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clear;
close all;

% Load mock data
load('mockdata2023.mat');

% Number of Days being examined
days = 1:400;

% Day the pattern changes: vaccine break
phase_change_day = 122;

% Day the pattern stabilizes
stabilization_day = 244;

% Find the cumulative number of infections
cumulative_infections = cumsum(newInfections);

% SIRDV Model: 5x5 matrix - placeholders for vaccine parameters
x_t = [0.75 0.10 0.10 0.05 0.01];

% Vaccinated and Vaccine-Break values.
vaccinated = 0.01;
vaccine_break = 0.001;

% Adjusted A matrix to include vaccinated and vaccine_break
A_phase1 = [.98889      0      .3  0      0;
            .0011      .8      0  0 vaccine_break;
            0          .1999  .7  0      0;
            .00001     .0001  0  1      0;
            vaccinated  0      0  0 1-vaccine_break];

A_phase2 = [.9      0.04      .3      0      0;
            .06      .7      0      0 vaccine_break;
            0          .1      .7      0      0;
            0          .00001  0      1      0;
            vaccinated  0      0      0 1-vaccine_break];

% Phase 3 where infections and deaths level out
A_phase3 = eye(5);

% initial condition:
x0 = [1; 0; 0; 0; 0];

% Make System for Phase 1
sys_phase1 = ss(A_phase1, [], [], [], 1); % Ts = 1

% Simulate Phase 1
[Y1, T1, X1] = lsim(sys_phase1, [], days(1:phase_change_day), x0);

% Last state of phase 1 is initial condition for phase 2
x0_phase2 = X1(end, :);

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% Make System for Phase 2
sys_phase2 = ss(A_phase2, [], [], [], 1);

% Simulate Phase 2
[Y2, T2, X2] = lsim(sys_phase2, [], days(phase_change_day
+1:stabilization_day), x0_phase2);

% Combine Phase 1 and Phase 2
X_combined = [X1; X2];
vaxpop(1:244) = X_combined(1:244, 5);
vaxbreak(1:244) = X_combined(1:244, 2);

% Plot Simulations
figure;
plot(days, cumulativeDeaths, 'r', 'LineWidth', 1);
hold on;
plot(days, cumulative_infections, 'b', 'LineWidth', 1);
A= length(cumsum(X_combined(:,2)));
B= length(cumsum(X_combined(:,4)));
disp(A);
disp(B);

days2 = 1:244;
plot(days2, cumsum(X_combined(:,2)), 'g--', 'LineWidth', 1); % Infected
plot(days2, cumsum(X_combined(:,4)), 'k--', 'LineWidth', 1); % Deceased

days3=245:400;

% Last state of phase 1 is initial condition for phase 2
x0_phase3 = [0; 1.9 ; 0 ;.1507; 0];

% Make System for Phase 2
sys_phase3 = ss(A_phase3, [], [], [], 1);

% Simulate Phase 2
[Y3, T3, X3] = lsim(sys_phase3, [], days(stabilization_day+1:end), x0_phase3);

% Combine Phase 1 and Phase 2
X_combined = X3;

plot(days3, X_combined(:,2), 'g--', 'LineWidth', 1); % Infected
plot(days3, X_combined(:,4), 'k--', 'LineWidth', 1); % Deceased

hold off;

xlabel('Days');

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ylabel('Cumulative Counts');
title('Cumulative Deaths and Infections Over Time');
legend('Cumulative Deaths from mock data', 'Cumulative Infections from mock data', 'Model Infected', 'Model Deceased', 'Location', 'northwest');
grid on;

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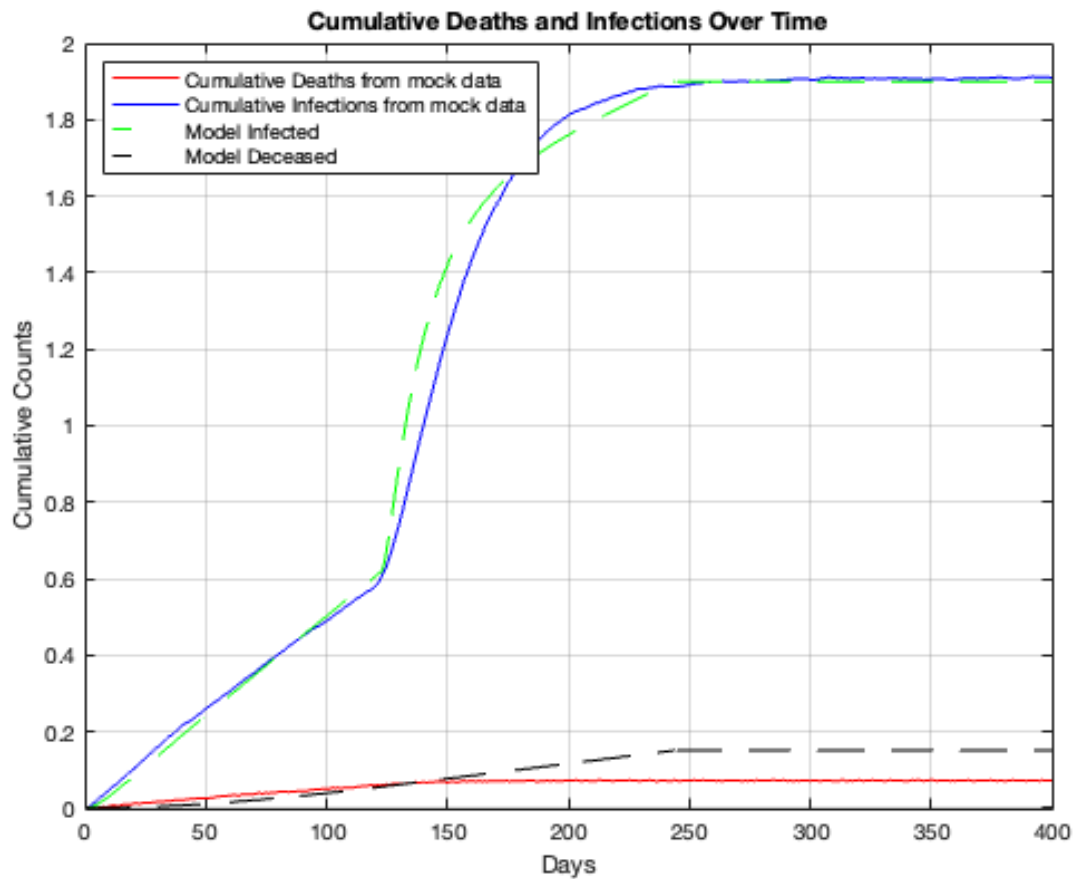
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vaxpop(244:365) = X_combined(1:122, 5);
vaxbreak(244:365) = X3(1:122, 2);
save competition vaxpop vaxbreak

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244

244



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