## Introduction to DSP: Systems & LTI Systems - Tutorial

1. Consider the following discrte-time signal,

$$x[n] = \begin{cases} -2, & n = -2 \\ 0, & n = -1 \\ 1, & n = 0 \\ 3, & n = 1 \\ -1, & n = 2 \\ 1, & n = 0 \\ 0, & \text{Otherwise} \end{cases}$$

Compute the followint signals.

(a) 
$$x[-n] = 1$$

(b) 
$$x[n+3] = 1$$

(c) 
$$x[-n+1]$$

(d) 
$$x[-n-2]$$

2. Find if the following systems satisfy the properties of linearity, time-invariance, causality, and stability. Compute the impulse response of the systems that are linear and time-invariant.

(a) 
$$y[n] = \sum_{k=0}^{\infty} x[n-k]$$

(b) 
$$y[n] = \sum_{k=-3}^{2} x[n+k] \cdot x[n-k]$$

(c) 
$$y[n] = y[n-1] + 0.1 \cdot x[n]$$

(d) 
$$y[n] = n \cdot x[n] + (n-1) \cdot x[n-1]$$

3. Compute of the output an LTI system with the following impulse response

$$h[n] = \begin{cases} 0, & n < 0 \\ 3, & n = 0 \\ 2, & n = 1 \\ 1, & n = 2 \\ 0, & n > 2 \end{cases}$$

(a)  $x[n] = \delta[n] + \delta[n-3]$ 

(b) 
$$x[n] = u[n]$$

(c)  $x[n] = \sin(0.5\pi n) u[n]$ 

(d) 
$$x[n] = 1, \forall n$$

(e) 
$$x[n] = (0.5)^n, \forall n$$

(f) 
$$x[n] = (0.5)^n u[n], \forall n$$

4. Find the zero state response, zero input response, homogenous, and particular solutions for the following system,

$$y[n] = -\frac{1}{3}y[n-1] + \frac{1}{2}(x[n] + x[n-1]); \ y[-1] = 2$$

for the input x[n] = u[n].

What is the impulse response of the system?