

Estimating treatment effects with competing intercurrent events in randomized controlled trials

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September 23, 2025
Online Causal Inference Seminar

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Overview

Motivating randomized controlled trials (RCTs)

Causal parameter of interest

Assumption and identification

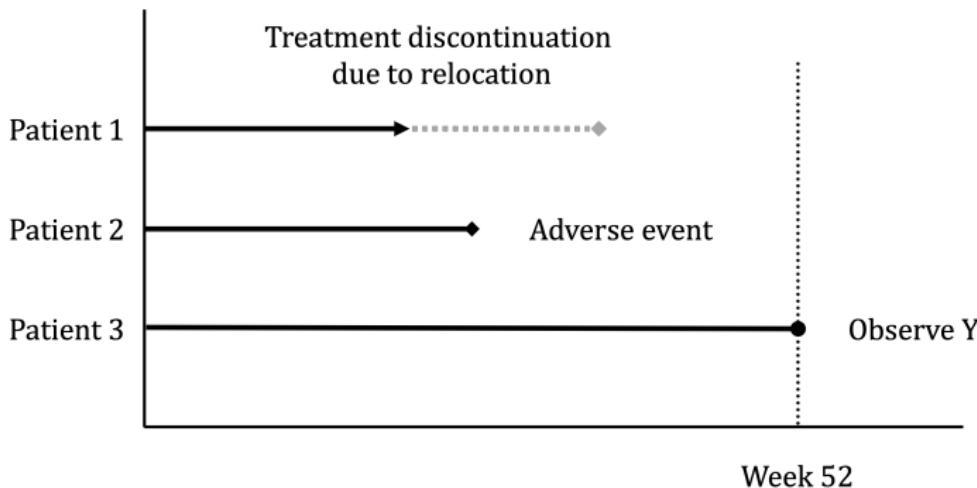
From basic estimators to augmented, robust estimators

Real-world application

Motivating example: two phase-3 immunology trials

- ▶ Morand et al. (2023) and Petri et al. (2023)
- ▶ Causal effect of baricitinib versus placebo on Systemic Lupus Erythematosus
- ▶ Primary endpoint: an immune response index measured *52 weeks after treatment initiation*
- ▶ Ideally, comparisons between two groups
- ▶ Outcomes not measured: 218/760 and 211/775 in two trials

Motivating example: two phase-3 immunology trials



- ▶ Treatment discontinuation due to relocation and adverse event in the example are called intercurrent events (ICEs)
- ▶ ICEs: events that occur *after* the treatment initiation and *affect* either the interpretation or existence of outcome measurements

ICEs in the motivating RCTs

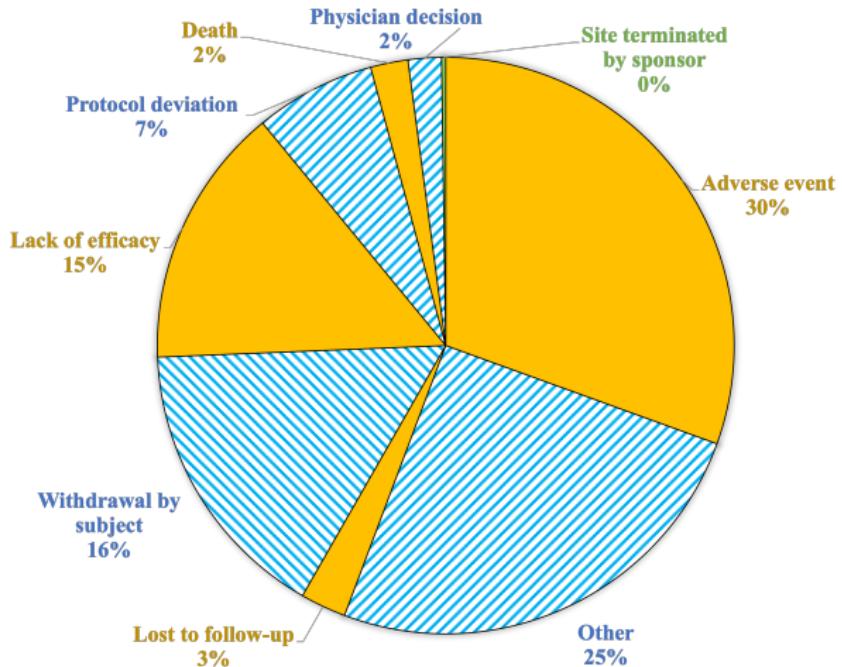


Figure: Pie chart showing the ICE types and proportions

Five strategies to address ICEs

- ▶ ICH E9 (R1): a guideline published in 2019 to address ICEs by the International Council for Harmonisation (ICH)
- ▶ Treatment policy strategy: intention-to-treat-type principle
- ▶ Hypothetical strategy: what if hypothetically the ICE would not occur
- ▶ Composite outcome strategy: modify the causal parameter of interest
 - ▶ an ICE is itself informative about the patients' outcome of interest
 - ▶ e.g., when the outcome is success or failure, the occurrence of ICE can be treated as another mode of failure
- ▶ While-on-treatment strategy: compare outcomes before ICEs
- ▶ Principal stratification strategy: causal effects on subgroups

Our proposal: combine two strategies

- ▶ Classify ICEs into two broad types:
 - ▶ effect-informative ICEs, e.g., adverse effect, lack of efficacy
 - ▶ effect-uninformative ICEs, e.g., treatment discontinuation due to relocation or COVID-19 lockdown
- ▶ Combining composite outcome and hypothetical strategies
 - ▶ effect-informative ICEs: composite outcome strategy
 - ▶ effect-uninformative ICEs: hypothetical strategy
- ▶ Key challenges:
 - ▶ combining composite outcome and hypothetical strategies needs new theory and method
 - ▶ need to deal with competing ICEs

Challenge in combining the two strategies

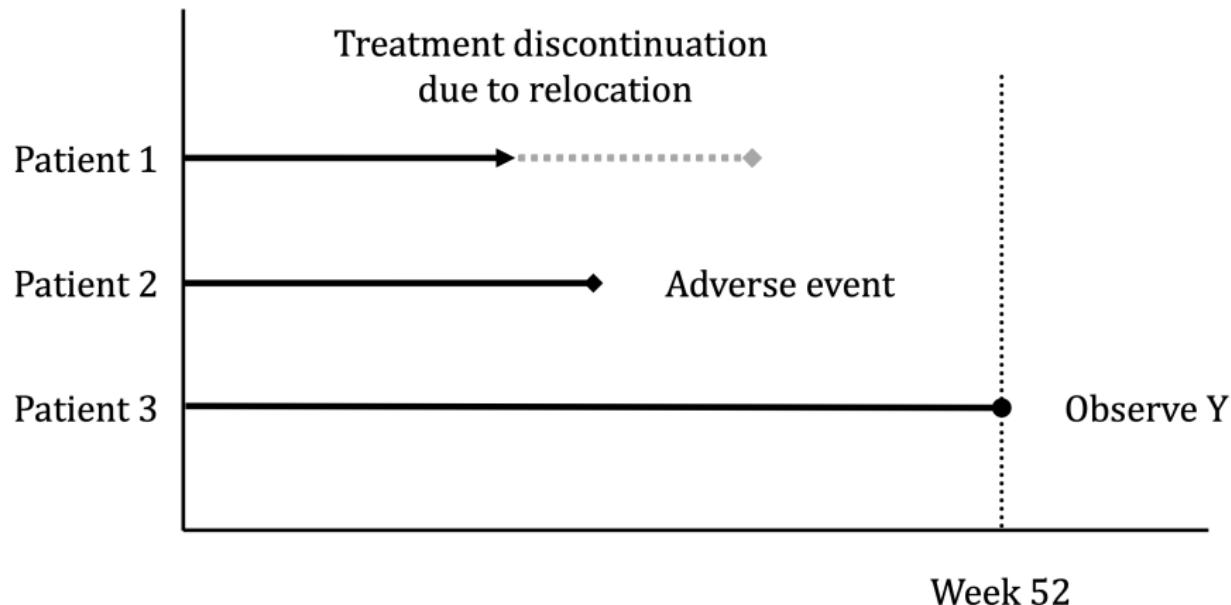


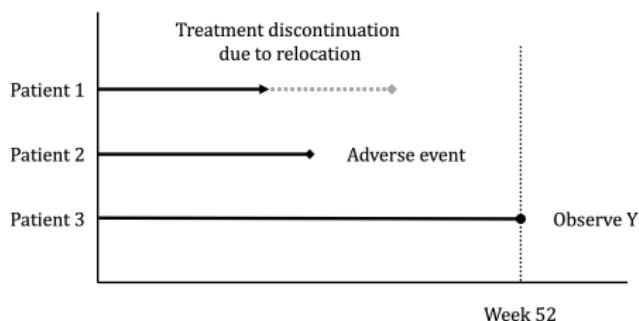
Figure: Illustration of the motivating immunology trial example

Notation and potential outcomes

- ▶ Binary treatment: $A = 1, 0$ for treatment and control
- ▶ Primary endpoint: Y , measured at a pre-specified time point k
- ▶ Two types of ICEs:
 - ▶ effect-informative ICEs: event time T
 - ▶ effect-uninformative ICEs: event time C
- ▶ Define $T = \infty$ if $T > k$, and $C = \infty$ if $C > k$
- ▶ Both ICEs are *post-treatment* variables, thus having potential values $T(a)$ and $C(a)$
- ▶ Potential outcomes: $Y(a, t, c)$
- ▶ Consistency: the observed outcome $Y = Y(A, T(A), C(A))$

Causal parameter of interest

$$\tau = \underbrace{E[Y(1, c = \infty) 1\{T(1) = \infty\}]}_{\text{hypothetical}} - \underbrace{E[Y(0, c = \infty) 1\{T(0) = \infty\}]}_{\text{composite}}$$



observed ICE types	(T, C, k) -relationship	$Y(A, c = \infty)$	$1(T = \infty)$	composite outcome
TD	$T \wedge k > C$?	?	?
AE	$C \wedge k > T$?	0	0
no AE/TD	$C \wedge T > k$	Y	1	Y

Identification assumptions

Assumption 1 (Randomization)

$A \perp\!\!\!\perp \{Y(a, c = \infty), T(a), C(a)\} \mid X$ for $a = 0, 1$.

- Guaranteed by the experimental design in a randomized trial

Identification assumptions

Assumption 1 (Randomization)

$A \perp\!\!\!\perp \{Y(a, c = \infty), T(a), C(a)\} \mid X$ for $a = 0, 1$.

- Guaranteed by the experimental design in a randomized trial

Assumption 2 (Effect-uninformative ICE time)

$C(a) \perp\!\!\!\perp \{Y(a, c = \infty), T(a)\} \mid X$ for $a = 0, 1$.

- Time to treatment discontinuation due to relocation is independent of the hypothetical potential outcome and the time to adverse effect given baseline covariates

Nonparametric identification

Theorem 1 (Nonparametric identification)

Under Assumptions 1 and 2, τ is nonparametrically identified by the following identification formulas:

$$\tau = E \{ \mu_1(X) S_1(k | X) - \mu_0(X) S_0(k | X) \} \quad (1)$$

$$= E \left[\frac{AY1(T \wedge C > k)}{e(X) G_1(k | X)} - \frac{(1-A)Y1(T \wedge C > k)}{\{1-e(X)\} G_0(k | X)} \right]. \quad (2)$$

Nonparametric identification 1: outcome models

$$\tau = E \{ \mu_1(X) S_1(k | X) - \mu_0(X) S_0(k | X) \}, \quad (1)$$

where

- ▶ $\mu_a(X) = E(Y | T \wedge C > k, X, A = a)$: conditional mean of observed outcome in the subsample with no ICE and $A = a$, and

Nonparametric identification 1: outcome models

$$\tau = E \{ \mu_1(X) S_1(k | X) - \mu_0(X) S_0(k | X) \}, \quad (1)$$

where

- ▶ $\mu_a(X) = E(Y | T \wedge C > k, X, A = a)$, and
- ▶ $S_a(k | X) = \text{pr}(T > k | X, A = a)$: survival probability of AE time larger than k in the subsample $A = a$ conditional on covariates

Nonparametric identification 2: weighting

$$\tau = E \left[\frac{AY1(T \wedge C > k)}{e(X)G_1(k | X)} - \frac{(1-A)Y1(T \wedge C > k)}{\{1 - e(X)\}G_0(k | X)} \right], \quad (2)$$

where

- ▶ $e(X) = \text{pr}(A = 1 | X)$: propensity score, and

Nonparametric identification 2: weighting

$$\tau = E \left[\frac{AY1(T \wedge C > k)}{e(X) G_1(k | X)} - \frac{(1 - A)Y1(T \wedge C > k)}{\{1 - e(X)\} G_0(k | X)} \right], \quad (2)$$

where

- ▶ $e(X) = \text{pr}(A = 1 | X)$, and
- ▶ $G_a(k | X) = \text{pr}(C > k | X, A = a)$: conditional probability of not censoring up until time k in the subsample $A = a$

Nonparametric identification

$$\tau = E\{\mu_1(X)S_1(k | X) - \mu_0(X)S_0(k | X)\} \quad (1)$$

$$= E\left[\frac{AY1(T \wedge C > k)}{e(X)G_1(k | X)} - \frac{(1-A)Y1(T \wedge C > k)}{\{1-e(X)\} G_0(k | X)}\right]. \quad (2)$$

- ▶ $\mu_a(X) = E(Y | T \wedge C > k, X, A = a)$
- ▶ $S_a(k | X) = \text{pr}(T > k | X, A = a)$
- ▶ $e(X) = \text{pr}(A = 1 | X)$
- ▶ $G_a(k | X) = \text{pr}(C > k | X, A = a)$
- ▶ Identification of $S_a(t | X)$ and $G_a(t | X)$ for $t \leq k$ (Robin and Rotnitzky, 1992; Robins and Finkelstein, 2000)

Two basic estimators based on two identification formulas

- ▶ Outcome regression estimator:

$$\hat{\tau}^{\text{out}} = n^{-1} \sum_{i=1}^n \hat{\mu}_1(X_i) \hat{S}_1(k | X_i) - n^{-1} \sum_{i=1}^n \hat{\mu}_0(X_i) \hat{S}_0(k | X_i)$$

- ▶ Inverse propensity score weighting estimator:

$$\hat{\tau}^{\text{ipw}} = n^{-1} \sum_{i=1}^n \frac{A_i Y_i \mathbf{1}(T_i \wedge C_i > k)}{\hat{e}(X_i) \hat{G}_1(k | X_i)} - n^{-1} \sum_{i=1}^n \frac{(1 - A_i) Y_i \mathbf{1}(T_i \wedge C_i > k)}{\{1 - \hat{e}(X_i)\} \hat{G}_0(k | X_i)}$$

- ▶ $\hat{\tau}^{\text{out}}$: consistent if **the subsample outcome model** and **the survival function** are correctly specified
- ▶ $\hat{\tau}^{\text{ipw}}$: consistent if **the propensity score model** and **the censoring mechanism** are correctly specified

An augmented, conditionally doubly robust estimator

- ▶ Similar to the classic doubly robust estimator by combining outcome regression and inverse propensity score weighting
- ▶ Augment weighting by outcome regression:

$$\hat{\tau}^{\text{aug}} = \hat{\tau}^{\text{ipw}} - n^{-1} \sum_{i=1}^n \left\{ \frac{A_i - \hat{e}(X_i)}{\hat{e}(X_i)} \hat{\mu}_1(X_i) \hat{S}_1(k | X_i) + \frac{A_i - \hat{e}(X_i)}{1 - \hat{e}(X_i)} \hat{\mu}_0(X_i) \hat{S}_0(k | X_i) \right\}.$$

- ▶ Conditionally doubly robust: Assume $G_a(k | X)$ is correct for $a = 0, 1$. $\hat{\tau}^{\text{aug}}$ is consistent for τ if either $e(X)$ is correct, or both $\mu_a(X)$ and $S_a(k | X)$ are correct for $a = 0, 1$
- ▶ $\hat{\tau}^{\text{aug}}$ improves $\hat{\tau}^{\text{ipw}}$ but may not improve $\hat{\tau}^{\text{out}}$

Another augmented, doubly robust, and semiparametrically efficient estimator, based on efficient influence function

$$\begin{aligned}\hat{\gamma}^{\text{eif}} &= \hat{\gamma}^{\text{aug}} + n^{-1} \sum_{i=1}^n \frac{A_i}{\hat{e}(X_i)} \hat{\mu}_1(X_i) \hat{S}_1(k | X_i) \int_0^{\tilde{T}_i} \frac{dM_{\hat{G}_1}(t)}{\hat{S}_1(t | X_i) \hat{G}_1(t | X_i)} \\ &\quad - n^{-1} \sum_{i=1}^n \frac{1 - A_i}{1 - \hat{e}(X_i)} \hat{\mu}_0(X_i) \hat{S}_0(k | X_i) \int_0^{\tilde{T}_i} \frac{dM_{\hat{G}_0}(t)}{\hat{S}_0(t | X_i) \hat{G}_0(t | X_i)}.\end{aligned}$$

- ▶ $\tilde{T}_i = C_i \wedge T_i \wedge k$ and $\Delta_i = 1(C_i \geq T_i \wedge k)$
- ▶ Further augmentation based on martingales:
 $dM_{G_a}(t) = 1(C \in (t, t + dt], \Delta = 0) - 1(\tilde{T} \geq t)d\Lambda_a(t | X)$ with
 $\Lambda_a(t | X)$ denoting the conditional cumulative hazard function for
the effect-uninformative ICE C in the treatment group $A = a$ for
 $a = 0, 1$

Double robustness and semiparametric efficiency

- ▶ $\hat{\tau}^{\text{eif}}$ is doubly robust in the sense that it is consistent for τ if either
 - ▶ $\mu_a(X)$ and $S_a(t | X)$ are correct for $t \leq k$ and $a = 0, 1$; or
 - ▶ $e(X)$ and $G_a(t | X)$ are correct for $t \leq k$ and $a = 0, 1$
- ▶ $\hat{\tau}^{\text{eif}}$ improves the previous three estimators in terms of robustness
- ▶ Asymptotically linear and achieves the semiparametric efficiency bound

Real-world application

- ▶ Two double-blinded, randomized, placebo-controlled phase-3 immunology trials
- ▶ Effect of baricitinib on systemic lupus erythematosus
- ▶ Doses: 2mg baricitinib, 4mg baricitinib, and placebo
- ▶ Primary outcome: Systemic lupus erythematosus Responder Index 4 (SRI4) at week 52, a binary composite responder index based on:
 - ▶ improvement in disease activity, and
 - ▶ without worsening of the overall condition or the development of substantial disease activity in new organ systems
- ▶ Effect-informative ICEs: 82.6% and 84.4%; and effect-uninformative ICEs: 17.4% and 15.6%
- ▶ Covariates: geographic region, corticosteroid use, Physician's Global Assessment score

Data analysis results

		Trial 1 (Petri et al., 2023)				Trial 2 (Morand et al., 2023)			
		$\hat{\tau}^{\text{out}}$	$\hat{\tau}^{\text{ipw}}$	$\hat{\tau}^{\text{aug}}$	$\hat{\tau}^{\text{eif}}$	$\hat{\tau}^{\text{out}}$	$\hat{\tau}^{\text{ipw}}$	$\hat{\tau}^{\text{aug}}$	$\hat{\tau}^{\text{eif}}$
2mg	point	0.030	0.029	0.026	0.026	0.019	0.019	0.022	0.022
	se	0.042	0.043	0.042	0.043	0.042	0.043	0.043	0.042
	p-value	0.479	0.504	0.534	0.540	0.643	0.662	0.602	0.606
4mg	point	0.113	0.120	0.115	0.113	-0.002	-0.002	-0.002	-0.002
	se	0.046	0.046	0.046	0.046	0.042	0.042	0.042	0.042
	p-value	0.013	0.008	0.012	0.013	0.961	0.962	0.966	0.969

- ▶ Coherent results across estimators: no severe model misspecification
- ▶ Different from ad hoc methods (details in the paper)
- ▶ Incoherent results from two trials: negative results for drug approval

Thank you very much!

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Simulation

	$\hat{\tau}^{\text{out}}$			$\hat{\tau}^{\text{ipw}}$			$\hat{\tau}^{\text{aug}}$			$\hat{\tau}^{\text{eif}}$		
	Bias	SD	CR									
all_correct	0.003	0.100	0.989	0.005	0.154	0.977	0.004	0.152	0.980	0.004	0.110	0.982
e_wrong	-0.002	0.134	0.978	-0.338	0.527	0.916	-0.003	0.479	0.961	0.000	0.234	0.979
e_G_wrong	-0.002	0.130	0.985	-0.194	1.591	0.831	0.141	1.559	0.972	-0.013	0.354	0.969
μ_S _wrong	-0.085	0.170	0.936	-0.009	0.186	0.974	-0.009	0.186	0.974	-0.012	0.176	0.972
all_wrong	0.230	0.233	0.837	0.660	5.799	0.898	0.850	5.782	0.967	0.573	3.022	0.919

Semiparametric efficient influence function (EIF)

Theorem 2 (EIF for μ_1)

Under the nonparametric model with Assumptions 1 and 2, the EIF for μ_1 is

$$D_{\mu_1} = \frac{A}{e(X)} \left\{ \frac{Y1(T \wedge C > k)}{G_1(k | X)} + \mu_1(X)S_1(k | X) \int_0^{\tilde{T}} \frac{dM_{G_1}(t)}{S_1(t | X)G_1(t | X)} \right\} - \frac{A - e(X)}{e(X)} \mu_1(X)S_1(k | X) - \mu_1, \quad (3)$$

- ▶ $\tilde{T} = T \wedge C \wedge k$: the observed event time;
- ▶ $dM_{G_1}(t) = 1(C \in (t, t + dt], \Delta = 0) - 1(\tilde{T} \geq t)d\Lambda_1(t | X)$: the martingale constructed from the censoring counting process;
- ▶ $\Lambda_1(t | X)$: the conditional cumulative hazard function for the censoring C in the treatment subgroup.

EIF estimator

With discrete observed time points, the integration part for i :

$$\begin{aligned} \int_0^{\tilde{T}_i} \frac{dM_{\hat{G}_1}(t)}{\hat{S}_1(t | X_i) \hat{G}_1(t | X_i)} &= \sum_{t \leq \tilde{T}_i} \frac{1(\Delta_i = 0, C_i = t) - \hat{\lambda}_{C_1}(t | X_i)}{\hat{S}_1(t | X_i) \hat{G}_1(t | X_i)} \\ &= - \sum_{t \leq \tilde{T}_i} \frac{\hat{\lambda}_{C_1}(t | X_i)}{\hat{S}_1(t | X_i) \hat{G}_1(t | X_i)} + \frac{1(\Delta_i = 0)}{\hat{S}_1(\tilde{T}_i | X_i) \hat{G}_1(\tilde{T}_i | X_i)}. \end{aligned} \quad (4)$$

- ▶ $\hat{\lambda}_{C_1}(t | X_i)$: estimated conditional hazard of censoring;
- ▶ First term in (4): summation of $-\hat{\lambda}_{C_1}(t | X_i)/\{\hat{S}_1(t | X_i) \hat{G}_1(t | X_i)\}$ over all observed event time points before \tilde{T}_i .
- ▶ Second term in (4):
 - ▶ 0 for observations that are not right-censored by LF;
 - ▶ $1/\{\hat{S}_1(\tilde{T}_i | X_i) \hat{G}_1(\tilde{T}_i | X_i)\}$ for observations with an LF event happened at time \tilde{T}_i .