Introduction

This is the project report for the final course project.

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Github: https://github.com/sjoslin2/Spring-24-DLH

Video: Link to the google drive

Paper 33 - ScoEHR: Generating Synthetic Electronic Health Records using Continuous-time Diffusion Models[1] https://www.mlforhc.org/s/ID145_Research-Paper_2023.pdf

· Background of the problem

Patient health data, mainly kept in electronic health records (EHRs), plays a crucial role in the healthcare sector, with its increase in usage rates in hospitals across both the US and UK. EHRs include both structured and unstructured data, from patient demographics to medical images, enabling extensive analysis to unveil disease progression and health trends. Leveraging EHRs, predictive and prescriptive machine learning models have revolutionized patient care, predicting outcomes and disease severity with high accuracy. However, sharing EHRs remains constrained by regulatory frameworks like HIPAA and GDPR, compounded by challenges in aggregating EHRs due to varying standards and policies. Synthetic data generation offers a solution, addressing access and bias issues. However, generating synthetic EHRs is complex due to high dimensionality and data heterogeneity. While generative Adversarial Networks (GANs) have been popular, they face challenges like mode collapse and unstable training. Recently, diffusion models have emerged as promising alternatives, offering stable training and high-fidelity data synthesis, making them ideal for synthetic EHR generation.

Paper explanation

This paper introduces ScoEHR, a synthetic EHR generation framework employing continuous-time diffusion models. ScoEHR combines an autoencoder with a continuous-time diffusion model. The ScoEHR transforms real data into a low-dimensional space through an encoder from a pre-trained autoencoder. Within this low-dimensional space, a forward stochastic differential equation (SDE) diffuses the data. Subsequently, a reverse SDE is learned and applied to generate new synthetic data. This synthetic data is then transformed using the decoder from the autoencoder to produce the final synthetic EHR data. ScoEHR was compared to medGAN, medWGAN, and medBGAN using the following four performance metrics of data generation utility:

- Preservation of feature marginal relationships,
- Preservation of feature correlations,

- Preservation of full feature distribution using log-clusters,
- Synthetic data performance in downstream predictions of patient outcomes.

Additionally, Physician evaluation confirms its realism, establishing ScoEHR as the current state-of-the-art in synthetic EHR generation.

Scope of Reproducibility

There are two central hypotheses that were tested as a part of this paper: ScoEHR produces higher-quality synthetic data than the previously-leading synthetic EHR models and United States board-certified physicians cannot differentiate between the synthetic data produced by ScoEHR and real EHR data.

- 1. Hypothesis 1:
- Hypothesis: The first hypothesis was tested by comparing ScoEHR against the three-leading synthetic EHR models (medGAN[2], medWGAN[3], and medBGAN[3]) on four key areas: preservation of feature marginal relationships, preservation of feature correlations, preservation of full feature distributing using log-clusters, and synthetic data performance in downstream predictions of patient outcomes.
- Scope of Reproducibility: While we were not successful at fully replicating the aforementioned hypothesis using the MIMIC-III dataset, our results were better than two of the three leading synthetic EHR models (medGAN[2] and medBGAN[3]) and our outcomes were similar to the results provided in the paper (though they weren't as good on some key metrics, they were within the right order of magnitude). The results are discussed in detail in the results and discussion section of this report.
- 1. Hypothesis 2:
- **Hypothesis:** The second hypothesis was tested by presenting both synthetic and real EHR data to physicians and asking them to identify the "real" data. By looking at what portion of synthetic data they identified as "real" and comparing it with the portion of real data they identified as "real" the authors were able to determine that physicians were not able to tell the difference between the synthetic and real data.
- **Scope of Reproducibility:** This was infeasible without real doctors available to validate the authenticity of synthetic records.

Methodology

The Methodology section consists of 5 sub-sections:

- Environment
- Data
- Model
- Training
- Evaluation

For each sub-section, a description/explanation of that sub-section is given as well as implementation code.

Environment

Python Version

Python 3.10.12

!python --version

Python 3.10.12

Manual Setup Needed

In order to run this notebook, you will need to:

- 1. Ensure that you downloaded it from the github repository. This means that you should see the following folders:
- ./ablation_saved_models/ This is where the saved Score Net models for the learning rate/epoch ablations live.
- ./ablation_synthetic_data/ This is where the synthetic data generated by the ablation models live.
- ./additional_workbooks/ contains the additional notebooks that contains the data preprocessing and loading synthetic data using pyHealth.
- ./mimic/ Folder where you need to manually add the MIMIC-III data files (detailed instructions in Data sub-section).
- ./saved_models/ This is where the saved Autoencoder and Score Net model parametres live.
- ./stats/ This contains stats information around the model training. If you train these models from scratch then your model trainings stats are displayed instead.
- ./synthetic_data/ This contains synthetic data generated by the model. If you want to generate your own synthetic data you'll need ~30 minutes of GPU time.
- 1. Ensure you have added the MIMIC-III data files into the ./mimic/ folder (detailed instructions in the Data sub-section).

Running This Notebook on Colab

If you would like to run this notebook in Colab, place it and all of the files from the github repository into a "ScoEHR" folder in your Google Drive.

Running This Notebook Without Colab

Make sure this notebook is in the same folder as all of the other files from the github repository.

Dependencies and Packages

This section installs all required modules and imports them for later use. If you are running this notebook in Colab, please install torchsde. Otherwise, please install all the required packages using requirements.txt using the command below. pip3 install -r requirements.txt

```
!pip install torchsde
Collecting torchsde
  Downloading torchsde-0.2.6-py3-none-any.whl (61 kB)
                                       — 61.2/61.2 kB 737.9 kB/s eta
0:00:00
ent already satisfied: numpy>=1.19 in /usr/local/lib/python3.10/dist-
packages (from torchsde) (1.25.2)
Requirement already satisfied: scipy>=1.5 in
/usr/local/lib/python3.10/dist-packages (from torchsde) (1.11.4)
Requirement already satisfied: torch>=1.6.0 in
/usr/local/lib/python3.10/dist-packages (from torchsde) (2.2.1+cu121)
Collecting trampoline>=0.1.2 (from torchsde)
  Downloading trampoline-0.1.2-py3-none-any.whl (5.2 kB)
Requirement already satisfied: filelock in
/usr/local/lib/python3.10/dist-packages (from torch>=1.6.0->torchsde)
(3.14.0)
Requirement already satisfied: typing-extensions>=4.8.0 in
/usr/local/lib/python3.10/dist-packages (from torch>=1.6.0->torchsde)
(4.11.0)
Requirement already satisfied: sympy in
/usr/local/lib/python3.10/dist-packages (from torch>=1.6.0->torchsde)
(1.12)
Requirement already satisfied: networkx in
/usr/local/lib/python3.10/dist-packages (from torch>=1.6.0->torchsde)
(3.3)
Requirement already satisfied: jinja2 in
/usr/local/lib/python3.10/dist-packages (from torch>=1.6.0->torchsde)
(3.1.3)
Requirement already satisfied: fsspec in
/usr/local/lib/python3.10/dist-packages (from torch>=1.6.0->torchsde)
(2023.6.0)
Collecting nvidia-cuda-nvrtc-cu12==12.1.105 (from torch>=1.6.0-
>torchsde)
  Using cached nvidia cuda nvrtc cu12-12.1.105-py3-none-
manylinux1 x86 64.whl (23.7 MB)
Collecting nvidia-cuda-runtime-cu12==12.1.105 (from torch>=1.6.0-
>torchsde)
  Using cached nvidia cuda runtime cu12-12.1.105-py3-none-
manylinux1 x86 64.whl (823 kB)
Collecting nvidia-cuda-cupti-cul2==12.1.105 (from torch>=1.6.0-
>torchsde)
  Using cached nvidia cuda cupti cu12-12.1.105-py3-none-
manylinux1 x86 64.whl (14.1 MB)
Collecting nvidia-cudnn-cu12==8.9.2.26 (from torch>=1.6.0->torchsde)
  Using cached nvidia cudnn cu12-8.9.2.26-py3-none-
manylinux1 x86 64.whl (731.7 MB)
Collecting nvidia-cublas-cu12==12.1.3.1 (from torch>=1.6.0->torchsde)
  Using cached nvidia cublas cu12-12.1.3.1-py3-none-
manylinux1 x86 64.whl (410.6 MB)
```

```
Collecting nvidia-cufft-cu12==11.0.2.54 (from torch>=1.6.0->torchsde)
  Using cached nvidia cufft cu12-11.0.2.54-py3-none-
manylinux1 x86 64.whl (121.6 MB)
Collecting nvidia-curand-cu12==10.3.2.106 (from torch>=1.6.0-
>torchsde)
  Using cached nvidia curand cu12-10.3.2.106-py3-none-
manylinux1 x86 64.whl (56.5 MB)
Collecting nvidia-cusolver-cu12==11.4.5.107 (from torch>=1.6.0-
>torchsde)
  Using cached nvidia cusolver cu12-11.4.5.107-py3-none-
manylinux1 x86 64.whl (124.2 MB)
Collecting nvidia-cusparse-cu12==12.1.0.106 (from torch>=1.6.0-
>torchsde)
  Using cached nvidia cusparse cu12-12.1.0.106-py3-none-
manylinux1 x86 64.whl (196.0 MB)
Collecting nvidia-nccl-cu12==2.19.3 (from torch>=1.6.0->torchsde)
  Using cached nvidia nccl cu12-2.19.3-py3-none-manylinux1 x86 64.whl
(166.0 MB)
Collecting nvidia-nvtx-cul2==12.1.105 (from torch>=1.6.0->torchsde)
  Using cached nvidia nvtx cu12-12.1.105-py3-none-
manylinux1 x86 64.whl (99 kB)
Requirement already satisfied: triton==2.2.0 in
/usr/local/lib/python3.10/dist-packages (from torch>=1.6.0->torchsde)
(2.2.0)
Collecting nvidia-nvjitlink-cu12 (from nvidia-cusolver-
cu12==11.4.5.107->torch>=1.6.0->torchsde
  Using cached nvidia nvjitlink cu12-12.4.127-py3-none-
manylinux2014 x86 64.whl (21.1 MB)
Requirement already satisfied: MarkupSafe>=2.0 in
/usr/local/lib/python3.10/dist-packages (from jinja2->torch>=1.6.0-
>torchsde) (2.1.5)
Requirement already satisfied: mpmath>=0.19 in
/usr/local/lib/python3.10/dist-packages (from sympy->torch>=1.6.0-
>torchsde) (1.3.0)
Installing collected packages: trampoline, nvidia-nvtx-cu12, nvidia-
nvjitlink-cu12, nvidia-nccl-cu12, nvidia-curand-cu12, nvidia-cufft-
cu12, nvidia-cuda-runtime-cu12, nvidia-cuda-nvrtc-cu12, nvidia-cuda-
cupti-cu12, nvidia-cublas-cu12, nvidia-cusparse-cu12, nvidia-cudnn-
cu12, nvidia-cusolver-cu12, torchsde
Successfully installed nvidia-cublas-cu12-12.1.3.1 nvidia-cuda-cupti-
cu12-12.1.105 nvidia-cuda-nvrtc-cu12-12.1.105 nvidia-cuda-runtime-
cu12-12.1.105 nvidia-cudnn-cu12-8.9.2.26 nvidia-cufft-cu12-11.0.2.54
nvidia-curand-cu12-10.3.2.106 nvidia-cusolver-cu12-11.4.5.107 nvidia-
cusparse-cu12-12.1.0.106 nvidia-nccl-cu12-2.19.3 nvidia-nvjitlink-
cu12-12.4.127 nvidia-nvtx-cu12-12.1.105 torchsde-0.2.6 trampoline-
0.1.2
# Import all the required packages
import torch
import os
```

```
import tqdm
import math
import time
import torchsde
import qc
import sklearn.cluster
import numpy as np
import torch.nn.functional as F
import _pickle as pickle
import pandas as pd
from torch import nn
from torch.utils.data import DataLoader
from torch.nn.init import calculate fan in and fan out
from torch.optim import lr scheduler
import torch.nn.functional as F
from sklearn.model selection import train test split
from datetime import datetime
from matplotlib import pyplot
import matplotlib.pyplot as plt
# Mount the google drive.
try:
  import google.colab
  IN COLAB = True
except:
  IN COLAB = False
device = "cuda" if torch.cuda.is_available() else "cpu"
if IN COLAB:
  from google.colab import drive
  drive.mount('/content/drive')
  file location = "/content/drive/MyDrive/ScoEHR/"
else:
  file location = "."
Mounted at /content/drive
```

Data

Data Download Instructions

We are using MIMIC-III dataset from physionet -> https://physionet.org/content/mimiciii/1.4/.

Please follow the instructions in piazza post #338 to access the MIMIC-III dataset. Download and decompress the following two csv files and place them in the ./mimic folder:

ADMISSIONS.csv

DIAGNOSES ICD.csv

Data Descriptions

MIMIC-III critical care database is an freely accessible database containing de-identified health data associated with approximately 40,000 patients who stayed in intensive care units at the Beth Israel Deaconess Medical Center between 2001 and 2012. There has been several versions of the MIMIC-III database since it was released. Current version of the dataset is MIMIC-III v1.4 released on 2nd September 2016 which majorly focused on enhancement of data quality and providing addition of large amount of data.

MIMIC-III is a relational database consisting of 26 tables, out of which only 2 tables namely ADMISSIONS and DIAGNOSES_ICD are used for this project. Tables are linked by identifiers which usually have the suffix 'ID'. For example, SUBJECT_ID refers to a unique patient and HADM_ID refers to a unique admission to the hospital.

The **ADMISSIONS** table contains several columns, including <code>row_id</code>, <code>subject_id</code>, <code>hadm_id</code>, <code>admittime</code>, <code>dischtime</code>, <code>deathtime</code>, <code>admission_type</code>, <code>admission_location</code>, <code>discharge_location</code>, <code>insurance</code>, <code>language</code>, <code>religion</code>, <code>marital_status</code>, <code>ethnicity</code>, <code>edregtime</code>, <code>edouttime</code>, <code>diagnosis</code>, <code>hospital_expire_flag</code>, <code>and has_chartevents_data</code>. However, for this project, we focus on only three columns: <code>subject_id</code>, <code>hadm_id</code>, <code>and admittime</code>. The hadm_id , which identifies the hospital stay serves as the primary key and the subject_id is the foriegn key for the ADMISSIONS table. A patient with multiple admissions will have duplicate subject_id entries for the same hadm_id. The admittime column represents the time of admission to the hospital.

The **DIAGNOSES_ICD** consists of following columns: *row_id*, *subject_id*, *hadm_id*, *seq_num*, *icd9_code*. For this project, we are only utilizing two columns: *hadm_id* and*** icd9_code***. The icd9_code colum provides the diagnoses code.

Statistics of MIMIC-III dataset:

Dataset: MIMIC3Dataset
Number of patients: 49993
Number of visits: 52769

Number of visits per patient: 1.0555

Number of events per visit in DIAGNOSES_ICD: 9.1038

Data Preprocessing

For the MIMIC-III dataset, we follow the data preprocessing methodology outlined by Choi et al. (2017). The code below processes the MIMIC-III dataset, creating longitudinal diagnosis records for patients and saves the serialized data to a file using pickle. It involves reading the ADMISSIONS.csv and DIAGNOSES_ICD.csv files, generalizing the ICD-9 codes up to the first three digit codes, and then generating the longitudinal diagnosis patient records. The resulting matrix file comprises one row per patient and one column per ICD code (later treated as features). Each row represents the count of occurrences of the corresponding patient's EHR containing the ICD code in their visits. If the patient's EHR never includes the ICD code across any visits, a '0' is placed in the column.

Set generate_matrix_file = True (default) to generate the preprocessed .matrix file required for training the model and/or comparing the real and synthetic data).

```
# Modified from:
https://github.com/mp2893/medgan/blob/master/process mimic.py
admissionFile = os.path.join(file location, 'mimic/ADMISSIONS.csv')
diagnosisFile = os.path.join(file location, 'mimic/DIAGNOSES ICD.csv')
outFile = os.path.join(file location,
'mimic/mimic processed choi count.matrix')
generate matrix file = True
def convert to icd9(dxStr):
    if dxStr.startswith('E'):
        if len(dxStr) > 4: return dxStr[:4] + '.' + dxStr[4:]
        else: return dxStr
    else:
        if len(dxStr) > 3: return dxStr[:3] + '.' + dxStr[3:]
        else: return dxStr
def convert to 3digit icd9(dxStr):
    if dxStr.startswith('E'):
        if len(dxStr) > 4: return dxStr[:4]
        else: return dxStr
        if len(dxStr) > 3: return dxStr[:3]
        else: return dxStr
if generate matrix file:
    binary count = 'count'
    print('Building pid-admission mapping, admission-date mapping')
    pidAdmMap = {}
    admDateMap = \{\}
    infd = open(admissionFile, 'r')
    infd.readline()
    for line in infd:
        tokens = line.strip().split(',')
        pid = int(tokens[1])
        admId = int(tokens[2])
        admTime = datetime.strptime(tokens[3], '%Y-%m-%d %H:%M:%S')
        admDateMap[admId] = admTime
        if pid in pidAdmMap: pidAdmMap[pid].append(admId)
        else: pidAdmMap[pid] = [admId]
    infd.close()
    print('Building admission-dxList mapping')
    admDxMap = \{\}
    infd = open(diagnosisFile, 'r')
```

```
infd.readline()
    for line in infd:
        tokens = line.strip().split(',')
        admId = int(tokens[2])
        # Uncomment this line and comment the line below, if you want
to use the entire ICD9 digits.
        \# dxStr = 'D' + convert to icd9(tokens[4][1:-1])
        dxStr = 'D' + convert to 3digit icd9(tokens[4][1:-1])
        if admId in admDxMap: admDxMap[admId].append(dxStr)
        else: admDxMap[admId] = [dxStr]
    infd.close()
    print('Building pid-sortedVisits mapping')
    pidSeqMap = \{\}
    for pid, admIdList in pidAdmMap.items():
        #if len(admIdList) < 2: continue
        sortedList = sorted([(admDateMap[admId], admDxMap[admId]) for
admId in admIdListl)
        pidSeqMap[pid] = sortedList
    print('Building pids, dates, strSegs')
    pids = []
    dates = []
    seas = []
    for pid, visits in pidSeqMap.items():
        pids.append(pid)
        seq = []
        date = []
        for visit in visits:
            date.append(visit[0])
            seq.append(visit[1])
        dates.append(date)
        seqs.append(seq)
    print('Converting strSeqs to intSeqs, and making types')
    types = \{\}
    newSeqs = []
    for patient in segs:
        newPatient = []
        for visit in patient:
            newVisit = []
            for code in visit:
                if code in types:
                    newVisit.append(types[code])
                else:
                    types[code] = len(types)
                    newVisit.append(types[code])
            newPatient.append(newVisit)
        newSegs.append(newPatient)
```

```
print('Constructing the matrix')
    numPatients = len(newSeqs)
    numCodes = len(types)
    matrix = np.zeros((numPatients, numCodes)).astype('float32')
    for i, patient in enumerate(newSegs):
        for visit in patient:
            for code in visit:
                if binary count == 'binary':
                    matrix[i][code] = 1.
                else:
                    matrix[i][code] += 1.
    pickle.dump(matrix, open(outFile, 'wb'), -1)
    print('Matrix construction complete')
Building pid-admission mapping, admission-date mapping
Building admission-dxList mapping
Building pid-sortedVisits mapping
Building pids, dates, strSeqs
Converting strSeqs to intSeqs, and making types
Constructing the matrix
Matrix construction complete
```

Define DataLoader Class

Used to create Datasets and Dataloaders to pull data from the generated .matrix file

```
# Modified from
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/datasets.py
class Dataset():
    def init (self, data dir, data file):
    def data(self, use train test split=True, test size=0.30):
        if use train test split:
            train_data, test_data = train_test_split(
                self.dataset full, test size=test size, random state=1
            return train data, test data
        else:
            return self.dataset full
class MIMIC3 ICD(Dataset):
    def init (
        self, data file="mimic/mimic processed choi count.matrix"
    ):
        """Loads the MIMIC-III dataset from the data directory."""
        data path = os.path.join(file_location, data_file)
```

```
data = np.load(data_path, allow_pickle=True)
self.dataset_full = torch.from_numpy(data)
```

Load the Data

Load the .matrix file and generated train and test dataloaders.

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/main.py
load data = True
batch size = 64
if load data:
    data file = 'mimic/mimic processed choi count.matrix'
    train data, test data = MIMIC3 ICD(data file=data file).data()
    real = test data.detach()
    train data = train data.to(device)
    test data = test data.to(device)
    train dataloader = DataLoader(dataset=train data,
batch size=batch size, drop last=True)
    test dataloader = DataLoader(dataset=test data,
batch_size=batch_size, drop_last=True)
    print("Train Data Shape: ", train_data.shape)
print("Test Data Shape: ", test_data.shape)
Train Data Shape: torch.Size([32564, 1071])
Test Data Shape: torch.Size([13956, 1071])
```

Model

Citation to the original paper

Naseer, AA; Walker, B; Landon, C; Ambrosy, A; Fudim, M; Wysham, N; Toro, B; Swaminathan, S; Lyons, T. ScoEHR: Generating Synthetic Electronic Health Records using Continuous-time Diffusion Models. *Proceedings of Machine Learning Research*, Volume 219: 489–508, January 2023.[1]

URL: https://static1.squarespace.com/static/59d5ac1780bd5ef9c396eda6/t/64d1aa32ed57852af9c0ad60/1691462195379/ID145_Research+Paper_2023.pdf

Link to the original paper's repo

https://github.com/aanaseer/ScoEHR/tree/main/scoehr

Model Description

The synthetic generation process involves two different models:

- Autoencoder: Used to lower the dimensionality of the data
- Continuous-Time Diffusion Model: Used to generated synthetic data

The Autoencoder is used to lower the dimensionality from the original dataset (one feature per ICD code or 1,071 features) to 144 features. This helps to capture relationships between related ICD codes and reduces the dimensionality of the output data that the continuous-time diffusion model must generate.

The Autoencoder is first trained and tested by itself to ensure that the Autoencoder model is able to successfully reduce the dimensionality of the data and then reproduce that original data using the reduced dimensionality dataset. Then, the training data is encoded using the autoencoder and the encoded training data is used to train the Continuous-Time Diffusion model.

This allows the Continous-Time Diffusion model to generate synthetic data in the lower dimensionality space. The Continuous-Time Diffusion Model (aka UNet aka Score Net) is used to generate the synthetic data. It works in combination with a Variance Preserving Stochastic Differential Equation (VPSDE). The VPSDE function is designed to take real data and convert real data into random noise in a controlled manner. The VPSDE function converts the data into noise at continuous time-steps between 0 (completely real data) and 1 (complete noise). This synthetic data is then decoded using the trained Autoencoder to generate synthetic data in a feature space that is tied back to ICD codes.

Model Part 1 - Autoencoder

Autoencoder Architecture:

Layers	Configuration	Activation Function	Output Dimension (batch, feature)
fully connected	input size 1071, output size 144	Tahnh	(512, 144)
fully connected	input size 144, output size 1071	Sigmoid	(512, 1071)

Autoencoder Training Objectives:

- Loss Function: torch.nn.BCELoss with reduction="sum"
- Optimiser: torch.optim.Adam with weight decay=0.0001

Other Autoencoder Info: The model is not pretrained, but weights are initiatlized using torch.nn.init.xavier_uniform_. The autoencoder post-encoding dimension of 144 was chosen by the original paper because previous papers indicated that 128 was the ideal post-encoding dimension, and 144 was the closest that worked with the UNet architecture of the upcoming Continous-Time Diffusion model.

Model Part 2 - UNet

UNet Architecture: Due to the complex nature of the model, it's difficult to describe it in a single table that captures each layer and their size/type/activation function. Instead, we focus on describing how the model works and it's overarching architecture.

Let's assume that this noise is added over n timesteps. The Score Net/UNet is trained to take data with noise added to it at time t_k (where k is between 1 and n), and back-convert that to the data at time t_{k-1} (before the noise was added). To support this, the loss function is defined as the difference between the actual t_{k-1} and the predicted t_{k-1} .

Therefore we are training the model to be able to convert noisy data into real data. Once this training is complete, to generate synthetic data we generate random noise and plug it into the model using a ReverseSDE function (that is designed to remove noise using the model). We start with noise at t_n and move step-wise backwards - at each step the model telling us what real parameters it *thinks* could represent the next step with noise added. When we get to t_0 we have data that follows the same patterns as real data, but because it was built based on noise is completely synthetic.

In terms of architecture, the Continuous-Time Diffusion Model (aka UNet aka Score Net) is a UNet architecture based on the reduced dimensionality space provided by the autoencoder. It has two down-sampling layers that progressively reduce the size of the input data using convolution. Each of these down-sampling layers also has two residual blocks that allow data to skip parts of the model as needed. Each residual block also incorporates self-attention. SiLU (sigmoid(x)*x) is used as the activation function throughout this model.

UNet Training Objectives:

- Loss Function: The loss function is a custom loss function designed to determine the loss between a predicted t_{k-1} and an actual t_{k-1} .
- Optimiser: Adam with an adaptive learning rate. The learning rate (λ) at epoch t is defined by the exponential decay formula:

$$\lambda(t) = \ln_0 \cdot e^{-k \cdot t}$$

where:

- $lr_0 = 0.5$ is the initial learning rate,
- k=0.1 is the decay rate,
- *t* is the epoch number.

Other UNet Info: The model is not pretrained, but weights are initialized using torch.nn.init.xavier uniform.

Implementation Code

Implementation code can be found in the following cells within this section.

Pretrained Model

Available at https://github.com/sjoslin2/Spring-24-DLH/tree/main/saved_models. Also used to generate synthetic data in the following cells (when enabled).

Define Autoencoder Class

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/models/autoencoder
.py
class Autoencoder(nn.Module):
    def init (self, enc in dim, enc out dim):
        super(Autoencoder, self). init ()
        self.encoder = nn.Sequential(nn.Linear(enc in dim,
enc out dim),
                                     nn.Tanh())
        self.decoder = nn.Sequential(
                                     nn.Linear(enc out dim,
enc in dim),
                                     nn.ReLU())
    def encode(self, x):
        x = self.encoder(x)
        return x
    def decode(self, x):
        x = self.decoder(x)
        return x
    def forward(self, x):
        x = self.encoder(x)
        x = self.decoder(x)
        return x
```

Define weight initialization

```
def weights_init(m):
    # From
https://github.com/astorfi/cor-gan/blob/b6df51a16399335bfe995c15b6951f
053453fbb3/Generative/medGAN/MIMIC/pytorch/MLP/medGAN.py#L263 # noqa:
E501
    classname = m.__class__.__name_
    if classname.find("Conv") != -1:
        nn.init.normal_(m.weight.data, 0.0, 0.02)
    elif classname.find("BatchNorm") != -1:
        nn.init.normal_(m.weight.data, 1.0, 0.02)
        nn.init.constant_(m.bias.data, 0)
    if type(m) == nn.Linear:
```

```
torch.nn.init.xavier_uniform_(m.weight)
m.bias.data.fill_(0.01)
```

Define UNet Class

UNet is trained to calculate how to move from noise to data at a given timestamp. It is later instantiated as score_net.

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/models/unet.py
class SiLU(nn.Module):
    def __init__(self):
        super().__init__()
    # noinspection PyMethodMayBeStatic
    def forward(self, x):
        return torch.sigmoid(x) * x
def group norm(out ch):
    return nn.GroupNorm(num groups=32, num channels=out ch, eps=1e-6,
affine=True)
def upsample(in ch, with conv):
    up = nn.Sequential()
    up.add module("up nn", nn.Upsample(scale factor=2,
mode="nearest"))
    if with conv:
        up.add module("up conv", conv2d(in ch, in ch, kernel size=(3,
3), stride=1))
    return up
def downsample(in ch, with conv):
    if with conv:
        down = conv2d(in_ch, in_ch, kernel_size=(3, 3), stride=2)
        down = nn.AvgPool2d(2, 2)
    return down
class ResidualBlock(nn.Module):
    def __init__(
        self,
        in ch,
        temb ch,
        out ch=None,
        conv shortcut=False,
```

```
dropout=0.0,
        normalize=group norm,
        act=SiLU(),
    ):
        super(). init ()
        self.in ch = in ch
        self.temb ch = \overline{temb} ch
        self.out ch = out ch if out ch is not None else in ch
        self.conv shortcut = conv shortcut
        self.dropout = dropout
        self.act = act
        self.temb proj = dense(temb ch, out ch)
        self.norm1 = normalize(in ch) if normalize is not None else
nn.Identitv()
        self.conv1 = conv2d(in ch, out ch)
        self.norm2 = normalize(out ch) if normalize is not None else
nn.Identity()
        self.dropout = nn.Dropout2d(p=dropout) if dropout > 0.0 else
nn.Identity()
        self.conv2 = conv2d(out ch, out ch, init scale=0.0)
        if in ch != out ch:
            if conv_shortcut:
                self.shortcut = conv2d(in ch, out ch)
                self.shortcut = conv2d(in ch, out ch, kernel size=(1,
1), padding=0)
        else:
            self.shortcut = nn.Identity()
    def forward(self, x, temb):
        # forward conv1
        h = x
        h = self.act(self.norm1(h))
        h = self.conv1(h)
        # add in timestep embedding
        h = h + self.temb proj(self.act(temb))[:, :, None, None]
        # forward conv2
        h = self.act(self.norm2(h))
        h = self.dropout(h)
        h = self.conv2(h)
        # shortcut
        x = self.shortcut(x)
        # combine and return
        assert x.shape == h.shape
        return x + h
```

```
class SelfAttention(nn.Module):
    copied modified from https://github.com/voletiv/self-attention-
GAN-pytorch/blob/master/sagan models.py#L29
    copied modified from
https://github.com/hojonathanho/diffusion/blob/master/diffusion tf/
models/unet.py#L66
    def __init__(self, in_channels, normalize=group_norm):
        super(). init ()
        self.in channels = in channels
        self.attn q = conv2d(
            in channels, in channels, kernel size=1, stride=1,
padding=0
        self.attn k = conv2d(
            in channels, in channels, kernel size=1, stride=1,
padding=0
        self.attn_v = conv2d(
            in channels, in channels, kernel size=1, stride=1,
padding=0
        self.proj out = conv2d(
            in channels, in channels, kernel size=1, stride=1,
padding=0, init scale=0.0
        self.softmax = nn.Softmax(dim=-1)
        if normalize is not None:
            self.norm = normalize(in channels)
        else:
            self.norm = nn.Identity()
    # noinspection PyUnusedLocal
    def forward(self, x, temp=None):
        """t is not used"""
        _{-}, C, H, W = x.size()
        h = self.norm(x)
        q = self.attn_q(h).view(-1, C, H * W)
        k = self.attn k(h).view(-1, C, H * W)
        v = self.attn_v(h).view(-1, C, H * W)
        attn = torch.bmm(q.permute(\frac{0}{2}, \frac{1}{2}), k) * (int(C) ** (\frac{-0.5}{2}))
        attn = self.softmax(attn)
        h = torch.bmm(v, attn.permute(0, 2, 1))
```

```
h = h.view(-1, C, H, W)
        h = self.proj out(h)
        assert h.shape == x.shape
        return x + h
def _calculate_correct_fan(tensor, mode):
    copied and modified from
https://github.com/pytorch/pytorch/blob/master/torch/nn/init.py#L337
    mode = mode.lower()
    valid_modes = ["fan_in", "fan_out", "fan_avg"]
    if mode not in valid modes:
        raise ValueError(
            "Mode {} not supported, please use one of {}".format(mode,
valid modes)
    fan in, fan out = calculate fan in and fan out(tensor)
    return fan in if mode == "fan in" else fan out
def kaiming uniform (tensor, gain=1.0, mode="fan in"):
    r"""Fills the input `Tensor` with values according to the method
    described in `Delving deep into rectifiers: Surpassing human-level
    performance on ImageNet classification` - He, K. et al. (2015),
using a
    uniform distribution. The resulting tensor will have values
sampled from
    :math: \mathcal{U}(-\text{bound}, \text{bound}) \) where
    .. math::
        \text{bound} = \text{gain} \times \sqrt{\frac{3}{\text{fan}}
mode } } }
   Also known as He initialization.
   Args:
        tensor: an n-dimensional `torch.Tensor`
        gain: multiplier to the dispersion
        mode: either ``'fan in'`` (default) or ``'fan out'``. Choosing
``'fan in'``
            preserves the magnitude of the variance of the weights in
the
            forward pass. Choosing ``'fan out'`` preserves the
magnitudes in the
            backwards pass.
    Examples:
        >>> w = torch.empty(3, 5)
```

```
>>> nn.init.kaiming uniform (w, mode='fan in')
    0.00
    fan = calculate correct fan(tensor, mode)
    var = gain / max(1.0, fan)
    bound = math.sqrt(3.0 * var) # Calculate uniform bounds from
standard deviation
    with torch.no grad():
        return tensor.uniform (-bound, bound)
def variance scaling init (tensor, scale):
    return kaiming uniform (tensor, gain=1e-10 if scale == 0 else
scale, mode="fan avg")
def dense(in channels, out channels, init scale=1.0):
    lin = nn.Linear(in channels, out channels)
    variance_scaling_init_(lin.weight, scale=init_scale)
    nn.init.zeros (lin.bias)
    return lin
def conv2d(
    in planes,
    out planes,
    kernel size=(3, 3),
    stride=1,
    dilation=1,
    padding=1,
    bias=True,
    padding mode="zeros",
    init scale=1.0,
):
    conv = nn.Conv2d(
        in planes,
        out planes,
        kernel size=kernel size,
        stride=stride,
        padding=padding,
        dilation=dilation,
        bias=bias,
        padding mode=padding mode,
    variance_scaling_init_(conv.weight, scale=init scale)
    if bias:
        nn.init.zeros_(conv.bias)
    return conv
def get sinusoidal positional embedding(
```

```
timesteps: torch.LongTensor, embedding dim: int
):
    Copied and modified from
https://github.com/hojonathanho/diffusion/blob/1e0dceb3b3495bbe19116a5
e1b3596cd0706c543/diffusion tf/nn.py#L90
    From Fairseg in
https://github.com/pytorch/fairseq/blob/master/fairseq/modules/sinusoi
dal positional embedding.pv#L15
    Build sinusoidal embeddings.
    This matches the implementation in tensor2tensor, but differs
slightly
    from the description in Section 3.5 of "Attention Is All You
Need",
    assert len(timesteps.size()) == 1
    timesteps = timesteps.to(torch.get default dtype())
    device = timesteps.device
    half dim = embedding dim // 2
    emb = math.log(10000) / (half dim - 1)
    emb = torch.exp(torch.arange(half dim, dtype=torch.float,
device=device) * -emb)
    emb = timesteps[:, None] * emb[None, :]
    emb = torch.cat([torch.sin(emb), torch.cos(emb)], dim=\frac{1}{1}) # bsz x
embd
    if embedding dim % 2 == 1: # zero pad
        emb = F.pad(emb, (0, 1), "constant", 0)
    assert list(emb.size()) == [timesteps.size(0), embedding dim]
    return emb
class TimestepEmbedding(nn.Module):
    def init (self, embedding dim, hidden dim, output dim,
act=SiLU()):
        super(). init ()
        self.embedding dim = embedding dim
        self.output dim = output dim
        self.hidden dim = hidden dim
        self.main = nn.Sequential(
            dense(embedding dim, hidden dim),
            dense(hidden dim, output dim),
        )
    def forward(self, temp):
```

```
temb = get sinusoidal positional_embedding(temp,
self.embedding dim)
        temb = self.main(temb)
        return temb
class UNet(nn.Module):
    def init (
        self,
        input channels,
        encoded latent embedding dim, # eg 64
        output channels=None,
        ch mult=(1, 2, 4, 8),
        num res blocks=2,
        attn resolutions=(16,),
        dropout=0.0,
        resamp with conv=True,
        act=SiLU(),
        normalize=group norm,
    ):
        super(). init ()
        self.input channels = input channels
        self.encoded latent embedding dim =
encoded latent embedding dim # eg 64
        self.input height =
int(np.sqrt(self.encoded latent embedding dim)) # eg 8
        self.ch = ch
        self.output channels = output channels = (
            input channels if output channels is None else
output channels
        self.ch mult = ch mult
        self.num res blocks = num res blocks
        self.attn resolutions = attn resolutions
        self.dropout = dropout
        self.resamp with conv = resamp with conv
        self.act = act
        self.normalize = normalize
        # init
        self.num_resolutions = num_resolutions = len(ch_mult)
        in ht = self.input height
        in ch = input channels
        temb ch = ch \frac{*}{*} 4
        assert (
            in ht % 2 ** (num resolutions - 1) == 0
        ), "input height doesn't satisfy the condition"
        # Timestep embedding
```

```
self.temb net = TimestepEmbedding(
            embedding dim=ch,
            hidden dim=temb ch,
            output dim=temb ch,
            act=act,
        )
        # Downsampling
        self.begin_conv = conv2d(in_ch, ch)
        unet chs = [ch]
        in_ht = in_ht
        in ch = ch
        down modules = []
        for i level in range(num resolutions):
            # Residual blocks for this resolution
            block modules = {}
            out c\overline{h} = ch * ch mult[i level]
            for i block in range(num res blocks):
                block modules["{}a {}a block".format(i level,
i block)] = ResidualBlock(
                    in ch=in ch,
                    temb ch=temb ch,
                    out ch=out ch,
                    dropout=dropout,
                    act=act,
                    normalize=normalize,
                if in ht in attn resolutions:
                    block modules[
                        "{}a {}b attn".format(i level, i block)
                    ] = SelfAttention(out ch, normalize=normalize)
                unet chs += [out ch]
                in ch = out ch
            # Downsample
            if i level != num resolutions - 1:
                block modules["{}b downsample".format(i level)] =
downsample(
                    out ch, with conv=resamp with conv
                in ht //= 2
                unet chs += [out ch]
            # convert list of modules to a module list, and append to
a list
            down modules += [nn.ModuleDict(block modules)]
        # convert to a module list
        self.down modules = nn.ModuleList(down modules)
        # Middle
        mid modules = []
        mid modules += [
```

```
ResidualBlock(
                in ch,
                temb ch=temb ch,
                out ch=in ch,
                dropout=dropout,
                act=act,
                normalize=normalize,
            )
        ]
        mid modules += [SelfAttention(in ch, normalize=normalize)]
        mid modules += [
            ResidualBlock(
                in ch,
                temb ch=temb ch,
                out ch=in ch,
                dropout=dropout,
                act=act,
                normalize=normalize,
            )
        ]
        self.mid modules = nn.ModuleList(mid_modules)
        # Upsampling
        up modules = []
        for i level in reversed(range(num resolutions)):
            # Residual blocks for this resolution
            block modules = {}
            out ch = ch * ch mult[i level]
            for i_block in range(num_res_blocks + 1):
                block_modules["{}a_{}a_block".format(i_level,
i block)] = ResidualBlock(
                    in ch=in ch + unet chs.pop(),
                    temb ch=temb ch,
                    out ch=out ch,
                    dropout=dropout,
                    act=act,
                    normalize=normalize,
                if in ht in attn resolutions:
                    block modules[
                         "{}a {}b attn".format(i level, i block)
                    ] = SelfAttention(out ch, normalize=normalize)
                in ch = out ch
            # Upsample
            if i level != 0:
                block modules["{}b upsample".format(i level)] =
upsample(
                    out ch, with conv=resamp with conv
                in ht *= 2
```

```
# convert list of modules to a module list, and append to
a list
            up modules += [nn.ModuleDict(block modules)]
        # conver to a module list
        self.up modules = nn.ModuleList(up modules)
        assert not unet chs
        # End
        self.end conv = nn.Sequential(
            normalize(in ch),
            self.act,
            conv2d(in ch, output channels, init scale=0.0),
        )
    # noinspection PyMethodMayBeStatic
    def compute cond module(self, module, x, temp):
        for m in module:
            x = m(x, temp)
        return x
    # noinspection PyArgumentList, PyShadowingNames
    def forward(self, x, temp):
        # Init
        x = x.view(-1, 1, self.input height, self.input height)
        temp = temp.view(
            -1,
        B, C, H, W = x.size()
        # Timestep embedding
        temb = self.temb net(temp)
        assert list(temb.shape) == [B, self.ch * 4]
        # Downsampling
        hs = [self.begin conv(x)]
        for i level in range(self.num resolutions):
            # Residual blocks for this resolution
            block modules = self.down modules[i level]
            for i block in range(self.num res blocks):
                resnet block =
block modules["{}a {}a block".format(i level, i block)]
                h = resnet block(hs[-1], temb)
                if h.size(2) in self.attn resolutions:
                    attn block =
block modules["{}a {}b attn".format(i level, i block)]
                    h = attn block(h, temb)
                hs.append(h)
            # Downsample
            if i level != self.num resolutions - 1:
                downsample =
block modules["{}b downsample".format(i level)]
                hs.append(downsample(hs[-1]))
```

```
# Middle
        h = hs[-1]
        h = self. compute cond module(self.mid modules, h, temb)
        # Upsamplina
        for i idx, i level in
enumerate(reversed(range(self.num resolutions))):
            # Residual blocks for this resolution
            block modules = self.up modules[i idx]
            for i block in range(self.num res blocks + 1):
                resnet block =
block modules["{}a_{}a_block".format(i_level, i_block)]
                h = resnet block(torch.cat([h, hs.pop()], axis=1),
temb)
                if h.size(2) in self.attn resolutions:
                    attn block =
block modules["{}a_{}b_attn".format(i_level, i_block)]
                    h = attn_block(h, temb)
            # Upsample
            if i level != 0:
                upsample =
block modules["{}b upsample".format(i level)]
                h = upsample(h)
        assert not hs
        # End
        h = self.end conv(h)
        assert list(h.size()) == [x.size(0), self.output channels,
x.size(2), x.size(3)
        h = h.view(-1, self.encoded_latent_embedding_dim)
        return h
```

Define DenoisingScoreMatching Class

This can be thought of as the loss function for UNet (score_net).

```
# Modified from:
https://urldefense.com/v3/__https://github.com/aanaseer/ScoEHR/blob/
main/scoehr/score_matching/dsm.py*5Cn__;JQ!!DZ3fjg!
4siitaFtGJbIpckDGCisikGoryCfrOwrQq9C_3mjuGsbqQ46APuYkClcW6isH1EtwJFmU9
D62SU44GBW8LA$
"""Implements the denoising score matching objective along with two
helper functions."""
def pad_to(x, stride):
    h, w = x.shape[-2:]
    if w % stride > 0:
        new_w = w + stride - w % stride
```

```
else:
        new w = w
    lh, uh = int((h - h) / 2), int(h - h) - int((h - h) / 2)
    lw, uw = int((new w - w) / 2), int(new w - w) - int((new w - w) / 2)
2)
    pads = (lw, uw, lh, uh)
    # zero-padding by default.
    # See others at
https://urldefense.com/v3/ https://pytorch.org/docs/stable/nn.functio
nal.html*torch.nn.functional.pad*5Cn ; IyU!!DZ3fjg!
4siitaFtGJbIpckDGCisikGoryCfr0wrQq9C 3mjuGsbqQ46APuYkClcW6isH1EtwJFmU9
D62SU48D6nVik$
    out = F.pad(x, pads, "constant", 0)
    return out, pads
def unpad(self, x, pad):
    if pad[0] + pad[1] > 0:
        x = x[:, pad[0]: -pad[1]]
    return x
class DenoisingScoreMatching(nn.Module):
    def __init__(self, sde, score_net, T=1.0, padding required=False):
        super(). init ()
        self.sde = sde
        self.score net = score net
        self.T = T
        self.padding required = padding required
    @torch.enable grad()
    def loss fn(self, x):
        t = torch.linspace(1 / x.size(0) + 1e-3, 1 - 1 / x.size(0),
x.size(0)) + (
            1 - 2 * torch.rand(x.size(0))
        ) * (1 / x.size(0))
        t = t.view(-1, 1).to(x)
        idx = torch.randperm(t.nelement())
        t = t.view(-1)[idx].view(t.size())
        perturbed x, noise, std, g = self.sde.sample(x, t)
        if self.padding required:
          # Modified from pad to 784 to pad to 1296
          # This is because we're testing the non-autoencoder Score
Net with
          # the Mimic data which has 1071 parameters instead of the
```

Define VPSDE (Variance Preserving Stochastic Differential Equation) Class

The VPSDE class is used to add noise to the data at each time stamp.

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/score matching/
sde library.py
"""Implementation for the VPSDE along with the associated Reverse SDE.
This file also contains a wrapper for SDE to be used with torchsde
library.
# This code is a modification of https://github.com/CW-Huang/sdeflow-
light/blob/main/lib/sdes.py
class VPSDE(nn.Module):
    """Implements the VPSDE."""
    def init (self, beta min=0.1, beta max=20.0, T=1.0,
t epsilon=0.001):
        super().__init__()
        self.beta min = beta min
        self.beta max = beta max
        self.T = T
        self.t epsilon = t epsilon
    def beta(self, t):
        return self.beta min + t * (self.beta max - self.beta min)
    def mean weight(self, t):
        return torch.exp(
            -0.25 * t**2 * (self.beta max - self.beta min) - 0.5 * t *
self.beta min
    def var(self, t):
        return 1.0 - torch.exp(
```

```
-0.5 * t**2 * (self.beta max - self.beta min) - t *
self.beta min
    def f(self, x, t):
        return -0.5 * self.beta(t) * x
    def q(self, x, t):
        return torch.ones like(x) * self.beta(t) ** 0.5
    def sample(self, x0, t):
        mean = self.mean weight(t) * x0
        std = torch.sqrt(self.var(t))
        noise = torch.randn like(x0)
        perturbed x = mean + (noise * std)
        return perturbed x, noise, std, self.g(perturbed x, t)
    def probability_flow_ode(self, t, x, score_net):
        return (
            self.f(x, self.T - t)
            - 0.5 * (self.g(x, self.T - t) ** 2) * score net(x, self.T
- t.squeeze())
        ) * -1
class WrapperForTorchSDE(nn.Module):
    """Wraps the SDE to be used with torchsde library."""
    def __init__(self, reverse_sde, noise_type="diagonal",
sde type="ito"):
        super().__init__()
        self.noise type = noise type
        self.sde type = sde type
        self.reverse_sde = reverse_sde
    def f(self, t, x):
        t = t.repeat(x.size(0)).view(-1, 1)
        return self.reverse sde.drift(x, t)
    def g(self, t, x):
        t = t.repeat(x.size(0)).view(-1, 1)
        return self.reverse sde.diffusion(x, t)
```

Define ReverseSDE Class

The ReverseSDE class is used to remove noise from the data at each time stamp based on the score_net weights.

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/score_matching/
sde_library.py
```

```
class ReverseSDE(nn.Module):
    """Implements the reverse SDE."""
    def init (self, sde, score net, T=1.0):
        super(). init ()
        self.sde = sde
        self.score net = score net
        self.T = T
    def drift(self, x, t):
        dt = -1
        return (
            self.sde.f(x, self.T - t)
            - (self.sde.g(x, self.T - t) ** 2) * self.score net(x,
self.T - t.squeeze())
        ) * dt
    def diffusion(self, x, t):
        return self.sde.g(x, self.T - t) # Actual
```

Training

Hyperparameters

- Training Batch Size: 64 While the original paper's github had a batch size of 256 given as an example, we chose this smaller batch size to allow training to be done with less GPU RAM (and using consumer-grade GPU hardward). Note that during synthetic data generation, the batch size is increased to 128. This is because a higher-end GPU (T4 and A100s were both tested) was used for synthetic data generation (due to the time it took to generate synthetic data), and the higher-end could support the larger batch size.
- Autoencoder Learning Rate: 0.001 This matched the example given in the original paper's github.
- Autoencoder Hidden Dimension Size: 144 This matched the example given in the original paper's github. Because the autoencoder dimensionality was used as an input into the UNet, and because of the structure of the layers of the UNet, only specific autoencoder hidden dimensions are supported (they must fit the following formula: $(4 \cdot n)^2$). As additional ablations, autoencoder hidden dimensions of 64 and 256 were also tested. An ablation where the autoencoder was not used was also tested. Ablation results are discussed in the results section.
- **UNet Learning Rate: 0.001.** This matched the example given in the original paper's github.

Computational Requirements

Autoencoder Number of Epochs:

While the original paper's github had an autoencoder epoch count of 20, we found that the test loss continued to decrease beyond this point and found that beyond 50 epochs there was

diminishing returns for the test loss. The times and RAM usage in the tables below are based on 50 epochs of autoencoder training.

UNet Number of Epochs:

While the original paper's github had a UNet epoch count of 5, we found that test loss continued to decrease well beyond this number and found 50 to be a reasonable balance between improving the test loss and a reasonable training time. As additional ablations, we also tested results using 12, 25, 30, 75, and 100 epochs. Ablation results are discussed in the results section. The times and RAM usage in the tables below are based on 50 epochs of UNet training.

GPU Hours (using Nvidia Tesla T4 GPU)

Autoencoder		UNet (ScoreNet)	Synthetic Data
Features	Autoencoder Training	Training	Generation
No Autoencoder	N/A	4.5 Hours	8.5 Hours
64	3.5 Minutes	27 Minutes	37 Minutes
144	3.5 Minutes	42 Minutes	68 Minutes
256	3.5 Minutes	73 Minutes	2 Hours

GPU RAM Usage (using Nvidia Tesla T4 GPU)

Autoencoder Features	Autoencoder Training	UNet (ScoreNet) Training	Synthetic Data Generation
No Autoencoder	N/A	6.2 GB	3.3 GB
64	0.3 GB	1.2 GB	2.3 GB
144	0.4 GB	1.5 GB	2.3 GB
256	0.4 GB	2.3 GB	2.7 GB

Type of Hardware

While most runs were generated using an Nvidia Tesla T4 GPU (see results for GPU hours in the table above), some synthetic data was generated using an Nvidia A100 Tensor Core GPU. This was substantially faster at generating synthetic data:

- T4 GPU Synthetic Data Generation (144 Autoencoder Features): 68 minutes
- A100 GPU Synthetic Data Generation (144 Autoencoder Features): 19 minutes

Training Code

Training code can be found in the following cells within this section.

Instantiate and Train Autoencoders

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/train/train_autoen
coder_utils.py
train autoencoder model = False
```

```
save autoencoder model = False
# Note, these must all be integers that fit the following formula: (4
* n) ^ 2
# This is a requirement of the UNet that comes later
# 64 = (4 * 2) ^ 2
# 144 = (4 * 3) ^ 2
# 256 = (4 * 4) ^ 2
autoencoder dims = [64, 144, 256]
n epochs autoencoder = 200
lr autoencoder = 0.001
enc in dim = train data.shape[1]
loss infos = {}
loss fn autoencoder = torch.nn.MSELoss(reduction="sum")
for enc out dim in autoencoder dims:
    autoencoder = Autoencoder(enc in dim, enc out dim)
    autoencoder.to(device)
    autoencoder stats path = os.path.join(file location,
                'stats/autoencoder count ' + str(enc out dim) +
'.pkl')
    autoencoder model path = os.path.join(file location,
                'saved models/autoencoder count ' + str(enc out dim) +
'.pt')
    if train autoencoder model:
        autoencoder.apply(weights init)
        optimiser autoencoder =
torch.optim.Adam(autoencoder.parameters(), lr=lr autoencoder,
weight decay=0.0001)
        print(f"==> Training the {enc out dim} autoencoder with
{n epochs autoencoder} epochs.")
        epoch train loss list = []
        epoch_test_loss_list = []
        for epoch in tqdm.tqdm(range(n epochs autoencoder)):
            epoch train loss = 0
            epoch test loss = 0
            autoencoder.train()
            for x in train dataloader:
                optimiser autoencoder.zero grad()
                encode and decode = autoencoder(x)
                loss = loss fn autoencoder(encode and decode, x) /
x.shape[0]
                epoch train loss += loss.item()
                loss.backward()
```

```
optimiser autoencoder.step()
            autoencoder.eval()
            with torch.no grad():
                for x in test dataloader:
                    encode and decode = autoencoder(x)
                    loss = loss fn autoencoder(encode and decode, x) /
x.shape[0]
                    epoch test loss += loss.item()
            avg train loss = epoch train loss / len(train dataloader)
            avg_test_loss = epoch_test_loss / len(test dataloader)
            epoch train loss list.append(avg train loss)
            epoch test loss list.append(avg test loss)
        print("==> Autoencoder training completed.")
        loss info = dict()
        loss info['epoch train loss list'] = epoch train loss list
        loss info['epoch test loss list'] = epoch test loss list
        if save autoencoder model:
            with open(autoencoder stats path, 'wb') as file:
                pickle.dump(loss info, file, -1)
            torch.save({'model state dict': autoencoder.state dict()},
autoencoder model path)
        del optimiser autoencoder
    else:
        print("===> Loading trained models")
        loss info = dict()
        with open(autoencoder stats path, 'rb') as file:
            loss info = pickle.load(file)
    loss infos[enc out dim] = loss info
    del autoencoder
    gc.collect()
    if device == "cuda":
        torch.cuda.empty cache()
for enc out dim in autoencoder dims:
    loss info = loss infos[enc out dim]
    epoch_train_loss_list = loss_info['epoch_train_loss_list']
    epoch test loss list = loss info['epoch test loss list']
    plt.plot(epoch test loss list,
             label='autoencoder ' + str(enc out dim) + ' test loss')
plt.xlabel('epoch')
plt.title('AE loss during training')
plt.legend()
```

```
plt.yscale("log")
plt.show()

===> Loading trained models
===> Loading trained models
===> Loading trained models
```

AE loss during training autoencoder 64 test loss autoencoder 144 test loss autoencoder 256 test loss 6×10^{0} 4×10^{0} 3×10^{0} 2×10^{0} 0 25 50 75 100 125 150 175 200 epoch

Instantiate and Train Score Net (UNet) with autoencoders

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/main.py

train_score_net = False
save_score_net_model = False

# Which autoencoders should be used to train the Score Net model
# These must all be integers that fit the following formula: (4 * n) ^
2
# This is a requirement of the UNet architecture
# 64 = (4 * 2) ^ 2
# 144 = (4 * 3) ^ 2
# 256 = (4 * 4) ^ 2
autoencoder_dims = [64, 144, 256]
```

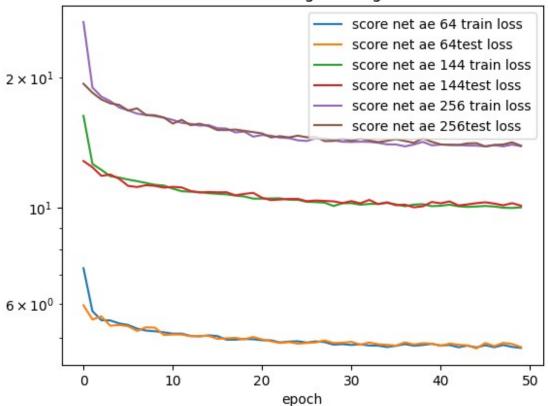
```
n epochs score net = 50
lr score net = 0.001
T = 1
padding required = False
loss lists = {}
lr 0 = 0.5 # initial learning rate
k = 0.1 # decay rate
def lambda func(t):
    return lr 0 * np.exp(-k * t)
for enc out dim in autoencoder dims:
    # Encode training and test data:
    # Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/main.py
    autoencoder = Autoencoder(enc in dim, enc out dim)
    autoencoder_model_path = os.path.join(file_location,
              'saved models/autoencoder count ' + str(enc out dim) +
'.pt')
    checkpoint = torch.load(autoencoder model path,
map location=device)
    autoencoder.to(device)
    autoencoder.load state dict(checkpoint['model state dict'])
    autoencoder.eval()
    train data encoded =
autoencoder.encode(train dataloader.dataset).detach()
    train dataloader encoded = DataLoader(
            dataset=train data encoded,
            batch size=batch size,
            shuffle=True.
            drop last=True,
    test data encoded =
autoencoder.encode(test dataloader.dataset).detach()
    test dataloader encoded = DataLoader(
            dataset=test data encoded,
            batch size=batch size,
            shuffle=True,
            drop last=True,
    sde = VPSDE()
```

```
score net = UNet(
        input channels=1,
        encoded latent embedding dim=enc out dim,
        ch=128.
        ch mult=(1, 2, 2),
        num res blocks=2,
        attn resolutions=(16,),
        resamp with conv=True,
        dropout=0,
    )
    score net.apply(weights init)
    score net.to(device)
    loss_fn_instance_dsm = DenoisingScoreMatching(sde=sde,
score net=score net, T=T, padding required=padding required)
    optimiser score net =
torch.optim.Adam(loss fn instance dsm.parameters(), lr=lr score net)
    score net stats path = os.path.join(file location,
                'stats/scorenet_count_ae_' + str(enc_out_dim) +
'.pkl')
    score net model path = os.path.join(file location,
                'saved_models/scorenet_count_ae_' + str(enc out dim) +
'.pt')
    # Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/train/train scoren
et.py
    loss list = dict()
    if train score net:
        print(f"==> Training the {enc out dim} ae score net with
{n epochs score net} epochs.")
        scheduler = lr_scheduler.LambdaLR(optimiser_score_net,
lr lambda=lambda func)
        start_time = time.time()
        train loss list = []
        test_loss_list = []
        for epoch in range(n_epochs_score_net):
            epoch loss = 0
            for x in tqdm.tqdm(train dataloader encoded):
                optimiser_score_net.zero_grad()
                loss = loss_fn_instance_dsm.loss fn(x).mean()
                epoch loss += loss.item()
                loss.backward()
                torch.nn.utils.clip grad norm (score net.parameters(),
1)
                optimiser score net.step()
```

```
avg loss = epoch loss / len(train dataloader encoded)
            train loss list.append(avg loss)
            scheduler.step()
            time elapsed = time.time() - start time
            print(f"Epoch: {epoch+1} | Total Time:
{time elapsed:.2f}s | Train Loss: {avg loss:.5f}")
            epoch loss = 0
            with torch.no grad():
                for x in tqdm.tqdm(test dataloader encoded):
                    loss = loss fn instance dsm.loss fn(x).mean()
                    epoch loss += loss.item()
            avg loss = epoch loss / len(test dataloader encoded)
            test loss list.append(avg loss)
            time elapsed = time.time() - start time
            print(f"Epoch: {epoch+1} | Total Time:
{time elapsed:.2f}s | Test Loss: {avg loss:.5f}")
        print("==> Score net training completed.")
        loss list['train loss list'] = train loss list
        loss list['test loss list'] = test loss list
        with open(score net stats path, 'wb') as file:
            pickle.dump(loss_list, file, -1)
        if save score net model:
            torch.save({'model state dict': score net.state dict()},
score net model path)
    else:
        print("===> Loading model")
        checkpoint = torch.load(score net model path,
map location=torch.device(device))
        score net.load state dict(checkpoint['model state dict'])
        print("===> Showing stats from loaded model")
        with open(score net stats path, 'rb') as file:
            loss list = pickle.load(file)
    loss lists[enc out dim] = loss list
    del train data encoded
    del train dataloader encoded
    del test data encoded
    del test dataloader encoded
    del loss fn instance dsm
    del optimiser_score_net
    del checkpoint
```

```
del autoencoder
    del autoencoder model path
    gc.collect()
    if device == "cuda":
        torch.cuda.empty cache()
for enc_out_dim in autoencoder_dims:
    loss list = loss lists[enc out dim]
    train_loss_list = loss_list['train_loss_list']
    test_loss_list = loss_list['test_loss_list']
    plt.plot(Train_loss_list,
             label='score net ae ' + str(enc_out_dim) + ' train loss')
    plt.plot(test loss list,
             label='score net ae ' + str(enc out dim) + 'test loss')
plt.xlabel('epoch')
plt.title('Loss during training')
plt.legend()
plt.yscale("log")
plt.show()
===> Loading model
===> Showing stats from loaded model
===> Loading model
===> Showing stats from loaded model
===> Loading model
===> Showing stats from loaded model
```





Instantiate and train score net (UNet) with ablations

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/main.py
train score net = False
save score net model = False
# Which autoencoders should be used to train the Score Net model
# These must all be integers that fit the following formula: (4 * n) ^
# This is a requirement of the UNet architecture
# 64 = (4 * 2) ^ 2
# 144 = (4 * 3) ^ 2
# 256 = (4 * 4) ^ 2
autoencoder_dims = [144]
n epochs score net ablations = [12, 25, 50, 75, 100]
lr score net ablations = [0.00025, 0.0005, 0.001, 0.0025, 0.005]
padding required = False
```

```
loss lists = {}
lr 0 = 0.5 # initial learning rate
k = 0.1 # decay rate
def lambda func(t):
    return lr 0 * np.exp(-k * t)
for n epochs score net in n epochs score net ablations:
    lr score net = 0.001
    enc out dim = 144
    # Encode training and test data:
    # Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/main.py
    autoencoder = Autoencoder(enc in dim, enc out dim)
    autoencoder_model_path = os.path.join(file_location,
              'saved_models/autoencoder_count_' + str(enc_out_dim) +
'.pt')
    checkpoint = torch.load(autoencoder model path,
map_location=device)
    autoencoder.to(device)
    autoencoder.load state dict(checkpoint['model state dict'])
    autoencoder.eval()
    train data encoded =
autoencoder.encode(train_dataloader.dataset).detach()
    train dataloader encoded = DataLoader(
            dataset=train data encoded,
            batch size=batch size,
            shuffle=True.
            drop last=True,
    test data encoded =
autoencoder.encode(test dataloader.dataset).detach()
    test_dataloader_encoded = DataLoader(
            dataset=test data encoded,
            batch size=batch size,
            shuffle=True,
            drop last=True,
    )
    sde = VPSDE()
    score net = UNet(
        input channels=1,
        encoded_latent_embedding_dim=enc_out_dim,
        ch_mult=(1, 2, 2),
```

```
num res blocks=2,
        attn resolutions=(16,),
         resamp with conv=True,
        dropout=0,
    score net.apply(weights init)
    score net.to(device)
    loss fn instance dsm = DenoisingScoreMatching(sde=sde,
score net=score net, T=T, padding required=padding required)
    optimiser score net =
torch.optim.Adam(loss fn instance dsm.parameters(), lr=lr score net)
    score_net_model_path = os.path.join(file location,
                 'saved models/scorenet count ae 144 epoch' +
str(n epochs score net) + ' lr' + str(lr score net) + '.pt')
    # Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/train/train scoren
et.py
    loss list = dict()
    if train score net:
        print(f"==> Training the {enc out dim} ae score net with
{n epochs score net} epochs at a {lr score net} learning rate.")
        scheduler = lr scheduler.LambdaLR(optimiser score net,
lr lambda=lambda func)
        start time = time.time()
        train loss list = []
        test \overline{l}oss \overline{l}ist = []
        for epoch in range(n epochs score net):
            epoch loss = 0
            for x in tqdm.tqdm(train dataloader encoded):
                 optimiser score net.zero grad()
                 loss = loss fn instance dsm.loss fn(x).mean()
                epoch loss += loss.item()
                 loss.backward()
                torch.nn.utils.clip grad norm (score net.parameters(),
1)
                optimiser score net.step()
            avg loss = epoch loss / len(train dataloader encoded)
            train loss list.append(avg loss)
            scheduler.step()
            time elapsed = time.time() - start time
            print(f"Epoch: {epoch+1} | Total Time:
{time elapsed:.2f}s | Train Loss: {avg_loss:.5f}")
```

```
epoch loss = 0
            with torch.no grad():
                for x in tqdm.tqdm(test_dataloader_encoded):
                    loss = loss fn instance dsm.loss fn(x).mean()
                    epoch loss += loss.item()
            avg loss = epoch loss / len(test dataloader encoded)
            test loss list.append(avg loss)
            time elapsed = time.time() - start_time
            print(f"Epoch: {epoch+1} | Total Time:
{time elapsed:.2f}s | Test Loss: {avg loss:.5f}")
        print("==> Score net training completed.")
        loss list['train loss list'] = train loss list
        loss_list['test_loss_list'] = test_loss_list
        if save score net model:
            torch.save({'model state dict': score net.state dict()},
score net model path)
    else:
        print("===> Existing model will be used when generating
synthetic data.")
    loss lists[n epochs score net] = loss list
    del train data encoded
    del train_dataloader_encoded
    del test data encoded
    del test dataloader encoded
    del loss fn instance dsm
    del optimiser score net
    del checkpoint
    del autoencoder
    del autoencoder model path
    qc.collect()
    if device == "cuda":
        torch.cuda.empty cache()
for lr score net in lr score net ablations:
    n epochs score net = 50
    enc out dim = 144
    # Encode training and test data:
    # Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/main.py
    autoencoder = Autoencoder(enc in dim, enc out dim)
    autoencoder model path = os.path.join(file location,
```

```
'saved models/autoencoder count ' + str(enc out dim) +
'.pt')
    checkpoint = torch.load(autoencoder model path,
map location=device)
    autoencoder.to(device)
    autoencoder.load_state_dict(checkpoint['model_state_dict'])
    autoencoder.eval()
    train data encoded =
autoencoder.encode(train dataloader.dataset).detach()
    train_dataloader_encoded = DataLoader(
            dataset=train data encoded,
            batch size=batch size,
            shuffle=True,
            drop last=True,
    test data encoded =
autoencoder.encode(test dataloader.dataset).detach()
    test dataloader encoded = DataLoader(
            dataset=test data encoded,
            batch size=batch size,
            shuffle=True,
            drop last=True,
    )
    sde = VPSDE()
    score_net = UNet(
        input channels=1,
        encoded_latent_embedding_dim=enc_out_dim,
        ch=128,
        ch_{mult}=(1, 2, 2),
        num_res blocks=2,
        attn resolutions=(16,),
        resamp_with conv=True,
        dropout=0,
    )
    score net.apply(weights init)
    score net.to(device)
    loss fn instance dsm = DenoisingScoreMatching(sde=sde,
score net=score net, T=T, padding required=padding required)
    optimiser score net =
torch.optim.Adam(loss fn instance dsm.parameters(), lr=lr score net)
    score net model path = os.path.join(file location,
                'saved models/scorenet count ae 144 epoch' +
str(n epochs score net) + ' lr' + str(lr score net) + '.pt')
    # Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/train/train scoren
et.py
```

```
loss list = dict()
    if train score net:
        print(f"==> Training the {enc out dim} ae score net with
{n epochs score net} epochs at a {lr score net} learning rate.")
        scheduler = lr scheduler.LambdaLR(optimiser score net,
lr lambda=lambda func)
        start time = time.time()
        train loss list = []
        test_{loss} \overline{list} = []
        for epoch in range(n epochs score net):
            epoch loss = 0
            for x in tqdm.tqdm(train dataloader encoded):
                optimiser score net.zero grad()
                loss = loss_fn_instance_dsm.loss_fn(x).mean()
                epoch loss += loss.item()
                loss.backward()
                torch.nn.utils.clip grad norm (score net.parameters(),
1)
                optimiser score net.step()
            avg loss = epoch loss / len(train dataloader encoded)
            train loss list.append(avg loss)
            scheduler.step()
            time elapsed = time.time() - start time
            print(f"Epoch: {epoch+1} | Total Time:
{time elapsed:.2f}s | Train Loss: {avg loss:.5f}")
            epoch loss = 0
            with torch.no grad():
                for x in tqdm.tqdm(test_dataloader_encoded):
                    loss = loss fn instance dsm.loss fn(x).mean()
                    epoch loss += loss.item()
            avg loss = epoch loss / len(test dataloader encoded)
            test loss list.append(avg loss)
            time elapsed = time.time() - start_time
            print(f"Epoch: {epoch+1} | Total Time:
{time elapsed:.2f}s | Test Loss: {avg loss:.5f}")
        print("==> Score net training completed.")
        loss_list['train_loss_list'] = train_loss list
        loss_list['test_loss_list'] = test_loss_list
        if save score net model:
```

```
torch.save({'model state dict': score net.state dict()},
score net model path)
    else:
        print("===> Existing model will be used when generating
synthetic data.")
    loss_lists[lr_score_net] = loss_list
    del train data encoded
    del train dataloader encoded
    del test data encoded
    del test dataloader encoded
    del loss fn instance dsm
    del optimiser score net
    del checkpoint
    del autoencoder
    del autoencoder model path
    gc.collect()
    if device == "cuda":
        torch.cuda.empty cache()
===> Existing model will be used when generating synthetic data.
===> Existing model will be used when generating synthetic data.
===> Existing model will be used when generating synthetic data.
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===> Existing model will be used when generating synthetic data.
===> Existing model will be used when generating synthetic data.
```

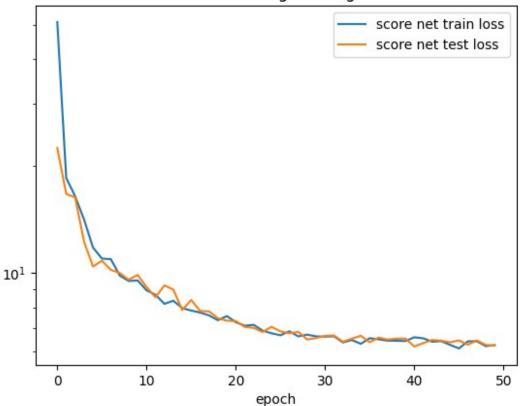
Train ScoreNet With No Autoencoder

```
shuffle=True,
        drop last=True,
test data no ae = F.pad(input=test dataloader.dataset, pad=(0,
padding added dims, 0, 0), mode='constant', value=0)
test_dataloader_no_ae = DataLoader(
        dataset=test data no ae,
        batch size=batch size,
        shuffle=True,
        drop last=True,
)
lr score net no ae = 0.001
T no ae = 1
padding required no ae = False
sde no ae = VPSDE()
score net no ae = UNet(
    input channels=1,
    encoded latent embedding dim=train data no ae.shape[1],
    ch=128.
    ch mult=(1, 2, 2),
    num res blocks=2,
    attn resolutions=(16,),
    resamp with conv=True,
    dropout=0,
)
score net no ae.apply(weights init)
score net no ae.to(device)
loss fn instance dsm no ae = DenoisingScoreMatching(sde=sde no ae,
score net=score net no ae, T=T no ae,
padding_required=padding_required_no_ae)
optimiser score net no ae =
torch.optim.Adam(loss fn instance dsm no ae.parameters(),
lr=lr score net no ae)
T = 1
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/train/train scoren
et.py
score_net_stats_path = os.path.join(file_location,
            'stats/scorenet count no ae.pkl')
score net model path = os.path.join(file location,
            'saved models/scorenet count no ae.pt')
n epochs score net no ae = 50
if train score net no ae:
```

```
print(f"==> Training the score net with {n epochs score net no ae}
epochs.")
    lr 0 no ae = 0.5 # initial learning rate
    k no ae = 0.1 # decay rate
    def lambda func no ae(t no ae):
        return lr_0_no_ae * np.exp(-k_no_ae * t_no_ae)
    scheduler no ae = lr scheduler.LambdaLR(optimiser score net no ae,
lr lambda=lambda func no ae)
    start time no ae = time.time()
    train loss list no ae = []
    test loss list no ae = []
    for epoch no ae in range(n epochs score net no ae):
        epoch loss no ae = 0
        for x no ae in tqdm.tqdm(train dataloader no ae):
            optimiser_score_net_no_ae.zero_grad()
            loss no ae =
loss fn instance dsm no ae.loss fn(x no ae).mean()
            epoch loss no ae += loss no ae.item()
            loss no ae.backward()
torch.nn.utils.clip_grad_norm_(score_net_no_ae.parameters(), 1)
            optimiser score net no ae.step()
        avg loss no ae = epoch loss no ae /
len(train dataloader no ae)
        train loss list no ae.append(avg loss no ae)
        scheduler no ae.step()
        time elapsed no ae = time.time() - start time no ae
        print(f"Epoch: {epoch no ae+1} | Total Time:
{time elapsed no ae:.2f}s | Train Loss: {avg loss no ae:.5f}")
        epoch loss no ae = 0
        with torch.no grad():
            for x no ae in tqdm.tqdm(test dataloader no ae):
                loss no ae =
loss fn instance dsm no ae.loss fn(x no ae).mean()
                epoch loss no ae += loss no ae.item()
        avg loss no ae = epoch loss no ae / len(test dataloader no ae)
        test_loss_list_no_ae.append(avg_loss_no_ae)
        time elapsed no ae = time.time() - start_time_no_ae
        print(f"Epoch: {epoch no ae+1} | Total Time:
{time elapsed no ae:.2f}s | Test Loss: {avg loss no ae:.5f}")
```

```
print("==> Score net training (no autoencoder) completed.")
    plt.plot(train loss list no ae, label='score net train loss')
    plt.plot(test_loss_list_no_ae, label='score net test loss')
    plt.xlabel('epoch')
    plt.title('Loss during training')
    plt.legend()
    plt.yscale("log")
    plt.show()
    loss list no ae = dict()
    loss_list_no_ae['train_loss_list'] = train_loss_list_no_ae
    loss list no ae['test loss list'] = test loss list no ae
    with open(score_net_stats_path, 'wb') as file:
        pickle.dump(loss list no ae, file, -1)
    if save score net model no ae:
        torch.save({'model state dict': score net no ae.state dict()},
score net model path)
else:
    print("===> Loading model")
    checkpoint no ae = torch.load(score net model path,
map location=torch.device(device))
score net no ae.load state dict(checkpoint no ae['model state dict'])
    print("===> Showing stats from loaded model")
    with open(score net stats path, 'rb') as file:
        loss list no ae = pickle.load(file)
    train_loss_list_no_ae = loss_list_no_ae['train loss list']
    test_loss_list_no_ae = loss_list_no_ae['test_loss_list']
    plt.plot(train_loss_list_no_ae, label='score net train loss')
    plt.plot(test loss list no ae, label='score net test loss')
    plt.xlabel('epoch')
    plt.title('Loss during training')
    plt.legend()
    plt.yscale("log")
    plt.show()
===> Loading model
===> Showing stats from loaded model
```





Generate Synthetic Data Once the model is trained, it can be used to generate synthetic data that can be compared to the original data to determine if it is statistically similar while still protecting the privacy of the original patients. The generation process is described in the Score Net model section.

Note: By default, instead of generating this data instead pre-generated data is loaded and used. You can change this by setting generate_data = True.

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/main.py
batch_size = 128

generate_data = False
save_generated_data = False
autoencoder_dims = [64, 144, 256]

T = 1

if generate_data:
    time_steps = 1000
    num_samples_to_generate = batch_size * 80
```

```
print("==> Commencing reverse solve using torchsde Euler
Maruyama.")
    for enc out dim in autoencoder dims:
        start time = time.time()
        print(f'==> Generating data for {enc out dim} ae score net')
        autoencoder = Autoencoder(enc_in_dim, enc_out_dim)
        autoencoder model path = os.path.join(file location,
                'saved_models/autoencoder_count_' + str(enc_out_dim) +
'.pt')
        checkpoint = torch.load(autoencoder model path,
map location=device)
        autoencoder.load state dict(checkpoint['model state dict'])
        autoencoder.eval()
        autoencoder.to(device)
        sde = VPSDE()
        score net = UNet(
        input channels=1,
        encoded latent embedding dim=enc out dim,
        ch=128.
        ch mult=(1, 2, 2),
        num res blocks=2,
        attn resolutions=(16,),
        resamp with conv=True,
        dropout=0,
        score net.apply(weights init)
        score net.to(device)
        score net model path = os.path.join(file location,
                'saved_models/scorenet_count_ae_' + str(enc_out_dim) +
'.pt')
        generated_data_location = os.path.join(file_location,
                'synthetic data/count ae ' + str(enc out dim) +
'.npy')
        try:
            generated data final =
torch.Tensor(np.load(generated data location))
            print(f'Total records loaded:
{generated_data_final.shape[0]}')
        except:
            generated data final = None
            print("No data loaded")
        checkpoint = torch.load(score net model path,
map location=torch.device(device))
        score net.load state dict(checkpoint['model state dict'])
```

```
reverse sde = ReverseSDE(sde=sde, score net=score net, T=T)
        torchsde SDE = WrapperForTorchSDE(reverse sde=reverse sde,
noise type="diagonal", sde type="ito")
        ts = torch.linspace(0, 1, time_steps + 1) * reverse sde.T
        ts = ts.to(device)
        with torch.no grad():
            assert (
                num samples to generate >= batch size
            ), "Num to generate should be greater than or equal to
batch size.
            batch iter = math.ceil(num samples to generate /
batch size)
            print(f"==> Able to generate {batch iter * batch size}
samples.")
            xs batches = None
            for i in range(0, batch iter):
                print(f"==> Batch {i + 1} out of {batch iter}.")
                x 0 = torch.randn(batch size, enc out dim,
device=device)
                x_batch_solved = torchsde.sdeint(torchsde SDE, x 0,
ts, method="euler")
                with torch.no grad():
                    print(
                        f''==> Decoding data generated in batch \{i + 1\}
out of {batch iter}."
                    x batch solved = torch.stack([x batch solved])
                    for x encoded in x batch solved:
                        out = autoencoder.decode(x_encoded.to(device))
                        out = out.cpu()
                        out = out[-1].round()
                        if generated data final is None:
                            generated data final = out.detach()[:,
0:train data.shape[1]]
                        else:
                            generated data final = torch.cat(
                                 (generated data final,
                                out.detach()[:,
0:train_data.shape[1]]))
                        # del out
                        torch.cuda.empty cache()
                if save generated data:
                    print("==> Saving generated data.")
                    np.save(generated_data_location,
generated data final)
                    print(f'Generated data saved to
```

Generate synthetic data (Learning Rate/Epoch ablation models)

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/main.py
batch size = 128
generate data = False
save generated data = False
enc in dim = train data.shape[1]
if generate data:
    time steps = 1000
    num samples to generate = batch size * 80
    print("==> Commencing reverse solve using torchsde Euler
Maruyama.")
    for model file in os.listdir(file location +
'/ablation saved_models/'):
        enc out dim = 144
        start time = time.time()
        print(f'==> Generating data for {model file}')
        autoencoder = Autoencoder(enc in dim, enc out dim)
        autoencoder model path = os.path.join(file location,
                'saved models/autoencoder count 144.pt')
        checkpoint = torch.load(autoencoder model path,
map location=device)
        autoencoder.load state dict(checkpoint['model state dict'])
        autoencoder.eval()
        autoencoder.to(device)
        sde = VPSDE()
        score net = UNet(
        input channels=1,
```

```
encoded latent embedding dim=enc out dim,
        ch=128,
        ch mult=(1, 2, 2),
        num res blocks=2,
        attn resolutions=(16,),
        resamp with conv=True,
        dropout=0,
        )
        score net.apply(weights init)
        score net.to(device)
        score net model path = os.path.join(file location,
                'ablation synthetic models/' + model file)
        generated data location = os.path.join(file location,
                'ablation_synthetic_data/' + model_file.split('.')[0]
+ '.' + model file.split('.')[1] + '.npy')
        try:
            generated data final =
torch.Tensor(np.load(generated data location))
            print(f'Total records loaded:
{generated_data_final.shape[0]}')
        except:
            generated data final = None
            print("No data loaded")
        checkpoint = torch.load(score net model path,
map location=torch.device(device))
        score net.load state dict(checkpoint['model state dict'])
        reverse sde = ReverseSDE(sde=sde, score net=score net, T=T)
        torchsde SDE = WrapperForTorchSDE(reverse sde=reverse sde,
noise_type="diagonal", sde_type="ito")
        ts = torch.linspace(0, 1, time steps + 1) * reverse sde.T
        ts = ts.to(device)
        with torch.no grad():
            assert (
                num samples to generate >= batch size
               "Num to generate should be greater than or equal to
batch size.'
            batch iter = math.ceil(num samples to generate /
batch_size)
            print(f"==> Able to generate {batch iter * batch size}
samples.")
            xs batches = None
            for i in range(0, batch iter):
                print(f"==> Batch {i + 1} out of {batch iter}.")
```

```
x 0 = torch.randn(batch size, enc out dim,
device=device)
                x batch solved = torchsde.sdeint(torchsde SDE, x 0,
ts, method="euler")
                with torch.no grad():
                    print(
                        f''=> Decoding data generated in batch \{i+1\}
out of {batch iter}."
                    x batch solved = torch.stack([x batch solved])
                    for x encoded in x batch solved:
                        out = autoencoder.decode(x encoded.to(device))
                        out = out.cpu()
                        out = out[-1].round()
                        if generated data final is None:
                            generated data final = out.detach()[:,
0:train data.shape[1]]
                        else:
                            generated data final = torch.cat(
                                (generated_data_final,
                                out.detach()[:,
0:train data.shape[1]]))
                        # del out
                        torch.cuda.empty cache()
                if save generated data:
                    print("==> Saving generated data.")
                    np.save(generated data location,
generated data final)
                    print(f'Generated data saved to
{generated data location}')
                time elapsed = time.time() - start time
                print(f'Time elapsed: {time elapsed} seconds')
                print(f'Total records saved:
{generated data final.shape[0]}')
else:
    print("No data generated.
                               Pre-generated data will be loaded in
the evaluation section.")
                    Pre-generated data will be loaded in the
No data generated.
evaluation section.
```

Generate Synthetic Data (No Autoencoder)

```
# Modified from:
https://github.com/aanaseer/ScoEHR/blob/main/scoehr/main.py
batch_size_no_ae = 64
```

```
generated data location = os.path.join(file location,
'synthetic data/count no ae.npy')
generate data no ae = False
save generated data no ae = False
T = 1
trv:
    generated data final no ae =
torch.Tensor(np.load(generated data location))
    print(f'Total records loaded:
{generated_data_final_no_ae.shape[0]}')
except:
    generated data final no ae = None
    print("No data loaded")
if generate data no ae:
    time steps no ae = 1000
    num samples to generate no ae = batch size no ae * 164
    print("==> Commencing reverse solve using torchsde Euler
Maruyama.")
    reverse_sde_no_ae = ReverseSDE(sde=sde_no_ae,
score net=score net no ae, T=T_no_ae)
    torchsde SDE no ae =
WrapperForTorchSDE(reverse_sde=reverse_sde_no_ae,
noise_type="diagonal", sde_type="ito")
    ts no ae = torch.linspace(0, 1, time steps no ae + 1) *
reverse sde no ae.T
    ts no ae = ts no ae.to(device)
    with torch.no grad():
        assert (
            num_samples_to_generate_no_ae >= batch size no ae
        ), "Num to generate should be greater than or equal to batch
size."
        batch iter no ae = math.ceil(num samples to generate no ae /
batch size no ae)
        print(f"==> Able to generate {batch iter no ae *
batch size no ae} samples.")
        xs batches no ae = None
        for i_no_ae in range(0, batch_iter_no_ae):
            print(f"==> Batch {i no ae + 1} out of
{batch iter no ae}.")
            x_0_no_ae = torch.randn(batch_size_no_ae,
train data no ae.shape[1], device=device)
            x batch solved no ae = torchsde.sdeint(torchsde SDE no ae,
```

```
x 0 no ae, ts no ae, method="euler")
            with torch.no grad():
                # print(
                      f"==> Decoding data generated in batch {i no ae
+ 1} out of {batch_iter_no_ae}."
                x batch solved no ae =
torch.stack([x batch solved no ae])
                for x no ae in x batch solved no ae:
                    out no ae = x no ae
                    out no ae = out no ae.cpu()
                    out_no_ae = out_no_ae[-1].round()
                    if generated_data_final_no_ae is None:
                        generated data final no ae =
out_no_ae.detach()[:, 0:train_data.shape[1]]
                    else:
                        generated data final no ae = torch.cat(
                            (generated data final no ae,
                             out no ae.detach()[:,
0:train data.shape[1]]))
                    # del out
                    torch.cuda.empty cache()
            # if generated data final no ae is None:
                  generated data final no ae = xs batches no ae[:,
0:train data.shape[1]]
            # else:
                  generated data final no ae =
torch.cat((generated data final no ae, xs batches no ae[:,
0:train data.shape[1]]))
            if save_generated_data_no_ae:
                print("==> Saving generated data.")
                np.save(generated_data location,
generated data final no ae)
                print(f'Generated data saved to
{generated data location}')
            print(f'Total records saved:
{generated data final no ae.shape[0]}')
Total records loaded: 10048
```

Evaluation

Metrics Descriptions

The original paper looked at three types of Metrics

1. Quantitative Metrics

- 2. Qualitative Metrics
- 3. Privacy Metrics

1. Quantitative Metrics

1.1 Dimensional Distribution Metric

Assessing if marginal distributions in real data are captured by the synthetic data. ie, for a given category of data, such as age, independent of other variables, the distribution is expected.

Binary Data:

$$DWM = \sum_{i=1}^{N} \dot{c} \frac{1}{n_d} \sum_{i=1}^{n_d} d_j,_i - \hat{d}_j,_i \vee \dot{c}$$

Continuous Variable Data:

$$DEM = \sum_{i=1}^{N} \frac{1}{n_c} \sum_{j=1}^{n_c} \mathbf{c}_j,_i - \hat{c}_j,_i \vee \mathbf{c}$$

Total Score:

$$\frac{DWM+DEM}{N}$$

A lower value indicates that the real and synthetic data have similar marginal relationships.

Results found in the paper:

Model	MIMIC-III Dataset	ED EHR Dataset
medGAN	0.0019 ± 0.0001	0.012 ± 0.001
medBGAN	0.0016 ± 0.0001	0.014 ± 0.001
medWGAN	0.0025 ± 0.0001	0.0088 ± 0.0001
ScoEHR	0.0029 ± 0.0001	0.0037 ± 0.0001

1.2 Pairwise Correlation Difference

Assessing if the correlations in the real and synthetic datasets are similar. The Pearson Correlation Matrices are found for the real and sythetic data which are used to compute the Frobenius Norm of the difference.

$$PCD = \|Corr(D) - Corr(\widehat{D})\|_{E}$$

The closer PCD is to zero, the better the inter-dimensional relationships are caputred by the synthetic data.

Results found in the paper:

Model	MIMIC-III Dataset	ED EHR Dataset
medGAN	120 ± 8	24.1 ± 0.2
medBGAN	146 ± 6	20.7 ± 0.5
medWGAN	22.1 ± 0.4	15.2 ± 0.3
ScoEHR	21.8 ± 0.3	33.6 ± 0.2

1.3 Marginal and Correlation Similarity

Assessing the similarity of the latent structure of the real and synthetic datsets. This is obtained by concatenating both datasets and using k-means clustering to determine 'G' clusters.

$$U = log\left(\frac{1}{G}\right) \sum_{i=1}^{G} \ddot{\iota} \ddot{\iota}$$

- *G* is the number of clusters
- n_i^R is the number of samples from the real dataset
- n_i^S is the number of samples from the synthetic dataset
- n_i is the number of samples in the j-th cluster
- $c \text{ is } \frac{n^R}{n^R + n^S}$

A lower log-cluster score indicates more similarity between the synthetic and real data.

Results found in the paper:

Model	MIMIC-III Dataset	ED EHR Dataset
medGAN	-2.9 ± 0.1	-3.7 ± 0.3
medBGAN	-3.2 ± 0.1	-2.5 ± 0.2
medWGAN	-5.4 ± 0.2	-6.1 ± 0.4
ScoEHR	-6.0 ± 0.1	-7.8 ± 0.5

1.4 Synthetic Ranking Agreement

Assessing the utility of the synethic data for use in downstream machine learning tasks by comparing results obtained through synthetic data and results obtained when using real data. This is obtained by training and testing a machine learning model using both real and synthetic data and finding their respective AUROC.

$$SRA = \frac{1}{L(L-1)} \sum_{i=1}^{L} \sum_{k \neq i} I((A_i - A_k)(B_i - B_k)) > 0$$

- L is the number of machine learning models
- A are a set of AUROC values for models trained and tested with real data

- B are a set of AUROC values for models trained and tested with synthetic data
- *I* is the indicator function.

A higher SRA indicates similarity in machine learning tasks.

Results found in the paper:

Model	MIMIC-III Dataset	ED EHR Dataset
medGAN	0.83 ± 0.02	0.81 ± 0.02
medBGAN	0.86 ± 0.03	0.85 ± 0.03
medWGAN	0.81 ± 0.03	0.83 ± 0.04
ScoEHR	0.87 ± 0.02	0.86 ± 0.03

Note: We chose not to recreate this metric because neither the paper nor the paper's github specified how many or which machine learning tasks were used to generate this metric. The paper also did not explain how they generated truth-values for the synthetic data to use when calculating the AUROC metrics.

2. Qualitative Metrics

Clinician Review

A random mixed set of real and synthetic data was inspected to evaluate realism.

In the paper, 100 synthetic patients and 100 real patients were combined and label as 'realistic' or 'unrealistic' by 3 board certified clinicians.

- If a patient is considered 'unrealistic' if one clinician labeled them as such, 81% of real patients were labeled as real and 81% of synthetic patients were labeled as real
- If a patient is considered realistic if at least one clinician labeled them as realistic, 100% of real and synthetic patients were labeled realistic
- If a patient is considered realistic only if a majority of the 3 clinicians agreed, 93% of real patients were labeled as real and 95% of the synthetic patients were labeled as real

Note: We are not recreating this metric due to lack of connections with board-certified clinicians. This metric is referenced for completeness.

3. Privacy

Assessing if, given a random sample of synthetic data and training data, it could be determined with likely probability that someone's data was used in the training. This is determined by

calculating the Cosine Similarity between the real and synthetic data. If the probabliity is 50% or higher, the patients privacy is considered to be compromised.

Evaluation Code

Evaluation code can be found in the following cells within this section.

Load the data for evaluation purposes

```
# Load the autoencoder ablation data (this includes the primary model
as well)
autoencoder dims = [64, 144, 256, 0]
generated data final = {}
record counts = []
synthetic records = {}
for enc out dim in autoencoder dims:
    if enc out dim == 0:
        generated data location = os.path.join(file location,
          'synthetic data/count no ae.npy')
        generated_data_location = os.path.join(file_location,
          'synthetic data/count ae ' + str(enc out dim) + '.npy')
    generated data final[enc out dim] =
torch.Tensor(np.load(generated data location))
    print(f'{generated data final[enc out dim].shape[0]} records
loaded for {enc out dim} ae')
    record counts.append(generated data final[enc out dim].shape[0])
synthetic data size = min(record counts)
real = test data[0:synthetic data size].to("cpu").detach()
for enc out dim in autoencoder dims:
    synthetic records[enc out dim] = generated data final[enc out dim]
[0:synthetic data size].to("cpu").detach()
ablation files = os.listdir(file location +
'/ablation synthetic data/')
for data file in ablation files:
    generated data location = os.path.join(file location,
'ablation synthetic data', data file)
    generated data final[data file] =
torch.Tensor(np.load(generated data location))
    print(f'{generated data final[data file].shape[0]} records loaded
for {data file} ablation')
    record counts.append(generated data final[data file].shape[0])
synthetic data size = min(record counts)
```

```
real = real[0:synthetic data size].to("cpu").detach()
for data file in ablation files:
    synthetic records[data file] = generated data final[data file]
[0:synthetic data size].to("cpu").detach()
10240 records loaded for 64 ae
10240 records loaded for 144 ae
10240 records loaded for 256 ae
10048 records loaded for 0 ae
10240 records loaded for scorenet count ae 144 epoch25 lr0.001.npy
ablation
10240 records loaded for scorenet count ae 144 epoch12 lr0.001.npy
ablation
10240 records loaded for scorenet count ae 144 epoch50 lr0.001.npy
ablation
10240 records loaded for scorenet count ae 144 epoch30 lr0.005.npy
ablation
10240 records loaded for scorenet count ae 144 epoch75 lr0.001.npy
ablation
10240 records loaded for scorenet count ae 144 epoch30 lr0.00025.npy
ablation
10240 records loaded for scorenet count ae 144 epoch30 lr0.0005.npy
ablation
10240 records loaded for scorenet count ae 144 epoch30 lr0.001.npy
10240 records loaded for scorenet count ae 144 epoch30 lr0.0025.npy
ablation
10240 records loaded for scorenet count ae 144 epoch100 lr0.001.npy
ablation
```

1.1 Dimensional Distribution Metric

```
DDM results = {}
for enc out dim in autoencoder dims:
    print(f'==> Showing results for {enc out dim} Autoencoder:')
    synthetic = synthetic records[enc out dim]
    #Note: Because this is entirely count data, DWM is not needed
    DEM = torch.sum(torch.mean(torch.abs(real - synthetic), axis=0))
    DDM = DEM / len(real)
    DDM = DDM.item()
    DDM results[enc out dim] = DDM
    print(f"Dimensional Distribution Metric: {round(DDM, 4)}")
    DDM original = 0.0029
    DDM compare = round(((DDM - DDM original) / abs(DDM original)) *
100,2)
    if (DDM compare < 0):
      print(f"Recreated results have {abs(DDM compare)}% better
marginal relationships than the original.")
    elif ((DDM compare > 0)):
```

```
print(f"Recreated results have {DDM compare}% worse marginal
relationships than the original.")
    else:
      print("Recreated results have the same marginal relationships as
the original.")
for data_file in ablation files:
      print(f'==> Showing results for {data file} ablation:')
      synthetic = synthetic records[data file]
      #Note: Because this is entirely count data, DWM is not needed
      DEM = torch.sum(torch.mean(torch.abs(real - synthetic), axis=0))
      DDM = DEM / len(real)
      DDM = DDM.item()
      DDM results[data file] = DDM
      print(f"Dimensional Distribution Metric: {round(DDM, 4)}")
      DDM original = 0.0029
      DDM compare = round(((DDM - DDM original) / abs(DDM original)) *
100,2)
      if (DDM compare < 0):
        print(f"Recreated results have {abs(DDM compare)}% better
marginal relationships than the original.")
      elif ((DDM_compare > 0)):
        print(f"Recreated results have {DDM compare}% worse marginal
relationships than the original.")
      else:
        print("Recreated results have the same marginal relationships
as the original.")
==> Showing results for 64 Autoencoder:
Dimensional Distribution Metric: 0.0023
Recreated results have 21.39% better marginal relationships than the
original.
==> Showing results for 144 Autoencoder:
Dimensional Distribution Metric: 0.0021
Recreated results have 27.87% better marginal relationships than the
original.
==> Showing results for 256 Autoencoder:
Dimensional Distribution Metric: 0.0021
Recreated results have 28.7% better marginal relationships than the
original.
==> Showing results for 0 Autoencoder:
Dimensional Distribution Metric: 0.0025
Recreated results have 13.3% better marginal relationships than the
original.
==> Showing results for scorenet count ae 144 epoch25 lr0.001.npy
ablation:
Dimensional Distribution Metric: 0.0022
Recreated results have 22.66% better marginal relationships than the
original.
==> Showing results for scorenet count ae 144 epoch12 lr0.001.npy
```

ablation:

Dimensional Distribution Metric: 0.0021

Recreated results have 26.56% better marginal relationships than the original.

==> Showing results for scorenet_count_ae_144_epoch50_lr0.001.npy ablation:

Dimensional Distribution Metric: 0.0022

Recreated results have 24.89% better marginal relationships than the original.

==> Showing results for scorenet_count_ae_144_epoch30_lr0.005.npy
ablation:

Dimensional Distribution Metric: 5.4636

Recreated results have 188300.88% worse marginal relationships than the original.

==> Showing results for scorenet_count_ae_144_epoch75_lr0.001.npy
ablation:

Dimensional Distribution Metric: 0.0022

Recreated results have 25.36% better marginal relationships than the original.

==> Showing results for scorenet_count_ae_144_epoch30_lr0.00025.npy ablation:

Dimensional Distribution Metric: 0.0019

Recreated results have 34.92% better marginal relationships than the original.

==> Showing results for scorenet_count_ae_144_epoch30_lr0.0005.npy ablation:

Dimensional Distribution Metric: 0.0022

Recreated results have 25.12% better marginal relationships than the original.

==> Showing results for scorenet_count_ae_144_epoch30_lr0.001.npy
ablation:

Dimensional Distribution Metric: 0.0021

Recreated results have 26.64% better marginal relationships than the original.

==> Showing results for scorenet_count_ae_144_epoch30_lr0.0025.npy
ablation:

Dimensional Distribution Metric: 0.0021

Recreated results have 27.18% better marginal relationships than the original.

==> Showing results for scorenet_count_ae_144_epoch100_lr0.001.npy
ablation:

Dimensional Distribution Metric: 0.0021

Recreated results have 25.99% better marginal relationships than the original.

1.2 Pairwise Correlation Difference

```
PCD_results = {}
for enc_out_dim in autoencoder_dims:
```

```
print(f'==> Showing results for {enc out dim} Autoencoder:')
    synthetic = synthetic records[enc out dim]
    corr real = torch.corrcoef(real.T)
    corr synthetic = torch.corrcoef(synthetic.T)
    #This allows us to ignore the rows and columns with no variance
(the nan values)
    corr real[torch.isnan(corr real)] = 0
    corr synthetic[torch.isnan(corr synthetic)] = 0
    PCD = torch.norm(corr real - corr synthetic).item()
    PCD results[enc out dim] = PCD
    PCD original = 21.8
    PCD_compare = round(((PCD - PCD_original) / abs(PCD original)) *
100.2)
    print(f"PCD: {round(PCD, 2)}")
    if (PCD compare < 0):
      print(f"Recreated results have {abs(PCD compare)}% better inter-
dimensional relationships than the original.")
    elif ((PCD compare > 0)):
      print(f"Recreated results have {PCD compare}% worse inter-
dimensional relationships than the original.")
      print("Recreated results have the same marginal inter-
dimensional as the original.")
for data file in ablation files:
      print(f'==> Showing results for {data file} ablation:')
      synthetic = synthetic_records[data_file]
      corr real = torch.corrcoef(real.T)
      corr synthetic = torch.corrcoef(synthetic.T)
      #This allows us to ignore the rows and columns with no variance
(the nan values)
      corr real[torch.isnan(corr real)] = 0
      corr synthetic[torch.isnan(corr synthetic)] = 0
      PCD = torch.norm(corr_real - corr_synthetic).item()
      PCD results[data file] = PCD
      PCD original = 21.8
      PCD compare = round(((PCD - PCD original) / abs(PCD original)) *
100,2)
      print(f"PCD: {round(PCD, 2)}")
      if (PCD compare < 0):
        print(f"Recreated results have {abs(PCD_compare)}% better
inter-dimensional relationships than the original.")
      elif ((PCD compare > 0)):
        print(f"Recreated results have {PCD compare}% worse inter-
```

```
dimensional relationships than the original.")
      else:
        print("Recreated results have the same marginal inter-
dimensional as the original.")
==> Showing results for 64 Autoencoder:
PCD: 33.64
Recreated results have 54.3% worse inter-dimensional relationships
than the original.
==> Showing results for 144 Autoencoder:
PCD: 37.25
Recreated results have 70.88% worse inter-dimensional relationships
than the original.
==> Showing results for 256 Autoencoder:
PCD: 36.47
Recreated results have 67.29% worse inter-dimensional relationships
than the original.
==> Showing results for 0 Autoencoder:
PCD: 28.85
Recreated results have 32.32% worse inter-dimensional relationships
than the original.
==> Showing results for scorenet count ae 144 epoch25 lr0.001.npy
ablation:
PCD: 34.31
Recreated results have 57.36% worse inter-dimensional relationships
than the original.
==> Showing results for scorenet count ae 144 epoch12 lr0.001.npy
ablation:
PCD: 36.3
Recreated results have 66.52% worse inter-dimensional relationships
than the original.
==> Showing results for scorenet count ae 144 epoch50 lr0.001.npy
ablation:
PCD: 37.8
Recreated results have 73.4% worse inter-dimensional relationships
than the original.
==> Showing results for scorenet count ae 144 epoch30 lr0.005.npy
ablation:
PCD: 131.44
Recreated results have 502.95% worse inter-dimensional relationships
than the original.
==> Showing results for scorenet count ae 144 epoch75 lr0.001.npy
ablation:
PCD: 35.55
Recreated results have 63.07% worse inter-dimensional relationships
than the original.
==> Showing results for scorenet count ae 144 epoch30 lr0.00025.npy
ablation:
PCD: 35.65
Recreated results have 63.52% worse inter-dimensional relationships
```

```
than the original.
==> Showing results for scorenet count ae 144 epoch30 lr0.0005.npy
ablation:
PCD: 36.95
Recreated results have 69.48% worse inter-dimensional relationships
than the original.
==> Showing results for scorenet count ae 144 epoch30 lr0.001.npy
ablation:
PCD: 39.51
Recreated results have 81.22% worse inter-dimensional relationships
than the original.
==> Showing results for scorenet count ae 144 epoch30 lr0.0025.npy
ablation:
PCD: 39.15
Recreated results have 79.61% worse inter-dimensional relationships
than the original.
==> Showing results for scorenet count ae 144 epoch100 lr0.001.npy
ablation:
PCD: 38.59
Recreated results have 77.0% worse inter-dimensional relationships
than the original.
```

1.3 Marginal and Correlation Similarity

Change **generate_U_results** to True to generate results - otherwise pre-generated results are used. Note that this takes substantial time if run on a CPU-only machine.

20 was chosen for G (the number of clusters), because the ScoEHR paper did not specify how many clusters they used, however they referenced the Generation and evaluation of synthetic patient data[4] paper which used 20 clusters.

```
generate_U_results = False

G = 20

U_results = {}

if generate_U_results:
    for enc_out_dim in autoencoder_dims:
        print(f'==> Showing results for {enc_out_dim} Autoencoder:')
        synthetic = synthetic_records[enc_out_dim]
        all = np.concatenate((real, synthetic))
        kmeans_model = sklearn.cluster.KMeans(n_clusters=G,
random_state=1, init='k-means++', n_init=10).fit(all)
        kmeans_labels = kmeans_model.labels_
        real_count_per_cluster =
torch.tensor(np.bincount(kmeans_labels[0:len(real)]))
        count_per_cluster = torch.tensor(np.bincount(kmeans_labels))

c = len(real) / (len(real) + len(synthetic))
```

```
U = float(math.log(1/G) *
torch.sum(torch.pow((real count per cluster/count per cluster) -
(c,2))
        U results[enc out dim] = U
        U original = -6.0
        U compare = round(((U - U original) / abs(U original)) *
100,2)
        print(f"U: {round(U, 2)}")
        if (U compare < 0):
          print(f"Recreated results have {abs(U compare)}% better
similarity between the synthetic and real data than the original.")
        elif ((U compare > 0)):
          print(f"Recreated results have {U compare}% worse similarity
between the synthetic and real data than the original.")
        else:
          print("Recreated results have the same similarity between
the synthetic and real data as the original.")
    for data file in ablation files:
        print(f'==> Showing results for {data file} Autoencoder:')
        synthetic = synthetic_records[data_file]
        all = np.concatenate((real, synthetic))
        kmeans model = sklearn.cluster.KMeans(n clusters=G,
random state=1, init='k-means++', n init=10).fit(all)
        kmeans labels = kmeans model.labels
        real count per cluster =
torch.tensor(np.bincount(kmeans labels[0:len(real)]))
        count per cluster = torch.tensor(np.bincount(kmeans labels))
        c = len(real) / (len(real) + len(synthetic))
        U = float(math.log(1/G) *
torch.sum(torch.pow((real_count_per_cluster/count_per_cluster) -
(c,2))
        U results[data file] = U
        U original = -6.0
        U_compare = round(((U - U_original) / abs(U original)) *
100,2)
        print(f"U: {round(U, 2)}")
        if (U compare < 0):
          print(f"Recreated results have {abs(U compare)}% better
similarity between the synthetic and real data than the original.")
        elif ((U compare > 0)):
          print(f"Recreated results have {U compare}% worse similarity
between the synthetic and real data than the original.")
        else:
          print("Recreated results have the same similarity between
the synthetic and real data as the original.")
else:
    print("Loading pre-generated U results.")
```

```
U results = \{64: -3.466517448425293,
      144: -5.009627819061279.
      256: -3.68813157081604,
      0: -3.2830593585968018.
      'scorenet_count_ae_144_epoch25_lr0.001.npy': -4.556731224060059,
      'scorenet_count_ae_144_epoch12_lr0.001.npy': -6.487917423248291,
      'scorenet count ae 144 epoch50 lr0.001.npy': -
3.4607372283935547,
      'scorenet count ae 144 epoch30 lr0.005.npy': -29748.265625,
      'scorenet count ae 144 epoch75 lr0.001.npy': -3.354243040084839,
      'scorenet count ae 144 epoch30 lr0.00025.npy': -
5.999951362609863,
      'scorenet count ae 144 epoch30 lr0.0005.npy': -
3.6509108543395996.
      'scorenet count ae 144 epoch30 lr0.001.npy': -5.168017387390137,
      'scorenet count ae 144 epoch30 lr0.0025.npy': -
5.266237258911133,
      'scorenet count ae 144 epoch100 lr0.001.npv': -
3.966243267059326}
Loading pre-generated U results.
```

3. Privacy

```
Privacy results = {}
for enc out dim in autoencoder dims:
    print(f'==> Showing results for {enc out dim} Autoencoder:')
    synthetic = synthetic records[enc out dim]
    cosine sim = torch.nn.functional.cosine similarity(real,
synthetic, dim=1)
    privacy = ((\cos ine \sin > 0.5).sum() / \cos ine sim.shape[0]).item()
    Privacy results[enc out dim] = privacy
    print(f"Privacy is NOT protected for {round(privacy * 100, 2)} %
of patients")
for data file in ablation files:
    print(f'==> Showing results for {data file} ablation:')
    synthetic = synthetic_records[data_file]
    cosine sim = torch.nn.functional.cosine similarity(real,
synthetic, dim=1)
    privacy = ((cosine_sim > 0.5).sum() / cosine_sim.shape[0]).item()
    Privacy_results[data_file] = privacy
    print(f"Privacy is NOT protected for {round(privacy * 100, 2)} %
of patients")
==> Showing results for 64 Autoencoder:
Privacy is NOT protected for 2.23 % of patients
```

```
==> Showing results for 144 Autoencoder:
Privacy is NOT protected for 2.79 % of patients
==> Showing results for 256 Autoencoder:
Privacy is NOT protected for 2.46 % of patients
==> Showing results for 0 Autoencoder:
Privacy is NOT protected for 1.79 % of patients
==> Showing results for scorenet count ae 144 epoch25 lr0.001.npy
ablation:
Privacy is NOT protected for 2.53 % of patients
==> Showing results for scorenet count ae 144 epoch12 lr0.001.npy
ablation:
Privacy is NOT protected for 1.99 % of patients
==> Showing results for scorenet count ae 144 epoch50 lr0.001.npy
Privacy is NOT protected for 2.59 % of patients
==> Showing results for scorenet count ae 144 epoch30 lr0.005.npy
ablation:
Privacy is NOT protected for 0.0 % of patients
==> Showing results for scorenet count ae 144 epoch75 lr0.001.npy
ablation:
Privacy is NOT protected for 2.68 % of patients
==> Showing results for scorenet count ae 144 epoch30 lr0.00025.npy
ablation:
Privacy is NOT protected for 2.81 % of patients
==> Showing results for scorenet count ae 144 epoch30 lr0.0005.npy
ablation:
Privacy is NOT protected for 2.49 % of patients
==> Showing results for scorenet count ae 144 epoch30 lr0.001.npy
ablation:
Privacy is NOT protected for 2.64 % of patients
==> Showing results for scorenet count ae 144 epoch30 lr0.0025.npy
Privacy is NOT protected for 3.03 % of patients
==> Showing results for scorenet_count_ae 144 epoch100 lr0.001.npy
ablation:
Privacy is NOT protected for 2.5 % of patients
```

Results

Table of Results

Utility metrics measured with data generated using MIMIC-III dataset for all models. Results for medGAN, medBGAN, medWGAN, and ScoEHR from ScoEHR paper[1], while our results were determined by experiment. The best results for each metric are indicated in bold.

Model	Log-Cluster (U)	PCD	Dimensional Distribution (DDM)	Records Not Privacy Protected (%)
medGAN	-2.9	120	0.0019	N/A
medBGAN	-3.2	146	0.0016	N/A
medWGAN	-5.4	22.1	0.0025	N/A
ScoEHR	-6.0	21.8	0.0029	0%
Team 97 ScoEHR Recreation	-5.0	37.3	0.0021	2.8%

Claims Supported by Experiment Results

The code to generate the above table of results, including our experiment results, can be found in the cell titled *Code to generate the table of results*. The Team 97 ScoEHR Recreation results are the results in the 144 model line (this is the 144-feature autoencoder which matches the autoencoder size from the paper).

Results With Respect to the Hypothesis and Results From the Original Paper

As noted in the scope of reproducibility, two central hypotheses were tested as a part of this paper: ScoEHR produces higher-quality synthetic data than the previously-leading synthetic EHR models and United States board-certified physicians cannot differentiate between the synthetic data produced by ScoEHR and real EHR data.

1. Hypothesis 1:

- Hypothesis: The first hypothesis was tested by comparing ScoEHR against the three-leading synthetic EHR models (medGAN, medWGAN, and medBGAN) on four key areas: preservation of feature marginal relationships, preservation of feature correlations, preservation of full feature distributing using log-clusters, and synthetic data performance in downstream predictions of patient outcomes.
- Original Paper's Results: As can be seen in the results table, the ScoEHR paper's results
 did demonstrate that ScoEHR produced higher-quality synthetic data than the
 previously-leading synthetic EHR models. While the ScoEHR generated data didn't show
 top results in every category (it had the worst results for Dimensional Distribution), it did
 in two of the three categories of the categories (log-clustering and PCD), demonstrating
 that overall its results were better than that of the other three-leading synthetic EHR
 models.
- Our Recreation Results: While we were not able to exactly match the metrics from the ScoEHR paper (our log-cluster metric was -5.0 instead of -6.0 in the original paper, our PCD was 37.3 instead of 21.8 in the original paper, and our dimensional distribution was 0.0021 instead of 0.0029 in the original paper as a reminder lower results are better for each category), our results were still similar to the results from the paper and arguably in line with the three-leading synthetic EHR models. For example, our log-cluster metric (-5.0) was better than two of the three comparison models (-2.9 for medGAN, -3.2 for

medBGAN, and -5.4 for medWGAN), our PCD metric (37.3) was better than two of the three comparison models (120 for medGAN, 146 for medBGAN, and 22.1 for medWGAN), and our dimensional distribution metric (0.0021) was better than one of the three comparison models (0.0019 for medGAN, 0.0016 for medBGAN, and 0.0025 for medWGAN) and was better than the results in the original paper (0.0029). Based on these results, while we were not able to exactly match the paper's results, I would argue that we were very close (and debatably reached) the original hypothesis that our synthetic generated data was better than the three-leading synthetic EHR models.

1. Hypothesis 2:

- **Hypothesis:** The second hypothesis was tested by presenting both synthetic and real EHR data to physicians and asking them to identify the "real" data. By looking at what portion of synthetic data they identified as "real" and comparing it with the portion of real data they identified as "real" the authors were able to determine that physicians were not able to tell the difference between the synthetic and real data.
- Original Paper's Results: In the original paper, the authors reported three different ways to test this hypothesis. First, they marked a patient as unrealistic if at least one clinician labeled them as unrealistic for this test 81% of the real patients were marked as real, and 81% of the synthetic patients were marked as real, showing no noticeable difference between the real and synthetic data. For the second test, patients were marked as real if at least one clinician labeled them as real. In that test, 100% of both the real and synthetic patients were marked as real in the final test, patients were marked as real if a majority of clinicians labeled them as real in this test 93% of the real patients were marked as real while 95% of the synthetic patients were marked as real. These three tests demonstrated that the paper was able to match its hypothesis and the synthetic data was not distinguishable from the real data by clinicians.
- Our Recreation Results: Due to a lack of access to medical clinicians we did not attempt to recreate this section; however, we still included it here for completeness.

Experiments Beyond the Original Paper

We tested two experiments beyond the original paper:

- 1. Feature frequency analysis of the autoencoder
- 2. Feature frequency of synthetic data

Feature frequency analysis of the autoencoder

- Overview: The original paper didn't discuss the autoencoder in great detail or explain why they chose the hidden layer dimension they did beyond the fact that it is close to hidden dimensions chosen in previous papers. One additional experiment we wanted to run was to understand how closely the autoencoder would be able to recreate the original dataset (so taking the test data, encoding it, decoding it, and seeing how close the decoded data was to the original results. To do this, we created a visual representation of the frequency of features in the original dataset compared to the frequency of features in the encoded-decoded dataset.
- Results: Shown below the cell titled Feature frequency analysis of the autoencoder

 Discussion: As you can see, all three encoded-decoded datasets have a feature distribution that is roughly similar to the original feature distribution, getting closer to the original feature distribution as the dimensionality of the autoencoder increases. This suggests that the autoencoders do a good job of recreating the original data, but with higher dimensional autoencoders doing a better job (as expected).

Feature frequency of the synthetic data

• Overview: While the original paper compared the synthetic data against the real data using a variety of metrics, one metric they didn't compare was the frequency of ICD codes in the real data vs. the synthetic data. It's possible for the synthetic data to have similar ICD-code relationships as the real data (e.g., ICD codes appear in the same pairs), and the same relative frequency across ICD codes without the overall frequency matching the real data. If the synthetic data is used for a test that is dependent on the raw frequency of the data, its possible to get different results if the average frequency in the synthetic data doesn't match the average frequency in the real world. To confirm that the synthetic data and the real data have a similar frequency, an experiment was run that looked at the raw frequency (average count) across all ICD codes across all records.

Results:

- Frequency of real data ICD codes: 0.0132
- Frequency of synthetic data ICD codes: 0.0083
- Note: These results can be found in the cell titled Code for the feature frequency analysis of synthetic data
- Discussion: As can be seen in the results, there is a significant difference between the average ICD code frequency in the synthetic data compared to the real data, even though the results are *good* based on the metrics in the original paper. This would suggest that more work is needed to determine what metrics are needed to determine that synthetic data and real data are similar.

Ablation Study

We tested three ablations:

- 1. Synthetic data results without using an autoencoder
- 2. Synthetic data results with a varied UNet learning rate
- 3. Synthetic data results with a varied UNet epoch count

Synthetic Data Results With Autoencoder Variations

Overview: This was a recreation of an ablation included in the original paper which
hypothesized that the synthetic data generated using an autoencoder would be
more accurate than the synthetic data generated without using an autoencoder. In
addition, we tested autoencoders with different numbers of features. While the
paper didn't fully explain their thought process around why removing the

autoencoder would make results worse, we assume it is because the autoencoder would help to identify relationships between ICD codes that frequently occur together which would help improve the metrics (and take the responsibility of identifying all of the ICD code relationships off of the UNet).

Results:

Madal	Lan Chartan (LI)	DCD	Dimensional Distribution
Model	Log-Cluster (U)	PCD	(DDM)
Paper ScoEHR (144 Feature Autoencoder)	-6.0	21.8	0.0029
Team 97 ScoEHR 64 Feature Autoencoder	-3.5	33.6	0.0023
Team 97 ScoEHR 144 Feature Autoencoder	-5.0	37.3	0.0021
Team 97 ScoEHR 256 Feature Autoencoder	-3.7	36.5	0.0021
Paper ScoEHR No Autoencoder	-1.4	22.8	5
Team 97 No Autoencoder	-3.3	28.8	0.0025

Note: These results can be found in the cell titled *Code to generate the table of results*.

• Discussion: While our results aligned with the hypothesis that no autoencoder would produce worse results than using an autoencoder (two of the three metrics were better with the autoencoder than with no autoencoder), one of our results, the dimensional distribution metric was significantly different than the ablation within the paper (0.0025 for our recreation vs 5 for the paper). Our no autoencoder result was relatively close to the results for the autoencoder model, while the paper indicated that no autoencoder was so far off from the autoencoder results that it should not be considered. We haven't found anything that would explain these differences, and we assume that our implementation for no autoencoder was significantly different from the way the paper implemented it. In addition to this, our results showed that the autoencoder with 144 features (as described in the paper) produced the best results.

Synthetic Data Results With a Varied UNet Learning Rate

- Overview: A critical hyperparameter, the learning rate, was adjusted between a range of 0.00025 and 0.005 in order to see if there are any differences in found local minimas.
- Results

Model	Log-Cluster (U)	PCD	Dimensional Distribution (DDM)
0.00025 Learning Rate	-6.0	35.6	0.0019
0.0005 Learning Rate	-3.7	36.9	0.0022
0.001 Learning Rate	-5.2	39.5	0.0021
0.0025 Learning Rate	-5.3	39.2	0.0021
0.005 Learning Rate	-29748	131.4	5.4636

Note: These results can be found in the cell titled *Code to generate the table of results*

• Discussion: As expected, the smaller, more granular, learning rate has the best performance, likely due to being more sensitive to finding local minimas. Despite this, all of the metrics for learning rates between 0.00025 and 0.0025 had comparable results. It is not until the learning rate is set to 0.005 that we see a significant degradation in the quality of the synthetic data.

Synthetic Data Results With a Varied UNet Epoch Count

- Overview: The number of epochs, a key metric that is not discussed or justified within the paper. Using a range of 12 to 100 epochs, we investigate when loss seems to converge and metrics no longer improve.
- Results

Model	Log-Cluster (U)	PCD	Dimensional Distribution (DDM)
12 Epochs	-6.5	36.3	0.0021
25 Epochs	-4.6	34.3	0.0022
30 Epochs	-5.2	39.5	0.0021
50 Epochs	-3.5	37.8	0.0022
75 Epochs	-3.4	35.6	0.0022
100 Epochs	-4.0	38.6	0.0021

Note: These results can be found in the cell titled *Code to generate the table of results*

 Discussion: While the paper seemed to prefer an epoch of 20, we noticed that our results converged around 50 epochs. There are some oddities with our results, such as a Log-Cluster spike at 30 epochs before going back down, PCD oscilating through epochs, and Dimensional Distribution staying very tight.

Code to generate the table of results

```
#Modified from https://stackoverflow.com/questions/35160256/how-do-i-
output-lists-as-a-table-in-jupyter-notebook
DDM results["Paper"] = 0.0029
PCD results["Paper"] = 21.8
U_results["Paper"] = -6.0
Privacy_results["Paper"] = 0
DDM results["Paper No AE"] = 5
PCD results["Paper No AE"] = 22.8
U_results["Paper No AE"] = -1.4
Privacy results["Paper No AE"] = 0
DDM results["medGAN"] = 0.0019
PCD results["medGAN"] = 120
U results["medGAN"] = -2.9
Privacy results["medGAN"] = 0
DDM results["medBGAN"] = 0.0016
PCD results["medBGAN"] = 146
U results["medBGAN"] = -3.2
Privacy_results["medBGAN"] = 0
DDM results["medWGAN"] = 0.0025
PCD results["medWGAN"] = 22.1
U results["medWGAN"] = -5.4
Privacy results["medWGAN"] = 0
data = []
data.append(["Model", "DDM", "PCD", "U", "Privacy (%)"])
model_list = autoencoder_dims + ablation_files + ["Paper", "Paper No
AE", "medGAN", "medBGAN", "medWGAN"]
for model in model list:
    data row = [model,
                str(round(DDM results[model], 4)),
                str(round(PCD_results[model], 1)),
                str(round(U results[model], 2)),
                str(round(Privacy results[model] * 100, 2))]
    data.append(data row)
def print matrix(list of list):
    #Determine the width of each column
    col width = [0 for i in list of list[0]]
    for list in list of list:
        for i in range(len(list)):
```

```
col width[i] = max(col width[i], len(str(list[i])))
   number width = len(str(max([len(i) for i in list of list])))
   cols = max(map(len, list of list))
   output = ""
   #Create first row
   output += "+"
   for width in col_width:
      output += "-"*(width+2)+"+"
   output += "\n"
   #Create data rows
   for i in range(len(list of list)):
      list = list of list[i]
      output += "|"
      for j in range(len(list)):
         item = str(list[j])
         output += " "
         output += item
         output += " "*(col width[j]-len(item))
         output += " |"
      output += "\n"
      if i != len(list of_list)-1:
         output += "+"
         for width in col_width:
            output += "-"*(width+2)+"+"
         output += "\n"
   #Create last row
   output += "+"
   for width in col_width:
      output += "-"*(width+2)+"+"
   output += "\n"
   return output
print(print matrix(data))
+-----+
                          | Model
| Privacy (%) |
+----+
64
                                   | 0.0023 | 33.6 | -3.47
| 2.23 |
      -----
```

```
+-----+
           | 0.0021 | 37.3 | -5.01
144
2.79
+-----
            | 0.0021 | 36.5 | -3.69
256
2.46
+-----
+------
          | 0.0025 | 28.8 | -3.28
1.79
+-----
+-----+
+-----
+-----
| scorenet_count_ae_144_epoch12_lr0.001.npy                                  | 0.0021 | 36.3 | -6.49
.
+-----+----+----+
+-----+
scorenet_count_ae_144_epoch50_lr0.001.npy | 0.0022 | 37.8 | -3.46
| 2.59 |
+-----+----+-----
+-----+
29748.27 | 0.0 |
+-----
+-----
1 2.68
+-----
scorenet count ae 144 epoch30 lr0.00025.npy | 0.0019 | 35.6 | -6.0
+-----
+-----+
scorenet count ae 144 epoch30 lr0.0005.npy | 0.0022 | 36.9 | -3.65
2.49
+-----+----+-----
+-----+
+-----
+-----+
| 3.03 |
+-----
+-----+
```

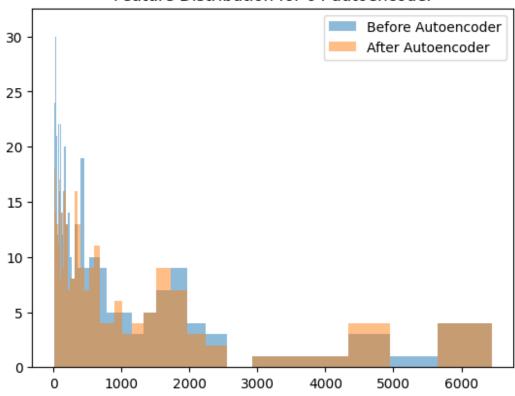
```
scorenet count ae 144 epoch100 lr0.001.npy | 0.0021 | 38.6 | -3.97
    +-----+
         | 0.0029 | 21.8 | -6.0
Paper
·
+-----+----+-----+
+-----+
           | 5 | 22.8 | -1.4
| Paper No AE
+-----+
       | 0.0019 | 120 | -2.9
| medGAN
+-----+----+-----
+----+
            | 0.0016 | 146 | -3.2
| medBGAN
| 0
.
+-----+----+----+
+-----+
    | 0.0025 | 22.1 | -5.4
medWGAN
+-----+----+-----
+----+
```

Feature frequency analysis of the autoencoder

```
for enc out dim in autoencoder dims:
    if enc out dim == 0:
        continue
    autoencoder = Autoencoder(enc in dim, enc out dim)
    autoencoder model path = os.path.join(file location,
            'saved_models/autoencoder_count_' + str(enc_out_dim) +
'.pt')
    checkpoint = torch.load(autoencoder model path,
map location=device)
    autoencoder.load state dict(checkpoint['model state dict'])
    autoencoder.eval()
    autoencoder.to(device)
    test data encoded = autoencoder.encode(test data).detach()
    test data decoded = autoencoder.decode(test data encoded).detach()
    print(f'Showing feature distribution for {enc out dim}
autoendoer.')
    print("")
    test_data_decoded_count = test_data_decoded.round()
```

```
print("Original Test Data Mean: ", test_data.mean())
    print("After Autoencoder Test Data Mean ",
test data decoded count.mean())
    test data np = test data.sum(axis=0).cpu().numpy()
    test data decoded np =
test_data_decoded_count.sum(axis=0).cpu().numpy()
    \max count = \max(test data np.\max(), test data decoded np.\max())
    bins = np.logspace(1.0, np.log10(max count), num=50)
    pyplot.title(f'Feature Distribution for {enc out dim}
autoencoder')
    pyplot.hist(test data np, bins, alpha=0.5, label='Before
Autoencoder')
    pyplot.hist(test data decoded np, bins, alpha=0.5, label='After
Autoencoder')
    pyplot.legend(loc='upper right')
    pyplot.show()
    print("")
    del autoencoder
    qc.collect()
    if device == "cuda":
        torch.cuda.empty cache()
Showing feature distribution for 64 autoendoer.
Original Test Data Mean: tensor(0.0131)
After Autoencoder Test Data Mean tensor(0.0117)
```

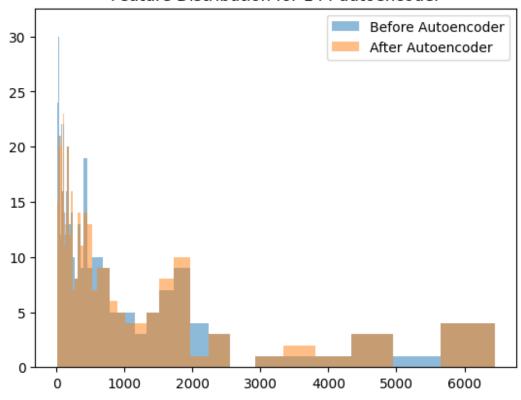
Feature Distribution for 64 autoencoder



Showing feature distribution for 144 autoendoer.

Original Test Data Mean: tensor(0.0131)
After Autoencoder Test Data Mean tensor(0.0126)

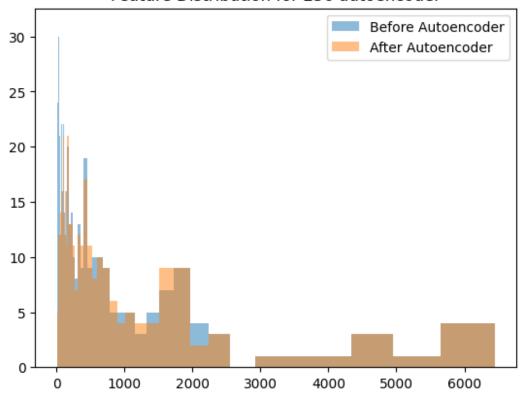
Feature Distribution for 144 autoencoder



Showing feature distribution for 256 autoendoer.

Original Test Data Mean: tensor(0.0131)
After Autoencoder Test Data Mean tensor(0.0126)

Feature Distribution for 256 autoencoder



Code for the feature frequency analysis of synthetic data

```
for data file in ablation files:
    print(f'==> Showing results for {data file} ablation:')
    print(synthetic records[data file].mean())
for enc out dim in autoencoder dims:
    print(f'==> Showing results for {enc out dim} Autoencoder:')
    print(synthetic records[enc out dim].mean())
print("==> Showing results for real data")
print(real.mean())
==> Showing results for scorenet count ae 144 epoch25 lr0.001.npy
ablation:
tensor(0.0102)
==> Showing results for scorenet count ae 144 epoch12 lr0.001.npy
ablation:
tensor(0.0087)
==> Showing results for scorenet count ae 144 epoch50 lr0.001.npy
ablation:
tensor(0.0094)
==> Showing results for scorenet count ae 144 epoch30 lr0.005.npy
ablation:
```

```
tensor(51.2590)
==> Showing results for scorenet count ae 144 epoch75 lr0.001.npy
ablation:
tensor(0.0093)
==> Showing results for scorenet count ae 144 epoch30 lr0.00025.npy
ablation:
tensor(0.0062)
==> Showing results for scorenet count ae 144 epoch30 lr0.0005.npy
ablation:
tensor(0.0093)
==> Showing results for scorenet count ae 144 epoch30 lr0.001.npy
ablation:
tensor(0.0088)
==> Showing results for scorenet count ae 144 epoch30 lr0.0025.npy
ablation:
tensor(0.0088)
==> Showing results for scorenet count ae 144 epoch100 lr0.001.npy
ablation:
tensor(0.0091)
==> Showing results for 64 Autoencoder:
tensor(0.0106)
==> Showing results for 144 Autoencoder:
tensor(0.0085)
==> Showing results for 256 Autoencoder:
tensor(0.0083)
==> Showing results for 0 Autoencoder:
tensor(0.0128)
==> Showing results for real data
tensor(0.0132)
```

Discussion

Implications of the Experimental Results

The implications of the experimental results are significant in the world of synthetically generated health data. We were able to recreate results showing that using the ScoEHR model architecture to generate synthetic health data produced results that were at least as good as other leading synthetic generation models, if not better, based on the measured metrics. While we don't think that these metrics show the full picture of whether synthetic data is close enough to real data to be able to be in its place (for example because the frequency of ICD codes is significantly different even if the metrics are promising), it is a big step in the right direction of synthetically generated health data.

Whether the Original Paper Was Reproducible (and If It Wasn't, What Factors Made It Irreproducible)

We found that overall the original paper was reproducible, and even though we weren't able to reproduce the exact same measures of the metrics as the paper, we were able to generate synthetic health data using their model architecture, and our metrics were relatively similar to their metrics. Some of the things that prevented us from exactly reproducing their model included the fact that they did not specify the exact hyperparameter values for their model, and they did not provide enough information in the paper or in the GitHub code to be confident that we are recreating their metrics in the exact same way. As mentioned later in 'What Was Hard - Understanding Metrics', due to vagueness within the original paper, the Synthetic Ranking Agreement metric was unable to be replicated. Never the less, we found it promising that our results were similar to the original paper's results.

What Was Easy

Understanding the Autoencoder Architecture

The autoencoder architecture in the paper was a standard autoencoder architecture, and the code was relatively easy to follow. Understanding and recreating this section of the paper was therefore straightforward and easy.

Access to Code in GitHub

Having access to the author's code in GitHub made the process of reproducing the paper significantly easier than it would have been otherwise. Interpreting and developing both the UNet that the authors used, as well as the author's variance-preserving stochastic differential equations (VPDSE) implementation would have been extremely challenging without having their original code to work from, and a different implementation of it would likely have resulted in results that differed even further from the original paper authors' results.

What Was Difficult

Understanding the UNet and VPSDE Architecture and Diffusion Model

We found it challenging to understand both the UNet and VPSDE architecture that the authors used in the paper, as well as the concept of diffusion models. We had not previously worked with diffusion models, and needed to understand them before the chapter in the course's textbook was released, so this required substantial external research to understand. This, paired with needing to learn about UNets and a refresher on stochastic differential equations meant that a substantial amount of independent research was needed to be able to understand the structure of the paper model's architecture.

Computational Requirements

Several of the models required a substantial amount of time both to train as well as to generate the synthetic data. For example, the ablation model that did not use an autoencoder (and therefore had a higher feature dimension) required ~13 hours between training and generating one set of synthetic data using a T4 GPU; with just a CPU this time would have been significantly

higher. This was a challenge for two reasons. First, it required us to explore cloud machine learning training locations as none of us had access to a GPU with enough RAM to run the model locally. Second, it meant that iterating and testing different results took a substantial amount of time.

Determining Correct Hyperparameters

We found identifying the correct hyperparameters (e.g., batch size, number of epochs for training the autoencoder, number of epochs for training the UNet, autoencoder learning rate, UNet learning rate, etc.) to be challenging because these hyperparameters were not specified in the original paper. Additionally, while the paper's GitHub code specified some example hyperparameters, these were specified for a data set that we did not use, and it was unclear if they used the same parameters for all data sets or if they varied for each data set. This challenge was part of the reason that we tested different ablations for learning rates and number of epochs to identify how much varying these hyperparameters would impact the end results.

Understanding Metrics

We found it challenging to understand the metrics that were used to calculate the final results in the paper. While some of the metrics were explained in a way that was clear how to implement them, in other cases insufficient detail was given to ensure that we could clearly recreate them. For example, for the log-cluster metric the paper specified the math that was used to calculate it, but included a variable, G, for the number of k-means clusters that should be used and G was never defined. Additionally, for the Synthetic Ranking Agreement, the paper specified that when using synthetic and real data for machine learning tasks there should be the same results, however the authors did not describe which machine learning tasks they used for the test. Additionally, since the synthetic data is unlabeled, we were unable to understand how to produce a AUROC score. These issues were compounded by the fact that non of the metrics were included in the GitHub code.

Recommendations to the Original Authors or Others Who Work in This Area For Improving Reproducibility

Better Documentation of Hyperparameters

Better documentation of hyperparameters would make it significantly easier to reproduce the results from this paper. We would encourage the original authors to specify what they used for each hyperparameter, and we would encourage others who work in this area to review our ablation results when deciding what to use for each hyperparameter.

Better Documentation of Metrics

Better documentation of the metrics - not just what they are but also how they are specifically implemented in these examples would make it easier to reproduce the results of this paper. For others who work in this area, we would encourage them to review our code for how we implemented these metrics as a baseline. Additionally, for metrics that we chose not to implement due to a lack of clarity in the paper/GitHub code, we were sometimes able to find examples of how other researchers implemented them by reviewing similar papers from the references section of the ScoEHR paper, and we'd encourage others to do the same thing.

Additional Discussions

Data Preprocessing using pyhealth.datasets.MIMIC3Dataset

We successfully attempted to preprocess the data and generate the matrix file using the pyhealth.datasets.MIMIC3Dataset. Basic information from the PATIENTS and ADMISSIONS tables was retrieved, and the DIAGNOSES_ICD table was loaded explicitly using PyHealth. To utilize the pyhealth.datasets.MIMIC3Dataset, we needed to download the PATIENTS.csv file in addition to the ADMISSIONS and DIAGNOSES_ICD CSV files. The code for this process is available in the Colab notebook at the following GitHub link:

Data Preprocessing using pyhealth.ipvnb.

Loading Synthetic data using pyhealth SampleData set

We attempted to load the generated synthetic data to pyHealth SampleData set. Since the generated data does not have the actual ICD9 code labels and visits information, we were only able to load all count data into a single visit for each patient. The code for this process is available in the colab notebook at the fillowing Github link: pyhealthSampleDataset.ipynb

Public GitHub Repo

URL: https://github.com/sjoslin2/Spring-24-DLH

References

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