Avl tree-insertion,deletion:

```
#include<conio.h>
#include<stdio.h>
#include<stdlib.h>
typedef struct node
{  int data;
   struct node *left,*right;
   int ht;
}node;
  node *insert(node *,int);
  node *Delete(node *,int);
  void  preorder(node *);
  void  inorder(node *);
  int   height( node *);
  node *rotateright(node *);
  node *rotateleft(node *);
  node *RR(node *);
  node *LL(node *);
  node *LR(node *);
  node *RL(node *);
  int BF(node *);

int main()
{
    node *root=NULL;
    int x,n,i,op;
    do
       {
          printf("\n");
          printf("\n1) Create the AVL Tree");
```

```
printf("\n2) Insert Element into the AVL Tree");
printf("\n3) Delete Element from the AVL Tree ");
printf("\n4) Print the AVL Tree");
printf("\n5) Quit");
printf("\nEnter Your Choice: ");
scanf("%d",&op);
switch(op)
  {
  case 1:printf("\nEnter Total Number of Elements in the AVL Tree: ");
       scanf("%d",&n);
       printf("\n Enter AVL Tree Elements: ");
       root=NULL;
       for(i=0;i<n;i++)
       {
        scanf("%d",&x);
        root=insert(root,x);
       }
       break;
  case 2:printf("\nEnter a Element to Insert in the AVL Tree: ");
       scanf("%d",&x);
       root=insert(root,x);
       break;
  case 3:printf("\nEnter a Element to Delete from the AVL Tree: ");
       scanf("%d",&x);
       root=Delete(root,x);
       break;
  case 4:   printf("\nPreorder Sequence of the AVL Tree:\n");
     preorder(root);
     printf("\nInorder sequence of the AVL Tree:\n");
     inorder(root);
     break;
```

```
            }
    }while(op!=5);
}

node * insert(node *T,int x)
{
    if(T==NULL)
    {
        T=(node*)malloc(sizeof(node));
        T->data=x;
        T->left=NULL;
        T->right=NULL;
    }
    else
        if(x > T->data)
        {
            T->right=insert(T->right,x);
            if(BF(T)==-2)
                if(x>T->right->data)
                    T=RR(T);
                else
                    T=RL(T);
        }
        else
            if(x<T->data)
            {
                T->left=insert(T->left,x);
                if(BF(T)==2)
                    if(x < T->left->data)
                        T=LL(T);
                    else
```

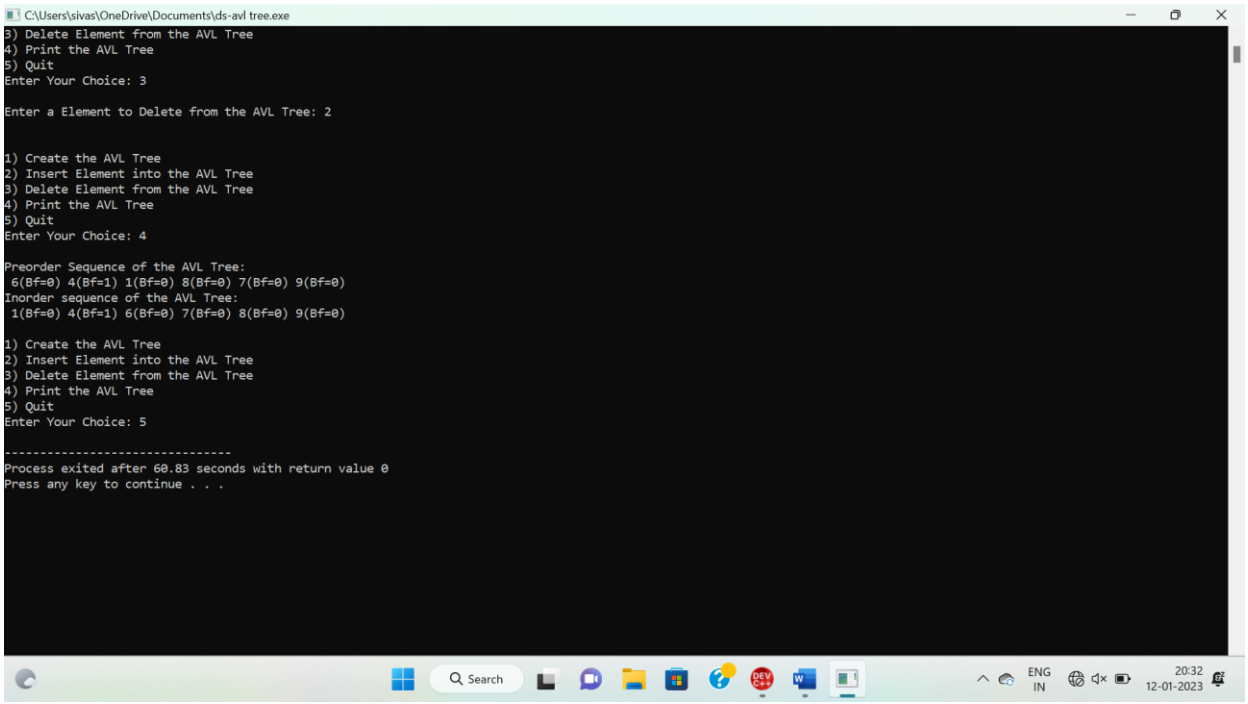
```
                T=LR(T);
        }
        T->ht=height(T);
        return(T);
}

node * Delete(node *T,int x)
{    node *p;

   if(T==NULL)
   {
      return NULL;
   }
   else

      if(x > T->data)
      {
         T->right=Delete(T->right,x);
         if(BF(T)==2)
            if(BF(T->left)>=0)
               T=LL(T);
            else
               T=LR(T);
      }
      else
         if(x<T->data)
            {
               T->left=Delete(T->left,x);
               if(BF(T)==-2)
                  if(BF(T->right)<=0)
                     T=RR(T);
```

```
                else
                    T=RL(T);
             }
          else
           {
              if(T->right !=NULL)
              {
                 p=T->right;
                 while(p->left != NULL)
                 p=p->left;

                 T->data=p->data;
                 T->right=Delete(T->right,p->data);
                 if(BF(T)==2)
                  if(BF(T->left)>=0)
                     T=LL(T);
                  else
                     T=LR(T);
               }
              else
               return(T->left);

          }
   T->ht=height(T);
   return(T);
}
int height(node *T)
{
   int lh,rh;
   if(T==NULL)
      return(0);
```

```
    if(T->left==NULL)
       lh=0;
    else
       lh=1+T->left->ht;
    if(T->right==NULL)
       rh=0;
    else
       rh=1+T->right->ht;
    if(lh>rh)
       return(lh);
    return(rh);
}
node * rotateright(node *x)
{
    node *y;
    y=x->left;
    x->left=y->right;
    y->right=x;
    x->ht=height(x);
    y->ht=height(y);
    return(y);
}
node * rotateleft(node *x)
{
    node *y;
    y=x->right;
    x->right=y->left;
    y->left=x;
    x->ht=height(x);
    y->ht=height(y);
    return(y);
```

```
}
node * RR(node *T)
{
   T=rotateleft(T);
   return(T);
}
node * LL(node *T)
{
   T=rotateright(T);
   return(T);
}
node * LR(node *T)
{
   T->left=rotateleft(T->left);
   T=rotateright(T);
   return(T);
}
node * RL(node *T)
{
   T->right=rotateright(T->right);
   T=rotateleft(T);
   return(T);
}
int BF(node *T)
{
   int lh,rh;
   if(T==NULL)
   return(0);
   if(T->left==NULL)
      lh=0;
   else
```

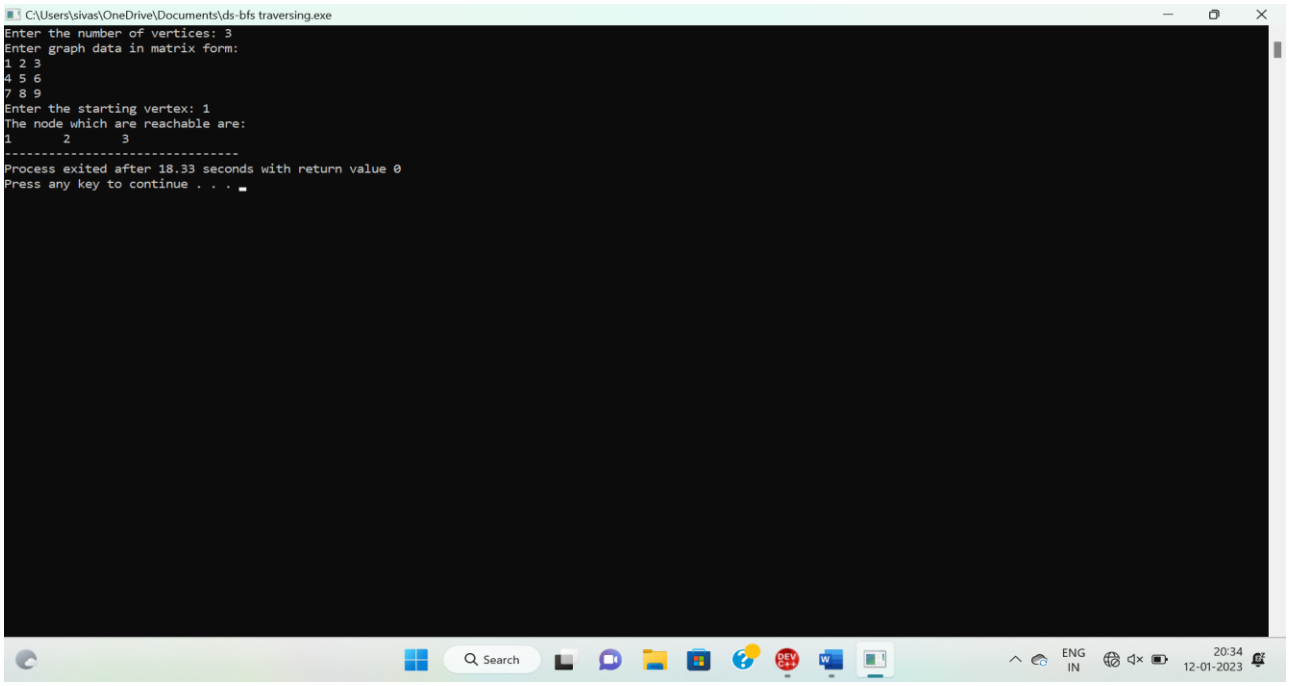
```
    lh=1+T->left->ht;
  if(T->right==NULL)
    rh=0;
  else
    rh=1+T->right->ht;
  return(lh-rh);
}

void preorder(node *T)
{
  if(T!=NULL)
  {
    printf(" %d(Bf=%d)",T->data,BF(T));
    preorder(T->left);
    preorder(T->right);
  }
}
void inorder(node *T)
{
  if(T!=NULL)
  {
    inorder(T->left);
    printf(" %d(Bf=%d)",T->data,BF(T));
    inorder(T->right);
  }
}
```



Bfs traversing:

```
#include <stdio.h>

int n, i, j, visited[10], queue[10], front = -1, rear = -1;

int adj[10][10];


void bfs(int v)

{

   for (i = 1; i <= n; i++)

      if (adj[v][i] && !visited[i])

         queue[++rear] = i;

   if (front <= rear)

   {

      visited[queue[front]] = 1;

      bfs(queue[front++]);

   }

}

int main()

{
```

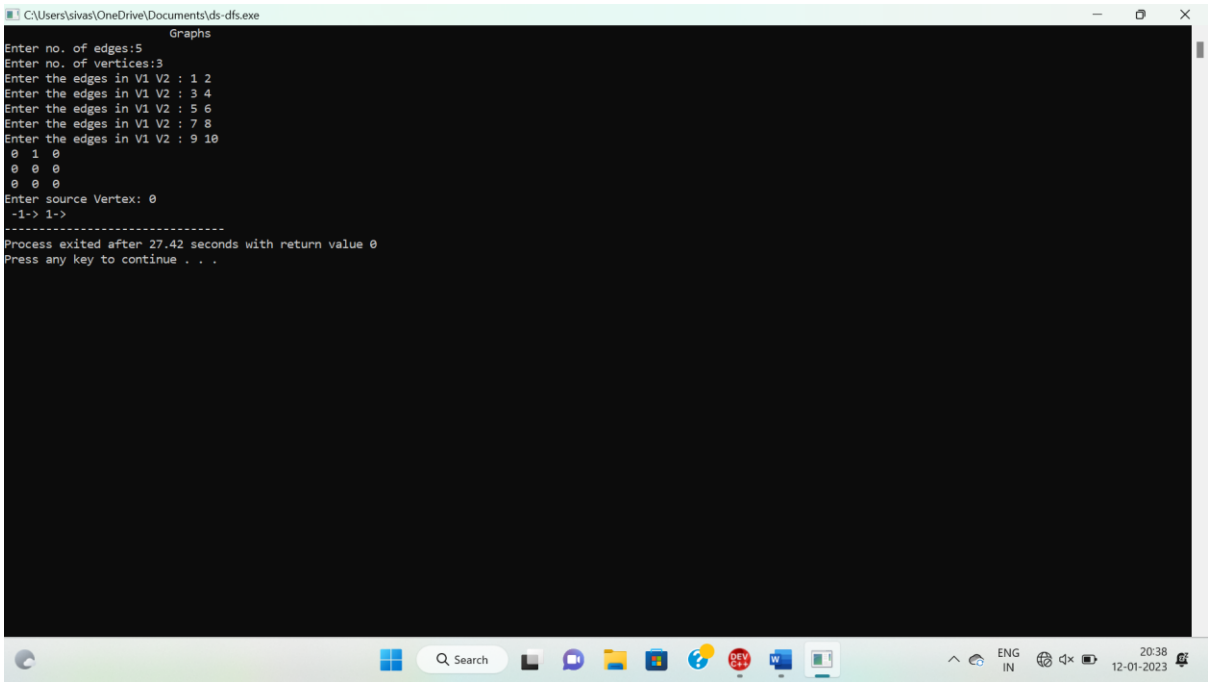
```
    int v;
    printf("Enter the number of vertices: ");
    scanf("%d", &n);
    for (i = 1; i <= n; i++)
    {
        queue[i] = 0;
        visited[i] = 0;
    }
    printf("Enter graph data in matrix form:    \n");
    for (i = 1; i <= n; i++)
        for (j = 1; j <= n; j++)
            scanf("%d", &adj[i][j]);
    printf("Enter the starting vertex: ");
    scanf("%d", &v);
    bfs(v);
    printf("The node which are reachable are:    \n");
    for (i = 1; i <= n; i++)
        if (visited[i])
            printf("%d\t", i);
        else
            printf("BFS is not possible. Not all nodes are reachable");
    return 0;
}
```



Dfs traversing:

```
#include <stdio.h>

#include <stdlib.h>

int sourceV,Vertex,Edge,time,visited[10],Graph[10][10];

void DepthFirstSearch(int i)

{

int j;

visited[i]=1;

printf(" %d->",i++);

for(j=0;j<Vertex;j++)

{

if(Graph[i][j]==1&&visited[j]==0)

DepthFirstSearch(j);

}

}

int main()

{

int i,j,vertex1,vertex2;

printf("\t\t\tGraphs\n");
```

```
printf("Enter no. of edges:");
scanf("%d",&Edge);
printf("Enter no. of vertices:");
scanf("%d",&Vertex);
for(i=0;i<Vertex;i++)
{
for(j=0;j<Vertex;j++)
Graph[i][j]=0;
}
for(i=0;i<Edge;i++)
{
printf("Enter the edges in V1 V2 : ");
scanf("%d%d",&vertex1,&vertex2);
Graph[vertex1-1][vertex2-1]=1;
}
for(i=0;i<Vertex;i++)
{
for(j=0;j<Vertex;j++)
printf(" %d ",Graph[i][j]);
printf("\n");
}
printf("Enter source Vertex: ");
scanf("%d",&sourceV);
DepthFirstSearch(sourceV-1);
return 0;
}
```

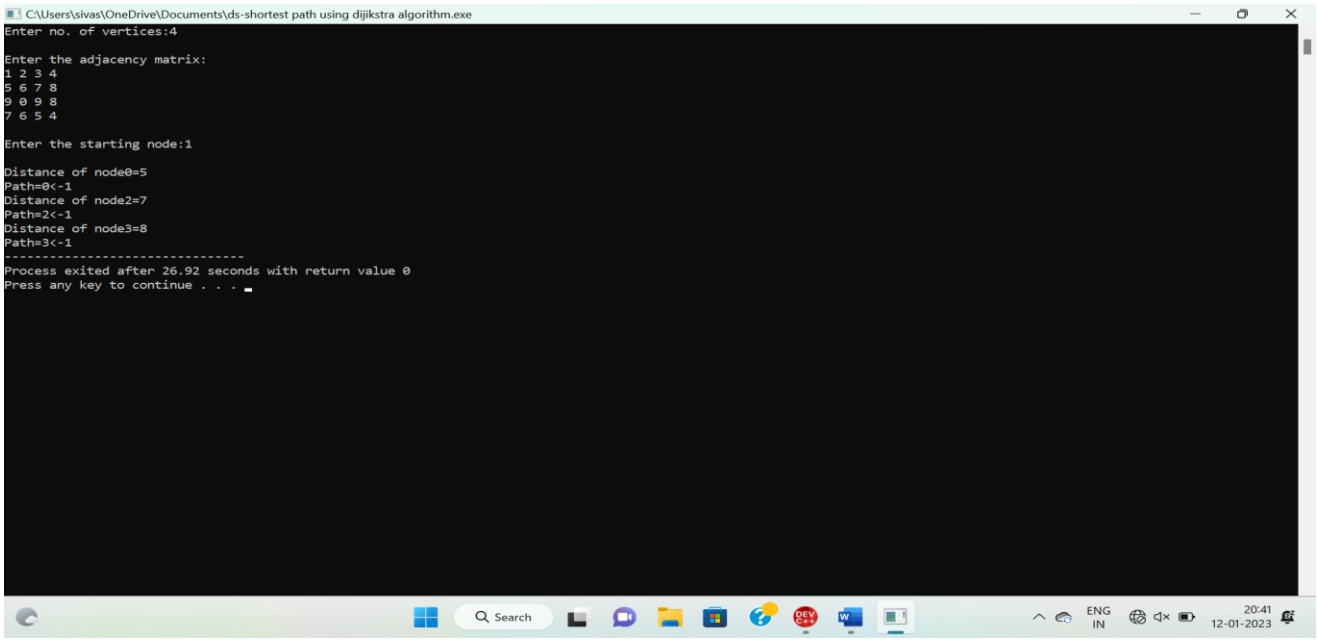


Shortest path using dijkstra algorithm:

```
#include<stdio.h>

#include<conio.h>

#define INFINITY 9999

#define MAX 10

void dijkstra(int G[MAX][MAX],int n,int startnode);

int main()

{

int G[MAX][MAX],i,j,n,u;

printf("Enter no. of vertices:");

scanf("%d",&n);

printf("\nEnter the adjacency matrix:\n");

for(i=0;i<n;i++)

for(j=0;j<n;j++)

scanf("%d",&G[i][j]);

printf("\nEnter the starting node:");

scanf("%d",&u);
```

```
dijkstra(G,n,u);
return 0;
}
void dijkstra(int G[MAX][MAX],int n,int startnode)
{
int cost[MAX][MAX],distance[MAX],pred[MAX];
int visited[MAX],count,mindistance,nextnode,i,j;
for(i=0;i<n;i++)
for(j=0;j<n;j++)
if(G[i][j]==0)
cost[i][j]=INFINITY;
else
cost[i][j]=G[i][j];
for(i=0;i<n;i++)
{
distance[i]=cost[startnode][i];
pred[i]=startnode;
visited[i]=0;
}
distance[startnode]=0;
visited[startnode]=1;
count=1;
while(count<n-1)
{
mindistance=INFINITY;
for(i=0;i<n;i++)
if(distance[i]<mindistance&&!visited[i])
{
mindistance=distance[i];
nextnode=i;
}
```

```
visited[nextnode]=1;
for(i=0;i<n;i++)
if(!visited[i])
if(mindistance+cost[nextnode][i]<distance[i])
{
distance[i]=mindistance+cost[nextnode][i];
pred[i]=nextnode;
}
count++;
}
for(i=0;i<n;i++)
if(i!=startnode)
{
printf("\nDistance of node%d=%d",i,distance[i]);
printf("\nPath=%d",i);
j=i;
do
{
j=pred[j];
printf("<-%d",j);
}while(j!=startnode);
}
}
```

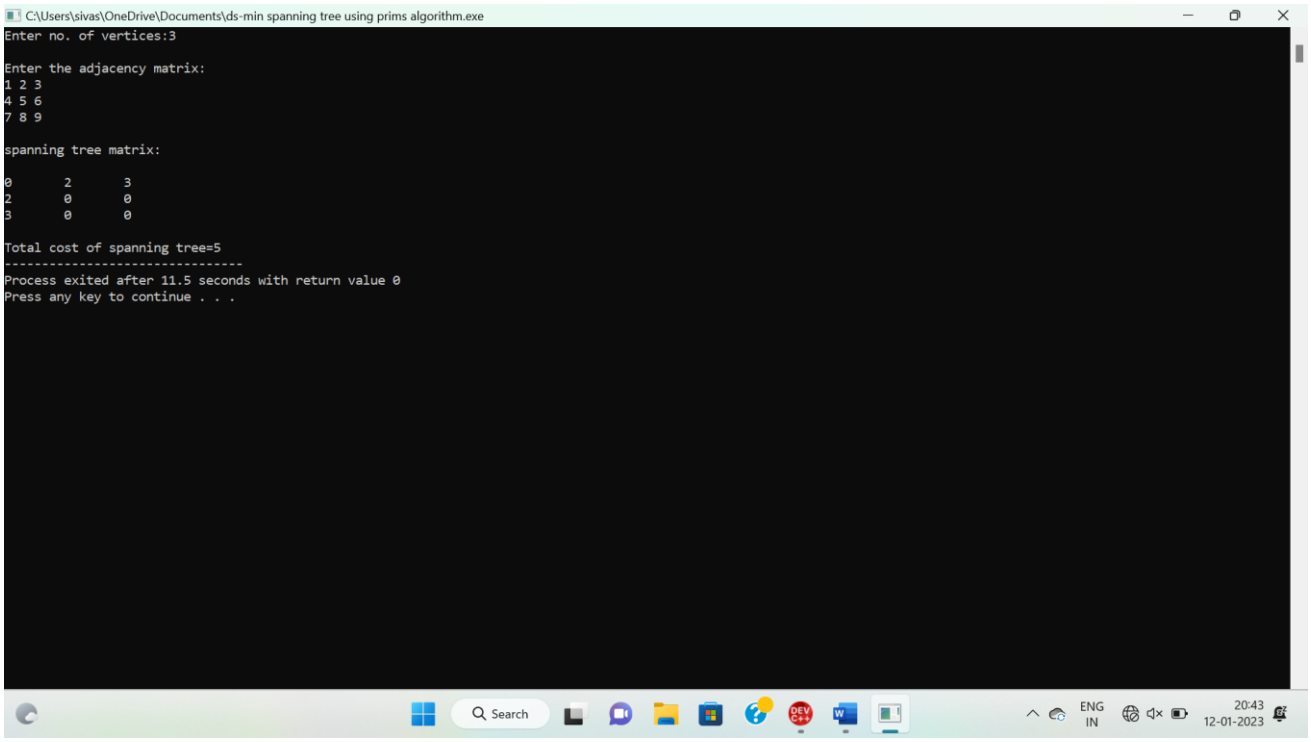


Implementaion of minimum spanning tree using prims algorithm:

```
#include<stdio.h>

#include<stdlib.h>

#define infinity 9999

#define MAX 20

int G[MAX][MAX],spanning[MAX][MAX],n;

int prims();

int main()

{

int i,j,total_cost;

printf("Enter no. of vertices:");

scanf("%d",&n);

printf("\nEnter the adjacency matrix:\n");

for(i=0;i<n;i++)

for(j=0;j<n;j++)

scanf("%d",&G[i][j]);

total_cost=prims();

printf("\nspanning tree matrix:\n");
```

```
for(i=0;i<n;i++)
{
printf("\n");
for(j=0;j<n;j++)
printf("%d\t",spanning[i][j]);
}
printf("\n\nTotal cost of spanning tree=%d",total_cost);
return 0;
}

int prims()
{
int cost[MAX][MAX];
int u,v,min_distance,distance[MAX],from[MAX];
int visited[MAX],no_of_edges,i,min_cost,j;
for(i=0;i<n;i++)
for(j=0;j<n;j++)
{
if(G[i][j]==0)
cost[i][j]=infinity;
else
cost[i][j]=G[i][j];
spanning[i][j]=0;
}
distance[0]=0;
visited[0]=1;
for(i=1;i<n;i++)
{
distance[i]=cost[0][i];
from[i]=0;
visited[i]=0;
```

```
}
min_cost=0;
no_of_edges=n-1;
while(no_of_edges>0)
{
min_distance=infinity;
for(i=1;i<n;i++)
if(visited[i]==0&&distance[i]<min_distance)
{
v=i;
min_distance=distance[i];
}
u=from[v];
spanning[u][v]=distance[v];
spanning[v][u]=distance[v];
no_of_edges--;
visited[v]=1;
for(i=1;i<n;i++)
if(visited[i]==0&&cost[i][v]<distance[i])
{
distance[i]=cost[i][v];
from[i]=v;
}
min_cost=min_cost+cost[u][v];
}
return(min_cost);
}
```



Implementation of minimum spanning tree using kruskal algorithm:

```
#include<stdio.h>

#define MAX 30

typedef struct edge

{

int u,v,w;

}edge;

typedef struct edgelist

{

edge data[MAX];

int n;

}edgelist;

edgelist elist;

int G[MAX][MAX],n;

edgelist spanlist;

void kruskal();

int find(int belongs[],int vertexno);
```

```
void union1(int belongs[],int c1,int c2);
void sort();
void print();
int main()
{
int i,j,total_cost;
printf("\nEnter number of vertices:");
scanf("%d",&n);
printf("\nEnter the adjacency matrix:\n");
for(i=0;i<n;i++)
for(j=0;j<n;j++)
scanf("%d",&G[i][j]);
kruskal();
print();
}
void kruskal()
{
int belongs[MAX],i,j,cno1,cno2;
elist.n=0;
for(i=1;i<n;i++)
for(j=0;j<i;j++)
{
if(G[i][j]!=0)
{
elist.data[elist.n].u=i;
elist.data[elist.n].v=j;
elist.data[elist.n].w=G[i][j];
elist.n++;
}
}
sort();
```

```
for(i=0;i<n;i++)
belongs[i]=i;
spanlist.n=0;
for(i=0;i<elist.n;i++)
{
cno1=find(belongs,elist.data[i].u);
cno2=find(belongs,elist.data[i].v);
if(cno1!=cno2)
{
spanlist.data[spanlist.n]=elist.data[i];
spanlist.n=spanlist.n+1;
union1(belongs,cno1,cno2);
}
}
}
int find(int belongs[],int vertexno)
{
return(belongs[vertexno]);
}
void union1(int belongs[],int c1,int c2)
{
int i;
for(i=0;i<n;i++)
if(belongs[i]==c2)
belongs[i]=c1;
}
void sort()
{
int i,j;
edge temp;
for(i=1;i<elist.n;i++)
```

```
for(j=0;j<elist.n-1;j++)
if(elist.data[j].w>elist.data[j+1].w)
{
temp=elist.data[j];
elist.data[j]=elist.data[j+1];
elist.data[j+1]=temp;
}
}
void print()
{
int i,cost=0;
for(i=0;i<spanlist.n;i++)
{
printf("\n%d\t%d\t%d",spanlist.data[i].u,spanlist.data[i].v,spanlist.data[i].w);
cost=cost+spanlist.data[i].w;
}
printf("\n\nCost of the spanning tree=%d",cost);
}
```