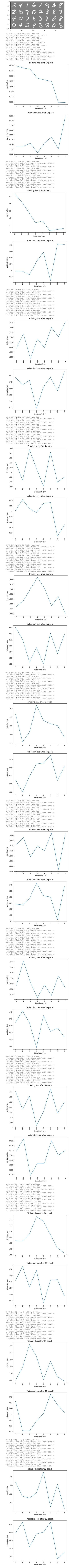
In [28]:	<pre>import torch.nn as nn import torch.nn . functional as F import torchvision import torchvision . transforms as transforms from torch.utils.data import random_split import matplotlib.pyplot as plt import numpy as np import math from torch.autograd import variable</pre>
In [2]: Out[2]:	from torch.autograd import variable from torchvision.utils import make_grid import os from torchsummary import summary Device configuration
In [3]:	Hyper-parameters num_epochs =15 batch_size = 32 learning_rate = 0.01 Data loading and downloading
In [4]:	<pre># dataset has PILImage images of range [0, 1]. # We transform them to Tensors of normalized range [-1, 1] transform = transforms.Compose([transforms.ToTensor()]) # CIFAR10: 60000 32x32 color images in 10 classes, with 6000 images per class train_dataset = torchvision.datasets.MNIST(root='./data', train=True, download=True, transform=transform) test_dataset = torchvision.datasets.MNIST(root='./data', train=False, download=True, transform=transform) TRAIN_SPLIT=0.9 VAL_SPLIT=0.1 numTrainSamples = int(len(train_dataset) * TRAIN_SPLIT) numValSamples = int(len(train_dataset) * VAL_SPLIT) (train_Data_walData) = random_split(train_dataset)</pre>
	<pre>numvalSamples = int(len(train_dataset) * VAL_SPLIT) ((trainData, valData) = random_split(train_dataset,</pre>
	<pre>definit(self):</pre>
	<pre>super(CNN, self)init() self.conv1 = nn.Conv2d(1,32,kernel_size = 3, stride = 1, padding = 1) self.conv2 = nn.Conv2d(32,32,kernel_size = 3, stride = 1, padding = 1) self.fc1 = nn.Linear(7*7*32, 500) self.fc2 = nn.Linear(500, 10) self.activ = nn.ReLU() def pool(self, x, kernel_size = 2, stride = 2): out = F.max_pool2d(x, kernel_size, stride) return out def forward(self, x, softmax = True): out = self.activ(self.conv1(x)) out = self.pool(out) out = self.activ(self.conv2(out))</pre>
In [7]: Out[7]:	<pre>out = self.pool(out) out = out.reshape(out.size(0),-1) out = self.activ(self.fcl(out)) out = self.fc2(out) if softmax: return F.softmax(out, dim = 1) else: return out CNN().forward <bound (conv1):="" 1))<="" 1),="" 3),="" 32,="" cnn(="" cnn.forward="" conv2d(1,="" kernel_size="(3," method="" of="" padding="(1," pre="" stride="(1,"></bound></pre>
In [8]:	<pre>(conv2): Conv2d(32, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1)) (fc1): Linear(in_features=1568, out_features=500, bias=True) (fc2): Linear(in_features=500, out_features=10, bias=True) (activ): ReLU())> Training Error ,Valdation error plots for every epoch and average prediction accuracy # get some random training images</pre>
	<pre>dataiter = iter(train_loader) images, labels = next(dataiter) # show images imshow(torchvision.utils.make_grid(images)) model = CNN().to(device) criterion = nn.CrossEntropyLoss() optimizer = torch.optim.SGD(model.parameters(), lr=learning_rate) n_total_steps = len(train_loader) training_loss=[] validation_loss=[] n_correct = 0 n_samples = 0 n_class_correct = [0 for i in range(10)] n_class_samples = [0 for i in range(10)]</pre>
	<pre>train_loss_epoch=[] validation_loss_epoch=[] num_iter=int(math.ceil(len(trainData)/batch_size)) for epoch in range(num_epochs):</pre>
	<pre>labels_val=labels_val.to(device) # Forward pass outputs = model(images) outputs_val=model(images_val) loss = criterion(outputs, labels) loss_val=criterion(outputs_val, labels) # Backward and optimize optimizer.zero_grad() loss.backward() optimizer.step() train_loss=loss.cpu().detach().numpy() val_loss=loss_val.cpu().detach().numpy()</pre>
	<pre>_, predicted = torch.max(outputs_val, 1) n_samples += labels.size(0) n_correct += (predicted == labels).sum().item() batch_size_list=list(labels.size()) batch_size=batch_size_list[0] for j in range(batch_size): label = labels[j] pred = predicted[j] if (label == pred):</pre>
	<pre>if (i+1) % 200 == 0: print (f'Epoch [{epoch+1}/{num_epochs}], Step [{i+1}/{n_total_steps}], Los:loss') print(f' Validation Accuracy of the network: {acc} %') training_loss.append(train_loss) validation_loss.append(val_loss) plt.plot(range(len(training_loss)), training_loss) plt.xlabel("iteration X 200") plt.ylabel("training loss") plt.title(f'Training loss after {epoch+1} epoch') plt.show() plt.plot(range(len(validation_loss)), validation_loss) plt.xlabel("iteration X 200") plt.ylabel("validation_loss") plt.title(f'Validation_loss after {epoch+1} epoch')</pre>
	<pre>plt.show() train_loss_epoch.append(train_loss) validation_loss_epoch.append(val_loss) fig,ax1=plt.subplots() ax2=ax1.twinx() line1=ax1.plot(range(len(train_loss_epoch)),train_loss_epoch,color="blue",label="trainin loss") ax1.set_ylabel("training loss") line2=ax2.plot(range(len(train_loss_epoch)),validation_loss_epoch,color="orange",label="valdation loss") ax2.set_ylabel("validation loss") lines=line1+line2 labels=[l.get_label() for l in lines] ax1.legend(lines,labels) print('Finished Training')</pre>
	<pre>PATH = './cnn.pth' torch.save(model.state_dict(), PATH)</pre>



	Validat Epoch [1 Validat	3/15], Step [400/1688], Los:loss ion Accuracy of the network: 10.109048218435321 % 3/15], Step [600/1688], Los:loss ion Accuracy of the network: 10.095566024165707 % 3/15], Step [800/1688], Los:loss ion Accuracy of the network: 10.093767809650457 % 3/15], Step [1000/1688], Los:loss ion Accuracy of the network: 10.095972901768912 % 3/15], Step [1200/1688], Los:loss ion Accuracy of the network: 10.097699944071588 % 3/15], Step [1400/1688], Los:loss ion Accuracy of the network: 10.096653352419652 % 3/15], Step [1600/1688], Los:loss ion Accuracy of the network: 10.097198709736457 % Training loss after 13 epoch	
	1.54 - 1.53 - 1.52 - 1.51 - 1.50 -		
	1.48 - 1.47 - 1.46 -	Validation loss after 13 epoch	
	2.44 - validation loss 2.42 - 2.40 -		
	Validat Epoch [1 Validat	0 1 2 3 4 5 6 7 iteration X 200 4/15], Step [200/1688], Los:loss ion Accuracy of the network: 10.095285404624278 % 4/15], Step [400/1688], Los:loss ion Accuracy of the network: 10.094572368421053 % 4/15], Step [600/1688], Los:loss ion Accuracy of the network: 10.087356946415898 % 4/15], Step [800/1688], Los:loss ion Accuracy of the network: 10.085626978543791 % 4/15], Step [1000/1688], Los:loss ion Accuracy of the network: 10.088966614365411 % 4/15], Step [1200/1688], Los:loss ion Accuracy of the network: 10.088872926028344 % 4/15], Step [1400/1688], Los:loss ion Accuracy of the network: 10.084095484921178 % 4/15], Step [1600/1688], Los:loss ion Accuracy of the network: 10.084095484921178 % 4/15], Step [1600/1688], Los:loss ion Accuracy of the network: 10.08245200475705 %	
	1.54 - 1.53 - 1.52 - \$\frac{1}{1}\$ 1.50 - 1.49 -	Training loss after 14 epoch	
	1.48 - 1.47 - 1.46 -	0 1 2 3 4 5 6 7 iteration X 200 Validation loss after 14 epoch	
	2.40 - ssol uniquation loss 2.36 - 2.34 - 2.32 -	0 1 2 3 4 5 6 7 iteration X 200	
	Validat Epoch [1 Validat	5/15], Step [200/1688], Los:loss ion Accuracy of the network: 10.08308157099698 % 5/15], Step [400/1688], Los:loss ion Accuracy of the network: 10.081739971704394 % 5/15], Step [600/1688], Los:loss ion Accuracy of the network: 10.086739641795972 % 5/15], Step [800/1688], Los:loss ion Accuracy of the network: 10.090762115258677 % 5/15], Step [1000/1688], Los:loss ion Accuracy of the network: 10.088629628126014 % 5/15], Step [1200/1688], Los:loss ion Accuracy of the network: 10.08728656572165 % 5/15], Step [1400/1688], Los:loss ion Accuracy of the network: 10.087088526685843 % 5/15], Step [1600/1688], Los:loss ion Accuracy of the network: 10.0878884432466709 % Training loss after 15 epoch	
	1.53 - 1.52 - 1.51 - \$\frac{1}{1}\$ 1.50 - 1.48 -		
	2.46 - 2.44 - 2.42 - 80 2.40 -	Validation loss after 15 epoch	
	2.36 - 2.34 -	0 1 2 3 4 5 6 7 iteration X 200	
	2.2 - 2.1 - 2.0 - 2.0 - 1.8 - 1.7 - 1.6 -	- valdation loss	- 2.425 - 2.400 - 2.375 - 2.350 Solution of the plan of the pla
In [9]:	with tor	ch.no_grad(): n_correct = 0 n_samples = 0 n_class_correct = [0 for i in range(10)] n_class_samples = [0 for i in range(10)] for images, labels in test_loader: images = images.to(device) labels = labels.to(device) outputs = model(images) # max returns (value ,index) _, predicted = torch.max(outputs, 1) n_samples += labels.size(0) n_correct += (predicted == labels).sum().item() batch_size_list=list(labels.size()) batch_size=batch_size_list[0]	
	Accuracy Accuracy Accuracy Accuracy Accuracy	<pre>for i in range(batch_size): label = labels[i] pred = predicted[i] if (label == pred):</pre>	
	Accuracy Accuracy Accuracy Dime output of fine floor((W) input so for	of 6: 97.28601252609603 % of 7: 97.37354085603113 % of 8: 95.17453798767967 % of 9: 94.44995044598612 % ensons of the input and output at each the filter with kernalsize = K X K ,stride = S,padding = P for input imagesize = W $\frac{-K+2P}{S}$ + 1) MNIST data dimension is 28 * 28 a batch size of 32 the input dimension for the conv1 layer is 28 X 28 X 32 1 layer contains the 32 filters with kernalsize = 3X3,stride = 1 ,zero padding = 1 s	X W is given by $floor(rac{(W-K+2P)}{S}+1)$ X
<pre>In [23]: Out[23]:</pre>	 input input 14X14 input after f input input conv1 (conv1 (conv2 (fc1): 	is 28X28X32 ,for 2X2 maxpool with stride = 2 has output size of 14X14X32 is 14X14X32 ,for conv-2 layer contains the 32 filters with kernalsize = 3X3,stride 4X32 is 14X14X32,for 2X2 maxpool with stride = 2 has output size of 7X7X32 flatting the outputsize is 7X7X32 = 1568 is 1568 and output after FC1 is 500 is 500 and output after FC2 is 10	= 1 ,zero padding = 1 so output size is
In [31]:	(activ	number of parameters CNN(),input_size=(1, 28, 28),device = 'cpu') Layer (type)	
	Trainable Non-trainer Input si Forward/ Params s Estimate	ReLU-6 Linear-7 [-1, 10] 5,010	
	total reconed NO C 1) The numerous affineurons affineuro	referring the top of table: no of parametrs in convolution layers = 320 + 9,248 = 9,568 (<2% parameters are no of parametrs in fully connected layers = 7,84,500 + 5,010 = 7,89,510 (almost atted layers)10=2078 +10=2078 The Nuerons The number of neurons in i/p are 28 X 28 = 784 2) The number of neurons after conv1 lagrer maxpool layer are 32 X 14 X 14 = 6272 4) The number of neurons after conv2 after maxpool 2 layer are 32 X 7 X 7 = 1568 6) The number of neurons after FC1 lay 0 The number of neurons in Convolutional layer are 784+25088+6272+6272=38416	98% parameters are contained in fully yer are 32 X 28 X 28 = 25088 3) The number of layer are 32 X 14 X 14=6272 5) The number of
	• The notation of the notation	Normalization seen that Batch normalization leads to faster convergence and increased accurate alization of Conv layers e refer this article visulization reference: //debuggercafe.com/visualizing-filters-and-feature-maps-in-convolutional-neurons	
In [11]: In [12]:	conv_lay model_ch counter # append for i in if	<pre>ights = [] # we will save the conv layer weights in this list ers = [] # we will save the 49 conv layers in this list ildren=list(model.children()) = 0 lall the conv layers and their respective weights to the list range(len(model_children)): type(model_children[i]) == nn.Conv2d: counter += 1 model_weights.append(model_children[i]).weight) conv_layers.append(model_children[i]) f type(model_children[i]) == nn.Sequential: for j in range(len(model_children[i])): for child in model_children[i][j].children(): if type(child) == nn.Conv2d:</pre>	
In [13]:	for weig # print pri CONV: Co. CONV: Co.	<pre>Total convolutional layers: {counter}") nvolutional layers: 2 ht, conv in zip(model_weights, conv_layers): (f"WEIGHT: {weight} \nSHAPE: {weight.shape}") nt(f"CONV: {conv} ====> SHAPE: {weight.shape}") nv2d(1, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1)) = nv2d(32, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1)) /*Sualizing the CNN</pre> /-1 layer	
In [14]:	plt.figu for i, f fil fil plt plt	re(figsize=(20, 17)) ilter in enumerate(model_weights[0]): ter=filter.cpu() ter=filter.detach().numpy() .subplot(8, 8, i+1) # (8, 8) because in conv0 we have 7x7 filter.imshow(filter[0, :, :], cmap='gray') .axis('off') ()	
In [15]:	 We cr 32 dif Given trainir plt.figu for i, f fill fill plt	r-2 layer eated 32 dimension from the original 1 dimension our second convulation layer ferent channel these are second layer channel and are supposed to be more spe the size 3X3 for each kernel we can see the image of that size is not big enough ng for but these feature are extracted from the feature which were already highlighed re(figsize=(20, 17)) ilter in enumerate(model_weights[1]): ter=filter.cpu() ter=filter.detach().numpy() .subplot(8, 8, i+1) # (8, 8) because in conv0 we have 7x7 filter.imshow(filter[0, :, :], cmap='gray')	cific. for us to visualize what exactly is the model ghted by the 1st layer of convolution.
	plt.show	.axis('off') ()	
In [16]:	are a	e choosen the 20th filter for visulization vailble 7 = test loader.dataset.data[[index],:,:].clone()	on ,totally 32 filters
	test_img ntest_im new_test new_test print(te plt.imsh #plt.ims plt.show test_img	<pre>= test_im.reshape(1,1,28,28).clone().float() g=test_img[0].permute(1,2,0) img=torch.zeros(28,28) img[:,:]=ntest_img[:,:,0] st_img.size()) ow(new_test_img) how(test_img[0].permute(1,2,0))</pre>	
	conv2_te conv2_ou conv2_ou conv2_ou conv2_ou conv2_ou vis_conv plt.imsh plt.titl plt.show	<pre>mp = model.conv1.forward(test_img) mp = model.activ.forward(conv2_temp) mp = model.pool(conv2_temp) t = model.conv2.forward(conv2_temp) t = conv2_out.cpu() t = conv2_out - conv2_out.min() t = conv2_out/conv2_out.max() t = conv2_out.reshape(32,1,14,14) 2 = make_grid(conv2_out) ow(vis_conv2.permute(1,2,0)) e("Activations after conv2 layer")</pre>	
	5 - 10 - 15 - 20 -		
	0 0 20 - 40 - 60 -	Activations after conv1 layer	
	100 - 120 - 0 - 10 - 20 - 30 -	Activations after conv2 layer	
	50 - 60 - 0 • After we are mean. • Refer	visulizing the above activationmaps in convlayer-1 and convlayer-2 we can concle going in deeper ing that filter can detect less number of features this article https://towardsdatascience.com/applied-deep-learning-part-4-convo	
In [17]:	• by vis dim = le prob_map max_prob for y in	<pre>ing parts of the image ulizing the below plots and matrix's we can say that learning is meaningful. n(range(0,14,2)) = np.zeros((dim, dim), dtype = float) _class_map = np.zeros_like(prob_map) range(0,14,2): x in range(0,14,2): temp = test_im.clone() temp[y:y+7, x:x+7] = 0 with torch.no_grad(): temp = temp.clone().reshape(1,1,28,28).float() temp=temp.to(device) out = model.forward(temp, softmax = False) proba = F.softmax(out, dim=1).cpu().detach().numpy() pred = np.argmax(proba)</pre>	
	<pre>print(pr print("M</pre>	<pre>prob = proba[:, 9] max_prob_class = pred prob_map[int(y/2), int(x/2)] = prob[0] max_prob_class_map[int(y/2), int(x/2)] = max_prob_class if ((x%4 == 0) & (y%4 == 0)): plt.imshow(temp.cpu().numpy().reshape(28, 28)) plt.title("Probability of 9 is {}".format(prob[0])) plt.show() robability Map for the class 9 as positive as patch is moved is</pre>	

Epoch [13/15], Step [200/1688], Los:loss

Validation Accuracy of the network: 10.108892256550645 %

