1. We build a computer, where the real numbers are represented using 5 digits as explained below:

S	A	В	С	E
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where

- S is the sign bit; 0 for positive and 1 for negative
- A,B,C: First three significant digits in decimal expansion with the decimal point occurring between A and B
- E is the exponent in base 10 with a bias of 5
- All digits after the third significant digit are chopped off
- +0 is represented by setting S=0 and A=0 (B,C,E) can be anything
- -0 is represented by setting S=1 and A=0 (B,C,E) can be anything
- $+\infty$ is represented by S=0, A=B=C=E=9
- $-\infty$ is represented by S=1, A=B=C=E=9
- Not A Number is represented by setting S other than 0 and 1.

For example, the number $\pi = 3.14159...$ is represented as follows. Chopping off after the third significant digit, we have $\pi = +3.14 \times 10^0$. Hence, the representation of π in our system is:



The number -0.001259 is represented as follows. Chopping off after the third significant digit, we have the number as -1.25×10^{-3} . Hence, the representation in our system is:

1	1	9	۲ .	9
1	1)	

Answer the following questions:

- (a) How many non-zero floating point numbers (from now on abbreviated as FPN) can be represented by our machine (both positive and negative)?
- (b) How many FPNs are in the following intervals?
 - (9, 10)
 - (10, 11)
 - (0, 1)
- (c) Identify the smallest positive and largest positive FPN on this machine.
- (d) Identify the machine precision.
- (e) What is the smallest positive integer not representable exactly on this machine?
- (f) Consider the recurrence:

$$a_{n+1} = 5a_n - 4a_{n-1}$$

with $a_1 = a_2 = 2.93$. Note that $a_1, a_2, 5$ and 4 are exactly represented on our machine. Compute a_n for $n \in \{3, 4, ..., 10\}$ in our machine (Work out the values by hand). Note that at each step in the recurrence $5a_n$ and $4a_{n-1}$ will be both chopped down to the first three significant digits before the subtraction is performed.

2. Consider the following integral:

$$I_n = \int_0^1 x^{2n} \sin(\pi x) \, dx$$

- Obtain a recurrence relation for I_n in terms of I_{n-1} . (HINT: Integration by parts).
- Evaluate I_0 .

- Use the recurrence above to obtain I_n for $n \in \{1, 2, 3, \dots, 15\}$ in Python.
- Use the built-in quadrature function in Python to obtain I_n for $n \in \{1, 2, 3, \dots, 15\}$.
- Explain your observation.
- Rewrite the equations in matrix form, i.e.,

$$Ay = b$$

- Plot the condition number of the matrix A as a function of n.
- Comment on how the condition number scales with n.
- ullet Comment on the relationship of the condition number and accuracy of the solution I_n obtained.
- 3. Show that if the parabolic run-out conditions are used for the cubic spline interpolation, then the interpolating polynomials in the first and last intervals are indeed parabolas.
- 4. A slightly easier spline interpolation is the so-called quadratic spline. Interpolation is carried out by piecewise quadratics.
 - What are the suitable joint conditions for quadratic spline?
 - Show how the coefficients of this spline are obtained.
 - What are the suitable end conditions?
 - Compare the required computational efforts for quadratic and cubic spline.
 - Write a Python code for interpolating the Runge function $f(x) = \frac{1}{1 + 25x^2}$ at equi-spaced nodes using a quadratic spline.