

Definition (From linear maps to matrices)

Let $\{\vec{x}_i\}_{i=1}^n$ be a basis for V and $\{\vec{y}_j\}_{j=1}^m$ be a basis for W ,

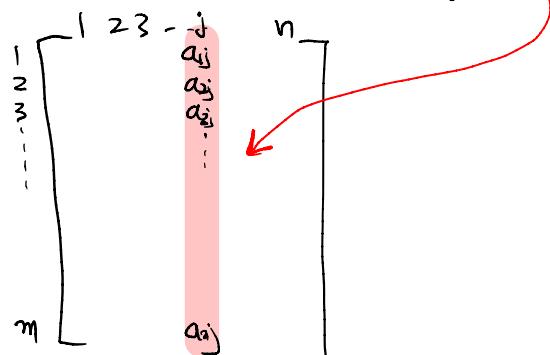
The matrix representing $T: V \rightarrow W$ with respect to these bases

- has n columns

- the j -th column has m entries $a_{1j}, a_{2j}, \dots, a_{mj}$ determined by

$$T(\vec{x}_j) = a_{1j}\vec{y}_1 + a_{2j}\vec{y}_2 + \dots + a_{mj}\vec{y}_m$$

$$T \in \mathbb{R}^{m \times n}$$



Example Let $V = \mathbb{R}^2, W = \mathbb{R}^3$. Let $T: V \rightarrow W$ be the linear map such that

$$T\begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \quad T\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ 0 \\ 7 \end{pmatrix}$$

What is the matrix B representing T , w.r.t.

$$\vec{x}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad \vec{x}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \text{ for } V, \quad \vec{y}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \quad \vec{y}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad \vec{y}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \text{ for } W.$$

$$\Rightarrow T(\vec{x}_1) = T\begin{pmatrix} 1 \\ 1 \end{pmatrix} = T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + \begin{pmatrix} 4 \\ 0 \\ 7 \end{pmatrix} = \begin{pmatrix} 5 \\ 2 \\ 10 \end{pmatrix}$$

$$\Rightarrow c_1 \underbrace{\begin{pmatrix} 1 \\ 1 \end{pmatrix}}_{=\vec{x}_1} + c_2 \underbrace{\begin{pmatrix} 0 \\ 1 \end{pmatrix}}_{=\vec{x}_2} + c_3 \underbrace{\begin{pmatrix} 0 \\ 0 \end{pmatrix}}_{=\vec{0}} = \begin{pmatrix} 5 \\ 2 \\ 10 \end{pmatrix} \Rightarrow c_1 = 5, c_2 = -3, c_3 = 5$$

$$\hookrightarrow B = \begin{bmatrix} 5 & 1 & 0 \\ -3 & 0 & 1 \\ 5 & 0 & 0 \end{bmatrix}$$

$$T(\vec{x}_2) = -1 \cdot T\begin{pmatrix} 0 \\ 1 \end{pmatrix} + 2 \cdot T\begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 7 \\ -2 \\ 11 \end{pmatrix}$$

$$\Rightarrow c_1 \underbrace{\begin{pmatrix} 1 \\ 1 \end{pmatrix}}_{=\vec{x}_1} + c_2 \underbrace{\begin{pmatrix} 0 \\ 1 \end{pmatrix}}_{=\vec{x}_2} + c_3 \underbrace{\begin{pmatrix} 0 \\ 0 \end{pmatrix}}_{=\vec{0}} \rightarrow c_1 = 7, c_2 = -9, c_3 = 4$$

$$\hookrightarrow B = \begin{bmatrix} 5 & 7 \\ -3 & -9 \\ 5 & 4 \end{bmatrix}$$

Example) Suppose that $A \in \mathbb{R}^{5 \times 5}$, $\vec{v} \in \mathbb{R}^5$ s.t. $\vec{v} \in \text{Col}(A)$
 Then, what can we say about $\text{Nul}(A)$?
 → First, Rank of A cannot be 5.
 Then, $\dim \text{Nul}(A) > 0$ (FTLA)

Example) We consider linear maps $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ s.t. $\vec{x} \mapsto A\vec{x}$

1) $A = \begin{bmatrix} c & 0 \\ 0 & c \end{bmatrix} : \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mapsto \begin{bmatrix} cx_1 \\ cx_2 \end{bmatrix}$ elongation

2) $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} : \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mapsto \begin{bmatrix} x_2 \\ x_1 \end{bmatrix}$

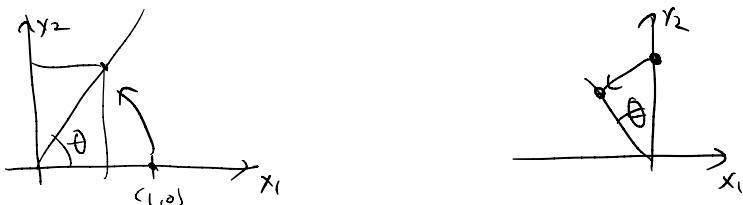
3) $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mapsto \begin{bmatrix} x_1 \\ 0 \end{bmatrix}$ projection

4) $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} : \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mapsto \begin{bmatrix} -x_2 \\ x_1 \end{bmatrix}$

Example) Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the map which rotates a vector counter-clockwise by θ . Find A that represents T with the standard basis.

⇒ \mathbb{R}^2 has $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ as a basis.

$$T_{\theta} \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) = \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}, \quad T_{\theta} \left(\begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix}$$



∴ Hence $A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$

Example) Let $T : \mathbb{P}_3 \rightarrow \mathbb{P}_2$ be the linear map given by

$$T(p(t)) = \frac{d}{dt} p(t)$$

\mathbb{P}_3 \mathbb{P}_2

What is the matrix A that represents T wrt the standard bases (of $\mathbb{P}_3, \mathbb{P}_2$)

\Rightarrow The bases for $\mathbb{P}_3 = \{1, t, t^2, t^3\} \Rightarrow A \in \mathbb{R}^{3 \times 4}$
 $\mathbb{P}_2 = \{1, t, t^2\},$

i) $T(1) = 0 \rightarrow \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow A = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

ii) $T(t) = 1 \rightarrow \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \rightarrow A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

iii) $T(t^2) = 2t \rightarrow \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix} \rightarrow A = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

iv) $T(t^3) = 3t^2 \rightarrow \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix} \rightarrow A = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix}$

We can do differentiation with matrix multiplications!

Note, what is the nullspace of A ?

$$\text{Null}(A) = \text{span} \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\} \subseteq \mathbb{P}_3$$

What does it mean? It corresponds to $p(t) = c \in \mathbb{R}$
 This makes sense in that $\frac{d}{dt} p(t) = \frac{d}{dt}(c) = 0$

Example) $p(t) = -t^3 - t + 3$, what is $p'(t)$?

$$\Rightarrow p(t) : \begin{bmatrix} 3 \\ -1 \\ 0 \\ 7 \end{bmatrix}, \quad \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 3 \\ -1 \\ 0 \\ 7 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 21 \end{bmatrix} \rightarrow -1 + 21t^2 = p'(t)$$

• Orthogonality

The inner product and distances.

Definition) The inner product (or dot product) of $\vec{v}, \vec{w} \in \mathbb{R}^n$

$$\vec{v} \cdot \vec{w} = \vec{v}^T \vec{w} = v_1 w_1 + \dots + v_n w_n$$

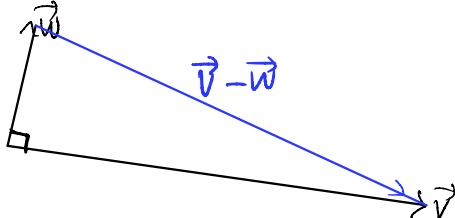
Example) $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = 1 - 2 - 6 = -7$

Definition) The norm of a vector $\vec{v} \in \mathbb{R}^n$ is

$$\|\vec{v}\| \triangleq \sqrt{\vec{v} \cdot \vec{v}} = \sqrt{v_1^2 + \dots + v_n^2}$$

The distance between \vec{v} and \vec{w}
 $\text{dist}(\vec{v}, \vec{w}) \triangleq \|\vec{v} - \vec{w}\|$

Definition) \vec{v} and $\vec{w} \in \mathbb{R}^n$ are orthogonal if

$$\vec{v} \cdot \vec{w} = 0$$


Rythagoras: \vec{v} and \vec{w} are orthogonal

$$\Leftrightarrow \|\vec{v}\|^2 + \|\vec{w}\|^2 = \|\vec{v} - \vec{w}\|^2$$

$$\Leftrightarrow \vec{v} \cdot \vec{v} + \vec{w} \cdot \vec{w} = (\vec{v} - \vec{w}) \cdot (\vec{v} - \vec{w}) = \vec{v} \cdot \vec{v} + \vec{w} \cdot \vec{w} - 2\vec{v} \cdot \vec{w}$$

$$\Leftrightarrow \vec{v} \cdot \vec{w} = 0$$

Theorem, Suppose that $\vec{v}_1, \dots, \vec{v}_m$ are nonzero and pairwise orthogonal.
 Then, they are independent.

proof) Suppose that

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_m \vec{v}_m = \vec{0} \quad (*)$$

and we will examine c_1, \dots, c_m .

i) Take the dot product of \vec{v}_i on $(*)$

$$\rightarrow c_1 \vec{v}_i \cdot \vec{v}_i + \dots + c_m \vec{v}_i \cdot \vec{v}_i = \vec{0} \cdot \vec{v}_i = 0$$

$$\Leftrightarrow c_1 \cdot \|\vec{v}_i\|^2 = 0$$

$$\Leftrightarrow c_1 = 0$$

→ Hence $(*)$ only has the trivial solution

→ $\vec{v}_1, \dots, \vec{v}_m$ are linearly independent.

Example) Let us consider $A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \\ 3 & 6 \end{bmatrix}$.

Find $\text{Nul}(A)$ and $\text{Col}(A^T)$.

$$\text{i)} \begin{bmatrix} 1 & 2 \\ 2 & 4 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow \begin{aligned} x_1 &= -2x_2 \\ x_2 &= x_2 \end{aligned}$$

$$\text{Nul}(A) = \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \end{bmatrix} \right\} \quad \text{"orthogonal"}$$

$$\text{ii)} \text{Col}(A^T) = \text{Col} \left(\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \end{bmatrix} \right) = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$$

Example) Repeat for $A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 0 \\ 3 & 6 & 0 \end{bmatrix}$

$$\text{i)} \text{Nul}(A) : \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 0 \\ 3 & 6 & 0 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{cases} x_1 = -2x_2 \\ x_2 = x_3 \\ x_3 = 0 \end{cases} \rightarrow \text{Nul}(A) = \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} \right\}$$

$$\text{ii)} \text{Col}(A^T) = \text{Col} \left(\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 1 & 0 & 0 \end{bmatrix} \right) \rightarrow \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \right\} \quad \text{orthogonal!}$$

* Vectors in $\text{Nul}(A)$ are orthogonal to the vectors in $\text{Col}(A^T)$.

proof) Suppose that

$$A = n \begin{bmatrix} \vec{a}_{(1)} \\ \vdots \\ \vec{a}_{(m)} \end{bmatrix} \in \mathbb{R}^{n \times m}$$

where $\vec{a}_{(i)} \in \mathbb{R}^m$ is i -th row vector of A .

Then, $\forall \vec{x} \in \text{Nul}(A)$, $\vec{a}_{(i)} \cdot \vec{x} = 0$ for all $i = 1, \dots, n$

Since, $\forall \vec{y} \in \text{Col}(A^T)$, $\vec{y} = c_1 \cdot \vec{a}_{(1)} + c_2 \cdot \vec{a}_{(2)} + \dots + c_m \cdot \vec{a}_{(m)}$

$$\begin{aligned} \vec{x} \cdot \vec{y} &= \vec{x} \cdot (c_1 \cdot \vec{a}_{(1)} + \dots + c_m \cdot \vec{a}_{(m)}) \\ &= c_1 \cdot (\vec{x} \cdot \vec{a}_{(1)}) + \dots + c_m \cdot (\vec{x} \cdot \vec{a}_{(m)}) = 0 \end{aligned}$$

$$\therefore \forall \vec{x} \in \text{Nul}(A), \forall \vec{y} \in \text{Col}(A^T)$$

$$\vec{x} \cdot \vec{y} = 0$$

Definition) Let W be a subspace of \mathbb{R}^n and $\vec{v} \in \mathbb{R}^n$

- \vec{v} is orthogonal to W , if $\vec{v} \cdot \vec{w} = 0$ for all $\vec{w} \in W$
 - Another subspace V is orthogonal to W , if every vector in V is orthogonal to W .
 - The orthogonal complement of W is the space W^\perp of all vectors that are orthogonal to W .
- $$\Rightarrow W^\perp = \{ \vec{v} \in \mathbb{R}^n \mid \vec{v} \cdot \vec{w} = 0 \ \forall \vec{w} \in W \}$$

Example) Show that W^\perp is a subspace of \mathbb{R}^n . (W is a subspace of \mathbb{R}^n)

$$\begin{aligned} \Rightarrow & \text{i)} \vec{0} \in W^\perp \because \vec{0} \cdot \vec{w} = 0 \\ & \text{ii)} \text{Let } \vec{u}, \vec{v} \in W^\perp. \\ & (\vec{u} + \vec{v}) \in W^\perp \text{ because} \\ & (\vec{u} + \vec{v}) \cdot \vec{w} = \vec{u} \cdot \vec{w} + \vec{v} \cdot \vec{w} = 0 \quad \forall \vec{w} \in W \\ & \text{iii)} (c \cdot \vec{u}) \in W^\perp \text{ because} \\ & c \cdot \vec{u} \cdot \vec{w} = c \cdot 0 = 0 \end{aligned}$$

$\therefore W^\perp$ is a subspace of \mathbb{R}^n

Theorem) $\text{Nul}(A)$ is orthogonal to $\text{Col}(A^T)$
 $\text{Nul}(A^T)$ is orthogonal to $\text{Col}(A)$

• Example) Show that $\dim(W) + \dim(W^\perp) = n$ for $W \subseteq \mathbb{R}^n$ subspace

\Rightarrow Let $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_r$ be a basis for W ($\dim(W) = r$)
 Let $\vec{v}_{r+1}, \vec{v}_{r+2}, \dots, \vec{v}_k$ be a basis for W^\perp
 \rightarrow Thus, we need to show that $k = n$.

i) First, claim that $\{\vec{v}_1, \dots, \vec{v}_r, \vec{v}_{r+1}, \dots, \vec{v}_k\}$ is linearly indep.
 Suppose that

$$\underbrace{c_1 \vec{v}_1 + \dots + c_r \vec{v}_r}_{\vec{w} \in W} + \underbrace{c_{r+1} \vec{v}_{r+1} + \dots + c_k \vec{v}_k}_{\vec{w}' \in W^\perp} = \vec{0} \quad (4)$$

$$\vec{w} + \vec{w}' = \vec{0} \rightarrow \vec{w} = -\vec{w}' \rightarrow \vec{w} \in W \text{ and } \vec{w} \in W^\perp$$

This implies that \vec{w} is perpendicular to itself.

$$\rightarrow \vec{w} \cdot \vec{w} = 0 \rightarrow \vec{w} = \vec{0}, \vec{w}' = \vec{0}$$

$$\rightarrow (c_1, \dots, c_r = 0) \& (c_{r+1}, \dots, c_k = 0)$$

ii) We showed that ($k \leq n$) as
 $\{\vec{v}_1, \dots, \vec{v}_k\}$ are linearly indep.

Suppose that $(k < n)$. Then the matrix

$$A = \begin{bmatrix} & \overbrace{\quad v_1^T \quad} \\ \vdots & | \\ & \overbrace{\quad v_k^T \quad} \end{bmatrix} \in \mathbb{R}^{k \times n}$$

thus, $\text{Nul}(A)$ is non zero $\rightarrow \exists \vec{x} \in \text{Nul}(A) \text{ s.t. } \vec{x} \neq \vec{0}$.

$$\rightarrow \vec{0} = A\vec{x} = \begin{bmatrix} & \overbrace{\quad v_1^T \quad} \\ \vdots & | \\ & \overbrace{\quad v_k^T \quad} \end{bmatrix} \vec{x} = \begin{bmatrix} \vec{v}_1 \cdot \vec{x} \\ \vec{v}_2 \cdot \vec{x} \\ \vdots \\ \vec{v}_k \cdot \vec{x} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad \text{--- (1*)}$$

(*) implies that $\vec{x} \in W^\perp$ and $\vec{x} \in (W^\perp)^\perp \rightarrow \vec{x} = \vec{0}$
However, it contradicts that $\vec{x} \neq \vec{0}$ hence k cannot be smaller than n .

$$\therefore (k=n)$$