Project Proposal Rubric

(proposals due by 03/02/20, 6pm)

Partner (if applicable)

Title of Project

Goal or Objective

Machine Learning method to be used

Brief description of robot, simulation, plant to be controlled

Method of control you will use (e.g., deadbeat, forward model, inverse model, MPC, receding horizon, …). Discuss how the ML technique/model will be used to learn the control mapping, or be used by the controller.

Programming language to be used