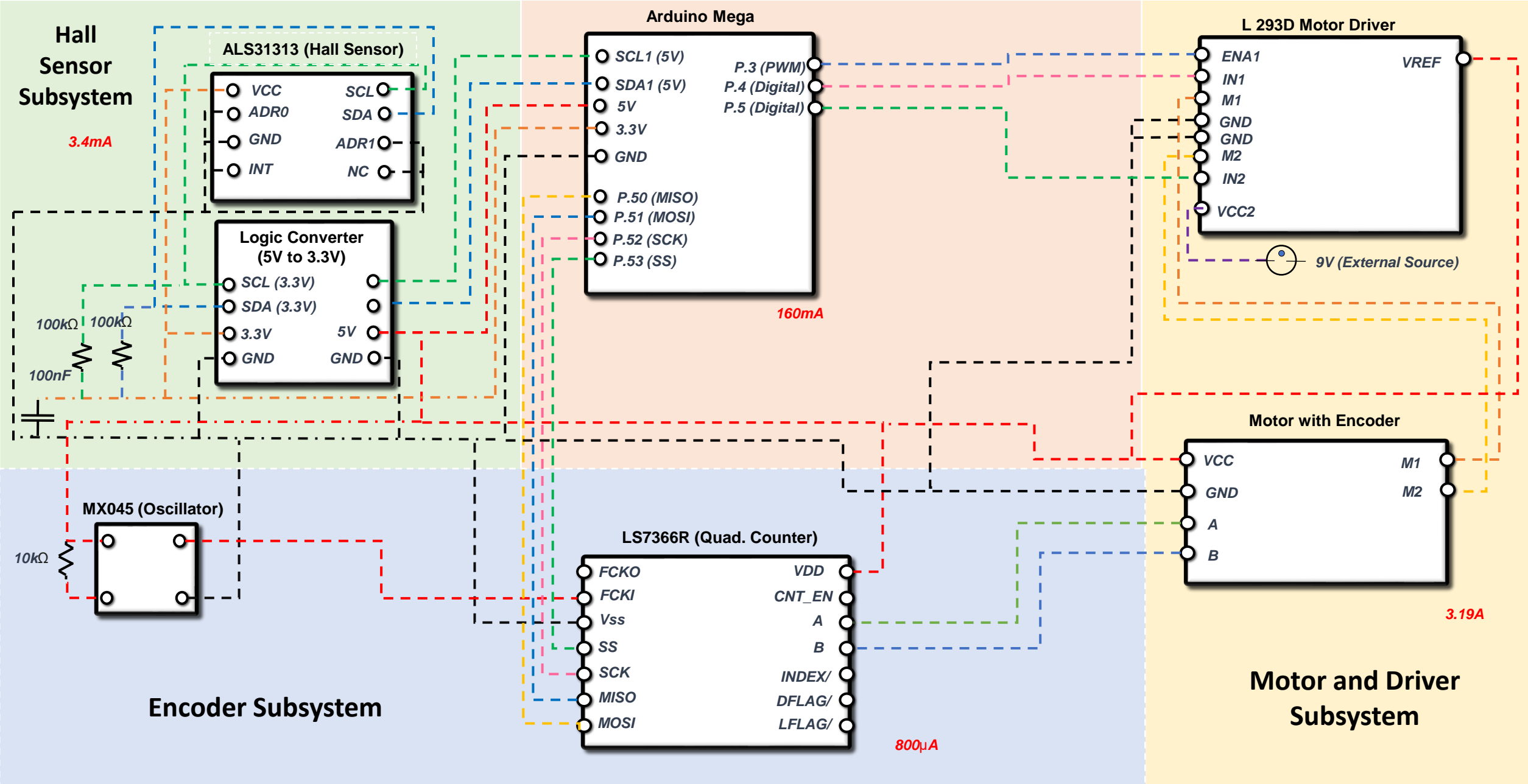


Electrical Design: System Circuit Diagram



System State Machine

State 0 : Waiting for Button Press, Polling



State 1 : Start Timer1 to enable encoder readings



State 2 : PI Control to Move Motor until desired reference angle

Button Press



State 5 : Outputting and Reading Hall Sensor Data



State 4 : Start MsTimer2 for Hall Sensor Reading



State 3 : Waiting for Button Press, Polling



Error (Reference Angle – Encoder Reading) < ± 2 degree