view frames Result Recorded at time: 1613810590.471 map Broadcaster: /lio_sam_imuPreintegration Average rate: 500.150 Hz Most recent transform: 1574795931.725 (39014658.747 sec old) Buffer length: 4.992 sec odom Broadcaster: /lio_sam_imuPreintegration Broadcaster: /lio_sam_mapOptmization Average rate: 5.164 Hz Average rate: 500.150 Hz Most recent transform: 1574795931.725 (39014658.747 sec old) Most recent transform: 1574795931.179 (39014659.293 sec old) Buffer length: 4.992 sec Buffer length: 4.841 sec lidar_link base_link Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1613810590.471 sec old) Buffer length: 0.000 sec chassis link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1613810590.471 sec old) Most recent transform: 0.000 (1613810590.471 sec old) Most recent transform: 0.000 (1613810590.471 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec imu_link navsat link velodyne