Numerical Analysis Homework 3

Due day: Oct 27, 2025

Question 1. Hermite interpolation Given the function

$$f(x) = \frac{1}{1 + 25x^2}, \quad x \in [-1, 1].$$

with the function values and 1st derivatives at nodes:

$$x_1 = -1, \quad x_2 = 0, \quad x_3 = 1.$$

- 1. Construct the cubic Hermite interpolant H(x) and evaluate H(0.5).
- 2. Evaluate the absolution error of f(0.5) H(0.5), and show that the error agrees the prior error estimate of

$$f(x) - p(x) = \frac{f^{(2n+2)}(\xi)}{(2n+2)!} \prod_{j=0}^{n} (x - x_j)^2$$
, for some ξ between x and $\{x_j\}$.

- 3. Obtain the cubic Hermite interpolant in Newton form P(x), by constructing the Hermite divided-difference table.
 - 4. Plot f(x), H(x) and P(x) on [-1,1].

Question 2. Simple analysis on finite difference

Consider the forward difference approximation for the first derivative of a smooth function f(x):

$$D_h f(x) = \frac{f(x+h) - f(x)}{h}.$$

We showed in class that the total error in the derivative approximation can be written as:

$$E(h) = \frac{C_1}{h} + C_2 h,$$

with the optimal choice of step size h:

$$h_{\rm opt} = \sqrt{\frac{C_1}{C_2}},$$

where C_1 and C_2 are constants depending on f(x), machine precision ε , and its derivatives. Let $f(x) = e^x$, and take x = 1.5.

- 1. Compute f'(1.5) using the forward difference formula for a range of step sizes $h = 10^{-k}$, where k = 1, 2, ..., 10.
- 2. Plot the absolute error $|D_h f(1) f'(1)|$ versus h on a log-log scale. Code needs to be reported in latex.

- 3. Identify the h that minimizes the total error and compare it with the predicted h_{opt} .
- 4. Use the one-sided three points scheme to approximate f'(1.5), and repeat the sub-question #2.

Question 3. Solve nonlinear burger's equation by Finite difference scheme Consider the 1D viscous Burgers equation

$$u_t + uu_x = \nu u_{xx}, \quad x \in [0, 1], t > 0, \nu = 0.2.$$

Your task is to design, analyze, and implement a numerical method that is stable and achieves at least second-order accuracy in space

- 1. Report your finite difference scheme used.
- 2. Use the initial condition as a since wave $sin(2\pi x)$. Write your code to implement your scheme, and plot the numerical solution at T=1s.
- 3. Compute your $||u u_h||_{L_2}$ with different refined mesh, and show your spatial convergence in log-log plot.
 - 4. Plot your $||u u_h||_{L_2}$ vs time.

Solutions.

1) Error growth with degree.

From the remainder formula,

$$R_n(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} \prod_{i=0}^n (x - x_i), \qquad \xi \in (0,1).$$

For $f(x) = e^x$, we have $f^{(n+1)}(t) = e^t \le e$ on [0,1]. Hence

$$|R_n(x)| \le \frac{e}{(n+1)!} \Big| \prod_{i=0}^n (x - x_i) \Big|.$$

Taking the maximum over $x \in [0, 1]$ gives

$$\max_{x \in [0,1]} |R_n(x)| \le \frac{e}{(n+1)!} \max_{x \in [0,1]} \Big| \prod_{i=0}^n (x - x_i) \Big|.$$

On [0,1], each factor satisfies $|x-x_i| \leq 1$, so

$$0 \le \max_{x \in [0,1]} \Big| \prod_{i=0}^{n} (x - x_i) \Big| \le 1.$$

Therefore

$$\max_{x \in [0,1]} |R_n(x)| \le \frac{e}{(n+1)!} \xrightarrow[n \to \infty]{} 0.$$

1) x_k are roots of T_n .

Let $\theta_k = \frac{2k-1}{2n}\pi \in (0,\pi)$. Then $\arccos(\cos\theta_k) = \theta_k$, so

$$T_n(x_k) = \cos(n \arccos x_k) = \cos(n\theta_k) = \cos\left(\frac{2k-1}{2}\pi\right) = 0$$

Hence each x_k is a root. 2) Distinct and in (-1,1).

The θ_k are strictly increasing in $(0,\pi)$; since cos is strictly decreasing on $[0,\pi]$, the values $x_k = \cos \theta_k$ are distinct. Because $\theta_k \in (0,\pi)$, we have $x_k \in (-1,1)$. Thus all n roots lie in (-1,1) and are distinct. Because T_n has degree n, these are all the roots.