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# Travelling Salesman Problem

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## Problem

Given a set of cities and distance between every pair of cities, the problem is to find the shortest possible route that visits every city exactly once and returns to the starting point.

## Abstract

Travelling Salesman Problem falls under **NP complete** class of problems. Thus, there is no **polynomial time** algorithm known till now that solves this problem.

The TSP has many applications such as logistics, planning and the manufacture of **microchips**, also is also a sub-problem in **DNA sequencing**. This is also used in astronomy, as astronomers observing many sources will want to minimize the time spent moving the telescope between the sources.

So, in this report, we present two existing algorithms for **TSP**. They are:

- Genetic Algorithm.
- Brute Force

## Genetic Algorithm

Genetic algorithm is one of the popular techniques in CS to find complex solutions. Genetic algorithms are based on concept of evolution.

This algorithm chooses few arbitrary solutions and repeatedly performs optimizations on those solutions in hope to converge to the optimal solution.

As compared to the brute force algorithm which has a complexity of  $O(n!)$ , this algorithm performs quite well when it comes to real-world problems. This algorithm can be divided into following sections:

- Initializing with arbitrary solutions
- Optimizing the initialized solutions("Breeding")
- Choosing the best solutions from the above step.

This algorithm initially chooses  $n$  random solutions for the given graph(done by the function **initialPopulation()**). It most certainly won't be an optimal solution. The number of solutions it chooses can be given as an input by the user(instructions in *readme.txt*). This value, when at a lower, tends to give optimal solutions. After we get the solution set, we sort it according to their cost. And as we go ahead in the algorithm, this set essentially will contain the best solutions for the problem. And the top of this set will have the most optimal solution.

Now, after we get the set of solutions for the problems(not necessarily optimal ones), we randomly choose two of the solutions from the above set and apply what we call **crossOver()** on them. This is essentially breeding the two chosen solutions. How this works is given as follows,

Example :

```
parent1: 1 2 3 4 5
parent2: 1 2 4 5 3

substring in parent1: 2 3 4
substring in parent2: 2 4 5

substring inverted in parent1: 4 3 2
substring inverted in parent2: 5 4 2

child1: 1 5 4 2 5
child2: 1 4 3 2 3
```

Here, let's introduce the concept of **genes**. These are essentially the vertices that are inherited by the children from the two parents we chose to breed.

We will have two random points, one of them less than the other, and in the range of number of vertices in the graph. Now, for each child, we inherit genes from their

respective parents from start till first point and from second point till the end. For the middle part, as shown above, we inherit genes from the other parent in reverse order. This goes for both of the children inheriting. The children we get in this might or might not be the solutions for the problem, hence, we check them before adding them to the set of solutions we are forming. After we see that the children we got are indeed the solutions for the problem, we insert them in the set we created above, using binary search. This ensure the property of the sortedness of the set. Everytime we insert into the set, we discard the bottom most solution for the problem since it clearly is not an optimal solution i.e. in a sorted set, the bottom most solution is the worst, hence we remove it.

We do the above mentioned **breeding** user defined amount of times(taken care by the function **run()**). Here, we introduce the concept of **generations**. This is essentially, how many times do you want to breed the solution set we got, to get the optimal solution. This is analogous to the real life human genetic lineage. Hence the name **Genetic Algorithm**.

### Parallelizing Genetic Algorithm

Analysing the above approach, we reached to the conclusion that a lot of overhead we are getting is when the algorithm is running the breeding said number of times(on a scale of 1000) and attempted to parallelize that and sure enough, we saw good results from doing that. Obvioulsy, we couldn't just parallelize the loop for breeding as there are insertions and deletions and readings in the solution set by different threads which will lead to invalidation of the correctness of the algorithm. Hence, we approached the problem of parallelizing it in a different way. We tried the following approaches.

- Introducing mutex/shared locks
- Each thread computing on it's own to find the best result and among the results, getting the best one.

We tried various ways of introducing mutex locks and shared locks but none of them seemed to give good results as the overhead for achieving the locks is accountable as the solution set is being accessed a good amount of times. We couldn't get good results using this method, hence we implemented the below algorithm.

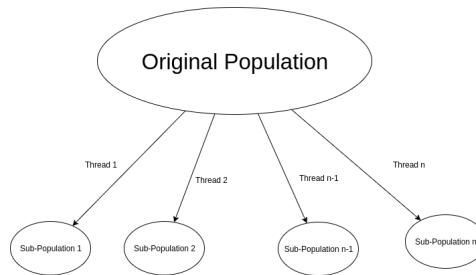


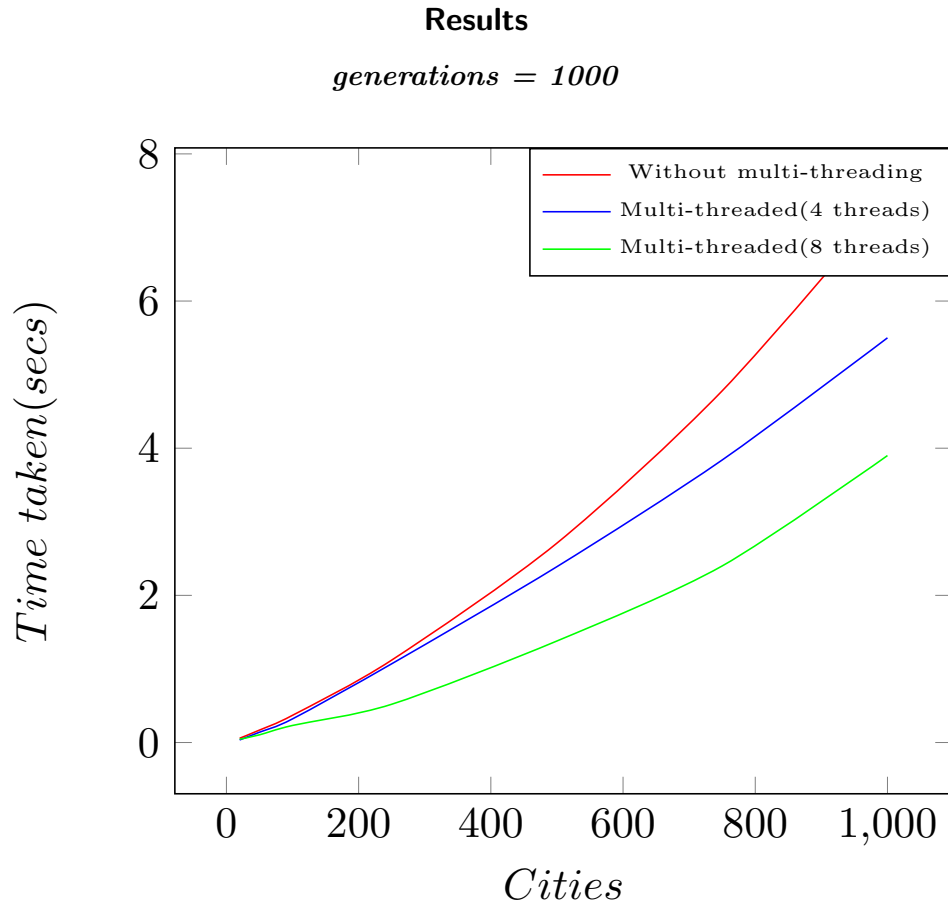
Figure 1: Work distribution for threads

The above figure shows the algorithm used, in a picturized way.

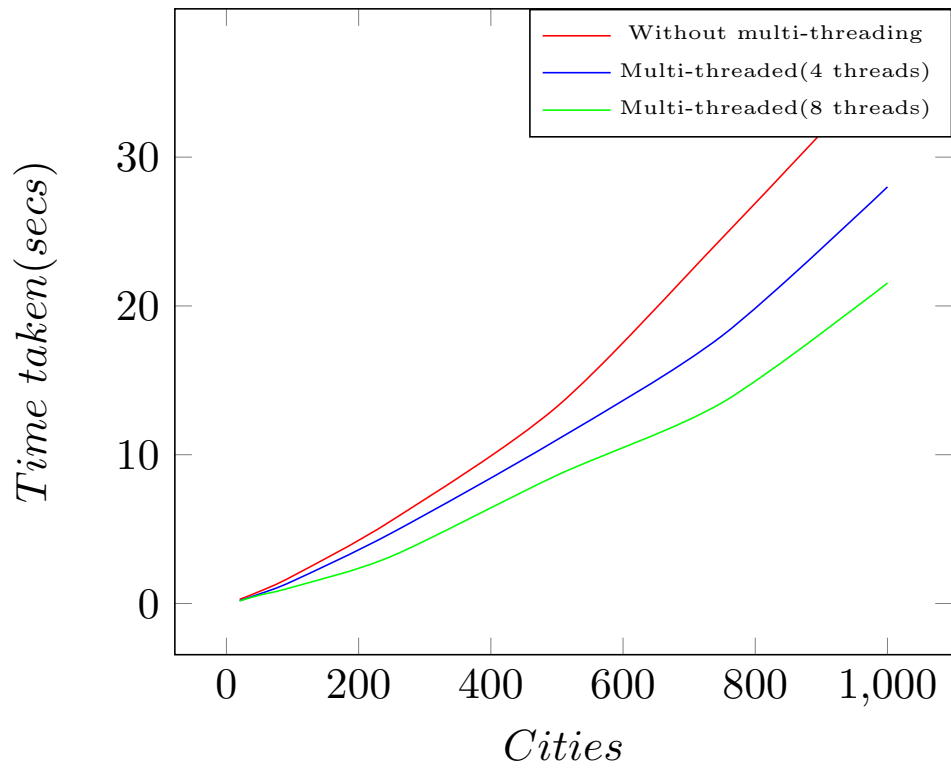
Since anyway we have a number of threads, we thought what if we make each thread compute it's own solution set and give us its best result and among the best results of all the threads, we get the very best one? And surely this approach fetched us good results. So in this implementation, each thread has it's own solution set and will work on that solution set to get optimal results. Essentially, we will be parallelizing the **run()** function.

The above mentioned algorithm is **Lock-free** and **Wait-free** implementation for the threads.

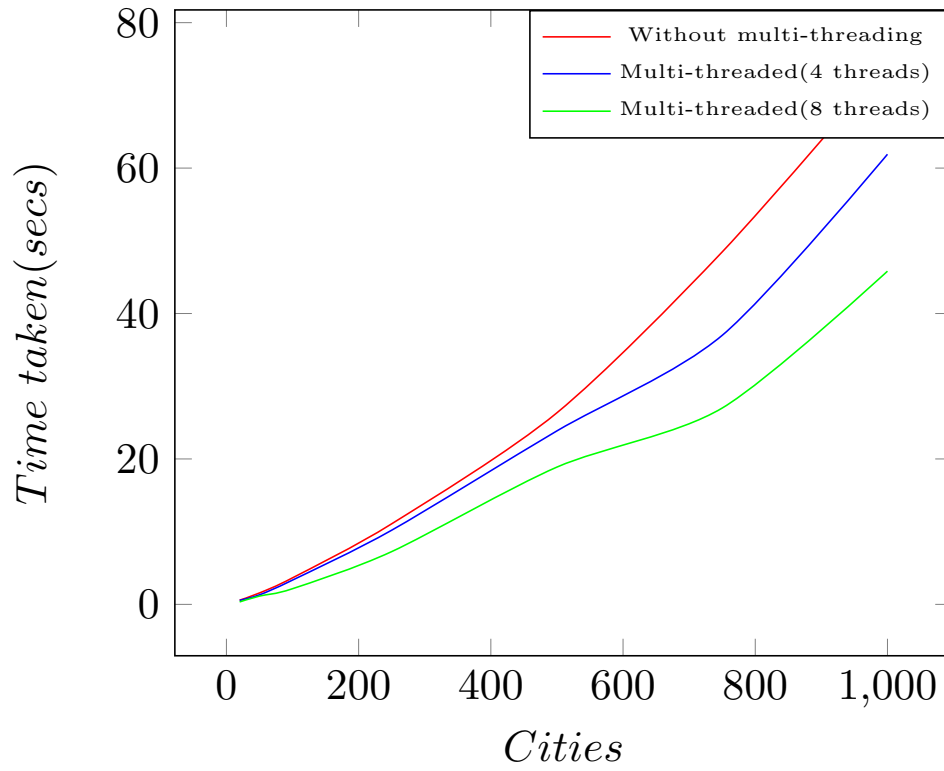
Taking into account the number of processors on the CPU, we gave 4 and 8 threads for testing of the algorithm.



*generations = 5000*



*generations = 10000*



### **Inference**

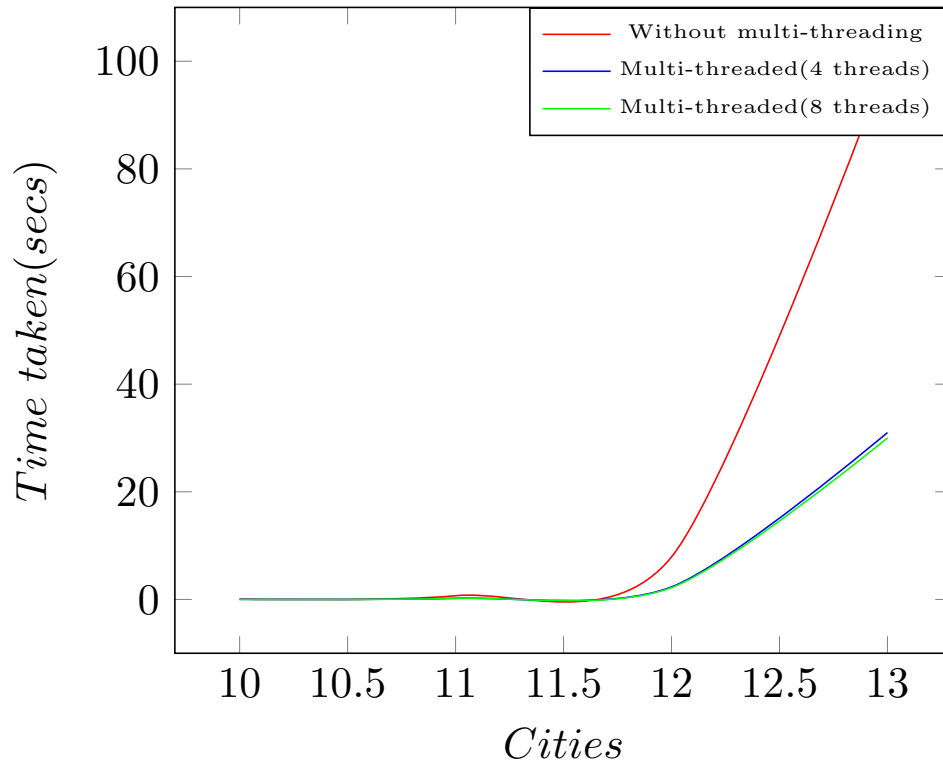
As we can see, multi-threading is helping a lot for easier computation in the algorithm. Here 4, 8 threads are used so as to account for the processors in the system (usually, 4 cores => 8 threads can run in parallel). As we increase the number of threads, the time taken will obviously decrease but, we will reach a stage where we have to have a trade off between speed and accuracy. Hence the testing was done with 4, 8 threads.

## Brute Force

We tried approaching the problem with the conventional brute force method. In this, as the cases that we need to check are in the order of factorial, we could only check for less amount of cities. However, we parallelized the algorithm in the similar fashion as **DAM** algorithm we devised to find the prime numbers for an assignment in this course. Since we are finding all the patterns and checking the minimal cost, we aimed at parallelizing this pattern-finding in hopes to achieve better result. The results are shown below.

### Results

*generations = 10000*



### Inference

We can see the improvement that has been achieved after parallelizing it. As the time complexity for sequential execution is exponential, with multi-threading, it has been arguably reduced. Although this is not a good way of solving the problem, for less number of cities, we get the exact answer unlike the above discussed algorithm. This aims to find the exact answer for the given number of cities.