

Control and algorithmic supervision for preventing collisions

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Designed Data Structure

Three dimensional Matrix

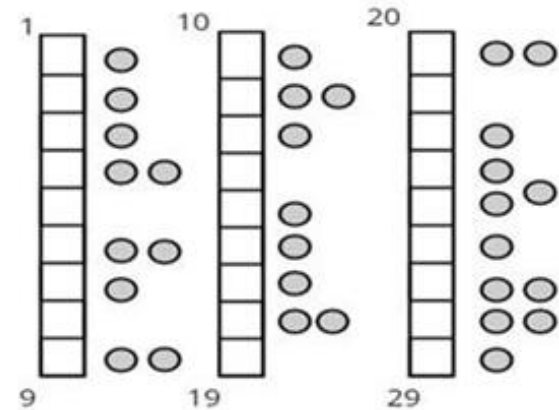
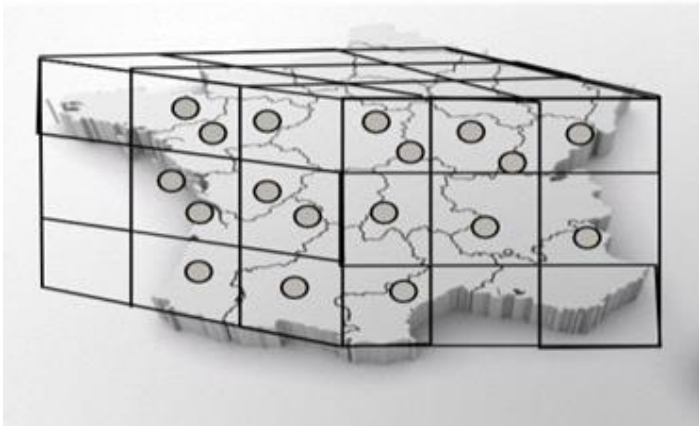


Figure 1-2: Representation of the matrix designed for Bello and the classification of bees.

Operations of the Data Structure

- **Create the cells:** we use this to define the cells in which the bees will be found. In each cube will be found the bees stored in a stack, these bees being the same cube are the ones that are at collision risk.
- **Detect collision:** given the coordinates of a bee it will be added to a certain stack with those bees that are at risk collision.
- **Adjacent bees:** determines which bees are adjacent cubes and end up being at collision risk.

Method	Complexity
areaDeUbicacion()	$O(n)$
abejasAdyacentes()	$O(m)$
detectarColisiones()	$O(n + m)$

Table 1:Complexity

Design of the data structure

- The complexity must be less than $O(n^2)$
- Inserting and removing from a stack is $O(n)$.
- The 3D matrix represents an space.
- While two bees are at risk, do not have to analyze the others.

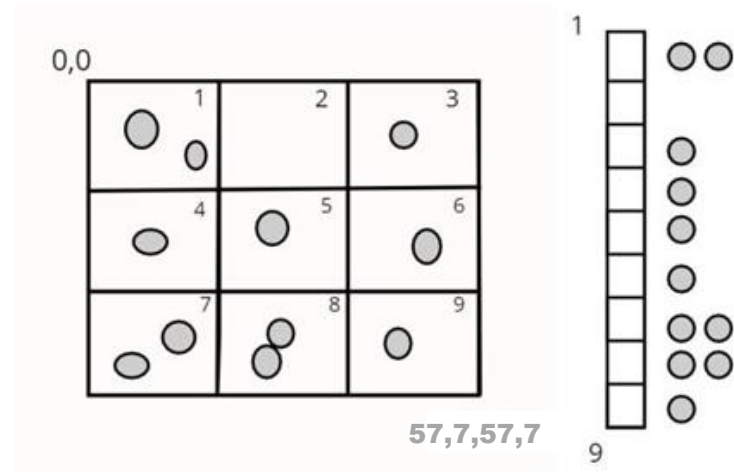


Figure 3: 2D approach

Time and memory used

Método	Tiempo promedio(ms)						
	Número de abejas						
	4	10	100	1.000	10.000	100.000	1'000.000
areaDeUbicacion()	0,6	3,6	3,6	11,6	28,4	275,8	3.315,2
detectarColisiones()	0	4,2	11	8,2	37,8	131,8	673,6
guardarArchivo()	1,6	3,2	7,4	5	112,8	770	6.060,2

Número de abejas	Memoria
10	1
100	2
1000	4
10000	15
100000	80
1000000	245

Table2-3:Time in ms and memory in MB and results

Software

Number of bees	Resultados
4	4
10	4
100	24
1000	279
10000	9546
100000	99184
1000000	1000000

Table 4: obtained results

$$X = \frac{(Max - Min) * 111111}{\frac{100}{\sqrt{3}}}$$

Equation 1: size of the axis

$$D = \frac{(x - Min) * 111111}{\frac{100}{\sqrt{3}}}$$

Equation 2: clasiffication of bees

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