

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1 \\ a_{21}x_1 + a_{22}x_2 + a_{23}x_3 = b_2 \end{cases} \rightarrow \begin{bmatrix} a_{11} \\ a_{21} \end{bmatrix} \vec{x}_1 + \begin{bmatrix} a_{12} \\ a_{22} \end{bmatrix} \vec{x}_2 + \begin{bmatrix} a_{13} \\ a_{23} \end{bmatrix} \vec{x}_3 = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 1 & 1 \\ \vec{a}_1 & \vec{a}_2 & \vec{a}_3 \end{bmatrix} \begin{bmatrix} \vec{x}_1 \\ \vec{x}_2 \\ \vec{x}_3 \end{bmatrix} = \begin{bmatrix} \vec{b} \end{bmatrix} \rightarrow A\vec{x} = \vec{b}$$

• Matrix times matrix

$$AB \triangleq \left[\begin{array}{c|c|c|c|c} A & | & b_1 & b_2 & \cdots & b_p \end{array} \right] \triangleq \left[\begin{array}{c|c|c|c|c} 1 & 1 & \cdots & 1 \\ Ab_1 & Ab_2 & \cdots & Ab_p \end{array} \right]$$

\top matrix times vector

\Rightarrow Each column of AB is a linear combination of the columns of A with weights given by the corresponding column of B .

Remark) Show that $(AB)\vec{x} = A(B\vec{x})$ (associative property)

$$\begin{aligned} \rightarrow (AB)\vec{x} &= x_1 \underbrace{[AB]}_{\text{first column of } (AB)}_1 + x_2 [AB]_2 + \cdots \\ \vec{x} &= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \end{bmatrix} \\ &= x_1 A\vec{b}_1 + x_2 A\vec{b}_2 + \cdots \\ &= Ax_1\vec{b}_1 + Ax_2\vec{b}_2 \\ &= A(\underbrace{x_1\vec{b}_1 + x_2\vec{b}_2 + \cdots}_{B\vec{x}}) \\ &= A(B\vec{x}) \end{aligned}$$

Example) Suppose that $A \in \mathbb{R}^{m \times n}$, $B \in \mathbb{R}^{p \times q}$

(a) Under which condition does AB makes sense?

$$\rightarrow n=p$$

(b) What is the dim. of AB ?

$$\rightarrow AB \in \mathbb{R}^{m \times q}$$

Theorem)

- $A(BC) = (AB)C$
- $A(B+C) = AB+AC$
- $(A+B)C = AC+BC$

(associative property) HW
 (left distributive property)
 (right " — ")

- Transpose of a matrix

Def) The transpose A^T of a matrix A is the matrix whose columns are formed from the corresponding row of A .

Example) $\begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix}^T = \begin{bmatrix} a & c & e \\ b & d & f \end{bmatrix}$

A matrix is called symmetric if $A^T = A$.

Example) Show that $(AB)^T = B^T A^T$

$$\Rightarrow \underbrace{[AB]_{(i,j)}}_{(i,j)\text{ th element of } (AB)} = \left\langle \underbrace{[A]_{(i,:)}}_{i\text{-th row vector of } A}, \underbrace{[B]_{:,j}}_{j\text{-th column vector of } B} \right\rangle$$

$$[(AB)^T]_{(i,j)} = [(AB)]_{(j,i)} = \left\langle [A]_{(j,:)}, [B]_{:,i} \right\rangle \quad - (*)$$

$$[B^T A^T]_{(i,j)} = \left\langle [B^T]_{(i,:)}, [A^T]_{:,j} \right\rangle = \left\langle [B]_{:,i}, [A]_{(j,:)} \right\rangle \quad - (**)$$

$$\therefore (*) = (**) , \quad (AB)^T = B^T A^T.$$

Theorem)

$$\begin{aligned} (A^T)^T &= A \\ (A+B)^T &= A^T + B^T \\ (AB)^T &= B^T A^T \end{aligned}$$

Example) Show that $(ABC)^T = C^T B^T A^T$

$$\Rightarrow (ABC)^T = ((AB)C)^T = C^T (AB)^T = C^T B^T A^T$$

- LU decomposition

- Definition) An elementary matrix is one that is obtained by performing a single elementary row operation on an identity matrix.

→ The result of an elementary row operation on A is EA . elementary matrix

$$\star \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \xrightarrow{R1 \leftrightarrow R2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} c & d \\ a & b \end{bmatrix}$$

$$\star \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \xrightarrow{R2 \leftarrow 2R2} \begin{bmatrix} 1 & & \\ & 2 & \\ & & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & & \\ & 2 & \\ & & 1 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = \begin{bmatrix} a & b & c \\ 2d & 2e & 2f \\ g & h & i \end{bmatrix}$$

$$\star \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \xrightarrow{R3 \leftarrow R3 + 3R1} \begin{bmatrix} 1 & & \\ & 1 & \\ 3 & & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = \begin{bmatrix} a & b & c \\ d & e & f \\ g+3a & h+3b & i+3c \end{bmatrix}$$

- Elementary matrices are invertible because elementary row operations are reversible.

$$\begin{bmatrix} 1 & \\ 3 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & \\ -3 & 1 \end{bmatrix} \quad R3 \leftarrow R3 + 3R1$$

$$\begin{bmatrix} 1 & \\ 2 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & \\ -2 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & \\ 1 & 2 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & \\ 1 & \frac{1}{2} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \quad (\text{interchange})$$

- Gaussian elimination revisited.

$$A = \begin{bmatrix} 2 & 1 \\ 4 & -6 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 2 & 1 \\ 4 & -6 \end{bmatrix} \xrightarrow{R2 \leftarrow R2 - 2R1} \begin{bmatrix} 2 & 1 \\ 0 & -8 \end{bmatrix} \quad (\text{echelon form})$$

$$\begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 4 & -6 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 0 & -8 \end{bmatrix}$$

$$E \ A = B$$

lower triangular form
↑
upper triangular form

$$A = E^{-1} B \Rightarrow \begin{bmatrix} 2 & 1 \\ 4 & -6 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 0 & -8 \end{bmatrix}$$

$$A = E^{-1} B$$

* $A = LU$ is known as the LU decomposition of A.

Example) Factor $A = \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix}$ as $A = LU$

$$\Rightarrow \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \xrightarrow[E_1]{R_2 \leftarrow R_2 - 2R_1} \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ -2 & 7 & 2 \end{bmatrix} \xrightarrow[E_2]{R_3 \leftarrow R_3 + R_1} \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 8 & 3 \end{bmatrix} \xrightarrow[E_3]{R_3 \leftarrow R_3 + R_2} \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix} = U$$

$$E_3 E_2 E_1 A = U \Rightarrow A = \underbrace{E_1^{-1} E_2^{-1} E_3^{-1}}_{L} U$$

$$\text{where } E_1 = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, E_1^{-1} = \begin{bmatrix} 1 & & \\ 2 & 1 & \\ 0 & 0 & 1 \end{bmatrix}$$

$$E_2 = \begin{bmatrix} 1 & & \\ 0 & 1 & \\ 0 & 0 & 1 \end{bmatrix}, E_2^{-1} = \begin{bmatrix} 1 & & \\ 0 & 1 & \\ 0 & 0 & 1 \end{bmatrix}$$

$$E_3 = \begin{bmatrix} 1 & & \\ 0 & 1 & \\ 0 & 0 & 1 \end{bmatrix}, E_3^{-1} = \begin{bmatrix} 1 & & \\ 0 & 1 & \\ 0 & 0 & 1 \end{bmatrix}$$

$$L = E_1^{-1} E_2^{-1} E_3^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \quad \therefore \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A \quad L \quad U$$

• Remark) Once we have $A = LU$, it is simple to solve $A\vec{x} = \vec{b}$

$$\begin{aligned} & A\vec{x} = \vec{b} \\ \Leftrightarrow & L(U\vec{x}) = \vec{b} \\ & \quad \text{with } \vec{c} \\ \Leftrightarrow & L\vec{c} = \vec{b}, \quad U\vec{x} = \vec{c} \end{aligned}$$

* Both of $(L\vec{c} = \vec{b})$ and $(U\vec{x} = \vec{c})$ are triangular and hence easily solved.

• $L\vec{c} = \vec{b}$ by forward substitution

• $U\vec{x} = \vec{c}$ by back substitution

* This can be quickly repeated for different \vec{b} !

$$\begin{bmatrix} \text{triangle} \\ \text{shape} \end{bmatrix} \begin{bmatrix} 1 \\ c \\ 1 \end{bmatrix} = \begin{bmatrix} b \\ 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} \text{triangle} \\ \text{shape} \end{bmatrix} \begin{bmatrix} 1 \\ x \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ c \\ 1 \end{bmatrix}$$

* $O(N)$

Example) Solve $\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \vec{x} = \begin{bmatrix} 4 \\ 10 \\ -3 \end{bmatrix}$ from $\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ -3 & 0 & 2 \\ 1 & 1 & 1 \end{bmatrix}$
 \Rightarrow HW

Definition) A permutation matrix is one that is obtained by performing row exchanges on an identity matrix

Theorem) For any matrix A , there is a permutation matrix P such that

$$PA = LU$$

Example) $A = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 1 & 0 \\ 2 & 1 & 0 \end{bmatrix}$, do LU decomposition.

$$PA = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} A \end{bmatrix} = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow[\substack{E \\ \text{=} \\ \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}]{\substack{R2 \leftarrow R2 - \frac{1}{2}R1}} \begin{bmatrix} 2 & 1 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} = U$$

$$\hookrightarrow E(PA) = U$$

$$PA = E^{-1}U = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_L \underbrace{\begin{bmatrix} 2 & 1 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}}_U$$

$$\therefore PA = LU$$