# Tutorial of the new endpoints, bootstrap and k-sample statistic

Hsin-wen Chang\*

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## 1 Testing under biased sampling and crossing CDFs

#### 1.1 Preliminaries

We introduce notation for the k-sample setup of biased sampling. Instead of observing directly from  $F_j$ , the observed samples  $\{X_{ij}, i = 1, ..., n_j\}$  (j = 1, ..., k) are size-biased and i.i.d. from

$$G_j(t) = \int_{-\infty}^t \frac{w_j(u)}{W_j} dF_j(u),$$

where  $w_i(t) > 0$  are known biasing functions depending on the size t of the datum, and  $W_j = \int_{-\infty}^{\infty} w_j(u) dF_j(u) < \infty$  are the normalizing constants. Note that a constant biasing function yields the special case of no biased sampling. The NPMLE  $F_j(t)$  (see, e.g., Owen, 2001, Ch. 6.1) is given by  $\hat{F}_j(t) \equiv \sum_{i=1}^{n_j} \hat{p}_{ij} I_{X_{ij} \leq t}$ , where  $\hat{p}_{ij} = \hat{W}_j / \{n_j w_j(X_{ij})\}$ and  $\hat{W}_j = n_j / \sum_{i=1}^{n_j} (1/w_j(X_{ij}))$ . Without loss of generality, assume that the sample proportion  $\kappa_j = n_j/n > 0$  is fixed, where  $n = \sum_{j=1}^k n_j$ . It can be shown that  $\sqrt{n}\{\hat{F}_j(t) - F_j(t)\}$  converges in distribution in  $l^{\infty}([\tau_1, \tau_2])$  to a tight Gaussian process with zero mean and covariance function  $\theta_j(s,t) = W_j^2/\kappa_j \times E[\{I_{X_{ij} \leq s} - F_0(s)\}\{I_{X_{ij} \leq t} - F_0(s)\}\}$  $F_0(t)$ / $w_i^2(X_{ij})$ ] (see, e.g., Chang et al., 2016, the term in bracket in equation (E1) of Appendix E), where  $\ell^{\infty}(T)$  is the space of all bounded real-valued functions on a set T endowed with the supremum norm. A uniformly consistent estimate of  $\theta_j(s,t)$  is given by  $\hat{\theta}_j(s,t) = \sum_{i=1}^{n_j} \hat{W}_j^2 \{ I_{X_{ij} \leq s} - \hat{H}(s) \} \{ I_{X_{ij} \leq t} - \hat{H}(t) \} / \{ n \kappa_j^2 w_j^2(X_{ij}) \}$ . For future reference, define an estimate for the common CDF  $F_0$  under  $H_0$  as  $\hat{H}(t) = \sum_{j=1}^k \kappa_j \hat{F}_j(t)$ , the deviations of the estimated group CDF from the common CDF as  $\hat{D}_j(t) = \hat{F}_j(t) - \hat{H}(t)$ , and  $\hat{\theta}(s,t) = \sum_{j=1}^{k} \hat{\theta}_{j}(s,t)$ . In computing the integrand of the statistics we considered in the later sections, we adopt the convention that 0/0 = 0.

<sup>\*</sup>Institute of Statistical Science, Academia Sinica, Taipei 11529, Taiwan.

#### 1.2 Two-sample test

To test for  $H_0$ , we start with an AD-type statistic:

$$A_n = n \int_{\tau_1}^{\tau_2} \frac{\hat{D}^2(t)}{\hat{\theta}(t,t)} d\hat{H}(t),$$

where  $\hat{D}(t) = \hat{F}_1(t) - \hat{F}_2(t)$  denotes the estimate for the quantity we are interested in:  $F_1(t) - F_2(t)$  for  $t \in [\tau_1, \tau_2]$ . Note that the denominator of the integrand of  $A_n$  is an estimate of the asymptotic variance of  $\sqrt{n}\hat{D}(t)$ ; this formulation takes into account the fact that the integrand of a usual AD statistic is studentized. An alternative is to simply replacing the elements in a usual two-sample AD statistic (Pettitt, 1976) by their counterparts in biased-sampling settings, leading to

$$U_n = \frac{n_1 n_2}{n} \int_{\tau_1}^{\tau_2} \frac{\hat{D}^2(t)}{\hat{H}(t) \left\{ 1 - \hat{H}(t) \right\}} d\hat{H}(t).$$

Unfortunately, this statistic did not perform well in our simulation study; this shows the importance of studentizing the integrand properly in an integral-type statistic.

Although both  $A_n$  and  $U_n$  incorporate variance of the estimated quantity of interest  $\hat{D}(t)$ , they do not consider the correlations between  $\hat{D}(s)$  and  $\hat{D}(t)$  for different s and t. To incorporate the correlations, consider replacing the integrand of  $A_n$  by an estimate of the Mahalanobis distance between  $\sqrt{n}[\hat{F}_1(s), \hat{F}_1(t)]^T$  and  $\sqrt{n}[\hat{F}_2(s), \hat{F}_2(t)]^T$ :  $M_n^A(s,t) \equiv n[\hat{D}(s), \hat{D}(t)]\hat{\Theta}^{-1}(s,t)[\hat{D}(s), \hat{D}(t)]^T$  and changing the single integral into double integrals, where

$$\hat{\Theta}(s,t) = \left[ \begin{array}{cc} \hat{\theta}(s,s) & \hat{\theta}(s,t) \\ \hat{\theta}(t,s) & \hat{\theta}(t,t) \end{array} \right].$$

This can be seen as a bivariate generalization of  $A_n$ . A similar generalization of  $U_n$  can be achieved by using the integrand  $M_n^U(s,t) \equiv n[\hat{D}(s),\hat{D}(t)]\hat{\Psi}^{-1}(s,t)[\hat{D}(s),\hat{D}(t)]^T$ , where

$$\hat{\Psi}(s,t) = \begin{bmatrix} \hat{H}(s) \left\{ 1 - \hat{H}(s) \right\} & \hat{H}(s) \left\{ 1 - \hat{H}(t) \right\} \\ \hat{H}(s) \left\{ 1 - \hat{H}(t) \right\} & \hat{H}(t) \left\{ 1 - \hat{H}(t) \right\} \end{bmatrix}.$$

The resulting statistics

$$BA_n = \int_{\substack{s,t \in [\tau_1, \tau_2] \\ s < t}} M_n^A(s, t) \ d\hat{H}(s) d\hat{H}(t) \text{ and}$$

$$BU_n = \kappa_1 \kappa_2 \int_{\substack{s,t \in [\tau_1, \tau_2] \\ s < t}} M_n^U(s, t) \ d\hat{H}(s) d\hat{H}(t)$$

can be viewed as testing the bivariate hypotheses  $H'_0$  versus  $H'_1$ . Although this testing problem is equivalent to testing the univariate  $H_0$  versus  $H_1$ , the statistics for the bivariate hypotheses incorporate the (pairwise) interactions among  $\hat{D}(t)$  at different t values, and hence may have better power in detecting difference between the underlying CDFs.

The limiting distributions need to be estimated because they are not distribution-free. This can be done using a similar multiplier bootstrap approach as the one proposed in Chang et al. (2016) for biased sampling data. Specifically, it suffices to bootstrap the key component  $\hat{D}(t)$  in the statistics by  $D^*(t) = D_1^*(t) - D_2^*(t)$ , where  $D_j^*(t) = \sum_{i=1}^{n_j} \xi_{ij} \hat{p}_{ij} \left\{ I_{X_{ij} \leq t} - \hat{H}(t) \right\}$  and  $\xi_{ij}$ s are (t) standard normal random variables independent of the data. The bootstrap procedure is given as follows.

(a) Given each draw of the multipliers  $\{\xi_{ij}, i = 1, \dots, n_j, j = 1, 2\}$ , compute a value for each of

$$A_{n}^{*} = n \int_{\tau_{1}}^{\tau_{2}} \frac{D^{*2}(t)}{\hat{\theta}(t,t)} \underline{d\hat{H}(t)}, \ U_{n}^{*} = \frac{n_{1}n_{2}}{n} \int_{\tau_{1}}^{\tau_{2}} \frac{D^{*2}(t)}{\hat{H}(t) \left\{1 - \hat{H}(t)\right\}} d\hat{H}(t),$$

$$BA_{n}^{*} = \int_{\substack{s,t \in [\tau_{1},\tau_{2}]\\s < t}} n[D^{*}(s), D^{*}(t)] \hat{\Theta}^{-1}(s,t) [D^{*}(s), D^{*}(t)]^{T} \ d\hat{H}(s) d\hat{H}(t), \text{ and}$$

$$BU_{n}^{*} = \kappa_{1}\kappa_{2} \int_{\substack{s,t \in [\tau_{1},\tau_{2}]\\s < t}} n[D^{*}(s), D^{*}(t)] \hat{\Psi}^{-1}(s,t) [D^{*}(s), D^{*}(t)]^{T} \ d\hat{H}(s) d\hat{H}(t).$$

Alternatively, change  $\hat{\theta}(s,t)$  in  $A_n^*$  and  $BA_n^*$  above to  $\hat{\theta}^*(s,t) = \sum_{j=1}^2 \hat{\theta}_j^*(s,t)$ , where  $\hat{\theta}_j^*(s,t)$  is the sample covariance of  $V_{ij}^*(t) = \xi_{ij} \hat{W}_j [I_{X_{ij} \leq t} - \hat{H}(t)] / \{\sqrt{\kappa_j} w_j(X_{ij})\}$ .

- (b) Repeat the procedure in (a) b times; we use b=1000 in our simulation study. This leads to b bootstrapped values for  $A_n^*$ ,  $U_n^*$ ,  $BA_n^*$ , and  $BU_n^*$ . Compute the upper  $\alpha$ -quantile of the b bootstrapped values for each of  $A_n^*$ ,  $U_n^*$ ,  $BA_n^*$ , and  $BU_n^*$ , and denote the corresponding quantiles as  $c_{A,\alpha}^*$ ,  $c_{U,\alpha}^*$ ,  $c_{BA,\alpha}^*$ , and  $c_{BU,\alpha}^*$ , respectively
- (c) To calibrate the tests, compare the test statistics based on the original data, namely  $A_n, U_n, BA_n$ , and  $BU_n$ , with the corresponding quantiles  $c_{A,\alpha}^*$ ,  $c_{U,\alpha}^*$ ,  $c_{BA,\alpha}^*$ , and  $c_{BU,\alpha}^*$ , respectively. We reject  $H_0$  if  $U_n > c_{A,\alpha}^*$ , and similarly for other statistics.

#### 1.3 k-sample statistic

To test for  $H_0$ , we start with replacing the elements in a usual k-sample AD statistic (Scholz and Stephens, 1987) by their counterparts in biased-sampling settings, leading

to

$$U_{k,n} = \int_{\tau_1}^{\tau_2} \left[ \sum_{j=1}^k n_j \frac{\hat{D}_j^2(t)}{\hat{H}(t) \left\{ 1 - \hat{H}(t) \right\}} \right] d\hat{H}(t).$$

To improve from  $U_{k,n}$ , consider replacing the sum of squares in its integrand by a weighted sum of squares between blocks  $\widehat{SSB}(t)$  (defined below), leading to

$$\underline{A_{k,n}} = \int_{\tau_1}^{\tau_2} \widehat{\text{SSB}}(t) \underline{d}\hat{H}(t),$$

where

$$\widehat{SSB}(t) = \sum_{j=1}^{k} \hat{\nu}_j(t) \left\{ \hat{\Psi}_j(t) - \check{\Psi}(t) \right\}^2, \tag{1}$$

 $\check{\Psi}(t) = \sum_{j=1}^{k} \hat{\nu}_{j}(t) \hat{\Psi}_{j}(t), \quad \hat{\Psi}_{j}(t) = \sqrt{n} \{\hat{F}_{j} - \hat{H}\}(t) / \sqrt{\hat{\theta}_{j}(t,t)\hat{\nu}_{j}(t)}, \quad \hat{\theta}_{j}(s,t) = \sum_{i=1}^{n_{j}} \hat{W}_{j}^{2} \{I_{X_{ij} \leq s} - \hat{H}(s)\} \{I_{X_{ij} \leq t} - \hat{H}(t)\} / \{n\kappa_{j}^{2}w_{j}^{2}(X_{ij})\}, \text{ and the varying group-specific weights } \hat{\nu}_{j}(t) \propto 1/\hat{\theta}_{j}(t,t) \text{ are normalized to sum to } 1, j = 1, \dots, k. \text{ This } k\text{-sample statistic reduces to the } A_{n} \text{ in Section } 1.2 \text{ when } k = 2. \text{ The formulation of } \widehat{SSB}(t) \text{ is inspired from } SSB^{o}(t) \text{ in Chang and McKeague } (2019) \text{ when deriving a statistic for comparing } k \text{ survival functions in right-censored data without sampling bias. In particular, the deviation } \hat{D}_{j}(t) \text{ of the estimated group CDF from the common CDF is first standardized by } \sqrt{\hat{\theta}_{j}(t,t)} \text{ in } \hat{\Psi}_{j}(t). \text{ In the weighted sum, each component of the sum compares the deviations of a group-specific quantity from an overall weighted average, where the weight is inversely proportional to the relevant estimated variance } \hat{\theta}_{j}(t,t).$ 

A data-driven rule for  $\tau_1$  and  $\tau_2$ :  $\tau_1 = \inf\{t : \hat{F}_j(t) > 0 \text{ for all } j = 1, \dots, k\}$  and  $\tau_2 = \sup\{t : \hat{F}_j(t) < 1 \text{ for all } j = 1, \dots, k\}$ .

For calibration, again we use a similar multiplier bootstrap method as in Section 1.2, based on sampling i.i.d. standard normal random variables (multiliers)  $\xi_{ij}$ s independent of the data. Specifically, it suffices to bootstrap the key component  $\hat{D}_j$  in the statistics by  $D_j^*(t)$ , The bootstrap procedure is given as follows.

(a) Given each draw of the multipliers  $\{\xi_{ij}, i = 1, \dots, n_j, j = 1, \dots, k\}$ , compute a value for each of

$$U_{k,n}^* = \int_{\tau_1}^{\tau_2} \left[ \sum_{j=1}^k n_j \frac{D^{*2}(t)}{\hat{H}(t) \left\{ 1 - \hat{H}(t) \right\}} \right] d\hat{H}(t), \ A_{k,n}^* = \int_{\tau_1}^{\tau_2} \widehat{SSB}^*(t) d\hat{H}(t),$$

where

$$\widehat{SSB}^*(t) = \sum_{j=1}^k \hat{\nu}_j^*(t) \left\{ \hat{\Psi}_j^*(t) - \check{\Psi}^*(t) \right\}^2,$$

 $\hat{\Psi}_j^*(t) = \sqrt{n}D_j^*(t)/\sqrt{\hat{\theta}_j^*(t,t)}\hat{\nu}_j^*(t), \ \hat{\theta}_j^*(s,t)$  is the sample covariance of  $V_{ij}^*(t) = 0$ 

 $\xi_{ij}\hat{W}_j[I_{X_{ij}\leq t}-\hat{H}(t)]/\{\sqrt{\kappa_j}w_j(X_{ij})\},\ \check{\Psi}^*(t)=\sum_{j=1}^k\hat{\nu}_j^*(t)\hat{\Psi}_j^*(t),\ \text{and the varying group-specific weights }\hat{\nu}_j^*(t)\propto 1/\hat{\theta}_j^*(t,t)\ (j=1,\ldots,k)\ \text{are normalized so that }\sum_{j=1}^k\hat{\nu}_j^*(t)=1.$ 

- (b) Repeat the procedure in (a) b times; we use b=1000 in our simulation study. This leads to b bootstrapped values for  $A_{k,n}^*$ ,  $U_{k,n}^*$ . Compute the upper  $\alpha$ -quantile of the b bootstrapped values for each of  $A_{k,n}^*$ ,  $U_{k,n}^*$ , and denote the corresponding quantiles as  $c_{A,\alpha}^*$ ,  $c_{U,\alpha}^*$ .
- (c) To calibrate the tests, compare the test statistics based on the original data, namely  $A_{k,n}, U_{k,n}$ , with the corresponding quantiles  $c_{A,\alpha}^*$ ,  $c_{U,\alpha}^*$ . We reject  $H_0$  if  $A_n > c_{A,\alpha}^*$ , and similarly for other statistics.

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