Date: -----

### **EXPERIMENT #9** TIMING CIRCUITS USING TIMER IC 555

### **I OBJECTIVE**

The objective of this experiment is to familiarize the student with timing applications such as monostable and astable multivibrators.

### II COMPONENTS AND INSTRUMENTATION

The focus will be on the timer IC 555 which is an 8-pin IC (Fig. 9.1). For power supply, you will use +5 V. As well, you need some resistors and capacitors. Note that it is important to bypass each power supply directly on your prototyping board, using a parallel combination of a  $100\mu F$  tantalum or electrolyte capacitors and or  $0.1~\mu F$  low inductance ceramic capacitor. For measurement, you will use a two channel oscilloscope.

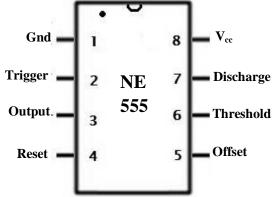


Fig. 9.1 Pin diagram of IC 555

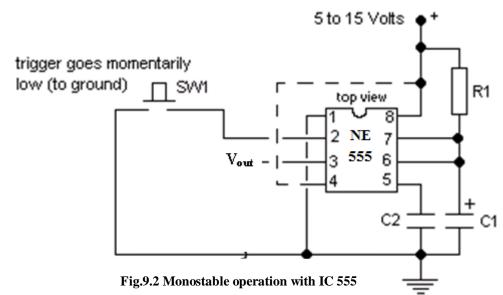
### III BRIEF THEORY

The IC 555 timer must be one of the most useful ICs ever made and it is used in many projects. With just a few external components it can be used to build many circuits and not all of them involve timing! The NE555 monolithic timing circuit is a highly stable controller capable of producing accurate time delays or oscillation. In the monostable mode of operation, the time is precisely controlled by one external resistor and capacitor. For astable operation as an oscillator, the free running frequency and the duty cycle are both accurately controlled with two external resistors and one capacitor. The circuit may be triggered or reset (on falling edge) and the output structure can source or sink up to 200mA.

**3.1** The monostable multivibrator circuit (shown in Fig.9.2) produces a single output pulse when triggered. The duration of the pulse is called the **time period** (T) and this is determined by resistor  $R_1$  and capacitor  $C_1$ . The time period is given by

$$T = 1.1 \times R_1 \times C_1$$

where T is the time period in seconds (s),  $R_1$  is the resistance in ohms ( $\Omega$ ) and  $C_1$  is the capacitance in farads (F). The maximum reliable time period is about 10 minutes. Fig.9.3 shows the typical waveforms of the trigger, the output voltage and the capacitor voltage.



# 3.2 An astable multivibrator circuit

(shown in Fig.9.4) produces a 'rectangular wave'. This is a digital waveform with sharp transitions between low (0V) and high (+ $V_{cc}$ ). The high (ON) and low (OFF) durations are given by

$$T_{on} = 0.7 \times (R_I + R_2) \times C_I$$
 and  
 $T_{off} = 0.7 \times R_2 \times C_I$ 

The time period (T) of the square wave is the time for one complete cycle.

$$T = 0.7 \times (R_1 + 2R_2) \times C_1$$

where T is the time period in seconds (s),  $R_1$  is the resistance in ohms  $(\Omega)$ ,  $R_2$  is the resistance in ohms  $(\Omega)$  and  $C_1$  is the capacitance in farads (F).

**Duty cycle:** The duty cycle of an astable circuit is the proportion of the complete cycle for which the output is high. It is usually expressed as a percentage.

Percentage duty cycle  $\delta = (T_{on}/T)X100$ 

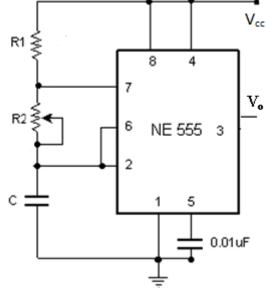
Fig.9.5 shows the typical waveforms of the output voltage and the capacitor voltage.

### Hints for design:

- Choose C<sub>1</sub> first (there are relatively few values available).
- Choose  $R_1$  and  $R_2$  to give the timing intervals. These resistors should be in the range 1k  $\Omega$  to 1M  $\Omega$ . Use a fixed resistor of at least 1k $\Omega$  in series if  $R_1$  is variable (this is not required for  $R_2$  if it is variable).

# trigger O 2Vcc/3 Vc Time (ms) Time (ms)

Fig. 9.3 Typical waveforms for monostable operation with IC 555



# IV PREPARATION

(Answers may be given on the reverse side.)

- Design a circuit using IC555 to produce a rectangular output with T<sub>on</sub> of 0.95ms at a frequency of 1kHz.
- 2. With the output from the circuit in previous question as the trigger signal, design a circuit using IC555 to produce a monostable output with a pulse width of 0.1ms. Is it true or false that this output is monostable but will appear as a 1kHz clock?

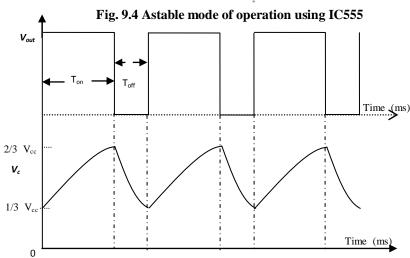


Fig. 9.5 Waveforms for a table operation with IC 555

- 3. It is necessary that the trigger signal in the monostable mode is normally high and should be low for a very short time. Why is this so? What is the consequence otherwise?
- 4. The Fig.9.6 shows divide by 3 operation using IC 555 in monostable mode. Can you suggest how this is possible?
- 5. It is possible to generate a square waveform in a stable mode with IC555, by using a diode. Can you suggest where this diode should be connected? Should there be any other changes in the circuit? In the design values?

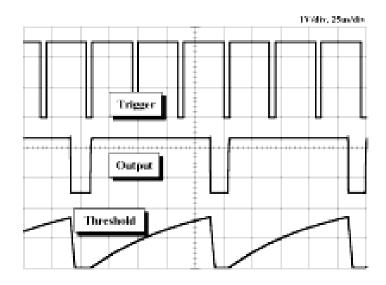
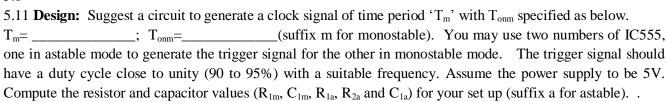


Fig.9.6 Divide by three operation using IC555 as a monoshot

### V EXPLORATIONS

5.1





# **5.3 Procedure:**

- 1. Make the connections as per the approved circuit diagram. With the connections approved, switch on the power supply.
- 2. Firstly verify the working of the astable circuit without connecting its output to the (trigger pin of) monostable circuit.
- 3. Observe the waveforms of capacitor voltage  $(V_{ca})$  and output voltage  $(V_{outa})$  of astable.
- 4. Note the timings  $T_{ona}$  and  $T_{offa}$  and compare with the calculated values. Adjust the setting of any potentiometer to get the required output pulse width.
- 5. Switch off the supply and connect the output of a the trigger input to the monostable circuit.
- 6. Observe the waveforms of capacitor voltage  $(V_{cm})$  and output voltage  $(V_{outm})$  of monostable circuit.
- 7. Verify the synchronization of the output of a stable and the monostable circuits.
- 8. Note the timings  $T_{onm}$  and  $T_{offm}$  and compare with the calculated values.
- 9. Measure (using LCR bridge) and note the values of resistors and capacitors used.

		Tabl	le 9.1 Design	and measur	ed data		
Astable circuit					Monostable circuit		
Tona	$T_{ m offa}$	$C_{1a}$	$R_{1a}$	$\mathbf{R}_{2\mathbf{a}}$	$T_{onm}$	R <sub>1m</sub>	C <sub>1m</sub>
(cal)	(cal)				(cal)		
	]	Revised desig	gn (rounding	to standard	l resistor valu	es)	
Tona	$T_{ m offa}$	C <sub>1a</sub>	$R_{1a}$	$R_{2a}$	Tonm	R <sub>1m</sub>	C <sub>1m</sub>
(cal)	(cal)				(cal)		
			Actually us	ed (measure	ed)		
Tona	$T_{\rm offa}$	C <sub>1a</sub>	$R_{1a}$	$R_{2a}$	Tonm	R <sub>1m</sub>	C <sub>1m</sub>

Compute the $\%$ error in $T_{onm}$ (based on the measured values of components)								