# Point Pattern Analysis: Processes

#### SERGIO REY

GPH 483/598
Geographic Information Analysis
School of Geographical Sciences
Arizona State University
Spring 2010

# **Outline**

- Properties of Point Processes
  - First Order Properties
  - Second Order Property
- Point Processes
  - Complete Spatial Randomness
  - Homogeneous Poisson Process
  - Inhomogeneous Poisson Process (IPP)

# First Order Properties: Spatial Analysis

### Mean value of the process in space

- Variation in mean value of the process in space
- Global, large scale spatial trend

## First Order Property of Point Patterns, Intensity: $\lambda$

- Intensity:  $\lambda$  = number of events expected per unit area
- Estimation of  $\lambda$
- Spatial variation of  $\lambda$ ,  $\lambda(s)$ , s is a location

$$\lambda(s) = \lim_{ds \to 0} \left\{ \frac{E(Y(ds))}{ds} \right\}$$
 (1)

# Second Order Properties: Spatial Analysis

### **Spatial Correlation Structure**

- Deviations in values from process mean
- Local or small scale effects

## Second Order Property of Point Patterns

- Relationship between number of events in pairs of areas
- Second order intensity  $\gamma(s_i, s_i)$

$$\gamma(s_i, s_j) = \lim_{ds_i \to 0, ds_j \to 0} \left\{ \frac{E(Y(ds_i)Y(ds_j))}{ds_i ds_j} \right\}$$
(2)

# **Spatial Stationarity**

## First Order Stationarity

$$\lambda(s) = \lambda \forall s \in A \tag{3}$$

$$E(Y(A)) = \lambda \times A \tag{4}$$

## Second Order Stationarity

$$\gamma(s_i, s_j) = \gamma(s_i - s_j) = \gamma(h)$$
 (5)

- h is the vector difference between locations  $s_i$  and  $s_i$
- h encompasses direction and distance (relative location)
- Second order intensity only depends on h for second order stationarity

# Spatial Isotropy and Stationarity

## **Isotropic Process**

- When a stationary process is invariant to rotation about the origin.
- Relationship between two events depend only on the distance separating their locations and not on their orientation to each other.
- Depends only on distance, not direction

### Usefulness

- Two pairs of events from a stationary process separated by same distance and relative direction should have same "relatedness"
- Two pairs of events from a stationary and isotropic process separated by the same distance (irrespective of direction) should have the same "relatedness"
- Both allow for replication and the ability to carry out estimation of the underlying DGP.

# Complete Spatial Randomness

### **CSR**

- Standard of Reference
- Uniform: each location has equal probability
- Independent: location of points independent
- Homogeneous Planar Poisson Point Process

## Poisson Point Process

## Intensity

- number of points in region A : N(A)
- intensity:  $\lambda = N/|A|$
- implies:  $\lambda |A|$  points randomly scattered in a region with area |A|
- e.g.,  $10 \times 1$  (points per  $km^2$ )

### Poisson Distribution

 $N(A) \sim Poi(\lambda |A|)$ 

## Poisson Distribution

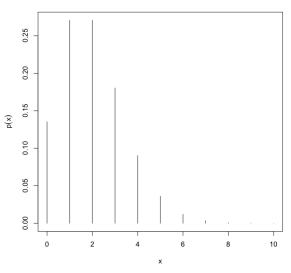
## Single Parameter Distribution: $\lambda |A|$

- Generally,  $\lambda$  is the number of events in some well defined *interval* 
  - Time: phone calls to operator in one hour
  - Time: accidents at an intersection per week
  - Space: trees in a quadrat
- Let x be a Poisson random variable
  - $E[x] = V[x] = \lambda |A|$

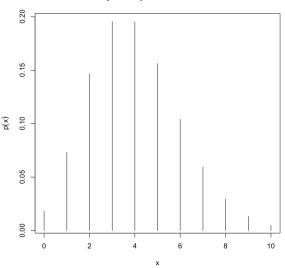
### Poisson Distribution

$$P(x) = \frac{e^{-\lambda|A|}(\lambda|A|)^x}{x!}$$
 (6)

#### Probability Density for Poisson with Mean=2







# In Space

## Single Parameter

$$P[N(A) = x] = e^{-\lambda |A|} (\lambda |A|)^x / x! \tag{7}$$

# Spatial Example

# CSR with $\lambda = 5/km^2$

- Region = Circle
  - area =  $|A| = \pi r^2$
  - r = 0.1 km then area  $\approx 0.03 \text{ km}^2$
- Probability of Zero Points in Circle

$$P[N(A) = 0] = e^{-\lambda |A|} (\lambda |A|)^{x} / x!$$
 (8)

$$\approx e^{-5 \times 0.03} (5 \times 0.03)^0 / 0!$$
 (9)

$$\approx e^{-5 \times 0.03}$$
 (10)

# Complete Spatial Randomness (CSR)

## Homogeneous spatial Poisson point process

- The number of events occurring within a finite region A is a random variable following a Poisson distribution with mean  $\lambda |A|$ , with |A| denoting area of A.
- ② Given the total number of events N occurring within an area A, the locations of the N events represent an independent random sample of N locations where each location is equally likely to be chosen as an event.
  - Criterion 2 is the general concept of CSR (uniform (random)) distribution in *A*.
  - Criterion 1 pertains to the intensity  $\lambda$ .

# Homogeneous Poisson process

### **Implications**

- The number of events in nonoverlapping regions in *A* are statistically independent.
- ② For any region  $R \subset A$ :

$$\lim_{|R|\to 0} \frac{Pr[exactly \ one \ event \ in \ R]}{|R|} = \lambda > 0 \tag{12}$$

3

$$\lim_{|R|\to 0} \frac{Pr[more\ than\ one\ event\ in\ R]}{|R|} = 0 \tag{13}$$

# Homogeneous Poisson process

### **Implications**

- $\lambda$  is the intensity of the spatial point pattern.
- For a Poisson random variable, Y:

$$E[Y] = \lambda = V[Y] \tag{14}$$

- Provides the motivation for some quadrat tests of CSR hypothesis.
  - If  $Y_R$  is the count in quadrat R
  - If  $\widehat{E[Y]} < \widehat{V[Y]}$ : overdispersion = spatial clustering
  - If  $\widehat{E[Y]} > \widehat{V[Y]}$ : underdispersion = spatial uniformity

# Simulating CSR

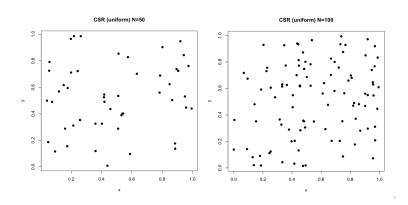
### N – conditioned

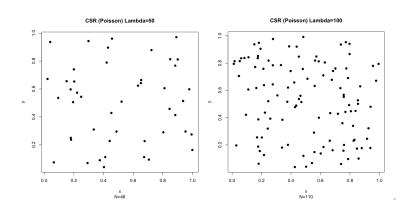
- CSR= uniform distribution
- random uniform draws for x and y point coordinates
- N fixed

### $\lambda$ – conditioned

- CSR= Poisson distribution
- $\lambda$  and |A| given
- N(A) random

# **CSR Uniform**





## Limitations of CSR

## Stationary Poisson Process

- homogeneous
- translation invariant

## Rare in practice

very few (any?) actual processes are CSR

### Strawman

- purely a benchmark
- null hypothesis

# Inhomogeneous Poisson Process (IPP)

### Criteria

- The number of events occurring within a finite region A is a random variable following a Poisson Distribution with mean  $\int_A \lambda(s) ds$ .
- ② Given the total number of events N occurring within A, the N events represent an independent sample of N locations, with the probability of sampling a particular point s proportional to  $\lambda(s)$ .

## Spatially Variable Intensity $\lambda(s)$

- Useful for constant risk hypothesis
- Underlying population at risk is spatially clustered
- Want to control for that since with individual constant risk apparent clusters would be generated.
- Compare pattern against constant risk, not CSR.

# Inhomogeneous Poisson Process

### **Implications**

- Apparent clusters can occur solely due to heterogeneities in the intensity function  $\lambda(s)$ .
- Individual event locations still remain independent of one another.
- Process is not stationary due to intensity heterogeneity

### HPP vs. IPP

HPP is a special case of IPP with a constant intensity

# CSR vs. Constant Risk Hypotheses

#### **CSR**

- Intensity is spatially constant
- Population at risk assumed spatially uniform
- Useful null hypothesis if these conditions are met

## Constant Risk Hypothesis

- Population density variable
- Individual risk constant
- Expected number of events should vary with population density
- Clusters due to deviation from CSR
- Clusters due to deviation from CSR and Constant Risk