

- Bases for column and nullspaces

Bases for null spaces

To find a basis for  $\text{Nul}(A)$ :

- Find the parametric form of the solutions to  $A\vec{x} = \vec{0}$ .
- Express solutions  $\vec{x}$  as a linear combination of vectors with free variables as coefficients.
- These vectors form a basis of  $\text{Nul}(A)$ .

Example) Find  $\text{Nul}(A)$  with

$$A = \begin{bmatrix} 3 & 6 & 6 & 3 & 9 \\ 6 & 12 & 15 & 0 & 3 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 3 & 6 & 6 & 3 & 9 \\ 6 & 12 & 15 & 0 & 3 \end{bmatrix} \xrightarrow{\text{R2} \leftarrow \text{R2} - 2\text{R1}} \begin{bmatrix} 3 & 6 & 6 & 3 & 9 \\ 0 & 0 & 3 & -6 & -15 \end{bmatrix} \xrightarrow{\text{R1} \leftarrow \text{R1} - 3\text{R2}} \begin{bmatrix} 3 & 6 & 0 & 15 & 39 \\ 0 & 0 & 3 & -6 & -15 \end{bmatrix}$$

$$\xrightarrow{\text{R1}/3, \text{R2}/3} \begin{bmatrix} 1 & 2 & 0 & 5 & 13 \\ 0 & 0 & 1 & -2 & -5 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{cases} x_1 = -2x_2 - 5x_4 - 13x_5 \\ x_2 = x_2 \\ x_3 = 2x_4 + 5x_5 \\ x_4 = x_4 \\ x_5 = x_5 \end{cases} \xrightarrow{\vec{x} = \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}x_2 + \begin{bmatrix} -5 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix}x_4 + \begin{bmatrix} 13 \\ 0 \\ 5 \\ 0 \\ 1 \end{bmatrix}x_5}$$

$$\therefore \text{Nul}(A) = \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 13 \\ 0 \\ 5 \\ 0 \\ 1 \end{bmatrix} \right\}$$

*always*

\* Are these vectors linearly independent?  
 $\Rightarrow$  Yes,

- Bases for column spaces

$\rightarrow$  A basis of  $\text{Col}(A)$  is given by the pivot columns of  $A$ .

Example) Find a basis for  $\text{Col}(A)$  with

$$A = \begin{bmatrix} 1 & 2 & 0 & 4 \\ 2 & 4 & 1 & 3 \\ 3 & 6 & 2 & 22 \\ 4 & 8 & 0 & 16 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 2 & 0 & 4 \\ 2 & 4 & 1 & 3 \\ 3 & 6 & 2 & 22 \\ 4 & 8 & 0 & 16 \end{bmatrix} \xrightarrow{\text{Gauss-Jordan}} \begin{bmatrix} 1 & 2 & 0 & 4 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{RREF}}$$

$$\therefore \text{A basis of } \text{Col}(A) \text{ is } \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \\ 0 \end{bmatrix} \right\}.$$

- The four fundamental subspaces.

Definition : The row space of  $A$  is  $\text{Col}(A^T)$ .  
 The left null space of  $A$  is  $\text{Nul}(A^T)$ .

Theorem) Fundamental theorem of linear algebra. (FTLA)

Let  $A \in \mathbb{R}^{m \times n}$  of rank  $r$ .

- $\dim \text{Col}(A) = r$
- $\dim \text{Col}(A^T) = r$  # of columns
- $\dim \text{Nul}(A) = n - r$
- $\dim \text{Nul}(A^T) = m - r$  # of rows

- Linear transformations.

Definition) A map  $T: V \rightarrow W$  is a linear transformation if

$$\forall \vec{x}, \vec{y} \in V, \forall c, d \in \mathbb{R}$$

$$T(c\vec{x} + d\vec{y}) = cT(\vec{x}) + dT(\vec{y})$$

↓

In other words, a linear transformation respects addition & scaling.

$$1) T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y})$$

$$2) T(c\vec{x}) = c \cdot T(\vec{x})$$

$$3) T(\vec{0}) = \vec{0}$$

Example) Let  $A$  be an  $m \times n$  matrix, then  $T(\vec{x}) = A\vec{x}$  is a linear transformation  
 $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ .

$$\rightarrow T(a\vec{x} + b\vec{y}) = A(a\vec{x} + b\vec{y}) = a \underbrace{A\vec{x}}_{T(\vec{x})} + b \underbrace{A\vec{y}}_{T(\vec{y})} = aT(\vec{x}) + bT(\vec{y})$$

Example) Let  $\mathbb{P}_n$  be the vector space of polynomials of degree at most  $n$ .

Consider the map  $T: \mathbb{P}_n \rightarrow \mathbb{P}_{n+1}$  given by

$$T(p(t)) = \frac{d}{dt} p(t)$$

This map is linear!

$$\forall p(t), q(t) \in \mathbb{P}_n$$

$$\Rightarrow T(ap(t) + bq(t)) = \frac{d}{dt} (ap(t) + bq(t)) = a \frac{d}{dt} p(t) + b \frac{d}{dt} q(t) = aT(p(t)) + bT(q(t))$$

• Representing linear maps by matrices.

• Let  $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n$  be a basis for  $V$ .

A linear map  $T: V \rightarrow W$  is determined by the values  $T(\vec{x}_1), T(\vec{x}_2), \dots, T(\vec{x}_n)$ .

Why?

Take any  $\vec{v} \in V$ , then  $\vec{v} = c_1\vec{x}_1 + c_2\vec{x}_2 + \dots + c_n\vec{x}_n$ .

Again, it means that we can represent  $\vec{v}$  as

$$\begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} \in \mathbb{R}^n$$

By the linearity of  $T$ ,

$$T(\vec{v}) = T(c_1\vec{x}_1 + \dots + c_n\vec{x}_n) = c_1T(\vec{x}_1) + \dots + c_nT(\vec{x}_n) \in W$$

Definition) Let  $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n$  be a basis for  $V$  and  $\vec{y}_1, \vec{y}_2, \dots, \vec{y}_m$  be a basis for  $W$ .

The matrix representing  $T$  with respect to these bases (of  $V$  and  $W$ )

- has  $n$  columns (one for each of the  $\vec{x}_j$ )
- the  $j$ th column has  $m$  entries,  $a_{1j}, a_{2j}, \dots, a_{mj}$  determined by

$$T(\vec{x}_j) = a_{1j}\vec{y}_1 + a_{2j}\vec{y}_2 + \dots + a_{mj}\vec{y}_m$$

$$T = \begin{bmatrix} & & & & & \\ & 1 & 2 & \cdots & n & \\ \vdash & \downarrow & \downarrow & & \downarrow & \downarrow \\ & a_{11} & a_{12} & \cdots & a_{1n} & \\ & a_{21} & a_{22} & \cdots & a_{2n} & \\ & \vdots & \vdots & & \vdots & \vdots \\ & a_{m1} & a_{m2} & \cdots & a_{mn} & \\ \vdash & \downarrow & \downarrow & & \downarrow & \downarrow \\ & j & & & & \end{bmatrix}$$

Example) Let  $V = \mathbb{R}^2$  and  $W = \mathbb{R}^3$ . Let  $T$  be the linear map such that

$$T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \quad T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 4 \\ 0 \\ 7 \end{bmatrix}$$

What is the matrix  $A$  representing  $T$ , w.r.t. standard bases.

$$\Rightarrow \vec{x}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad \vec{x}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \quad \vec{y}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{y}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \vec{y}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$T(\vec{x}_1) = T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = a_{11} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + a_{21} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + a_{31} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\therefore a_{11}=1, \quad a_{21}=2, \quad a_{31}=3$$

$$T(\vec{x}_2) = T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 4 \\ 0 \\ 7 \end{bmatrix} = a_{12} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + a_{22} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + a_{32} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\therefore a_{12}=4, \quad a_{22}=0, \quad a_{32}=7$$

$$\therefore A = \begin{bmatrix} 1 & 4 \\ 2 & 0 \\ 3 & 7 \end{bmatrix}$$

Example) Let  $V = \mathbb{R}^2$  and  $W = \mathbb{R}^3$ . Let  $T$  be the linear map s.t.

$$T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \quad T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 4 \\ 0 \\ 7 \end{bmatrix}$$

What is the matrix  $B$  representing  $T(\cdot)$  with respect to

$$\vec{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \quad \vec{x}_2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix} \text{ for } V, \quad \vec{y}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \quad \vec{y}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \vec{y}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \text{ for } W.$$

$$\begin{aligned} \rightarrow T(\vec{x}_1) &= T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) + T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) \\ &= \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \begin{bmatrix} 4 \\ 0 \\ 7 \end{bmatrix} = \boxed{\begin{bmatrix} 5 \\ 2 \\ 10 \end{bmatrix}} = c_1 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \end{aligned}$$

$c_1 = 5, c_2 = -3, c_3 = 5$

$$B = \begin{bmatrix} 5 & ? & ? \\ -3 & ? & ? \\ 1 & ? & ? \end{bmatrix}$$

$$T(\vec{x}_2) = -1 \cdot T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) + 2 \cdot T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \boxed{\begin{bmatrix} 7 \\ -2 \\ 11 \end{bmatrix}} = d_1 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + d_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + d_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$d_1 = 7, d_2 = -9, d_3 = 4$

$\therefore B = \boxed{\begin{bmatrix} 5 & 7 \\ -3 & -9 \\ 1 & 4 \end{bmatrix}}$  represents  $T(\cdot)$