

$$\left(\frac{\partial S}{\partial T}\right)_v = \frac{C_v}{T}$$

$$\left(\frac{\partial S}{\partial v}\right)_T = \frac{1}{T} \left[p + \left(\frac{\partial u}{\partial v}\right)_T \right]$$

= ?

State function

$$\left(\frac{\partial}{\partial T} \left(\frac{\partial S}{\partial v}\right)_T\right)_v = \left(\frac{\partial}{\partial v} \left(\frac{\partial S}{\partial T}\right)_v\right)_T$$

~~$$\frac{\partial S}{\partial T} = \frac{C_v}{T} \rightarrow \left(\frac{\partial}{\partial v} \frac{C_v}{T}\right)_T$$~~

$$\frac{\partial S}{\partial T} = \frac{C_v}{T} = \frac{1}{T} \left(\frac{\partial u}{\partial T}\right)_v$$

$$\left(\frac{\partial}{\partial v} \left(\frac{\partial S}{\partial T}\right)\right) = \frac{1}{T} \frac{\partial^2 u}{\partial v \partial T}$$

$$\left(\frac{\partial}{\partial T} \left(\frac{\partial S}{\partial v}\right)_T\right)_v = \frac{1}{T} \left[\left(\frac{\partial p}{\partial T}\right)_v + \frac{\partial^2 u}{\partial T \partial v} \right] \text{ product rule}$$

$$= \frac{1}{T^2} \left[p + \left(\frac{\partial u}{\partial v}\right)_T \right]$$

$$dS = \frac{1}{T} du + \frac{P}{T} dV$$

also, in stable state

maybe
for the
first

$$dS = \left(\frac{\partial S}{\partial T} \right)_V dT + \left(\frac{\partial S}{\partial V} \right)_T dV$$

This dependence is that in
state to which

$$du = \left(\frac{\partial u}{\partial T} \right)_V dT + \left(\frac{\partial u}{\partial V} \right)_T dV$$

$$= C_V dT + \left(\frac{\partial u}{\partial V} \right)_T dV$$

$$dS = \frac{1}{T} \left[C_V dT + \left(\frac{\partial u}{\partial V} \right)_T dV \right] + \frac{P}{T} dV$$

$$= \frac{C_V dT}{T} + \frac{1}{T} \left(P + \left(\frac{\partial u}{\partial V} \right)_T \right) dV$$