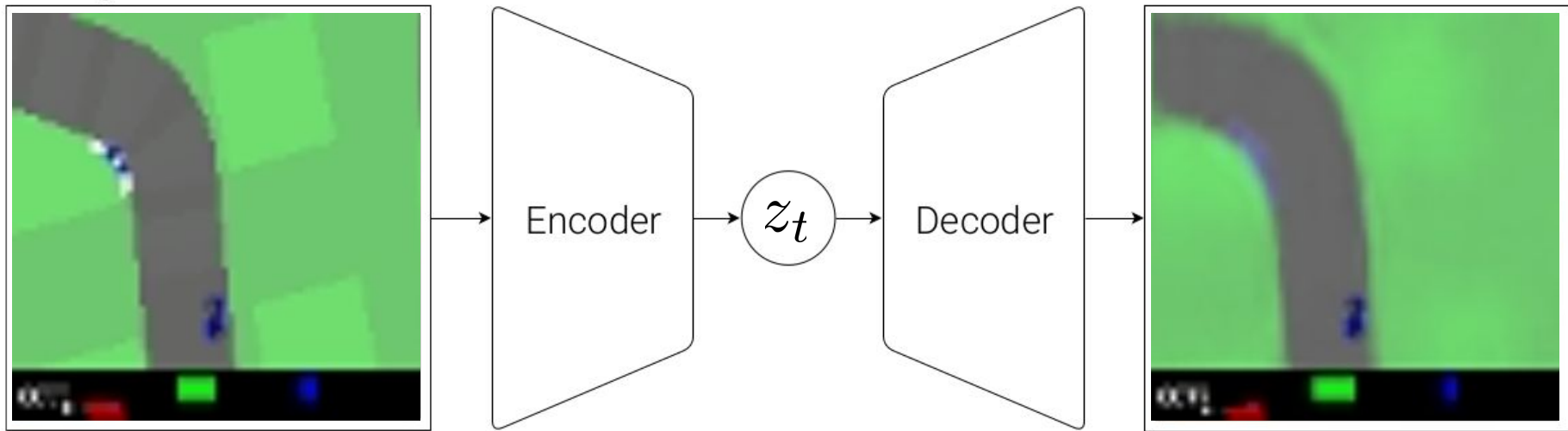


Original Observed Frame

Reconstructed Frame



$s_t$

$\hat{s}_t$