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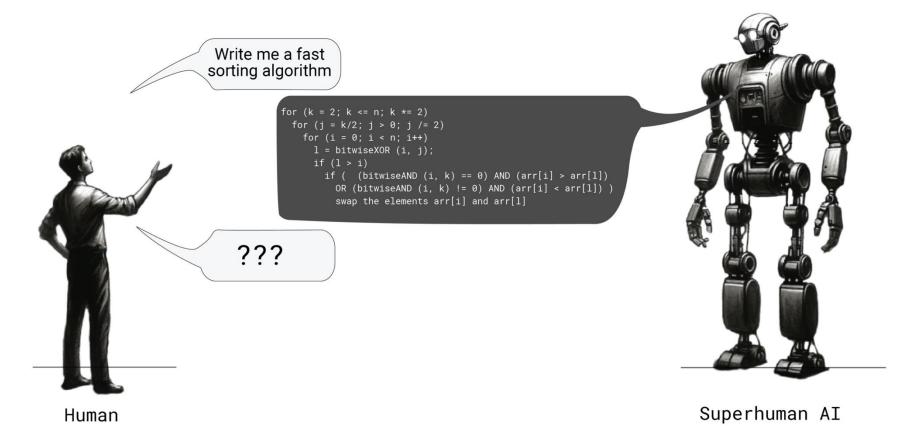
Consistency and Alignment in LLMs

"Truth or Deceit? A Bayesian Decoding Game

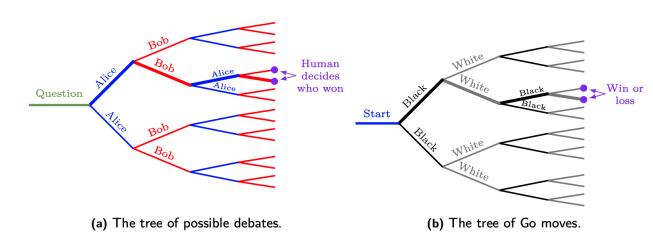
Enhances Consistency and Reliability"

https://arxiv.org/abs/2408.00639

Al Safety via Debate

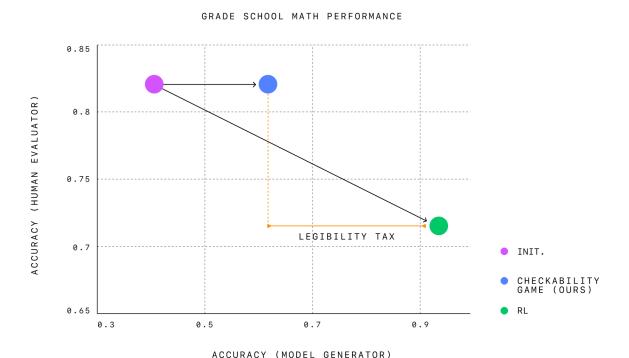


"One approach to specifying complex goals asks **HUMANS** to judge during training which agent behaviors are safe and useful, but this can **FAIL** if the task is **COMPLICATED** for a human to judge."



[Debate Game]

Al Safety and Consistency via Multi-agents Debate [1]



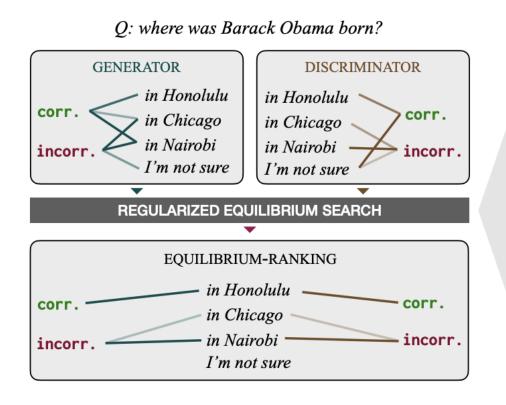
[Zero-sum Game]

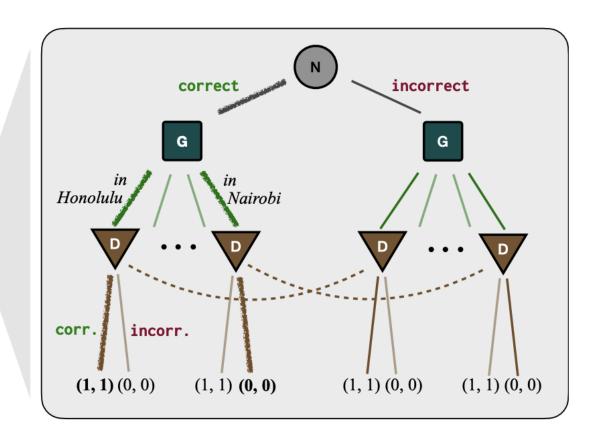
Prover-Verifier Games

Improve Legibility of

Language Model Outputs [2]

[Consensus Game] Equilibrium Consensus Game^[3]





Three Communication Paradigms

1. Competitive

agents work towards their own goals that might conflict with the goals of other agents.

2. Debate

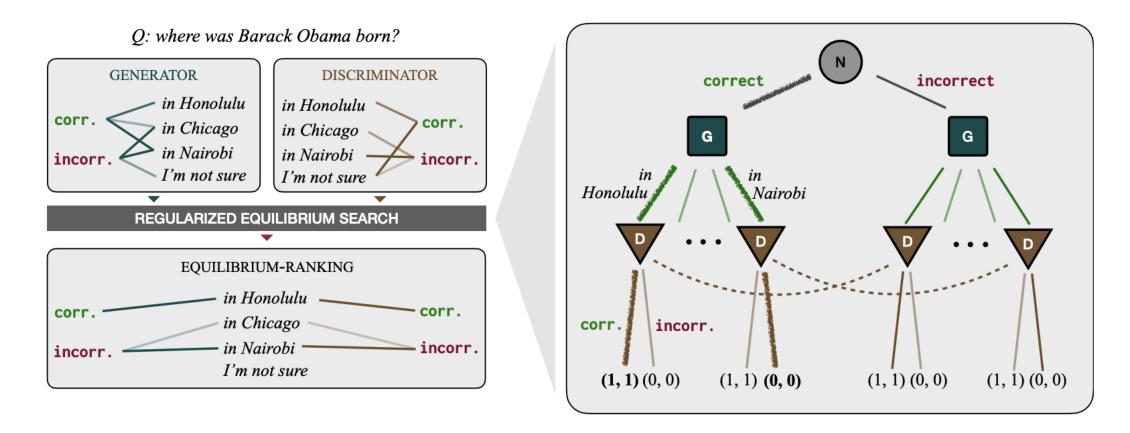
employed when agents engage in argumentative interactions, presenting and defending their own viewpoints or solutions, and critiquing those of others.

3. Cooperative

agents work together towards a shared goal or objectives, exchanging information to enhance a collective solution.

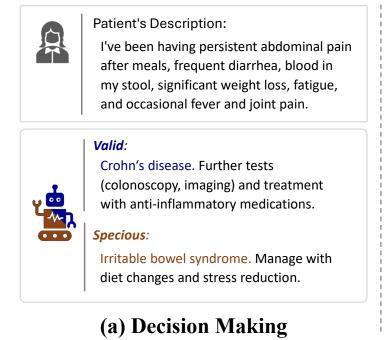
[Consensus Games] suit AI consistency better than [Zero-sum Games] or [Debate Games], as they foster cooperative alignment toward shared objectives rather than competition.

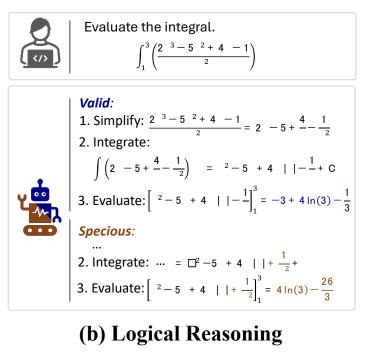
[Consensus Game] Equilibrium Consensus Game^[3]

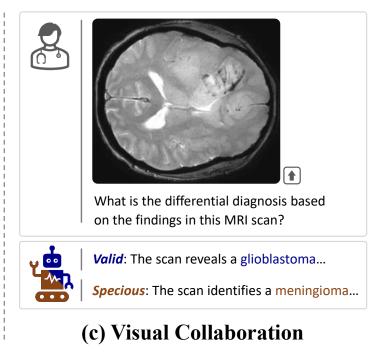


But with **Collusion**, like **Model Collapse** in generic GAN

Where does collusion lead in AI communication?



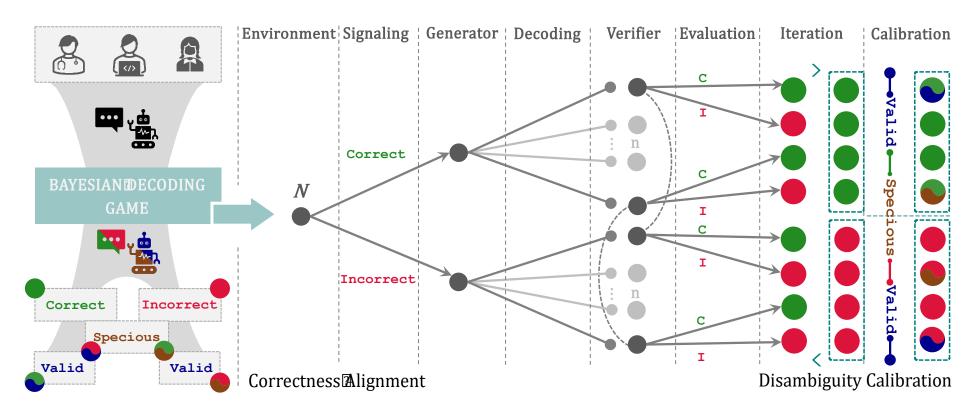




How can we efficiently ensure that LLM outputs are not only aligned with human intent but also valid, especially when human evaluation may overlook specious errors?

BAYESIAN DECODING GAME (BDG)

A multi-step signalling game with complex action spaces



LLMs should match alignment & consistency of {Correct, Incorrect} outputs through a signalling game.

Verifier judges the type of decoding from generators **{Valid, Specious}** based on a convex combination.

No-Regret Optimization

Through repeated interactions and iterative policy refinement, no-regret learning approximates equilibria in large games. Cumulative regret is defined as:

$$\operatorname{Reg}_{i}^{(T)} := \frac{1}{T} \left(\sum_{t=1}^{T} u_{i} \left(s_{i}^{*}, s_{D}^{(t)}; b_{i} \right) - u_{i} \left(s_{i}^{(t)}, s_{D}^{(t)}; b_{i} \right) \right),$$

where s_i^* is the optimal hindsight strategy that maximizes this value. Rather than computing regret at each iteration, s_i^* is selected based on the time-averaged strategy profile.

In sequential games with private information and discrete choices, global regret minimization is achieved by minimizing regret locally within each information set, given the finite nature of these sets. For example, to minimize overall regret, the generator must minimize regret by selecting an optimal mixed strategy s_G , conditioned on the signal correctness received from the environment. The verifier follows a similar procedure, updating its strategy with respect to each $y \in \mathcal{Y}$.

Markovian Strategy Update

$$b_{G}^{(t+1)}(y \mid x, v) = a_{V}^{(t)}(v \mid x, y), \quad b_{V}^{(t+1)}(v \mid x, y) = a_{G}^{(t)}(y \mid x, v)$$

$$a_{G}^{(t+1)}(y \mid x, v) \propto \exp\left\{\frac{\frac{1}{2}b_{G}^{(t+1)}(y \mid x, v) + \lambda_{G} \log a_{G}^{(t)}(y \mid x, v, b_{G}^{(t)})}{1/(\eta_{G}t) + \lambda_{G}}\right\}$$

$$a_{V}^{(t+1)}(v \mid x, y) \propto \exp \left\{ \frac{\frac{1}{2} b_{V}^{(t+1)}(v \mid x, y) + \lambda_{V} \log a_{V}^{(t)}(v \mid x, y, b_{V}^{(t)})}{1/(\eta_{V} t) + \lambda_{V}} \right\}.$$

Markovian Strategy Update. To maximize the utility given by Eq. 1, whereas each player's belief $b_{i,t}$ at time t of the opponent's strategy is given by the opponent's strategy in period t-1. We hence propose a Markovian strategy update schedule. The palyers update their strategy based on the belief:

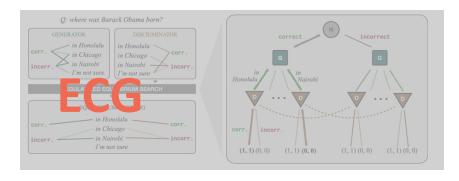
Disambiguity Maximization

Definition 5. (Reliability) A prompt-candidate set (x, \mathcal{Y}) couple can be made **more Reliable** by a Disambiguity Metric if such a η^* exist for the maximization problem $\max \eta$ s.t. $\min Rel(y_{i,C}) \ge \max Rel(y_{i,I}), \ \eta < \overline{\eta}$. If such a maximal η does not exist, then we say that the prompt-candidate set **cannot be made more Reliable** by Disambiguity Metric.

Theorem 4. A prompt-candidate couple can be made **more Reliable** by the disambiguity metric $DA(x,y), y \in \mathcal{Y}$ if and only if (1) $\min c(y_{i,C}) > \max c(y_{i,I})$ and (2) $\overline{\eta} \cdot DA(x,y_{i,I}) + (1-\overline{\eta})c(y_{i,I}) > \overline{\eta} \cdot DA(x,y_{i,C}) + (1-\overline{\eta})c(y_{i,C})$ for some $y_{i,C}, y_{i,I}$

Intuition 2. As for the first condition, the least preferred correct candidate has to be preferred over the most preferred incorrect candidate. Secondly, some incorrect candidates are strictly preferred to some candidates that are initially classified as correct, when disambiguation is maximized. Those two conditions ensure the decoding preference changes under the constraint.

Inherent Inconsistency & Reachable Consistency



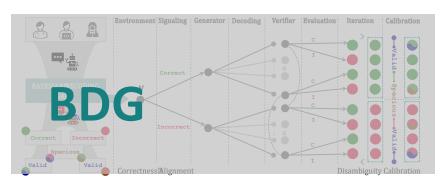


Table 2: Comparison of inconsistency (InC.%) and improvements (Imp.%) between G, ECG, and BDG.

Domain	Model	InC.%	G	ECG	Imp.%	BDG	Imp.%
MMLU	LLaMA-7B LLaMA-13B	69.0% ↓ 60.6% ↓	30.4 41.7	39.9 45.1	31.3% 8.1%	40.5 46.9	33.2% [↑] 12.5% [↑]
ARC-E.	LLaMA-7B LLaMA-13B	56.1% 46.1% 4	68.2 71.2	71.5 76.4	4.8% 7.3%	75.3 78.1	10.4% [↑] 9.7% [↑]
ARC-C.	LLaMA-7B LLaMA-13B	65.9% ↓ 59.1% ↓	47.3 51.9	58.3 61.4	23.2% [↑] 18.3% [↑]	59.6 62.2	26.0% [↑] 19.8% [↑]
RACE-H.	LLaMA-7B LLaMA-13B	62.0% * 58.8% *	46.4 47.9	56.4 62.8	21.5% [↑] 31.1% [↑]	57.7 60.3	24.4% [↑] 25.9% [↑]
Average 59.7% ✓		50.6	59.0	18.2%	60.1	20.2%	

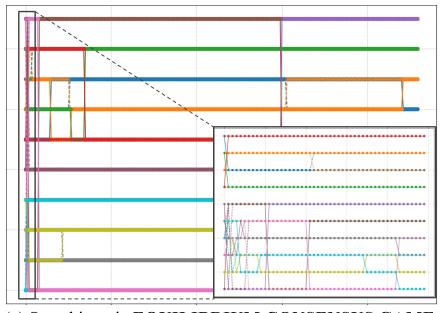
Searching & Convergence Behavior

Question:

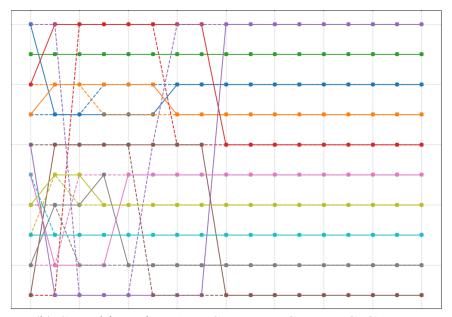
Which of these events during a storm at sea {can, can not } add oxygen from the atmosphere to ocean water? A. high winds B. lightning C. pressure change D. temperature change

G Ranking Candidate 1 G Ranking Candidate 6 **C:** *Mixing Wind (A): Directly mixes oxygen into water.* **I:** Lightning (B): No real impact on oxygen levels. -x- V Ranking Candidate 1 -x- V Ranking Candidate 6 → G Ranking Candidate 2 G Ranking Candidate 7 **C:** Pressure Change (C): Alters gas solubility, affecting oxygen. **I:** Wind (A): Distributes, but doesn't add oxygen. -x- V Ranking Candidate 2 -×- ∨ Ranking Candidate 7 - G Ranking Candidate 3 G Ranking Candidate 8 **C:** *High Winds (A): Cooler water holds more oxygen.* **I:** Temperature Rise (D): Warmer water holds less oxygen. -x- V Ranking Candidate 3 -*- V_Ranking Candidate 8 G Ranking Candidate 4 G Ranking Candidate 9 **C:** Wind (A): Wind-driven waves increase oxygen diffusion. I: Rainfall (#)Doesn't add atmospheric oxygen. -x- V Ranking Candidate 4 -x- V Ranking Candidate 9 - G Ranking Candidate 5 G Ranking Candidate 10 **C:** High Winds (A): Storm winds exchange water and oxygen. **I:** Cloud Cover (#): Irrelevant to oxygen levels. -x- V Ranking Candidate 5 -x- V Ranking Candidate 10

(a) MCQA with Inconsistent & Ambiguous Decoding

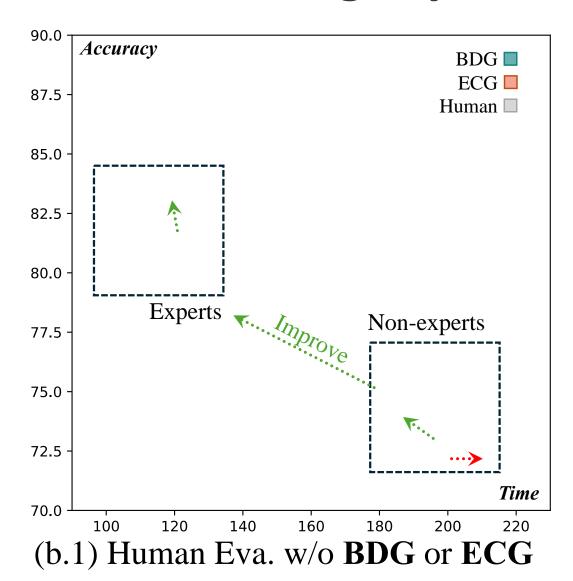


(c) Searching via **EQUILIBRIUM CONSENSUS GAME**



(b) Searching via **BAYESIAN DECODING GAME**

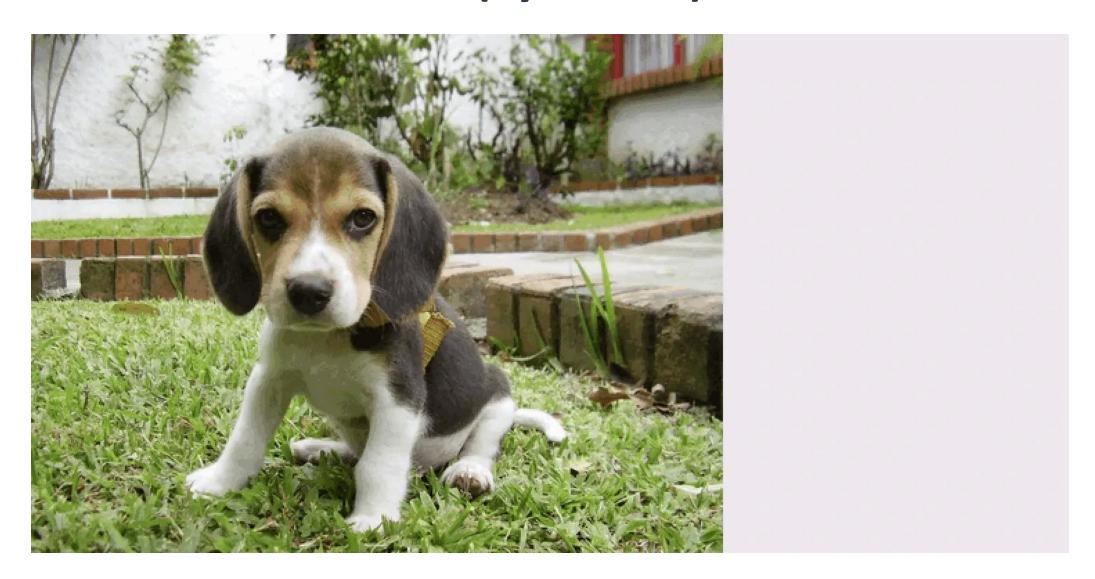
Intrinsic Ambiguity & Provable Reliability



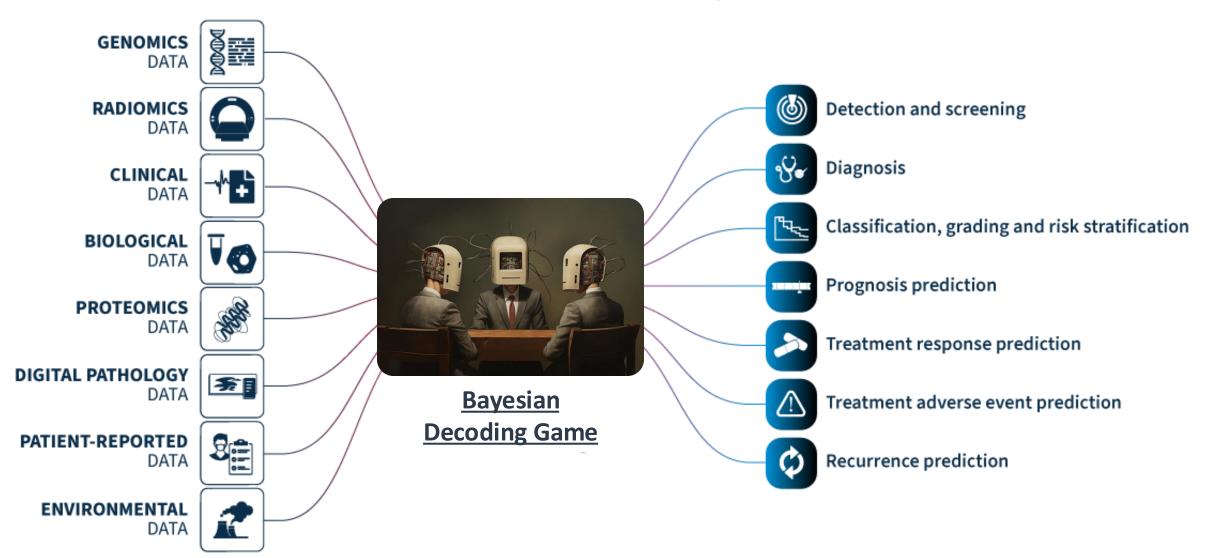
6 Time Accuracy the less, the better the higher, the better

(b.2) Per-case report

Human vs. Al Human (Symbolic) & Als Consensus



Hallucinations Multi-modality Consensus



^[1] https://www.sophiagenetics.com/science-hub/the-power-of-multimodal-data-driven-medicine/

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Thank you for your attention.