Newtonian gravitation for C++ programmers

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Wednesday 27th November, 2024 19:13

Abstract

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1 Numerical: integer field line count

```
long long unsigned int get_intersecting_line_count(
        const vector < vector = 3 > & unit_vectors,
        const vector_3 sphere_location,
        const real_type sphere_radius)
        long long unsigned int count = 0;
        vector_3 cross_section_edge_dir(sphere_location.x, sphere_radius, 0);
        cross_section_edge_dir.normalize();
        vector_3 receiver_dir(sphere_location.x, 0, 0);
        receiver_dir.normalize();
        const real_type min_dot = cross_section_edge_dir.dot(receiver_dir);
        for (size_t i = 0; i < unit_vectors.size(); i++)
                if (unit_vectors[i].dot(receiver_dir) >= min_dot)
                         count++;
        return count;
int main(int argc, char** argv)
        // Field line count
        const size_t n = 10000000000;
        cout << "Allocating memory for field lines" << endl;</pre>
        vector<vector_3> unit_vectors(n);
```

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```
for (size_t i = 0; i < n; i++)
        unit_vectors[i] = RandomUnitVector();
        static const size_t output_mod = 10000;
        if (i % output_mod = 0)
                cout << "Getting pseudorandom locations: "</pre>
                << static_cast < float > (i) / n << endl;
}
string filename = "newton.txt";
ofstream out_file(filename.c_str());
out_file << setprecision(30);
const real_type start_distance = 10.0;
const real_type end_distance = 100.0;
const size_t distance_res = 1000;
const real_type distance_step_size =
        (end_distance - start_distance)
        / (distance_{res} - 1);
for (size_t step_index = 0; step_index < distance_res; step_index++)
        const real_type r =
                start_distance +
                step_index * distance_step_size;
        const vector_3 receiver_pos(r, 0, 0);
        const real_type receiver_radius = 1.0;
        const real_type epsilon = 1.0;
        vector_3 receiver_pos_plus = receiver_pos;
        receiver_pos_plus.x += epsilon;
        const long long signed int collision_count_plus =
                get_intersecting_line_count(
                        unit_vectors,
                        receiver_pos_plus,
                        receiver_radius);
        const long long signed int collision_count =
                get_intersecting_line_count(
                        unit_vectors,
                        receiver_pos,
                        receiver_radius);
        const real_type gradient =
                static_cast < real_type >
                (collision_count_plus - collision_count)
                / epsilon;
```

2 Analytical: real field line count

const real_type emitter_area =

$$n = \frac{c^3 A}{4G\hbar \log 2}. (1)$$

Here r is the receiver radius, R is the distance from the centre of the emitter, and β is the collision count function:

$$\alpha = \frac{\beta(R+\epsilon) - \beta(R)}{\epsilon},\tag{2}$$

$$g = \frac{-\alpha}{r^2} \approx \frac{n}{2R^3},\tag{3}$$

$$g_N = \frac{nc\hbar \log 2}{4\pi M R^2} = \frac{c^4 A}{16\pi G M R^2} = \frac{GM}{R^2}.$$
 (4)

```
4.0 * pi * emitter_radius * emitter_radius;
// Field line count
// re: holographic principle:
const real_type n =
        (c3 * emitter\_area)
        / (\log (2.0) * 4.0 * G * hbar);
const real_type emitter_mass = c2 * emitter_radius / (2.0 * G);
// 1.73502e+70 is the 't Hooft-Susskind constant:
// the number of field lines for a black hole of
// unit Schwarzschild radius
//const\ real_type\ G_- =
       (c3 * pi)
        / (log(2.0) * hbar * 1.73502e + 70);
const string filename = "newton.txt";
ofstream out_file (filename.c_str());
out_file << setprecision(30);
const real_type start_distance = 10.0;
const real_type end_distance = 100.0;
const size_t distance_res = 1000;
const real_type distance_step_size =
        (end_distance - start_distance)
        / (distance_{res} - 1);
for (size_t step_index = 0; step_index < distance_res; step_index++)</pre>
        const real_type r =
                start_distance + step_index * distance_step_size;
        const vector_3 receiver_pos(r, 0, 0);
        const real_type receiver_radius = 1.0;
        const real_type epsilon = 1.0;
        vector_3 receiver_pos_plus = receiver_pos;
        receiver_pos_plus.x += epsilon;
        // https://en.wikipedia.org/wiki/Directional_derivative
        const real_type collision_count_plus =
                get_intersecting_line_count(
                        receiver_pos_plus,
                        receiver_radius);
        const real_type collision_count =
                get_intersecting_line_count(
                        receiver_pos,
```

```
receiver_radius);
        const real_type gradient =
                 (collision_count_plus - collision_count)
                 / epsilon;
        real_type gradient_strength =
                 -gradient
                 / (receiver_radius * receiver_radius);
        \mathbf{const} \ \text{real\_type} \ \text{gradient\_strength\_} =
                 n / (2.0 * pow(receiver_pos.x, 3.0));
        {f const} real_type newton_strength =
                 n * c * hbar * log(2.0)
                 (pow(receiver_pos.x, 2.0)
                         * emitter_mass * 4.0 * pi);
        const real_type newton_strength_ =
                 c4 * emitter\_area
                 / (16.0 * pi * G
                         * pow(receiver_pos.x, 2.0) * emitter_mass);
        const real_type newton_strength__ =
                 G * emitter_mass / pow(receiver_pos.x, 2.0);
        //cout \ll newton\_strength\_ / newton\_strength \ll endl;
        cout << "r: " << r << " \ gradient \ strength: "
                 << gradient_strength << endl;</pre>
        out_file << r << " " << gradient_strength << endl;
out_file.close();
return 0;
```