# Jiayang Song

#### Ph.D. Candidate · University of Alberta

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#### Research Interests \_\_\_

- Software EngineeringCyber-Physical System
- Safety and Quality Assurance
- Trustworthy AI System
- Foundation Model
- · Embodied Agent

# Work Experience \_

## **Graduate Research Assistant Fellowship**

ADVISORS: PROF. LEI MA

University of Alberta 01.2022 - Current

- Quality and Safety Assurance for AI System Engineering
- Software Engineering Methodology for Trustworthy Foundation Model
- University research projects/grants: FES, MIF-RCES, Amii-Rap
- Industrial collaboration projects: Nvidia, TIER IV

#### **NSERC Research Program**

ADVISOR: PROF. MEHRDAD R. KERMANI

Western University 04.2018 - 09.2018

- Kinematic model design and construction for robotic arms
- Testing and evaluation for Magnetorheological clutches
- Magnetic field sensor network design and construction

# Education \_\_

# **University of Alberta**

Edmonton, Canada 01.2022 - 05.2025

#### Ph.D., ELECTRICAL AND COMPUTER ENGINEERING

- Area of Interest: Software Engineering and Intelligent System
- Thesis: Quality Assurance for Trustworthy Al-enabled Cyber-Physical System
- Advisor: Prof. Lei Ma

# **University of Toronto**

Toronto, Canada 09.2019 - 06.2021

#### M.Eng, Electrical and Computer Engineering

• Graduate with distinction

• Specialization: Deep Reinforcement Learning, Data Science

#### **Western University**

London, Canada 09.2015 - 04.2019

#### B.Eng. Electrical and Computer Engineering

· Graduate with distinction

- Specialization: Control System, Wireless Communication
- Dean's Honor List 2017, 2018, 2019

# Research Projects and Collaborations \_

#### **Foundational Models for Autonomous Driving System**

University of Alberta 2024 - Current

ADVISOR: PROF. LEI MA

• Collaboration with TIER IV, Tokyo, Japan

- Exploring the potential of Multimodal Foundation Model-driven autonomous driving systems
- Developing novel frameworks for ADS scenario understanding, annotation and prediction

# **Quality and Safety Assurance for Autonomous Driving Systems**

ADVISOR: PROF. LEI MA

University of Alberta 2024 - Current

- Collaboration with Autoware Foundation, Japan
- Developing an automated testing method for Autoware Software and simulator
- · Designing system level testing criteria and reliability assessment through fault injection

#### **AI-enabled Resilient Grid for Clean Energy Integration**

University of Alberta

2024 - Current

ADVISORS: ASSOC. PROF. LEI MA. PROF. YUNWEI RYAN LI. PROF. ROBERT BENKOCZI

- Major Innovation Fund Resilient and Clean Energy Systems Initiative (MIF-RCES)
- Investigating software-defined modelling for resilient grid via digital twin techniques
- Developing testing and validation frameworks for Al-enabled energy systems

#### **Application of Foundation Models in Robotics with Safety Assurance**

ADVISORS: PROF. LEI MA

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University of Alberta

2023 - Current

- Investigating the best practice of LLM-empowered embodied agent
- Adapting LLMs for both robotics development and operation

# Trustworthiness Assurance and Engineering for AI-enabled Cyber-physical Systems

University of Alberta

2023 - 2024

- Alberta machine intelligence institute (Amii) Research Allocation Panel
- Developed runtime safety measurement and prediction methods for AI-CPS across domains
- Conducted empirical studies to identify the simulation-to-reality gap in the deployment phase of AI-CPS

#### **Model-based Analysis and Testing Guidance for Autonomous Driving System**

University of Alberta

ADVISORS: PROF. LEI MA 2023 - 2024

• Industry collaboration

- Developed a model-based ADS test case selection framework
- The designed framework has been applied and validated on real ADS development

# Safety and Reliability Assurance of Next Generation Al-enabled Cyber-Physical **Systems for Energy Systems**

University of Alberta

ADVISORS: PROF. LEI MA, PROF. PETR MUSILEK

2022 - 2024

- University research project: Future Energy Systems (FES)
- Developed safety enhancement and monitoring frameworks for AI-CPSs across various application domains
- Designed two automated repair techniques for AI controllers

# Benchmarking and Evaluating Al-enabled Cyber-Physical Systems for Robotic Manipulation

University of Alberta

ADVISORS: PROF. LEI MA 2022 - 2023

- Collaboration with NVIDIA AI Tech Centre, Singapore
- Developed a benchmark and a testing framework for AI-CPSs in robotic manipulation using NVIDIA Isaac Sim
- · Conducted performance and safety analysis for Al-CPSs in diverse robotic manipulation tasks

# Mentoring\_

2022 Jiaxuan Peng, Master's thesis University of St Andrews

2023 Atsuhiro Matuyama, Bachelor's thesis The University of Tokyo

2023 Ryosuke Miyake, Bachelor's thesis The University of Tokyo 2023 Soma Sugihara, Bachelor's thesis The University of Tokyo

2024 Yahan Gu, Research Internship The University of British Columbia

#### **Teaching Experience** Winter 2025 Exploring Software Development Domains, Teaching Assistant Winter 2025 - Undergraduate course (approx. 60 participants per semester) - Advanced software engineering concepts using Rust University of Alberta Winter 2023 - Support lectures and provide supervision to students Analog Electronics, Teaching Assistant - Bachelor's course (approx. 300 participants per semester) Fall 2023 - Circuit design with feedback topologies and amplifiers University of Alberta - Support lectures and provide supervision to students Introduction to Digital Logic Design, Teaching Assistant - Bachelor's course (approx. 250 participants per semester) Fall 2024 - Introduction to computer-aided design and simulation tools for digital University of Alberta design and implementation - Provide supervision to students Fundamentals of Electrical Engineering, Teaching Assistant Fall 2024 - Bachelor's course (approx. 300 participants per semester) Winter 2024 University of Alberta - Physical concepts of passive circuit elements, Kirchhoff's laws and DC Winter 2023 circuit equations Sensory Cybernetics, Teaching Assistant - Graduate course (approx. 30 participants per semester) Fall 2020 University of Toronto - Theoretical foundations of the senses from both a systems and a

# Professional Activities \_\_\_

#### **TALKS**

- Invited Talk at University of Alberta @ Guest Lecture, Edmonton, Canada (2023-2024)
  - Topic: Quality Assurance for Al-enabled Cyber-Physical Systems

neurophysiological point of view

- Invited Talk at East China Normal University, Shanghai, China (2023)
  - Topic: Al-enabled Cyber-Physical Systems and Software Foundation
- Invited Talk at 44th International Conference on Software Engineering (ICSE 2022), May 2022
  - Topic: When cyber-physical systems meet AI: A benchmark, an evaluation, and a way forward

#### **REVIEWER**

- IEEE Transactions on Software Engineering (TSE)
- Empirical Software Engineering (EMSE)
- International Journal of Human-Computer Interaction (IJHCI)
- IEEE Transaction on Reliability (ToR)
- IEEE International Conference on Robotics and Automation (ICRA)
- Conference on Neural Information Processing Systems (NeurIPS), 2024
- International Conference on Artificial Intelligence and Statistics (AISTATS)
- International Conference on Learning Representations (ICLR)
- International Conference on Machine Learning (ICML)
- Annual AAAI Conference on Artificial Intelligence (AAAI)

#### Peer-reviewed Publications

#### JOURNAL

**Jiayang Song**, Xuan Xie, and Lei Ma. SIEGE: A Semantics-Guided Safety Enhancement Framework for Al-enabled Cyber-Physical Systems. (TSE 2023, CORE Rank A\*)

Yuheng Huang, **Jiayang Song**, Zhijie Wang, Huaming Chen and Lei Ma. Look Before You Leap: An Exploratory Study of Uncertainty Measurement for Large Language Models. (TSE 2024, CORE Rank A\*))

Da, Song, Xuan Xie, **Jiayang Song**, Derui Zhu, Yuheng Huang, Felix Juefei-Xu, and Lei Ma. LUNA: A Model-Based Universal Analysis Framework for Large Language Models. (TSE 2023, CORE Rank A\*)

Zhehua Zhou, Xuan Xie, **Jiayang Song**, Zhan Shu and Lei Ma. GenSafe: A Generalizable Safety Enhancer for Safe Reinforcement Learning Algorithms Based on Reduced Order Markov Decision Process Model. (TNNLS, 2024)

## **CONFERENCE**

- **Jiayang Song**, Yuheng Huang, Zhehua Zhou and Lei Ma. Multilingual Blending: LLM Safety Alignment Evaluation with Language Mixture. (NAACL Findings 2025)
- **Jiayang Song**, Deyun Lyu, Zhenya Zhang, Zhijie Wang, Tianyi Zhang, and Lei Ma. When cyber-physical systems meet Al: a benchmark, an evaluation, and a way forward. (ICSE 2022, CORE Rank A\*)
- Zhehua Zhou, **Jiayang Song(equal contribution)**, Xuan Xie, Zhan Shu and Lei Ma. Towards Building Al-CPS with NVIDIA Isaac Sim: An Industrial Benchmark and Case Study for Robotics Manipulation. (ICSE 2024, Core Rank A\*)
- Zhou, Zhehua, **Jiayang Song**, Kunpeng Yao, Zhan Shu, and Lei Ma. ISR-LLM: Iterative Self-Refined Large Language Model for Long-Horizon Sequential Task Planning. (ICRA 2024, Core Rank A\*)
- Zhijie Wang, Zhehua Zhou, **Jiayang Song**, Yuheng Huang, Zhan Shu, and Lei Ma. Towards Testing and Evaluating Vision-Language-Action Models for Robotic Manipulation: An Empirical Study. (FSE 2025, Core Rank A\*)

# Preprint Manuscript \_\_\_\_\_ Under Review

- **Jiayang Song**, Zhehua Zhou, Jiawei Liu, Chunrong Fang, Zhan Shu, and Lei Ma. Self-refined large language model as automated reward function designer for deep reinforcement learning in robotics. (Under Review)
- Xuan Xie, **Jiayang Song**, Zhehua Zhou, Fuyuan Zhang and Lei Ma. Mosaic: Model-based Safety Analysis Framework for AI-enabled Cyber-Physical Systems. (Under Review)
- Yuheng Huang, **Jiayang Song**, Qiang Hu, Felix Juefei-Xu and Lei Ma. Active Testing of Large Language Model via Multi-Stage Sampling. (Under Review)
- Xuan Xie, **Jiayang Song**, Zhehua Zhou, Yuheng Huang, aDa Songnd Lei Ma. Online Safety Analysis for LLMs: a Benchmark, an Assessment, and a Path Forward. (Under Review)
- Xuan Xie, **Jiayang Song**, Yuheng Huang, Da Song, Fuyuan Zhang, Felix Juefei-Xu and Lei Ma. LeCov: Multi-level Testing Criteria for Large Language Models. (Under Review)
- Renzhi Wang, Zhehua Zhou, **Jiayang Song**, Xuan Xie, Xiaofei Xie and Lei Ma. MORTAR: A Model-based Runtime Action Repair Framework for Al-enabled Cyber-Physical Systems. (Under Review)
- Deyun Lyu, **Jiayang Song**, Zhenya Zhang, Zhijie Wang, Tianyi Zhang, Lei Ma, and Jianjun Zhao. AutoRepair: Automated Repair for AI-Enabled Cyber-Physical Systems under Safety-Critical Conditions. (Under Review)
- Xiaoning Ren, **Jiayang Song**, Chongyang Liu, Jie Li, Yinxing Xue, Lei Ma. Antidote or Placebo? Unraveling the Efficacy of Neuron Coverage Criteria on Testing Transformer-based Language Models. (Under Review)
- Zhijie Wang, Zhehua Zhou, **Jiayang Song**, Yuheng Huang, Zhan Shu, and Lei Ma. LADEV: A Language-Driven Testing and Evaluation Platform for Vision-Language-Action Models in Robotic Manipulation. (Under Review)
- Shengming Zhao, Yuheng Huang, **Jiayang Song**, Zhijie Wang, Chengcheng Wan and Lei Ma. Towards Understanding Retrieval Accuracy and Prompt Quality in RAG Systems. (Under Review)