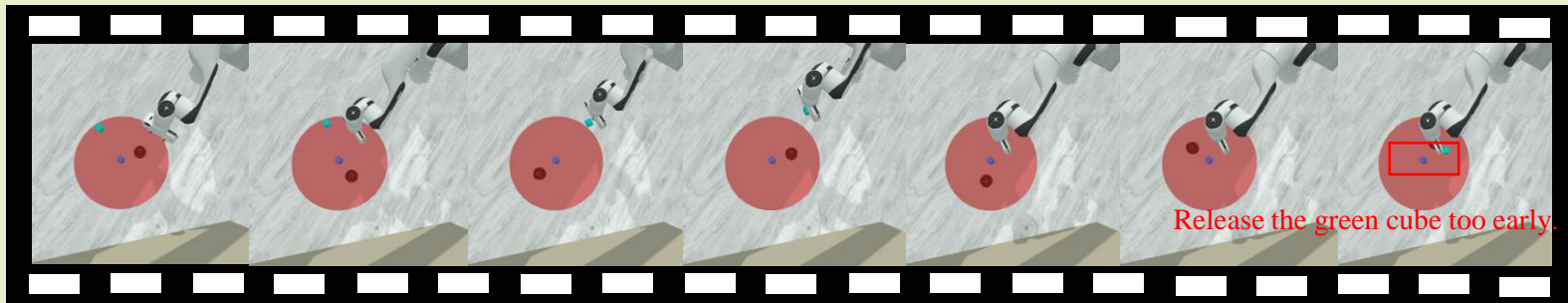


Task: Pull out the green cube on the spinning disc and stack it on the apple on the disc.



RoboFAC-7B

**<Failure Explanation>**

The task failed because the robot arm released the green cube too early while attempting to stack it onto the apple. The apple was not yet properly aligned beneath the green cube when the release occurred, resulting in the green cube missing its target and failing to stack on the apple. This timing error indicates that the robot arm did not wait for the apple to be fully rotated into position before releasing the green cube.

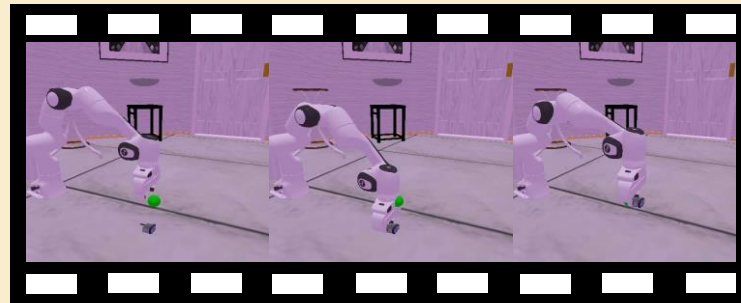


GPT-4o

**<Failure Explanation>**

The task failed because the robot arm repeatedly attempted to grasp the red object but was unable to successfully pick it up. This could be due to improper alignment of the gripper with the object, insufficient gripping force, or a mismatch between the gripper's design and the object's shape or size. Additionally, the robot arm appeared to move the blue object out of the red circular area, which may indicate a lack of precision or misinterpretation of the task requirements.

Task: Pick the cube to the target position.



RoboFAC-7B

**<Failure Detection>**

**Q:** Based on the video of the robotic arm executing a task, did it finish the task successfully?  
**A:** Yes.



GPT-4o

**<Failure Detection >**

**Q:** Based on the video of the robotic arm executing a task, did it finish the task successfully?  
**A:** No.