

Gradient Descent

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References:
Duc D. Nguyen's lecture notes
Wikipedia

Artificial Intelligence (AI) Stats News (Sep 10, 2019): 120 Million Workers Need To Be Retrained Because Of AI in the next three years

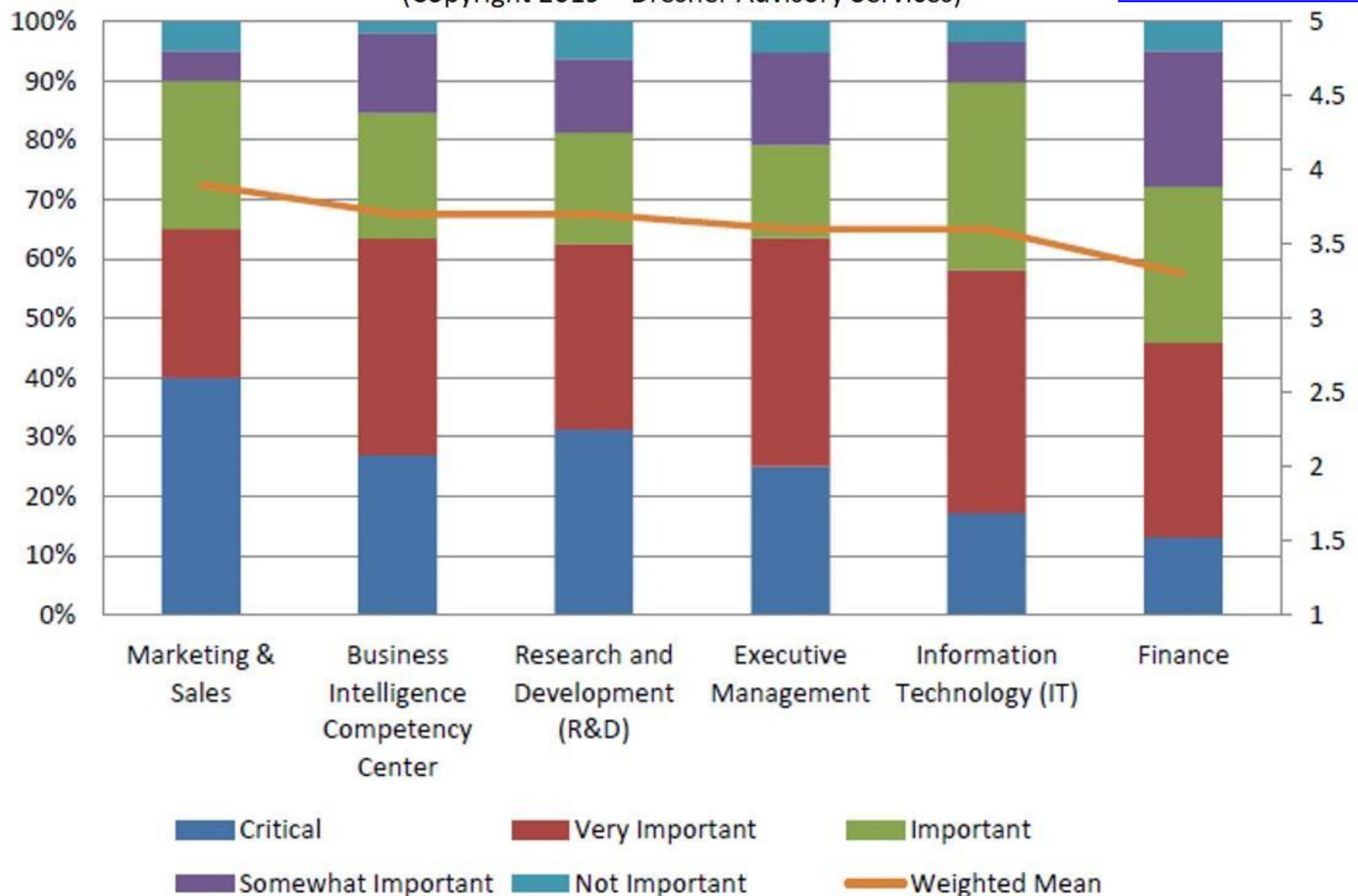


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Importance of Data Science and Machine Learning by Function

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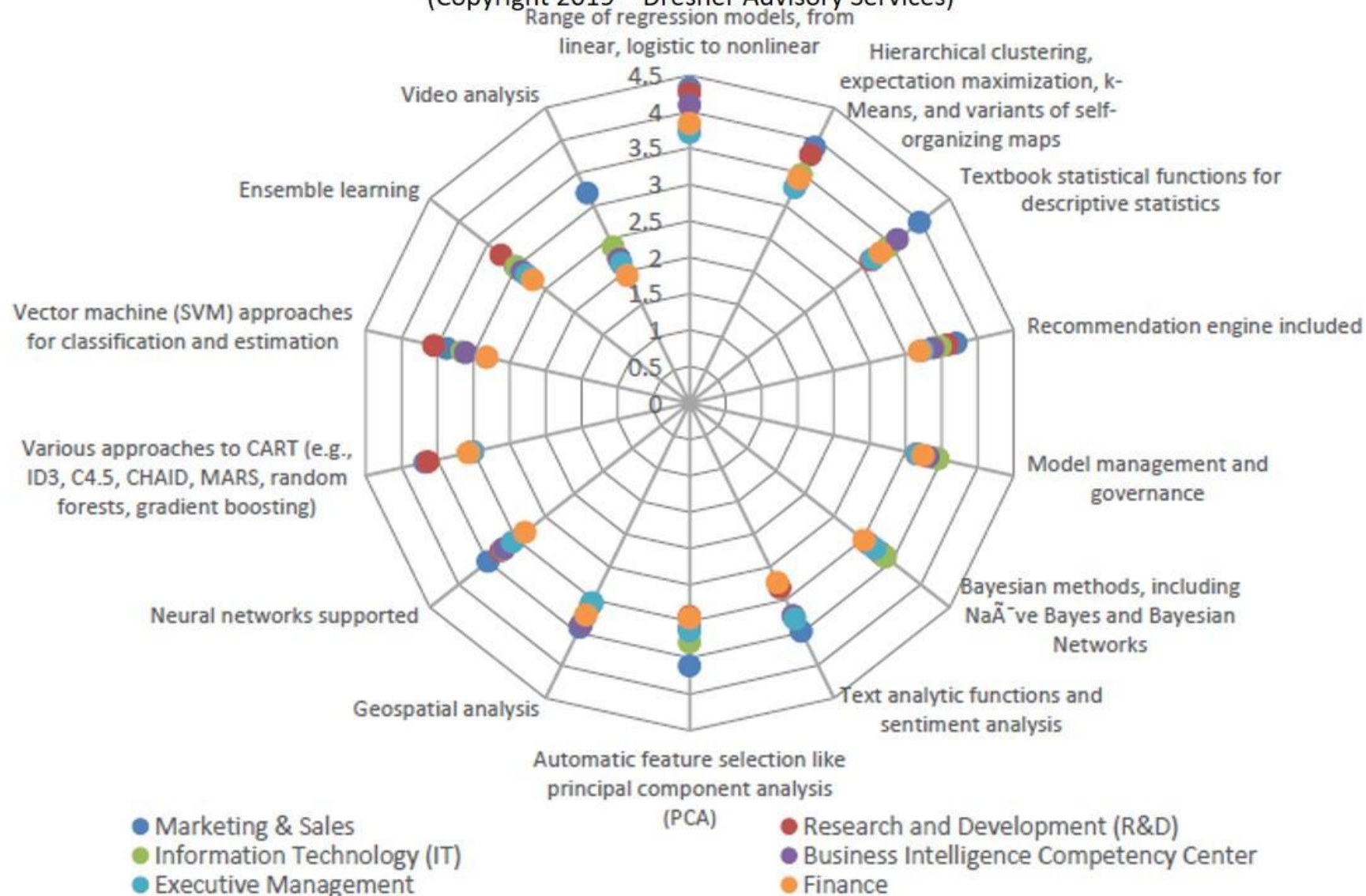


Analytical Features for Data Science and Machine

Learning by Function

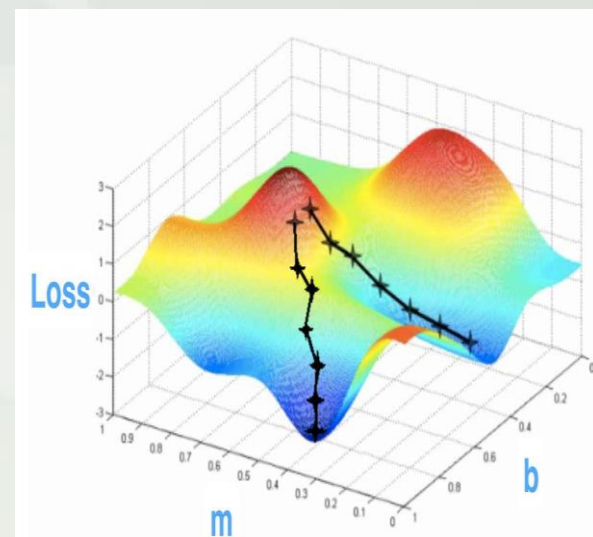
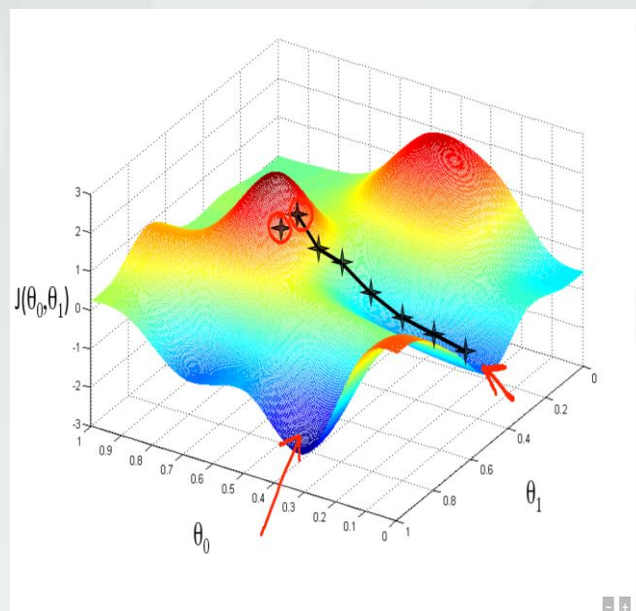
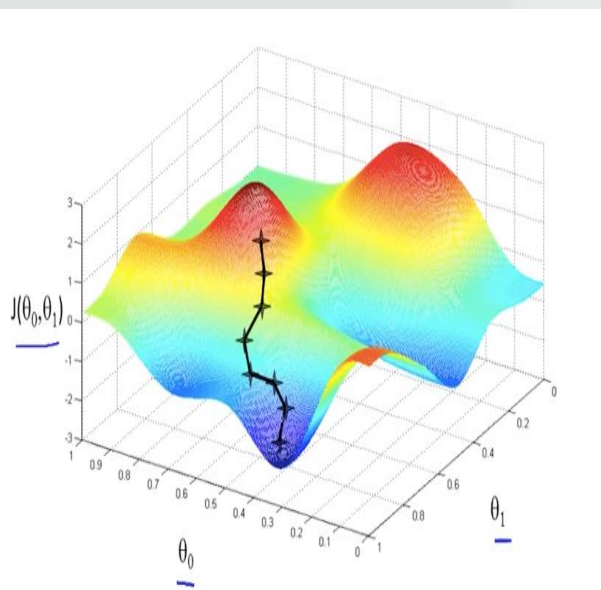
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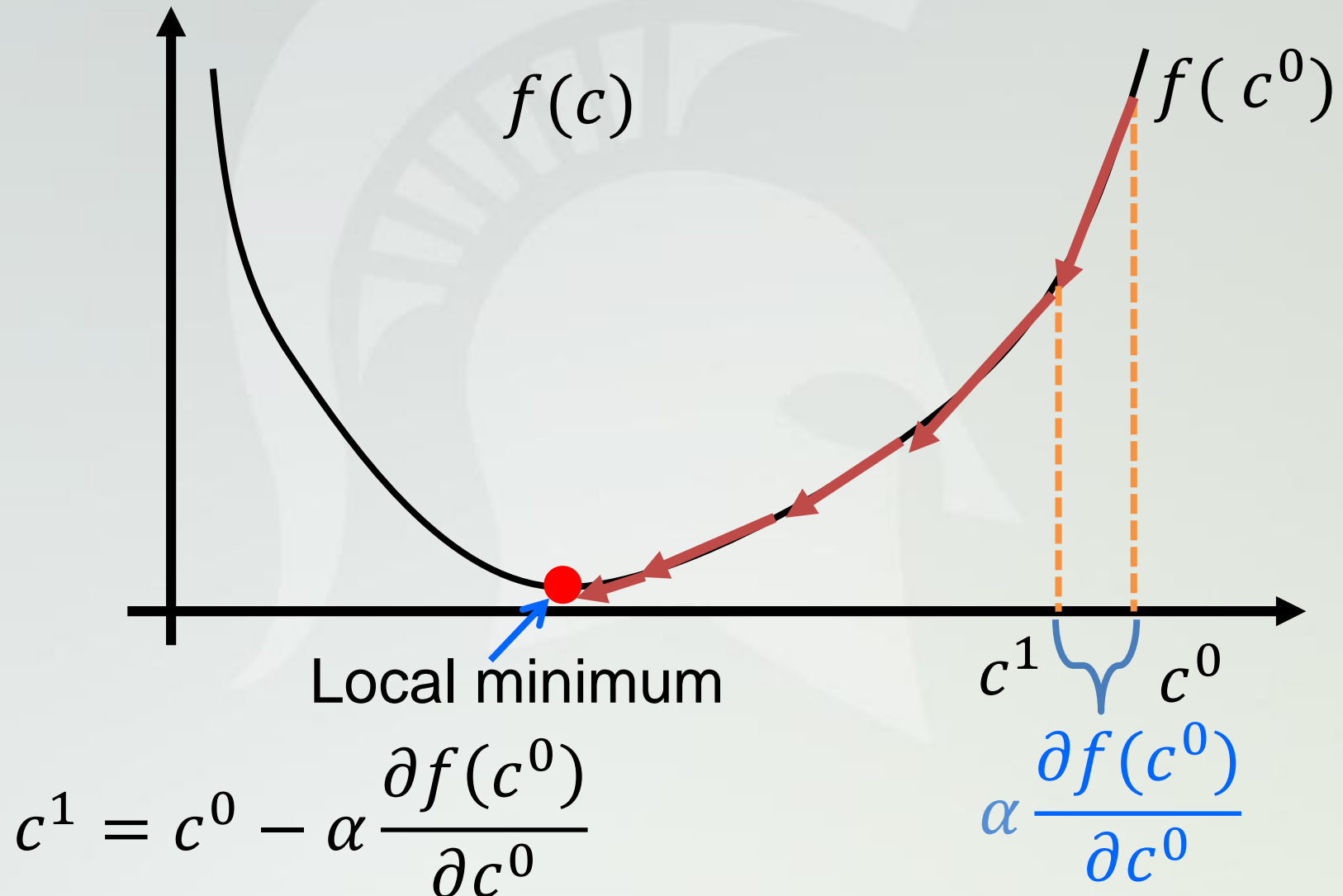
Introduction

- In general, the loss function has no analytical solutions. We use Gradient Descent (steepest descent or gradient ascent for local maximum).
- Gradient = direction of the steepest ascent
- Find a local minimum of a function
- Often a first-order iterative optimization algorithm



General Idea

Consider a general function $f(c)$ which can be the loss function of interest



Algorithm

Find a local minimum of a C^1 continuous $f(c)$

- Start with random value c^0
- Update new value:

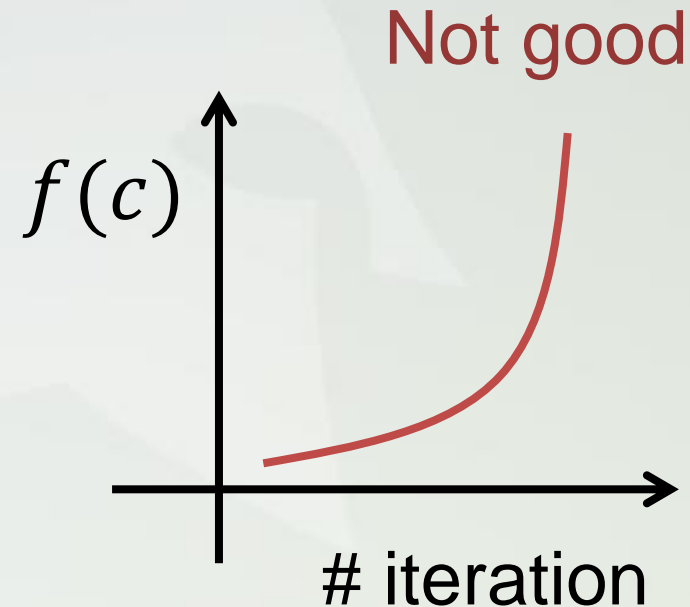
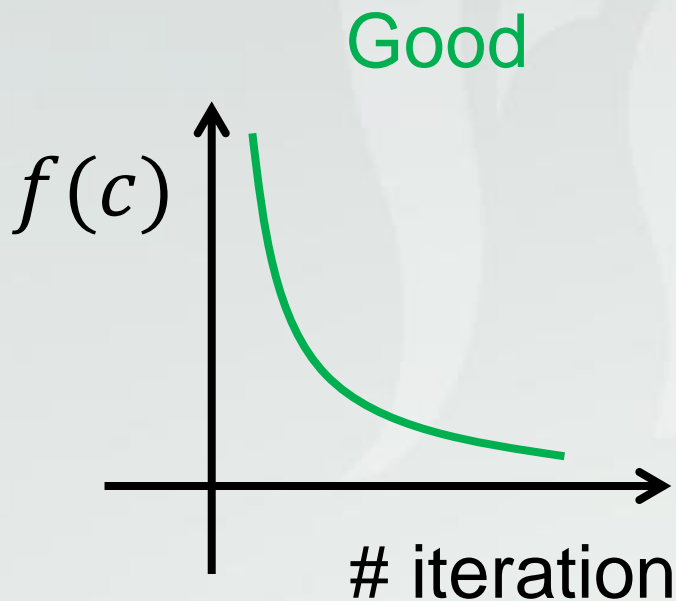
$$c^{i+1} = c^i - \alpha \frac{\partial f(c^i)}{\partial c^i}$$

α : **learning rate**, very small (like 0.01 or smaller)

- Repeat until $\left\| \frac{\partial f(c^i)}{\partial c^i} \right\| \leq \text{tolerance}$

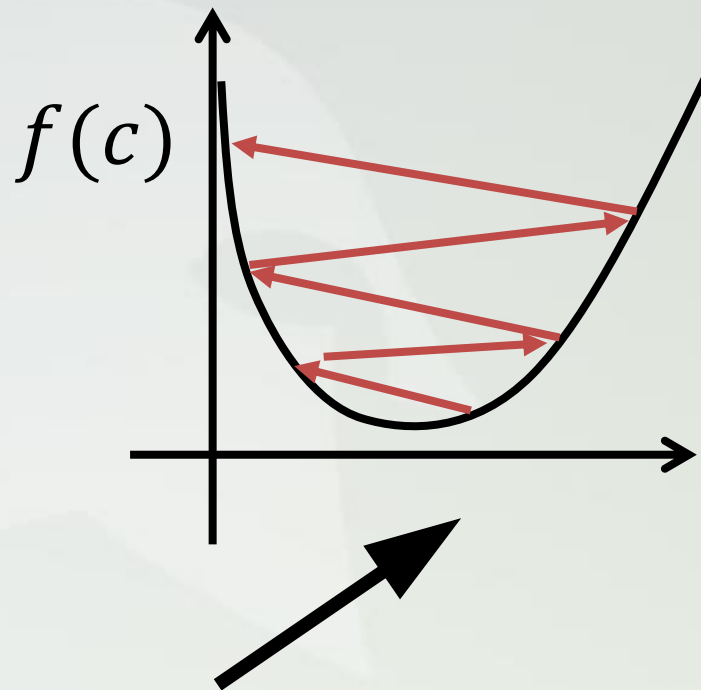
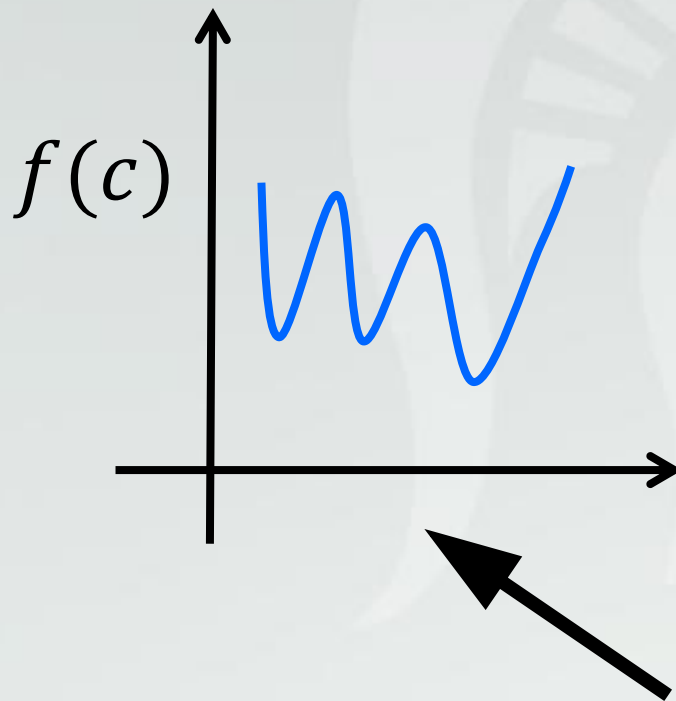
Making Sure Gradient Descent Working Correctly

- Function $f(c)$ should decrease after every iteration (monotonically decreases)



Making Sure Gradient Descent Working Correctly

- Use smaller learning rate α



Very large learning rate

Making Sure Gradient Descent Working Correctly

- Feature scaling:
 - Example: assume features for the house price includes number of bedrooms and living area
 - # of bedrooms between 0 and 5
 - But living area between 1 and 5000 feet²
 - Make all features have the same level of magnitude

Application for Minimizing Loss Function

- Linear regression: loss function for predictor $p_c(x) = c_0 + c_1x$ is

$$\begin{aligned} L(c_0, c_1) &= \sum_{i=1}^M (p(x^{(i)}) - y^{(i)})^2 \\ &= \sum_{i=1}^M (c_0 + c_1x^{(i)} - y^{(i)})^2 \end{aligned}$$

Use gradient descent to $\min_{c_0, c_1} L(c_0, c_1)$

Application for Minimizing Loss Function

- Step 1: Assign initial values for c_0, c_1 :

$$c_0 = 0, c_1 = 1$$

- Step 2: Update the change in values for c_0, c_1 :

$$c_0 := c_0 - \alpha \frac{\partial}{\partial c_0} L(c_0, c_1)$$

$$:= c_0 - \alpha \sum_{i=1}^M 2(c_0 + c_1 x^{(i)} - y^{(i)})$$

- Step 2: (continue)

$$\begin{aligned}c_1 &:= c_1 - \alpha \frac{\partial}{\partial c_1} L(c_0, c_1) \\&= c_1 - \alpha \sum_{i=1}^M 2x^{(i)}(c_0 + c_1 x^{(i)} - y^{(i)})\end{aligned}$$

- Step 3: Repeat Step 2 until it converges
- Logistic regression: do it similarly

Other Gradient Descent Methods

- **Stochastic gradient descent (SGD):**
- Herbert Robbins and Sutton Monro (1951)
- Good for **large/huge data sets**
 - 1) Choose an initial parameter set \mathbf{c} and learning rate α
 - 2) Randomly shuffle samples in the training set to update \mathbf{c}

$$\mathbf{c} := \mathbf{c} - \alpha \frac{\partial}{\partial \mathbf{c}} L(\mathbf{c}, \mathbf{x}^{(i)}, y^{(i)}), i = 1, 2, \dots, M$$

(Note: no sum over i)

- 3) Repeat 2) until the convergence is reached.

Other Gradient Descent Methods

- **SGD with momentum:** accelerate SGD

$$\begin{aligned} \mathbf{v} &:= \gamma \mathbf{v} + \alpha \frac{\partial}{\partial \mathbf{c}} L(\mathbf{c}, \mathbf{x}^{(i)}, y^{(i)}) \\ \mathbf{c} &:= \mathbf{c} - \mathbf{v} \end{aligned}$$

<https://distill.pub/2017/momentum/>

- Adaptive learning rates are often used.
- If multiple passes are needed, the data can be shuffled for each pass to prevent cycles.

Other Gradient Descent Methods

- A Method for Stochastic Optimization (Adam) by Kingma & Ba, 2015: An efficiency version of SGD using first and second order momentum, well suited for large data set problems
- Kalman-based Stochastic Gradient Descent: *SIAM Journal on Optimization*. **26** (4): 2620–2648.
[arXiv:1512.01139](https://arxiv.org/abs/1512.01139)

Other Gradient Descent Methods

High-order SGD

$$\mathbf{g} := \frac{\partial}{\partial \mathbf{c}} L(\mathbf{c}, \mathbf{x}^{(i)}, y^{(i)}) \quad (\text{Compute gradient})$$

$$\mathbf{m} := \beta_1 \mathbf{m} + (1 - \beta_1) \mathbf{g} \quad (\text{Update 1}^{\text{st}} \text{ order momentum})$$

$$\mathbf{v} := \beta_2 \mathbf{v} + (1 - \beta_2) \mathbf{g}^2 \quad (\text{Update 2}^{\text{nd}} \text{ order momentum})$$

$$\hat{\mathbf{m}} := \frac{\mathbf{m}}{\beta_1^k} \quad (\text{Compute corrected-1}^{\text{st}} \text{ order momentum})$$

$$\hat{\mathbf{v}} := \frac{\mathbf{v}}{\beta_2^k} \quad (\text{Compute corrected-2}^{\text{nd}} \text{ order momentum})$$

$$\mathbf{c} := \mathbf{c} - \alpha \frac{\hat{\mathbf{m}}}{\sqrt{\hat{\mathbf{v}}} + \epsilon} \quad (\text{Update parameters})$$

Other Gradient Descent Methods

Adaptive Gradient Descent

- Barzilai-Bowein method (for $L(\mathbf{c})$ convex and $\frac{\partial}{\partial \mathbf{c}} L(\mathbf{c})$ Lipschitz):

- $\mathbf{c}^n = \mathbf{c}^{n-1} - \alpha^n \frac{\partial}{\partial \mathbf{c}} L(\mathbf{c})$

$$\alpha^n = \frac{(\mathbf{c}^n - \mathbf{c}^{n-1})^T \left[\frac{\partial}{\partial \mathbf{c}} L(\mathbf{c}) \Big|_{\mathbf{c}=\mathbf{c}^n} - \frac{\partial}{\partial \mathbf{c}} L(\mathbf{c}) \Big|_{\mathbf{c}=\mathbf{c}^{n-1}} \right]}{\left\| \frac{\partial}{\partial \mathbf{c}} L(\mathbf{c}) \Big|_{\mathbf{c}=\mathbf{c}^n} - \frac{\partial}{\partial \mathbf{c}} L(\mathbf{c}) \Big|_{\mathbf{c}=\mathbf{c}^{n-1}} \right\|^2}$$

Convex \Rightarrow the global minimum!

Discussions

Other potential mathematical approaches:

Explicit Euler, implicit Euler, Crank–Nicholson, leapfrog, Gauss–Legendre Runge–Kutta, Gauss–Radau Runge–Kutta, Gauss–Lobatto Runge–Kutta, **symplectic** Runge–Kutta, Adams–Bashforth, Adams–Moulton, Strong stability preserving, hybrid multistep-multistage methods and adaptive SGD.

(<http://users.math.msu.edu/users/wei/paper/p175.pdf>)

Discussions

Pros and Cons of Gradient Descent

■ Pros

- Can be applied for any dimensional space
- Nonlinear problems
- Easy to implement

■ Cons:

- Local optima problem
- Slowly to reach the local minimum
- Cannot be applied for discontinuous functions

Discussions

- **Sample noise (uncertainty in $\{y^{(i)}\}$)**
- **Parameter linear dependence (in $\{c_i\}$)**
- **Manifold properties:**
 - **Smoothness -- differentiability**
 - **Convex/concave**
 - **Tangent bundle/cotangent bundle**
 - **Topological structure of the tangent space**
 - **...**

Discussions

Not to be confused with

- Method of steepest descent (for integrals)
- Conjugated gradient method