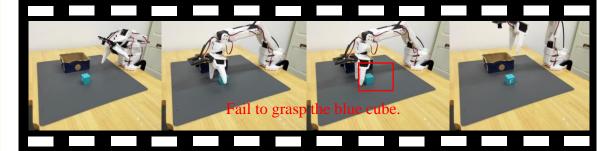


## Instruction: Put the blue cube in the box

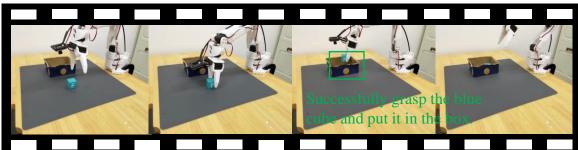




## <Low-level Correction >

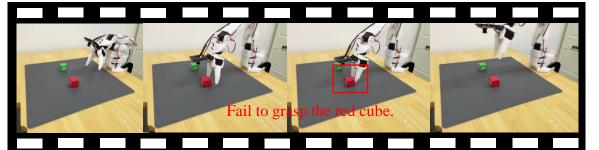
Move the robot arm slightly backward to create space, then adjust its position to the left and downward to align with the center of the cube before attempting to grasp it again.







## Instruction: Put the blue cube in the box





## <Low-level Correction >

Move the robot arm slightly backward to create space, then adjust the arm to the left to align with the center of the red cube. After achieving alignment, lower the end-effector to grasp the red cube securely before lifting it and moving it towards the green cube for stacking.



