4. Matrix Decompositions (Exercises Only)

Exercises

4.1

Compute the determinant using Laplace Expansion (using the first row) and the Sarrus Rule for:

$$A = egin{bmatrix} 1 & 3 & 5 \ 2 & 4 & 6 \ 0 & 2 & 4 \end{bmatrix}$$

Starting out with the Laplace expansion method, we find the minors:

$$A_{11} = egin{bmatrix} 4 & 6 \ 2 & 4 \end{bmatrix} \ A_{12} = egin{bmatrix} 2 & 6 \ 0 & 4 \end{bmatrix} \ A_{13} = egin{bmatrix} 2 & 4 \ 0 & 2 \end{bmatrix}$$

Now we find the determinants of the minors:

$$\det(A_{11}) = 16 - 12 = 4$$
 $\det(A_{12}) = 8 - 0 = 8$ $\det(A_{13}) = 4 - 0 = 4$

And now the cofactors:

$$C_{11} = -1^2(4) = 4$$
 $C_{12} = -1^3(8) = -8$ $C_{13} = -1^4(4) = 4$

And now we can compute the determinant:

$$\det(A) = a_{11}C_{11} + a_{12}C_{12} + a_{13}C_{13}$$

$$= 1(4) + 3(-8) + 5(4)$$

$$= 4 - 24 + 20$$

$$= 0$$

Now we can compute the determinant using the Sarrus Rule:

$$\det(A) = a_{11}a_{22}a_{33} + a_{21}a_{32}a_{13} + a_{31}a_{12}a_{23} - a_{31}a_{22}a_{13} - a_{11}a_{32}a_{23} - a_{21}a_{12}a_{33}$$

$$= 1(4)(4) + 2(2)(5) + 0(3)(6) - 0(4)(5) - 1(2)(6) - 2(3)(4)$$

$$= 16 + 20 - 12 - 24$$

$$= 36 - 36$$

$$= 0$$

4.2

Compute the following determinant efficiently:

$$\begin{vmatrix} 2 & 0 & 1 & 2 & 0 \\ 2 & -1 & 0 & 1 & 1 \\ 0 & 1 & 2 & 1 & 2 \\ -2 & 0 & 2 & -1 & 2 \\ 2 & 0 & 0 & 1 & 1 \end{vmatrix}$$

Since it doesn't specify a method I think I will get it in upper triangular form using Gaussian Elimination, then take the product of the diagonal elements to find the determinant.

After performing Gaussian Elimination we get:

$$\begin{bmatrix} 2 & 0 & 1 & 2 & 0 \\ 0 & -1 & -1 & -1 & 1 \\ 0 & 0 & 1 & 0 & 3 \\ 0 & 0 & 0 & 1 & -7 \\ 0 & 0 & 0 & 0 & -3 \end{bmatrix}$$

We didn't perform any row swaps or scaling of rows so we don't need to worry about that. Now we take the product of the diagonal elements to find the determinant:

$$\det(A) = 2(-1)(1)(1)(-3) = 6$$

4.3

Compute the eigenspaces of:

$$\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \quad \begin{bmatrix} -2 & 2 \\ 2 & 1 \end{bmatrix}$$

Starting with: $\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$:

We start out by finding the characteristic polynomial:

$$\det(A-\lambda I) = egin{array}{cc} 1-\lambda & 0 \ 1 & 1-\lambda \ \end{pmatrix} = 0$$
 $(1-\lambda)(1-\lambda) = 0$ $\lambda_1 = 1$

- Note that the algebraic multiplicity of the eigenvalue is 2
- This means that the geometric multiplicity must either 1 or 2.

We can find the eigenvectors:

$$egin{bmatrix} 1-\lambda_1 & 0 \ 1 & 1-\lambda_1 \end{bmatrix}x=0 \ egin{bmatrix} 0 & 0 \ 1 & 0 \end{bmatrix}x=0 \ x=egin{bmatrix} 1 \ 0 \end{bmatrix}$$

Thus, the eigenspace is:

$$E_1 = \mathrm{span}[egin{bmatrix}1\0\end{bmatrix}]$$

Now
$$\begin{bmatrix} -2 & 2 \\ 2 & 1 \end{bmatrix}$$
:

4.4:

$$\begin{bmatrix} -\lambda & -1 & 1 & 1 \\ 0 & -\lambda & -1 & 3 - \lambda \\ 0 & 1 & -2 - \lambda & 2\lambda \\ 1 & -1 & 1 & -\lambda \end{bmatrix}$$

$$\begin{bmatrix} -\lambda & -1 - \lambda & 0 & 1 \\ 0 & -\lambda & -1 - \lambda & 3 - \lambda \\ 0 & 1 & -1 - \lambda & 2\lambda \\ 1 & 0 & 0 & -\lambda \end{bmatrix}$$

4.5

a.

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Diagonalizability:

• Check for eigenvectors that span \mathbb{R}^n

$$\det(A-\lambda I) = egin{vmatrix} 1-\lambda & 0 \ 0 & 1-\lambda \end{bmatrix} = 0$$
 $\lambda = 1$

Find eigenvectors:

$$\begin{bmatrix} 1-1 & 0 \\ 0 & 1-1 \end{bmatrix} x = 0$$

• Any vector in \mathbb{R}^2 is an eigenvector of this matrix and therefore there are two linearly independent vectors in the null space of $(A - \lambda I)$ meaning this is diagonalizable

Invertibility:

Check that the determinant is nonzero:

$$\det(A) = (1)(1) - 0 = 1$$

ullet You may have immediately been able to see these results by recognizing that this matrix if I_2

b.

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

Diagonalizability:

• Check for eigenvectors that span \mathbb{R}^n

$$\det(A-\lambda I) = egin{vmatrix} 1-\lambda & 0 \ 0 & -\lambda \end{vmatrix} = 0 \ -\lambda(1-\lambda) = 0 \ \lambda_1 = 0 & \lambda_2 = 1 \ \end{pmatrix}$$

Find eigenvectors:

First λ₁:

$$egin{bmatrix} 1-0 & 0 \ 0 & 0-0 \end{bmatrix} x = 0 \ egin{bmatrix} 1 & 0 \ 0 & 0 \end{bmatrix} x = 0 \ x_1 := egin{bmatrix} 0 \ 1 \end{bmatrix}$$

• Now λ_2 :

$$\begin{bmatrix} 1-1 & 0 \\ 0 & 0-1 \end{bmatrix} x = 0$$

$$egin{bmatrix} 0 & 0 \ 0 & -1 \end{bmatrix} x = 0 \ x_2 := egin{bmatrix} 1 \ 0 \end{bmatrix}$$

• x_1 and x_2 are linearly independent and form a basis for \mathbb{R}^2 therefore this matrix is diagonalizable \checkmark

Invertibility:

· Check that the determinant is nonzero:

$$\det(A) = 0 - 0 = 0$$

C.

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

Diagonalizability:

• Check for eigenvectors that span \mathbb{R}^n

$$\det(A-\lambda I) = egin{array}{cc} 1-\lambda & 1 \ 0 & 1-\lambda \ \end{vmatrix} = 0$$
 $(1-\lambda)(1-\lambda) = 0$ $\lambda = 1$

Find eigenvectors:

$$egin{bmatrix} 1-1 & 1 \ 0 & 1-1 \end{bmatrix} x = 0 \ egin{bmatrix} 0 & 1 \ 0 & 0 \end{bmatrix} x = 0 \ x := egin{bmatrix} 0 \ 1 \end{bmatrix}$$

• The eigenvectors do not form a basis for \mathbb{R}^2 therefore this is not diagonalizable X

Invertibility:

• Check that the determinant is nonzero:

$$\det(A) = (1)(1) - 0 = 1$$

$$\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

Diagonalizability:

• Check for eigenvectors that span \mathbb{R}^n

$$\det(A-\lambda I) = egin{vmatrix} 0-\lambda & 1 \ 0 & 0-\lambda \end{bmatrix} = 0$$
 $\lambda^2 = 0$ $\lambda = 0$

Find eigenvectors:

$$egin{bmatrix} 0 & 1 \ 0 & 0 \end{bmatrix} x = 0$$
 $x := egin{bmatrix} 0 \ 1 \end{bmatrix}$

• The eigenvectors do not form a basis for \mathbb{R}^2 therefore this is not diagonalizable X

Invertibility:

Check that the determinant is nonzero:

$$\det(A) = (0)(0) - (1)(0) = 0$$

4.6

Compute the eigenspaces of the following transformation matrices. Are they diagonalizable?

a.

$$A = egin{bmatrix} 2 & 3 & 0 \ 1 & 4 & 3 \ 0 & 0 & 1 \end{bmatrix}$$

• First we find the characteristic polynomial:

$$\det(A-\lambda I) = egin{bmatrix} 2-\lambda & 3 & 0 \ 1 & 4-\lambda & 3 \ 0 & 0 & 1-\lambda \end{bmatrix} = 0$$

 We can compute this with a Laplace expansion. It will be easiest to preform Laplace expansion in the third row because there are two zeros, so two of the terms will disappear:

$$\det(A - \lambda I) = a_{31}C_{31} + a_{32}C_{32} + a_{33}C_{33}$$

$$\det(A-\lambda I)=0C_{31}+0C_{32}+(1-\lambda)C_{33}$$

$$\det(A-\lambda I)=(1-\lambda)C_{33}$$

• To find the C_{33} we first find the determinant of the minor A_{33}

$$A_{33} = egin{bmatrix} 2 - \lambda & 3 \ 1 & 4 - \lambda \end{bmatrix} \ \det(A_{33}) = (2 - \lambda)(4 - \lambda) - 3 \ \det(A_{33}) = 8 - 2\lambda - 4\lambda + \lambda^2 - 3 \ \det(A_{33}) = \lambda^2 - 6\lambda + 5 \ \det(A_{33}) = (\lambda - 5)(\lambda - 1) \ \end{pmatrix}$$

This gives us the cofactor C_{33} :

$$C_{33} = (\lambda - 5)(\lambda - 1)$$

Now we can return to the characteristic polynomial of $(A - \lambda I)$

$$\det(A - \lambda I) = (1 - \lambda)(\lambda - 5)(\lambda - 1) = 0$$

$$\lambda_1 = 1 \quad \lambda_2 = 5$$

- note that λ_1 has an algebraic multiplicity of 2
- Now we can compute the eigenvectors of *A*:
- $\lambda_1 = 1$

$$egin{bmatrix} 2-1 & 3 & 0 \ 1 & 4-1 & 3 \ 0 & 0 & 1-1 \end{bmatrix} x = 0$$

$$\begin{bmatrix} 1 & 3 & 0 \\ 1 & 3 & 3 \\ 0 & 0 & 0 \end{bmatrix} x = 0$$

$$x_1 := egin{bmatrix} -3 \ 1 \ 0 \end{bmatrix}$$

• $\lambda_2 = 5$

$$\begin{bmatrix} 2-5 & 3 & 0 \\ 1 & 4-5 & 3 \\ 0 & 0 & 1-5 \end{bmatrix} x = 0$$
$$\begin{bmatrix} -3 & 3 & 0 \\ 1 & -1 & 3 \\ 0 & 0 & -4 \end{bmatrix} x = 0$$

$$x_2 := egin{bmatrix} 1 \ 1 \ 0 \end{bmatrix}$$

Therefore the eigenspaces of A are:

$$E_1 = \mathrm{span}[egin{bmatrix} -3 \ 1 \ 0 \end{bmatrix}]$$

$$E_5 = \mathrm{span}[egin{bmatrix}1\1\0\end{bmatrix}]$$

A is *not* diagonalizable because its eigenvectors do not form a basis for \mathbb{R}^3

b.

• First we find the characteristic polynomial:

$$\det(A-\lambda I) = egin{bmatrix} 1-\lambda & 1 & 0 & 0 \ 0 & -\lambda & 0 & 0 \ 0 & 0 & -\lambda & 0 \ 0 & 0 & 0 & -\lambda \end{bmatrix} = 0$$

Doing a Laplace expansion in the first row:

$$\det(A-\lambda I) = a_{11}C_{11} + a_{12}C_{12} + a_{13}C_{13} + a_{14}C_{14}$$
 $\det(A-\lambda I) = (1-\lambda)C_{11} + (1)C_{12} + (0)C_{13} + (0)C_{14}$ $\det(A-\lambda I) = (1-\lambda)C_{11} + C_{12}$

• We start by finding the cofactor C_{11} . The first step in that is finding the determinant of the minor A_{11} :

$$A_{11}=egin{bmatrix} -\lambda & 0 & 0 \ 0 & -\lambda & 0 \ 0 & 0 & -\lambda \end{bmatrix}$$

• Since it's in row echelon form the determinant is just the product of the diagonal elements:

$$\det(A_{11}) = -\lambda^3$$
 $C_{11} = -\lambda^3$

• Now we can find the second cofactor C_{12} :

$$A_{12} = egin{bmatrix} 0 & 0 & 0 \ 0 & -\lambda & 0 \ 0 & 0 & -\lambda \end{bmatrix}$$

• The determinant of A_{12} is evidently zero so the entire C_{12} term disappears:

$$\det(A-\lambda I)=(1-\lambda)(-\lambda^3)$$
 $\lambda_1=1 \quad \lambda_2=0$

- Now we find the eigenvectors:
- $\lambda_1 = 1$

$$egin{bmatrix} 1-1 & 1 & 0 & 0 \ 0 & -1 & 0 & 0 \ 0 & 0 & -1 & 0 \ 0 & 0 & 0 & 1 \end{bmatrix} x=0$$

$$egin{bmatrix} 0 & 1 & 0 & 0 \ 0 & -1 & 0 & 0 \ 0 & 0 & -1 & 0 \ 0 & 0 & 0 & 1 \end{bmatrix} x = 0$$

$$x_1 := egin{bmatrix} 1 \ 0 \ 0 \ 0 \end{bmatrix}$$

•
$$\lambda_1=0$$

• Writing this out as a system of linear equations:

$$x_1 + x_2 = 0$$

$$x_1=-x_2$$

• therefore:

$$x = egin{bmatrix} -x_2 \ x_2 \ x_3 \ x_4 \end{bmatrix}$$

• Expressing this vector as a linear combination:

$$x=x_2egin{bmatrix} -1\ 1\ 0\ 0 \end{bmatrix}, x_3egin{bmatrix} 0\ 0\ 1\ 0 \end{bmatrix}, x_4egin{bmatrix} 0\ 0\ 0\ 1 \end{bmatrix}$$

• Therefore:

$$x_2 := egin{bmatrix} -1 \ 1 \ 0 \ 0 \end{bmatrix} x_3 := egin{bmatrix} 0 \ 0 \ 1 \ 0 \end{bmatrix} x_4 := egin{bmatrix} 0 \ 0 \ 0 \ 1 \end{bmatrix}$$

• The eigenspaces of A are:

$$E_1 = \mathrm{span}[egin{bmatrix} 1 \ 0 \ 0 \ 0 \end{bmatrix}]$$

$$E_0 = \mathrm{span}[egin{bmatrix} -1 \ 1 \ 0 \ 0 \end{bmatrix}, egin{bmatrix} 0 \ 0 \ 1 \ 0 \end{bmatrix}, egin{bmatrix} 0 \ 0 \ 1 \ 0 \end{bmatrix}]$$

• Putting all of the eigenvectors for *A* into a matrix:

$$\begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

• We can see that the columns of this matrix are linearly independent. Therefore the eigenvectors form a basis for \mathbb{R}^4 and A is diagonalizable.

4.7

a.

$$A = \begin{bmatrix} 0 & 1 \\ -8 & 4 \end{bmatrix}$$

• First we find the characteristic polynomial:

$$\det(A-\lambda I) = egin{bmatrix} -\lambda & 1 \ -8 & 4-\lambda \end{bmatrix}$$

· This matrix has no real eigenvalues

b.

$$A = egin{bmatrix} 1 & 1 & 1 \ 1 & 1 & 1 \ 1 & 1 & 1 \end{bmatrix}$$

First we find the characteristic polynomial:

$$\det(A-\lambda I) = egin{vmatrix} 1-\lambda & 1 & 1 \ 1 & 1-\lambda & 1 \ 1 & 1 & 1-\lambda \end{bmatrix} = 0$$

1. $R_2 \leftarrow R_2 - R_1$

$$egin{bmatrix} 1-\lambda & 1 & 1 \ -\lambda & -\lambda & 0 \ 1 & 1 & 1-\lambda \end{bmatrix}$$

2. $R_3 \leftarrow R_3 - R_1$

$$egin{bmatrix} 1-\lambda & 1 & 1 \ \lambda & -\lambda & 0 \ \lambda & 0 & -\lambda \end{bmatrix}$$

• Now we preform a Laplace expansion along the first row:

$$\det = (1-\lambda) igg| egin{array}{c|c} -\lambda & 0 \ 0 & -\lambda \end{array} - igg| \lambda & 0 \ \lambda & -\lambda \end{array} + igg| \lambda & -\lambda \end{array} + igg| \lambda & -\lambda \end{array}$$
 $\det = (1-\lambda)(\lambda^2) - (-\lambda^2) + \lambda^2$ $\det = \lambda^2 - \lambda^3 + 2\lambda^2$ $= -\lambda^3 + 3\lambda^2$ $= -\lambda^2(\lambda - 3)$ $\lambda_1 = 3$ $\lambda_1 = 0$

- Now we find the eigenvectors:
- $\lambda_1 = 3$

$$\begin{bmatrix} 1-3 & 1 & 1 \\ 1 & 1-3 & 1 \\ 1 & 1 & 1-3 \end{bmatrix} x = 0$$

$$\begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} x = 0$$

$$x_1 := egin{bmatrix} 1 \ 1 \ 1 \end{bmatrix}$$

• $\lambda_1 = 0$

$$egin{bmatrix} 1 & 1 & 1 \ 1 & 1 & 1 \ 1 & 1 & 1 \end{bmatrix} x = 0$$

$$x_2 := egin{bmatrix} 1 \ 0 \ -1 \end{bmatrix} \qquad x_3 := egin{bmatrix} 1 \ -1 \ 0 \end{bmatrix}$$

- The matrix is diagonalizable because its eigenvectors form a basis for \mathbb{R}^3
- The diagonal form of the matrix is:

$$D = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

The basis with respect to which the matrix is diagonal is:

$$B := egin{bmatrix} 1 \ 1 \ 1 \ \end{bmatrix}, egin{bmatrix} 1 \ 0 \ -1 \ \end{bmatrix}, egin{bmatrix} 1 \ -1 \ 0 \ \end{bmatrix}$$

C.

d.

$$A = egin{bmatrix} 5 & -6 & -6 \ -1 & 4 & 2 \ 3 & -6 & -4 \end{bmatrix}$$

• First we find the characteristic polynomial:

$$\det(A - \lambda I) = egin{vmatrix} 5 - \lambda & -6 & -6 \ -1 & 4 & 2 \ 3 & -6 & -4 \ \end{bmatrix} = 0$$

• Performing a Laplace expansion along the first row:

$$\det(A-\lambda I) = (5-\lambda) \underbrace{ \begin{bmatrix} 4 & 2 \\ -6 & -4-\lambda \end{bmatrix}}_{A_{11}} + 6 \underbrace{ \begin{bmatrix} -1 & 2 \\ 3 & -4-\lambda \end{bmatrix}}_{A_{12}} - 6 \underbrace{ \begin{bmatrix} -1 & 4-\lambda \\ 3 & -6 \end{bmatrix}}_{A_{13}}$$

Computing the determinants of the minors:

• A₁₁

$$\det(A_{11}) = egin{array}{c|c} 4 & 2 \ -6 & -4 - \lambda \end{array} = (4 - \lambda)(-4 - \lambda) + 12$$
 $\det(A_{11}) = \lambda^2 - 4$

• A₁₂

$$\det(A_{11}) = egin{bmatrix} -1 & 2 \ 3 & -4 - \lambda \end{bmatrix} = \lambda - 2$$

• A_{13}

$$\det(A_{11}) = egin{bmatrix} -1 & 4-\lambda \ 3 & -6 \end{bmatrix} = 3(\lambda-2)$$

Plugging those determinants back in:

$$\det(A - \lambda I) = (5 - \lambda)(\lambda^2 - 4) + 6(\lambda - 2) - 6[3(\lambda - 2)]$$

= $(5 - \lambda)(\lambda - 2)(\lambda + 2) + 6(\lambda - 2) - 6[3(\lambda - 2)]$

Factoring out a $(\lambda - 2)$:

$$\begin{aligned} \det(A - \lambda I) &= (\lambda - 2) \left[(5 - \lambda)(\lambda + 2) + 6 - 18 \right] \\ &= (\lambda - 2) [5\lambda + 10 - \lambda^2 - 2\lambda + 6 - 16] \\ &= (\lambda - 2)(3\lambda + 10 - \lambda^2 - 12) \\ &= (\lambda - 2)(-\lambda^2 + 3\lambda - 2) \end{aligned}$$

Factoring out a -1 from the right polynomial (we can just ignore it since $\det(A - \lambda I) = 0$ and $\frac{0}{-1} = 0$):

$$\det(A-\lambda I) = (\lambda-2)(\lambda^2-3\lambda+2) \ = (\lambda-2)(\lambda-2)(\lambda-1)$$

Therefore the eigenvalues are:

$$\lambda_1=2$$
 $\lambda_2=1$

- Now we find the eigenvectors:
- $\lambda_1=2$

$$\begin{bmatrix} 5-2 & -6 & -6 \\ -1 & 4-2 & 2 \\ 3 & -6 & -4-2 \end{bmatrix} x = 0$$

$$\begin{bmatrix} 3 & -6 & -6 \\ -1 & 2 & 2 \\ 3 & -6 & -6 \end{bmatrix} x = 0$$

1.
$$R_1 \leftarrow \frac{1}{3}R_1$$
, $R_3 \leftarrow \frac{1}{3}R_3$:

$$\begin{bmatrix} 1 & -2 & -2 \\ -1 & 2 & 2 \\ 1 & -2 & -2 \end{bmatrix}$$

1.
$$R_2 \leftarrow R_2 + R_1$$
, $R_3 \leftarrow R_3 - R_1$

$$egin{bmatrix} 1 & -2 & -2 \ 0 & 0 & 0 \ 0 & 0 & 0 \ \end{bmatrix} \ x_1 - 2x_2 - 2x_3 = 0 \ x_1 = 2x_2 + 2x_3 \ x = egin{bmatrix} 0x_1 + 2x_2 + 2x_3 \ 0x_1 + x_2 + 0x_3 \ 0x_1 + 0x_2 + x3 \ \end{bmatrix} = egin{bmatrix} 2x_2 \ x_2 \ 0 \ \end{bmatrix} + egin{bmatrix} 2x_3 \ 0 \ x_3 \ \end{bmatrix} = x_2 egin{bmatrix} 2 \ 1 \ 0 \ \end{bmatrix} + x_3 egin{bmatrix} 2 \ 0 \ 1 \ \end{bmatrix} \ x_1 := egin{bmatrix} 2 \ 1 \ 0 \ \end{bmatrix} \ x_2 := egin{bmatrix} 2 \ 0 \ 1 \ \end{bmatrix}$$

 $\lambda_1 = 1$

$$egin{bmatrix} 5-1 & -6 & -6 \ -1 & 4-1 & 2 \ 3 & -6 & -4-1 \end{bmatrix} x=0 \ egin{bmatrix} 4 & -6 & -6 \ -1 & 3 & 2 \ 3 & -6 & -5 \end{bmatrix} x=0 \ 4x_1-6x_2-6x_3=0 \ -x_1+3x_2+2x_3=0 \ 3x_3-6x_2-5x_3 \end{bmatrix}$$

From equation 2:

$$x_1 = 3x_2 + 2x_3$$

Plugging this into equation 1:

$$egin{aligned} 4(3x_2+2x_3)-6x_2-6x_3&=0\ 12x_2+8x_3-6x_2-6x_3&=0\ 6x_2+2x_3&=0\ x_3&=-3x_2 \end{aligned}$$

Plugging this back into the equation for x_1 :

$$x_1 = 3x_2 + 2(-3x_2) \ x_1 = -3x_2$$
 $x = egin{bmatrix} 0x_1 - 3x_2 + 0x_3 \ 0x_1 + x_2 + 0x_3 \ 0x_1 - 3x_2 + 0x_3 \end{bmatrix} = x_2 egin{bmatrix} -3 \ 1 \ -3 \end{bmatrix}$ $x_3 := egin{bmatrix} -3 \ 1 \ -3 \end{bmatrix}$

- The matrix is diagonalizable because its eigenvectors form a basis for \mathbb{R}^3
- The diagonal form of the matrix is:

$$D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

The basis with respect to which the matrix is diagonal is:

$$B := egin{bmatrix} 2 \ 1 \ 0 \end{bmatrix}, egin{bmatrix} 2 \ 0 \ 1 \end{bmatrix}, egin{bmatrix} -3 \ 1 \ -3 \end{bmatrix}$$

4.8

Find the SVD:

$$A=egin{bmatrix} 3 & 2 & 2 \ 2 & 3 & -2 \end{bmatrix}$$

• The first step in finding the SVD is finding A^TA :

$$A^TA = egin{bmatrix} 3 & 2 \ 2 & 3 \ 2 & -2 \end{bmatrix} egin{bmatrix} 3 & 2 & 2 \ 2 & 3 & -2 \end{bmatrix} = egin{bmatrix} 13 & 12 & 2 \ 12 & 13 & -2 \ 2 & -2 & 8 \end{bmatrix}$$

- Now we eigendecompose A^TA .
- We start by finding the characteristic polynomial:

$$\det(A^TA-\lambda I)=egin{pmatrix}13-\lambda&12&2\12&13-\lambda&-2\2&-2&8-\lambda\end{pmatrix}=0$$

Performing a Laplace expansion along the first row:

$$\det(A^TA - \lambda I) = (13 - \lambda) \underbrace{ egin{bmatrix} 13 - \lambda & -2 \ -2 & 8 - \lambda \end{bmatrix}}_{A_{11}} - 12 \underbrace{ egin{bmatrix} 12 & -2 \ 2 & 8 - \lambda \end{bmatrix}}_{A_{12}} + 2 \underbrace{ egin{bmatrix} 12 & 13 - \lambda \ 2 & -2 \end{bmatrix}}_{A_{13}}$$

Starting with the first minor A₁₁:

$$\det(A_{11}) = (13 - \lambda)(8 - \lambda) - 4$$

= $104 - 13\lambda - 8\lambda + \lambda^2 - 4$
= $\lambda^2 - 21\lambda + 100$

• Now A_{12}

$$\det(A_{12}) = 96 - 12\lambda + 4 = 100 - 12\lambda$$

• Now A_{13}

$$\det(A_{13}) = -24 - 2(13 - \lambda) \ = 24 - 26 + 2\lambda \ = 2\lambda - 50$$

• Plugging back into the equation for $\det(A^TA - \lambda I)$:

$$\begin{aligned} \det(A^TA - \lambda I) &= (13 - \lambda)(\lambda^2 - 21\lambda + 100) - 12(100 - 12\lambda) + 2(2\lambda - 50) \\ &= 13\lambda^2 - 273\lambda + 1300 - \lambda^3 + 21\lambda^2 - 100\lambda - 12(100 - 12\lambda) + 2(2\lambda - 50) \\ &= -\lambda^3 + 13\lambda^2 + 21\lambda^2 - 100\lambda - 273\lambda + 1300 - 12(100 - 12\lambda) + 2(2\lambda - 50) \\ &= -\lambda^3 + 34\lambda^2 - 373\lambda + 1300 - 1200 - 144\lambda + 4\lambda - 100 \\ &= \lambda^3 + 34\lambda^2 - 255\lambda \\ &= -\lambda(\lambda^2 - 34\lambda - 255) \\ &= -\lambda(\lambda - 25)(\lambda - 9) \end{aligned}$$

• This gives us the eigenvalues of A^TA :

$$\lambda_1=25 \qquad \lambda_2=9 \qquad \lambda_3=0$$

- Now we find the eigenvectors of A^TA using the eigenvalues:
- $\lambda_1 = 25$

$$\begin{bmatrix} 13 - 25 & 12 & 2 \\ 12 & 13 - 25 & -2 \\ 2 & -2 & 8 - 25 \end{bmatrix} x = 0$$

$$\begin{bmatrix} -12 & 12 & 2 \\ 12 & -12 & -2 \\ 2 & -2 & -17 \end{bmatrix} x = 0$$

- We can get this matrix into row echelon form with Gaussian Elimination:
- 1. $R_2 \leftarrow R_2 + R_1$:

$$\begin{bmatrix} -12 & 12 & 2 \\ 0 & 0 & 0 \\ 2 & -2 & -17 \end{bmatrix}$$

2. $R_3 \leftrightarrow R_2$

$$\begin{bmatrix} -12 & 12 & 2 \\ 2 & -2 & -17 \\ 0 & 0 & 0 \end{bmatrix}$$

1. $R_1 \leftarrow -\frac{1}{12}R_1$

$$\begin{bmatrix} 1 & -1 & -\frac{1}{6} \\ 2 & -2 & -17 \\ 0 & 0 & 0 \end{bmatrix}$$

4. $R_2 \leftarrow R_2 - 2R_1$

$$\begin{bmatrix} 1 & -1 & -\frac{1}{6} \\ 0 & 0 & -\frac{100}{6} \\ 0 & 0 & 0 \end{bmatrix}$$

 $5. \ R_2 \leftarrow -\frac{6}{100} R_2$

$$\begin{bmatrix} 1 & -1 & -\frac{1}{6} \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

• Now writing this as a system of linear equations:

$$x_1 - x_2 - rac{1}{6}x_3 = 0$$
 $x_3 = 0$

· We see that:

$$x_1 - x_2 - rac{1}{6}(0) = 0$$
 $x_1 = x_2$

Therefore our first eigenvector is:

$$x_1 := egin{bmatrix} 1 \ 1 \ 0 \end{bmatrix}$$

• $\lambda_2=9$

$$\begin{bmatrix} 13 - 9 & 12 & 2 \\ 12 & 13 - 9 & -2 \\ 2 & -2 & 8 - 9 \end{bmatrix} x = 0$$
$$\begin{bmatrix} 4 & 12 & 2 \\ 12 & 4 & -2 \\ 2 & -2 & -1 \end{bmatrix} x = 0$$

We can get this matrix into row echelon form with Gaussian Elimination:

1.
$$R_1 \leftarrow \frac{1}{4}R_1$$

$$\begin{bmatrix} 1 & 3 & \frac{1}{2} \\ 12 & 4 & -2 \\ 2 & -2 & -1 \end{bmatrix}$$

2.
$$R_2 \leftarrow R_2 - 12R_1, R_3 \leftarrow R_3 - 2R_1$$

$$\begin{bmatrix} 1 & 3 & \frac{1}{2} \\ 0 & -32 & -8 \\ 0 & -8 & -2 \end{bmatrix}$$

3.
$$R_2 \leftarrow -\frac{1}{32}R_2$$

$$\begin{bmatrix} 1 & 3 & \frac{1}{2} \\ 0 & 1 & \frac{1}{4} \\ 0 & -8 & -2 \end{bmatrix}$$

4.
$$R_3 \leftarrow R_3 + 8R_2$$

$$\begin{bmatrix} 1 & 3 & \frac{1}{2} \\ 0 & 1 & \frac{1}{4} \\ 0 & 0 & 0 \end{bmatrix}$$

• Now writing this as a system of linear equations:

$$x_1 + 3x_2 + rac{1}{2}x_3 = 0$$
 $x_2 + rac{1}{4}x_3 = 0$
 $x_2 = -rac{1}{4}x_3$
 $x_1 = -3x_2 - rac{1}{2}d_3$
 $x_1 = -3(-rac{1}{4}x_3) - rac{1}{2}x_3$
 $x_1 = rac{1}{4}x_3$

• Our second eigenvector is:

$$x_1 := \left[egin{array}{c} rac{1}{4} \ -rac{1}{4} \ 1 \end{array}
ight]$$

• $\lambda_3 = 0$

$$\begin{bmatrix} 13 - 0 & 12 & 2 \\ 12 & 13 - 0 & -2 \\ 2 & -2 & 8 - 0 \end{bmatrix} x = 0$$
$$\begin{bmatrix} 13 & 12 & 2 \\ 12 & 13 & -2 \\ 2 & -2 & 8 \end{bmatrix} x = 0$$

- We can get this matrix into row echelon form with Gaussian Elimination:
- 1. $R_3 \leftrightarrow R_1$

$$\begin{bmatrix} 2 & -2 & 8 \\ 13 & 12 & 2 \\ 12 & 13 & -2 \end{bmatrix}$$

2.
$$R_1 \leftarrow \frac{1}{2}R_1$$

$$\begin{bmatrix} 1 & -1 & 4 \\ 13 & 12 & 2 \\ 12 & 13 & -2 \end{bmatrix}$$

3.
$$R_2 \leftarrow R_2 - 13R_1, R_3 \leftarrow R_3 - 12R_1$$

$$\begin{bmatrix} 1 & -1 & 4 \\ 0 & 25 & -50 \\ 0 & 25 & -50 \end{bmatrix}$$

4.
$$R_3 \leftarrow R_3 - R_2$$

$$\begin{bmatrix} 1 & -1 & 4 \\ 0 & 25 & -50 \\ 0 & 0 & 0 \end{bmatrix}$$

$$5. \ R_2 \leftarrow \frac{1}{25} R_2$$

$$\begin{bmatrix} 1 & -1 & 4 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix}$$

• Now writing this as a system of linear equations:

$$x_1 - x_2 + 4x_3 = 0$$
 $x_2 - 2x_3 = 0$
 $x_2 = 2x_3$
 $x_1 = x_2 - 4x_3$
 $x_1 = -2x_3$

• Our third eigenvector is:

$$x_3 = egin{bmatrix} -2 \ 2 \ 1 \end{bmatrix}$$

- Now that we have the eigenvectors and eigenvalues for A^TA we can construct two of the three matrices in the SVD: Σ and V
- Σ is a diagonal matrix of the same shape as A with the square root of the eigenvalues along the diagonal put in descending order. These values are the singular values:

$$\Sigma = egin{bmatrix} 5 & 0 & 0 \ 0 & 3 & 0 \end{bmatrix}$$

• V is an orthogonal matrix of right singular vectors. All we need to do to construct V is normalize the eigenvectors of A^TA . The eigenvectors are already orthogonal (because A^TA is symmetric), so we just need to normalize them.

$$v_1 = rac{x_1}{\|x_1\|}$$
 $\|x_1\| = \sqrt{x_1^T x_1} = \sqrt{2}$
 $v_1 = egin{bmatrix} rac{1}{\sqrt{2}} \ rac{1}{\sqrt{2}} \ 0 \end{bmatrix}$
 $v_2 = rac{x_2}{\|x_2\|}$
 $\|x_2\| = \sqrt{x_2^T x_2} = rac{\sqrt{18}}{4}$
 $v_2 = egin{bmatrix} rac{1}{\sqrt{18}} \ -rac{1}{\sqrt{18}} \ rac{4}{\sqrt{18}} \end{bmatrix}$
 $v_3 = rac{x_3}{\|x_3\|}$
 $\|x_3\| = \sqrt{x_3^T x_3} = 3$
 $v_3 = egin{bmatrix} -rac{2}{3} \ rac{2}{3} \ rac{1}{2} \ rac{2}{3} \ rac{2}{3} \ rac{1}{2} \ rac{2}{3} \$

Putting these together gives us the matrix V:

$$V = egin{bmatrix} rac{1}{\sqrt{2}} & rac{1}{\sqrt{18}} & -rac{2}{3} \ rac{1}{\sqrt{2}} & -rac{1}{\sqrt{18}} & rac{2}{3} \ 0 & rac{4}{\sqrt{18}} & rac{1}{3} \end{bmatrix}$$

• The only matrix left to find is the matrix of left singular vectors U.

$$u_1 = \sigma_1 A v_1 = egin{bmatrix} rac{1}{\sqrt{2}} \ rac{1}{\sqrt{2}} \end{bmatrix}$$

$$u_2=\sigma_2 A v_2=egin{bmatrix} rac{1}{\sqrt{2}} \ -rac{1}{\sqrt{2}} \end{bmatrix}$$

• Which finally gives us *U*:

$$U = egin{bmatrix} rac{1}{\sqrt{2}} & rac{1}{\sqrt{2}} \ rac{1}{\sqrt{2}} & -rac{1}{\sqrt{2}} \end{bmatrix}$$

In summary the SVD of A is:

$$A = U\Sigma V^T$$

$$A = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 5 & 0 & 0 \\ 0 & 3 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{18}} & -\frac{1}{\sqrt{18}} & \frac{4}{\sqrt{18}} \\ -\frac{2}{3} & \frac{2}{3} & \frac{1}{3} \end{bmatrix}$$

4.9

Find the singular value decomposition of:

$$A = egin{bmatrix} 2 & 2 \ -1 & 1 \end{bmatrix}$$

• The first step in finding the SVD is finding A^TA :

$$A^TA = egin{bmatrix} 2 & -1 \ 2 & 1 \end{bmatrix} egin{bmatrix} 2 & 2 \ -1 & 1 \end{bmatrix} = egin{bmatrix} 5 & 3 \ 3 & 5 \end{bmatrix}$$

- Now we eigendecompose A^TA .
- We start by finding the characteristic polynomial:

$$egin{aligned} \det(A^TA-\lambda I) &= egin{array}{ccc} 5-\lambda & 3 & & = 0 \ &= (5-\lambda)(5-\lambda)-9 \ &= 25-10\lambda+\lambda^2-9 \ &= \lambda^2-10\lambda+16 \ 0 &= (\lambda-8)(\lambda-2) \end{aligned}$$

• This gives us the eigenvalues of A^TA :

$$\lambda_1 = 8$$
 $\lambda_2 = 2$

- Now we find the eigenvectors of A^TA using the eigenvalues:
- $\lambda_1 = 8$

$$\begin{bmatrix} 5-8 & 3 \\ 3 & 5-8 \end{bmatrix} x = 0$$
$$\begin{bmatrix} -3 & 3 \\ 3 & -3 \end{bmatrix} x = 0$$

- We can get this matrix into row echelon form with Gaussian Elimination:
- 1. $R_2 \leftarrow R_2 R_1$

$$\begin{bmatrix} -3 & 3 \\ 0 & 0 \end{bmatrix} x = 0$$

2. $R_1 \leftarrow -\frac{1}{3}R_1$

$$\begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} x = 0$$

Now writing this as a system of linear equations:

$$x_1 = x_2 \ x_1 := egin{bmatrix} 1 \ 1 \end{bmatrix}$$

ullet $\lambda_2=2$

$$\begin{bmatrix} 5-2 & 3 \\ 3 & 5-2 \end{bmatrix} x = 0$$
$$\begin{bmatrix} 3 & 3 \\ 3 & 3 \end{bmatrix} x = 0$$

We can get this matrix into row echelon form with Gaussian Elimination:

1.
$$R_2 \leftarrow R_2 - R_1$$

$$\begin{bmatrix} 3 & 3 \\ 0 & 0 \end{bmatrix} x = 0$$

2.
$$R_1 \leftarrow \frac{1}{3}R_1$$

$$egin{bmatrix} 1 & 1 \ 0 & 0 \end{bmatrix} x = 0$$

• Now writing this as a system of linear equations:

$$x_1=-x_2$$

$$x_2 := egin{bmatrix} -1 \ 1 \end{bmatrix}$$

- Now that we have the eigenvectors and eigenvalues for A^TA we can construct two of the three matrices in the SVD: Σ and V
- Σ is a diagonal matrix of the same shape as A with the square root of the eigenvalues along the diagonal put in descending order. These values are the singular values:

$$\Sigma = egin{bmatrix} \sqrt{8} & 0 \ 0 & \sqrt{2} \end{bmatrix}$$

• V is an orthogonal matrix of right singular vectors. All we need to do to construct V is normalize the eigenvectors of A^TA . The eigenvectors are already orthogonal (because A^TA is symmetric), so we just need to normalize them.

$$egin{align} v_1 &= rac{x_1}{\|x_1\|} \ \|x_1\| &= \sqrt{x_1^T x_1} = \sqrt{2} \ v_1 &= \left[rac{1}{\sqrt{2}}
ight] \ v_2 &= rac{x_2}{\|x_2\|} \ \|x_2\| &= \sqrt{x_2^T x_2} = \sqrt{2} \ v_2 &= \left[-rac{1}{\sqrt{2}}
ight] \ rac{1}{\sqrt{2}} \ rac{1}{\sqrt{2}}$$

• Putting these together gives us the matrix *V*:

$$V = egin{bmatrix} rac{1}{\sqrt{2}} & -rac{1}{\sqrt{2}} \ rac{1}{\sqrt{2}} & rac{1}{\sqrt{2}} \end{bmatrix}$$

The only matrix left to find is the matrix of left singular vectors U.

$$u_1 = \sigma_1 A v_1 = egin{bmatrix} 1 \ 0 \end{bmatrix}$$

$$u_2 = \sigma_2 A v_2 = egin{bmatrix} 0 \ 1 \end{bmatrix}$$

Which finally gives us U:

$$U = egin{bmatrix} 1 & 0 \ 0 & 1 \end{bmatrix} \$\$ - Insummary the SVD of \$A\$ is:$$

A = U \Sigma V^T

A = \begin{bmatrix}

1 & 0 \

0 & 1 \

\end{bmatrix}

\begin{bmatrix}\sqrt{8} & 0 \ 0 & \sqrt{2} \end{bmatrix}

\begin{bmatrix}

\dfrac{1}{\sqrt{2}} & \dfrac{1}{\sqrt{2}} \

 $-\dfrac{1}{\sqrt{2}} \& \dfrac{1}{\sqrt{2}}$

\end{bmatrix}

4.10 Find the best rank-1 approximation of:

A =

\begin{bmatrix}

3 & 2 & 2 \

2 & 3 & -2

\end{bmatrix}

 $-We can use the SVD we got in question 4.8. \ To get a rank 1 approximation we use the formula:$

 $A_1 = \sum_{1 \leq 1} \left(\frac{1}{\sqrt{2}} \right) \left(\frac{1}{\sqrt{2}} \right) \\ \left(\frac{1}{\sqrt{2}} \right) \\ \left(\frac{1}{\sqrt{2}} \right) \\ \left(\frac{1}{\sqrt{2}} \right) \\ \left(\frac{1}{2} \right) \\ \left(\frac{1}{2$

```
#### 4.11 Show that for any A \in \mathbb{R}^{m} times n, the matrices A^TA and A^T possess the
A = U \Sigma V^T
-Where \$U\$ and \$V\$ are orthogonal matrices and \$\Sigma\$ is a diagonal matrix whose diagonal entries are the square of the square of
A^TA = (U\Sigma V^T)^T(U\Sigma V^T) = V\Sigma^TU^TU\Sigma V^T
                                                                                                                                        -Because \$U\$ is orthogonal:
A^TA = V\Sigma^T\Sigma V^T
AA^T = (U \Sigma V^T)(U \Sigma V^T)^T = U \Sigma V^T V\Sigma^TU^T
                                                                                                                                         -Because V\$ is orthogonal
AA^T = U\Sigma \Sigma^T U^T
- In both equations we end up with $\Sigma^T \Sigma$ and $\Sigma \Sigma^T$. Because $\Sigma$ is diagonal
\max x \left| Ax \right| 2 \right| = \sum 1
           -Where \$\sigma_1\$ is the largest singular value of \$A \in \mathbb{R}^{m \times n}\$ - if \$x\$ is a unit vector, \$\|x\|_2 = 1\$ so:
|A| 2 = \max x|Ax| 2
             If we break A down into its [[Singular Value Decomposition | singular value decomposition]]:
|A| 2 = \max x |U \setminus Sigma V^Tx|
                                                                              -Because \$U\$ is orthogonal, it preserves norms and angles:
|A| 2 = \max x |Sigma V^Tx|
                                             -\$V^T\$ is also orthogonal, so it preserves norms. We now make a substitution:
z = V^Tx
                                     -because \$V^T\$ is orthogonal (and therefore preserves lengths) and \$x\$ is length 1:
|z| 2 = 1
                                                                                                            Sonowour maximization problem becomes:
|A| 2 = \max z|Sigma z|
The question now is, which $z$, given the constraint that $z$ must be unitlength, maximizes the Euclideann and the state of the state
\Sigma =
\begin{bmatrix}
\sigma 1 & ... & 0 \
```

... & ... & ... \

 $This means that we can write out the equation for the Euclidean norm \$\|\Sigma z\|_2 \$ in terms of the components of$

$$|\sigma_1^2 = \sqrt{\frac{1^2z_1^2 + ... \sigma_n^2}{1}}$$

Since z is unit length:

$$\sum_{i=0}^n z_i^2 = 1$$

 $Therefore to maximize \$\|\Sigma z\|_2 \$ we \textit{""concentrate"} all of the weight possible for \$z\$ into the element correspondent and the property of the property of$

z = \begin{bmatrix}

1 \ 0 \ \vdots \ 0

\end{bmatrix}

 $Therefore, all of the other terms in \$\sqrt{\sigma_1^2 z_1^2 + \ldots \sigma_n^2 z_n^2} \$ disappear and we are left with:$

$$|A|_2 = \sqrt{\sum_{1}^2} = \sum_{1}^2$$