

Seung Jun Baek

**Topics:** Discrete-time LTI systems and DTFT

1. An LTI system has impulse response  $h[n] = 5(-1/2)^n u[n]$ . Use the Fourier transform to find the output of this system when the input is  $x[n] = (1/3)^n u[n]$ .
2. Consider an LTI system with frequency response

$$H(e^{j\omega}) = \frac{1 - e^{-j2\omega}}{1 + \frac{1}{2}e^{-j4\omega}}$$

Determine the output  $y[n]$  for all  $n$  if the input  $x[n]$  for all  $n$  is

$$x[n] = \sin\left(\frac{\pi n}{4}\right)$$

3. (a) Determine the Fourier transform of the sequence

$$r[n] = \begin{cases} 1, & 0 \leq n \leq M, \\ 0, & \text{otherwise} \end{cases}$$

- (b) Consider the sequence

$$w[n] = \begin{cases} \frac{1}{2} \left[ 1 - \cos\left(\frac{2\pi n}{M}\right) \right], & 0 \leq n \leq M, \\ 0, & \text{otherwise} \end{cases}$$

Sketch  $w[n]$  and express its DTFT  $W(e^{j\omega})$  in terms of  $R(e^{j\omega})$  which is DTFT of  $r[n]$ .

- (c) Sketch the magnitude of  $R(e^{j\omega})$  and  $W(e^{j\omega})$  for the case  $M = 4$ .

4. An LTI discrete-time system has frequency response given by

$$H(e^{j\omega}) = \frac{1}{1 - 0.8e^{-j\omega}} + \frac{e^{-j2\omega}}{1 - 0.8e^{-j\omega}}$$

- (a) Use one of the above forms of the frequency response to obtain an equation for the impulse response  $h[n]$  of the system.
- (b) From the frequency response, determine the difference equation that is satisfied by the input  $x[n]$  and the output  $y[n]$  of the system.
- (c) If the input to this system is

$$x[n] = 4 + 2\cos(\omega_0 n)$$

for what value of  $\omega_0$  will the output be of the form  $y[n] = A = \text{constant}$  for  $-\infty < n < \infty$ ? What is the constant  $A$ ?

5. Which of the following discrete-time signals could be eigenfunctions of any stable LTI system?

- (a)  $5^n u[n]$

- (b)  $e^{j2wn}$
- (c)  $e^{jwn} + e^{j2wn}$
- (d)  $5^n$
- (e)  $5^n e^{j2wn}$

6. Consider an LTI system with frequency response

$$H(e^{jw}) = e^{-j(w - \frac{\pi}{4})} \left( \frac{1 + e^{-j2w} + 4e^{-j4w}}{1 + \frac{1}{2}e^{-j2w}} \right)$$

Determine the output  $y[n]$  for all  $n$  if the input for all  $n$  is

$$x[n] = \cos\left(\frac{\pi n}{2}\right).$$

7. For  $X(e^{jw}) = 1/(1 - ae^{-jw})$ , with  $-1 < a < 0$ , determine and sketch the following as a function of  $w$  :

- (a)  $Re\{X(e^{jw})\}$
- (b)  $Im\{X(e^{jw})\}$
- (c)  $|X(e^{jw})|$
- (d)  $Arg\{X(e^{jw})\}$

8. A sequence has the discrete-time Fourier transform

$$X(e^{jw}) = \frac{1 - a^2}{(1 - ae^{-jw})(1 - ae^{jw})}, \quad |a| < 1.$$

- (a) Find the sequence  $x[n]$ .
- (b) Calculate  $\int_{-\pi}^{\pi} X(e^{jw}) \cos(w) dw / 2\pi$ .

## 1. (MATLAB):

Try to avoid using `for` or `while` loops in the code – use vectors and matrices if possible

- (a) **Plotting discrete signals:** Construct a sequence  $x[n] = \left(\frac{1}{2}\right)^n u[n]$ . Also consider impulse response of a moving average system

$$h[n] = \begin{cases} \frac{1}{M+1} & 0 \leq n \leq M \\ 0 & \text{otherwise} \end{cases}$$

When you plot discrete sequences, always use `stem` function rather than the usual `plot` function. Let  $N = 20$  and  $M = 5$ . Plot the sequences  $x[n]$  and  $h[n]$  for index vector  $0 \leq n \leq N - 1$  where  $N = 20$ . Also use `subplot` to plot two sequences in one page:  $x[n]$  above and  $h[n]$  below. (Hint: Some part of your code will look like

```
'subplot(2,1,1); stem(...); subplot(2,1,2); stem(...)'
```

- (b) **Discrete convolution:** Let  $y[n]$  be the output of the system with impulse response  $h[n]$  and input sequence  $x[n]$ . We would like to find out  $y[n]$ , and you may want to use built-in `conv` function. Also you will find that the length of output  $y[n]$  will be different from  $x[n]$  or  $h[n]$ . Plot  $y[n]$  against the index vector  $nn$  that starts from 0 and has the same length as  $y[n]$ . You might find `length` or `size` function useful.
- (c) **Computing DTFT:** Plot the magnitude and phase of the DTFT of  $x[n]$ ,  $h[n]$  and  $y[n]$ . Use `subplot` to plot magnitude and phase of each signal in one page respectively against  $\omega$  ranging from  $-3\pi$  to  $3\pi$  with the step size of  $0.01\pi$ . You should use normal `plot` function for plotting in the frequency domain. (Warning: remember vectorized coding – you should use ONLY vectors and matrices to compute DTFT!) (Hint: When computing DTFT, try to express the complex exponentials as a *matrix*.)