Medical Robotics

Rigid Body Kinematics

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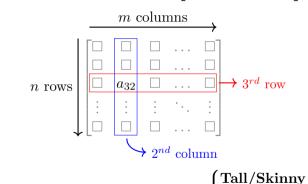
What is a rigid body?

 ${\bf Coming\ soon.}$

Mathematical Preliminary

Matrices

► Matrices are rectangular array of numbers. $\begin{vmatrix} 1.1 & -24 & \sqrt{2} \\ 0 & 1.12 & -5.24 \end{vmatrix}$



► Consider a matrix A with n rows and m columns. $\begin{cases} \textbf{Tall/Skinny} & n > m \\ \textbf{Square} & n = m \\ \textbf{Wide/Fat} & n < m \end{cases}$

 \triangleright n-vectors can be interpreted as $n \times 1$ matrices. These are called *column vectors*.

▶ A matrix with only one row is called a *row vector*, which can be referred to as n-row-vector. $\mathbf{x} = \begin{bmatrix} 1.45 & -3.1 & 12.4 \end{bmatrix}$

▶ Block matrices & Submatrices: $\mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{C} \\ \mathbf{D} & \mathbf{E} \end{bmatrix}$. What are the dimensions of the different matrices?

Matrices are also compact way to give a set of indexed column *n*-vectors, $\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3 \dots \mathbf{x}_m$.

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 & \mathbf{x}_3 & \dots & \mathbf{x}_m \end{bmatrix}$$

- ▶ Zero matrix= $\mathbf{0}_{n \times m} = \begin{bmatrix} 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{bmatrix}$
- ▶ **Identity matrix** is a square $n \times n$ matrix with all zero elements, except the diagonals where all elements are 1.

$$i_{mn} = \begin{cases} 1 & m = n \\ 0 & m \neq n \end{cases}$$
 $\mathbf{I}_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \mathbf{e}_3 \end{bmatrix}$

▶ **Diagonal matrices** is a square matrix with non-zero elements on its diagonal.

$$\begin{bmatrix} 0.4 & 0 & 0 & 0 \\ 0 & -11 & 0 & 0 \\ 0 & 0 & 21 & 0 \\ 0 & 0 & 0 & 9.3 \end{bmatrix} = \mathbf{diag} (0.4, -11, 21, 9.3)$$

▶ Triangular matrices: Are square matrices. Upper triangular $a_{ij} = 0, \forall i > j;$ Lower triangular $a_{ij} = 0, \forall i < j.$

Matrix operations: Transpose

▶ **Transpose** switches the rows and columns of a matrix. **A** is a $n \times m$ matrix, then its transpose is represented by \mathbf{A}^{\top} , which is a $m \times n$ matrix.

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix} \implies \mathbf{A}^{\top} = \begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \\ a_{13} & a_{23} \end{bmatrix}$$

Transpose converts between column and row vectors.

What is the transpose of a block matrix?
$$\mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{C} \\ \mathbf{D} & \mathbf{E} \end{bmatrix}$$

Matrix operations: Matrix Addition

▶ Matrix addition can only be carried out with matrices of same size. Like vectors we perform element wise addition.

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} + \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} \\ a_{21} + b_{21} & a_{22} + b_{22} \end{bmatrix}$$

- ▶ Properties of matrix addition:
 - ightharpoonup Commutative: $\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$
 - ightharpoonup Associative: $(\mathbf{A} + \mathbf{B}) + \mathbf{C} = \mathbf{A} + (\mathbf{B} + \mathbf{C})$
 - ightharpoonup Addition with zero matrix: $\mathbf{A} + \mathbf{0} = \mathbf{0} + \mathbf{A} = \mathbf{A}$
 - ightharpoonup Transpose of sum: $(\mathbf{A} + \mathbf{B})^{\top} = \mathbf{A}^{\top} + \mathbf{B}^{\top}$

Matrix operations: Scalar multiplication

▶ Scalar multiplication Each element of the matrix gets multiplied by the scalar.

$$\alpha \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = \begin{bmatrix} \alpha a_{11} & \alpha a_{12} \\ \alpha a_{21} & \alpha a_{22} \end{bmatrix}$$

We will mostly only deal with matrices with real entries. Such matrices are elements of the set $\mathbb{R}^{n \times m}$.

▶ Given the aforementioned matrix operations and their properties, is $\mathbb{R}^{n \times m}$ a vector space?

Matrix operations: Matrix multiplication

▶ A useful multiplication operation can be defined for matrices.

▶ It is possible to multiply two matrices $\mathbf{A} \in \mathbb{R}^{n \times p}$ and $\mathbf{B} \in \mathbb{R}^{p \times m}$ through this matrix multiplication procedure.

▶ The product matrix $\mathbf{C} := \mathbf{AB} \in \mathbb{R}^{n \times m}$, if the number of columns of \mathbf{A} is equal to the number of rows of \mathbf{B} .

$$c_{ij} := \sum_{k=1}^{p} a_{ik} b_{kj} \quad \forall i \in \{1, \dots n\} , j \in \{1 \dots m\}$$

Matrix multiplication

► Inner product is a special case of matrix multiplication between a row vector and a column vector.

$$\mathbf{x}^{\top}\mathbf{y} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}^{\top} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \sum_{i=1}^n x_i y_i$$

Matrix multiplication: Post-multiplication by a column vector

▶ Consider a matrix $\mathbf{A} \in \mathbb{R}^{n \times m}$ and a *m*-vector $\mathbf{x} \in \mathbb{R}^m$. We can multiply \mathbf{A} and \mathbf{x} to obtain $\mathbf{y} = \mathbf{A}\mathbf{x} \in \mathbb{R}^n$.

$$\mathbf{y} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & a_{22} & \dots & a_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nm} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^m a_{1i} x_i \\ \sum_{i=1}^m a_{2i} x_i \\ \vdots \\ \sum_{i=1}^m a_{ni} x_i \end{bmatrix} = \sum_{i=1}^m x_i \begin{bmatrix} a_{1i} \\ a_{2i} \\ \vdots \\ a_{ni} \end{bmatrix} = \sum_{i=1}^m x_i \mathbf{a}_i$$

ightharpoonup Post-multiplying a matrix **A** by a column vector **x** results in a linear combination of the columns of matrix **A**.

ightharpoonup x provides the column mixture.

Matrix multiplication: Pre-multiplication by a row vector

ightharpoonup Let $\mathbf{x}^{\top} \in \mathbb{R}^n$ and $\mathbf{A} \in \mathbb{R}^{n \times m}$, then $\mathbf{y} = \mathbf{x}^{\top} \mathbf{A}$.

$$\mathbf{y} = \begin{bmatrix} x_1 & \dots & x_n \end{bmatrix} \begin{bmatrix} a_{11} & \dots & a_{1m} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nm} \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^n x_i a_{i1} & \dots & \sum_{i=1}^n x_i a_{im} \end{bmatrix} = \sum_{i=1}^n x_i \tilde{\mathbf{a}}_i^\top$$

where,
$$\tilde{\mathbf{a}}_i^{\top} = \begin{bmatrix} a_{i1} & \dots & a_{im} \end{bmatrix}$$

- ightharpoonup Pre-multiplying a matrix **A** by a row vector **x** results in a linear combination of the rows of **A**.
- $\triangleright \mathbf{x}^{\top}$ provides the row mixture.

Matrix multiplication

▶ Multiplying two matrices $\mathbf{A} \in \mathbb{R}^{n \times p}$ and $\mathbf{B} \in \mathbb{R}^{p \times m}$ produces $\mathbf{C} \in \mathbb{R}^{n \times m}$,

$$\mathbf{C} = \mathbf{A}\mathbf{B} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1p} \\ a_{21} & a_{22} & \dots & a_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{np} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1m} \\ b_{21} & b_{22} & \dots & b_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ b_{p1} & b_{p2} & \dots & b_{pm} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \dots & c_{1m} \\ c_{21} & c_{22} & \dots & c_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ c_{p1} & c_{n2} & \dots & c_{nm} \end{bmatrix}$$

- ► Four interpretations of matrix multiplication.
 - 1. Inner-Product interpretation
 - 2. Column interpretation
 - 3. Row interpretation
 - 4. Outer product interpretation.

Matrix multiplication: Inner-product Interpretation

$$\mathbf{C} = \mathbf{AB}, \ \mathbf{A} \in \mathbb{R}^{n \times p}, \ \mathbf{B} \in \mathbb{R}^{p \times m}, \ \mathbf{C} \in \mathbb{R}^{n \times m}$$

▶ ij^{th} element of **C** is the inner product of the i^{th} row of **A** and the j^{th} column of **B**.

$$c_{ij} = \sum_{k=1}^{m} a_{ik} b_{kj} = \tilde{\mathbf{a}}_{i}^{\top} \mathbf{b}_{j}$$

where, $i \in \{1 \dots n\}, j \in \{1 \dots m\}$

Matrix multiplication: Column interpretation

$$\mathbf{C} = \mathbf{AB}, \ \mathbf{A} \in \mathbb{R}^{n \times p}, \ \mathbf{B} \in \mathbb{R}^{p \times m}, \ \mathbf{C} \in \mathbb{R}^{n \times m}$$

▶ Columns of **C** are the linear combinations of the columns of **A**.

$$\mathbf{C} = \mathbf{A} \begin{bmatrix} \mathbf{b}_1 & \mathbf{b}_2 & \dots & \mathbf{b}_m \end{bmatrix} = \begin{bmatrix} \mathbf{A}\mathbf{b}_1 & \mathbf{A}\mathbf{b}_2 & \dots & \mathbf{A}\mathbf{b}_m \end{bmatrix}$$

 \triangleright j^{th} column of **C** is the linear combination of the columns of **A**

$$\mathbf{c}_j = \sum_{k=1}^p b_{kj} \mathbf{a}_k$$

Matrix multiplication: Row interpretation

$$C = AB, A \in \mathbb{R}^{n \times p}, B \in \mathbb{R}^{p \times m}, C \in \mathbb{R}^{n \times m}$$

▶ Rows of **C** are the linear combinations of the rows of **B**.

$$\mathbf{C} = egin{bmatrix} ilde{\mathbf{a}}_1^{ op} \ ilde{\mathbf{a}}_2^{ op} \ \dots \ ilde{\mathbf{a}}_n^{ op} \end{bmatrix} \mathbf{B} = egin{bmatrix} ilde{\mathbf{a}}_1^{ op} \mathbf{B} \ ilde{\mathbf{a}}_2^{ op} \mathbf{B} \ \dots \ ilde{\mathbf{a}}_n^{ op} \mathbf{B} \end{bmatrix}$$

ightharpoonup ith row of C is the linear combination of the rows of B

$$\tilde{\mathbf{c}}_i^{\top} = \sum_{k=1}^p a_{ik} \tilde{\mathbf{b}}_k^{\top}$$

Matrix multiplication: Outer product interpretation

▶ Outer product: Product between a colum vector and a row vector. Let $\mathbf{x} \in \mathbb{R}^n$ and $\mathbf{y} \in \mathbb{R}^m$. The outer product is defined as,

$$\mathbf{x}\mathbf{y}^{\top} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \begin{bmatrix} y_1 & y_2 & \dots & y_m \end{bmatrix} = \begin{bmatrix} x_1y_1 & x_1y_2 & \dots & x_1y_m \\ x_2y_1 & x_2y_2 & \dots & x_2y_m \\ \vdots & \vdots & \ddots & \vdots \\ x_ny_1 & x_ny_2 & \dots & x_ny_m \end{bmatrix} \in \mathbb{R}^{n \times m}$$

Matrix multiplication: Outer product interpretation

$$\mathbf{C} = \mathbf{AB}, \ \mathbf{A} \in \mathbb{R}^{n \times p}, \ \mathbf{B} \in \mathbb{R}^{p \times m}, \ \mathbf{C} \in \mathbb{R}^{n \times m}$$

ightharpoonup C can be written as the sum of p outer products of columns of A and rows of B.

$$\mathbf{C} = \mathbf{A}\mathbf{B} = egin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \mathbf{a}_3 & \dots & \mathbf{a}_p \end{bmatrix} egin{bmatrix} \mathbf{b}_1^{\intercal} \ \mathbf{b}_2^{\intercal} \ \mathbf{b}_3^{\intercal} \ dots \ \mathbf{b}_{\intercal}^{\intercal} \end{bmatrix} = \sum_{i=1}^p \mathbf{a}_i \mathbf{b}_i^{\intercal}$$

Properties of matrix multiplication

- Not commutative: $AB \neq BA$ The product of two matrices might not always be defined. When it is defined, AB and BA need not match.
- ▶ Distributive: A(B+C) = AB + BC and (A+B)C = AC + BC
- $\qquad \textbf{Associative: } \mathbf{A}\left(\mathbf{BC}\right) = (\mathbf{AB})\,\mathbf{C}$
- ► Transpose: $(\mathbf{A}\mathbf{B})^{\top} = \mathbf{B}^{\top}\mathbf{A}^{\top}$
- ► Scalar product: $\alpha(AB) = (\alpha A)B = A(\alpha B)$



Linear transformations

▶ Linear functions $f: \mathbb{R}^m \to \mathbb{R}$,

$$y = f(\mathbf{x}) = \mathbf{w}^{\top} \mathbf{x}; \ \mathbf{w}, \mathbf{x} \in \mathbb{R}^m, \ y \in \mathbb{R}$$

 \blacktriangleright Generalization of the linear function is when its range \mathbb{R}^n :

$$\mathbf{y} = f(\mathbf{x}); \ \mathbf{x} \in \mathbb{R}^m, \ \mathbf{y} \in \mathbb{R}^n$$

▶ These can be represented as, $\mathbf{y} = \mathbf{A}\mathbf{x}$, $\mathbf{A} \in \mathbb{R}^{n \times m}$.

▶ Matrices can be thought of as representing a particular linear transformation.

Why does matrix multiplication have this strange definition?

Consider the following two functions,

$$\mathbf{y} = f\left(\mathbf{x}\right) = \mathbf{A}\mathbf{x} \longrightarrow \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = f\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} ax_1 + bx_2 \\ cx_1 + dx_2 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\mathbf{v} = g\left(\mathbf{u}\right) = \mathbf{B}\mathbf{u} \longrightarrow \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = g\left(\begin{bmatrix} u_1 \\ u_2 \end{bmatrix}\right) = \begin{bmatrix} \alpha u_1 + \beta u_2 \\ \gamma u_1 + \delta u_2 \end{bmatrix} = \begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$\mathbf{z} = h\left(\mathbf{u}\right) = f\left(g\left(\mathbf{u}\right)\right) = f\left(\begin{bmatrix} \alpha u_1 + \beta u_2 \\ \gamma u_1 + \delta u_2 \end{bmatrix}\right) = \begin{bmatrix} a\alpha u_1 + a\beta u_2 + b\gamma u_1 + b\delta u_2 \\ c\alpha u_1 + c\beta u_2 + d\gamma u_1 + d\delta u_2 \end{bmatrix}$$

$$= \begin{bmatrix} (a\alpha + b\gamma) u_1 + (a\beta + b\delta) u_2 \\ (c\alpha + d\gamma) u_1 + (c\beta + d\delta) u_2 \end{bmatrix} = \begin{bmatrix} a\alpha + b\gamma & a\beta + b\delta \\ c\alpha + d\gamma & c\beta + d\delta \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$\mathbf{z} = \mathbf{A} \left(\mathbf{B}\mathbf{u}\right) = (\mathbf{A}\mathbf{B}) \mathbf{u} \implies \mathbf{A}\mathbf{B} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} = \begin{bmatrix} a\alpha + b\gamma & a\beta + b\delta \\ c\alpha + d\gamma & c\beta + d\delta \end{bmatrix}$$

Matrix multiplication represents the composition of linear transformations.

Rank of a matrix A

▶ Rank of a matrix A: dimension of the subspace spanned by the columns of A or the rows of $A \in \mathbb{R}^{n \times m}$.

$$rank\left(\mathbf{A}\right) = \dim span\left(\left\{\mathbf{a}_{1}, \mathbf{a}_{2}, \dots \mathbf{a}_{m}\right\}\right) \rightarrow \text{Column rank}$$

$$= \dim span\left(\left\{\tilde{\mathbf{a}}_{1}^{\top}, \tilde{\mathbf{a}}_{2}^{\top}, \dots \tilde{\mathbf{a}}_{n}^{\top}\right\}\right) \rightarrow \text{Row rank}$$

- ▶ Column Rank is always equal to the row rank.
- ▶ Rank tells us the number of independent columns/row in the matrix.
- ► Full rank matrix A: rank(A) = min(n, m)Rank deficient matrix A: rank(A) < min(n, m)

Matrix Inverse

- Consider the square matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$. $\mathbf{B} \in \mathbb{R}^{n \times n}$ is the inverse of \mathbf{A} , if $\mathbf{A}\mathbf{B} = \mathbf{B}\mathbf{A} = \mathbf{I}_n$, and \mathbf{B} is represented as \mathbf{A}^{-1} .
- ▶ Not all matrices have inverses. A matrix with an inverse is called **non-singular**, otherwise it is called **singular**.
- \triangleright For a non-singular matrix \mathbf{A} , \mathbf{A}^{-1} is unique. \mathbf{A}^{-1} is both the left and right inverse.
- ightharpoonup A matrix **A** has an inverse, if and only if **A** is full rank, i.e. $rank(\mathbf{A}) = n$
- ightharpoonup $\mathbf{A}\mathbf{x} = \mathbf{b}$ can be solved as follows, $\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$. It is never solved like this in practice.
- ► Inverse of product of matrices, $(\mathbf{AB})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$.
- $(\mathbf{A}^{-1})^{-1} = \mathbf{A} \text{ and } (\mathbf{A}^{-1})^{\top} = (\mathbf{A}^{\top})^{-1}$

Representation of vectors in a basis

▶ Consider the vector space \mathbb{R}^n with basis $\{\mathbf{v}_1, \mathbf{v}_2, \dots \mathbf{v}_n\}$. Any vector in $\mathbf{b} \in \mathbb{R}^n$ can be representated as a linear combination of \mathbf{v}_i s,

$$\mathbf{b} = \sum_{i=1}^{n} \mathbf{v}_{i} \mathbf{a}_{i} = \mathbf{V} \mathbf{a}; \ \mathbf{a} \in \mathbb{R}^{n}, \ \mathbf{V} = \begin{bmatrix} \mathbf{v}_{1} & \mathbf{v}_{2} & \cdots & \mathbf{v}_{n} \end{bmatrix} \in \mathbb{R}^{n \times n}$$



 $\{\mathbf{v}_1, \mathbf{v}_2\}$, $\{\mathbf{u}_1, \mathbf{u}_2\}$ and $\{\mathbf{e}_1, \mathbf{e}_2\}$ are valid basis for \mathbb{R}^2 , and the presentation for **b** in each one of them is different.

Matrix Inverse

- ▶ Consider the equation $\mathbf{A}\mathbf{x} = \mathbf{y}$, where $\mathbf{A} \in \mathbb{R}^{n \times n}$ and $\mathbf{x}, \mathbf{y} \in mbR^n$.
- ▶ Assume **A** is non-singular \implies columns of **A**, $\{\mathbf{a}_1, \mathbf{a}_2, \cdots \mathbf{a}_n\}$, represent a basis for \mathbb{R}^n .
- ightharpoonup Then **x** represents **y** in the basis consisiting of the columns of **A**.

$$\mathbf{y} = \mathbf{A}\mathbf{x} = \sum_{i=1}^{n} \mathbf{a}_{i} x_{i} \implies \mathbf{x} = \mathbf{A}^{-1}\mathbf{y} = \begin{bmatrix} \tilde{\mathbf{b}}_{1}^{\top} \\ \tilde{\mathbf{b}}_{2}^{\top} \\ \vdots \\ \tilde{\mathbf{b}}_{n}^{\top} \end{bmatrix} \mathbf{y} = \begin{bmatrix} \tilde{\mathbf{b}}_{1}^{\top} \mathbf{y} \\ \tilde{\mathbf{b}}_{2}^{\top} \mathbf{y} \\ \vdots \\ \tilde{\mathbf{b}}_{n}^{\top} \mathbf{y} \end{bmatrix}$$

 $ightharpoonup A^{-1}$ is the matrix that allows change of basis to the columns of **A** from the standard basis!

Some more definitions and conventions