



# TRANSFORMING HEAVY TAILED DATA IMPROVES THE POWER OF INFERENCE

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# EXISTING TRANSFORMATION APPROACHES

- Data transformations are rather common however are typically designed to maximize Gaussianity.

## An Analysis of Transformations

THE usual techniques for the analysis of linear models as exemplified by the analysis of variance and by multiple regression analysis are usually justified by assuming

- (i) simplicity of structure for  $E(y)$ ;
- (ii) constancy of error variance;
- (iii) **normality** of distributions;
- (iv) independence of observations.

# EXISTING TRANSFORMATION APPROACHES

- Data transformations are rather common however are typically designed to maximize Gaussianity.

$$y^{(\lambda)} = \begin{cases} \frac{y^\lambda - 1}{\lambda} & (\lambda \neq 0), \\ \log y & (\lambda = 0), \end{cases}$$

$$\frac{1}{(2\pi)^{\frac{1}{2}n} \sigma^n} \exp \left\{ -\frac{(\mathbf{y}^{(\lambda)} - \mathbf{a}\boldsymbol{\theta})' (\mathbf{y}^{(\lambda)} - \mathbf{a}\boldsymbol{\theta})}{2\sigma^2} \right\} J(\lambda; \mathbf{y}),$$

- However its not clear why transforming to maximize Gaussianity is a good idea, especially in the context of testing as the test-statistic is Gaussian in the limit.
- Instead it may make more sense to transform to try to improve power.

# MODEL

Consider the following signal plus noise model with a mean  $\mu : \mathcal{V} \rightarrow \mathbb{R}$ , for some finite set of indices  $\mathcal{V}$ , and random observations

$$Y_i(v) = \mu(v) + \epsilon_i(v), \text{ for all } v \in \mathcal{V}.$$

Here  $\epsilon_i : \mathcal{V} \rightarrow \mathbb{R}$ , for  $1 \leq i \leq n$ , are i.i.d. mean-zero random images (or vectors indexed by  $\mathcal{V}$ ), for some number of observations  $n \in \mathbb{N}$ . Let  $\sigma^2(v) := \text{var}(\epsilon_1(v))$  and assume that  $\min_{v \in \mathcal{V}} \sigma^2(v) > 0$ .

**Remark 2.1.** *In our applications,  $\mathcal{V}$  will correspond to the set of vertices/voxels for the 2D surface and 3D volume data respectively. However the framework is fully general. In particular, given  $m \in \mathbb{N}$ , taking  $\mathcal{V} = \{1, 2, \dots, m\}$  we recover vectors in  $\mathbb{R}^m$  and taking  $\mathcal{V} = \{1\}$  we recover random variables in  $\mathbb{R}$ .*

## NULL HYPOTHESES TO TEST

at each  $v \in \mathcal{V}$ , we shall be interested in testing the point-null:

$$H_0^P(v) : \mu(v) = 0 \quad \text{v.s.} \quad H_1^P(v) : \mu(v) \neq 0.$$

$$\text{null set } \mathcal{N} \subseteq \mathcal{V} \quad \mathcal{N} = \{v \in \mathcal{V} : \mu(v) = 0\}$$

We shall also be interested in testing the directional null

$$H_0^D(v) : \mu(v) \leq 0 \quad \text{v.s.} \quad H_1^D(v) : \mu(v) > 0$$

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$$H_0^D(v) \text{ is true on } \mathcal{D} = \{v \in \mathcal{V} : \mu(v) \leq 0\}$$

# TEST-STATISTICS

$$T_n(v) = \frac{\sqrt{n}\hat{\mu}_n(v)}{\hat{\sigma}_n(v)}$$

for each  $v \in \mathcal{V}$

where  $\hat{\mu}_n(v) = \sum_{i=1}^n Y_i(v)$

$$\hat{\sigma}_n(v) = \left( \frac{1}{n-1} \sum_{i=1}^n (Y_i(v) - \bar{Y}_n)^2 \right)^{1/2}$$

This test statistic is widely used despite not being necessarily being optimal

## TRANSFORMED TEST-STATISTICS

$$T_n^*(v) = \frac{\frac{1}{\sqrt{n}} \sum_{i=1}^n f_v(Y_i(v))}{\left( \frac{1}{n-1} \sum_{j=1}^n (f_v(Y_j(v)) - \sum_{i=1}^n f_v(Y_i(v))^2 \right)^{1/2}}$$

for each  $v \in \mathcal{V}$ , where  $f_v : \mathbb{R} \rightarrow \mathbb{R}$

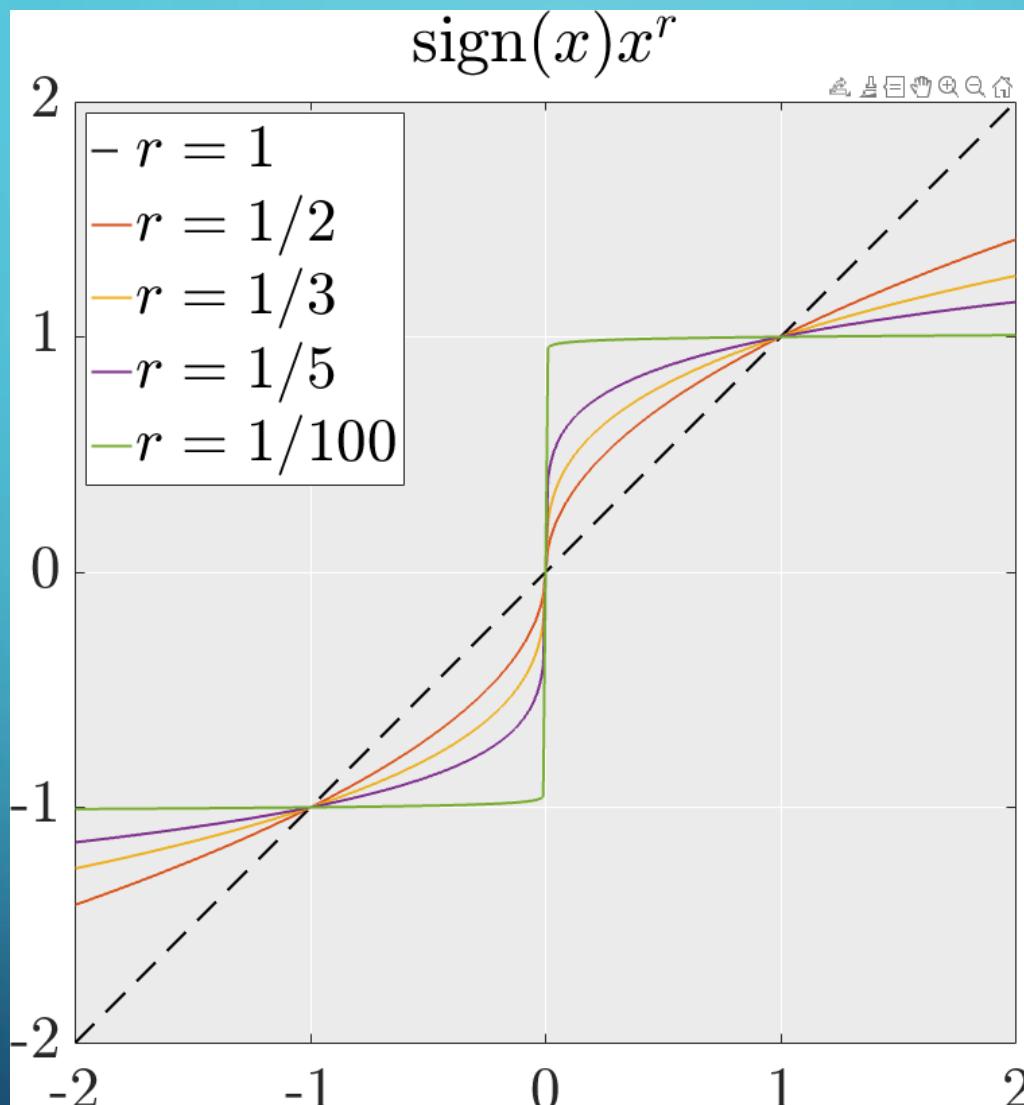
## NATURAL FAMILY OF TRANSFORMATIONS

- Natural to choose the same function at each v.

$$f(x) = \begin{cases} x^r & \text{if } x \geq 0 \\ -(-x)^r & \text{if } x < 0 \end{cases}, \text{ for } r > 0,$$

- This family is the signed power family has the special property that it makes the test-statistics robust to the pointwise variance of the data
- Other transformation families such as those basd on the arcsinh family etc can be used but do not have this property.

# ANTISYMMETRIC TRANSFORMATIONS



# INVARIANCE UNDER SIGN-FLIPPING

We will develop theory for testing using sign-flipping. To do so we shall require the following assumption on the errors

**Assumption 1.** (Null invariance under sign-flipping) For all  $g_1, \dots, g_n \in \{\pm 1\}$ ,

$$\{g_1\epsilon_1(v), \dots, g_n\epsilon_n(v)\}_{v \in \mathcal{N}} =_d \{\epsilon_1(v), \dots, \epsilon_n(v)\}_{v \in \mathcal{N}}.$$

## TRANSFORMING PRESERVES THE NULL

**Definition 2.2.** Given  $f : \mathbb{R} \rightarrow \mathbb{R}$  we say that  $f$  is antisymmetric if  $f(-x) = -f(x)$  for all  $x \in \mathbb{R}$ .

**Theorem 2.4.** Suppose that  $\epsilon_1, \dots, \epsilon_n$  each have a symmetric distribution and let  $f$  be an antisymmetric function. Then for each  $v \in \mathcal{V}$  we have  $\mathbb{E}[f(\epsilon_i(v))] = 0$  for all  $1 \leq i \leq n$ .

*Proof.* To establish the first result note that the fact that  $f$  is antisymmetric and  $\epsilon_1(v)$  is symmetric means that the problem is completely symmetric. In particular,

$$\mathbb{E}(f(\epsilon_1(v))) = \mathbb{E}(f(-\epsilon_1(v))) = -\mathbb{E}(f(\epsilon_1(v)))$$

So  $\mu(v) = 0$  implies  $\mathbb{E}[f(Y_i(v))] = 0$

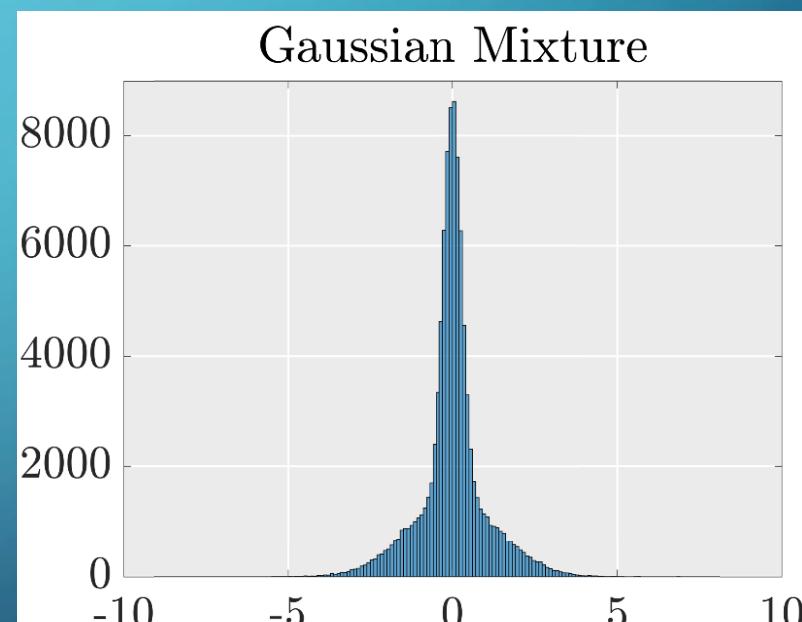
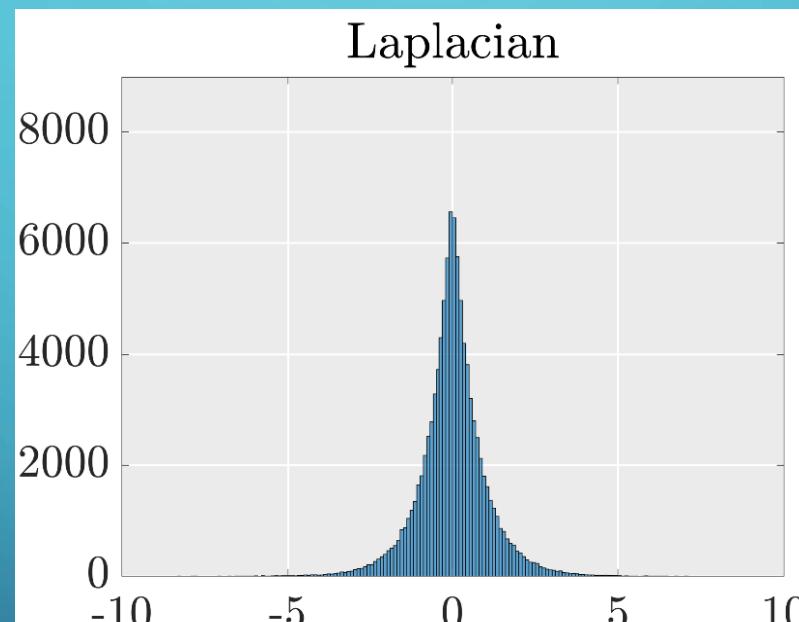
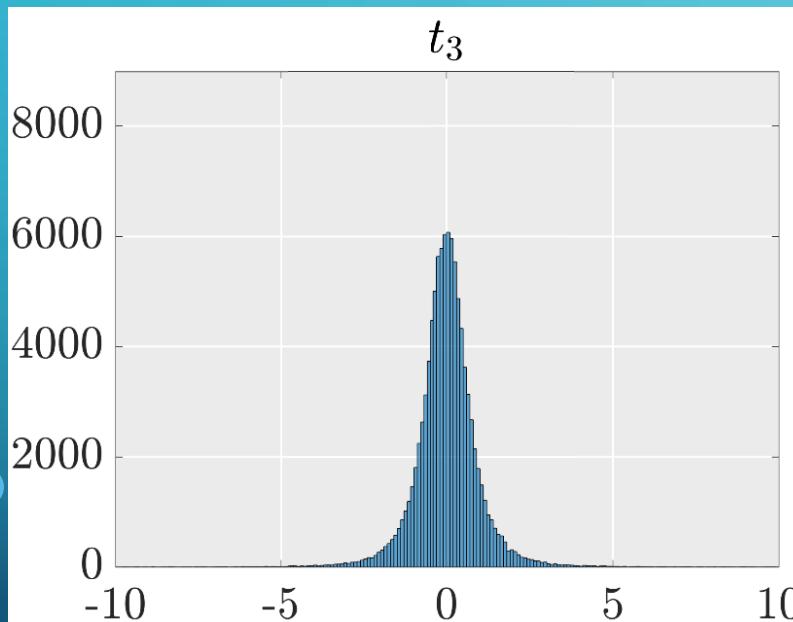
## PRESERVING THE DIRECTIONAL NULL

**Theorem 2.5.** Suppose that  $\epsilon_1, \dots, \epsilon_n$  each have a symmetric distribution and let  $f$  be an increasing antisymmetric function, then  $\mathbb{E}[f(Y_i(v))] \leq 0$  for all  $v \in \mathcal{V}$  such that  $\mu(v) \leq 0$  and all  $1 \leq i \leq n$ .

*Proof.* Since  $f$  is increasing, applying Theorem 2.4, it follows that  $\mu(v) \leq 0$  implies

$$\mathbb{E}[f(Y_i(v))] = \mathbb{E}[f(\mu(v) + \epsilon_i(v))] \leq \mathbb{E}[f(\epsilon_i(v))] = 0.$$

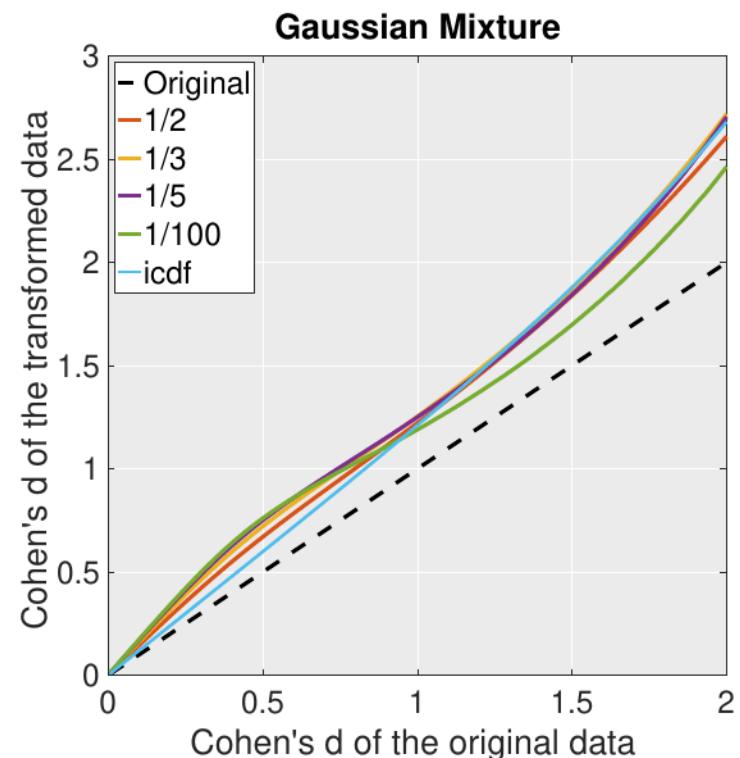
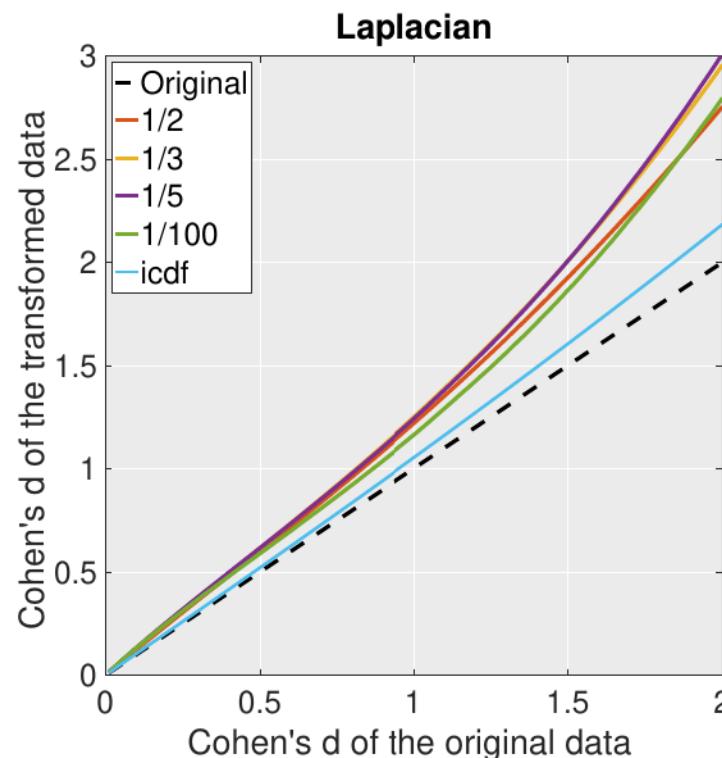
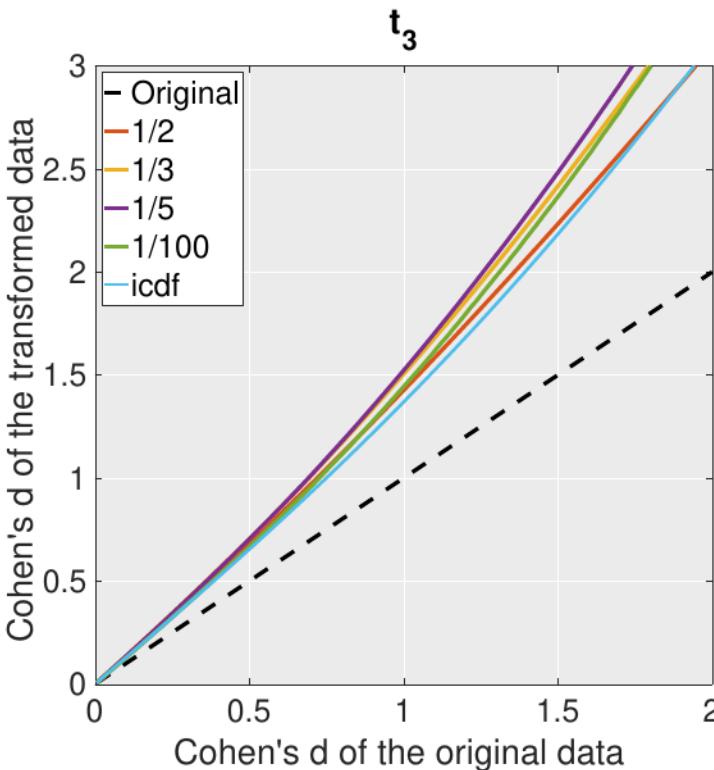
# SIMULATING DATA FROM HEAVY TAILED DISTRIBUTIONS



# TRANSFORMATIONS CAN BE USED TO INCREASE COHEN'S D

- Cohen's d is equivalent to asymptotic relative efficiency

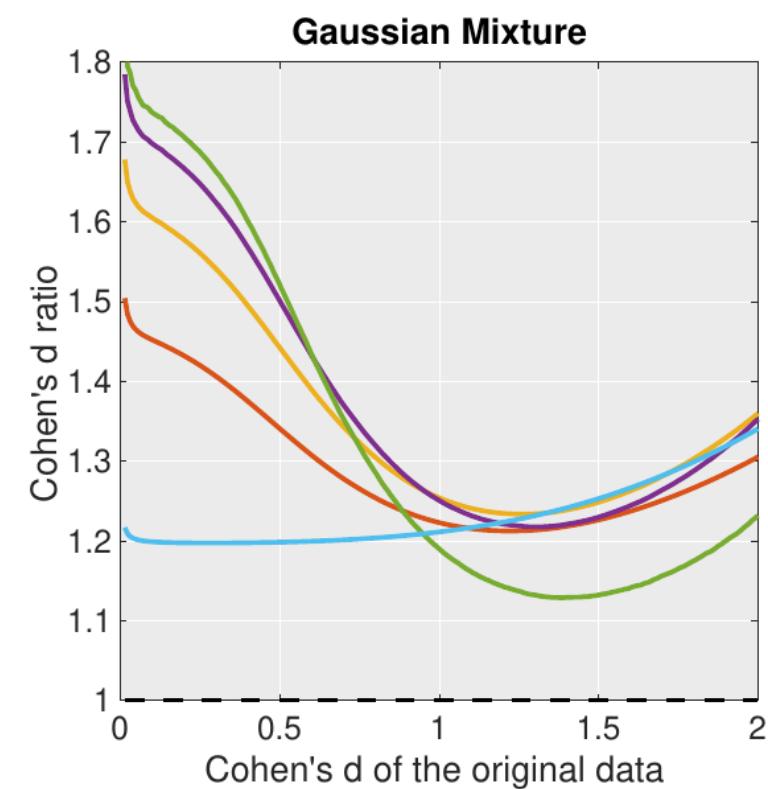
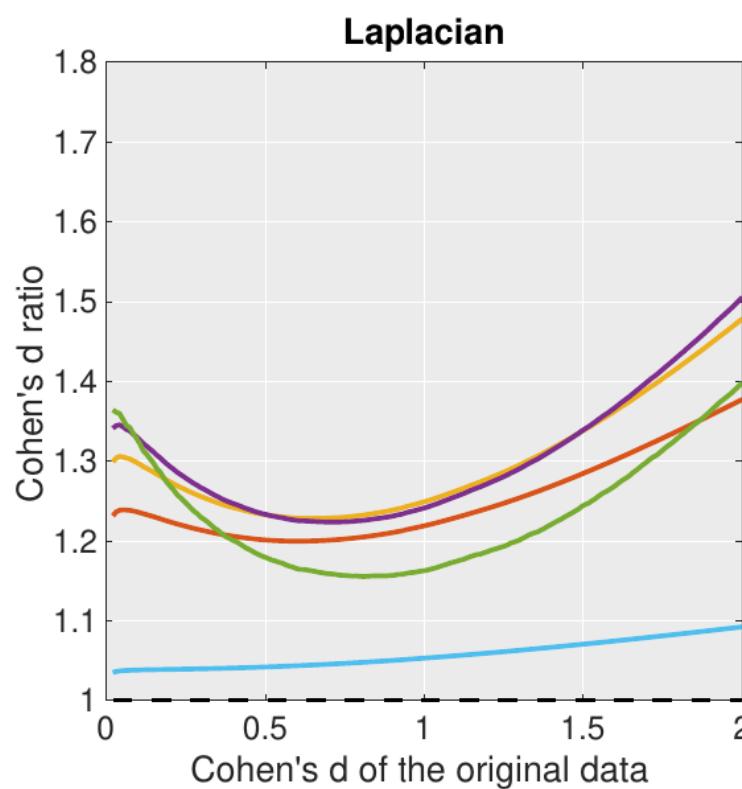
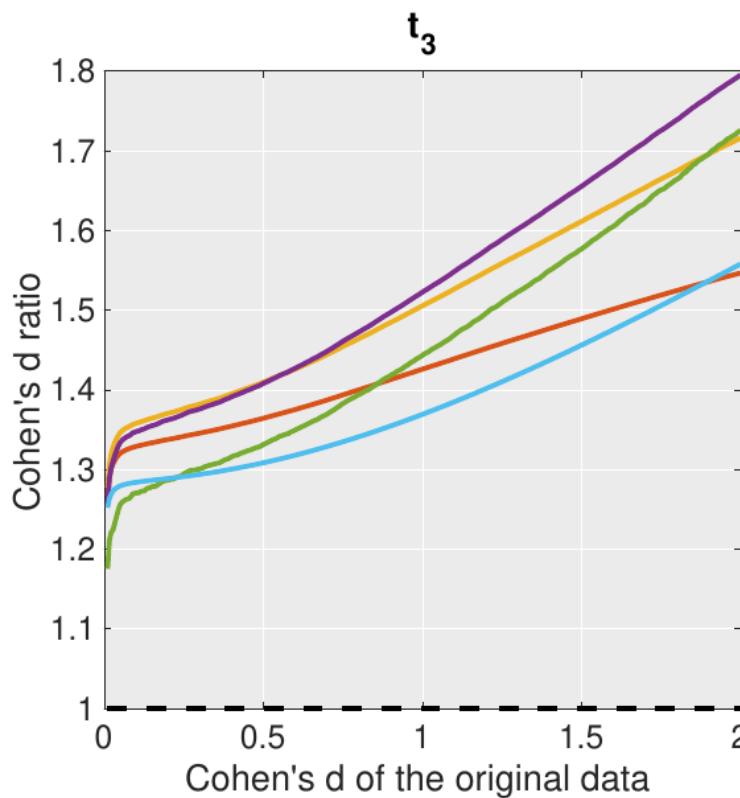
$$\frac{\mathbb{E}[f(Y)]}{\text{std}(f(Y))} \quad \text{vs} \quad \frac{\mathbb{E}[Y]}{\text{std}(Y)}$$



# TRANSFORMATIONS CAN BE USED TO INCREASE COHEN'S D

- Cohen's d is equivalent to asymptotic relative efficiency

$$\frac{\mathbb{E}[f(Y)]}{\text{std}(f(Y))} / \frac{\mathbb{E}[Y]}{\text{std}(Y)}$$



# INFERENCE USING A CLT

**Theorem 4.1.** Suppose that  $(f_v)_{v \in \mathcal{V}} : \mathbb{R} \rightarrow \mathbb{R}$  is a collection of real valued anti-symmetric functions such that  $\max_{v \in \mathcal{V}} \mathbb{E}(f_v(Y_1(v))^2) < \infty$ . Then as  $n \rightarrow \infty$ ,

$$T_n^*|_{\mathcal{N}} \xrightarrow{d} \mathcal{G}|_{\mathcal{N}}(0, \rho)$$

where  $\rho(u, v) = \text{corr}(f_u(\epsilon_1(u)), f_v(\epsilon_1(v)))$  for  $u, v \in \mathcal{V}$ . Moreover  $\min_{v \in \mathcal{D} \setminus \mathcal{N}} T_n^*|_{\mathcal{N}}(v)$  converges almost surely to  $-\infty$ .

# INFERENCE USING THE MULTIPLIER BOOTSTRAP

Given a number of bootstraps  $B \in \mathbb{N}$  for  $2 \leq b \leq B$ , define bootstrapped test-statistics,  $T_{n,b}^*(v) = \frac{\sqrt{n}\hat{\mu}_{n,b}(v)}{\hat{\sigma}_{n,b}}$ , at each  $v \in \mathcal{V}$ , where

$$\hat{\mu}_{n,b}(v) = \frac{1}{\sqrt{n}} \sum_{i=1}^n g_{bi} \left( f_v(Y_i(v)) - \frac{1}{n} \sum_{j=1}^n f_v(Y_j(v)) \right), \text{ and}$$

$$\hat{\sigma}_{n,b}(v) = \left( \frac{1}{n-1} \sum_{j=1}^n \left( g_{bj} \left( f_v(Y_i(v)) - \frac{1}{n} \sum_{j=1}^n f_v(Y_j(v)) \right) - \hat{\mu}_{n,b}(v) \right)^2 \right)^{1/2},$$

We take  $T_{n,1}^* = T_n^*$

# INFERENCE USING THE MULTIPLIER BOOTSTRAP

**Theorem 4.2.** Suppose that  $(f_v)_{v \in \mathcal{V}} : \mathbb{R} \rightarrow \mathbb{R}$  is a collection of real valued anti-symmetric functions such that  $\max_{v \in \mathcal{V}} \mathbb{E}(f_v(Y_1(v))^2) < \infty$ . Then

$$(T_{n,2}^*, \dots, T_{n,B}^*)^T \xrightarrow{d} \mathcal{G}(0, \rho I_{(B-1) \times (B-1)}), \text{ and moreover,}$$

$$(T_{n,1}^*|_{\mathcal{N}}, T_{n,2}^*|_{\mathcal{N}}, \dots, T_{n,B}^*|_{\mathcal{N}})^T \xrightarrow{d} \mathcal{G}|_{\mathcal{N}}(0, \rho I_{B \times B}),$$

where  $\rho(u, v) = \text{corr}(f_u(\epsilon_1(u)), f_v(\epsilon_1(v)))$  for each  $u, v \in \mathcal{V}$ .

# TESTING USING THE BOOTSTRAPPED DATA

$$\lambda_{\alpha,n,B} = \inf \left\{ \lambda : \frac{1}{B} \sum_{b=1}^B \mathbb{1} \left[ \max_{v \in \mathcal{V}} T_{n,b}^*(v) \leq \lambda \right] \geq \alpha \right\}$$

Consider the test which rejects  $H_0^D(v)$  at each voxel  $v \in \mathcal{V}$  if  $T_n^*(v) > \lambda_{\alpha,n,B}$ .

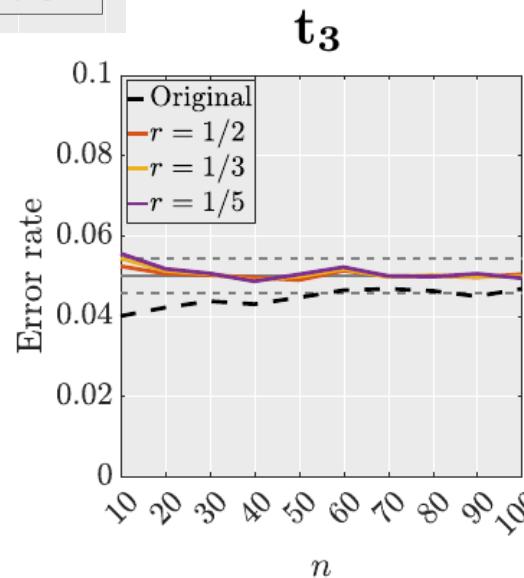
**Theorem 4.3.** (*Directional FWER control*) Let  $\mathcal{R}_n = \{v \in \mathcal{V} : T_n^*(v) > \lambda_{\alpha,n,B}\}$  and let  $\mathcal{D} = \{v \in \mathcal{V} : \mu(v) \leq 0\}$ . Then, for  $\alpha \in (\frac{1}{B}, 1)$  we have

$$\lim_{n \rightarrow \infty} \mathbb{P}(\mathcal{R}_n \cap \mathcal{D} \neq \emptyset) \leq \frac{\lfloor \alpha B \rfloor}{B} \leq \alpha.$$

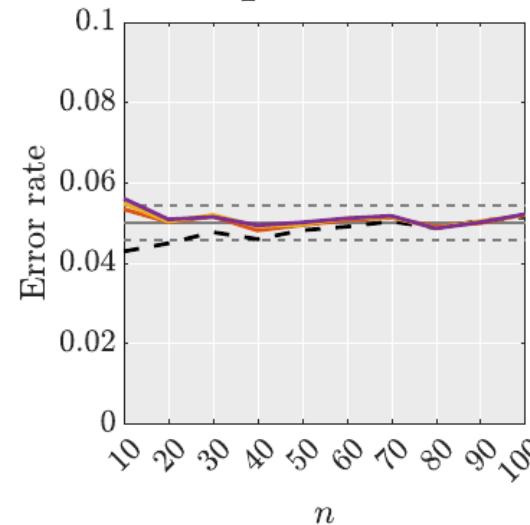
- Original
- $r = 1/2$
- $r = 1/3$
- $r = 1/5$

# FALSE POSITIVE RATES

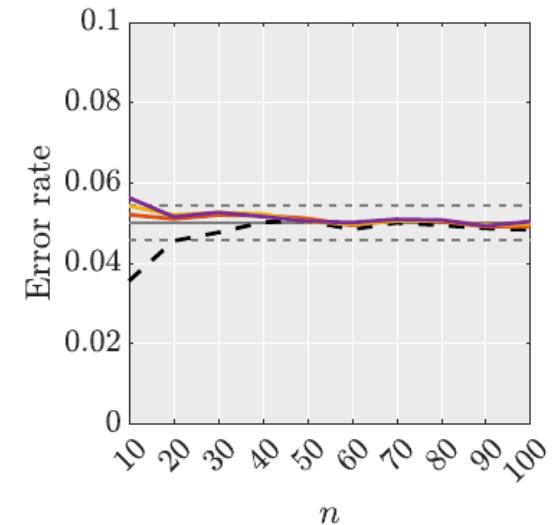
**Parametric**



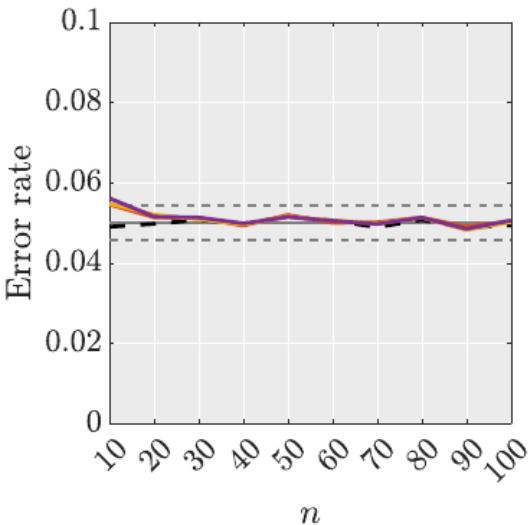
**Laplacian**



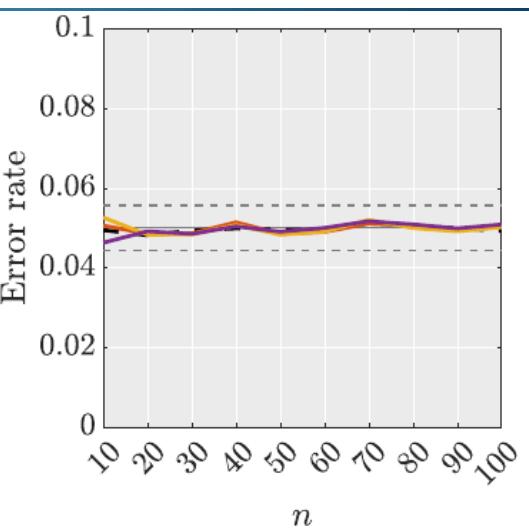
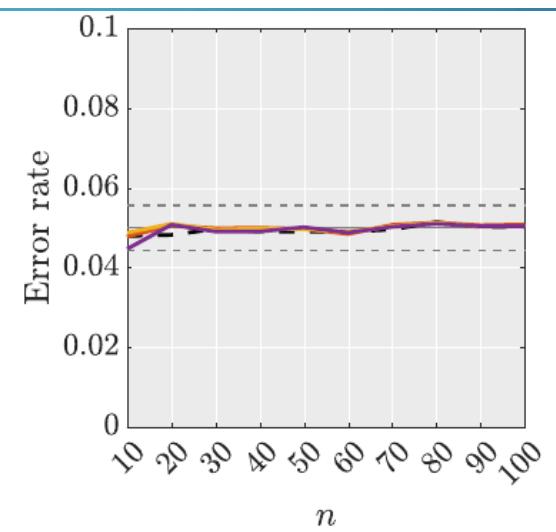
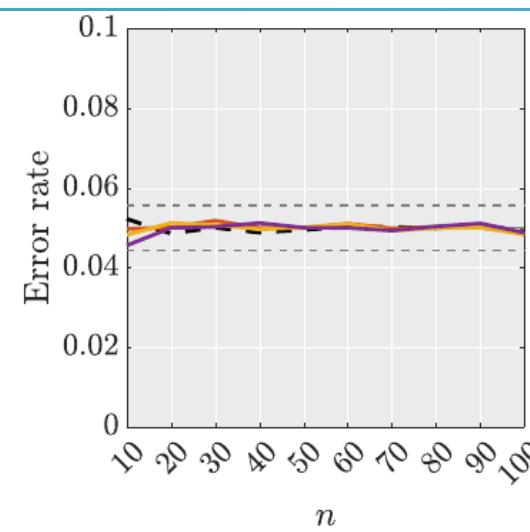
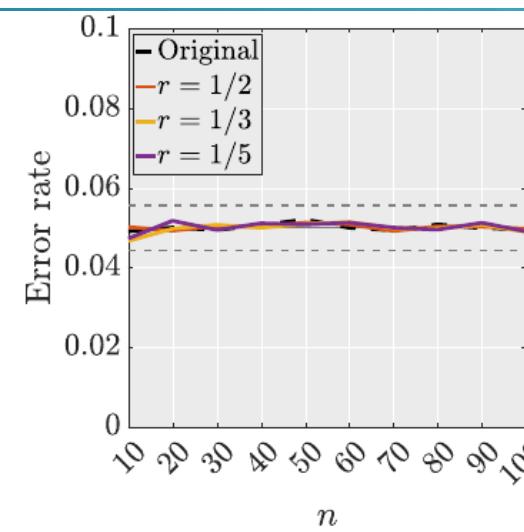
**Gaussian-Mixture**



**Gaussian**

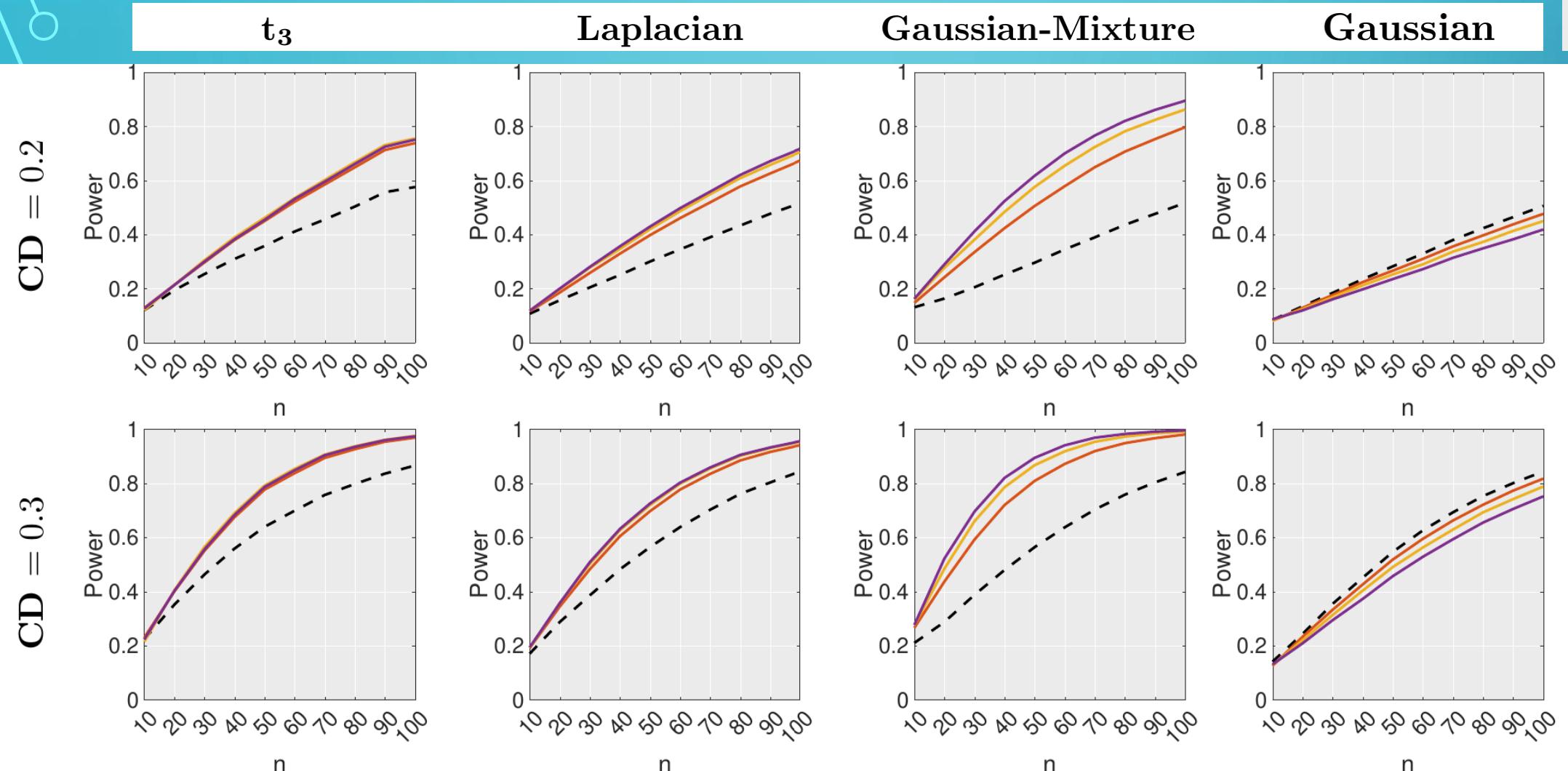


**Bootstrap**



# COMPARING THE POWER (PARAMETRIC)

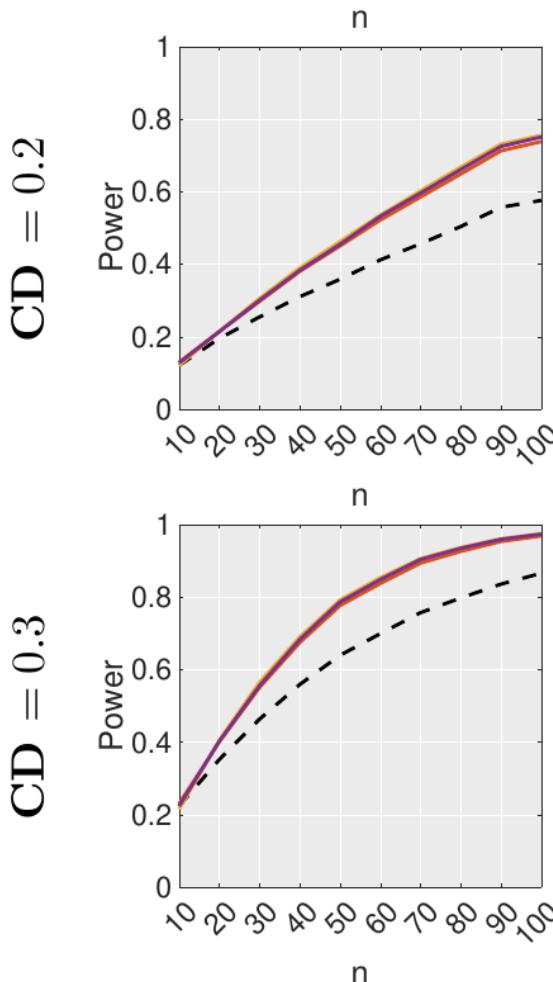
- Original
- $r = 1/2$
- $r = 1/3$
- $r = 1/5$



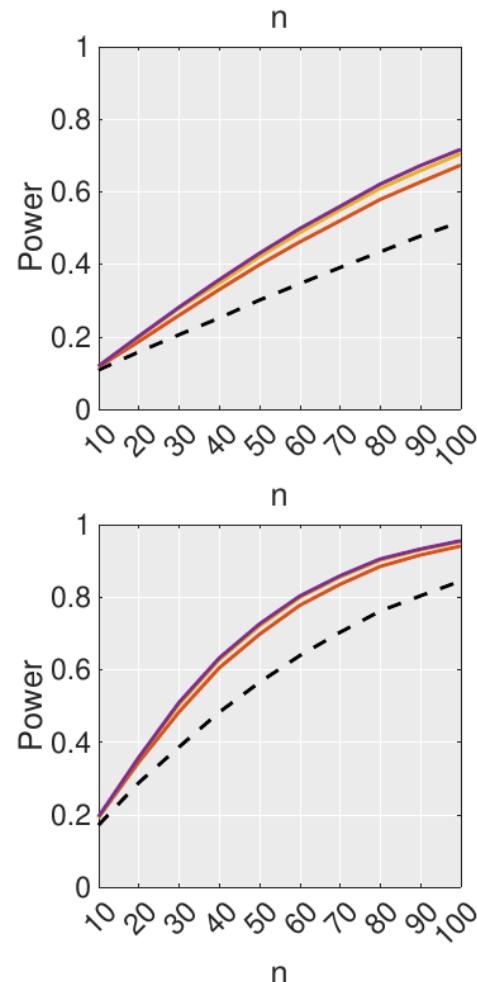
# COMPARING THE POWER (BOOTSTRAP)

- Original
- $r = 1/2$
- $r = 1/3$
- $r = 1/5$

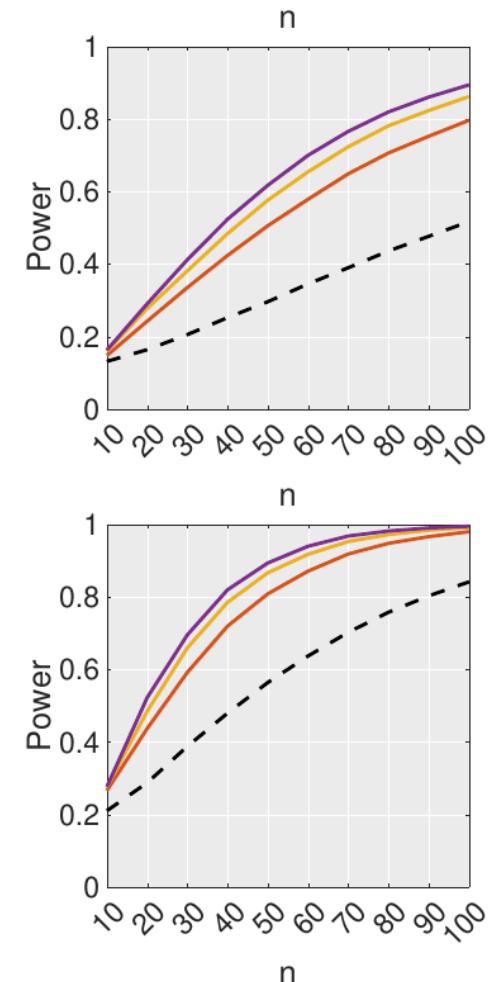
$t_3$



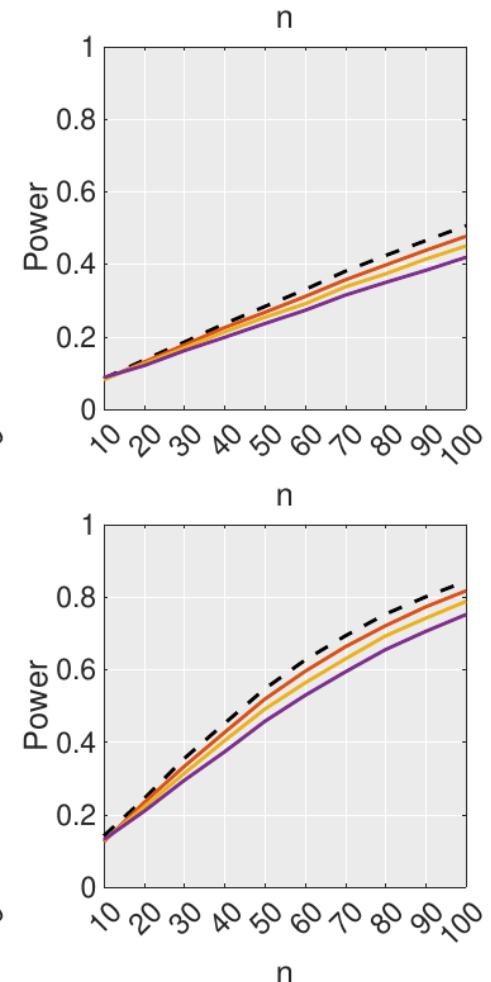
Laplacian



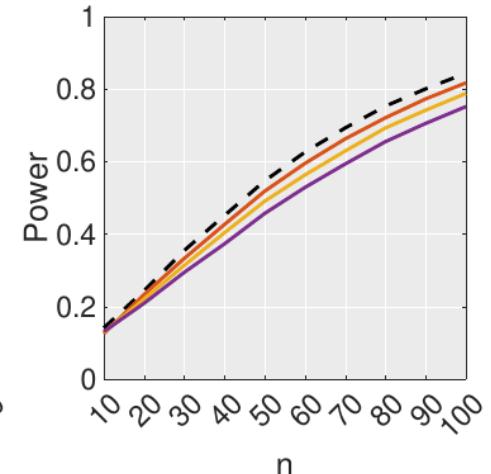
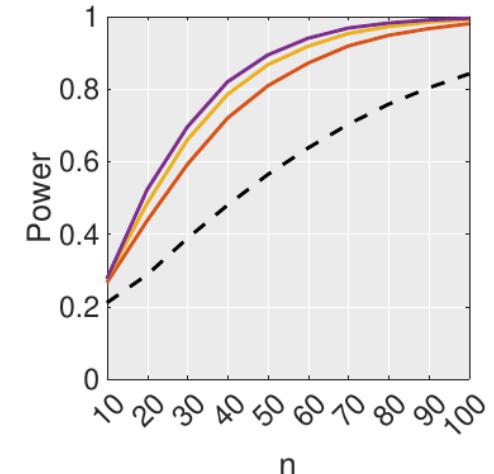
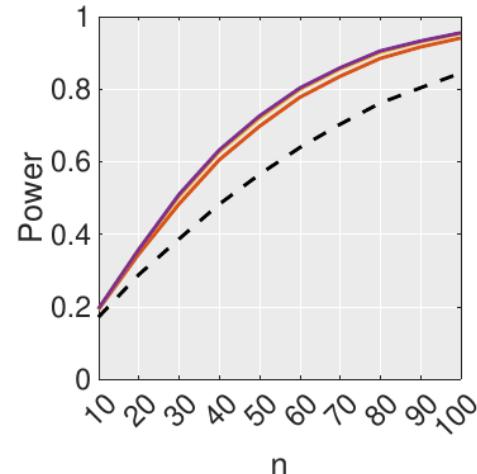
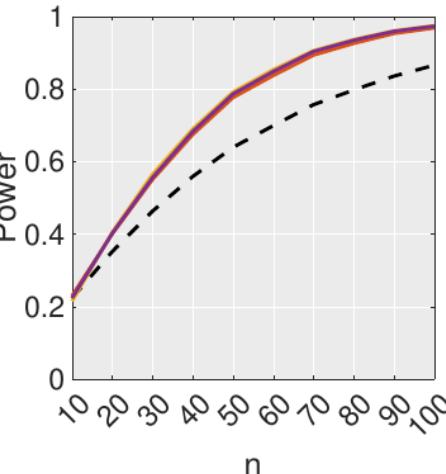
Gaussian-Mixture



Gaussian

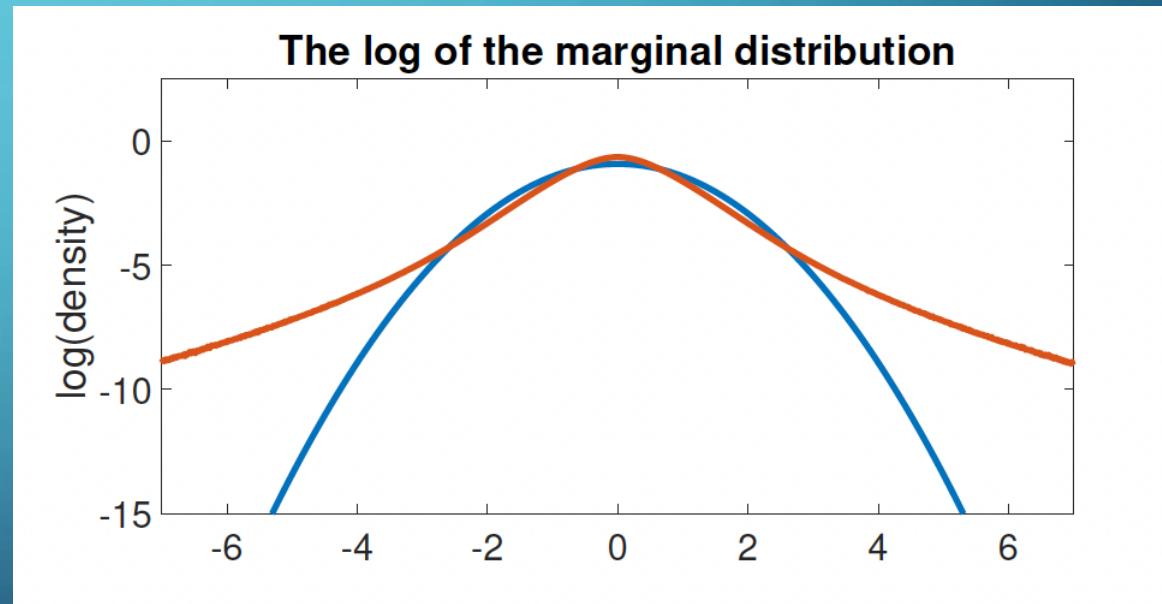
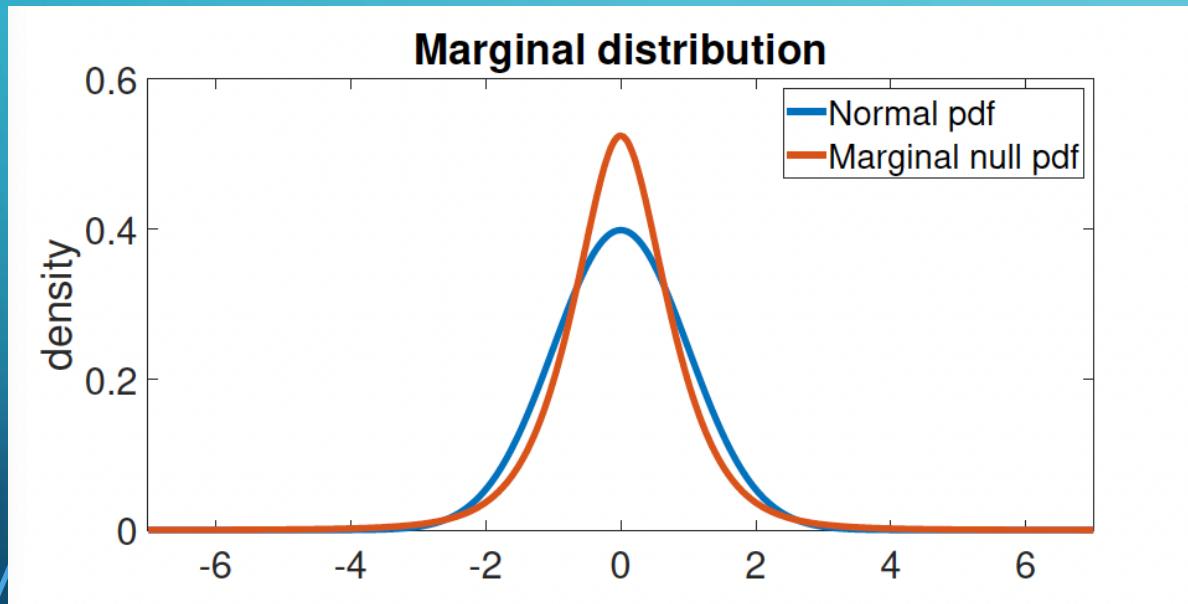


$CD = 0.3$



# NULL DISTRIBUTION OF FMRI DATA IS HEAVY TAILED

Examine the null distribution using resting state data processed with fake task designs (from 7000 subjects from the UK Biobank).

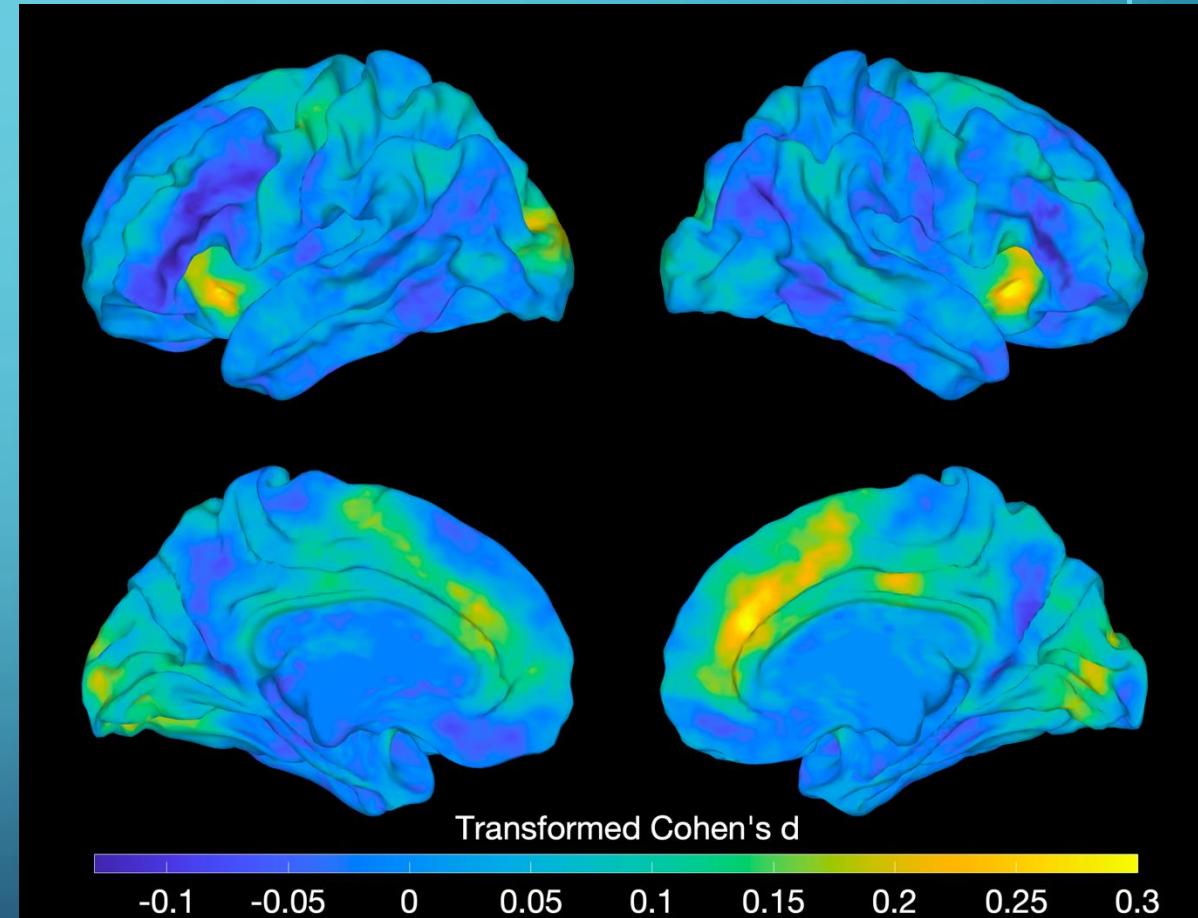
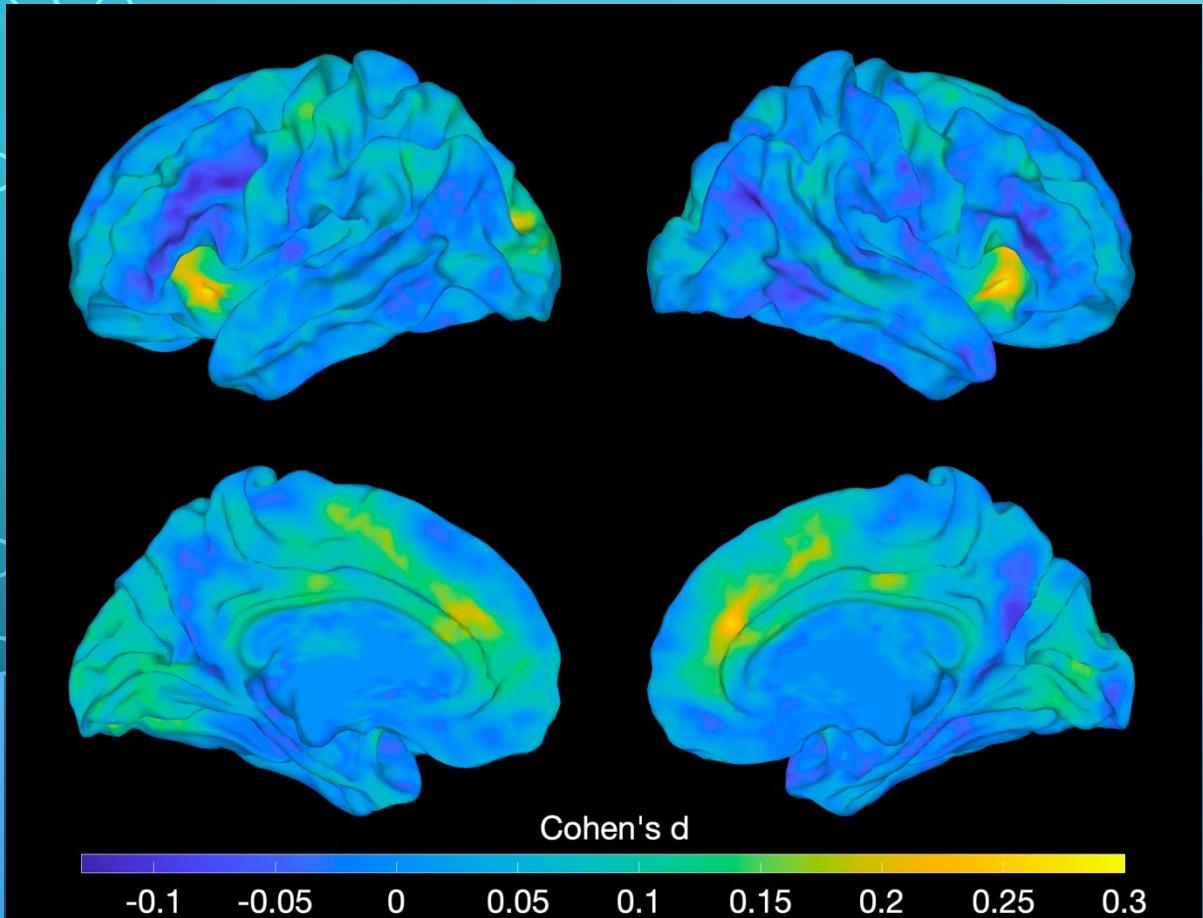


See Davenport et al (2023) for further details.

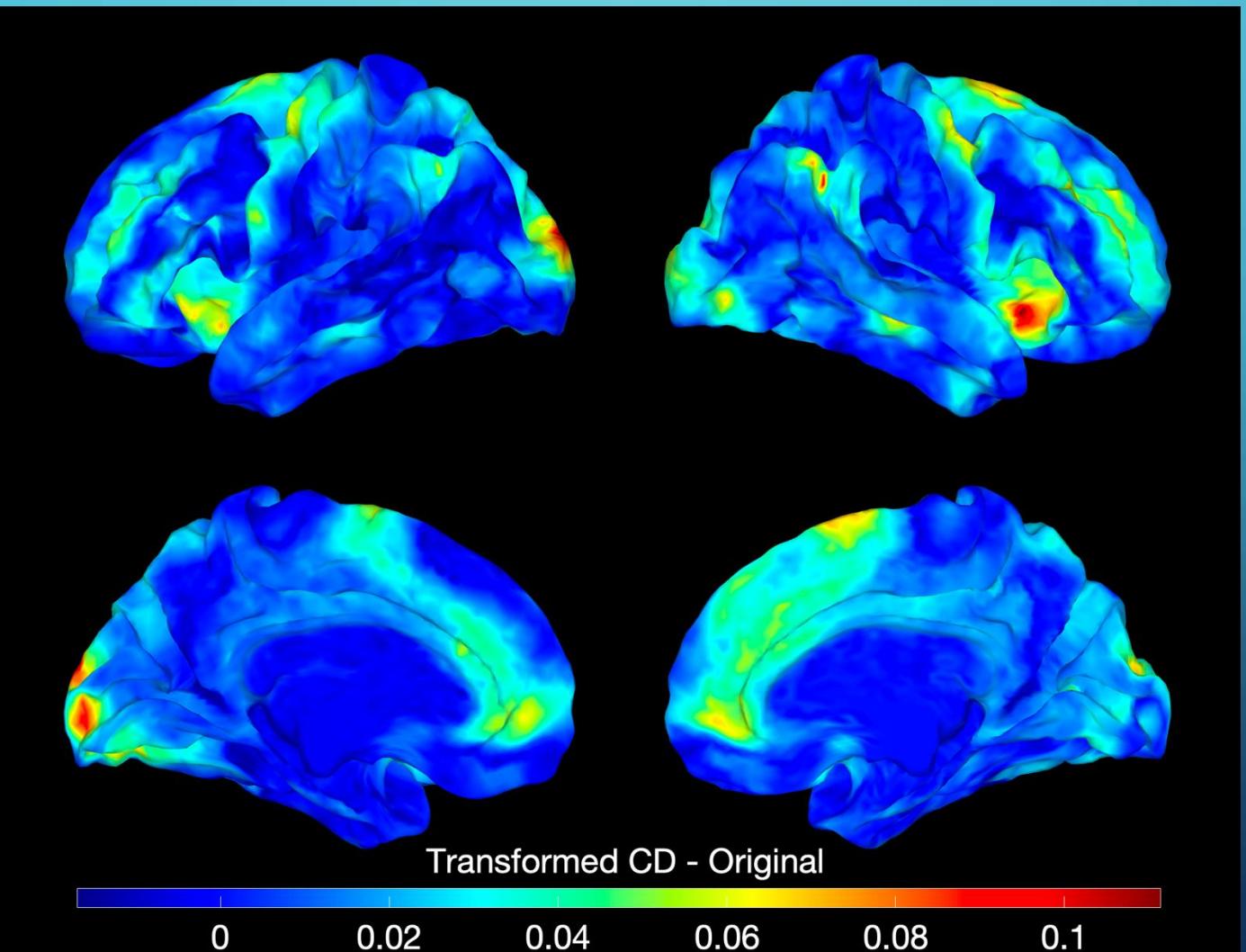
## APPLICATION TO ABCD DATA

- We have  $n = 15000$  subjects from the ABCD – MID task. We consider the contrast for anticipating large vs small rewards.
- We have data at 18000 brain imaging vertices for each of these subjects.
- We consider inference with and without transformations.
- We use a transformation of  $r = 1/5$  as this performed best in the simulations.

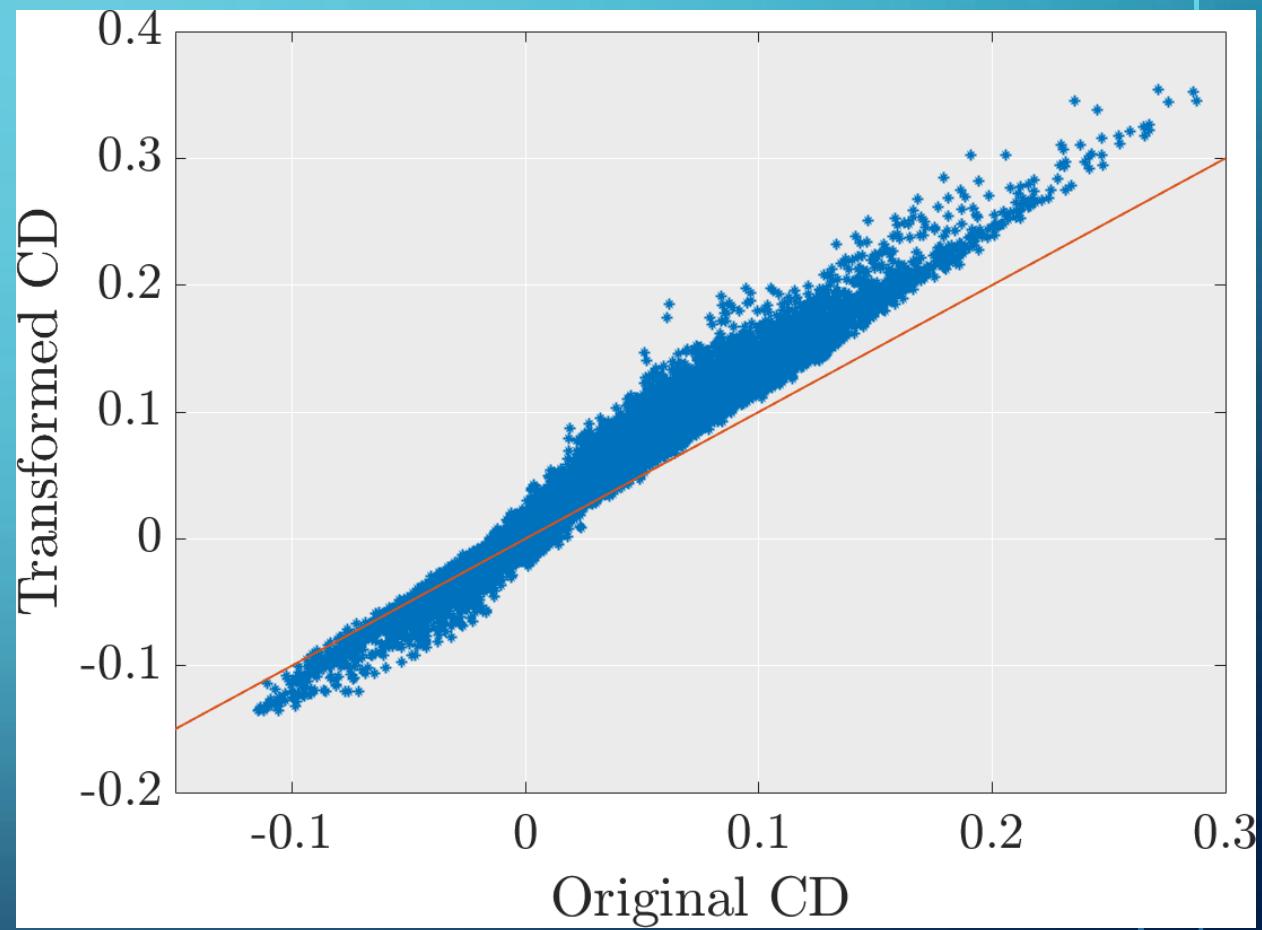
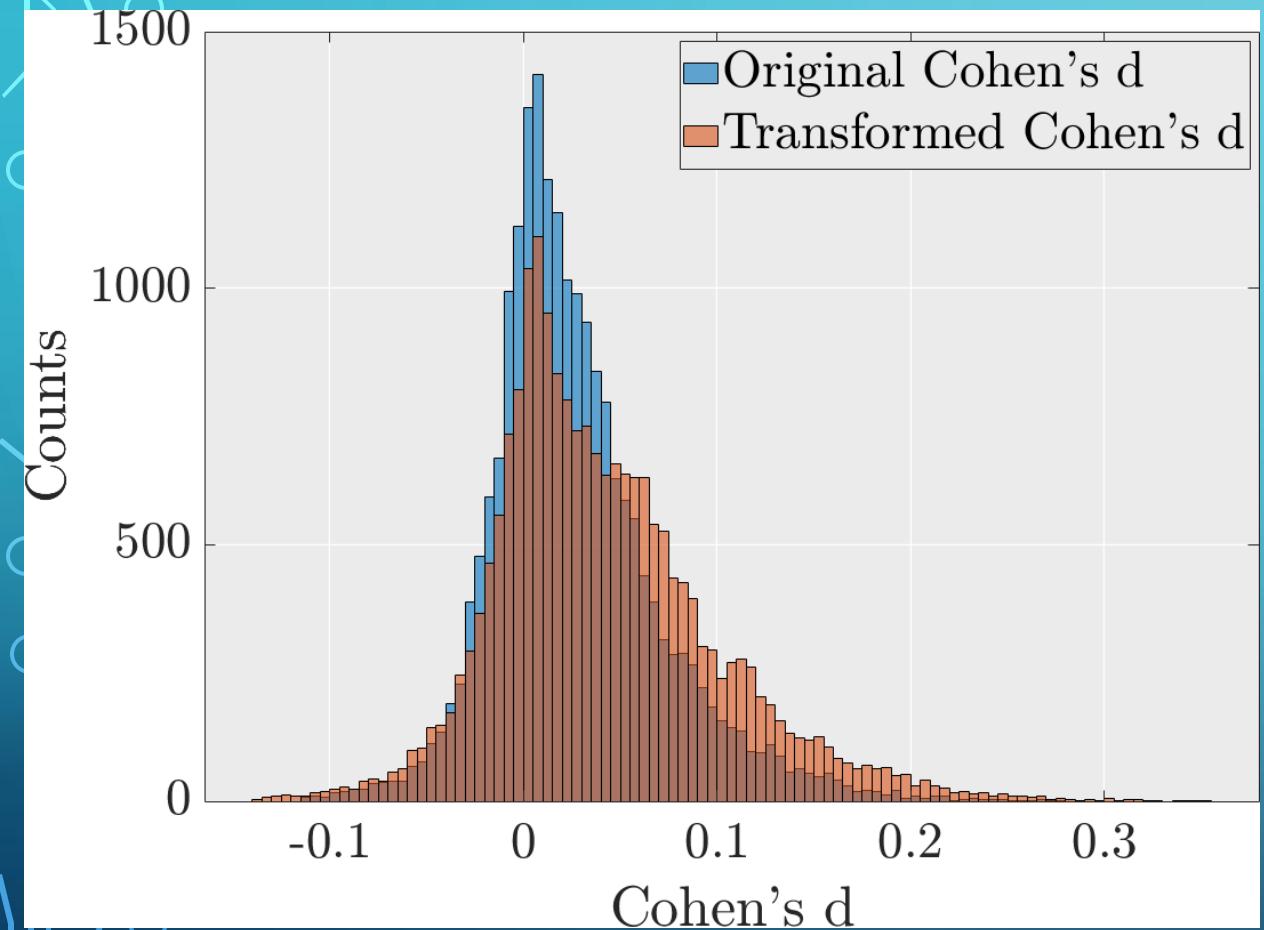
# COHEN'S D BEFORE AND AFTER



# ABSOLUTE DIFFERENCE IN COHEN'S D



# COMPARING COHEN'S D



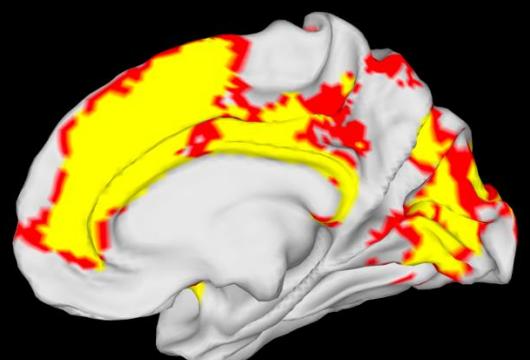
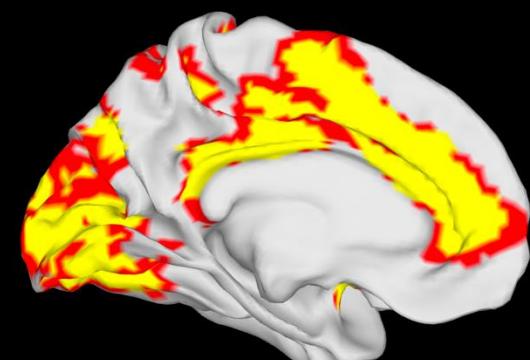
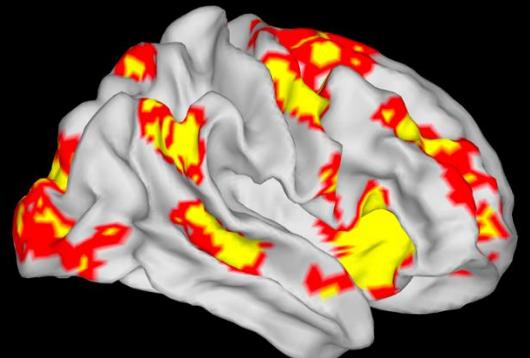
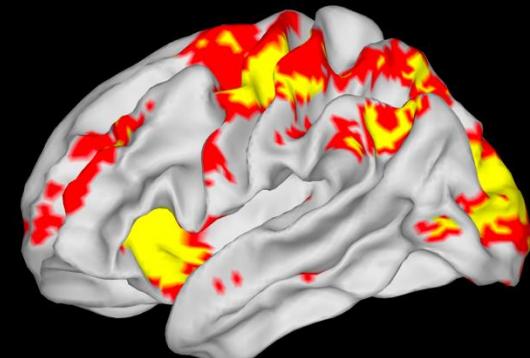
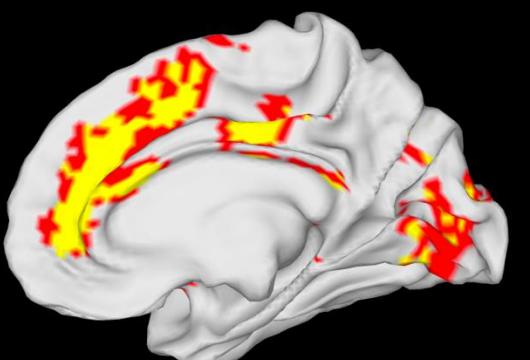
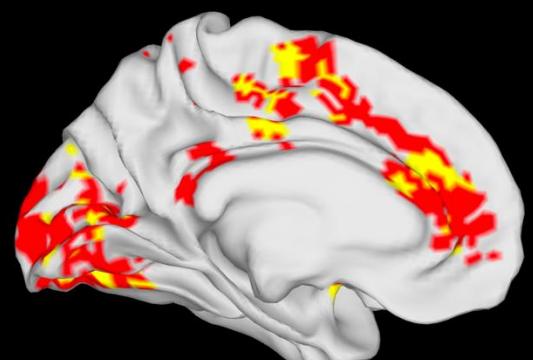
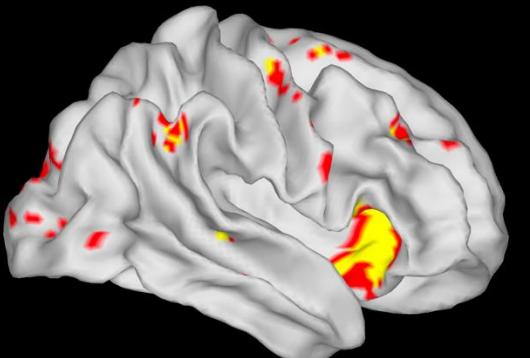
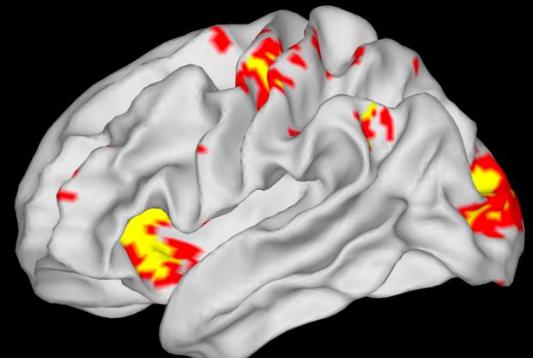
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- We have data at 18000 brain imaging vertices for each of these subjects.
- We consider inference with and without transformations.
- We use a transformation of  $r = 1/5$  as this performed best in the simulations.
- We use the multiplier bootstrap to do directional inference. Bootstrapping is performed jointly over all voxels to ensure that the dependence structure is preserved.

# COMPARING DISCOVERIES

Vertices significant for both  
original and transformed

Vertices significant for  
transformed and not original

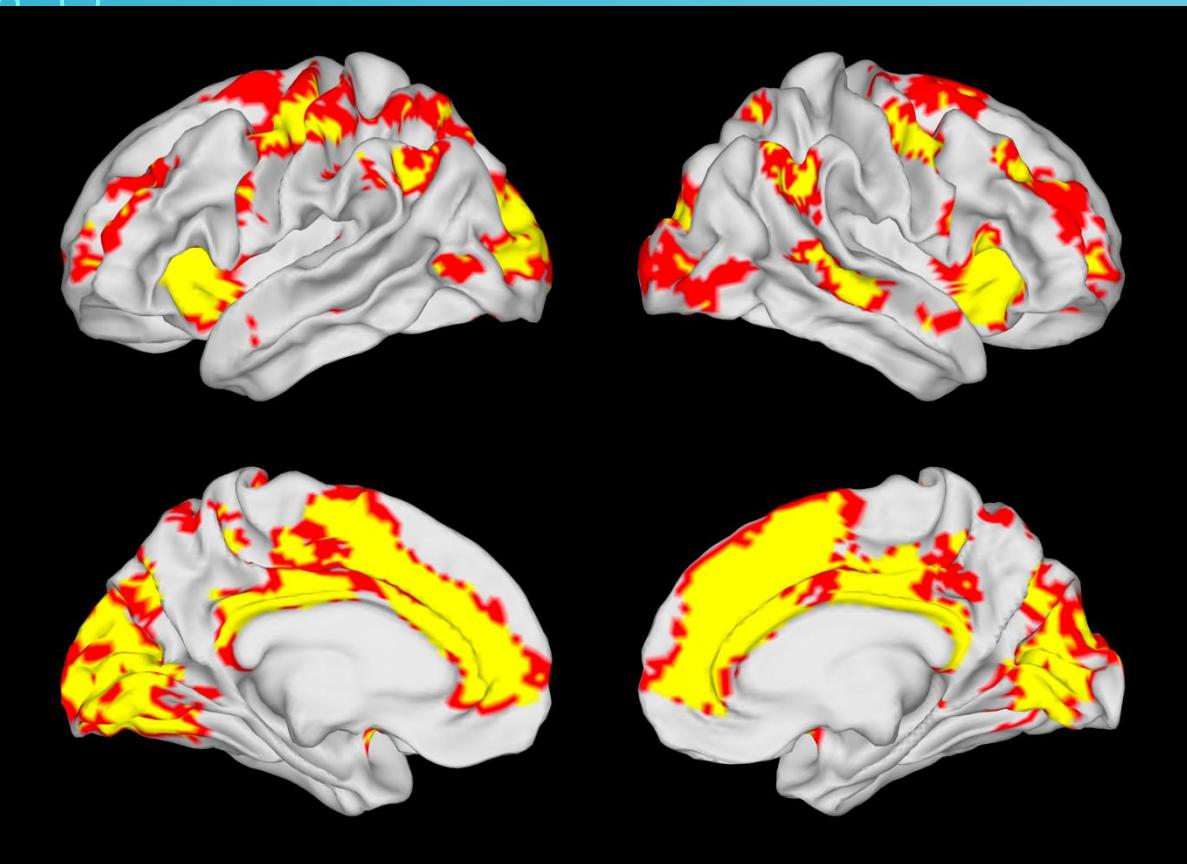


N = 1000

N = 4000

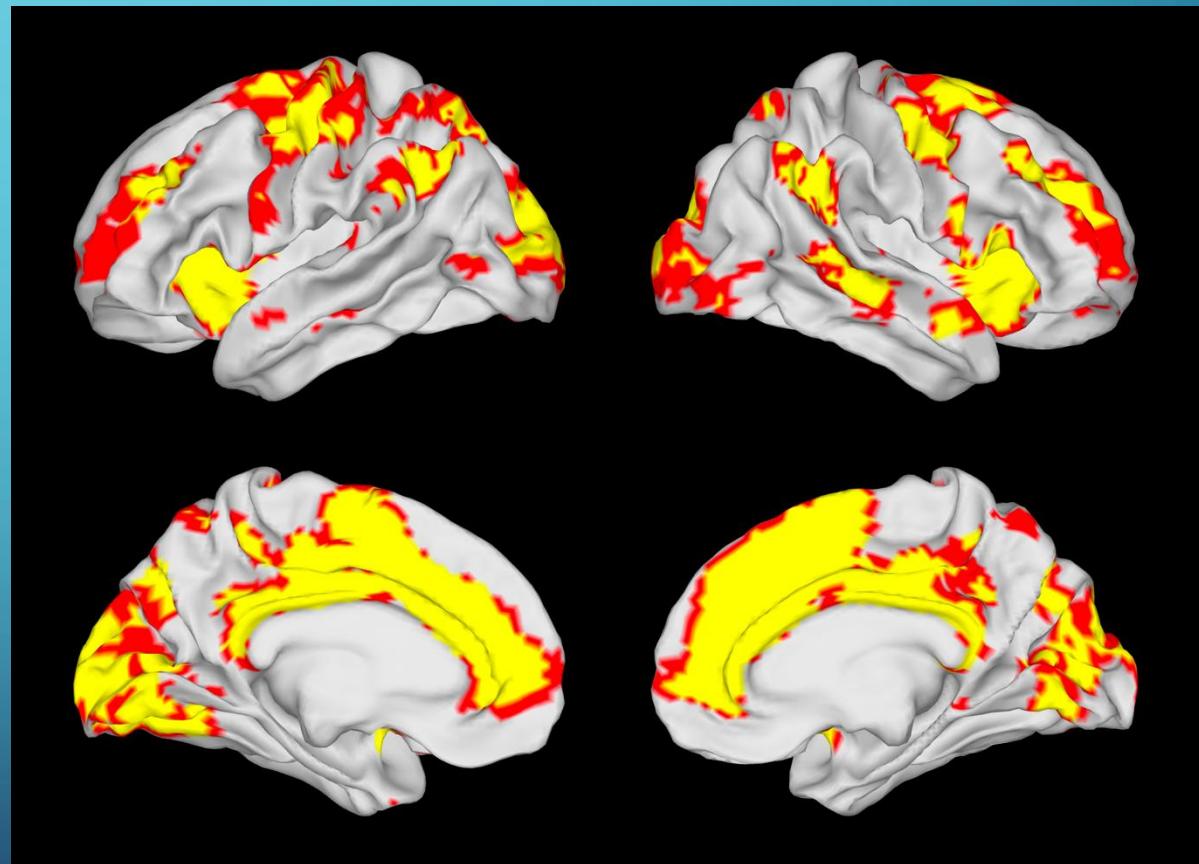
# COMPARING DISCOVERIES

Vertices significant for both  
original and transformed



$N = 3000$

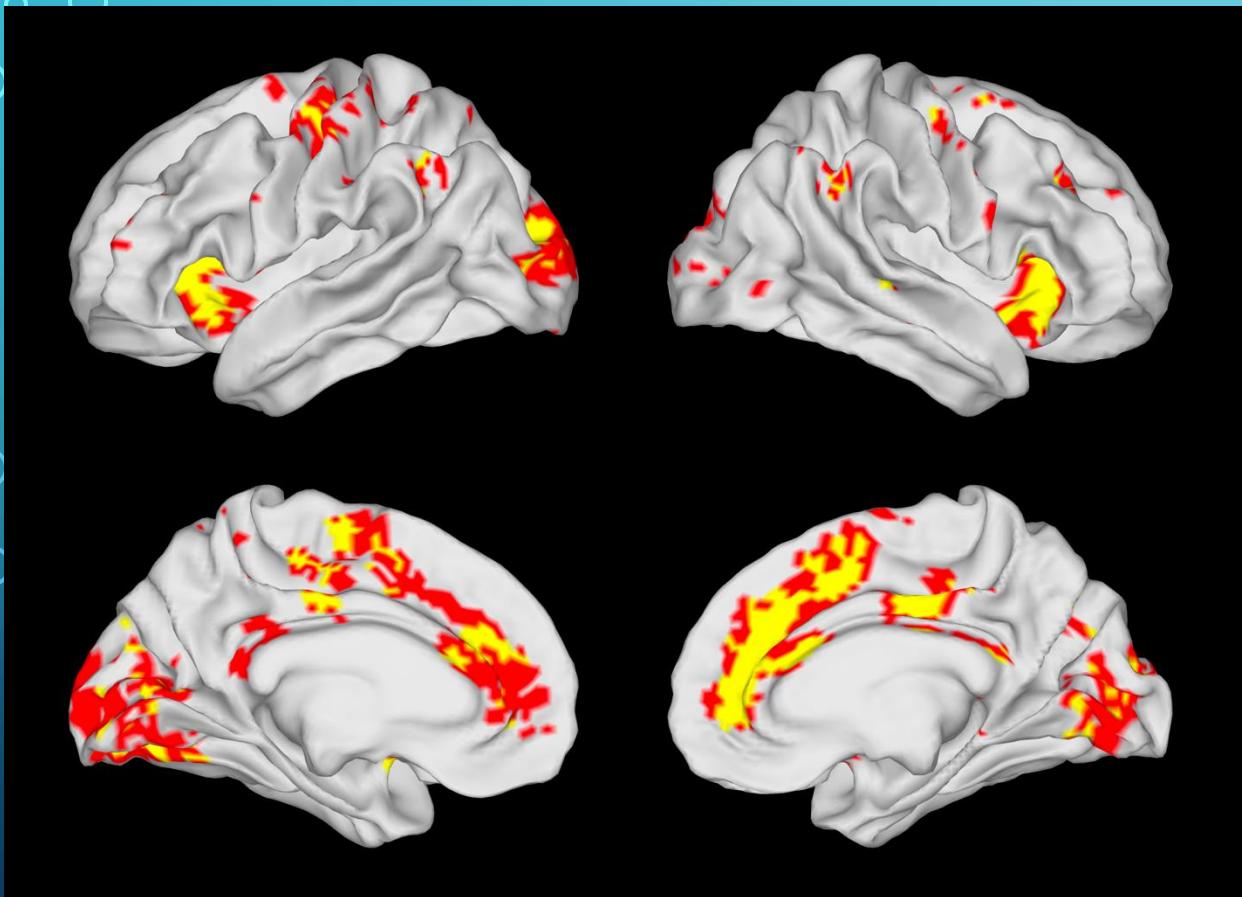
Vertices significant for  
transformed and not original



$N = 6000$

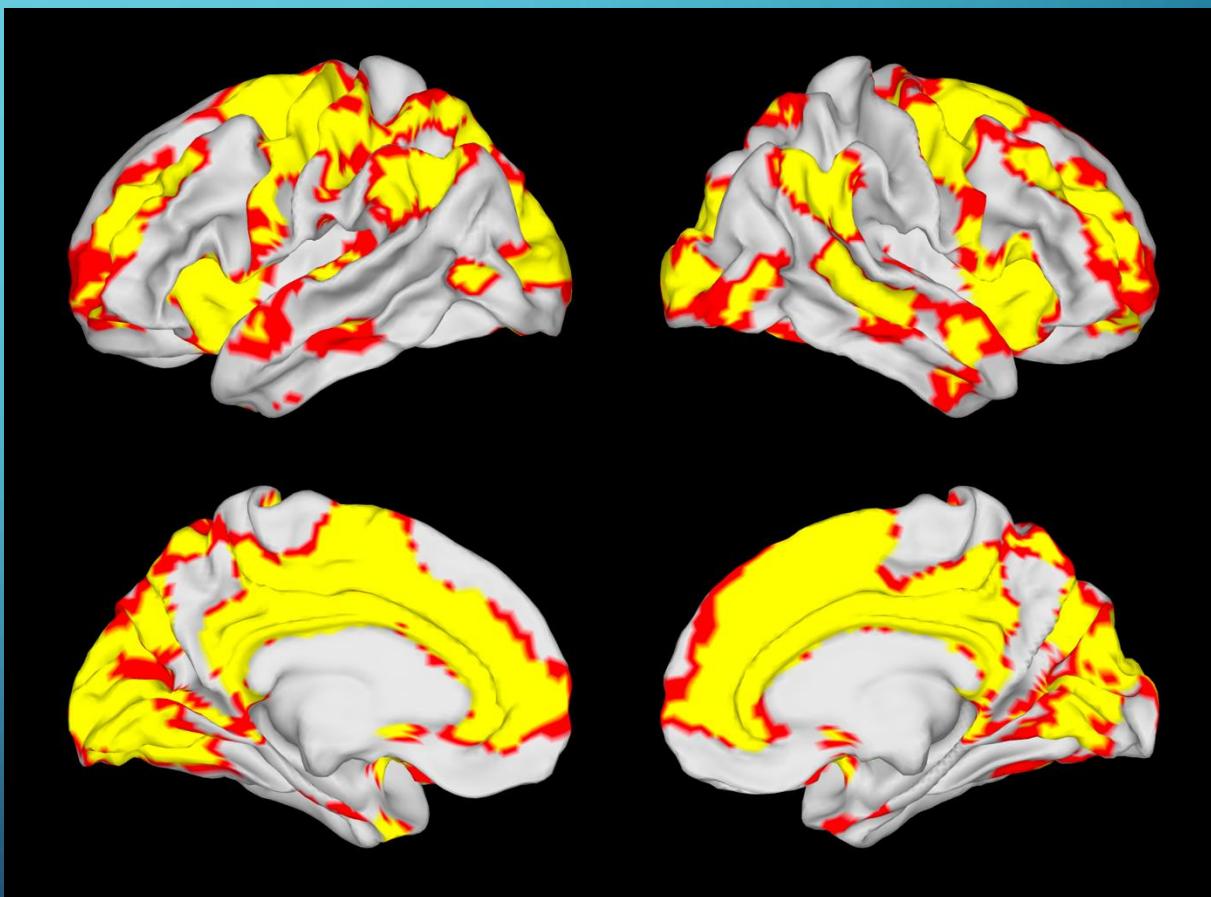
# COMPARING DISCOVERIES

Vertices significant for both  
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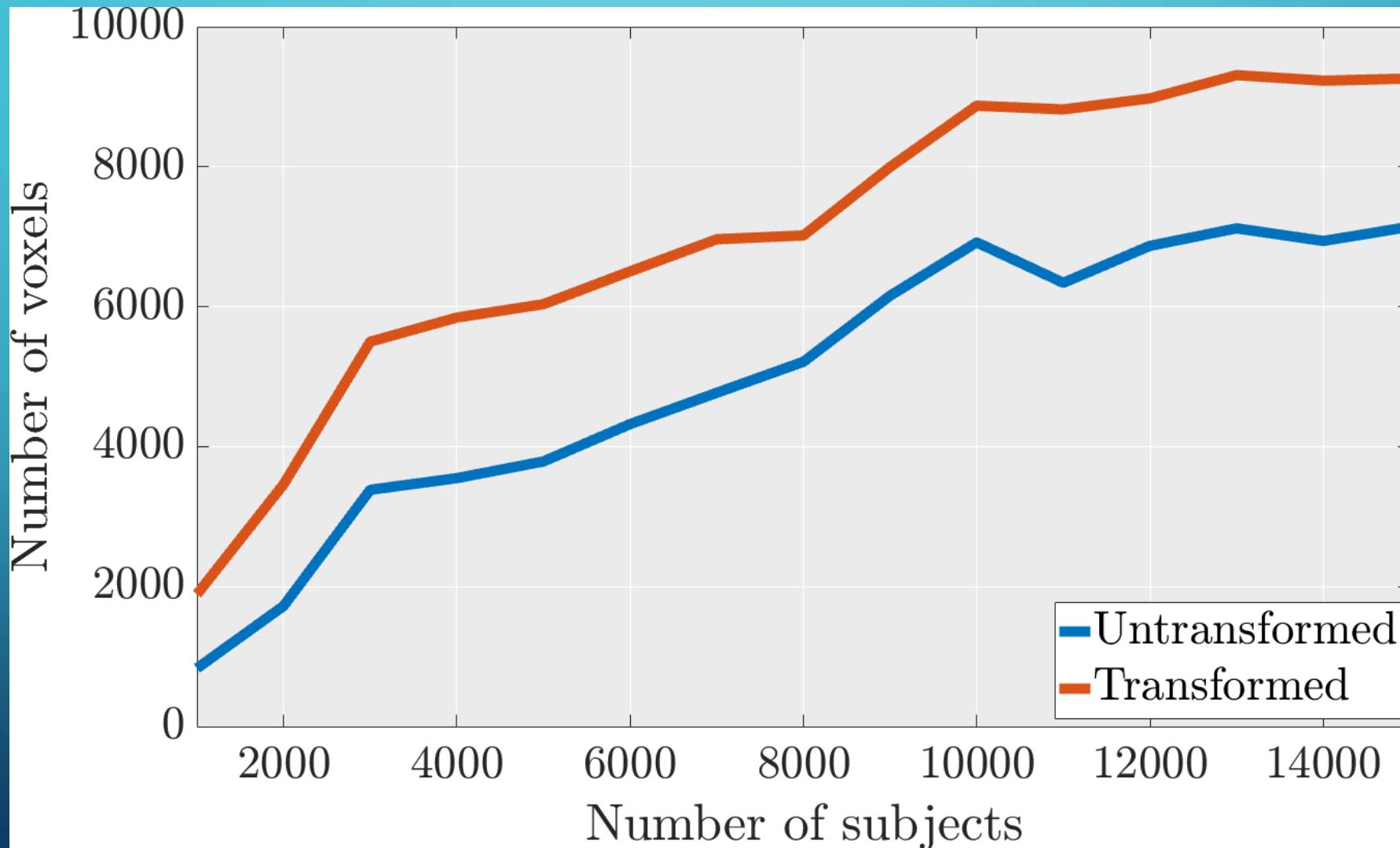
$N = 1000$

Vertices significant for  
transformed and not original



$N = 15000$

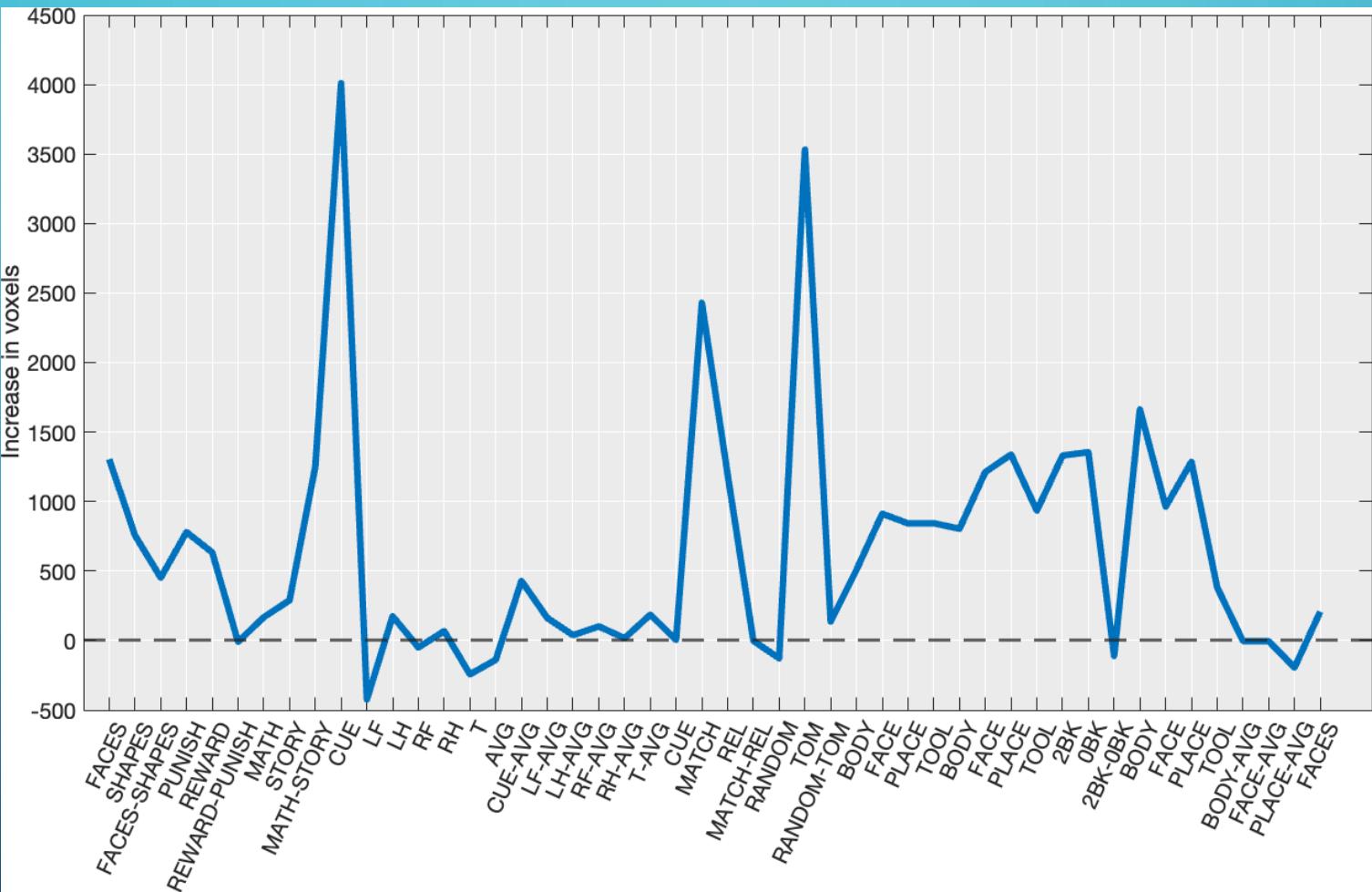
# DISCOVERIES VS NUMBER OF SUBJECTS



# CONCLUSIONS

- Transformations can be combined with non-parametric inference
- Transformations can be chosen to optimize power instead of Gaussianity
- The optimal transformation can be chosen based on the distribution of the data – in advance – in order to optimize power.
- fMRI data usually has a low sample size which can cause low power – this work helps to improve that
- We have focussed on  $H_0^D(v) : \mu(v) \leq 0$  but testing  $H_0^D(v) : \mu(v) \leq c$  is just as easy
- We focussed on the directional null however the point null can also be used and allows for exact inference based on sign-flipping.

# INCREASE IN POWER ON THE HCP DATA



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