

Consistency Models: *One-Step Image Generation*

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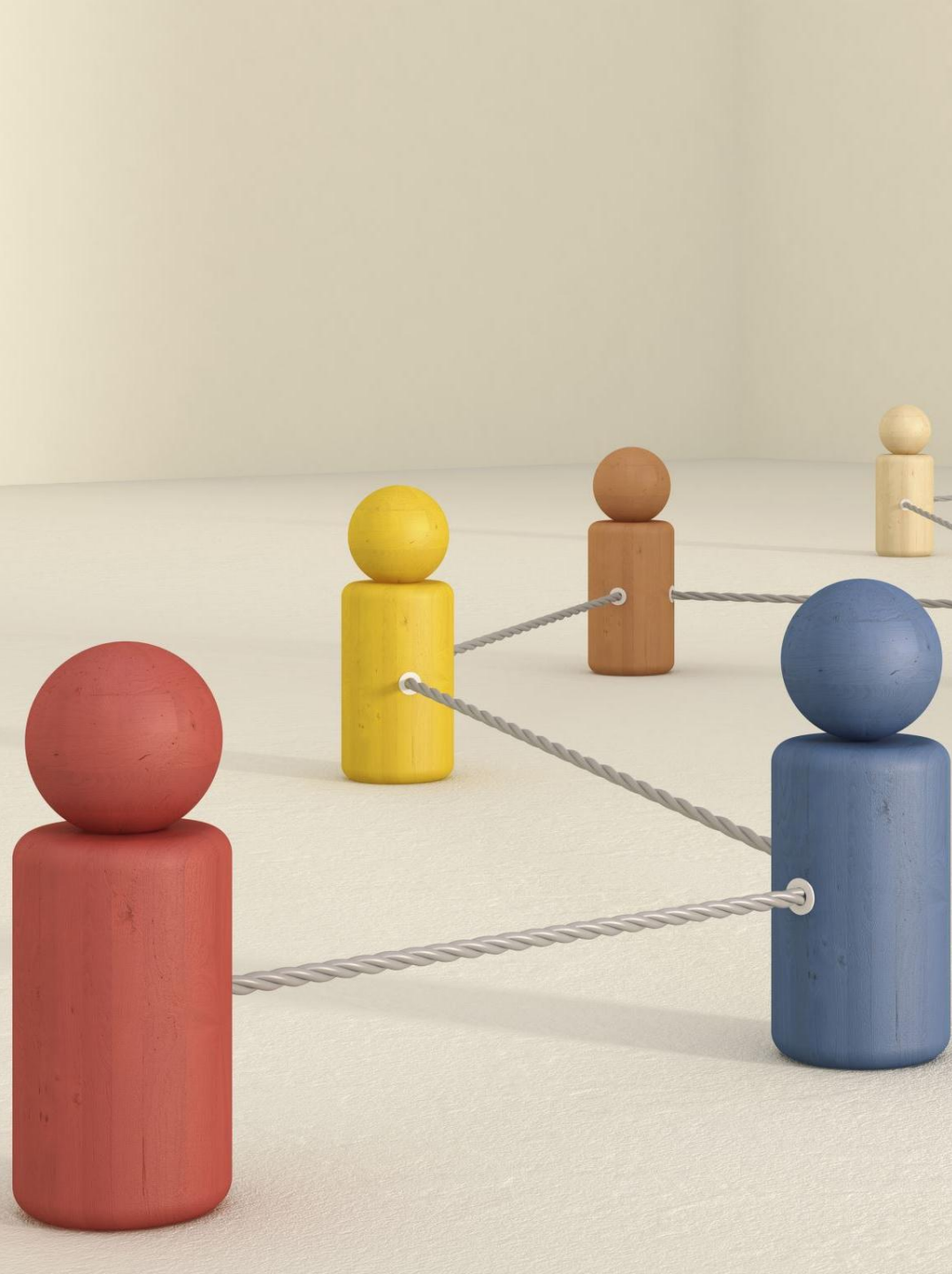


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Introduction

Generative models learn high-dimensional data distributions (e.g., images)



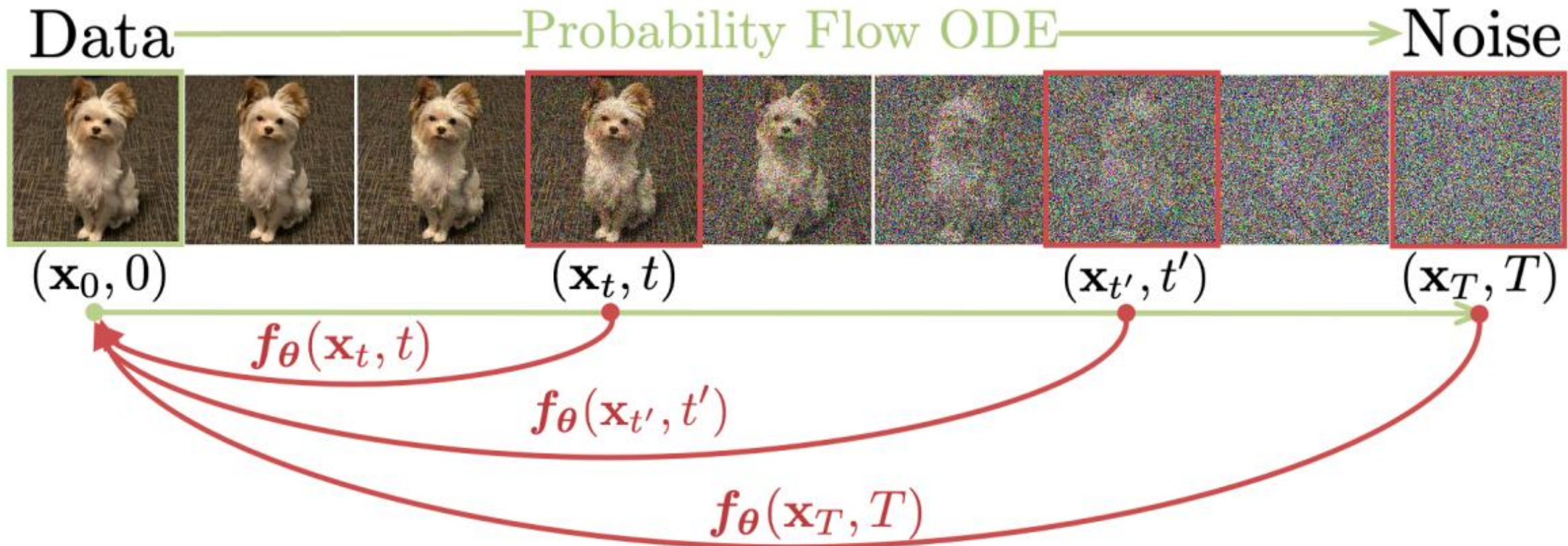
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graph TD; A[Generative models learn high-dimensional data distributions (e.g., images)] --> B[Applications: Image synthesis, inpainting, super-resolution, image denoising]; B --> C[Diffusion Models (DMs): Powerful but slow sampling (100s - 1000s steps) so not feasible for real-time application (e.g., MRI reconstruction).]; C --> D[Consistency Models (CMs): Directly map noisy data to clean data for one-step generation. Allows multistep sampling for quality-compute trade-off.];
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Applications: Image synthesis, inpainting, super-resolution, image denoising

Diffusion Models (DMs): Powerful but **slow sampling** (100s - 1000s steps) so not feasible for real-time application (e.g., MRI reconstruction).

Consistency Models (CMs): Directly map noisy data to clean data for **one-step generation**. Allows multistep sampling for **quality-compute trade-off**.

Consistency Models Concept



$f_\theta(x_t, t) = f_\theta(x_{t'}, t')$ for any $(x_t, x_{t'})$ on the same PF ODE trajectory

$f_\theta(x_\varepsilon, \varepsilon) = x_\varepsilon$ (boundary condition)



Core Mathematical Foundation

Forward Diffusion as SDE¹:

$$d\mathbf{x}_t = \boldsymbol{\mu}(\mathbf{x}_t, t) dt + \sigma(t) d\mathbf{w}_t,$$

where $t \in [0, T]$; $\boldsymbol{\mu}(\mathbf{x}_t, t)$, $\sigma(t)$ = drift and diffusion coefficients, \mathbf{w}_t = standard Brownian motion.

Probability Flow ODE (Reverse Diffusion):

- Same marginal distributions as original SDE, enabling deterministic transformations.

$$d\mathbf{x}_t = \left[\boldsymbol{\mu}(\mathbf{x}_t, t) - \frac{1}{2} \sigma(t)^2 \nabla \log p_t(\mathbf{x}_t) \right] dt.$$

where $\nabla \log p_t(\mathbf{x}_t)$ is called the score function of $p_t(\mathbf{x}_t)$

Simplification to empirical PF ODE²:

- Applied $\boldsymbol{\mu}(\mathbf{x}, t) = 0$ and $\sigma(t) = \sqrt{2t}$

$$\frac{d\mathbf{x}_t}{dt} = -t \mathbf{s}_\phi(\mathbf{x}_t, t).$$

1. Y. Song, et al, "Score-based generative modelling through stochastic differential equations," ICLR, 2020.

2. T. Karras, M. Aittala, T. Aila, and S. Laine. "Elucidating the design space of diffusion-based generative models," NeurIPS, 2022.

Training Method 1: Consistency Distillation (CD)

1. Start with pre-trained model
2. Sample noisy \mathbf{x} at time, t_{n+1}
3. Get teacher's estimate at t_n
4. Minimise output differences between adjacent points
5. Update online network and target networks.

Algorithm 2 Consistency Distillation (CD)

Input: dataset \mathcal{D} , initial model parameter θ , learning rate η , ODE solver $\Phi(\cdot, \cdot; \phi)$, $d(\cdot, \cdot)$, $\lambda(\cdot)$, and μ

$\theta^- \leftarrow \theta$

repeat

Sample $\mathbf{x} \sim \mathcal{D}$ and $n \sim \mathcal{U}[[1, N - 1]]$

Sample $\mathbf{x}_{t_{n+1}} \sim \mathcal{N}(\mathbf{x}; t_{n+1}^2 \mathbf{I})$

$\hat{\mathbf{x}}_{t_n}^\phi \leftarrow \mathbf{x}_{t_{n+1}} + (t_n - t_{n+1})\Phi(\mathbf{x}_{t_{n+1}}, t_{n+1}; \phi)$

$\mathcal{L}(\theta, \theta^-; \phi) \leftarrow$

$\lambda(t_n)d(\mathbf{f}_\theta(\mathbf{x}_{t_{n+1}}, t_{n+1}), \mathbf{f}_{\theta^-}(\hat{\mathbf{x}}_{t_n}^\phi, t_n))$

$\theta \leftarrow \theta - \eta \nabla_\theta \mathcal{L}(\theta, \theta^-; \phi)$

$\theta^- \leftarrow \text{stopgrad}(\mu \theta^- + (1 - \mu)\theta)$

until convergence

Training Method 2: Consistency Training (CT)

- **No teacher:** Uses score matching technique (unbiased estimator)
- **Progressive schedules, (N) and μ :**
 - Small $N(k)$ (bigger Δt) \rightarrow Faster initial learning; higher bias.
 - Large $N(k)$ (smaller Δt) \rightarrow Higher precision in later training. Higher variance, better results.
 - Slow updates of θ^- in later training \rightarrow stabilises learning & reduces sensitivity to small fluctuations in θ .

Algorithm 3 Consistency Training (CT)

Input: dataset \mathcal{D} , initial model parameter θ , learning rate η , step schedule $N(\cdot)$, EMA decay rate schedule $\mu(\cdot)$, $d(\cdot, \cdot)$, and $\lambda(\cdot)$

$\theta^- \leftarrow \theta$ and $k \leftarrow 0$

repeat

Sample $\mathbf{x} \sim \mathcal{D}$, and $n \sim \mathcal{U}[[1, N(k) - 1]]$

Sample $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$

$\mathcal{L}(\theta, \theta^-) \leftarrow$

$\lambda(t_n)d(\mathbf{f}_\theta(\mathbf{x} + t_{n+1}\mathbf{z}, t_{n+1}), \mathbf{f}_{\theta^-}(\mathbf{x} + t_n\mathbf{z}, t_n))$

$\theta \leftarrow \theta - \eta \nabla_\theta \mathcal{L}(\theta, \theta^-)$

$\theta^- \leftarrow \text{stopgrad}(\mu(k)\theta^- + (1 - \mu(k))\theta)$

$k \leftarrow k + 1$

until convergence

Sampling with Consistency Models

One-Step Sampling:

- Directly map noise to clean data, \hat{x}_ϵ , across all time steps using $f_\theta(x_T, T)$

Multi-Step Sampling:

- Balances **speed** and **quality**.
- Alternates between denoising and noise injection at each step: to maintain smooth transitions and avoid instability.
- Controlled Noise Injection: Scaling factor ensures noise matches time step's level.

Algorithm 1 Multistep Consistency Sampling

Input: Consistency model $f_\theta(\cdot, \cdot)$, sequence of time points $\tau_1 > \tau_2 > \dots > \tau_{N-1}$, initial noise $\hat{\mathbf{x}}_T$

$\mathbf{x} \leftarrow f_\theta(\hat{\mathbf{x}}_T, T)$

for $n = 1$ **to** $N - 1$ **do**

 Sample $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$

$\hat{\mathbf{x}}_{\tau_n} \leftarrow \mathbf{x} + \sqrt{\tau_n^2 - \epsilon^2} \mathbf{z}$

$\mathbf{x} \leftarrow f_\theta(\hat{\mathbf{x}}_{\tau_n}, \tau_n)$

end for

Output: \mathbf{x}

Results

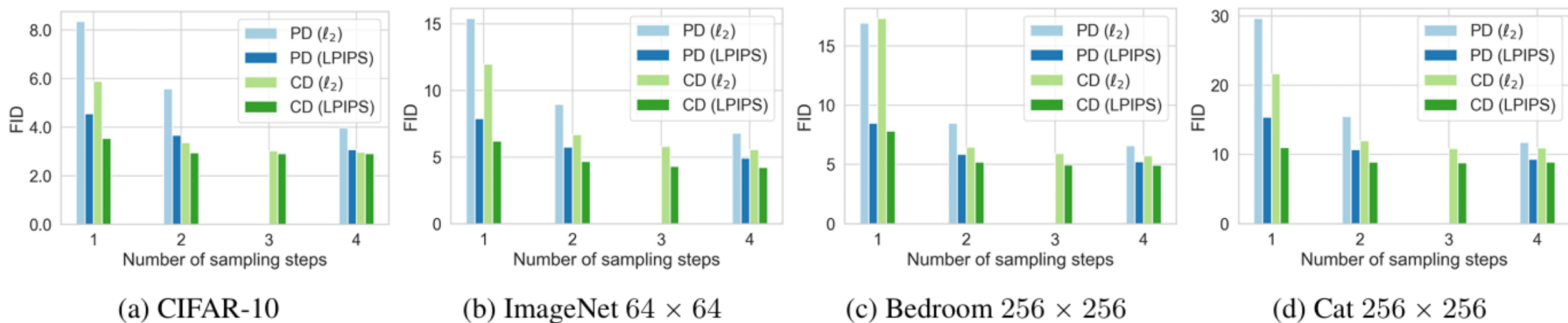


Figure 4: Multistep image generation with consistency distillation (CD). CD outperforms progressive distillation (PD) across all datasets and sampling steps. The only exception is single-step generation on Bedroom 256×256 .

1-Step FID: 3.55, 2-step FID: 2.93 (CIFAR-10) | 1-Step FID: 6.20, 2-step FID: 4.70 (ImageNet)

Results

Table 1: Sample quality on CIFAR-10. *Methods that require synthetic data construction for distillation.

METHOD	NFE (↓)	FID (↓)	IS (↑)
Diffusion + Samplers			
DDIM (Song et al., 2020)	50	4.67	
DDIM (Song et al., 2020)	20	6.84	
DDIM (Song et al., 2020)	10	8.23	
DPM-solver-2 (Lu et al., 2022)	10	5.94	
DPM-solver-fast (Lu et al., 2022)	10	4.70	
3-DEIS (Zhang & Chen, 2022)	10	4.17	
Diffusion + Distillation			
Knowledge Distillation* (Luhman & Luhman, 2021)	1	9.36	
DFNO* (Zheng et al., 2022)	1	4.12	
1-Rectified Flow (+distill)* (Liu et al., 2022)	1	6.18	9.08
2-Rectified Flow (+distill)* (Liu et al., 2022)	1	4.85	9.01
3-Rectified Flow (+distill)* (Liu et al., 2022)	1	5.21	8.79
PD (Salimans & Ho, 2022)	1	8.34	8.69
CD	1	3.55	9.48
PD (Salimans & Ho, 2022)	2	5.58	9.05
CD	2	2.93	9.75

Direct Generation

BigGAN (Brock et al., 2019)	1	14.7	9.22
Diffusion GAN (Xiao et al., 2022)	1	14.6	8.93
AutoGAN (Gong et al., 2019)	1	12.4	8.55
E2GAN (Tian et al., 2020)	1	11.3	8.51
ViTGAN (Lee et al., 2021)	1	6.66	9.30
TransGAN (Jiang et al., 2021)	1	9.26	9.05
StyleGAN2-ADA (Karras et al., 2020)	1	2.92	9.83
StyleGAN-XL (Sauer et al., 2022)	1	1.85	
Score SDE (Song et al., 2021)	2000	2.20	9.89
DDPM (Ho et al., 2020)	1000	3.17	9.46
LSGM (Vahdat et al., 2021)	147	2.10	
PFGM (Xu et al., 2022)	110	2.35	9.68
EDM (Karras et al., 2022)	35	2.04	9.84
1-Rectified Flow (Liu et al., 2022)	1	378	1.13
Glow (Kingma & Dhariwal, 2018)	1	48.9	3.92
Residual Flow (Chen et al., 2019)	1	46.4	
GLFlow (Xiao et al., 2019)	1	44.6	
DenseFlow (Grcić et al., 2021)	1	34.9	
DC-VAE (Parmar et al., 2021)	1	17.9	8.20
CT	1	8.70	8.49
CT	2	5.83	8.85

Results

Table 2: Sample quality on ImageNet 64×64 , and LSUN Bedroom & Cat 256×256 . [†]Distillation techniques.

METHOD	NFE (\downarrow)	FID (\downarrow)	Prec. (\uparrow)	Rec. (\uparrow)
ImageNet 64×64				
PD [†] (Salimans & Ho, 2022)	1	15.39	0.59	0.62
DFNO [†] (Zheng et al., 2022)	1	8.35		
CD[†]	1	6.20	0.68	0.63
PD [†] (Salimans & Ho, 2022)	2	8.95	0.63	0.65
CD[†]	2	4.70	0.69	0.64
ADM (Dhariwal & Nichol, 2021)	250	2.07	0.74	0.63
EDM (Karras et al., 2022)	79	2.44	0.71	0.67
BigGAN-deep (Brock et al., 2019)	1	4.06	0.79	0.48
CT	1	13.0	0.71	0.47
CT	2	11.1	0.69	0.56
LSUN Bedroom 256×256				
PD [†] (Salimans & Ho, 2022)	1	16.92	0.47	0.27
PD [†] (Salimans & Ho, 2022)	2	8.47	0.56	0.39
CD[†]	1	7.80	0.66	0.34
CD[†]	2	5.22	0.68	0.39
DDPM (Ho et al., 2020)	1000	4.89	0.60	0.45
ADM (Dhariwal & Nichol, 2021)	1000	1.90	0.66	0.51
EDM (Karras et al., 2022)	79	3.57	0.66	0.45
PGGAN (Karras et al., 2018)	1	8.34		
PG-SWGAN (Wu et al., 2019)	1	8.0		
TDPM (GAN) (Zheng et al., 2023)	1	5.24		
StyleGAN2 (Karras et al., 2020)	1	2.35	0.59	0.48
CT	1	16.0	0.60	0.17
CT	2	7.85	0.68	0.33

Results

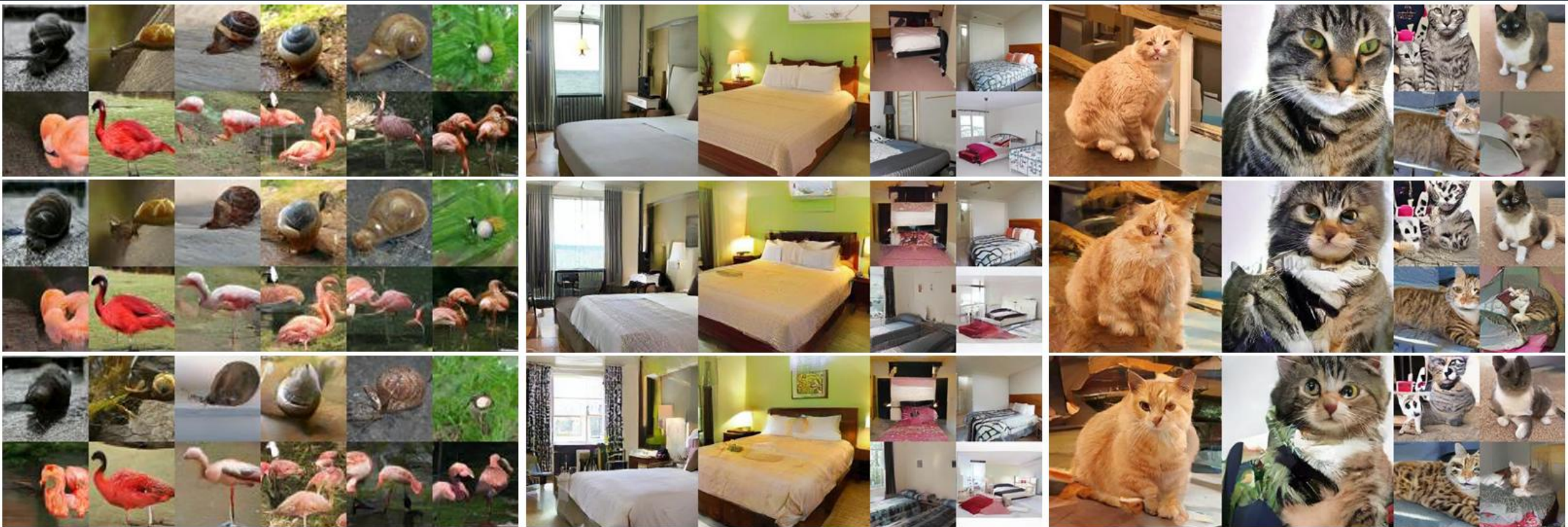


Figure 5: Samples generated by EDM (*top*), CT + single-step generation (*middle*), and CT + 2-step generation (*Bottom*). All corresponding images are generated from the same initial noise.

Advantages



Fast, efficient one-step generation



Quality-compute trade-off for multistep generation



Zero-shot editing capabilities



Two Training Modes: distillation and as standalone



Outperforms existing distillation techniques and doesn't require synthetic datasets



Better samples than existing single-step generation models (except for some GANs)

Limitations



Distillation limits quality to that of the pre-trained model.



LPIPS introduced undesirable biases in evaluation, affecting the perceived quality of generated samples.



High computational resources: required for training.



Not always state-of-the-art: Sample quality can lag behind fully iterative diffusion or very large GANs.

Future Work



Improved Techniques for Training Consistency Models (ICLR 2024 | Oral)



Improved Consistency Training (iCT): learns directly from data without distillation.



Removed EMA for teacher network: led to significant improvement in FIDs.



Pseudo-Huber Losses: replaces LPIPS, reducing bias in evaluation.



Lognormal Noise Schedule: as CT objective, improving sample quality & efficiency.



Improved Sample Quality: 4x over CT, better FID scores, and **surpassed CD**.

Simplifying, Stabilizing and Scaling Continuous-Time Consistency Models (Preprint Oct. 2024)



Simplified, Unified Theoretical Formulation: to identify root causes of training instability.



Improved Network Architecture and Training Objectives: for stable and scalable training.



Large-Scale Model Training: trained largest CM with up to 1.5B parameters on ImageNet 512x512.



Efficient Sampling: Quality comparable to leading diffusion models using only 2 steps (~50x speedup; 0.11s for 1 sample).



Narrowed FID gap with teacher: to within 10% in 2 steps.

Beyond OpenAI

Consistency Models Made Easy (by CMU | ICLR 2025):

- Easy Consistency Tuning: makes training CMs cost-effective and more accessible (CIFAR-10: 1 hour on 1 A100 vs. 1 week on 8 A100s).

Consistency Trajectory Models (by Sony AI | ICLR 2024):

- Generalises CMs and DMs, for efficient traversal along PF ODE.
- Flexible Sampling: supports deterministic and stochastic.
- SoTA FID for 1-step sampling on CIFAR-10 (FID 1.73) and ImageNet (FID 1.92).
- Beats EDM (35 NFE) and StyleGAN-XL. **Achieves student-beats-teacher.**

Conclusion

Motivation

- Diffusion Models need many iterative steps → slow sampling.
- Consistency Models aim for **fast one-step generation** without zero-shot editing and sample quality.

Key Ideas

- **Self-Consistency**: Any noisy version of a data point (at different times) maps back to the same clean sample.
- **Consistency Distillation**: Uses a pretrained diffusion model; 1-step approx. a teacher's multi-step ODE path.
- **Consistency Training**: from scratch by enforcing consistency on multiple noise levels of same data, no teacher.
- Architecture: Enforces a boundary condition at near-zero noise.

Advantages

- One-step or Few step Generation (**potential for real-time applications**), Zero-Shot Editing, Comparable (or Better) Quality, No synthetic data needed.

Additional theoretical + practical refinements **under active development**.

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