

PRE-DETERMINATION OF PERFORMANCE CHARACTERISTICS OF A THREE PHASE INDUCTION MACHINE USING MATLAB

AC & SPECIAL MACHINES ASSIGNMENT-2

SUBMITTED BY-

SAMBHAV R JAIN

107108103

This is a program written using MATLAB, to pre-determine the performance of a three phase induction machine operated either as a generator or a motor. The only inputs required from the user are no-load and blocked-rotor test results, measured stator resistance. The behavior is analyzed at different slips of operation.

PROGRAM CODE:

```
clc
clear all
close all
disp('This is a program that evaluates the performance characteristics
of a three-phase induction machine from N.L. and B.R. test results');
fs=input('Enter the supplied frequency:');
P=input('Enter the number of poles created by the stator winding:');
Ns=120*fs/P;
s=0:0.001:0.18;
Nr=Ns*(1.-s);
ws=2*pi*Ns/60;
wr=2*pi.*Nr/60;

%Accepting data from the user:
V=input('Please enter the value of rated line voltage of the
machine:\n');
a=menu('How is the stator of the machine connected?','Star','Delta');
if a==1
    Vr=V/sqrt(3);
elseif a==2
    Vr=V;
End

%To get the single phase equivalent circuit parameters from no-load
%and blocked-rotor test results
Voc=input('Enter the no-load terminal voltage per phase:');
Ioc=input('Enter the no-load current per phase:');
Woc=input('Enter the no-load single phase wattmeter reading:');
Vsc=input('Enter the blocked-rotor terminal voltage per phase:');
Isc=input('Enter the blocked-rotor current per phase:');
Wsc=input('Enter the blocked-rotor single phase wattmeter reading:');
Rl=input('Enter the measured stator resistance(a.c.) per phase:');
```

```
%No load parameter determination
pfoc=Woc/Voc/Ioc;
Iw=Ioc*pfoc;
Im=Ioc*sqrt(1-pfoc^2);
R0=Voc/Iw;
X0=Voc/Im;

%Blocked rotor parameter determination
Z01=Vsc/Isc;
R01=Wsc/Isc^2;
X01=sqrt(Z01^2-R01^2);
R2dash=R01-R1;

%Calculation
Rldash=R2dash*(1./s-1);
I2dash=Vr./(R01+Rldash+X01*i);
Z0=(R0*X0*i)/(R0+X0*i);
I0=Vr/Z0;
I1=I0+I2dash; %This is the total load current drawn per phase
Pir=3*(abs(I2dash).^2)*R2dash./s; %Three-phase power input to the
%rotor
%abs returns the magnitude of a complex number)
Pd=3*(abs(I2dash).^2).*Rldash; %Total power developed
Td=Pir./ws; %Developed torque
Wm=3*(Woc/3); %Assuming 1/3rd of no-load losses is mechanical losses
%Woc is per phase, hence multiplying it by three
Wi=3*(Woc*2/3); %Assuming 2/3rd of no-load losses is iron losses
%Woc is per phase, hence multiplying it by three
Wcu1=3*(abs(I1).^2)*R1; %Stator copper losses
Po=Pd-Wm; %Total output power
Pi=Pir+Wcu1+Wi; %Total input power (three phase)
n=Po./Pi*100; %Efficiency
pf=(Pi/3)./(Vr*abs(I1));
```

```
%Plots
m=1;
while m~=2
    k=menu('Choose:', 'Torque-Slip', 'Power-Slip', 'Speed-Torque', 'Slip-
Output Power', 'Load current-Output Power', 'Speed-Output
Power', 'Efficiency-Output Power', 'Power Factor-Output Power');
    switch k
        case 1
            plot(s*100, Td);
            grid on;
            xlabel('% Slip, s ----->');
            ylabel('Developed Torque, Td (N-m) ----->');
            title('Torque-Slip Characteristic');
        case 2
            plot(s*100, Pd);
            grid on;
            xlabel('% Slip, s ----->');
            ylabel('Developed Power, Pd (W) ----->');
            title('Power-Slip Characteristic');
        case 3
            plot(Td, Nr);
            grid on;
            xlabel('Developed Torque, Td (N-m) ----->');
            ylabel('Speed, Nr (RPM) ----->');
            title('Speed-Torque Characteristic');
        case 4
            plot(Po, s*100);
            grid on;
            xlabel('Output Power, Po (W) ----->');
            ylabel('% Slip, s ----->');
            title('Slip-Output Power Characteristic');
        case 5
            plot(Po, sqrt(3)*abs(I1));
            grid on;
            xlabel('Output Power, Po (W) ----->');
```

```
ylabel('Load current, I (A) ----->');
title('Load Current-Output Power Characteristic');
case 6
    plot(Po,Nr);
    grid on;
    xlabel('Output Power, Po (W) ----->');
    ylabel('Speed, Nr (RPM) ----->');
    title('Speed-Output Power Characteristic');
case 7
    plot(Po,n);
    grid on;
    xlabel('Output Power, Po (W) ----->');
    ylabel('% Efficiency, n ----->');
    title('Efficiency-Output Power Characteristic');
case 8
    plot(Po,pf);
    grid on;
    xlabel('Output Power, Po (W) ----->');
    ylabel('Power Factor, P.F. ----->');
    title('Power Factor-Output Power Characteristic');
end
m=menu('Would you like to plot another characteristic?','Yes','No');
end
```

OUTPUT:

This is a program that evaluates the performance characteristics of a three-phase induction machine from N.L. and B.R. test results

Enter the supplied frequency:50

Enter the number of poles created by the stator winding:4

Please enter the value of rated line voltage of the machine:

415

Enter the no-load terminal voltage per phase:408

Enter the no-load current per phase:4.2/sqrt(3)

Enter the no-load single phase wattmeter reading:256/3

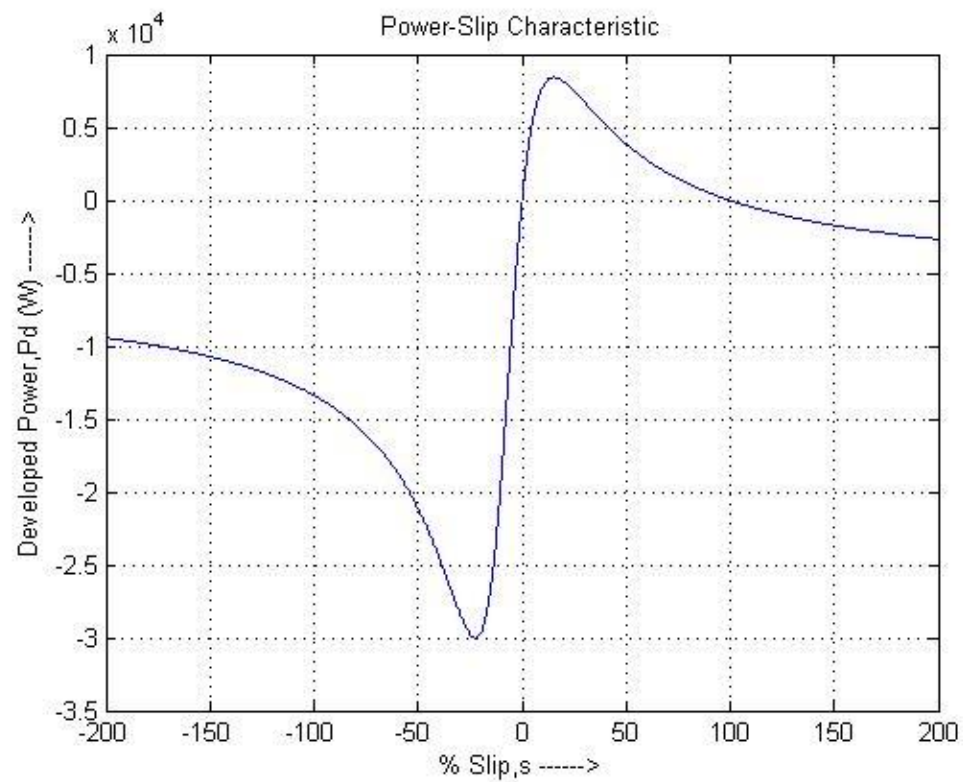
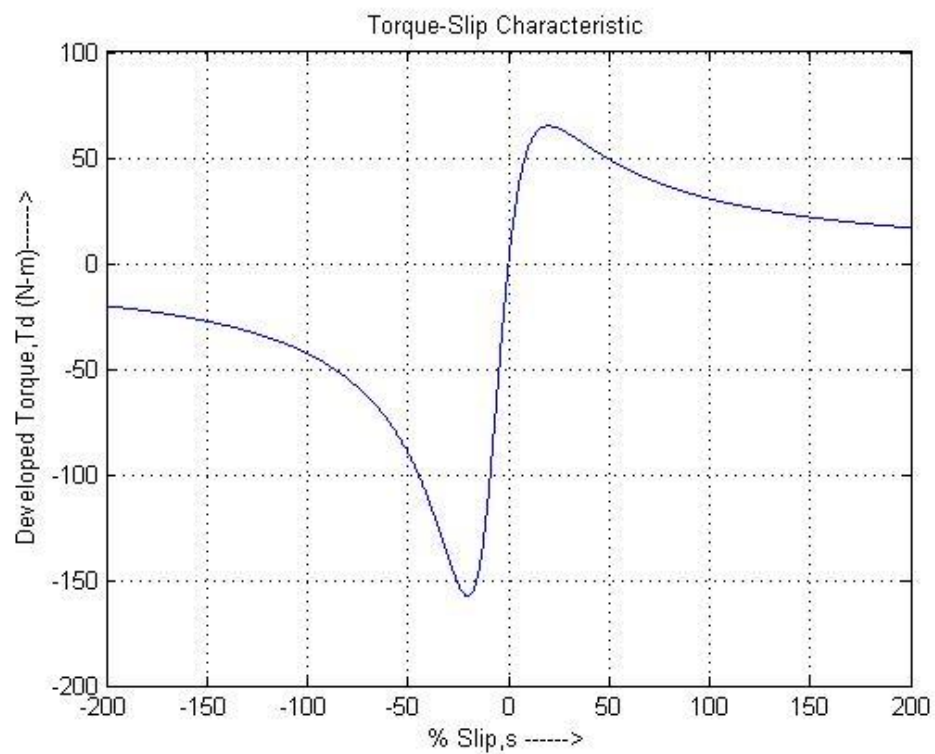
Enter the blocked-rotor terminal voltage per phase:85

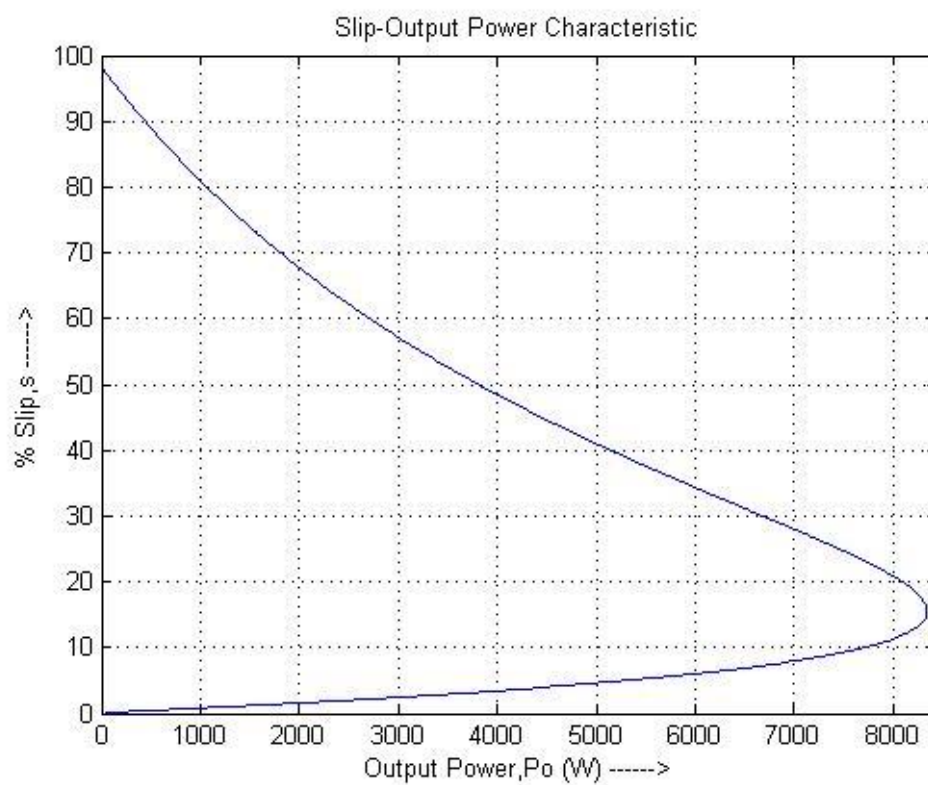
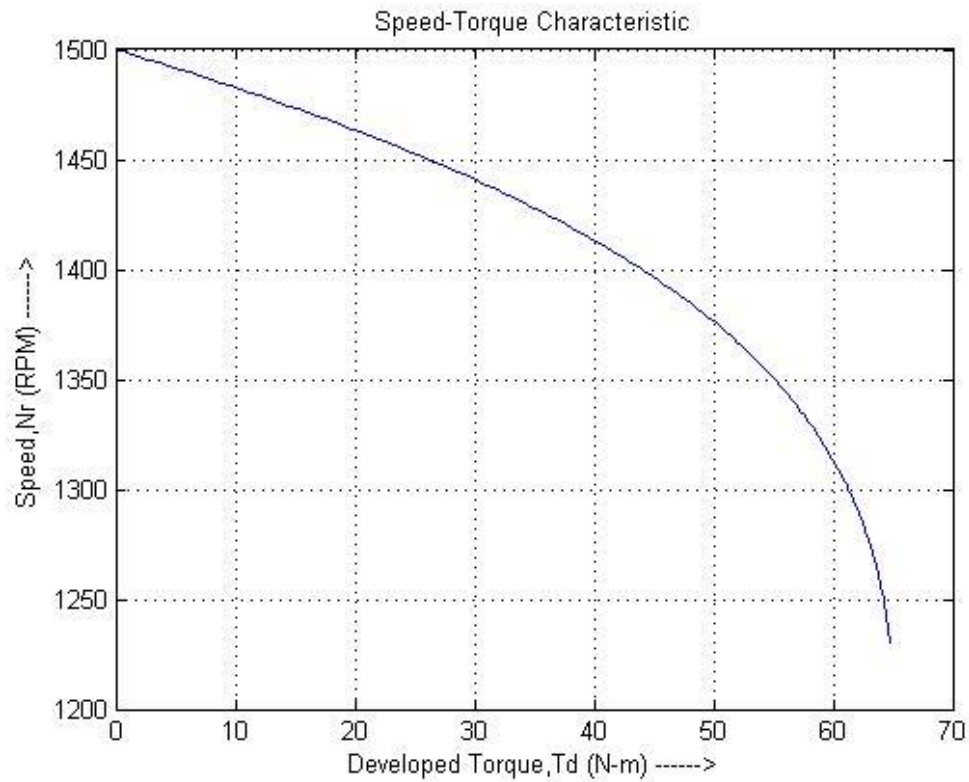
Enter the blocked-rotor current per phase:7.5/sqrt(3)

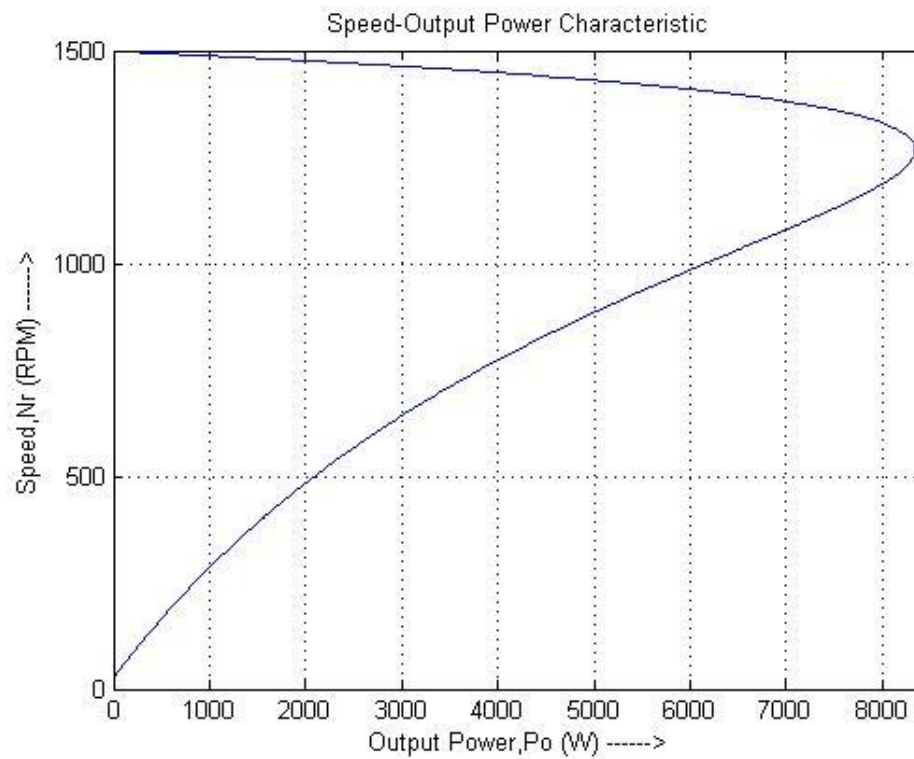
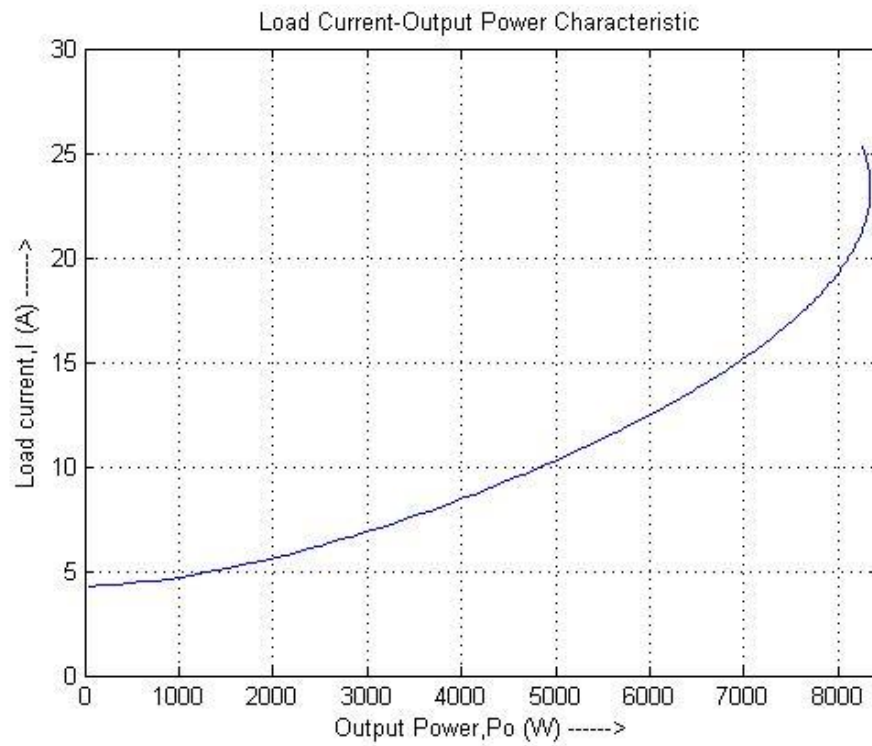
Enter the blocked-rotor single phase wattmeter reading:620/3

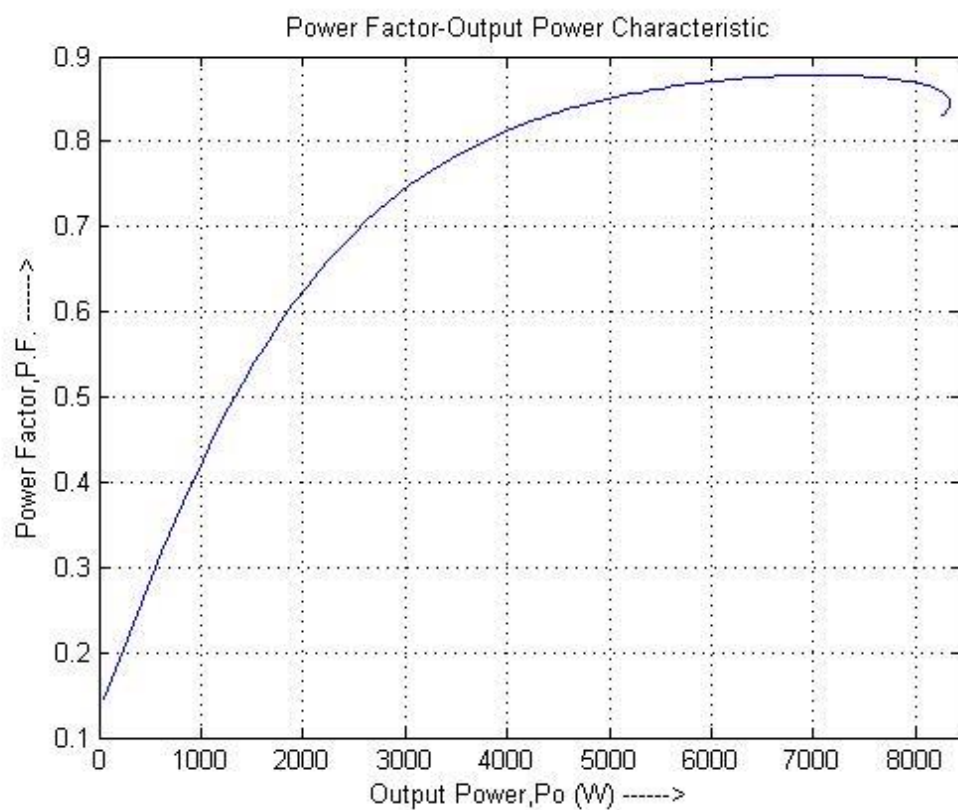
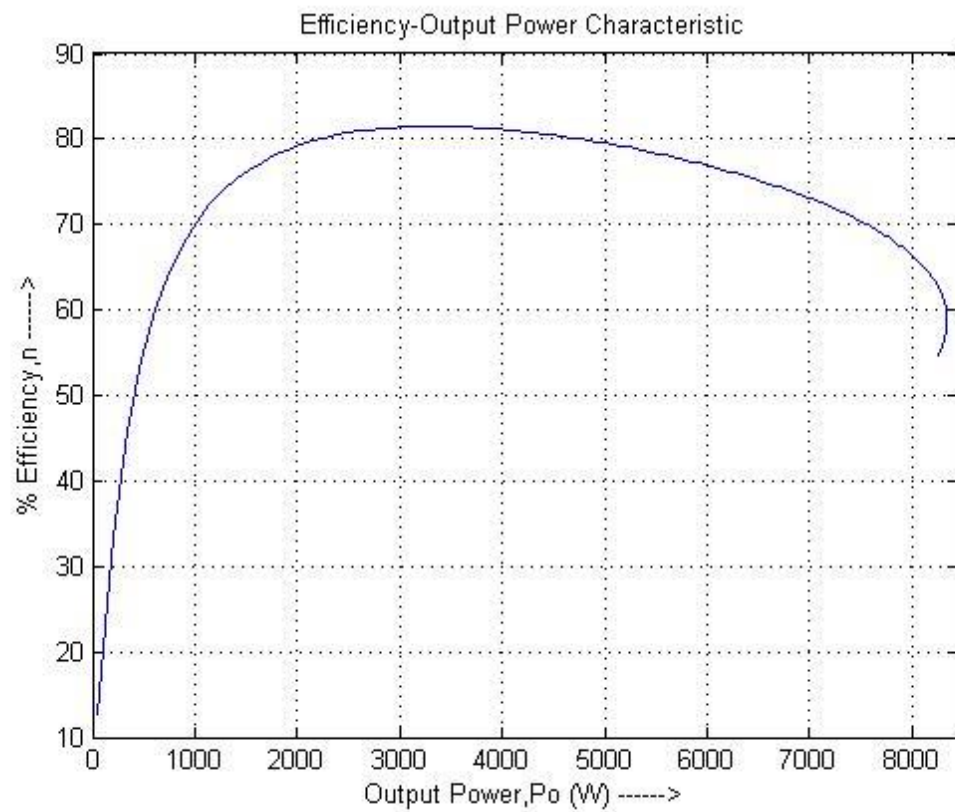
Enter the measured stator resistance(a.c.) per phase:7.425

PLOTS:









RESULT:

Hence the performance characteristics of a three phase induction machine are pre-determined using MATLAB, and its behavior is analyzed at various slips of operation.