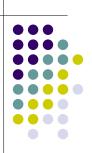
CSCC 69H3

Operating Systems
Summer 2016
Sina Meraji
U of T



Logistics

Instructor: Sina Meraji

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• Office: BA-1180

• Office hours: Tue 17-18 pm(by appointment)

TAs:

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• Arnamoy Bhattacharyya, Jonathan Eidelman

• Webpage:

 http://www.cdf.toronto.edu/~csc369h/summer/index.sht ml



Course Objective



- To understand
 - The role of the OS
 - Its major components
 - The design principles and implementations
 - Working on real Operating System assignments

Workload

Linux kernel has more than 10 million lines of code!



- This course is very work-inter
- Why?
 - Lectures cover a lot of new cor
 - Many of them very abstract
 - · Learning by doing!
 - This course is much more like the real world:
 - Assignments build on realistic O\$
 - Lot of existing code given to you
 - Don't expect to understand all of it
 - You need to be able to work in a team
 - You need to be comfortable with the prereqs.

Assignments (40%)



- Code Reading component:
 - Questions about the code we give you
 - Reinforce lecture concepts, familiarize you with the code **before** you start writing
- Programming component
 - Language for this course is C
 - Correctness and performance considerations
- Design document component
 - Think about what you need to build first
 - Tell us in plain English what you were thinking.
 - Tell us how to find your code.
- Familarize yourself with VMs, VirtualBox,KVM

Exams



- Midterm (20%)
 - Monday, in class time
- Final (40%),
 - Will be cumulative
 - I will be explicit about what you are responsible for on the final
 - Lots of final exams from CSCC69 are available for study
 - You have to get more than 40(out of 100) to pass the course

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There's tons of help ...



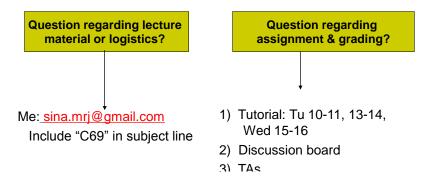
• Instructor: Sina Meraji

TAs:

Discussion board:

Check course webpage

• Who to ask in case of questions?



Academic Dishonesty



- Plagiarism and cheating
 - Please don't do it!
 - Serious academic offenses
 - Can discuss tools and concepts with classmates
 - Can discuss solutions to assignments with your partner only!
 - All potential cases will be investigated fully

Grading



Work	Notes	Weight	Due Date
Assignment 1		13%	TBD
Assignment 2		15%	TBD
Midterm		20%	TBD
Assignment 3		12%	TBD
Final		40%	you have to get more than 40%

Late policy



- Assignments will be submitted electronically
- Due at 11:55pm on due date
- You can submit up to 2 days late
- 10% penalty for each day

Introduction



- Read Chapter 1
 - Some (much?) of this should be review
- What is an OS and why do I want one?
 - How does it relate to the other parts of a computer system?
 - Review some computer organization and C concepts
- What are the major parts of an OS?

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What is an Operating System?



Application programs

Text editor Web browser Compiler

Operating system

Hardware

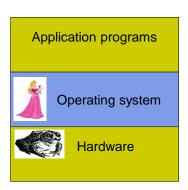
CPU(s) Memory I/O devices

The software layer between user applications and hardware.

- Turns ugly hardware into beautiful abstractions (provides services)
- Serves as a resource manager
 - Allows proper use of resources (hardware, software, data)
- Serves as a control program (protection)
 - Controls execution of user programs to prevent errors and improper use of the computer

What is an Operating System?



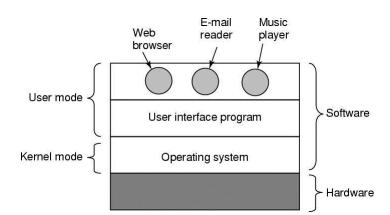


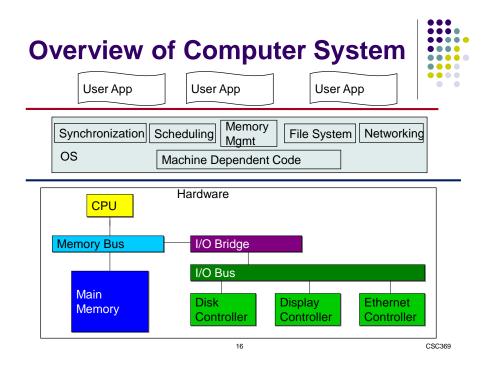
The software layer between user applications and hardware.

- Turns ugly hardware into beautiful abstractions (provides services)
- Serves as a resource manager
- Serves as a control program (protection)
- Will spend much of the rest of the semester on three core abstractions and resource management services:
 - Processes & threads
 - Memory management
 - File & I/O systems

What is an Operating System



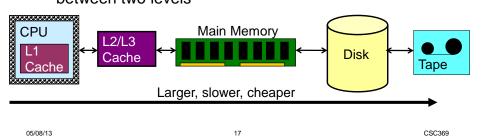




Storage Hierarchy



- Processor registers, main memory, and auxiliary memory form a rudimentary memory hierarchy
- The hierarchy can be classified according to memory speed, cost, and volatility
- Caches can be installed to hide performance differences when there is a large access-time gap between two levels



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Storage Structure



- Main memory (DRAM) stores programs and data during program execution
 - DRAM cannot store these permanently because it is too small & it is a volatile storage device
 - Forms a large array of bytes (1 byte = 8 bits) of memory, each with its own address
 - We say that main memory is byte-addressable

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Caching



- When the processor accesses info at some level of the storage hierarchy, that info may be copied to a cache memory closer to the processor, on a temporary basis
 - A cache is smaller and costlier
- Because caches have limited sizes, cache management is an important design problem
 - Coherency

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Concurrency



- Every modern computer is a multiprocessor
 - CPU and device controllers can execute concurrently, competing for memory cycles
 - A memory controller synchronizes access to shared memory
 - Interrupts allow device controllers to signal the CPU that some event has occurred (e.g. disk I/O complete, network packet arrived, etc.)
 - Generated by a hardware device
 - Interrupts are also used to signal errors (e.g. division by zero) or requests for OS service from a user program (a system call)
 - These types of interrupts are called traps or exceptions
- An Operating System is an event-driven program

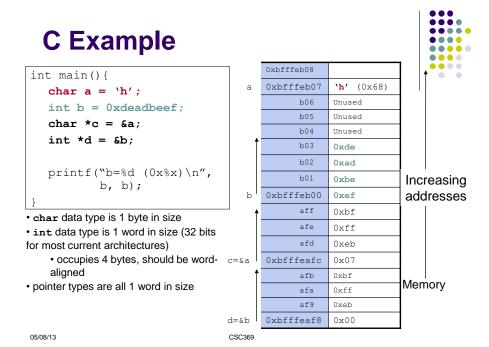
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Aside: C Programming & Memory



- A variable in a C program is a symbolic name for a data item, stored in memory
 - The type of the variable indicates how much storage (how many bytes) it needs
 - Type also determines <u>alignment</u> requirements
 - The address of the variable is an index into the big array of memory words where the data item is stored
 - The value of the variable is the actual contents of memory at that location
 - A pointer type variable is just a data item whose contents are a memory location (usually the address of another var)

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Processes and Threads

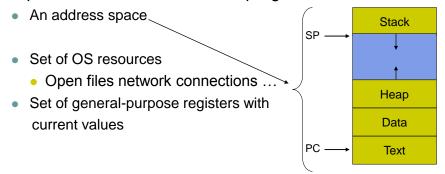


Reading: 2.1-2.2

Part 1: The Process Concept



- Process = job / unit of work
- Process = a program in execution
- A process contains all state of program in execution



A process is named by its process ID (PID)

Process Data Structures



How does the OS represent a process in the kernel?

- At any time, there are many processes in the system, each in its own particular state
- The OS data structure representing each process is called the Process Control Block (PCB)
- The PCB contains all of the info about a process
- The PCB also is where the OS keeps all of a process' hardware execution state (PC, SP, regs, etc.) when the process is not running
 - This state is everything that is needed to restore the hardware to the same configuration it was in when the process was switched out of the hardware (FreeBSD, 81 fields, 408 bytes)

Process Control Block



- Generally includes:
 - Process state (ready, running, blocked ...)
 - Program counter: address of the next instruction
 - CPU registers: must be saved at an interrupt
 - CPU scheduling information: process priority
 - Memory management info: page tables
 - I/O status information: list of open files

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Linux PCB



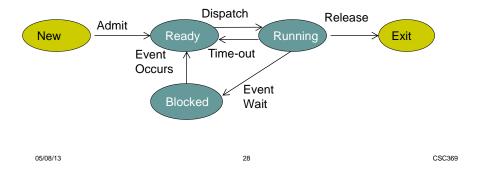
- Called the task struct in Linux
 - Defined in /include/linux/sched.h

```
struct task_struct {
/* these are hardcoded - don't touch */
volatile long state; /* -1 unrunnable, 0 runnable, >0 stopped */
long counter; long priority; unsigned long signal;
unsigned long blocked; /* bitmap of masked signals */
unsigned long flags; /* per process flags, defined below */
int errno; long debugreg[8]; /* Hardware debugging registers */
struct exec_domain *exec_domain;
/* various fields */
struct linux_binfmt *binfmt;
struct task_struct *next_task, *prev_task;
struct task_struct *next_run, *prev_run;
unsigned long saved_kernel_stack;
unsigned long kernel_stack_page;
int exit_code, exit_signal;
```

Process states & state changes



- The OS manages processes by keeping track of their state
 - Different events cause changes to a process state, which the OS must record/implement



State Queues

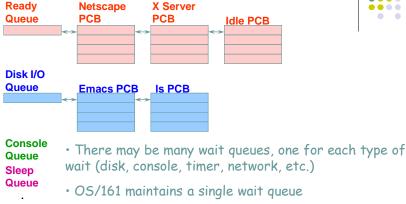


How does the OS keep track of processes?

- The OS maintains a collection of queues that represent the state of all processes in the system
- Typically, the OS has one queue for each state
 - Ready, waiting, etc.
- Each PCB is queued on a state queue according to its current state
- As a process changes state, its PCB is unlinked from one queue and linked into another

State Queues





"struct array *sleepers" in kern/thread/thread.c

record address of thing thread is waiting for

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PCBs and State Queues



- PCBs are data structures dynamically allocated in OS memory
- When a process is created, the OS allocates a PCB for it, initializes it, and places it on the Ready queue
- As the process computes, does I/O, etc., its PCB moves from one queue to another
- When the process terminates, its PCB is deallocated

What is a Context Switch?



- Context switch: switch the CPU to another process, saving the state of the old process and loading the saved state for the new process
- Context switch time is pure overhead, so some systems offer specific hardware support
- A performance bottleneck, so new structures (threads) are being used to avoid it

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Operations on Processes



- Processes execute concurrently and must be created and deleted dynamically
- Process creation:
 - System Initialization
 - A running process
 - A user request
 - Initialization of a batch job
- Process termination:
 - When a process finishes executing last statement
 - When a parent causes the termination of a child
 - An Error occurred

Process Creation



- A process is created by another process
 - Parent is creator, child is created
 - In Linux, the parent is the "PPID" field of "ps -f"
- In some systems, the parent defines (or donates) resources and privileges for its children
 - Unix: Process User ID is inherited children of your shell execute with your privileges
- After creating a child, the parent may either wait for it to finish its task or continue in parallel (or both)

Process Creation: Unix



- In Unix, processes are created using fork()
 int fork()
- fork()
 - Creates a new address space
 - Initializes the address space with a copy of the entire contents of the address space of the parent
 - Initializes the kernel resources to point to the resources used by parent (e.g., open files)
- Fork returns twice
 - Returns the child's PID to the parent, "0" to the child
 - Huh?

fork()

```
int main(int argc, char *argv[])
{
  char *name = argv[0];
  int child_pid = fork();
  if (child_pid == 0) {
     printf("Child of %s is %d\n", name,
     getpid());
     return 0;
  } else {
     printf("My child is %d\n", child_pid);
     return 0;
  }
}
```

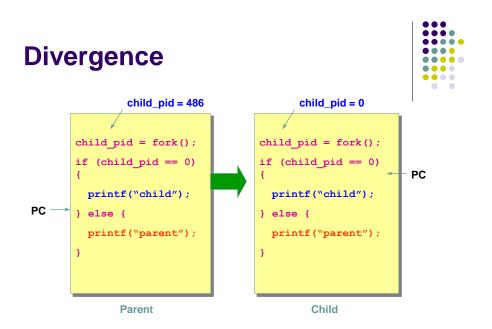
What does this program print?

Example Output



smeraji% cc t.c smeraji% ./a.out My child is 486 Child of a.out is 486

Duplicating Address Spaces child_pid = 486 $child_pid = 0$ PC-PC child_pid = fork(); child_pid = fork(); if (child_pid == 0) if (child_pid == 0) printf("child"); printf("child"); } else { } else { printf("parent"); printf("parent"); **Parent** Child

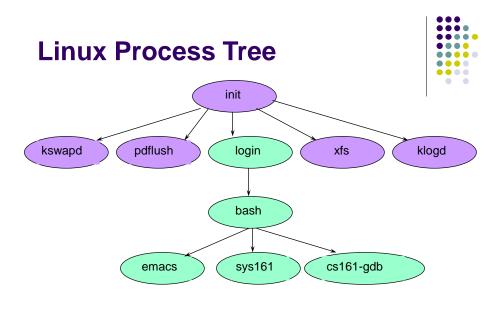


Why fork()?



- Very useful when the child...
 - Is cooperating with the parent
 - Relies upon the parent's data to accomplish its task
- Example: Web server

```
while (1) {
  int sock = accept();
  if ((child_pid = fork()) == 0) {
    Handle client request
  } else {
    .....
  }
}
```



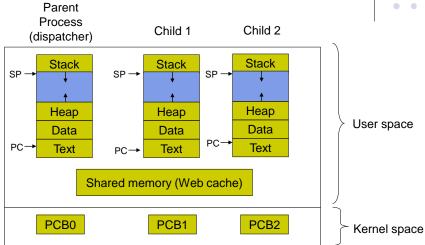
Unix Shells



```
while (1) {
  char *cmd = read_command();
  int child_pid = fork();
  if (child_pid == 0) {
    exec(cmd);
    } else {
    wait(child_pid);
  }
}
```

Example for use of processes: Concurrent Web Server





Parallel Programs



- Recall our Web server example that forks off copies of itself to handle multiple simultaneous requests
 - Or any parallel program that executes on a multiprocessor
- To execute these programs we need to
 - Create several processes that execute in parallel
 - Create shared memory for processes to share data
 - Have the OS schedule these processes in parallel
- This situation is very inefficient
 - Space: PCB, page tables, etc.
 - Time: create data structures, fork and copy addr space, etc.

Example for use of processes: Concurrent Web Server Parent **Process** Child 1 Child 2 (dispatcher) Stack Stack Stack Heap Heap Heap User space Data Data Data Text Text Text Shared memory (Web cache) PCB0 PCB1 PCB2 Kernel space

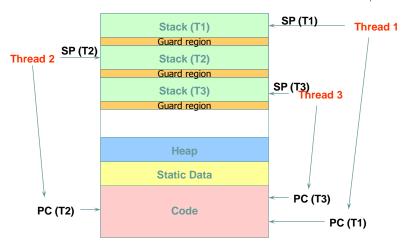
Rethinking Processes



- What is similar in these cooperating processes?
 - They all share the same code and data (address space)
 - They all share the same privileges
 - They all share the same resources (files, sockets, etc.)
- What don't they share?
 - Each has its own execution state: PC, SP, and registers
- Key idea: Why don't we separate the concept of a process from its execution state?
 - Process: address space, privileges, resources, etc.
 - Execution state: PC, SP, registers
- Exec state also called thread of control, or thread

Idea: Have threads in a Process!





Threads



- Separate the concepts of processes and threads
 - The thread defines a sequential execution stream within a process (PC, SP, registers)
 - The process defines the address space and general process attributes (everything but threads of execution)
- A thread is bound to a single process
 - Processes, however, can have multiple threads
 - Every process has at least one thread
- Processes are the containers in which threads execute
 - Processes become static, threads are the dynamic entities

Threads: Concurrent Servers



• Recall our forking Web server:

```
while (1) {
  int sock = accept();
  if ((child_pid = fork()) == 0) {
    Handle client request
  } else {
    Close socket
  }
}
```

 Using fork() to create new processes to handle requests in parallel is overkill for such a simple task

Threads: Concurrent Servers



Instead, we can create a new thread for each request

```
web_server() {
  while (1) {
    int sock = accept();
    thread_fork(handle_request, sock);
  }
}
handle_request(int sock) {
    Process request
    close(sock);
}
```

Thread Interface (Pthread API)



- pthread_create(pthread_t *tid, pthread_attr_t attr, void *(*start_routine)(void *), void *arg)
 - Create a new thread of control
 - New thread id returned in tid, new thread starts executing in start_routine with argument arg
- pthread_join(pthread_t tid)
 - Wait for tid to exit
- pthread_cancel(pthread_t tid)
 - Destroy tid
- pthread_exit()
 - Terminate the calling thread

Thread Scheduling



- The thread scheduler determines when a thread runs
- It uses queues to keep track of what threads are doing
 - Just like the OS and processes
 - But it is implemented at user-level in a library
- Run queue: Threads currently running (usually one)
- Ready queue: Threads ready to run
- Are there wait queues?
 - How would you implement thread_sleep(time)?

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Threads Summary



- The operating system is a large multithreaded program
 - Each process executes as a thread within the OS
- Multithreading is also very useful for applications
 - Efficient multithreading requires fast primitives
 - Processes are too heavyweight
- Solution is to separate threads from processes
- Now, how do we get our threads to correctly cooperate with each other?
 - Synchronization... coming right up!

Cooperating Processes



- A process is independent if it cannot affect or be affected by the other processes executing in the system
- No data sharing ⇒ process is independent
- A process is cooperating if it is not independent
- Cooperating processes must be able to communicate with each other and to synchronize their actions

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Interprocess Communication



- Cooperating processes need to exchange information, using either
 - Shared memory (e.g. fork())
 - Message passing
- Message passing models
 - send(P, msg) send msg to process P
 - receive(Q, msg) receive msg from process Q

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Announcement



- Check course website regularly
- Tutorials start this week