

Data structure [A15]

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- ▶ Application of DFS
 - ▶ Strongly connected component
 - ▶ Why this algorithm works
 - ▶ Topological sort
- ▶ Advanced BFS
 - ▶ Shortest path: Dijkstra algorithm
 - ▶ Importance of data structure for implementing algorithms

Strongly connected component

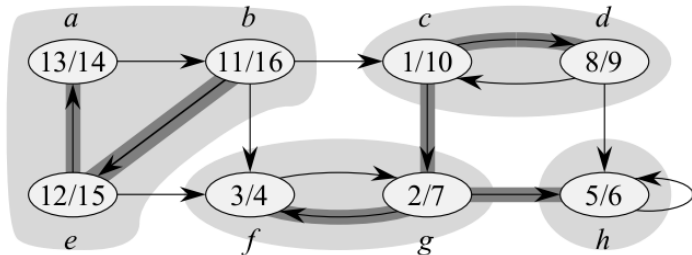


그림: Strongly connected component

Strongly connected component

STRONGLY-CONNECTED-COMPONENTS(G)

- 1 call DFS(G) to compute finishing times $u.f$ for each vertex u
- 2 compute G^T
- 3 call DFS(G^T), but in the main loop of DFS, consider the vertices in order of decreasing $u.f$ (as computed in line 1)
- 4 output the vertices of each tree in the depth-first forest formed in line 3 as a separate strongly connected component

그림: Strongly connected component algorithm

Parenthesis theorem

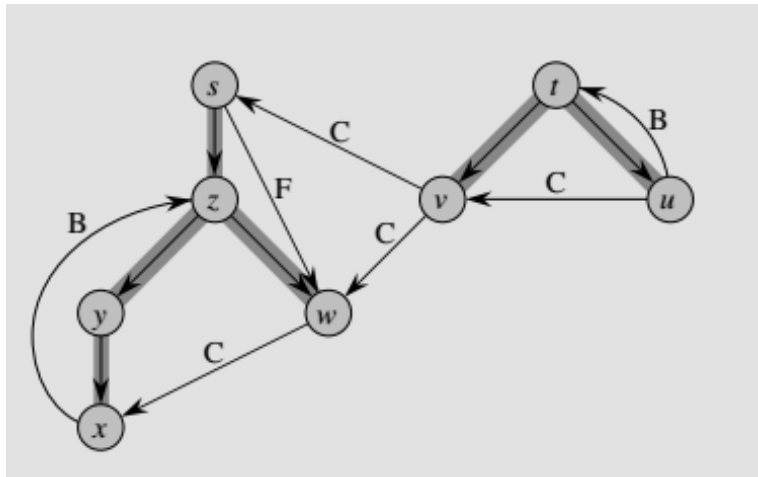


그림: d

Types of edges

1. **Tree edges** are edges in the depth-first forest G_π . Edge (u, v) is a tree edge if v was first discovered by exploring edge (u, v) .
2. **Back edges** are those edges (u, v) connecting a vertex u to an ancestor v in a depth-first tree. We consider self-loops, which may occur in directed graphs, to be back edges.
3. **Forward edges** are those nontree edges (u, v) connecting a vertex u to a descendant v in a depth-first tree.
4. **Cross edges** are all other edges. They can go between vertices in the same depth-first tree, as long as one vertex is not an ancestor of the other, or they can go between vertices in different depth-first trees.

그림: q

Parenthesis theorem

Theorem 22.7 (Parenthesis theorem)

In any depth-first search of a (directed or undirected) graph $G = (V, E)$, for any two vertices u and v , exactly one of the following three conditions holds:

- the intervals $[u.d, u.f]$ and $[v.d, v.f]$ are entirely disjoint, and neither u nor v is a descendant of the other in the depth-first forest,
- the interval $[u.d, u.f]$ is contained entirely within the interval $[v.d, v.f]$, and u is a descendant of v in a depth-first tree, or
- the interval $[v.d, v.f]$ is contained entirely within the interval $[u.d, u.f]$, and v is a descendant of u in a depth-first tree.

그림: a

Parenthesis theorem

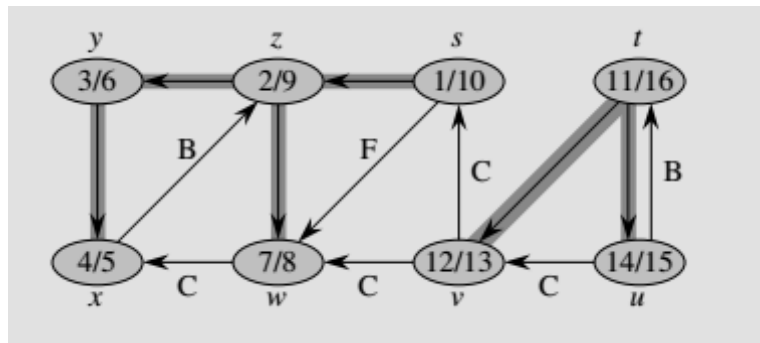


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Parenthesis theorem

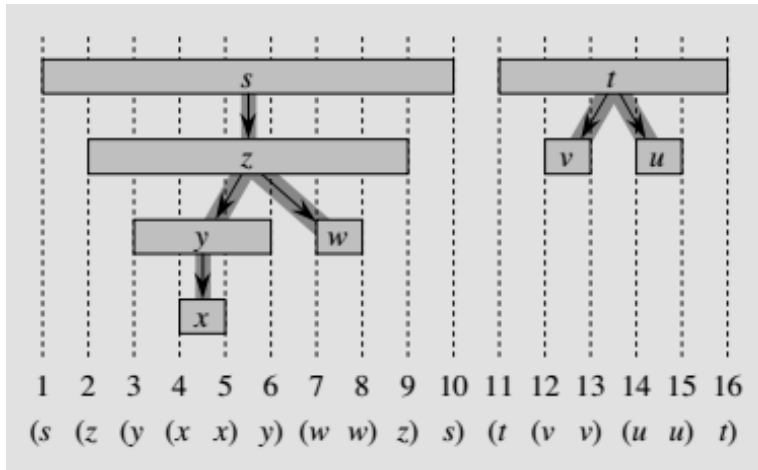


그림: c

Strongly connected component

Lemma 22.13

Let C and C' be distinct strongly connected components in directed graph $G = (V, E)$, let $u, v \in C$, let $u', v' \in C'$, and suppose that G contains a path $u \rightsquigarrow u'$. Then G cannot also contain a path $v' \rightsquigarrow v$.

그림: m

Strongly connected component

Lemma 22.14

Let C and C' be distinct strongly connected components in directed graph $G = (V, E)$. Suppose that there is an edge $(u, v) \in E$, where $u \in C$ and $v \in C'$. Then $f(C) > f(C')$.

그림: n

Strongly connected component

Corollary 22.15

Let C and C' be distinct strongly connected components in directed graph $G = (V, E)$. Suppose that there is an edge $(u, v) \in E^T$, where $u \in C$ and $v \in C'$. Then $f(C) < f(C')$.

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Topological sort

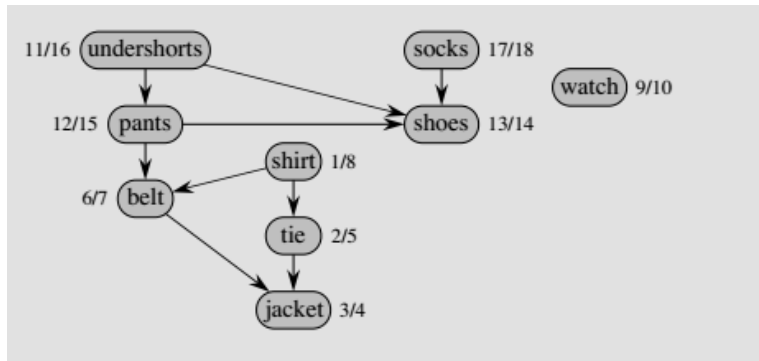


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Topological sort

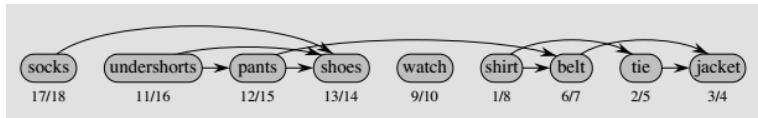


그림: k

Topological sort

TOPOLOGICAL-SORT(G)

- 1 call DFS(G) to compute finishing times $v.f$ for each vertex v
- 2 as each vertex is finished, insert it onto the front of a linked list
- 3 **return** the linked list of vertices

그림: |

Single source shortest path

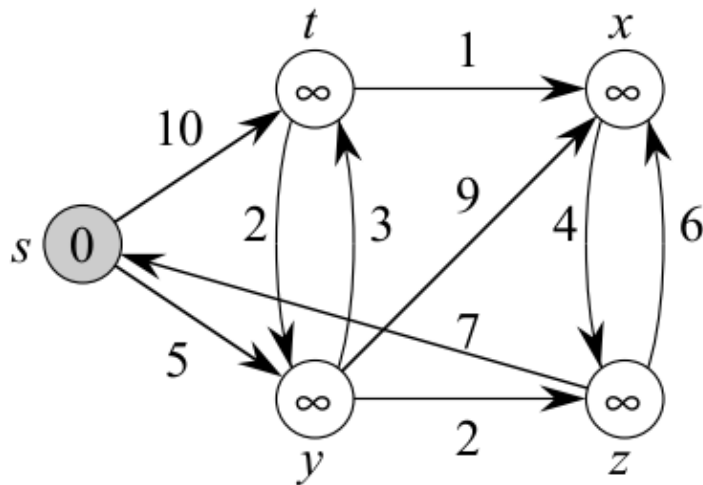


그림: Problem

Single source shortest path

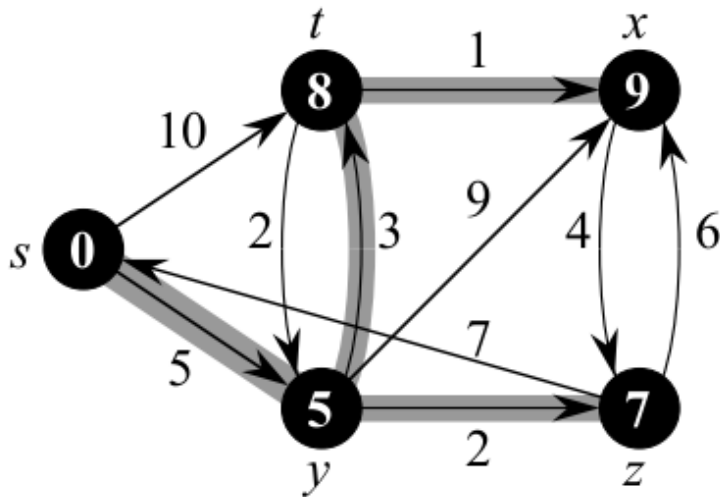


그림: Solution

Administrivia

- ▶ 기말고사: 6/19 (월) 12:00-13:40
- ▶ Final project
 - ▶ Due: 6/22 (목)
 - ▶ red black tree 를 확장하여 string 을 다루도록 하시오
- ▶ 수요일 수업: 보강
 - ▶ 질의/응답

Dijkstra algorithm

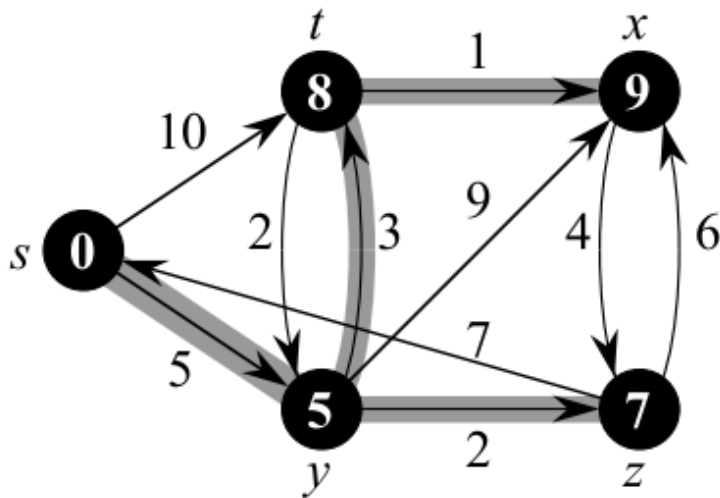
DIJKSTRA(G, w, s)

```
1  INITIALIZE-SINGLE-SOURCE( $G, s$ )
2   $S = \emptyset$ 
3   $Q = G.V$ 
4  while  $Q \neq \emptyset$ 
5       $u = \text{EXTRACT-MIN}(Q)$ 
6       $S = S \cup \{u\}$ 
7      for each vertex  $v \in G.Adj[u]$ 
8          RELAX( $u, v, w$ )
```

그림: Dijkstra algorithm

Dijkstra algorithm (6/6)

- ▶ $G_w = (V, E, w)$



Single source shortest path

```
g = Dijkstra()  
s = g.add_vertex('s')  
...  
z = g.add_vertex('z')  
s.add(t, 10)  
...  
z.add(x, 6)  
s.d = 0  
g.shortest_path()  
g.print_vertices()
```

Shortest path algorithm

```
class Dijkstra:
    def shortest_path(self):
        q = self.q
        vset = self.vertices
        for v in vset:
            n = PrioNode(v.d, v.n)
            v.set_priority(n)
            q.insert(n)
        while not q.is_empty():
            u = q.extract()
            self.relax(vset[u.n])
```

Decrease key

```
class MinQueue(MaxQueue):  
    def decrease_key(self, i, key):  
        A = self.A  
        if key > A[i].key:  
            print ("Error")  
            sys.exit(-1)  
        A[i].key = key  
        self.update_key(i)
```

Implement decrease key

```
class DijkVertex(Vertex):  
    def decrease_key(self, q):  
        prio = self.priority  
        ndx = prio.ndx  
        q.decrease_key(ndx, self.d)
```


Do not trust google

```
def dijkstra(graph, initial):  
    visited = {'initial': 0}  
    path = {}  
    nodes = set(graph.nodes)  
    while nodes:  
        min_node = find_min(nodes)  
        nodes.remove(min_node)  
        current_weight = visited[min_node]  
  
        relax(graph, visited, current_weight, min_node)  
    return visited, path
```

The Devil is in the detail

```
def find_min(nodes, visited):  
    min_node = None  
    for node in nodes:  
        if node in visited:  
            if min_node is None:  
                min_node = node  
            elif visited[node] < visited[min_node]:  
                min_node = node  
    return min_node
```

Extract-min

- ▶ 모든 vertex 를 queue 에 저장
- ▶ 가장 앞에는 가장 작은 d 값을 갖는 vertex 가 저장됨
- ▶ 이 vertex 주변의 vertex 의 d 값을 조정
- ▶ 조정된 값을 기반으로 queue 에서의 순서가 바뀜

→ 정렬될 필요가 있을까? 없다 (Heap 이면 충분)

Priority queue

- ▶ `q.insert(v)`
- ▶ `q.extract_min()` $\rightarrow v$
- ▶ `q.decrease_key(v)`

Priority queue (min)

- ▶ insert(x)
- ▶ minimum()
- ▶ extract-min()
- ▶ decrease-key(i)
- ▶ empty()

Priority queue

```
def main():  
    print("---- main ----")  
    q = MinQueue()  
    q.insert(PrioNode(0, 8))  
    q.insert(PrioNode(1, 4))  
    print(q.A)  
    q.decrease_key(1, 1)  
    print(q.A)
```

Priority node

```
class PrioNode:
    def __init__(self, n, key):
        self.n = n
        self.key = key
    def __repr__(self):
        return "(%d:%d,%d)" % (self.ndx, self.n, self.l)
```

Min queue

```
class MinQueue(MaxQueue):  
    def __init__(self):  
    def compare(self, a, b):  
    def update_key(self, i):  
    def decrease_key(self, i, key):
```


Max queue

```
class MaxQueue(Heap):  
    def __init__(self):  
    def compare(self, a, b):  
    def exchange(self, i, j):  
    def update_key(self, i):  
    def increase_key(self, i, key):  
    def insert(self, n):  
    def extract(self):  
    def empty(self):
```

Heap

```
class Heap:
    def __init__(self):
    def parent(self, n):
    def left(self, n):
    def right(self, n):
    def compare(self, a, b):
    def exchange(self, i, j):
    def heapify(self, i):
```

Dijkstra algorithm (1/6)

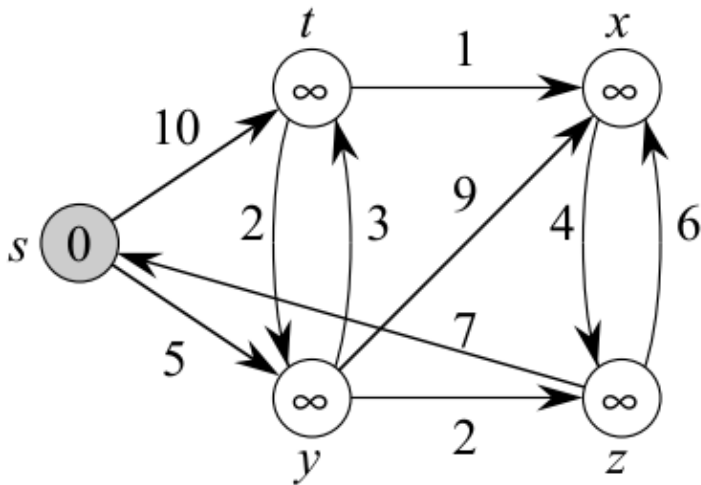


그림: Dijkstra algorithm (1/6)

Dijkstra algorithm (2/6)

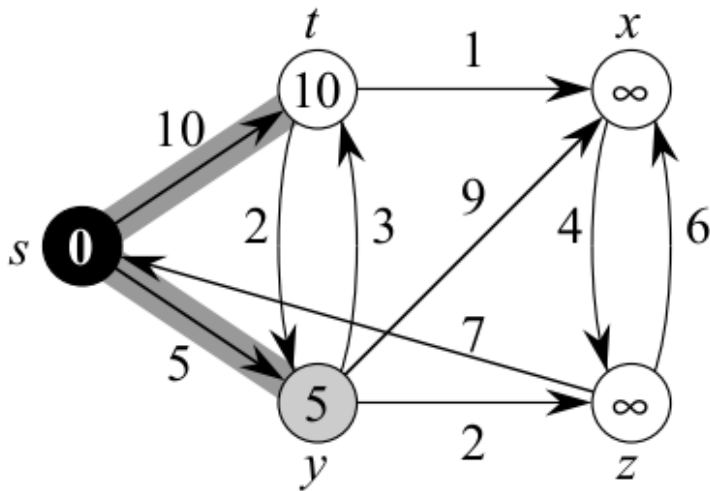


그림: Dijkstra algorithm (2/6)

Dijkstra algorithm (3/6)

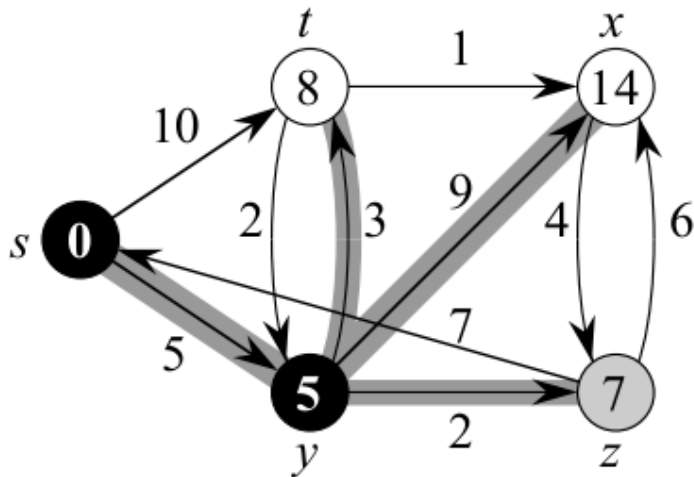


그림: Dijkstra algorithm (3/6)

Dijkstra algorithm (4/6)

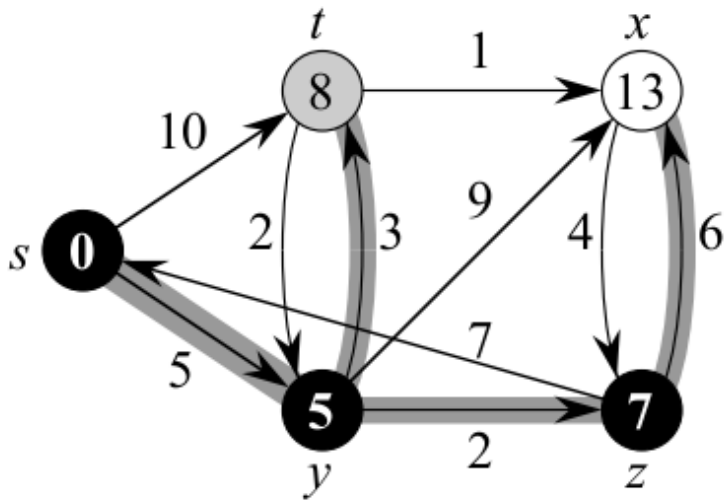


그림: Dijkstra algorithm (4/6)

Dijkstra algorithm (5/6)

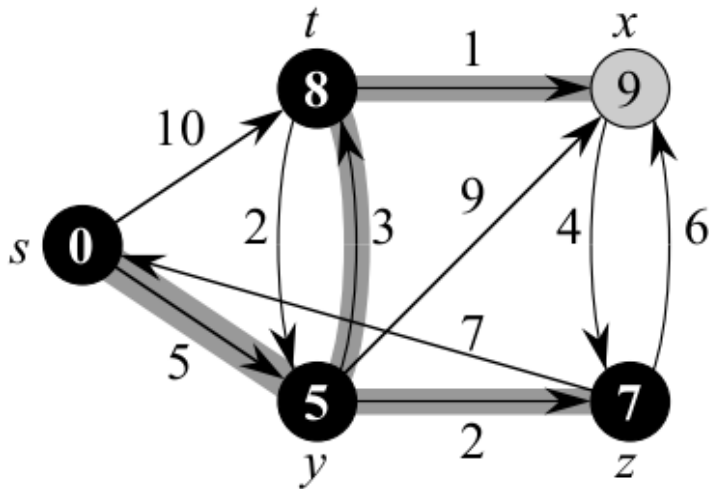


그림: Dijkstra algorithm (5/6)

Dijkstra algorithm (6/6)

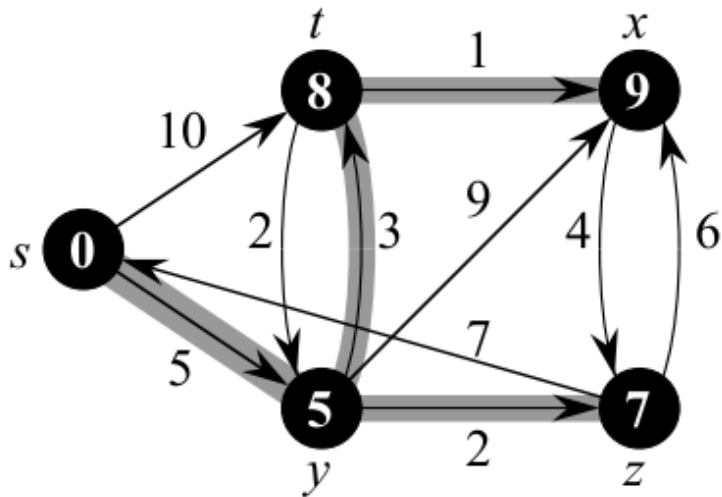


그림: Dijkstra algorithm (6/6)

Wrap-up (1/2)

- ▶ We reviewed applications of DFS
 - ▶ Why strongly connected components work
 - ▶ How to sort partially ordered relations
- ▶ We extended BFS
 - ▶ Single source shortest path algorithm (a.k.a, Dijkstra algorithm)

Wrap-up (2/2)

- ▶ We learned that algorithm description is based on abstract data type
 - ▶ A line in an algorithm usually translated to a data structure operation
 - ▶ The complexity of an algorithm is determined by this single line, i.e., an operation performed on a **data structure**
 - ▶ Data structure is usually hidden in algorithm description but plays very important role in software development in general