C++ Functions in Maxliklib Library

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Abstract

The functions in the maxliklib repository are described. Arguments and their definitions are specified, and dependencies of functions are stated.

Keywords: Maximization procedures, quadrature procedures, maximum likelihood

The maxliklib repository consists of C++ functions helpful in estimation related to maximum likelihood. The functions should be appropriate for C++14. They rely on the Armadillo library (Sanderson & Curtin, 2016, 2018) at http://arma.sourceforge.net, the StatsLib library at https://www.kthohr.com/statslib.html, and the Boost library at https://www.boost.org. Unless otherwise noted, for the library members considered, it is assumed that users have verified that function arguments are valid. Namespaces assumed where relevant are std, arma, and boost::math. The following functions are found in the library, with files in the source code with the suffix .cpp.

- addsel
- berresp
- conjgrad
- contresp
- cumresp
- CX
- \bullet eaps

- fitquad
- genfact
- \bullet genprods
- genresp
- genresplik
- genrespmle
- gpcm
- gradascent
- gradresp
- gumbell
- \bullet gumbelu
- hermcoeff
- hermpoly
- hermpw
- intsel
- invcdf
- irtm
- \bullet irtmle
- irtms
- \bullet irtmsave
- irtmsaves
- ivecsel
- linsel
- \bullet loggamma
- logistic

- logit
- logitbeta
- logitdirichlet
- loglogl
- loglogu
- logmean
- lw
- lwm
- maxberresp
- maxf2vvar
- \bullet maxlinq2
- \bullet maxquad
- maxselect
- \bullet multlogit
- modit
- normal
- normalv
- nrv
- oneparamirt
- pack
- pcm
- posterior
- posteriors
- probit
- qnormpwe

• ranklogit

• rebound • regprod • regprodf • savmaxf2v • sintsel • sivecsel • startoneparamirt • startgpcm • startpcm • starttwoparamirt • svecsel • truncresp • twoparamirt • unpack vecsel • wmc

Distributions of Sums of Independent Multinomial Variables

The functions in this section implement a modified and generalized version of the Lord-Wingersky algorithm (Lord & Wingersky, 1984; Thissen et al., 1995). The numerical procedures and their rationale are discussed in lw.pdf.

lw

The function lw finds the probability mass function of the sum S of mutually independent Bernoulli random variables X_j , $0 \le j < n$. The function declaration is

vec lw(const double & c, const vec & p).

In the function definition, c is a constant c, and p is an n-dimensional vector \mathbf{p} . The vector \mathbf{p} with elements p_j , $0 < p_j < 1$, has dimension n. For $0 \le j < n$, p_j is the probability that $X_j = 1$. The variable c is normally a small positive number used as in lw.pdf to remove very small probabilities from consideration in order to speed computation. If c is not positive, then the modified Lord-Wingersky algorithm used by lw reduces to the conventional algorithm. The probability mass function is provided by lw, a vector with n+1 elements. For $0 \le k \le n$, element k of lw is the probability P(S=k) that S=k.

lwm

The function lwm finds the probability mass function of the sum S of n mutually independent random variables X_j , $0 \le j < n$ with integer values from 0 to $I_j - 1$ for an integer $I_j > 1$. The function declaration is

vec lwm(const double & c, const field < vec > & p).

Here p has n vector members \mathbf{p}_j , $0 \le j < n$. For each j, \mathbf{p}_j has positive elements p_{ij} , $0 \le i < I_j$, that sum to 1. The probability $P(X_j = i)$ is p_{ij} . The vector lwm has K+1 elements, where $K = \sum_{j=1}^{n} (I_j - 1)$ and P(S = k) is element k of lwm for $0 \le k < K$. The definition of c is the same as in lw.

Tools for Line Searches

The functions in this section facilitate line searches during function maximization. Throughout discussions in this section and in Functions related to the Newton-Raphson algorithm and Functions Related to Gradient Methods, the theoretical background and the definitions of η , γ_1 , γ_2 , and κ are found in convergence.pdf. For some positive integer p and nonempty open convex set O of p-dimensional vectors, a continuously differentiable real function f on O is to be maximized by an iterative algorithm with a starting value in O. It is assumed that, for some real a, the set A of members of O at which f is at least a is closed and bounded, and the set A_0 of members of O at which f exceeds a is nonempty. The function f is assumed to be strictly pseudoconcave on A_0 . The starting values for algorithms are assumed to be in A_0 . The convention is adopted that $f(\mathbf{x}) = -\infty$ if \mathbf{x} is not in O.

maxlinq2

The function maxlinq2 provides a line search for maximization algorithms. Only function values and gradients are used when order is 1, but Hessian matrices or their approximations are computed if order is greater than 1. The function declaration is

 $\max f2v \max linq2(const int \& order, const params \& mparams, const vec \& v, const \max f2v \& vary0, const function < f2v(const int \&, const vec \&) > f).$

Here the definition of maxf2v is

struct maxf2v{vec locmax; double max; vec grad, mat hess;};,

For a vector \mathbf{y} , the corresponding definitions of maxf2v are maxf2v.locmax equals \mathbf{y} , maxf2v.max equals $f(\mathbf{y})$, maxf2v.grad equals the gradient $\nabla f(\mathbf{y})$ of f at \mathbf{y} , and, for order greater than 1, maxf2v.hess equals the Hessian matrix $\nabla^2 f(\mathbf{y})$ of f at \mathbf{y} . The corresponding definition of f2v is

struct f2v{double value; vec grad; vec hess};,

where, for the vector \mathbf{y} , f2v.value is $f(\mathbf{y})$, f2v.grad is $\nabla f(\mathbf{y})$, and, for order greater than 1, f.hess is $\nabla^2 f(\mathbf{y})$. In the arguments of maxlinq2, vary0.locmax is the starting vector \mathbf{x} for the line search, the search direction is \mathbf{v} , and f is the function f together with its gradient and, for order greater than 1, its Hessian matrix. Maximization details are defined by mparams, where the definition of params is

struct params{bool print; int maxit; int maxits; double eta; double gamma1; double gamma2; double kappa; double tol;}.

Here mparams.print is used for output of the iteration number and function value at the end of the iteration, mparams.maxit is the number of primary iterations, mparams.maxits is the maximum number of uses of maxquad permitted for each primary iteration, mparams.eta is η , mparams.gamma1 is γ_1 , mparams.gamma2 is γ_2 , and mparams.kappa is κ . Iterations cease if the function value changes less than mparams.tol after a primary iteration.

In maxlinq2, maxlinq2.locmax is an approximate location $y = \mathbf{x} + \alpha \mathbf{v}$ of the maximum over α of $f(\mathbf{x} + \alpha \mathbf{v})$. The functions maxf2vvar, maxquad, modit, and rebound are all used.

maxquad

The function maxquad finds the location x of the maximum of a quadratic function q on the real line with value $q(x_0)$ and derivative $q_1(x_0)$ at x_0 and value $q(x_1)$ at $x_1 \neq x_0$. It is assumed that $q(x_0) \geq q(x_1)$. For a given s > 0, the function returns x unless $|x - x_0| > s$. If $|x - x_0| > s$ and $q_1(x_0) > 0$, then $x_0 + s$ is returned. If $|x - x_0| > s$ and $q_1(x_0) < 0$, then $x_0 - s$ is returned. The function declaration is

double maxquad(const double & x0, const double & x1, const double & f0, const double & f1, const double & g0, const double & stepmax).

Here x0 is x_0 , x1 is x_1 used, f0 is $q(x_0)$, f1 is $q(x_1)$, g0 is $q_1(x_0)$, and stepmax is s.

modit

The function modit truncates an iteration to conform to limits on step size and bounds in the case of a real function of one variable with a unique critical point and a limit of $-\infty$ as the absolute value of the function argument approaches ∞ . The function declaration is

double modit(const double & eta, const double & alpha0, const double & alpha1, const double & stepmax, const bounds & b),

and the struct bounds is defined as

struct bounds {double lower; double upper;}.

Here eta corresponds to η , alpha0 is the previous location α_0 , alpha1 is the proposed new location α_1 , stepmax is the positive limit s on step size, b.lower is the lower bound $b_L \geq -\infty$, and b.upper is the upper bound $b_U \leq \infty$. It is assumed that $\alpha_0 \neq \alpha_1$ and $b_L \leq \alpha_0 \leq b_U$. If $\alpha_1 > \alpha_0$, then $b_U > \alpha_0$ and the function returns the minimum of α_1 , $\alpha_0 + s$, and $\alpha_0 + \eta(b_U - \alpha_0)$. If $\alpha_1 < \alpha_0$, then $b_L < \alpha_0$ and the function returns the maximum of α_1 , $\alpha_0 - s$, and $\alpha_0 + \eta(b_L - \alpha_0)$.

rebound

The function rebound updates the lower and upper bounds for maximization of a differentiable real function f on the real line with a unique critical point and a limit of $-\infty$ as the absolute value of the function argument approaches ∞ . The function declaration is

bounds rebound(const double & y, const double & der, const bounds & b).

The struct bounds is defined as in modit. Here y is the current location y, der is the function derivative $f_1(y)$ at y, b.lower is the current lower bound L, and b.upper is the current upper bound U. It is assumed that $f_1(y) \neq 0$. If $f_1(y) > 0$, the returned lower bound is y and the returned upper bound is U. If $f_1(y) < 0$, the returned lower bound is L and the returned upper bound is y.

Functions related to the Newton-Raphson algorithm

In this section, functions are discussed that are related to the Newton-Raphson algorithm. It should be noted that references to function values, gradients, and Hessian matrices do not address computational methods. In fact, the function values, gradients, and Hessian matrices employed may be approximations derived by numerical differentiation or large-sample approximations. In this section, f is assumed to be twice continuously differentiable.

maxf2vvar

The function maxf2vvar is used to combine information on a location and on a function's value, gradient, and Hessian matrix at the location. The function maxf2vvar has declaration

maxf2v maxf2vvar(const int & order, const vec & y, const f2v & fy);.

The structs f2v and maxf2v are defined as in maxlinq2. At the vector \mathbf{y} , fy.value is $f(\mathbf{y})$, fy.grad is $\nabla f(\mathbf{y})$ if order is positive, and fy.hess is $\nabla^2 f(\mathbf{y})$ if order is greater than 1. The returned value maxf2vvar.locmax is \mathbf{y} , while maxf2vvar.max is $f(\mathbf{y})$, maxf2var.grad is $\nabla f(\mathbf{y})$ if order is positive, and maxf2var.hess is $\nabla^2 f(\mathbf{y})$ if order is greater than 1.

\mathbf{nrv}

The function nrv applies a modified version of the Newton-Raphson algorithm to maximization of the function f. The function nrv has declaration

 $\max f2v \text{ nrv}(\text{const int \& order, const params \& mparams, const vec \& start, const function} < f2v(\text{const int \&, vec \&}) > f).$

The structs f2v, maxf2v, and params are defined as in maxlinq2. The algorithm is found in convergence.pdf. The starting vector \mathbf{y}_0 must be in O. The function returns the approximation \mathbf{y} for the location of the maximum, together with $f(\mathbf{y})$, $\nabla f(\mathbf{y})$ and $\nabla^2 f(\mathbf{y})$.

The function nrv uses maxf2vvar, maxlinq2, maxquad, modit, and rebound. The value of order should be at least 2. The starting vector is start, and the function, gradient, and Hessian matrix are provided in f.

savmaxf2v

The function savmaxf2v is used to save basic results of maximization. The declaration is

void sav \max f2v(const int & order , const \max f2v & vlm, const string & out, const bool & fflag, const bool & pflag).

The value of order is 1, 2, or 3. The struct maxf2v is defined as in maxlinq2. If fflag is true, then the output file is defined by out. The output file must be a binary file used by Armadillo for storage. If pflag is true, then standard output is employed. Both fflag and pflag may have the same value. If order is 1, output is vlm.max, vlm.locmax, and vlm.grad. If order exceeds2, then output also includes vlm.hess, the inverse of -1 times vlm.hess, and the square roots of the diagonal elements of this inverse.

Functions Related to Gradient Methods

In this section, functions are considered based on gradient-based methods.

conjgrad

The function conjgrad implements a conjugate gradient algorithm for maximization of the function f. The function declaration is

maxf2v conjgrad(const int & order, const params & mparams, const vec & start, const function $\langle f2v(\text{const int } \& \text{ , const vec } \&) \rangle f)$.

Arguments are defined as *nrv*. The value of *order* must be at least 1. If *order* is at least 2, Hessian matrices are computed even though not used in the algorithm.

The function conjgrad uses maxf2vvar, maxlinq2, maxquad, modit, and rebound.

gradascent

The function gradascent uses a gradient-ascent algorithm for maximization of f. The function declaration for gradascent is

 $\max f2v \text{ gradascent}(\text{const order \& , const params \& mparams, } \text{const vec \& start, const function} < f2v(\text{const int \& , const vec \& }) > f).$

The functions maxf2vvar, maxlinq2, maxquad, modit, and rebound are used. Definitions are as in conjgrad.

maxselect

The function max elect uses either the conjugate-gradient, gradient-ascent, or modified Newton-Raphson algorithm for maximization of f. The function declaration for max elect is

 $\max f2v$ maxselect(const order & , const params & mparams, const char & algorithm const vec & start, const function< f2v(const int & , const vec &)> f).

The functions conjgrad, gradascent, maxf2vvar, maxlinq2, maxquad, modit, nrv, and rebound are used. Definitions are as in conjgrad, except that algorithm is C for conjugate gradient, G for gradient ascent, and N for Newton-Raphson.

Log-likelihood Components

In this section, components of log-likelihood functions are provided. A component has the form $\ell_c(\beta; \mathbf{Y}, A, F, q, r)$. Here the character A defines the type of model component involved, F is a distribution function with a positive and twicecontinuously differential derivative F_1 such that $\log F_1$ has a negative second derivative. The integer q > 0 is the parameter dimension, and the integer r > 0 is the data dimension. The character A is in the set \mathcal{A} with elements B(logit beta), C (cumulative), D (continuous), E (logit Dirichlet), G (graded), H (log gamma), L (multinomial logit), M (maximum of two independent Bernoulli variables), N (multivariate normal), P (log-mean Poisson case), R (rank logit), S (Bernoulli), and T(censored continuous). Distribution functions used in this section are in the set \mathcal{F} with four members, G_L , the standard minimum Gumbel distribution function with value $G_L(y) = 1 - \exp(-\exp(y))$ for y real (Gumbel, 1935), G_U , the standard maximum Gumbel distribution with value $G_U(y) = \exp(-\exp(-y))$ for y real, Ψ , the standard logistic distribution function with value $\Psi(y) = 1/[1 + \exp(-y)]$ for y real, and Φ , the standard normal distribution function with derivative $\Phi_1(y) = \exp(-y^2/2)/(2\pi)^{1/2}$ for real y. The value of F is only relevant in the cumulative, continuous, graded, Bernoulli, and censored continuous cases. The variables M, F, q, and r then define an open convex subset O(A, F, q, r) of q-dimensional vectors and a set $\mathcal{Y}(A, F, q, r)$ of r-dimensional vectors. The vector $\boldsymbol{\beta}$ is in O(A, F, q, r), and \mathbf{Y} is in $\mathcal{Y}(A, F, q, r)$.

To treat both continuous and discrete log-likelihood components, the integral symbol \int is used in the following sense. Consider a real function g on a nonempty finite-dimensional set C. If C is convex and has a nonempty interior and g is integrable, then f(g) denotes the integral of g over C. If C is finite or countably infinite and g is summable, then f(g) is the sum of f(g) over f(g) over f(g) in f(g) that are either convex sets with nonempty interior or finite or countably-infinite sets. Let f(g) be defined for f(g) and let f(g) denotes the restriction of f(g) to f(g) is the sum of f(g) over f(g) over f(g) in f(g) over

D in \mathcal{D} . Similar conventions apply if g is vector-valued or matrix-valued. The requirement is imposed here that, for $\boldsymbol{\beta}$ in O(A,F,q,r), $\int (\exp(\ell_c(\boldsymbol{\beta};\cdot,A,F,q,r))) = 1$. Here $\exp(\ell_c(\boldsymbol{\beta};\cdot,A,F,q,r))$ is the function on $\mathcal{Y}(A,F,q,r)$ equal to $\exp(\ell_c(\boldsymbol{\beta};\mathbf{y},A,F,q,r))$ if \mathbf{y} is in $\mathcal{Y}(A,F,q,r)$. The gradient function of $\ell_c(\cdot;\mathbf{y},A,F,q,r)$ is $\nabla \ell_c(\cdot;\mathbf{y},A,F,q,r)$ and the corresponding Hessian matrix is $\nabla^2 \ell_c(\cdot;\mathbf{y},A,F,q,r)$.

For a positive integer n and an observation i, $0 \le i < n$, positive integers q_i and r_i and character variables A_i in \mathcal{A} and F_i in \mathcal{F} are given. The component of the log likelihood for observation i involves the predicted random vector \mathbf{Y}_i in $\mathcal{Y}(A_i, F_i, q_i, r_i)$, the q_i by p predicting matrix \mathbf{X}_i in a nonempty set \mathcal{X}_i , the q_i -dimensional vector \mathbf{o}_i , and the positive real weight w_i . If $\boldsymbol{\beta}$ is in O, then let $\boldsymbol{\lambda}_i(\boldsymbol{\beta}) = \mathbf{o}_i + \mathbf{X}_i \boldsymbol{\beta}$ be in $O(A_i, F_i, q_i, r_i)$ for $0 \le i < n$, and let the log-likelihood function under study have the form

$$\ell(\boldsymbol{\beta}) = \sum_{i=0}^{n-1} w_i \ell_c(\boldsymbol{\lambda}_i(\boldsymbol{\beta}); \mathbf{Y}_i, A_i, F_i, q_i, r_i).$$
 (1)

It follows that the gradient of ℓ at β in O is

$$\nabla \ell(\boldsymbol{\beta}) = \sum_{i=0}^{n-1} w_i \mathbf{X}_i^T \nabla \ell_c(\boldsymbol{\lambda}_i(\boldsymbol{\beta}); \mathbf{Y}_i, A_i, F_i, q_i, r_i),$$
 (2)

and the Hessian matrix of ℓ at β is

$$\nabla^2 \ell(\boldsymbol{\beta}) = \sum_{i=0}^{n-1} w_i \mathbf{X}_i^T \nabla^2 \ell_c(\boldsymbol{\lambda}_i(\boldsymbol{\beta}); \mathbf{Y}_i, A_i, F_i, q_i, r_i) \mathbf{X}_i.$$
 (3)

The Hessian matrix $\nabla^2 \ell(\beta)$ has the approximation

$$\tilde{\nabla}^2 \ell(\boldsymbol{\beta}) = -\sum_{i=0}^{n-1} w_i \mathbf{X}_i^T \nabla \ell_c(\boldsymbol{\lambda}_i(\boldsymbol{\beta}); \mathbf{Y}_i, A_i, F_i, q_i, r_i) [\nabla \ell_i(\boldsymbol{\lambda}_i(\boldsymbol{\beta}); \mathbf{Y}_i, A_i, F_i, q_i)]^T \mathbf{X}_i \quad (4)$$

(Haberman, 2013; Louis, 1982).

The functions $\ell_c(\cdot; \mathbf{y}, A, F, q, r)$ used are considered in this section. Some are examined in the literature on survival analysis (Cox, 1972; Kalbfleisch & Prentice, 2002), generalized linear models (McCullagh & Nelder, 1989), multivariate analysis (Anderson, 2003), and discrete choice (McFadden, 1973). It should be noted that names for models are somewhat variable in different references, especially for graded and cumulative cases. In addition, graded and cumulative cases are defined to be consistent with the Bernoulli cases. The following C++ functions are employed for common examples. The structs f2v are defined as in maxlinq2. If the argument beta is not in O, then all values returned equal $-\infty$. It is assumed that the user of the function has verified that the input vector y is in \mathcal{Y}_i . In the cases under study in this section, unless otherwise stated, the components are strictly concave, so that ℓ is strictly concave whenever \mathbf{X}_i , $0 \leq i < n$, spans a space of dimension p. Conditions for a unique $\hat{\boldsymbol{\beta}}$ in O such that $\ell(\hat{\boldsymbol{\beta}})$ equals the supremum of ℓ over O are relatively

complex (Haberman, 1974, 1977, 1980). It is worth noting that in cases in which $\hat{\boldsymbol{\beta}}$ in O satisfies the conditions that $\nabla \ell(\hat{\boldsymbol{\beta}})$ is the p-dimensional vector $\mathbf{0}_p$ with all elements 0 and $\nabla^2 \ell(\hat{\boldsymbol{\beta}})$ is negative definite, then O can be restricted to ensure that ℓ is strictly concave on O and $\hat{\boldsymbol{\beta}}$ is the only member of O such that $\ell(\hat{\boldsymbol{\beta}})$ equals the supremum of ℓ on O and, for $\boldsymbol{\beta}$ in O, $\nabla \ell(\boldsymbol{\beta})$ is the unique vector with all elements 0 if $\boldsymbol{\beta}$ equals $\hat{\boldsymbol{\beta}}$. In all component functions, order is less than 1 if only the component value is computed, 1 if the component value and gradient are found, and greater than 1 if the component value, gradient, and Hessian are found. If order exceeds 2, the approximation of the Hessian by Equation 4 is employed. Repeated use is made of the struct resp with ivec component iresp and vec component dresp. In typical cases, resp.dresp or resp.iresp has no elements; however, exceptions do exist.

berresp

The function berresp is used to handle standard models for Bernoulli random variables. Here q = r = 1, A is S, $\mathcal{Y}(A, F, q, r)$ is the set of one-dimensional vectors \mathbf{y} with element y_0 equal 0 or 1, and O(A, F, q, r) is the set of all one-dimensional vectors, and F is in \mathcal{F} . For \mathbf{y} in $\mathcal{Y}(A, F, q, r)$ and $\boldsymbol{\beta}$ in O(A, F, q, r) with element β_0 ,

$$\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r) = \begin{cases} \log(F(\beta_0), & y_0 = 1, \\ \log(1 - F(\beta_0)), & y_0 = 0. \end{cases}$$
 (5)

The function declaration is

f2v berresp(const int & order, const char & transform, const resp & y, const vec & beta).

If transform is G, then $F = G_L$. If transform is H, then $F = G_U$. If transform is L, then $F = \Psi$. If transform is N, then $F = \Phi$. The function berresp.value is $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ if y.iresp is \mathbf{y} and beta is $\boldsymbol{\beta}$.

The function berresp requires loglogl, loglogu, logit, and probit.

contresp

The function contresp computes the function value, gradient, and Hessian matrix associated with the distribution of a location and scale model for a continuous random vector. Here r = 1, q = 2, A is D, $\mathcal{Y}(A, F, q, r)$ is the set of all one-dimensional vectors, O(A, F, q, r) is the set of all two-dimensional vectors $\boldsymbol{\beta}$ with element $\beta_1 > 0$, and F is in \mathcal{F} . For \mathbf{y} in $\mathcal{Y}(A, F, q, r)$ and $\boldsymbol{\beta}$ in O(A, F, q, r),

$$\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r) = \log(\beta_1) + \log(F_1(\beta_0 + \beta_1 y_0)). \tag{6}$$

These cases correspond to a model that a random variable Y has a distribution function $F(\beta_0 + \beta_1 y)$, where F is the distribution function of a random variable Z. Here $\ell_c(\cdot; \mathbf{y}, A, F, q, r)$ is concave, and the function is strictly concave if y_0 is not 0.

For all cases, the function declaration is

f2v contresp(const int & order, const char & transform, const resp & y, const vec & beta).

The variable transform is defined as in berresp. The function contresp value is $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ if y.dresp is \mathbf{y} and beta is $\boldsymbol{\beta}$. The function contresp requires gumbell, gumbell, logistic, and normal.

cumresp

The function cumresp computes the function value, gradient, and Hessian matrix associated with a cumulative response transformation. Here r = 1, $q \ge 1$, A is C, F is in \mathcal{F} , $\mathcal{Y}(A, F, q, r)$ is the set of one-dimensional vectors \mathbf{y} such that y_0 is a nonnegative integer no greater than q, O(A, F, q, r) is the set of all vectors of dimension q, and F is defined as in berresp. For $\boldsymbol{\beta}$ in O(A, F, q, r) and \mathbf{y} in $\mathcal{Y}(A, F, q, r)$, if $y_0 = k$, then

$$\ell_{i}(\boldsymbol{\beta}; \mathbf{y}) = \begin{cases} \log(1 - F(\beta_{0}), & k = 0, \\ \log(1 - F(\beta_{k})) + \sum_{j=0}^{k-1} \log(F(\beta_{j})), & 0 < k < q, \\ \sum_{j=0}^{q-1} \log(F(\beta_{j})), & k = q. \end{cases}$$
(7)

The function declaration is

f2v cumresp(const int & order, const char & transform, const resp & y, const vec & beta).

Here transform is defined as in berresp. The function cumresp.value is $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ if y.iresp is \mathbf{y} and beta is $\boldsymbol{\beta}$. The function cumresp requires berresp, loglogl, loglogu, logit, and probit. If r = 1, then use of cumresp is equivalent to use of berresp. In general, $\ell_c(\cdot; \mathbf{y}, A, F, q, r)$ is concave. Strict concavity holds if $q - y_0$ does not exceed 1.

gradresp

The function gradresp computes the function value, gradient, and Hessian matrix associated with a graded response transformation. Then r = 1, $q \ge 1$, A is G, F is in \mathcal{F} , O(A, F, q, r) is the set of all vectors of dimension q with strictly decreasing elements, $\mathcal{Y}(A, F, q, r)$ is the set of one-dimensional vectors \mathbf{y} with y_0 a nonnegative integer no greater than q, and, for $\boldsymbol{\beta}$ in O(A, F, q, r) and \mathbf{y} in $\mathcal{Y}(A, F, q, r)$, if

$$\ell_{i}(\boldsymbol{\beta}; \mathbf{y}) = \begin{cases} \log(1 - F(\beta_{0})), & k = 0, \\ \log(F(\beta_{k-1}) - F(\beta_{k})), & 0 < k < q, \\ \log(F(\beta_{k-1}), & k = q. \end{cases}$$
(8)

The function declaration is

f2v gradresp(const int & order, const char & transform, const resp & y, const vec & beta).

Here transform is defined as in berresp. The function gradresp.value is $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ if y.iresp is \mathbf{y} and beta is $\boldsymbol{\beta}$. If q = 1, then berresp, cumresp and gradresp yield the same result. The function $\ell_c(\cdot; \mathbf{y}, A, F, q, r)$ is concave. Strict concavity only holds if q is 1 or q is 2 and $y_0 = 1$.

gumbell

The function gumbell provides the computations required in contresp for $\ell_c(\cdot; \mathbf{y}, A, F, q, r)$ for the minimum Gumbel case of $F = G_L$, A with value D, q = 2, r = 1, $\mathcal{Y}(A, F, q, r)$ the set of real numbers, and O(A, F, q, r) the set of two-dimensional vectors $\boldsymbol{\beta}$ with $\beta_1 > 0$. The function declaration is

f2v gumbell(const int & order, const resp & y, const vec & beta).

The function gumbell value is then $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ if y dresp is \mathbf{y} and beta is $\boldsymbol{\beta}$.

gumbelu

The function gumbelu provides the computations required in contresp for $\ell_c(\cdot; \mathbf{y}, A, F, q, r)$ for the maximum Gumbel case of $F = G_U$, A with value D, $q = 2, r = 1, \mathcal{Y}(A, F, q, r)$ the set of real numbers, and O(A, F, q, r) the set of two-dimensional vectors $\boldsymbol{\beta}$ with $\beta_1 > 0$. The function declaration is

f2v gumbelu(const int & order, const resp & y, const vec & beta).

The function gumbelu value is then $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ if y dresp is \mathbf{y} and beta is $\boldsymbol{\beta}$.

loggamma

The function loggamma provides the computations required for $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ for the log-gamma distribution with A with value $H, q = 2, r = 1, \mathcal{Y}(A, F, q, r)$ the set of real numbers, and O(A, F, q, r) the set of two-dimensional vectors $\boldsymbol{\beta}$ with positive elements. The function declaration is

f2v loggamma(const int & order, const resp & y, const vec & beta).

The function loggamma. value is then $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ if y.dresp is \mathbf{y} and beta is $\boldsymbol{\beta}$.

logistic

The function logistic provides the computations required in contresp for $\ell_c(\cdot; \mathbf{y}, A, F, q, r)$ for the logistic case $F = \Psi$ in contresp with A with value D, $q = 2, r = 1, \mathcal{Y}(A, F, q, r)$ the set of real numbers, and O(A, F, q, r) the set of two-dimensional vectors $\boldsymbol{\beta}$ with $\beta_1 > 0$. The function declaration is

f2v logistic(const int & order, const resp & y, const vec & beta).

The function logistic value is $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ if y dresp is \mathbf{y} and beta is β .

logit

The function logit computes the function value, gradient, and Hessian matrix associated with the logit case in berresp with A equal to S, $F = \Psi$, and q = r = 1. The function declaration is

f2v logit(const int & order, const resp & y, const vec & beta).

The function logit.value is $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ if y iresp is \mathbf{y} and beta is $\boldsymbol{\beta}$.

logitbeta

The function logitbeta computes the function value, gradient, and Hessian matrix associated with the logit of a beta distribution with a two-dimensional parameter vector $\boldsymbol{\beta}$ with positive elements. Here $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ has A with value $H, q = 2, r = 1, \mathcal{Y}(A, F, q, r)$ the set of real numbers, and O(A, F, q, r) the set of two-dimensional vectors $\boldsymbol{\beta}$ with positive elements. The function declaration is

f2v logitbeta(const int & order, const resp & y, const vec & beta).

The function logitbeta value is $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ if q = 2, r = 1, y iresp is \mathbf{y} , A is B, and beta is $\boldsymbol{\beta}$.

logitdirichlet

The function logitdirichlet computes the function value, gradient, and Hessian matrix associated with the logits of a Dirichlet distribution with a q = r + 1-dimensional parameter vector $\boldsymbol{\beta}$ with positive elements. Here $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ has A with value E, $\mathcal{Y}(A, F, q, r)$ the set of r-dimensional vectors, and O(A, F, q, r) the set of q-dimensional vectors $\boldsymbol{\beta}$ with positive elements. The function declaration is

f2v logitdirichlet(const int & order, const resp & v, const vec & beta).

The function logitdirichlet.value is $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ if y.iresp is \mathbf{y} , beta is $\boldsymbol{\beta}$, and A is E. The q-dimensional random variable \mathbf{u} has a Dirichlet distribution with parameter vector $\boldsymbol{\beta}$ if 1 is the sum of the elements of \mathbf{u} and $y_i = \log(u_i/u_q)$ for integers i from 1 to r. If r = 1, then the logit Dirichlet case reduces to the case of a logit beta.

loglogl

The function loglogl computes the function value, gradient, and Hessian matrix associated with the complementary log-log case of berresp with A equal to S, $F = G_L$, and q = r = 1. The function declaration is

f2v loglogl(const int & order, const resp & y, const vec & beta).

The function loglogl value is $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ if y iresp is \mathbf{y} and beta is $\boldsymbol{\beta}$.

loglogu

The function log log u computes the function value, gradient, and Hessian matrix associated with the log-log case of berresp with A equal to S, $F = G_U$, and q = r = 1. The function declaration is

f2v loglogu(const int & order, const resp & y, const vec & beta).

The function loglogu. value is $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ if y iresp is \mathbf{y} and beta is β .

logmean

The function logmean computes the function value, gradient, and Hessian matrix associated with a log-mean transformation for a Poisson random variable. In this case, q = r = 1, A is P, the value of F in \mathcal{F} is irrelevant, $\mathcal{Y}(A, F, q, r)$ is the set of one-dimensional vectors \mathbf{y} such that y_0 is a nonnegative integer, and O(A, F, Q, R) is the set of all one-dimensional vectors. For $\boldsymbol{\beta}$ in O(A, F, q, r) and \mathbf{y} in $\mathcal{Y}(A, F, q, r)$,

$$\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r) = y_0 \beta_0 - \exp(\beta_0) - \log([y_0]!). \tag{9}$$

The function declaration is

f2v logmean(const int & order, const resp & y, const vec & beta).

The function logmean value is $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ if y iresp is \mathbf{y} and beta is $\boldsymbol{\beta}$.

maxberresp

The function *maxberresp* finds the log likelihood component, gradient, and Hessian matrix for the maximum of two unobserved Bernoulli random variables. Here

q = 2, r = 1, A is M, F is in $\mathcal{F}, O(A, F, q, r)$ is the set of two-dimensional vectors, and $\mathcal{Y}(A, F, q, r)$ is the set of one-dimensional vectors \mathbf{y} with y_0 equal 0 or 1. For y in $\mathcal{Y}(A, F, q, r)$ and $\boldsymbol{\beta}$ in O(A, F, q, r),

$$\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r) = \begin{cases} \log(F(\beta_0) + F(\beta_1) - F(\beta_0)F(\beta_1)), & y_0 = 1, \\ \log(1 - F(\beta_0)) + \log(1 - F(\beta_1)), & y_0 = 0. \end{cases}$$
(10)

It should be noted that

$$F(\beta_0) + F(\beta_1) - F(\beta_0)F(\beta_1) = 1 - [1 - F(\beta_0)][1 - F(\beta_1)] \tag{11}$$

and

$$\log(1 - F(\beta_0)) + \log(1 - F(\beta_1)) = \log([1 - F(\beta_0)][1 - F(\beta_1)]). \tag{12}$$

The function $\ell_c(\cdot; \mathbf{y}, A, F, q, r)$ is not necessarily concave if $y_0 = 1$.

The function declaration is

f2v maxberresp(const int & order, const char & transform, const resp & y, const vec & beta).

The variable transform is defined as in berresp. The function maxberesp.value is $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ if y.iresp is \mathbf{y} and beta is $\boldsymbol{\beta}$. The functions berresp, logit, loglogl, loglogu, and probit are required.

multlogit

The function multlogit computes the function value, gradient, and Hessian matrix associated with a multinomial logit transformation. In this case, r = 1, $q \ge 1$, F is irrelevant, A is L, $\mathcal{Y}(A, F, q, r)$ is the set of one-dimensional vectors \mathbf{y} such that y_0 is a nonnegative integer no greater than q, and O(A, F, q, r) is the set of all q-dimensional vectors. For $\boldsymbol{\beta}$ in O(A, F, q, r) and \mathbf{y} in $\mathcal{Y}(A, F, q, r)$, if $y_0 = k$, then

$$\ell_c(\beta; \mathbf{y}, A, F, q, r) = \begin{cases} -\log\left(1 + \sum_{k=0}^{q-1} \exp(\beta_k), & k = 0, \\ \beta_{k-1} + \ell_c(\beta; \mathbf{0}_1, A, F, q, r), & k > 0. \end{cases}$$
(13)

The function declaration is

f2v multlogit(const int & order, const resp & y, const vec & beta).

The function multlogit.value is $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ if y.iresp is \mathbf{y} and beta is $\boldsymbol{\beta}$. If q = 1, use of multlogit gives the same result as use of logit and as use of berresp, cumresp, or gradresp with transform equal L.

normal

The function normal computes the function value, gradient, and Hessian matrix associated with the normal case in contresp. Thus A is D, $F = \Phi$, q = 2, r = 1, $\mathcal{Y}(A, F, q, r)$ is the space of one-dimensional vectors, and O(A, F, q, r) is the set of two-dimensional vectors $\boldsymbol{\beta}$ with $\beta_1 > 0$. The function declaration is

f2v normal(const int & order, const vec & y, const vec & beta).

The function normal value is $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ if y dresp is \mathbf{y} and beta is $\boldsymbol{\beta}$.

normalv

The function normaly computes the function value, gradient, and Hessian matrix associated with the log-likelihood component associated with a multivariate normal model with r positive, q = r(r+3)/2, A equal to N, F irrelevant, $\mathcal{Y}(A, F, q, r)$ the set of all r-dimensional real vectors, and O(A, F, q, r) the set of q-dimensional vectors $\boldsymbol{\beta}$ with elements β_h , $0 \le h < q$ such that $\beta_h > 0$ if h = r + j(j+3)/2 and $0 \le j < r$. For such $\boldsymbol{\beta}$, let $\mathbf{a}(\boldsymbol{\beta})$ be the r-dimensional vector with elements $a_j(\boldsymbol{\beta}) = \beta_j$ for $0 \le j < r$, and let $\mathbf{B}(\boldsymbol{\beta})$ be the symmetric positive-definite r by r matrix with row j and column k equal to β_h if $0 \le k \le j < r$ and h = r + k + (j(j+1)/2. For an r-dimensional vector \mathbf{z} with elements z_j , $0 \le j < q$, let $\phi(\mathbf{z}; r)$ be the product of the $\Phi_1(z_j)$, $0 \le j < r$.

For **y** in $\mathcal{Y}(A, F, q, r)$,

$$\ell_c(\boldsymbol{\beta}; \mathbf{y}) = \sum_{j=0}^{r-1} \log(\beta_{r+j(j+3)/2)}) + \log(\phi(\mathbf{a}(\boldsymbol{\beta}) + \mathbf{B}(\boldsymbol{\beta})\mathbf{y}; r)).$$
 (14)

This case corresponds to a model that a random vector has a distribution $\mathbf{a}(\boldsymbol{\beta}) + \mathbf{B}(\boldsymbol{\beta})\mathbf{Z}$, where \mathbf{Z} is an r-dimensional multivariate normal random vector with zero mean and with covariance matrix equal to the identity matrix. The function $\ell_c(\cdot; \mathbf{y}, A, F, q, r)$ is always concave but is not strictly concave. The function declaration is

f2v normalv(const int & order, const resp & y, const vec & beta).

The function normalv.value is $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ if y.dresp is \mathbf{y} and beta is $\boldsymbol{\beta}$. If r is 1, then normalv reduces to normal. The function normalv requires pack and unpack.

pack

For the struct vecmat defined by

struct vecmax{vec v; mat m;};,

the function pack converts a d-dimensional vector pack.v and a d by d symmetric matrix pack.m to a vector with dimension d(d+3)/2 with d initial elements the vector pack.v and element h = d + k + (j(j+1)/2) equal to row j and column k of pack.m for nonnegative k no greater than j < d. The function declaration is

vec pack(const vecmat & u).

Diagonal elements of the matrix equal the corresponding elements of u, and off-diagonal elements are twice the corresponding elements of the vector.

probit

The function probit computes the function value, gradient, and Hessian matrix associated with a probit transformation in berresp with A equal to S, $F = \Psi$, and q = r = 1. The function declaration is

f2v probit(const int & order, const resp & y, const vec & beta).

The function probit value is $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ if y iresp is \mathbf{y} and beta is $\boldsymbol{\beta}$.

ranklogit

The function ranklogit computes the function value, gradient, and Hessian matrix associated with a model for discrete choice in which q+1 objects are ranked for some positive integer q and the r most-preferred objects are recorded for some positive integer r < q. Here A has value R, F is irrelevant, the set $\mathcal{Y}(A, F, q, r)$ consists of the vectors \mathbf{y} of dimension r with distinct nonnegative integer elements that are no greater than q, and O(A, F, q, r) is the set of all q-dimensional vectors. To describe the model, consider β in O(A, F, q, r). Let U_j , $0 \le j \le q$, be independent random variables such that U_0 and $U_i - \beta_i$, $1 \le j \le q$, have the common distribution function G_U . Let v denote a random permutation of the integers from 1 to q such that $U_{v(j)}, 1 \leq j \leq q$, is nonincreasing in j. For β in O(A, F, q, r) and \mathbf{y} in $\mathcal{Y}(A, F, q, r)$, the log-likelihood $\ell_c(\beta; \mathbf{y}, A, F, q, r)$ is the logarithm of the probability that $v^{-1}(k) = y_k$ for $0 \le k \le r$. To find $\ell_c(\beta; \mathbf{y}, A, F, q, r)$, let $\alpha(\beta)$ be the vector of dimension q+1such that element $j, 0 \le j \le q$, is $\alpha_j(\beta) = 0$ if j = 0 and $\alpha_j(\beta) = \beta_{j-1}$ if j > 0. Let $K_i(\mathbf{y})$ be the set of nonnegative integers no greater than q that are not equal to y_k for any nonnegative integer k < j. Thus $K_0(\mathbf{y})$ is the set of nonnegative integers no greater than q. Then the log-likelihood component is

$$\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r) = \sum_{j=0}^{r-1} \left\{ \alpha_{y_j}(\boldsymbol{\beta}) - \log \left[\sum_{k \in K_j(\mathbf{y})} \exp(\alpha_k(\boldsymbol{\beta})) \right] \right\}.$$
 (15)

The function declaration is

 $f2v \ ranklogit(const \ int \& \ order, \ const \ resp \& \ y, \ const \ vec \& \ beta).$

The function ranklogit value is $\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r)$ if y iresp is \mathbf{y} and beta is $\boldsymbol{\beta}$. If r = 1, use of ranklogit gives the same result as use of multlogit.

truncresp

The function truncresp computes the function value, gradient, and Hessian matrix associated with a right-censored continuous random variable with the distribution of $\beta_0 + \beta_1 Z$ for some real β_0 and positive real β_1 , where, as in contresp, Z has distribution function F in \mathcal{F} . In this case, q = r = 2, A is T, $\mathcal{Y}(A, F, q, r)$ consists of two-dimensional vectors \mathbf{y} such that y_0 is a real number and y_1 is 0 or 1, and O(A, F, q, r) is the set of all two-dimensional vectors $\boldsymbol{\beta}$ with element $\beta_1 > 0$. For $\boldsymbol{\beta}$ in O(A, F, q, r) and \mathbf{y} in $\mathcal{Y}(A, F, q, r)$, if $y_1 = 0$, then the observation is not censored and the corresponding log-likelihood component is

$$\ell_c(\boldsymbol{\beta}; \mathbf{y}, A, F, q, r) = \log(\beta_1) + \log(F_1(\beta_0 + \beta_1 y_0)), \tag{16}$$

while in the case of $y_1 = 1$, the the observation is censored at y_0 and the log-likelihood component is

$$\ell_c(\beta; \mathbf{y}, A, F, q, r) = \log(1 - F(\beta_0 + \beta_1 y_0)).$$
 (17)

The function declaration is

f2v truncresp(const int & order, const char & transform, const resp & y, const vec & beta).

Here y.iresp has the single element y_1 , y.dresp has the single element y_0 , beta is β , transform is defined as in berresp, and truncresp.value is $\ell_c(\beta; \mathbf{y}, A, F, q, r)$. Functions required are berresp, contresp, and their respective required functions.

unpack

The function unpack converts a vector of dimension d(d+3)/2 to the vector format described in pack. The function declaration is

vecmat unpack(const int & d, const vec & beta).

The vector unpack.v contains the first d elements of beta and row j and column k of unpack.m is element d+k+j(j+3)/2 of beta for nonnegative integers $k \leq j < d$.

Computation of Log Likelihood Functions

genresp

The function genresp provides a general tool for computation of a component of a log-likelihood function, its gradient, and its Hessian matrix. The function declaration is

f2v genresp(const int & order, const model & choice, const resp & y, const vec & beta).

Here model has the definition

struct model{char type; char transform}.

The function genresp uses berresp, contresp, cumresp, gradresp, loggamma, logitbeta, logitdirichlet, logmean, maxberresp, multlogit, ranklogit, and truncresp, together with the functions they in turn require.

genresplik

The function genresplik computes the log-likelihood function and its gradient and Hessian matrix. The function declaration is

```
f2v genresplik(const int & order, const field<pattern> & patterns, const xsel & patternnumber, const field<resp> & data, const resp & theta, const field<xsel> & selectbeta, const xsel & selectbetano, const field<xsel> & selectbetac, const xsel & selectbetacno, const field<xsel> & selectthetai, const xsel & selectthetaino, const field<xsel> & selectthetad, const xsel & selectthetadno, const field<xsel> & selectthetac, const xsel & selectthetacno, const field<xsel> & selectthetac, const xsel & selectthetacno, const vec & w, const xsel & obssel, const vec & beta).
```

The definitions of arguments and structs rely the the definition of *model* in genresp and the definition of *resp* in truncresp. The variable *theta* is a supplemental variable often used with item-response models.

In the case of xsel, the struct is defined as

struct xsel{bool all; uvec list}.

The struct is applied to a finite and nonempty collection collection of k objects numbered from 0 to k-1. If all is true, all members of the collection are considered. Otherwise, only members in list are used. Thus in the case of obssel, the observation numbers i to be used are specified. The function intsel is used for selections based on xsel. If xsel.bool is true, then an integer i is mapped by intsel to i, whereis if bool is false, then i is mapped to element i of xsel.list.

If patternnumber maps the integer i to j(i, 1), then element j(i, 1) of patterns defines the function λ_i and the model used for the response \mathbf{Y}_i . In addition, the weight w_i assigned to \mathbf{Y}_i is element i of w, while element j(i, 2) of selectbeta specifies the elements of beta used to define λ_i if selectbetano maps i to j(i, 2).

The struct pattern is defined as

 $struct\ pattern\{model\ choice;\ vec\ o;\ mat\ x;\ cube\ c;\}.$

Thus for element j(i,1) of patterns, the component choice defines the model for \mathbf{Y}_i , o defines \mathbf{o}_i , while x and c are used to specify \mathbf{X}_i . Definition of \mathbf{X}_i is somewhat complex. Let selectbetacno map i to j(i,3), and let selectthetacno map i to j(i,4). If k is not selected by element j(i,2) of selectbeta, then column k of \mathbf{X}_i is the zero vector. Otherwise, let k(i,2) be element m(i,2) selected by element m(i,2) of selectbeta. If m(i,2) is not selected by element m(i,3) of selectbetac, then column m(i,2) of m(i,3) of component m(i,3) of selectbetac. Then column m(i,3) be element m(i,3) selected by element m(i,3) of selectbetac. Then column m(i,3) of the sums of the products of element m(i,3) of component m(i,3) of patterns for pairs m(i,3) and m(i,3) such that m(i,3) is integer m(i,3) selected by element m(i,3) of selectthetac.

In the case of \mathbf{Y}_i , let element i of thetaino select j(i,5) and element i of thetadno select j(i,6). If element j(i,5) of thetai does not select anything, component iresp of element j(i,5) of data is component iresp of \mathbf{Y}_i . Otherwise, component iresp of \mathbf{Y}_i consists of the elements of the component iresp of element j(i,5) of theta selected by element j(i,5) of thetai. If element j(i,6) of thetad does not select anything, component dresp of element i of data is the double component of \mathbf{Y}_i . Otherwise, the double component of \mathbf{Y}_i consists of the elements of theta.dresp selected by element j(i,6) of thetad. The function genresplik uses addsel, cx, intsel, linsel, sintsel, sivecsel, svecsel, genresp, and all C++ functions genresp requires.

genrespmle

The function *genrespmle* applies maximizes the log-likelihood function, gradient, and Hessian matrix of genresplik. The function declaration is

```
maxf2v genrespmle(const int & order, const params & mparams, const char & algorithm, const field<pattern> & patterns, const xsel & patternnumber, const field<resp> & data, const resp & theta, const field<xsel> & selectbeta, const xsel & selectbetano, const field<xsel> & selectbetac, const xsel & selectbetacno, const field<xsel> & selectthetai, const xsel & selectthetaino, const field<xsel> & selectthetad, const xsel & selectthetadno, const field<xsel> & selectthetac, const xsel & selectthetacno, const vec & w, const xsel & obssel, const vec & start).
```

Definitions are as in maxlinq2, maxf2vvar, maxselect, and genresplik. The functions maxselect and genresplik are required, together with all C++ functions that these two functions need.

Tools for Computation of Log Likelihood Functions

addsel

The function addsel is used to add f2v structures. The function declaration is

```
void addsel(const int & order, const xsel & xselect, const f2v & x, f2v & y, const double & a).
```

Here order and xselect are defined as in Log-likelihood Components. The struct y is modified by use of the struct x and the multiplier a. In all cases, ax.value is added to y.value. If xselect.all is true, then x and y have compatible dimensions, ax.grad is added to y.grad if order is at least 1, and ax.hess is added to y.hess if order is at least 2. If xselect.all is false, then ax.grad is added to y.grad.elem(xselect.list) if order is at least 1 and ax.hess is added to y.hess.submat(xselect.list,xselect.list) if order is at least 2.

$\mathbf{c}\mathbf{x}$

The function cx is used to multiply a cube by a vector to yield a matrix. The function declaration is

mat cx(const cube & c, const vec & x).

Let the c_{ijk} be the elements of the cube defined by c, and let x_k be the elements of the vector defined by x. The result is that row i and column j of cx is the sum over k of $c_{ijk}x_k$.

intsel

The function *ivecsel* selects a nonnegative integer from a struct *xsel* defined as in genresplik. The function declaration is

int intsel(const xsel & xselect, const int & i).

The value of *intsel* is the *i*th integer defined by xselect.

ivecsel

The function *ivecsel* is employed to create a new integer vector from an old vector of integers by extracting of elements of the old vector. The function declaration is

ivec ivecsel(const xsel & xselect, const ivec & y).

Here the struct xsel is defined as in genresplik. If xselect.all is true, then ivecsel is y. Otherwise, ivecsel is a vector with the number of elements in component list of xselect, if j(i) is element i of of component list of xselect, then element i of ivecsel is element j(i) of y.

linsel

The function linsel is used to apply a linear transformation to an f2v struct. The function declaration is

f2v linsel(const int & order, const f2v & x, const mat & a).

Here order is defined as in Log-likelihood Components. Let \mathbf{a} be the matrix defined by a. It is always the case that linsel.value is x.value. If order is positive and \mathbf{g} is the vector specified by x.grad, then linsel.grad is $\mathbf{a}'\mathbf{g}$. If order exceeds 1 and \mathbf{H} is the matrix specified by x.hess, then linsel.hess is $\mathbf{a}'\mathbf{H}\mathbf{a}$.

sintsel

The function sintsel counts the number of integers selected from the first n nonnegative integers. The function declaration is

int sintsel(const xsel & xselect, const int & n).

The integers from 0 to n-1 are selected according to xselect, where xsel is defined as in genresplik.

sivecsel

The function *sivecsel* counts the number of integer vector elements selected. The function declaration is

int sivecsel(const xsel & xselect, const ivec & y).

The integers in y are selected according to xselect, where xsel is defined as in genresplik.

svecsel

The function svecsel counts the number of vector elements selected. The function declaration is

int svecsel(const xsel & xselect, const vec & y).

The integers in y are selected according to xselect, where xsel is defined as in genresplik.

vecsel

The function vecsel is employed to create a new vector from an old vector by extracting of elements of the old vector. The function declaration is

vec vecsel(const xsel & xselect, const vec & y).

Here the struct xsel is defined as in genresplik. If xselect.all is true, then vecsel is y. Otherwise, vecsel is a vector with the number of elements in xselect.list, and element i of vecsel is element j(i) of y if j(i) is element i of component list of vecsel.

Latent Structures

In this section, functions useful for analysis of latent structures are considered. The log-likelihood function in this section is defined based on the definitions in Log-likelihood Components; however, use of latent variables is involved. In typical cases, data involve multiple responses for each individual observation. For a positive integer m, m observations are present. For observation h, $0 \le h < m$, the observation has weight $w_{h*} > 0$, and n_h responses are observed. In addition, a latent vector appears in the model such the observed responses are conditionally independent given the latent vector and the predicting variables. Associated with the latent vector are positive integers q_* and r_* , A_* in \mathcal{A} , and F_* in \mathcal{F} . The latent vector $\boldsymbol{\theta}_h$ is in $\mathcal{Y}(A_*, F_*, q_*, r_*)$

and is predicted by the q_* by p predicting matrix \mathbf{X}_{h*} in the nonempty set \mathcal{X}_* and the fixed q_* -dimensional vector \mathbf{o}_* . It is assumed that $\mathbf{\lambda}_*(\beta) = \mathbf{o}_* + \mathbf{X}_*\beta$ is in $O(A_*, F_*, q_*, r_*)$ as long as \mathbf{X}_* is in \mathcal{X}_* and β is in O. For response i, $0 \le i < n_h$, positive integers q_{hi} and r_{hi} are given. The variable A_{hi} is in \mathcal{A} and F_{hi} is in \mathcal{F} . The component of the log likelihood for response i involves the predicted random vector \mathbf{Y}_{hi} in $\mathcal{Y}(A_{hi}, F_{hi}, q_{hi}, r_{hi})$, the latent vector $\mathbf{\theta}_h$, the q_{hi} by p predicting matrix \mathbf{X}_{hi} in a nonempty set \mathcal{X}_{hi} , the q_{hi} -dimensional vector \mathbf{o}_{hi} , the q_{hi} by q_* matrix \mathbf{D}_{hi} , the positive real weight w_{hi} , the q_{hi} by p matrix \mathbf{D}_{hik} , $0 \le k < q_*$, and the function $\ell_c(\cdot; \mathbf{y}, A_{hi}, F_{hi}, q_{hi}, r_{hi})$ on $O(A_{hi}, F_{hi}, q_{hi}, r_{hi})$ defined for \mathbf{y} in $\mathcal{Y}(A_{hi}, F_{hi}, q_{hi}, r_{hi})$. For any β in O, \mathbf{X} in \mathcal{X}_{hi} , and $\boldsymbol{\theta}$ in $\mathcal{Y}(A_*, F_*, q_*, r_*)$,

$$\lambda_{hi}(\boldsymbol{\beta}|\boldsymbol{\theta}) = \mathbf{o}_{hi} + \mathbf{X}_{hi}\boldsymbol{\beta} + \mathbf{D}_{hi}\boldsymbol{\theta} + \sum_{k=0}^{p-1} \theta_k \mathbf{D}_{hik}\boldsymbol{\beta}$$
(18)

is in $O(A_{hi}, F_{hi}, q_{hi}, r_{hi})$. A helpful general reference to applications in psychometrics is provided by van der Linden (2018). A large collection of references to other applications provided in Muthén (2002)

For example, in a simple two-parameter item-response model for dichotomous responses, a pool of T items numbered from 0 to T-1 is used, and p=2T. The element β_{2t} is the item intercept for item t, and β_{2t+1} is the corresponding item slope. The response \mathbf{Y}_{hi} , which corresponds to pool member t(h,i), is a one-dimensional vector with the single element Y_{0hi} equal to 0 or 1, the t(h,i) are all different for the same observation h, each q_{hi} and each r_{hi} is 1, r_* is 1, q_* is 2, \mathbf{o}_* is the two-dimensional vector with elements 0 and 1, all elements of the \mathbf{X}_{h*} are 0, the only nonzero element of \mathbf{X}_{hi} is row 0 and column 2t(h,i), which is 1, the \mathbf{D}_{hk} have all 0 elements, the \mathbf{D}_{hik} are 1 by 1 matrices with the single element 0 except for $\mathbf{D}_{hi(2t(h,i)+1)}$, which is the 1 by 1 matrix with the single element 1, and \mathbf{o}_{hi} is the vector with the single element 0. Thus $\mathbf{\lambda}_{hi}(\boldsymbol{\beta}|\boldsymbol{\theta})$ is the vector with the single element $\beta_{2t(h,i)} + \beta_{2t(h,i)+1}\theta_0$. The value of A_{hi} is S, and each F_{hi} is the same. If each F_{hi} is Ψ , then the model is a two-parameter logistic (2PL) model. If each F_{hi} is Φ , then the model is a normal ogive (2PN) model.

For β in O, the log-likelihood has the form

$$\ell(\boldsymbol{\beta}) = \sum_{h=0}^{m-1} w_{h*} \ell_h(\boldsymbol{\beta}), \tag{19}$$

where $\ell_h(\beta)$ is the component of the log-likelihood for observation h. Thus the gradient function of ℓ at β satisfies

$$\nabla \ell(\boldsymbol{\beta}) = \sum_{h=0}^{m-1} w_{h*} \nabla \ell_h(\boldsymbol{\beta}), \tag{20}$$

where $\nabla \ell_h(\beta)$ is the gradient function of ℓ_h at β . The Hessian function of ℓ at β satisfies

$$\nabla^2 \ell(\boldsymbol{\beta}) = \sum_{h=0}^{m-1} w_{h*} \nabla^2 \ell_h(\boldsymbol{\beta}), \tag{21}$$

where $\nabla^2 \ell_h(\boldsymbol{\beta})$ is the Hessian function of ℓ_h at $\boldsymbol{\beta}$. The approximation

$$\tilde{\nabla}^2 \ell(\boldsymbol{\beta}) = -\sum_{h=0}^{m-1} w_{h*} \nabla \ell_h(\boldsymbol{\beta}) [\nabla \ell_h(\boldsymbol{\beta})]^T, \tag{22}$$

may also be considered.

In turn, $\ell_h(\beta)$ involves the product

$$\ell_h(\boldsymbol{\beta}|\boldsymbol{\theta}) = \ell_c(\boldsymbol{\lambda}_*(\boldsymbol{\beta}); \boldsymbol{\theta}, A_*, F_*, q_*, r_*) \sum_{i=0}^{n_h-1} w_{hi} \ell_c(\boldsymbol{\lambda}_{hi}(\boldsymbol{\beta}|\boldsymbol{\theta}); \mathbf{Y}_{hi}, A_{hi}, F_{hi}, q_{hi}, r_{hi})$$
(23)

for $\boldsymbol{\theta}$ in $\mathcal{Y}(A_*, F_*, q_*, r_*)$. The component

$$\ell_h(\boldsymbol{\beta}) = \log \int (\exp(\ell_h(\boldsymbol{\beta}|\cdot))),$$
 (24)

where $\exp(\ell_h(\boldsymbol{\beta}|\cdot))$ is the function with value $\exp(\ell_h(\boldsymbol{\beta}|\boldsymbol{\theta}))$ for $\boldsymbol{\theta}$ in $\mathcal{Y}(A_*, F_*, q_*, r_*)$. In practice, $\ell_h(\boldsymbol{\beta})$ is evaluated by

$$\tilde{\ell}_h(\boldsymbol{\beta}) = \log \left[\sum_{k=1}^{Q} u_{hk} \exp(\ell_h(\boldsymbol{\beta}|\boldsymbol{\theta}_{hk})) \right], \tag{25}$$

for some positive weights u_{hk} and elements $\boldsymbol{\theta}_{hk}$ in $\mathcal{Y}(A_*, F_*, q_*, r_*)$.

For computations for latent-structure models, the following functions are employed.

gpcm

The main function gpcm finds maximum-likelihood estimates for a generalized partial credit (GPCM) model (Muraki, 1992) with a standard normal latent variable. As in the two-parameter item-response model for dichotomous responses, a pool of T items numbered from 0 to T-1 is used. For each nonnegative integer t < T, I_t is a positive integer greater than 1 that corresponds to pool member t, and p is the sum of the integers I_t for $0 \le t < T$. In the GPCM case, response \mathbf{Y}_{hi} is a one-dimensional vector with the single element Y_{0hi} . The response corresponds to item t(h,i) from the pool, where t(h,i) is a nonnegative integers less than T. Item t(h,i) has $I_{t(h,i)}$ possible nonnegative integer values from 0 to $I_{t(h,i)}-1$, the latent vector $\boldsymbol{\theta}_h$ has dimension 1, and θ_{h0} has a standard normal distribution. The t(h,i) are all different for the same observation h. Let J_{hi0} be the sum of the I_u for u < t(h,i), let J_{hi1} be the sum of the I_u for $u \le t(h,i)$, and let the nonnegative integer k be less than $I_{t(h,i)}-1$. Conditional on θ_{h0} , Y_{0hi} has a multinomial logit distribution with element k of the parameter vector $\boldsymbol{\lambda}_{hi}(\boldsymbol{\beta}|\boldsymbol{\theta})$ equal to $\beta_a + \beta_b k \theta_{h0}$, where $a = J_{hi0} + k$ and $b = J_{hi1}$.

The function gpcm considers the simplified case of n_h constant and t(h, i) = i for nonnegative integers $i < n_0$ and $I_i - 1$ equal to the maximum value of Y_{0hi} for

 $0 \le h < m$. The function uses a control file controlfile read from standard input. The file is a text file with any line consisting of a pair of entries separated by a space, The entries contain no blank characters. The following cases exist.

The variable data has string value infile that specifies the input file for the data. The default is infile.csv. Data are read as an integer matrix with row h and column i equal to Y_{0hi} .

The variable sf is associated with the string startvalue that specifies a file containing the vector of starting values. The default is to apply startgpcm.

The variable *outfile* has string value that specifies the name of the output file for results. The default is *outfile*.

The bool variable fflag indicates whether an output file is used. The default is true.

The bool variable *pflag* indicates whether anything is printed in ascii form in standard output. The default is *true*.

The character variable method specifies the algorithm applied. The possibilities are G for gradient ascent, C for conjugate gradient ascent, N for modified Newton-Raphson, and L for Louis approximation. The default is N.

The positive double variable tol specifies the convergence criterion mparams.tol. The default is 0.001.

The bool variable adapt indicates whether adaptive quadrature is used. The default is true.

The character variable quadrature indicates the quadrature procedure used, with G for Gauss-Hermite and Q for normal quantiles. The default is G.

The positive integer variable *points* that exceeds 1 gives the number of quadrature points, with the default 9.

The program uses irtmle and all its required functions. In addition, startgpcm and its required functions, hermpw, quormpwe, and savmaxf2v are needed.

invcdf

The function invcdf finds the inverse of the cumulative distribution function and its derivative at prob for F in \mathcal{F} . The function declaration is

f1 invcdf(const char & cdf, const double & prob).

The struct f1 is

struct f1{double value; double der}.

The variable cdf is defined as in berresp. At prob, the value of the inverse is invcdf.value, and the derivative is invcdf.der.

irtm

The function *irtm* finds the log likelihood component $\ell_h(\beta)$ and associated gradient and Hessian matrix for a latent structure model. The function uses numerical integration if $\mathcal{Y}(A_*, F_*, q_*, r_*)$ is not finite or countably infinite. The function declaration is

```
f2v irtm (const int & order, const field<pattern> & patterns,
const xsel & patternnumber, const field<resp> & data, const field <pwr> & thetas,
const adq & scale, dovecmat & obsscale,
const field<xsel> & selectbeta, const xsel & selectbetano,
const field<xsel> & selectbetac, const xsel & selectbetacno,
const field<xsel> & selectthetai, const xsel & selectthetaino,
const field<xsel> & selectthetad, const xsel & selectthetadno,
const field<xsel> & selectthetac, const xsel & selectthetacno,
const vec & w, const xsel & obssel, const vec & beta).
```

In this declaration, almost all arguments are defined as in genresplik. The exceptions are *thetas*, *scale*, and *obsscale*. These arguments rely on the structs *pwr*, *adq*, and *dovecmat* with the following definitions:

```
struct pwr{double weight; double kernel; resp theta;},
struct adq{bool adapt; xsel linselect;xselv quadselect;},
and
struct dovecmat{double s; vec v; mat m;}.
```

The structs thetas and obsscale define the u_{hk} and θ_{hk} of Equation 25, while scale is used in irtmle for computation of maximum-likelihood estimates of β . For element k of thetas, u_{hk} is obtained by multiplying thetas(h).weight by obsscale.s and dividing by thetas(h).kernel, the integer elements of θ_{hk} are the same as in thetas(h).theta.iresp, and the remaining elements of θ_{hk} are found by adding obsscale.v to the product of the matrix obsscale.m and the vector thetas(h).theta.dresp. Use of scale is discussed in the description of irtmle. In addition to functions needed by genresplik, fitquad and its required functions are needed.

irtmle

The function *irtmle* finds the maximum likelihood estimate for a latent structure model. As in irtm, the function uses numerical integration if $\mathcal{Y}(A_*, F_*, q_*, r_*)$ is not finite or countably infinite. The function declaration is

```
maxf2v irtmle (const int & order, const params & mparams,
const char & algorithm, const field<patterns> & patterns,
const field<xsel> & patternnumber, const xsel & patno,
const field<field<resp>> & data, const field<field<pwr>> > & thetas,</pr>
const xsel & thetano,
const field\langle adq \rangle \& scale, const xsel & scaleno, field\langle dovecmat \rangle \& obsscale,
const field<xsel> & selectbeta, const field<xsel> & selectbetano,
const xsel & selbetano,
const field < xsel > & selectbetac, const field < xsel > & selectbetacno,
const xsel & selbetacno,
const field<xsel> & selectthetai, const field<xsel> & selectthetaino,
const xsel & selthetaino,
const field<xsel> & selectthetad, const field<xsel> & selectthetadno,
const xsel & selthetadno,
const field<xsel> & selectthetac, const field<xsel> & selectthetacno,
const xsel & selthetacno.
const field < vec > & w, const xsel & wno,
const field < xsel & obssel, const xsel & obsselno,
const vec & obsweight, const xsel & datasel,
const field < xsel > & betasel, const xsel & betaselno, const vec & start).
```

In this declaration, maxf2v and mparams are defined as in maxlinq2 and maxf2vvar, while order is defined as in genresplik. whereas mparams is used for the basic iterations used for determination of the maximum-likelihood estimate, The variables algorithm and start are defined as in genrespmle. The vector obsweight provides the weights w_{h*} for $0 \le h \le m-1$. The variables patterns, selectbeta, selectbetac, selectthetai, selecthetad, and selectthetac are defined as in genresplik. For each observation h and each nonnegative integer $i < n_h$, if m(h, 1) is patno(h), then patterno(m(h,1)) assigns i to the member of patterns that corresponds to λ_{hi} . Similar arguments apply to triples such as selectbeta, selectbetano, and selbeta. In the case of w and w and w of or each observation h, w or assigns a vector in w of length n_h that corresponds to the w for $0 \le i < n_h$. A similar relationship exists between obssel and obselno. Selection of observations h is determined by datasel, and betasel and betaselno determine which subvector of the parameter vector β applies to h.

The functions irtms and its required functions and the functions that are prerequisites for genrespmle are required by irtmle.

irtms

The function *irtms* finds the log likelihood component $\ell(\beta)$ and associated gradient and Hessian matrix for a latent-structure model. As in irtm, the function uses numerical integration if $\mathcal{Y}(A_*, F_*, q_*, r_*)$ is not finite or countably infinite. The function declaration is

```
f2v irtms (const int & order, const field<pattern> & patterns,
const field < xsel & patternnumber, const xsel & patno,
const field<field<resp>> & data, const field<field <pwr>> > & thetas,
const xsel & thetano,
const field <adq> & scale, const xsel & scaleno, field <dovecmat> & obsscale,
const field<xsel> & selectbeta, const field<xsel> & selectbetano,
const xsel & selbetano,
const field<xsel> & selectbetac, const field<xsel> & selectbetacno,
const xsel & selbetacno.
const field<xsel> & selectthetai, const field<xsel> & selectthetaino,
const xsel & selthetaino.
const field < xsel > & select the tad, const field < xsel > & select the tadno.
const xsel & selthetadno,
const field<xsel> & selectthetac, const field<xsel> & selectthetacno,
const xsel & selthetacno,
const field < vec > & w, const xsel & wno, const field < xsel > & obssel,
const xsel & obsselno,
const vec & obsweight, const xsel & datasel,
const field<xsel> & betasel, const xsel & betaselno, const vec & beta).
```

Definitions are as in *irtmle*, except that *beta* is the general function argument of the log likelihood rather than a starting vector. The function irtm and its required functions are used by irtms.

irtmsave

The function *irtms*ave finds the log likelihood components of $\ell_h(\beta)$ and associated gradient and Hessian matrix for a latent structure model. The function declaration is

```
field<pwrf2v> irtmsave (const int & order, const field<pattern> & patterns, const xsel & patternnumber, const field<resp> & data, const field <pwr> & thetas, dovecmat & obsscale, const field<xsel> & selectbeta, const xsel & selectbetano, const field<xsel> & selectbetac, const xsel & selectbetacno, const field<xsel> & selectthetai, const xsel & selectthetaino, const field<xsel> & selectthetad, const xsel & selectthetadno, const field<xsel> & selectthetac, const xsel & selectthetacno, const field<xsel> & selectthetac, const xsel & selectthetacno, const vec & w, const xsel & obssel, const vec & beta).
```

In this declaration, almost all arguments are defined as in irtm. The struct pwr is defined as follows:

struct pwrf2v{double weight; double kernel; resp theta; double value; vec grad; mat hess;}.

For element i of thetas, element i of irtmsave has theta equal to thetas(i).theta, weight equal to thetas(i).weight, kernel equal to thetas(i).kernel, value equal to $\ell_h(\beta|\theta)$ for θ equal to point and β equal to beta, grad equal to the corresponding gradient at β (if order is positive), and hess equal to the corresponding Hessian at β (if order exceeds 1). Functions needed by genresplik are also needed in irtmsave.

irtmsaves

The function *irtms*aves finds the log likelihood components of all the $\ell_h(\beta)$ and associated gradient and Hessian matrix for a latent structure model. The function declaration is

```
field<pwrf2v> irtmsave s(const int & order, const field<pattern> & patterns,
const xsel & patternnumber, const xsel & patno,
const field<field<resp>> & data, const field<field<pwr>> > & thetas.
const xsel & thetano,
field < dovecmat > \& obsscale,
const field<xsel> & selectbeta, const field<xsel> & selectbetano,
const xsel & selbetano,
const field<xsel> & selectbetac, const field<xsel> & selectbetacno,
const xsel & selbetacno.
const field<xsel> & selectthetai, const field<xsel> & selectthetaino,
const xsel & selthetaino,
const field<xsel> & selectthetad, const field<xsel> & selectthetadno.
const xsel & selthetadno,
const field<xsel> & selectthetac, const field<xsel> & selectthetacno,
const xsel & selthetacno,
const field < vec > & w, const xsel & wno, const field < xsel > & obssel,
const xsel & obsselno.
const vec & obsweight, const xsel & datasel,
const field<xsel> & betasel, const xsel & betaselno, const vec & beta).
```

Definitions are as in irrtms and irrtmsave. Element i of irtmsaves(h) corresponds to $\ell_h(\boldsymbol{\beta}|\boldsymbol{\theta}_i)$. Functions required are irrtmsave and the functions used in irrtmsave.

oneparamirt

The main function *oneparamirt* finds maximum-likelihood estimates for a oneparameter item-response model with dichotomous responses and a univariate standard normal latent variable. In this model, a pool of T items numbered from 0 to T-1 is used. The model dimension p = T+1. Response \mathbf{Y}_{hi} is a one-dimensional vector with the single element Y_{0hi} . The response corresponds to item t(h,i) from the pool, where t(h,i) is a nonnegative integers less than T. Item t(h,i) has possible values 0 and 1, the latent vector $\boldsymbol{\theta}_h$ has dimension 1, and θ_{h0} has a standard normal distribution. The t(h,i) are all different for the same observation h. Conditional on θ_{h0} , Y_{0hi} has a Bernoulli distribution with probability of a value 1 equal to $F(\beta_{t(h,i)} + \beta_T \theta_{h0})$ for a distribution function F in \mathcal{F} .

The function one paramirt considers the simplified case of n_h constant and t(h,i)=i for nonnegative integers $i < n_0$. The function uses a control file control file read from standard input. The file is a text file with any line consisting of a pair of entries separated by a space, The entries contain no blank characters. The following cases exist.

The variable data has string value infile that specifies the input file for the data. The default is infile.csv. Data are read as an integer matrix with row h and column i equal to Y_{0hi} .

The character variable dist specifies the cumulative distribution associated with the binary responses. The possibilities are N for normal, L for logistic, and G for Gumbel. The default is L.

The variable sf is associated with the string startvalue that specifies a file containing the vector of starting values. The default is to apply startoneparamirt. The

The variables outfile, fflag, pflag, method, tol, adapt, iquadrature, and points are defined as in gpcm. that exceeds 1 gives the number of quadrature points, with the default 9.

The program uses irtmle and all its required functions. In addition, startoneparamirt and its required functions, hermpw, quormpwe, and savmaxf2v are needed.

pcm

posterior

For an observation, the function *posterior* finds the posterior distribution of the latent vector given the observed responses. The function declaration is

field<pwr> posterior (const field<pwrf2v> & irtcomps

The definition of pwr is in irtm, and the definition of pwrf2v is in irtmsave. The posterior is presented as q quadrature weights and points, where irtcomps has q members.

posteriors

For a latent-structure model, the function *posteriors* finds the posterior distributions of the latent vectors given the observed responses for each observation. The function declaration is

field<field<pwr>> > posteriors (const field<field<pwrf2v> > & irtcompsm

The definition of pwr is in irtm, and the definition of pwrf2v is in irtmsave. The posterior for each observation h is presented as q(h) quadrature weights and points, where irtcompsm(h) has q(h) members.

regprod

regprodf

startgpcm

startoneparamirt

startpcm

starttwoparamirt

The function *starttwoparamirt* finds a starting vector for use in twoparamirt. The function declaration is

vec starttwoparamirt(const char & cdf, const imat & responses).

As in invcdf, the cumulative distribution function is specified by $\operatorname{\mathsf{cdf}}$. The starting vector $\operatorname{starttwoparamirt}$ is based on the input matrix $\operatorname{responses}$ with m rows and n columns. Each row represents n binary items. The function invcdf is needed.

twoparamirt

The program twoparamirt provides a basic analysis of a two-parameter itemresponse model for binary responses with a univariate standard normal latent variable. For each observation, the same items apply. It uses a control file controlfile read from standard input. The file is a text file with any line consisting of a pair of entries separated by a space, The entries contain no blank characters. The following cases exist.

The variable data has string value *infile* that specifies the input file for the data. The default is *infile.csv*. Each line of the input file represents a different observation and contains the same number of entries, with each entry the response to an item. Items are presented in the same order for each observation.

The variable sf is associated with the string startvalue that specifies a file containing the vector of starting values. The default is to apply starttwoparamirt.

The variable *outfile* has string value that specifies the name of the output file for results. The default is *outfile*.

The bool variable fflag indicates whether an output file is used. The default is true.

The bool variable *pflag* indicates whether anything is printed in ascii form in standard output. The default is *true*.

The character variable dist specifies the cumulative distribution associated with the binary responses. The possibilities are N for normal, L for logistic, and G for Gumbel. The default is L.

The character variable method specifies the algorithm applied. The possibilities are G for gradient ascent, C for conjugate gradient ascent, N for modified Newton-Raphson, and L for Louis approximation. The default is N.

The positive double variable tol specifies the convergence criterion mparams.tol. The default is 0.001.

The bool variable adapt indicates whether adaptive quadrature is used. The default is true.

The character variable quadrature indicates the quadrature procedure used, with G for Gauss-Hermite and Q for normal quantiles. The default is G.

The positive integer variable *points* that exceeds 1 gives the number of quadrature points, with the default 9.

The program uses irtmle and all its required functions. In addition, starttwoparamirt and its required functions, hermpw, quormpwe, and savmaxf2v are needed.

Integration Tools

eaps

For each observation i, the function eaps generates a posterior weighted mean eaps(i).v and covariance matrix eaps(i).m that correspond to a discrete posterior distribution with points posts(i).m.col(j) with probabilities posts(i).v(j) for j from 1 to $posts(i).m.n_cols$. The function declaration is field < vecmat > eaps(const field < vecmat > & posts).

The definition of *vecmat* is as in pack. The function wmc is used.

fitquad

The function fit quad fits a quadratic function to function values and quadrature points and finds the linear transformation that maps the origin onto the location of the maximum of the quadratic function and has a symmetric Jacobian matrix equal to the positive-definite and symmetric square root of the inverse of the Hessian matrix of the fitted quadratic function. The function declaration is dovecmat fitquad(const field<f2v> & cresults, const field<pwr> & newthetas, const adq & scale, dovecmat & obsscale).

The structs are defined as in irtm. The linear components of the fitted quadratic not set to 0 are specified by *scale.linselect*, and the quadratic components not set to 0 are specified by *scale.quadselect*. If the fitted quadratic function is not strictly concave, then *fitquad* is *obsscale*.

genfact

For a vector sizes of positive integers, the function genfact generates all vectors i of nonnegative integers with the same number of elements as sizes such that each element of i is less than the corresponding element of sizes. The function declaration is

imat genfact(const ivec & sizes).

The columns of *genfact* are the possible vectors *i*. For example, if the elements of sizes are 2 and 3, then Column 0 of *genfact* has elements 0 and 0, and Column 1 has elements 1 and 0. In all, *sizes* has 6 columns, and Column 5 has elements 1 and 2.

genprods

The function genprods generates a collection of quadrature points and quadrature weights for a multivariate integral from quadrature weights and quadrature points for a univariate integral. The function declaration is

vecmat genprods(const imat & indices, const field<pw> & pws).

The struct vecmat is defined as in pack, and the struct pw has vec elements points and weights. Consider the case of Q quadrature points for a multidimensional integral on the space of D-dimensional vectors, where Q and D are positive integers. Then genprods.m has Q columns and genprods.v has Q elements. The matrix genprods.m has D rows. The array pws has D members. For $0 \le d < D$, pws(d).points and pws(d).weights have m(d) > 1 members, and the members of pws(d).weights are positive. The matrix indices specifies the quadrature vectors and quadrature weights to construct from pws. If indices has p columns, $0 \le k < p$, and $0 \le d < D$, then row d and column k of indices is nonnegative and less than m(d) and the corresponding row and column of genprods.m is pws(d).points(indices(d,k)). Element k of genprods.v is the product of pws(d).weights(indices(d,k)) for $0 \le d < D$.

hermcoeff

The function hermcoeff finds the coefficients of a Hermite polynomial of a given degree. The function declaration is

vec hermcoeff(const int & n).

The integer variable n is the nonnegative order. The vector hermcoeff has n+1 elements. The polynomial is $H_n(x) = \sum_{i=0}^n \alpha_i x^{n-i}$ for real x, and element i of hermcoeff is α_i . For example, if n is 2, then the elements of hermcoeff are 1, 0, and -1.

hermpoly

The function hermpoly evaluates the Hermite polynomials up to a given degree at a specified real value. The function declaration is

vec hermpoly(const int &n, const double & x).

The degree is the nonnegative integer variable n, and the real value is x. The vector hermpoly has n+1 elements. For $0 \le k \le n$, element k of hermpoly is the value of H_k at x.

hermpw

The function hermpw uses the algorithm of Golub and Welsch (1969) to find the quadrature points and quadrature weights for Gauss-Hermite quadrature. The function declaration is

pw hermpw(const int & n).

The struct hermpw has vector elements hermpw.points and hermpw.weights. The number of quadrature points is n. The ordered quadrature points are in hermpw.points. The corresponding weights are in hermpw.weights. The weights are relative to the standard normal density.

qnormpwe

The function *quormpwe* provides normal-scores quadrature of a given order. The function declaration is

pw qnormpwe(const int & n).

The struct qnormpwe has vector elements qnormpwe.points and qnormpwe.weights. The number of quadrature points is n. The ordered quadrature points are in qnormpwe.points. The corresponding weights are in qnormpwe.weights.

wmc

The function wmc computes a weighted mean vector and covariance matrix. The function declaration is

vecmat wmc(const vecmat & wx).

The elements of wx.v are probabilities corresponding to the rows of wx.m.

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