# Linear Systems Positive Definiteness and Matrix Norm

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## Positive definite matrices

▶ We know that  $\mathbf{x}^T\mathbf{x} > 0$  for all  $\mathbf{x} \in \mathbb{R}^n$  and  $\mathbf{x} \neq \mathbf{0}$ .

- ▶ What can we say about  $\mathbf{x}^T \mathbf{A} \mathbf{x}$ , where  $\mathbf{A} \in \mathbb{R}^{n \times n}$ ?
  - ▶ Is it positive for all  $\mathbf{x} \neq \mathbf{0}$ ?  $\mathbf{I}$ ,  $\begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$
  - ► Can it be zero for some  $\mathbf{x} \neq \mathbf{0}$ ?  $\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$

► Can it be negative some  $\mathbf{x} \neq \mathbf{0}$ ?  $\begin{bmatrix} -2 & 0 \\ 0 & -1 \end{bmatrix}$ ,  $\begin{bmatrix} 1 & -4 \\ -4 & 1 \end{bmatrix}$ 

## Positive definite matrices

Any matrix **A** for which  $\mathbf{x}^T \mathbf{A} \mathbf{x} > 0$ , for all  $\mathbf{x} \neq \mathbf{0}$  is called a *positive definite matrix*.

Positive definite matrices are very useful and are commonly encountered in practice: optimization, mechanics (mass matrix, stiffness matrix), stability analysis, co-variance matrices etc. Are the following matrices positive definite?  $\begin{bmatrix} 2 & -6 \\ 2 & 1 \end{bmatrix}$ ,  $\begin{bmatrix} 5 & -1 \\ 14 & 11 \end{bmatrix}$ 

The idea of positive definiteness is intimately related to the problem of minimization of a function.

Consider the following function of a single variable f(x). This function reaches a minimum at x=0, when  $\frac{df(x)}{dx}\big|_{x=0}=0$  and  $\frac{d^2f(x)}{dx^2}\big|_{x=0}>0$ . E.g.,

$$f(x) = 3x^2 \to \frac{df(x)}{dx}\Big|_{x=0} = 0, \frac{d^2f(x)}{dx^2}\Big|_{x=0} = 3 > 0$$

What about  $f(x_1, x_2) = ax_1^2 + 2bx_1x_2 + cx_2^2$ ? We can extend the previous idea using partial derivatives.

$$\frac{\partial f(x_1, x_2)}{\partial x_1} = 0, \ \frac{\partial f(x_1, x_2)}{\partial x_2} = 0, \ \frac{\partial^2 f(x_1, x_2)}{\partial x_1^2} > 0, \ \frac{\partial^2 f(x_1, x_2)}{\partial x_2^2} > 0$$

Is this enough?  $\frac{\partial^2 f(x_1,x_2)}{\partial x_1 \partial x_2}$  must also be taken into account.

Are these functions positive for all  $x_1, x_2$ ? 1)  $x_1^2 + x_1x_2 + x_2^2$ , 2)  $x_1^2 + 2x_1x_2 + x_2^2$ , 3)  $x_1^2 + 3x_1x_2 + x_2^2$ ?

▶ We can rearrange  $ax_1^2 + 2bx_1x_2 + cx_2^2$  in the following manner,

$$f(x_1, x_2) = ax_1^2 + 2bx_1x_2 + cx_2^2 = a\left(x_1 + \frac{b}{a}x_2\right)^2 + \left(c - \frac{b^2}{a}\right)x_2^2$$

 $f\left(\bullet\right)>0, \forall x_{1},x_{2}\neq0$  when,

$$a>0$$
 and  $c-\frac{b^2}{a}>0 \implies ac>b^2$ 

$$\frac{\partial^{2} f\left(x_{1}, x_{2}\right)}{\partial x_{1}^{2}} > 0 \quad \text{and} \quad \frac{\partial^{2} f\left(x_{1}, x_{2}\right)}{\partial x_{1}^{2}} \frac{\partial^{2} f\left(x_{1}, x_{2}\right)}{\partial x_{2}^{2}} > \left(\frac{\partial^{2} f\left(x_{1}, x_{2}\right)}{\partial x_{1} \partial x_{2}}\right)^{2}$$

▶ Verfy this on the following functions: 1)  $x_1^2 + x_1x_2 + x_2^2$ , 2)  $x_1^2 + 2x_1x_2 + x_2^2$ , 3)  $x_1^2 + 3x_1x_2 + x_2^2$ 

 $f(\bullet)$  can be expressed as  $\mathbf{x}^T \mathbf{A} \mathbf{x}$ , where  $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ , and  $\mathbf{A} = \begin{bmatrix} a & b \\ b & c \end{bmatrix}$ .  $f(\mathbf{x}) > 0$  for all  $\mathbf{x} \neq \mathbf{0}$ , when  $\mathbf{A}$  is positive definite.

 $\mathbf{x}^T \mathbf{A} \mathbf{x}$  is called a *quadratic form*. For a symmetric matrix  $\mathbf{A}$ ,

$$\mathbf{x}^{T}\mathbf{A}\mathbf{x} = \begin{bmatrix} x_{1} & x_{2} & \dots & x_{n} \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{12} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1n} & a_{2n} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{n} \end{bmatrix} = \sum_{i=1}^{n} a_{ii}x_{i}^{2} + 2\sum_{i=1}^{n} \sum_{j=1, j \neq i}^{n} a_{ij}x_{i}x_{j}$$

In general,  $\mathbf{A} \in \mathbb{R}^{n \times n}$  is positive definite, if:

- ▶ The eigenvalues of **A** are all positive.
- ▶ The pivots (without row exchange) are all positive.

Show that any A is positive definite if the symmetric matrix  $A + A^T$  is positive definite. Note: This should explain why we have only been talking about symmetric matrices.

### Matrix Norm

Since matrices also form vector spaces, we can talk about norms of matrices, which extent the idea of sizes and distances to spaces of matrices.

If we think of matrices a set of mn scalars, then we can use the same approach as vectors,

$$\|\mathbf{A}\|_F = \left(\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2\right)^{\frac{1}{2}}$$

This is called the *Frobinius norm*.

#### Matrix Norm

- ► There are other norms defined for matrices that are very useful from the point of the view of linear transformation.
- ► These are called *induced matrix norms*, that looks at how matrices map vectors from the range to domain spaces.
- Let  $\mathbf{A} \in \mathbb{R}^{m \times n} : \mathbb{R}^n \to \mathbb{R}^m$ , and  $\mathbf{x} \in \mathbb{R}^n$ ,  $\mathbf{y} \in \mathbb{R}^m$

$$\|\mathbf{y}\| = \|\mathbf{A}\mathbf{x}\| \le C \|\mathbf{x}\|, \ \forall \mathbf{x} \in \mathbb{R}^n, \ C \ge 0$$

C is the maximum factor by which A amplifies the vector x.

▶ The induced norm of a matrix is defined as,

$$\|\mathbf{A}\|_p = \max_{\mathbf{x}} \frac{\|\mathbf{A}\mathbf{x}\|_p}{\|\mathbf{x}\|_p} = \max_{\|\mathbf{x}\|_p = 1} \|\mathbf{A}\mathbf{x}\|_p$$

#### Matrix Norm

Consider a matrix 
$$\mathbf{A} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 \end{bmatrix} = \begin{bmatrix} \tilde{\mathbf{a}}_1^T \\ \tilde{\mathbf{a}}_2^T \end{bmatrix}$$
.

$$\|\mathbf{A}\|_1 = \max_i \|\mathbf{a}_i\|_1$$

$$\left\| \mathbf{A} \right\|_2 = \sqrt{\lambda_{\max}}$$

$$\|\mathbf{A}\|_{\infty} = \max_{i} \|\tilde{\mathbf{a}}_{i}\|_{1}$$





