the result to a further processing step such as an FPGA or ASIC. For many years, CMOS output stages were used to

transfer digitized data. The output level of a CMOS stage is load dependant and the signal is voltage mode. A single-ended type output means also no common-mode rejection of noise. With raising switching speeds, the current to drive capacitive loads increases, reducing CMOS voltage swing. At around 150 MHz the data transfer on a CMOS interface becomes unreliable. A new type of interface has to be used and LVDS is an excellent candidate.

An LVDS driver provides a constant current of 3.5 mA in a differential scheme. 100Ω termination resistors have to be used between the differential output lines as close as possible to the receiver pins. The ADC14V155 uses an interleaved DDR output scheme where odd bits are presented first and then even bits on the same pins. The outputs change state at rising AND falling clock edges. This saves 50% or 14 pins on the package and the same amount of connections on the receiving device. Besides the data pins, the Over-Range Indicator (OVR) and Data-Ready Strobe (DRDY) are provided in LVDS format.

## Conclusion

The ADC14V155 is a new generation ADC with superior performance. This advanced device delivers high precision with a very wide bandwidth. The surrounding components play a critical role in determining the signal integrity to cascading stages. System performance can be achieved by following some key design and layout techniques.



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