Introduction to Computational Neuroscience

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2025-11-13

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1 Installation

This section sets up the packages required for this document. This takes a few minutes to run, so we will start it and "leave it cooking".

```
import Pkg
Pkg.add("Plots")
Pkg.add("SimpleDiffEq")
```

```
   Resolving package versions...
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jl_NtO6Jj/QuartoSandbox/Project.toml`
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    Updating `/private/var/folders/dk/h27sxrrj3mg6myd8ht0ym9300000gn/T/
```

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  [d1d4a3ce] + BitFlags v0.1.9
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  [f0e56b4a] + ConcurrentUtilities v2.5.0
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  [864edb3b] + DataStructures v0.19.3
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⌅ [30392449] + Pixman_jll v0.44.2+0
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  [8e850ede] + nghttp2_jll v1.64.0+1
  [3f19e933] + p7zip_jll v17.5.0+2
        Info Packages marked with ⌅ have new versions available but
compatibility constraints restrict them from upgrading. To see why use `status
--outdated -m`
   Resolving package versions...
     Project No packages added to or removed from `/private/var/folders/dk/
h27sxrrj3mg6myd8ht0ym9300000gn/T/jl_NtO6Jj/QuartoSandbox/Project.toml`
    Manifest No packages added to or removed from `/private/var/folders/dk/
h27sxrrj3mg6myd8ht0ym9300000gn/T/jl_NtO6Jj/QuartoSandbox/Manifest.toml`
```

```
using Plots
using SimpleDiffEq
```

2 Introduction

- "All models are wrong but some are useful" (Box, 1976?)
- Introduction to modelling in computational neuroscience

3 Background maths

3.1 Euler integration

Given some differential equation for how x changes over time and so initial condition (i.e. x = some value at time t = 0), we can integrate them numerically using Euler integration.

$\frac{dx}{dt} = f(x, t)$

$x_{n+1} = x_n + h\frac{dx}{dt}$

$x_{n+1} = x_n + hf(x_n, nh)$

Depending on the step-size h.

3.2 Trappenberg example (Appendix B)

Solve differential equation

$\frac{dx}{dt} = t - x + 1$

with initial conditions $x(0) = 1$.

Known solution:

$x(t) = \exp(-t) + t$

```
function euler1(h)
    tmax = 5.0;                                  # max t value
    init = 1.0;                                  # initial condition

    t = 0:h:tmax;                               # vector of time values
    nsteps = length(t);                         # how many steps
    x = zeros(nsteps,1);                        # where we will store
    # results
    x[1] = init;

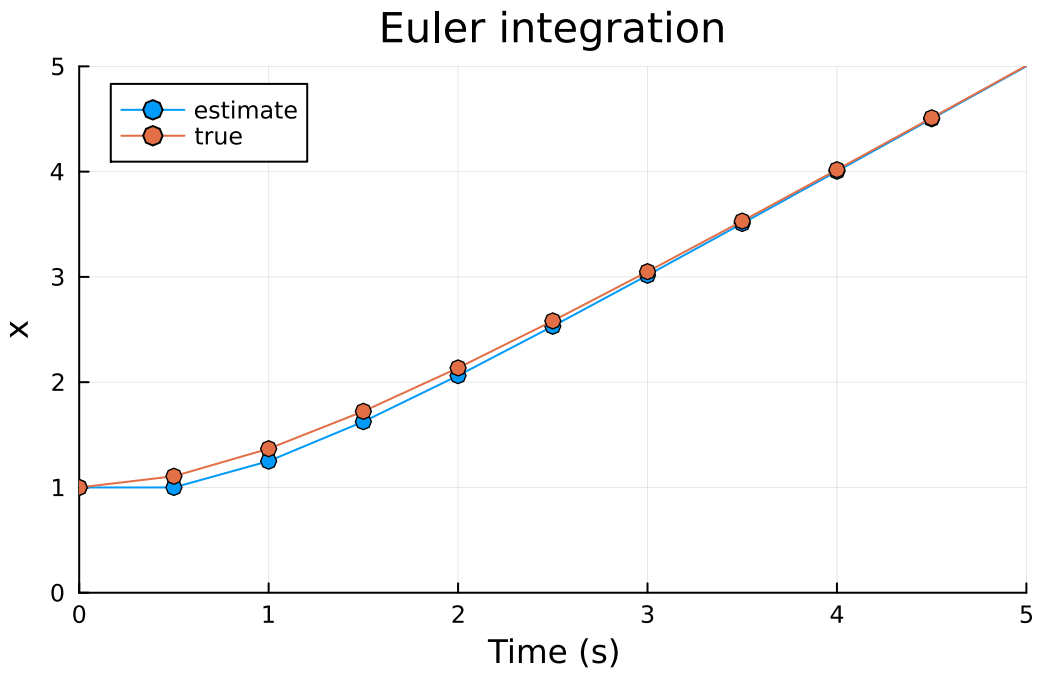

    # Start the integration
    for i=1:(nsteps-1)
        f = t[i] - x[i] + 1;                    # evaluate dx/dt
        x[i+1] = x[i] + (h*f);
    end
    ## why need space?
    hcat(t, x)
end

function plot_euler1(h)
    res = euler1(h);
    t = res[:,1]
    x = res[:,2]
    xtrue = @. exp(-t) + t;                      # true solution

    plot(t, hcat(x, xtrue), legend=:topleft,
         ylim=(0,5),
         xlim=(0,5),
         marker=:o,
         title = "Euler integration",
         xlabel="Time (s)", ylabel="x",
         label=["estimate" "true"])
end
```

```
plot_euler1 (generic function with 1 method)
```

```
h_step = 0.5   # adjust between 0.01 and 1
plot_euler1(h_step)
```



4 Hodgkin-Huxley model

4.1 Reminder of the biology

Its all in the channels!

http://tinyurl.com/matthews-channel

4.2 Reminder of the mathematics

See hh_maths.pdf

Julia has built-in functions for efficient numerical integration of ODEs. We will use them here so that we focus on the problem and not the numerics.

```
function hhode!(dy, y, p, t)
    v = y[1]; m = y[2]; n = y[3]; h = y[4];

    # Some constants of the system.
    I = p[1]
    gna = 1200; gk=360; gl=3;
    El=-54.387; Ek=-77.0; Ena=100.0;
    C = 10;


    am = 0.1*(v+40)/(1-exp(-(v+40)/10));
    bm = 4*exp(-(v+65)/18);
```

```
    ah = 0.07*exp(-(v+65)/20);
    bh = 1/(1+exp(-(v+35)/10));

    an = 0.01*(v+55)/(1-exp(-(v+55)/10));
    bn = 0.125*exp(-(v+65)/80);

    dv = (I - gna*h*(v-Ena)*m^3-gk*(v-Ek)*n^4-gl*(v-El))/C;

    dm = am*(1-m) -bm*m;
    dh = ah*(1-h) -bh*h;
    dn = an*(1-n) -bn*n;

    # Return derivatives
    dy[1]=dv;
    dy[2]=dm;
    dy[3]=dn;
    dy[4]=dh;

end


function plot_hh(;i=10)
    u0 = [-65.0;0.0529;0.3177;0.5961]
    tspan = (0.0,500.0)
    p = [i]
    prob = ODEProblem(hhode!,u0,tspan,p)

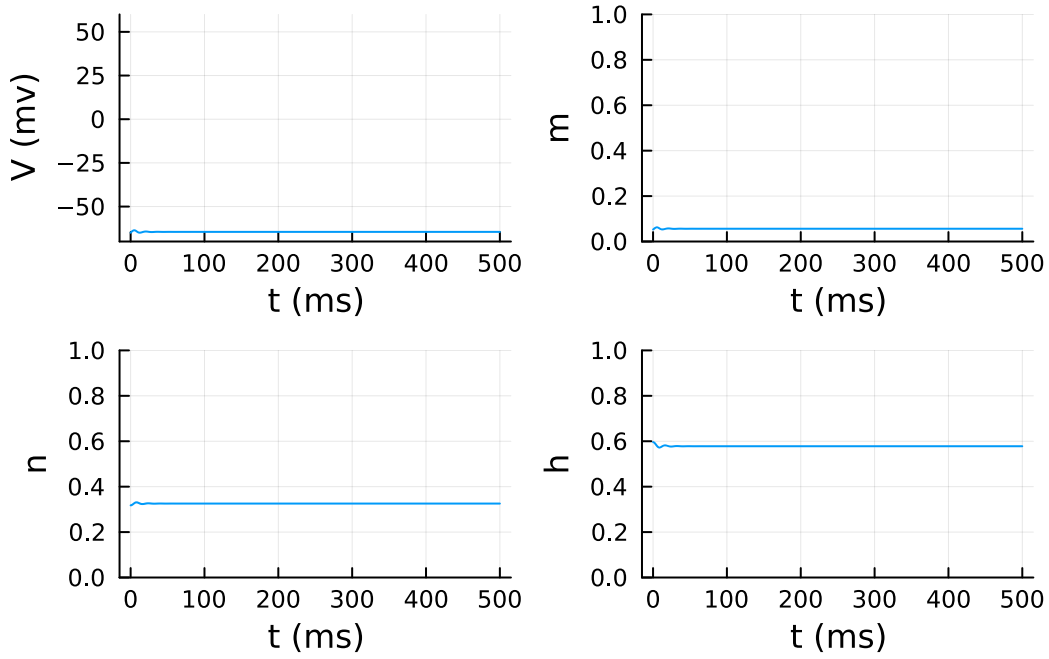
    ##sol = solve(prob,Vern7());
    sol = solve(prob, SimpleRK4(), dt = 0.01);


    l = @layout [a b; c d]
    p1 = plot(sol.t, sol[1,:], xlabel="t (ms)", ylabel= "V (mv)",
              ylim=(-70,60), legend=false);
    p2 = plot(sol.t, sol[2,:], xlabel="t (ms)", ylabel= "m",
              ylim=(0,1), legend=false);
    p3 = plot(sol.t, sol[3,:], xlabel="t (ms)", ylabel= "n",
              ylim=(0,1), legend=false);
    p4 = plot(sol.t, sol[4,:], xlabel="t (ms)", ylabel= "h",
              ylim=(0,1), legend=false);
    plot(p1, p2, p3, p4, layout = l)
end
```

```
plot_hh (generic function with 1 method)
```

Run with default I=0.1 and then compare with I=10.

```
i_step = 0.05
plot_hh(i=i_step)
```



4.3 Exercises

1. Can you find the critical value of I where you first generate a spike?
2. Can you work out the units on I (check equation 1 and Table 1 of hh_maths.pdf)?
3. Estimate the firing rate (in Hz) for the model as you vary I from 0 to 500. Can you plot a graph of it?
4. (Advanced) Apply a pulse of negative current with I=-50 for 5 ms followed by I=0 and describe what happens.
5. Try other manipulations, e.g. what if you set dh/dt to zero? What would this simulate?

5 Izhikevich models

Let's simplify the models as far as we can; we are going to use the simplification due to Izhikevich.

Read the basic description and guess which is the real data.

5.1 The basic model

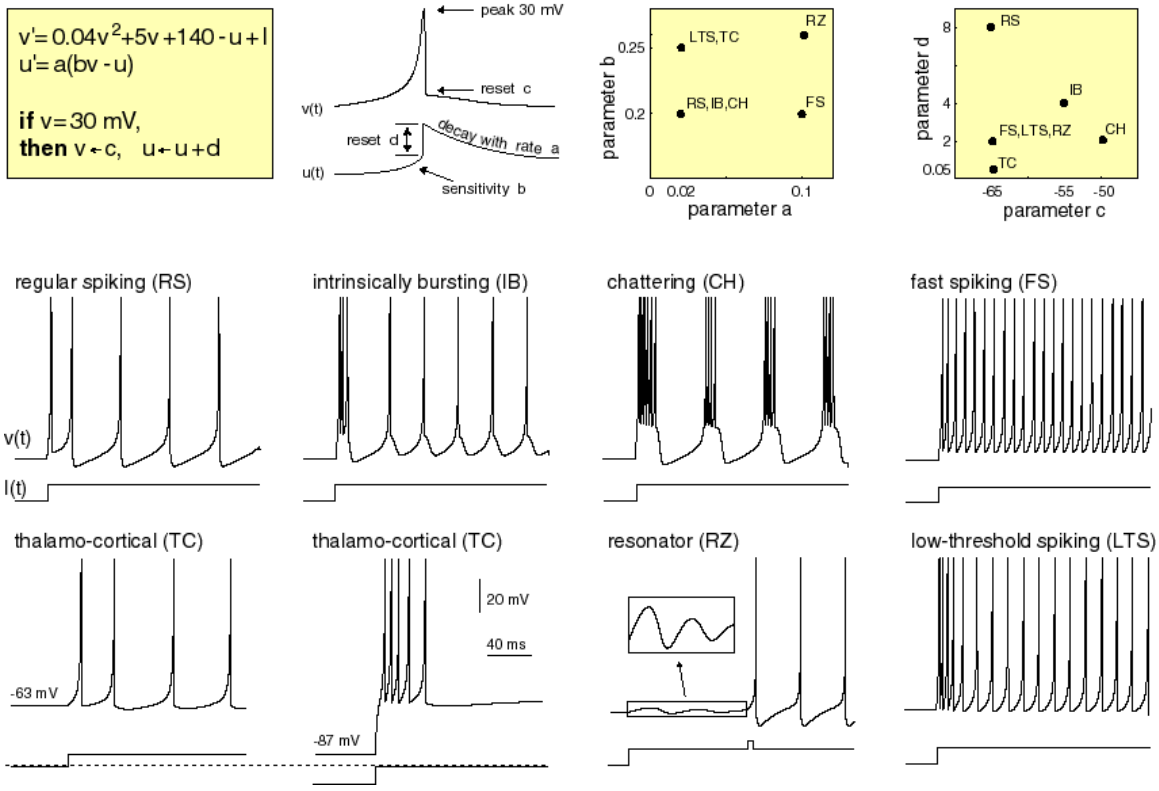


Figure 1: the basic model

5.2 Exercise: Izhikevich

1. izh.jl has the basic code for one of the models. Try to adapt using parameters a,b,c,d to generate each of the plots from above. e.g. how can you make a chattering cell (CH)?

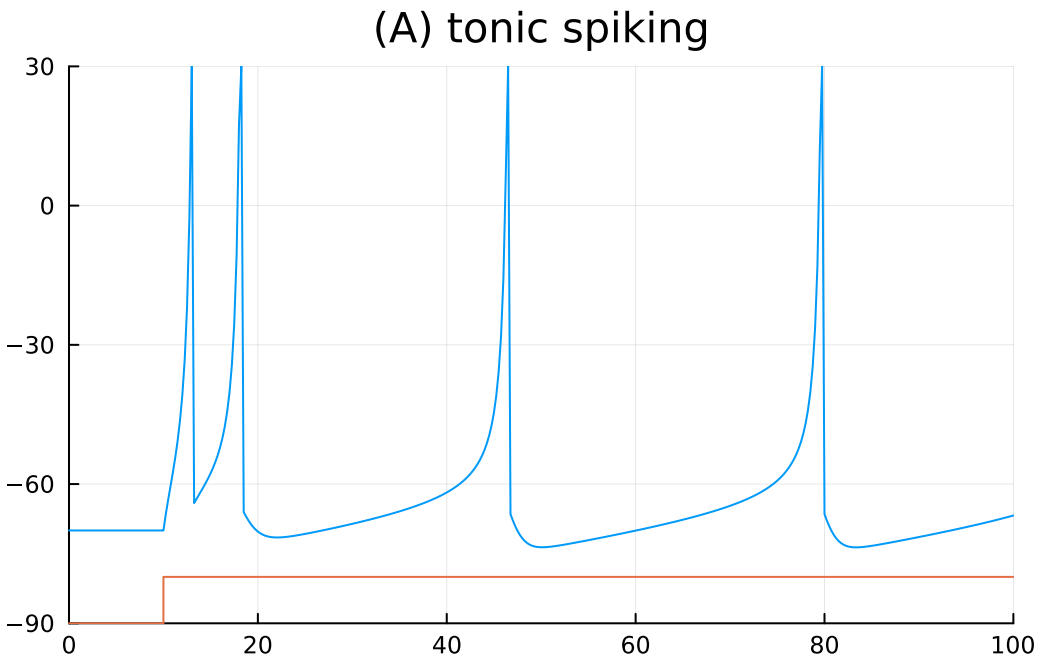
2. Explore figure1.jl. This regenerates figure 1 of the 2004 paper. See if you can follow in the code how the model is adapted in each case.

```
function izh(;a=0.02,b=0.2, c=-65.0, d=6.0)
    #a=0.02; b=0.2;  c=-65;  d=6;
    V=-70;  u=b*V;
    VV=[];  uu=[];
    tau = 0.25; tspan = 0:tau:100;
    T1=tspan[end]/10;
    for t=tspan
        if (t>T1)
            I=14;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
```

```
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot(tspan,VV, title="(A) tonic spiking",
         legend=false,
         xlims=(0, tspan[end]), ylims=(-90,30));
    plot!([0,T1,T1,tspan[end]],-90.0 .+ [0,0,10,10])

end

izh(a=0.02, b=0.2, c=-65,  d=8)
```



5.3 20 cell types?

```
begin
    #   This file generates figure 1 in the paper by
    #               Izhikevich E.M. (2004)
    #   Which Model to Use For Cortical Spiking Neurons?

    #ENV["MPLBACKEND"]="qt4agg"
```

```
using Statistics                # for the mean function

#(A) tonic spiking

function plot_ts(t,v,title)
    plot(t,v, title=title,
         titlefontsize=10,
         legend=false, axis=nothing,
         xlims=(0, t[end]), ylims=(-90,30));
end

function izh_a()
    a=0.02; b=0.2;  c=-65;  d=6;
    V=-70;  u=b*V;
    VV=[];  uu=[];
    tau = 0.25; tspan = 0:tau:100;
    T1=tspan[end]/10;
    for t=tspan
        if (t>T1)
            I=14;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV, "(A) tonic spiking")
    plot!([0,T1,T1,tspan[end]],-90.0 .+ [0,0,10,10])
end

function izh_b()
    # (B) phasic spiking
    a=0.02; b=0.25; c=-65;  d=6;
    V=-64; u=b*V;
    VV=[];  uu=[];
    tau = 0.25;tspan = 0:tau:200;
    T1=20;
    for t=tspan
        if (t>T1)
```

```
            I=0.5;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV, "(B) phasic spiking")
    plot!([0,T1,T1,tspan[end]],-90.0 .+ [0,0,10,10])
end


#(C) tonic bursting
function izh_c()
    a=0.02; b=0.2;  c=-50;  d=2;
    V=-70;  u=b*V;
    VV=[];  uu=[];
    tau = 0.25; tspan = 0:tau:220;
    T1=22;
    for t=tspan
        if (t>T1)
            I=15;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV, "(C) tonic bursting")
    plot!([0,T1,T1,tspan[end]],-90.0 .+[0,0,10,10])
end
```

```
#(D) phasic bursting
function izh_d()
    a=0.02; b=0.25; c=-55;  d=0.05;
    V=-64;  u=b*V;
    VV=[];  uu=[];
    tau = 0.2;  tspan = 0:tau:200;
    T1=20;
    for t=tspan
        if (t>T1)
            I=0.6;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV,"(D) phasic bursting")
    plot!([0,T1,T1,tspan[end]],-90.0 .+[0,0,10,10])
end


#(E) mixed mode
function izh_e()
    a=0.02; b=0.2;  c=-55;  d=4;
    V=-70;  u=b*V;
    VV=[];  uu=[];
    tau = 0.25; tspan = 0:tau:160;
    T1=tspan[end]/10;
    for t=tspan
        if (t>T1)
            I=10;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
```

```
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV, "(E) mixed mode")
    plot!([0,T1,T1,tspan[end]],-90.0 .+[0,0,10,10])
end

#(F) spike freq. adapt
function izh_f()
    a=0.01; b=0.2;  c=-65;  d=8;
    V=-70;  u=b*V;
    VV=[];  uu=[];
    tau = 0.25; tspan = 0:tau:85;
    T1=tspan[end]/10;
    for t=tspan
        if (t>T1)
            I=30;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV, "(F) spike freq. adapt")
    plot!([0,T1,T1,tspan[end]],-90.0 .+[0,0,10,10])
end


#(G) Class 1 exc.
function izh_g()
    a=0.02; b=-0.1; c=-55; d=6;
    V=-60; u=b*V;
    VV=[]; uu=[];
    tau = 0.25; tspan = 0:tau:300;
    T1=30;
    for t=tspan
        if (t>T1)
            I=(0.075*(t-T1));
```

```
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+4.1*V+108-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV,"(G) Class 1 excitable")
    plot!([0,T1,tspan[end],tspan[end]],-90.0 .+[0,0,20,0])
end


#(H) Class 2 exc.
function izh_h()
    a=0.2;  b=0.26; c=-65;  d=0;
    V=-64;  u=b*V;
    VV=[];  uu=[];
    tau = 0.25; tspan = 0:tau:300;
    T1=30;
    for t=tspan
        if (t>T1)
            I=-0.5+(0.015*(t-T1));
        else
            I=-0.5;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV, "(H) Class 2 excitable")
    plot!([0,T1,tspan[end],tspan[end]],-90.0 .+[0,0,20,0])
end
```

```
# (I) spike latency
function izh_i()
    a=0.02; b=0.2;  c=-65;  d=6;
    V=-70;  u=b*V;
    VV=[];  uu=[];
    tau = 0.2; tspan = 0:tau:100;
    T1=tspan[end]/10;
    for t=tspan
        if (t>T1) & (t < T1+3)
            I=7.04;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV, "(I) spike latency")
    plot!([0,T1,T1,T1 + 3,T1+3,tspan[end]],-90.0 .+[0,0,10,10,0,0])
end


#(J) subthresh. osc.
function izh_j()
    a=0.05; b=0.26; c=-60;  d=0;
    V=-62;  u=b*V;
    VV=[];  uu=[];
    tau = 0.25; tspan = 0:tau:200;
    T1=tspan[end]/10;
    for t=tspan
        if (t>T1) & (t < T1+5)
            I=2;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
```

```
            else
                push!(VV,V);
            end;
            push!(uu,u);
        end;
        plot_ts(tspan,VV,"(J) subthreshold osc.")
        plot!([0,T1,T1,T1+5,T1+5,tspan[end]],-90.0 .+[0,0,10,10,0,0])
        plot!(tspan[220:end],-10 .+ 20*(VV[220:end] .- mean(VV)));
    end


    #(K) resonator
    function izh_k()
        a=0.1;  b=0.26; c=-60;  d=-1;
        V=-62;  u=b*V;
        VV=[];  uu=[];
        tau = 0.25; tspan = 0:tau:400;
        T1=tspan[end]/10;
        T2=T1+20;
        T3 = 0.7*tspan[end];
        T4 = T3+40;
        for t=tspan
            if ((t>T1) & (t < T1+4)) || ((t>T2) & (t < T2+4)) || ((t>T3) & (t
< T3+4)) || ((t>T4) & (t < T4+4))
                I=0.65;
            else
                I=0;
            end;
            V = V + tau*(0.04*V^2+5*V+140-u+I);
            u = u + tau*a*(b*V-u);
            if V > 30
                push!(VV,30);
                V = c;
                u = u + d;
            else
                push!(VV,V);
            end;
            push!(uu,u);
        end;
        plot_ts(tspan,VV, "(K) resonator")
        plot!([0,T1,T1,(T1+8),(T1+8),T2,T2,(T2+8),(T2+8),T3,T3,(T3+8),
(T3+8),T4,T4,(T4+8),(T4+8),tspan[end]],-90.0 .
+[0,0,10,10,0,0,10,10,0,0,10,10,0,0,10,10,0,0]);
    end


    # (L) integrator
    function izh_l()
```

```
        a=0.02; b=-0.1; c=-55; d=6;
        V=-60; u=b*V;
        VV=[];  uu=[];
        tau = 0.25; tspan = 0:tau:100;
        T1=tspan[end]/11;
        T2=T1+5;
        T3 = 0.7*tspan[end];
        T4 = T3+10;
        for t=tspan
            if ((t>T1) & (t < T1+2)) | ((t>T2) & (t < T2+2)) | ((t>T3) & (t <
T3+2)) | ((t>T4) & (t < T4+2))
                I=9;
            else
                I=0;
            end;
            V = V + tau*(0.04*V^2+4.1*V+108-u+I);
            u = u + tau*a*(b*V-u);
            if V > 30
                push!(VV,30);
                V = c;
                u = u + d;
            else
                push!(VV,V);
            end;
            push!(uu,u);
        end;
        plot_ts(tspan,VV, "(L) integrator")
        plot!([0,T1,T1,(T1+2),(T1+2),T2,T2,(T2+2),(T2+2),T3,T3,(T3+2),
(T3+2),T4,T4,(T4+2),(T4+2),tspan[end]],-90.0 .
+[0,0,10,10,0,0,10,10,0,0,10,10,0,0,10,10,0,0]);
    end


    #(M) rebound spike
    function izh_m()
        a=0.03; b=0.25; c=-60;  d=4;
        V=-64;  u=b*V;
        VV=[];  uu=[];
        tau = 0.2;  tspan = 0:tau:200;
        T1=20;
        for t=tspan
            if (t>T1) & (t < T1+5)
                I=-15;
            else
                I=0;
            end;
            V = V + tau*(0.04*V^2+5*V+140-u+I);
            u = u + tau*a*(b*V-u);
```

```
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV,"(M) rebound spike")
    plot!([0,T1,T1,(T1+5),(T1+5),tspan[end]], -85.0 .+ [0,0,-5,-5,0,0]);
end


#(N) rebound burst
function izh_n()
    a=0.03; b=0.25; c=-52;  d=0;
    V=-64;  u=b*V;
    VV=[];  uu=[];
    tau = 0.2;  tspan = 0:tau:200;
    T1=20;
    for t=tspan
        if (t>T1) & (t < T1+5)
            I=-15;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV,"(N) rebound burst")
    plot!([0,T1,T1,(T1+5),(T1+5),tspan[end]],-85.0 .+ [0,0,-5,-5,0,0]);
end


#(O) thresh. variability
function izh_o()
    a=0.03; b=0.25; c=-60;  d=4;
    V=-64;  u=b*V;
    VV=[];  uu=[];
```

```
    tau = 0.25; tspan = 0:tau:100;
    for t=tspan
        if ((t>10) & (t < 15)) | ((t>80) & (t < 85))
            I=1;
        elseif (t>70) & (t < 75)
            I=-6;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV, "(O) thresh. variability")
    plot!([0,10,10,15,15,70,70,75,75,80,80,85,85,tspan[end]],
            -85.0 .+ [0,0,5,5,0,0,-5,-5,0,0,5,5,0,0]);
end


#(P) bistability
function izh_p()
    a=0.1;  b=0.26; c=-60;  d=0;
    V=-61;  u=b*V;
    VV=[];  uu=[];
    tau = 0.25; tspan = 0:tau:300;
    T1=tspan[end]/8;
    T2 = 216;
    for t=tspan
        if ((t>T1) & (t < T1+5)) || ((t>T2) & (t < T2+5))
            I=1.24;
        else
            I=0.24;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
```

```
            end;
            push!(uu,u);
        end;
        plot_ts(tspan,VV, "(P) bistability")

        plot!([0,T1,T1,(T1+5),(T1+5),T2,T2,(T2+5),(T2+5),tspan[end]],-90.0 .
+[0,0,10,10,0,0,10,10,0,0]);
    end


    # (Q) DAP
    function izh_q()
        a=1;  b=0.2; c=-60;  d=-21;
        V=-70;  u=b*V;
        VV=[];  uu=[];
        tau = 0.1; tspan = 0:tau:50;
        T1 = 10;
        for t=tspan
            if abs(t-T1)<1
                I=20;
            else
                I=0;
            end;
            V = V + tau*(0.04*V^2+5*V+140-u+I);
            u = u + tau*a*(b*V-u);
            if V > 30
                push!(VV,30);
                V = c;
                u = u + d;
            else
                push!(VV,V);
            end;
            push!(uu,u);
        end;
        plot_ts(tspan,VV,         "(Q) DAP         ")
        plot!([0,T1-1,T1-1,T1+1,T1+1,tspan[end]],-90.0 .+[0,0,10,10,0,0]);
    end


    #(R) accomodation
    function izh_r()
        a=0.02;  b=1; c=-55;  d=4;
        V=-65;  u=-16;
        VV=[];  uu=[];  II=[];
        tau = 0.5; tspan = 0:tau:400;
        for t=tspan
            if (t < 200)
                I=t/25;
```

```
        elseif t < 300
            I=0;
        elseif t < 312.5
            I=(t-300)/12.5*4;
        else
            I=0;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*(V+65));
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
        push!(II,I);
    end;
    plot_ts(tspan,VV, "(R) accomodation")
    plot!(tspan,II*1.5 .- 90.0);
end


# (S) inhibition induced spiking
function izh_s()
    a=-0.02;  b=-1; c=-60;  d=8;
    V=-63.8;  u=b*V;
    VV=[];  uu=[];
    tau = 0.5; tspan = 0:tau:350;
    for t=tspan
        if (t < 50) || (t>250)
            I=80;
        else
            I=75;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV,  "(S) inh. induced sp.")
```

```
    plot!([0,50,50,250,250,tspan[end]], -80.0 .+ [0,0,-10,-10,0,0]);
end


# (T) inhibition induced bursting
function izh_t()
    a=-0.026;  b=-1; c=-45;  d=-2;
    V=-63.8;  u=b*V;
    VV=[];  uu=[];
    tau = 0.5; tspan = 0:tau:350;
    for t=tspan
        if (t < 50) || (t>250)
            I=80;
        else
            I=75;
        end;
        V = V + tau*(0.04*V^2+5*V+140-u+I);
        u = u + tau*a*(b*V-u);
        if V > 30
            push!(VV,30);
            V = c;
            u = u + d;
        else
            push!(VV,V);
        end;
        push!(uu,u);
    end;
    plot_ts(tspan,VV,"(T) inh. induced brst.")
    plot!([0,50,50,250,250,tspan[end]],
            -80.0 .+ [0,0,-10,-10,0,0]);
end


p_a = izh_a();
p_b = izh_b();
p_c = izh_c();
p_d = izh_d();

p_e = izh_e()
p_f = izh_f()
p_g = izh_g()
p_h = izh_h()

p_i = izh_i()
p_j = izh_j()
p_k = izh_k()
p_l = izh_l()
```

```
    p_m = izh_m()
    p_n = izh_n()
    p_o = izh_o()
    p_p = izh_p()

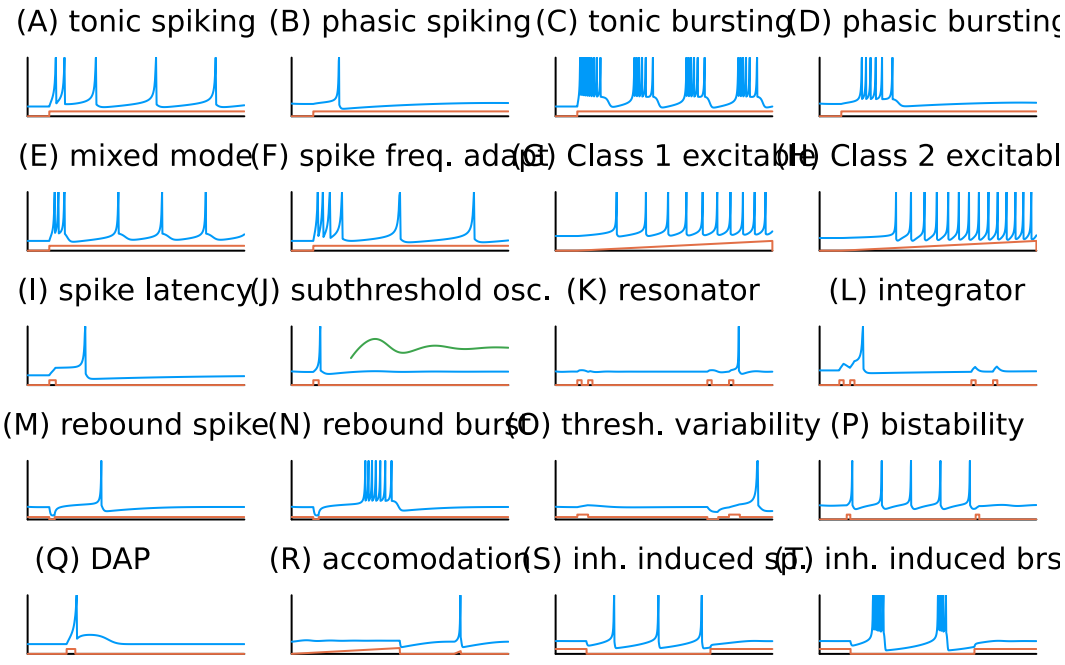
    p_q = izh_q()
    p_r = izh_r()
    p_s = izh_s()
    p_t = izh_t()


    l = @layout [a b c d; e f g h; i j k l; m n o p; q r s t]

    plot(p_a, p_b, p_c, p_d,
         p_e, p_f, p_g, p_h,
         p_i, p_j, p_k, p_l,
         p_m, p_n, p_o, p_p,
         p_q, p_r, p_s, p_t,
         layout = l)

    #set(gcf,'Units','normalized','Position',[0.3 0.1 0.6 0.8]);

end
```



6 Coupling two neurons

6.1 Winner-take-all (WTA) network.

Eqn 6.18 from Wilson (1999). Couple two neurons that inhibit each other.

$\tau \frac{dE_1}{dt} = -E_1 + S(K_1 - 3E_2)$

$\tau \frac{dE_2}{dt} = -E_2 + S(K_2 - 3E_1)$

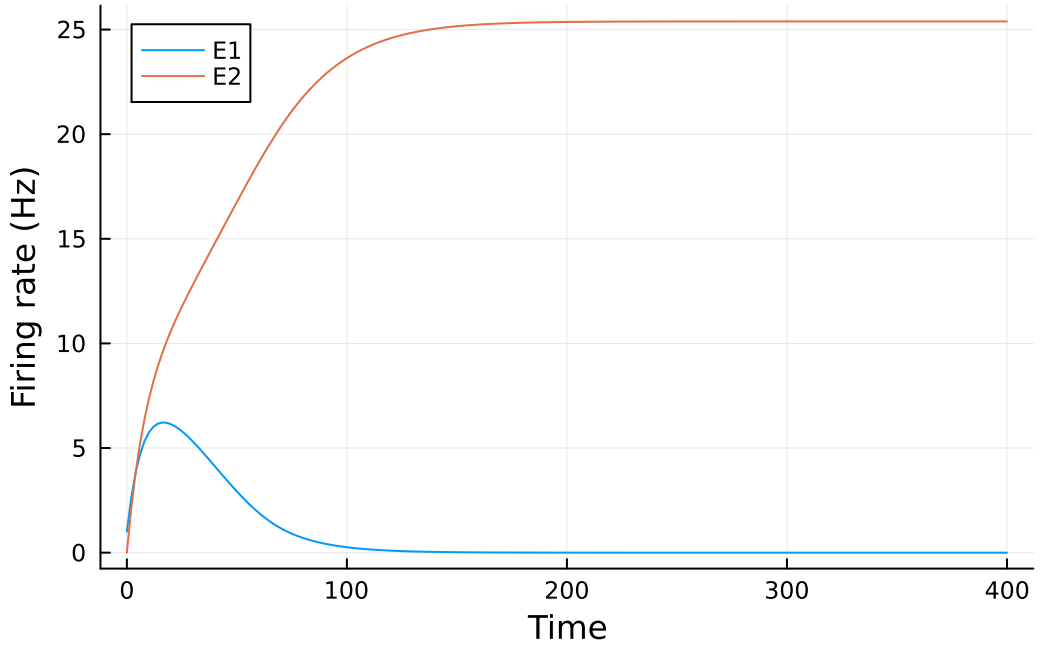
$S(x) = \left[100(x^2)/(120^2 + x^2)\right]_+$

We will first run WTA2 with input to neuron 1 = 60 and input to neuron 2 = 70. We will examine the phase plane.

```
function WTA2(k1, k2)
    Total_Equations = 2;  #Solve for this number of interacting Neurons
    DT = 2;  #Time increment as fraction of time constant
    Final_Time = 400;   #Final time value for calculation
    Last = (Int)(Final_Time/DT + 1);  #Last time step
    Time = DT*collect(0:Last-1);  #Time vector
    Tau = 20;  #Neural time constants in msec
    WTS = [1 2 2 1];  #Runge-Kutta Coefficient weights
    X = zeros(Total_Equations, Int(Last))
    K = zeros(Total_Equations, length(WTS))
    Weights = repeat(WTS, 2,1)
    X[1,1] = 1.0; X[2,1] = 0.0;
    Wt2 = [0 .5 .5 1];  #Second set of RK weights
    rkIndex = [1 1 2 3];
    K1= k1; K2=k2
    S(x) = x>0 ? 100x^2 / (120^2 +x^2) : 0
    K = zeros(2,length(rkIndex))
    for T = 2:Last
        for rk = 1:4  #Fourth Order Runge-Kutta
            XH = X[:, T-1] + K[:, rkIndex[rk]] *Wt2[rk];
            Tme = Time[T-1] + Wt2[rk]*DT;  #Time upgrade
            PSP1 = (K1 - 3*XH[2])*(XH[2] < K1/3);
            PSP2 = (K2 - 3*XH[1])*(XH[1] < K2/3);
            K[1, rk] = DT/Tau*(-XH[1] + S(PSP1))
            K[2, rk] = DT/Tau*(-XH[2] + S(PSP2))
        end
        newx = X[:, T-1] + sum((Weights.*K)',dims=1)'/6
        X[:, T] = newx
    end
    Time, X
end
```

```
WTA2 (generic function with 1 method)
```

```
time, res = WTA2(60.0, 70.0)
plot(time, res', label=["E1" "E2"], xlabel = "Time", ylabel="Firing rate
(Hz)")
```



6.1.a Exercises

1. When the input to both cells is equal, what is the critical value when one neurons dominates? Start with input to both cells equal to 20.
2. Examine what happens when input to both neurons is 100. Run it several times and see which one wins. Can you explain (and then test) your result?

6.2 Coupling inhibitory neurons, part II.

Wilson (Chapter 12) shows how pairs of neurons coupled with reciprocal inhibition can generate out-of-phase firing (not WTA).

Try IPSP.jl with $I_1 = 1.1, I_2 = 1.0, k = 5$. We should see out-of-phase spiking.

6.2.a Exercises

1. Set TauSyn to 2 ms (rather than 1 ms) and repeat with above parameters. What do you observe?
2. As above, but with $I_1 = 1.05$; now what happens?

```
function IPSPinteractions(Stim1, Stim2, ES, TauSyn)
    ## e.g. 1, 2, 4, 1.27
    Total_Neurons = 8;  #Solve for this number of interacting Neurons
    DT = 0.02;  #Time increment as fraction of time constant
```

```
    Final_Time = 100;   #Final time value for calculation
    Last = Int64(Final_Time/DT + 1);  #Last time step
    Time = DT*(0:Last-1);  #Time vector
    Tau = 1.0;  #Neural time constants in msec
    TauR = 5.6
    WTS = [1 2 2 1];  #Runge-Kutta Coefficient weights

    # Predefine X, K and WTS for speed
    X = zeros(Total_Neurons, Last)
    K = zeros(Total_Neurons, 4)
    Weights = zeros(Total_Neurons, 4)

    for NU = 1:Total_Neurons;  #Initialize
        Weights[NU, :] = WTS;  #Make into matrix for efficiency in main loop
    end
    X[1, 1] = -0.754;  #Initial conditions here if different from zero
    X[2, 1] = 0.279;  #Initial conditions here if different from zero
    X[3, 1] = -0.754;  #Initial conditions here if different from zero
    X[4, 1] = 0.279;  #Initial conditions here if different from zero
    Wt2 = [0 .5 .5 1];  #Second set of RK weights
    rkIndex = [1 1 2 3]
    #Stim1 = 1#input("Stimulating current strength, neuron 1 (red) (0-2): ")
    #Stim2 = 2#input("Stimulating current strength, neuron 2 (blue) (0-2): ")
    #ES = 4#input("Inhibitory synaptic conductance factor (0-6): ")

    #**********
    #TauSyn = 1.27;  #IPSP time constant
    #**********

    SynThresh = -0.2;  #Threshold for IPSP conductance change

    ST = 10.6
    for T = 2:Last
      for rk = 1:4  #Fourth Order Runge-Kutta
        XH = X[:, T-1] + K[:, rkIndex[rk]]*Wt2[rk]
        Tme =Time[T-1] + Wt2[rk]*DT;  #Time upgrade

        K[1, rk] = DT/Tau*(-(17.81 + 47.58*XH[1] + 33.8*XH[1]^2)*(XH[1] -
0.48) - 26*XH[2]*(XH[1] + 0.95) + Stim1 - ES*XH[7]*(XH[1] + 0.92));
        K[2, rk] = DT/TauR*(-XH[2] + 1.29*XH[1] + 0.79 + 3.3*(XH[1] + 0.38)^2)
        K[5, rk] = DT/TauSyn*(-XH[5] + (XH[3] > SynThresh))
        K[7, rk] = DT/TauSyn*(-XH[7] + XH[5])

        K[3, rk] = DT/Tau*(-(17.81 + 47.58*XH[3] + 33.8*XH[3]^2)*(XH[3] -
0.48) - 26*XH[4]*(XH[3] + 0.95)+ Stim2 - ES*XH[8]*(XH[3] + 0.92));
        K[4, rk] = DT/TauR*(-XH[4]+ 1.29*XH[3] + 0.79 + 3.3*(XH[3] + 0.38)^2)
        K[6, rk] = DT/TauSyn*(-XH[6] + (XH[1] > SynThresh))
        K[8, rk] = DT/TauSyn*(-XH[8] + XH[6])
```

```
     end
        X[:, T] = X[:, T-1] + sum((Weights.*K)', dims=1)'/6
    end
    Time, X
end
```

```
IPSPinteractions (generic function with 1 method)
```

```
time1, X = IPSPinteractions(1.0, 1.1, 5.0, 2.0)
plot(time1, X[ [1, 3], :]', label=["E1" "E3"], legend=:topleft)
```