

# Detection and localization of peaks in a smooth random field

Samuel Davenport (work with Fabian Telschow, Armin Schwartzman and Thomas E. Nichols)

University of California, San Diego

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## 1 Peak Detection

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# Peak Detection

# Smoothing

- Suppose we have  $n$  subjects and that for each subject we observe

$$X_i = \mu_X + \epsilon_i$$

on a finite lattice  $\mathcal{L} \subset S$ .

- Smoothing is typically done in order to increase the signal to noise ratio. I.e. for each  $i$ ,  $X_i$  is smoothed with a  $C^2$  kernel  $K$  to give

$$Y_i(v) = \sum_{l \in \mathcal{L}} K(v - l) \mu_X(l) + \sum_{l \in \mathcal{L}} K(v - l) \epsilon_i(l)$$

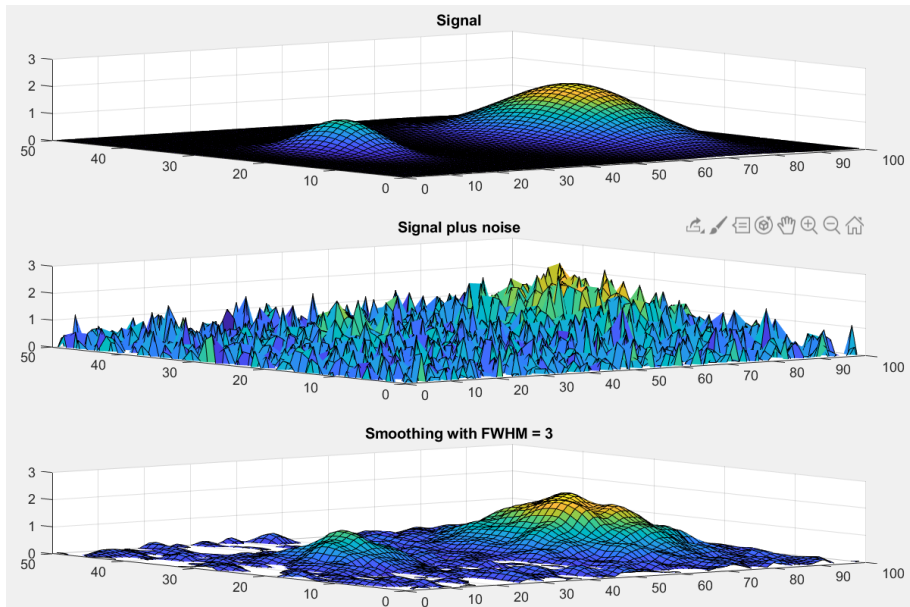
at each  $v \in \mathcal{L}$ .

- Let

$$\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n Y_i = \sum_{l \in \mathcal{L}} K(v - l) \bar{X}_n(l)$$

where  $\bar{X}_n = \sum_{i=1}^n X_i$ .

# Why you should smooth

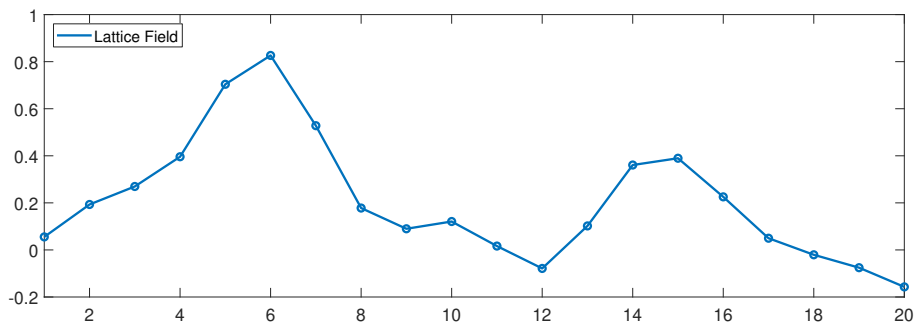


# Lattice smoothing

In applications when smoothing is performed (e.g. in fMRI) you evaluate

$$\hat{\mu}_n(v) = \sum_{l \in \mathcal{L}} K(v - l) \bar{X}(l)$$

at every voxel  $v \in \mathcal{L}$ . An example evaluation  $\hat{\mu}_n$  is shown below.



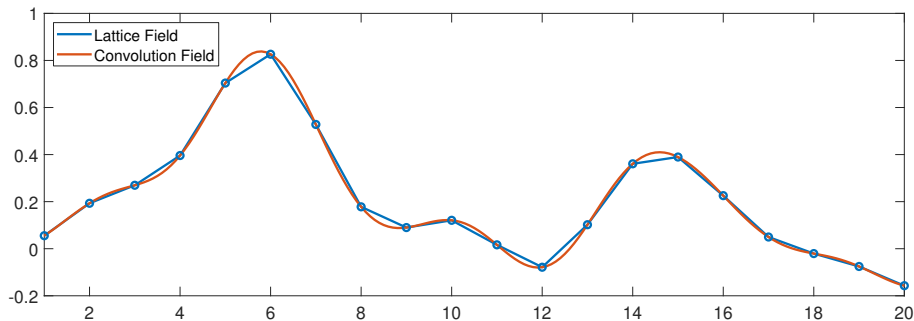
# Convolution Random Fields

## Definition

Instead we can evaluate the smoothing continuously, meaning that for all  $s \in S$ ,

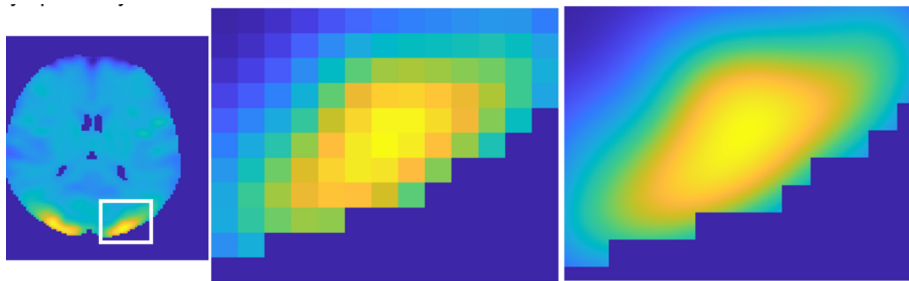
$$\hat{\mu}_n(s) := \sum_{l \in \mathcal{L}} K(s - l) \bar{X}(l).$$

We call this a convolution field.



# Convolution Fields in Brain Imaging

Taking slices through a 3D convolution field generated from brain imaging data, you get the following images!





Let  $M_u(\hat{\mu}_n)$  be the number of local maxima of  $\hat{\mu}_{Y,n}$  above a threshold  $u$  then

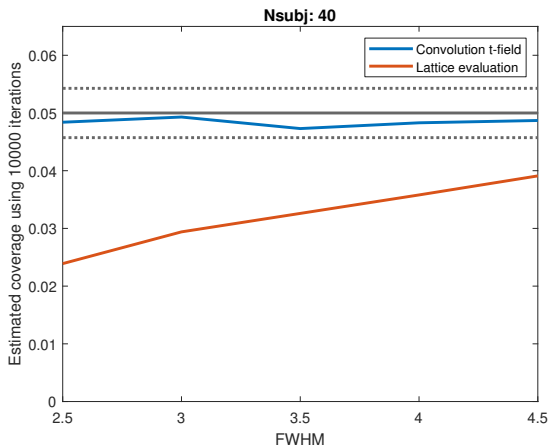
$$\mathbb{P}\left(\sup_{s \in S} \hat{\mu}_n(s) > u\right) = \mathbb{P}(M_u(\hat{\mu}_n) \geq 1) \leq \mathbb{E}[M_u(\hat{\mu}_n)]$$

because  $\hat{\mu}$  exceeds  $u$  if and only if there is at least one local maxima above  $u$ .

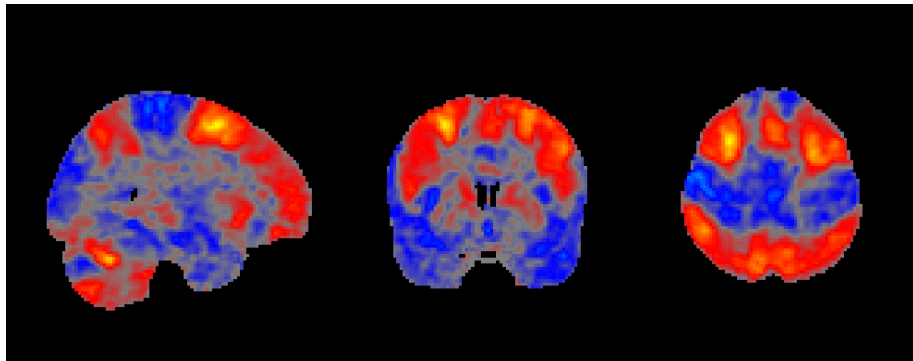
- Many good approximations exist to  $\mathbb{E}[M_u(\hat{\mu}_n)]$  at high thresholds  $u$  so can control FWER.
- FWER over space is the same as FWER over peaks so we can use this to find significant peaks.
- Using convolution fields to do inference means that RFT works at any applied smoothness because the theory is valid for continuous random fields.

# FWER for 2D Gaussian random fields

We generate mean-zero random fields by smoothing Gaussian white noise with an isotropic Gaussian kernel and take  $n = 40$ . (FWHM is proportional to the smoothing parameter of the kernel.)



# Detection and Localization



# Peak Confidence Regions

# Asymptotic confidence regions

Assume that  $\mu$  has  $J$  peaks at locations  $\theta_1, \dots, \theta_J$  within disjoint balls  $B_1, \dots, B_J$ .

## Theorem

For each  $j = 1, \dots, J$  corresponding to a local maximum of  $\mu$ , let  $\hat{\theta}_{j,n} = \operatorname{argmax}_{t \in B_j} \hat{\mu}_n(t)$  (and for the minima let  $\hat{\theta}_{j,n} = \operatorname{argmin}_{t \in B_j} \hat{\mu}_n(t)$ ) and let  $\hat{\boldsymbol{\theta}}_n := (\hat{\theta}_{1,n}^T, \dots, \hat{\theta}_{J,n}^T)^T$  and  $\boldsymbol{\theta} := (\theta_1^T, \dots, \theta_J^T)^T$ . Then, under regularity assumptions on  $\mu$  and the noise,

$$\sqrt{n}(\hat{\boldsymbol{\theta}}_n - \boldsymbol{\theta}) \xrightarrow{d} N(0, \mathbf{A}\boldsymbol{\Lambda}\mathbf{A}^T)$$

as  $n \rightarrow \infty$ . Here  $\mathbf{A} \in \mathbb{R}^{DJ \times DJ}$  depends on  $\nabla^2 \mu$  and  $\boldsymbol{\Lambda} \in \mathbb{R}^{DJ \times DJ}$  depends on the covariance of  $\nabla Y_1$ .

# Accounting for the variance

Expanding we have,

$$\hat{\theta}_{j,n} - \theta_j = -(\nabla^2 \hat{\mu}_n(\theta_{j,n}^*))^{-1} \nabla^T \hat{\mu}_n(\theta_j)$$

As  $n \rightarrow \infty$ ,  $(\nabla^2 \hat{\mu}_n(\theta_{j,n}^*))^{-1} \rightarrow (\nabla^2 \hat{\mu}_n(\theta_j))^{-1}$  so can be approximated by  $(\nabla^2 \hat{\mu}_n(\hat{\theta}_{j,n}))^{-1}$  when making asymptotic confidence intervals.

$$\begin{aligned} \hat{\theta}_{j,n} - \theta_j &= -\left(\nabla^2 \hat{\mu}_n(\theta_j) + \frac{1}{2}(\hat{\theta}_{j,n} - \theta_j)^T \nabla^3 \hat{\mu}_n(\tilde{\theta}_{j,n})\right)^{-1} \nabla^T \hat{\mu}_n(\theta_j) \\ &\approx -(\nabla^2 \hat{\mu}_n(\theta_j))^{-1} \nabla^T \hat{\mu}_n(\theta_j) \end{aligned}$$

We have

$$\begin{pmatrix} \nabla^T \hat{\mu}_n(\theta_j) \\ \text{vech}(\nabla^2 \hat{\mu}_n(\theta_j)) \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} 0 \\ \text{vech}(\nabla^2 \mu_n(\theta_j)) \end{pmatrix}, \frac{1}{n} \begin{pmatrix} \Lambda & 0 \\ 0 & \Omega \end{pmatrix} \right)$$

and for  $1 \leq k \leq K$  ( $K \in \mathbb{N}$ ) we can approximate this by simulating from the following distribution

$$\begin{pmatrix} A_k \\ B_k \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} 0 \\ \text{vech}(\nabla^2 \hat{\mu}_n(\hat{\theta}_{j,n})) \end{pmatrix}, \frac{1}{n} \begin{pmatrix} \hat{\Lambda} & 0 \\ 0 & \hat{\Omega} \end{pmatrix} \right).$$

and calculating  $\delta_{k,n} = (\text{vech}^{-1}(B_{k,n}))^{-1} A_{k,n}$ .

# Monte Carlo confidence regions

Let  $\hat{\Sigma}'_j = (\nabla^2 \hat{\mu}_n(\hat{\theta}_j))^{-1} \hat{\Lambda} (\nabla^2 \hat{\mu}_n(\hat{\theta}_j))^{-1}$  and for  $0 < \alpha < 1$ , choose  $\lambda_\alpha$  such that

$$\frac{1}{K} \sum_{k=1}^K 1 \left[ n(\hat{\delta}_{k,n}^T (\hat{\Sigma}'_j)^{-1} \hat{\delta}_{k,n}) > \lambda_\alpha \right] = \frac{\lfloor \alpha K \rfloor}{K}.$$

Given this we define a  $(1 - \alpha)$  Monte Carlo confidence region to be

$$\left\{ \theta : n(\hat{\theta}_{j,n} - \theta)^T (\hat{\Sigma}'_j)^{-1} (\hat{\theta}_{j,n} - \theta) < \lambda_\alpha \right\}.$$

- These regions are asymptotically valid (for the same reason as the asymptotic cases)
- Under stationarity we can prove that these intervals are bigger than the asymptotic ones.



# Example simulations

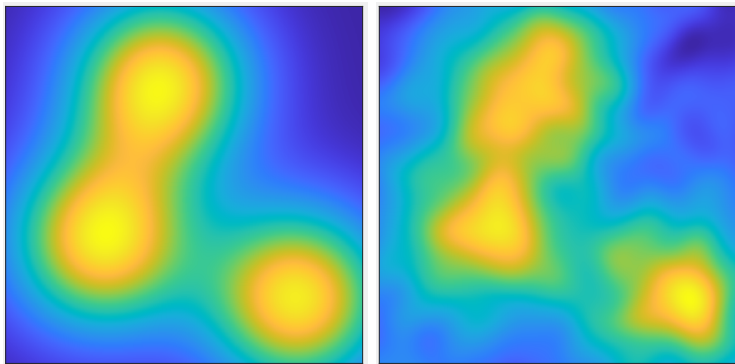
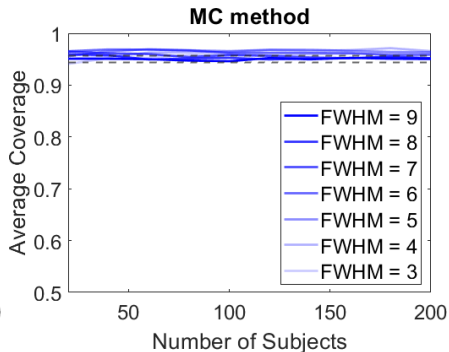
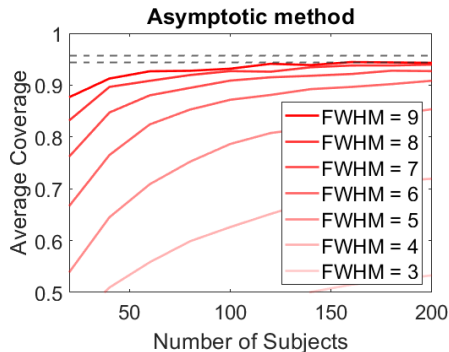


Figure 1: Left: True signal. Right: one realisation.

# Comparing coverage rates

Simulate  $n$



# Application to fMRI

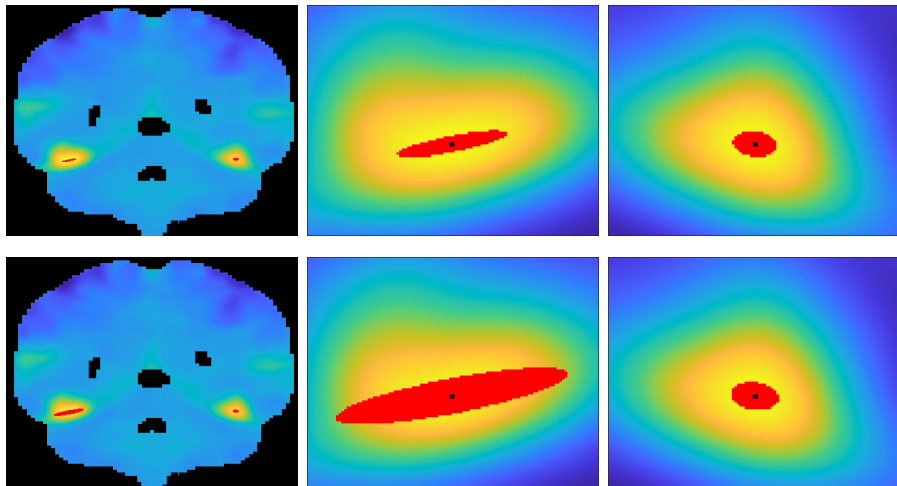


Figure 3: Peaks of the mean of 125 subjects

# Conclusion

- Using convolution fields accurately and quickly controls the FWER at the right level. (This is valid under non-stationarity.)
- Here we assumed Gaussianity but the framework works for t-fields and F-fields as well.
- You can derive asymptotic confidence regions and improve upon these if you additionally assume stationarity.
- Software (in MATLAB) to perform inference on random fields is available at the RFTtoolbox ([github.com/sjdavenport/RFTtoolbox](https://github.com/sjdavenport/RFTtoolbox)). (E.g. for LKC estimation, Peak Inference, Peak Height distribution, confidence regions)
- Slides available at [sjdavenport.github.io/talks](https://sjdavenport.github.io/talks).

- Pre-print on convolution fields soon to be out, in the mean time you can read a lot of the details in my thesis here:  
<https://sjdavenport.github.io/research/papers/thesis.pdf>.
- Pre-print on peak confidence regions is available on arxiv (Davenport, Nichols, & Schwarzman, 2022). (see <https://sjdavenport.github.io/research/>)

Davenport, S., Nichols, T. E., & Schwarzman, A. (2022). Confidence regions for the location of peaks of a smooth random field. *arXiv preprint arXiv:2208.00251*.