

[illegible]

The diagram illustrates the architecture of a Roach system, showing the connections between various components and the central Roach PPC system. The components are organized into several sections:

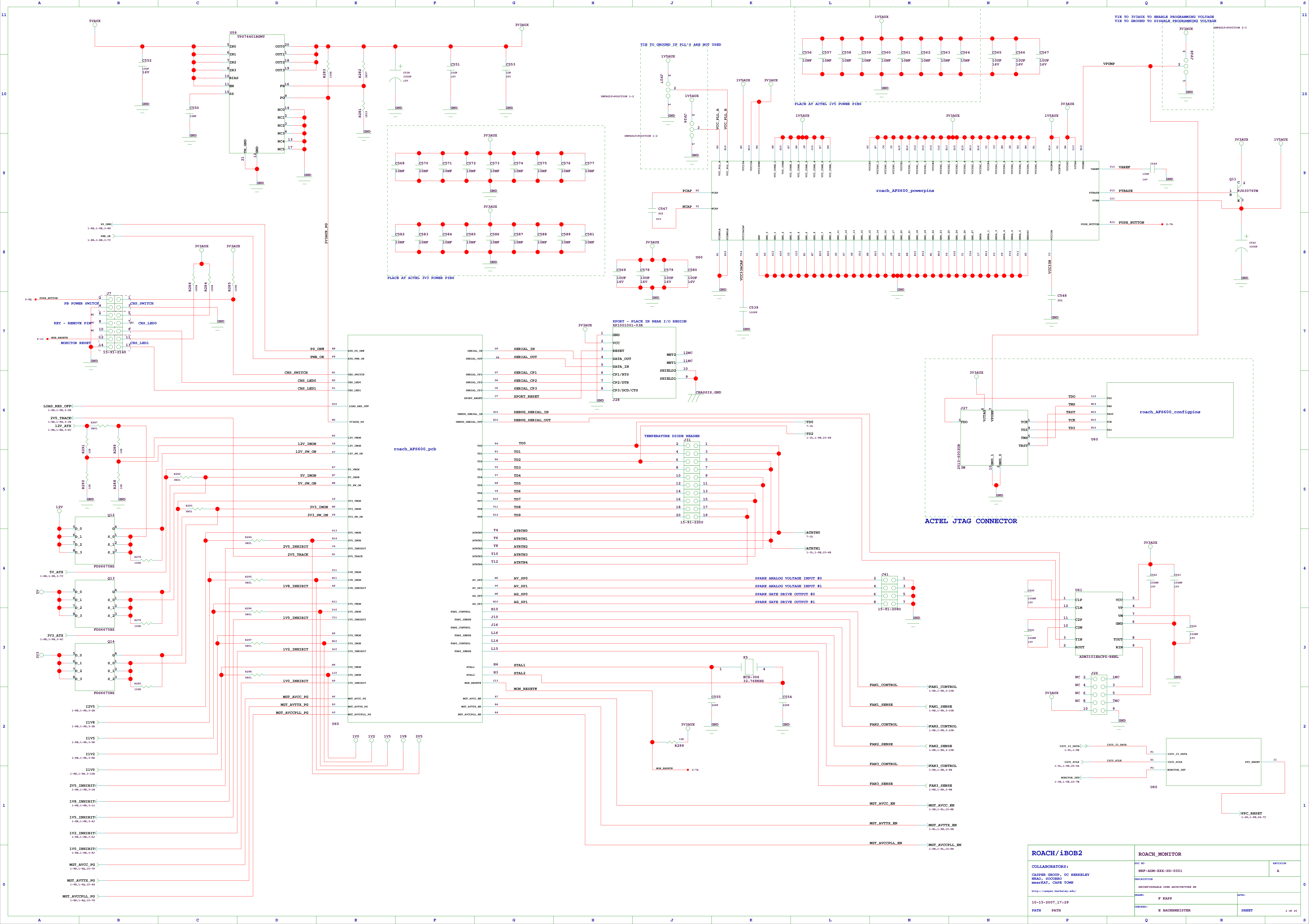
- Roach PPC Power:** Includes power supply components like `DDR_VREF +0.9V` and `DDR_VREF +0.9V`, and power management components like `ROACH_PPC_POWER_1` and `ROACH_PPC_POWER_2`.
- Roach PPC PCI:** Includes PCI interface components like `ROACH_PPC_PCI` and `ROACH_PPC_PCI_1`.
- Roach PPC USB:** Includes USB interface components like `ROACH_PPC_USB` and `ROACH_PPC_USB_1`.
- Roach PPC Serial:** Includes serial interface components like `ROACH_PPC_SERIAL` and `ROACH_PPC_SERIAL_1`.
- Roach PPC Test:** Includes test components like `ROACH_PPC_TEST` and `ROACH_PPC_TEST_1`.
- Roach PPC CPLD:** Includes CPLD components like `ROACH_PPC_CPLD` and `ROACH_PPC_CPLD_1`.

The diagram shows the connections between these components and the central Roach PPC system, with some components highlighted in red to indicate specific signals or states. The connections are labeled with component names and signal names, providing a detailed view of the system architecture.

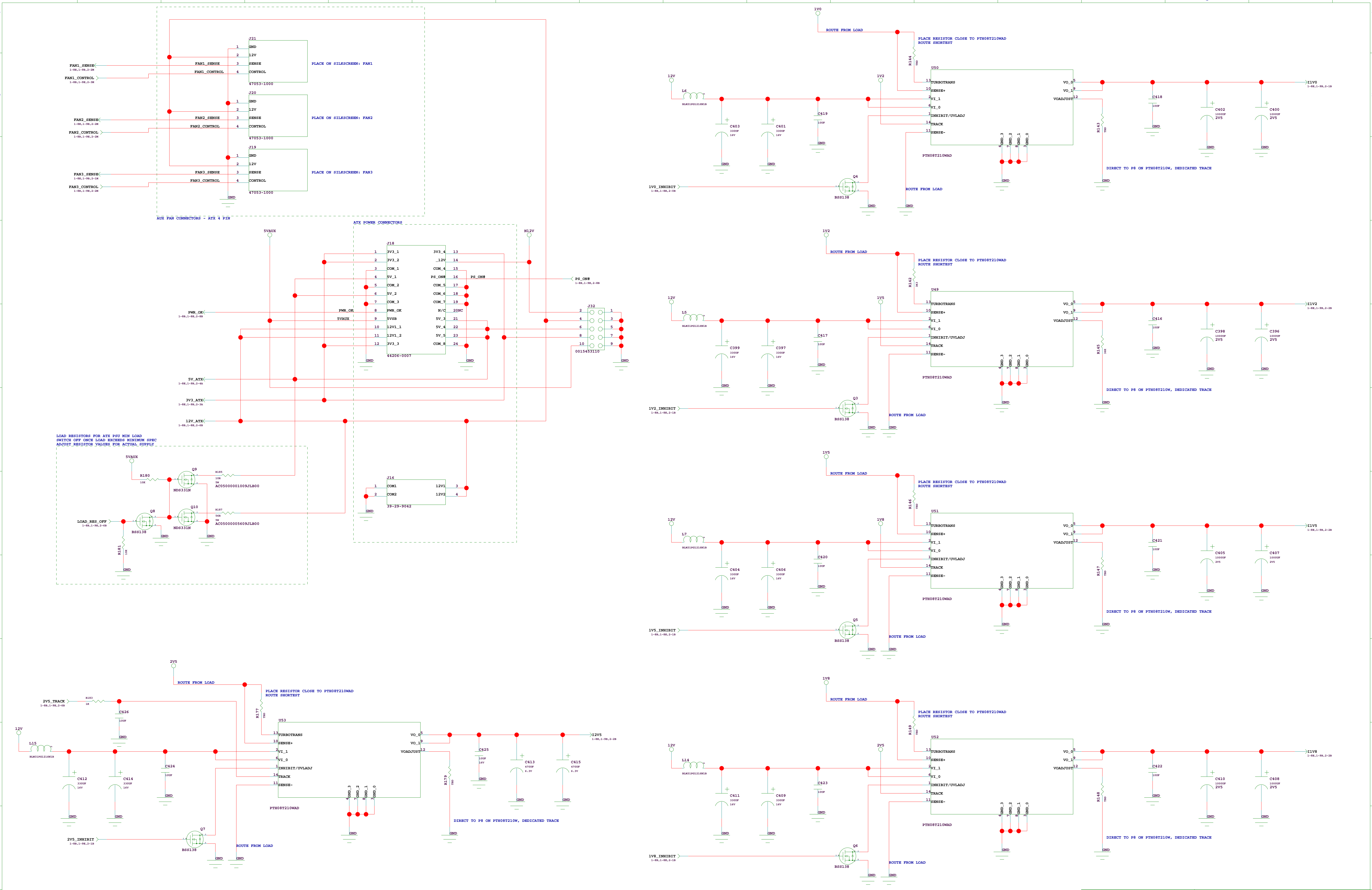
The diagram illustrates the 1000BASE-SX optical module. On the left, a green line represents the GND connection. A red line represents the optical signal path, which branches into ten parallel paths. Each path contains a red circular component (likely a laser or LED) and a blue circular component (likely a photodiode or detector). The components are labeled S1 through S10, and each is associated with a 1000BASE-SX label. The components are arranged in a vertical column, with the red components on the left and the blue components on the right of each pair.

ETIENNE BAUERMEISTER
HENRY COEN
STEVE DORAND
FRANCOIS KAPP
ALAN LANGMAN
GEORGE PECK
MIKE REVKELL
HAYDEN SO
DAN WERTHIMER

ROACH/iBOB2		ROACH_TOP	
COLLABORATORS: CASPER GROUP, UC BERKELEY WRAO, ESCOBAR msee@AT, CAC TOWN http://casper.berkeley.edu/		SOC NO NRP-ADM-XXX-SD-0001 DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW	REVISION A
10-15-2007_17:29 PATH PATH		NAME: F KAPP	DATE:
		CHECKED: R BAUMHEISTER	SHEET 1 OF 2

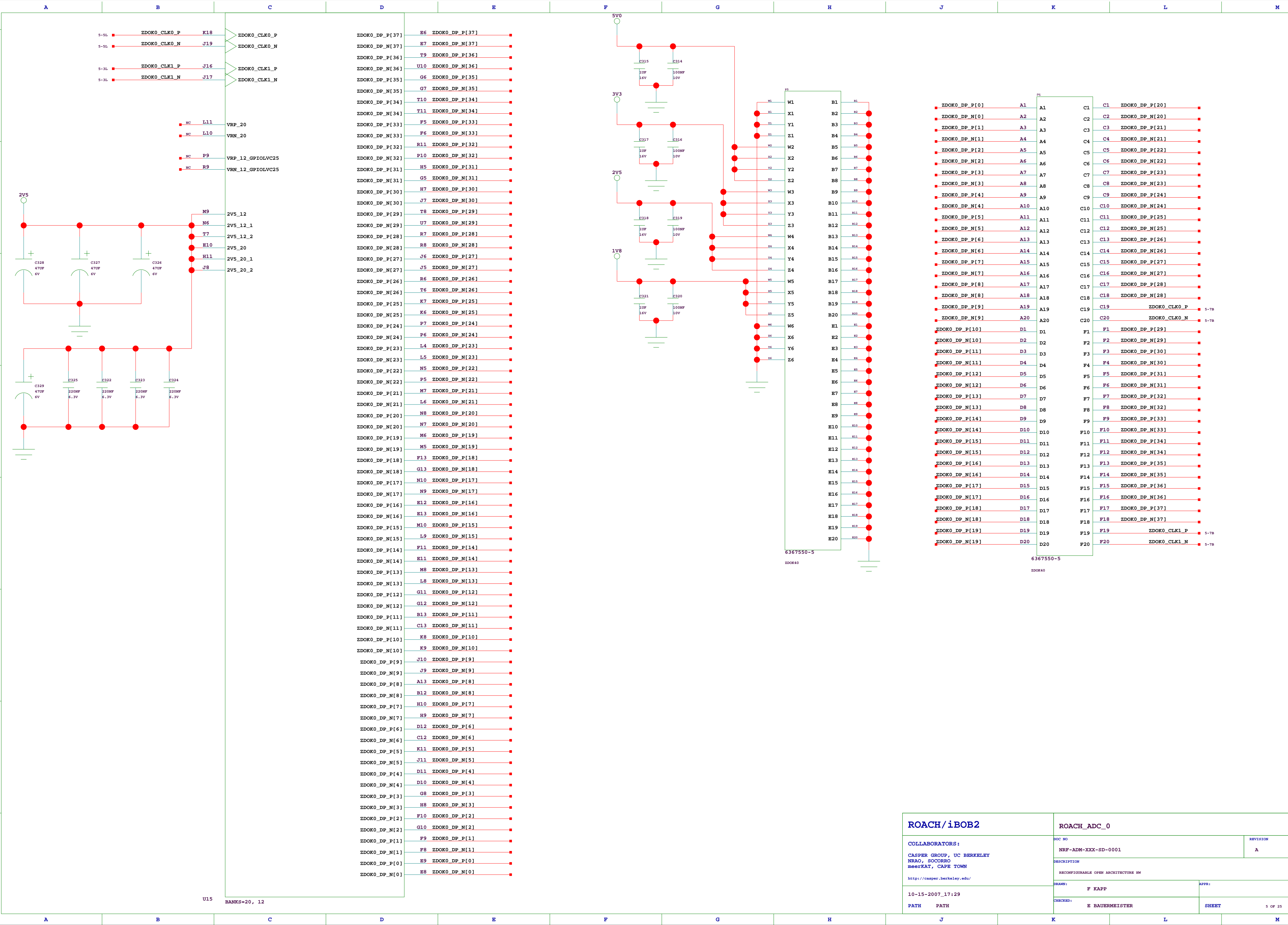


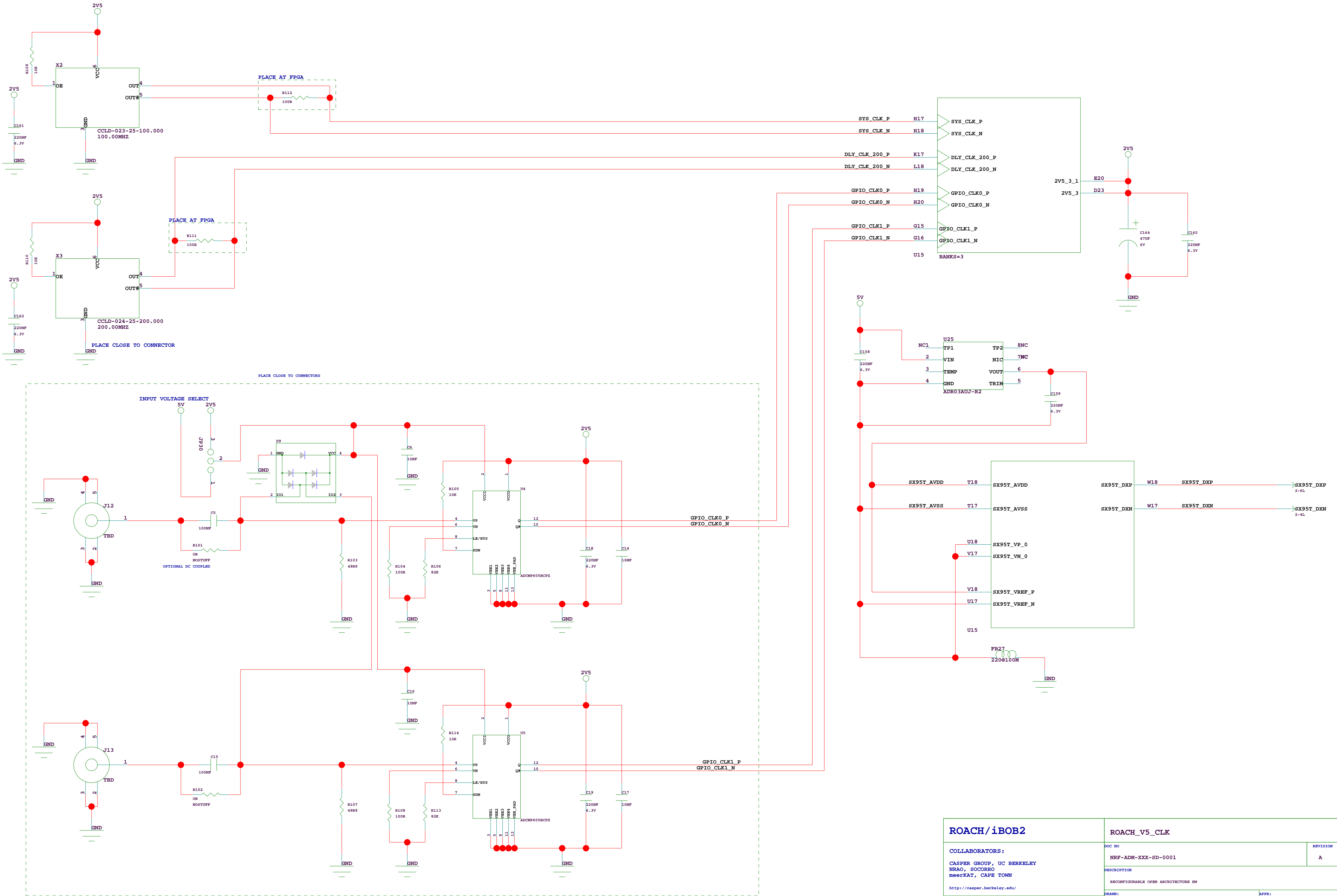
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COLLABORATORS:			DOC NO	REVISION
CASPER GROUP, UC BERKELEY			NRF-ADM-XXX-SD-0001	A
NRAO, SOONERO			DESCRIPTION	
RECONFIGURABLE OPEN ARCHITECTURE HW			BRANCH:	APP:
http://casper.berkeley.edu/			F KAPP	
10-15-2007_17:29			CHECKED:	R BAUERMBROSTER
PATH	PATH		SHEET	2 OF 25



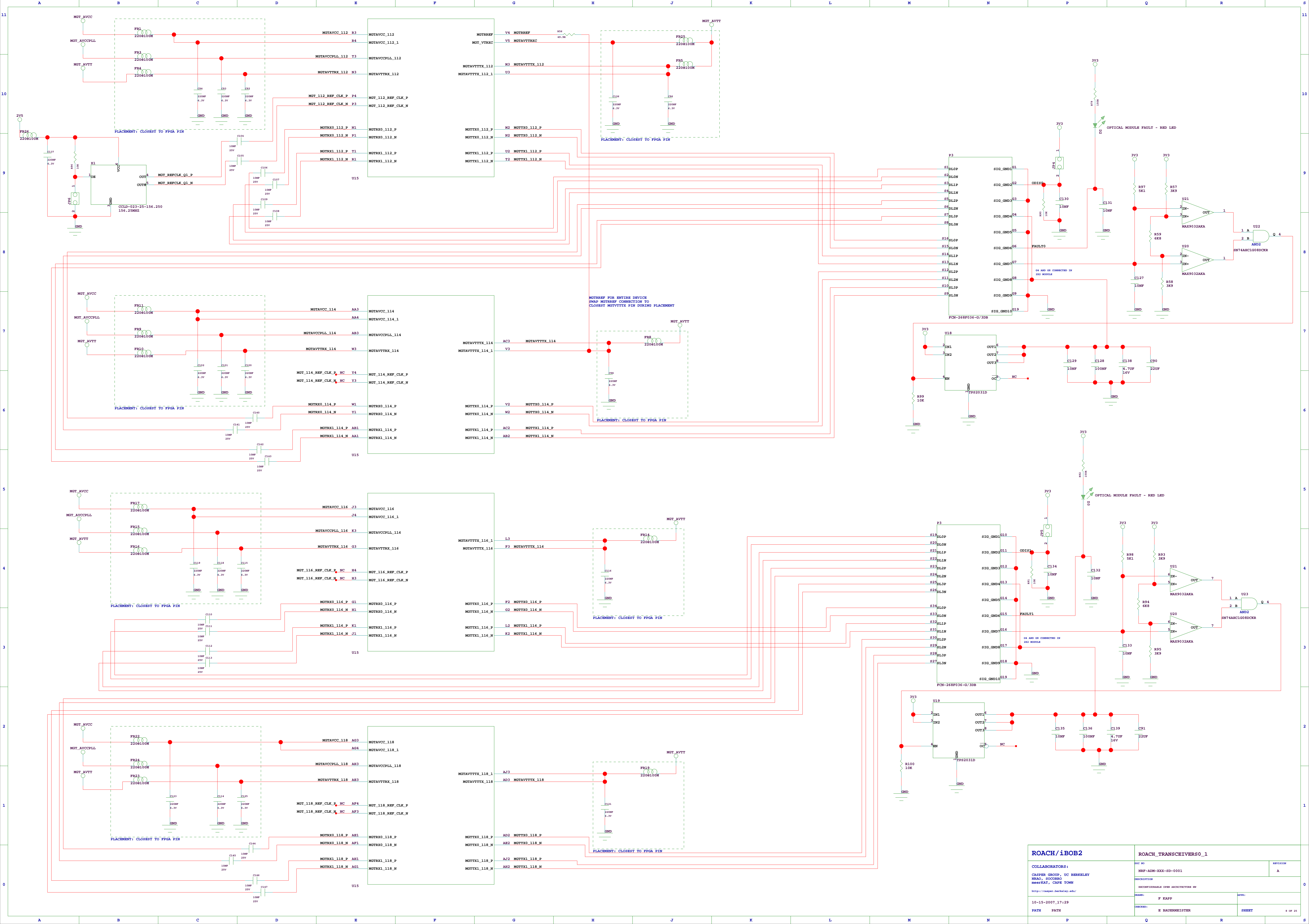
ADJUSTMENT AND T2 RESISTOR VALUES TBD
SOURCE VOLTAGES TO BE SELECTED

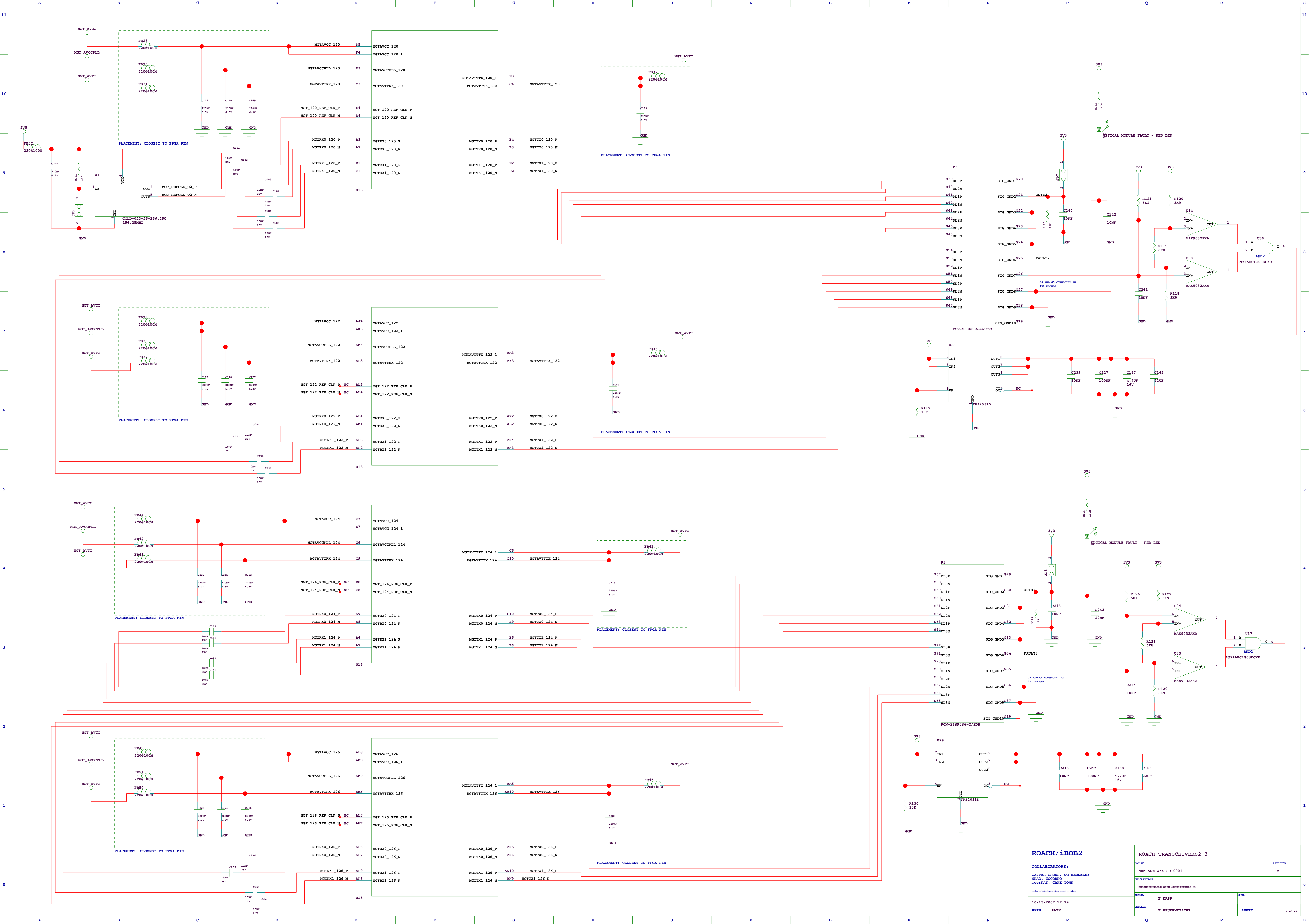
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COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO MesaCAT, CAPE TOWN http://casper.berkeley.edu/ 10-15-2007, 17:29 PATH PATH				DOC NO		REVISION	
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				RECONFIGURABLE OPEN ARCHITECTURE HW			
				DRAWN:		APPD:	
				F KAPP			
CHECKED:				R BAUERMEISTER		SHEET	
						3 OF 25	





ROACH/iBOB2		ROACH_V5_CLK	
COLLABORATORS:		DOC NO	REVISION
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-SD-0001	A
DESCRIPTION		RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/		DRAWN:	APPR:
10-15-2007_17:29		F KAPP	
PATH		CHECKED:	SHEET
		E BAUERMEISTER	7 OF 25





ROACH/iBOE2

COLLABORATORS:

CASPER GROUP, UC BERKELEY

NRAO, SOCCORO

BERKELEY, CALIF. TOWN

RECONFIGURABLE OPEN ARCHITECTURE HW

10-15-2007_17:29

PATH PATH

ROACH_TRANSCEIVERS2_3

DOC NO

NRF-ADM-XXX-BD-0001

DESCRIPTION

RECONFIGURABLE OPEN ARCHITECTURE HW

10-15-2007_17:29

PATH PATH

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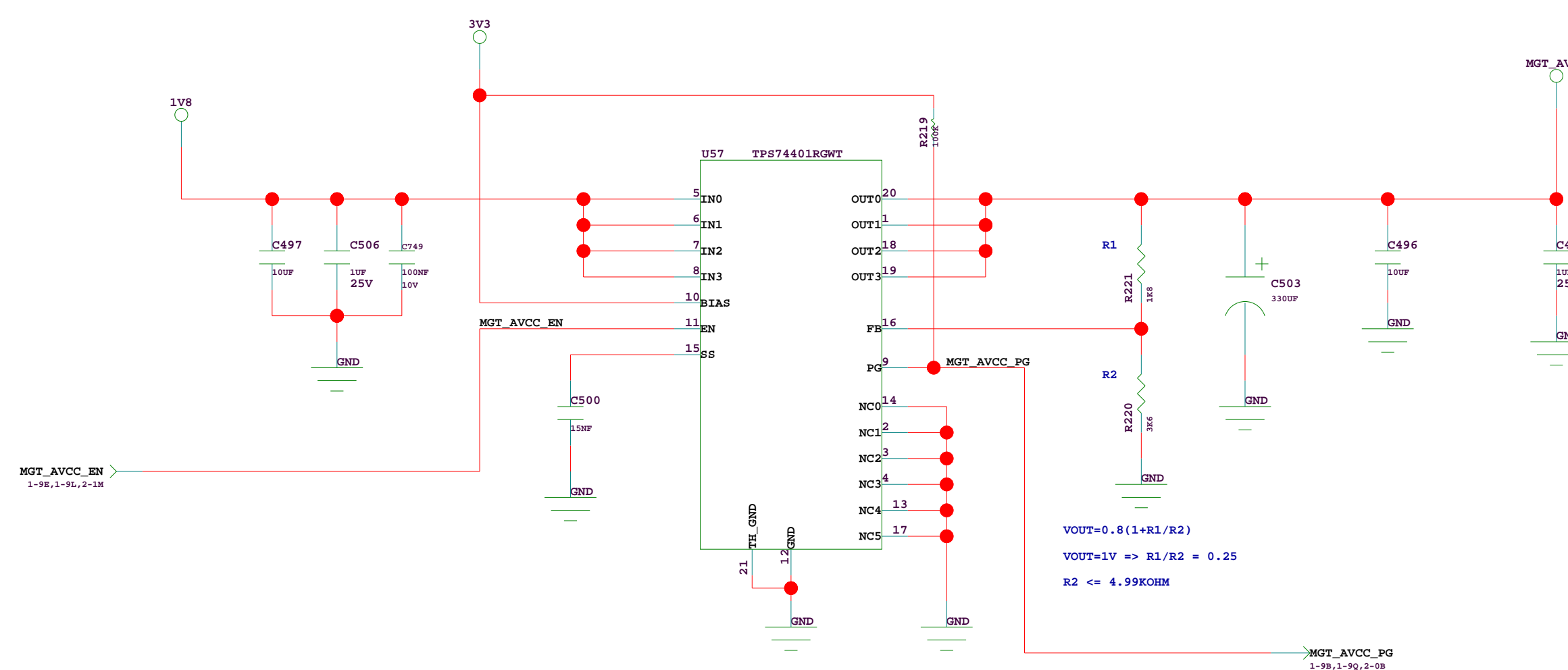
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DESCRIPTION

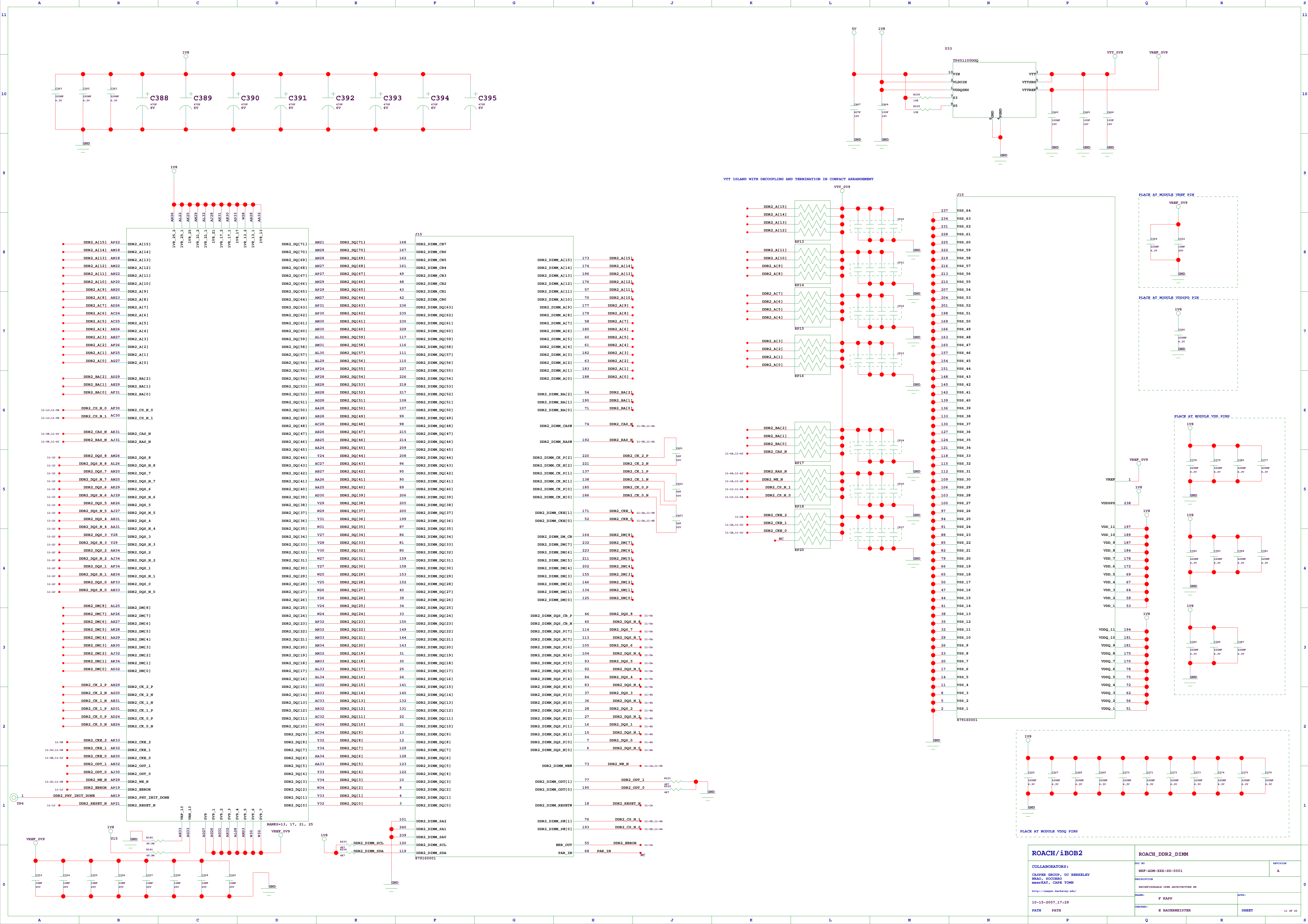
RECONFIGURABLE OPEN ARCHITECTURE HW

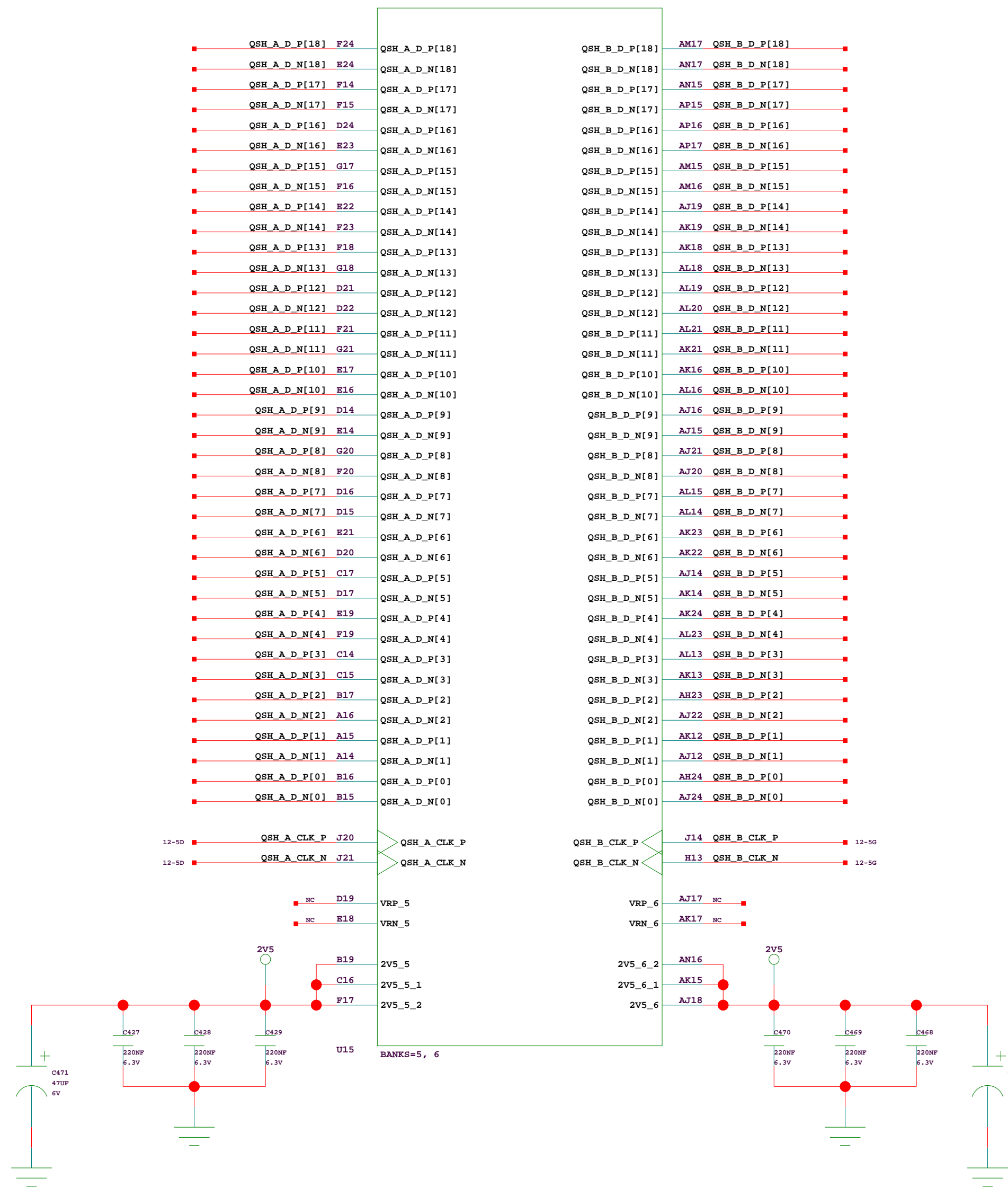
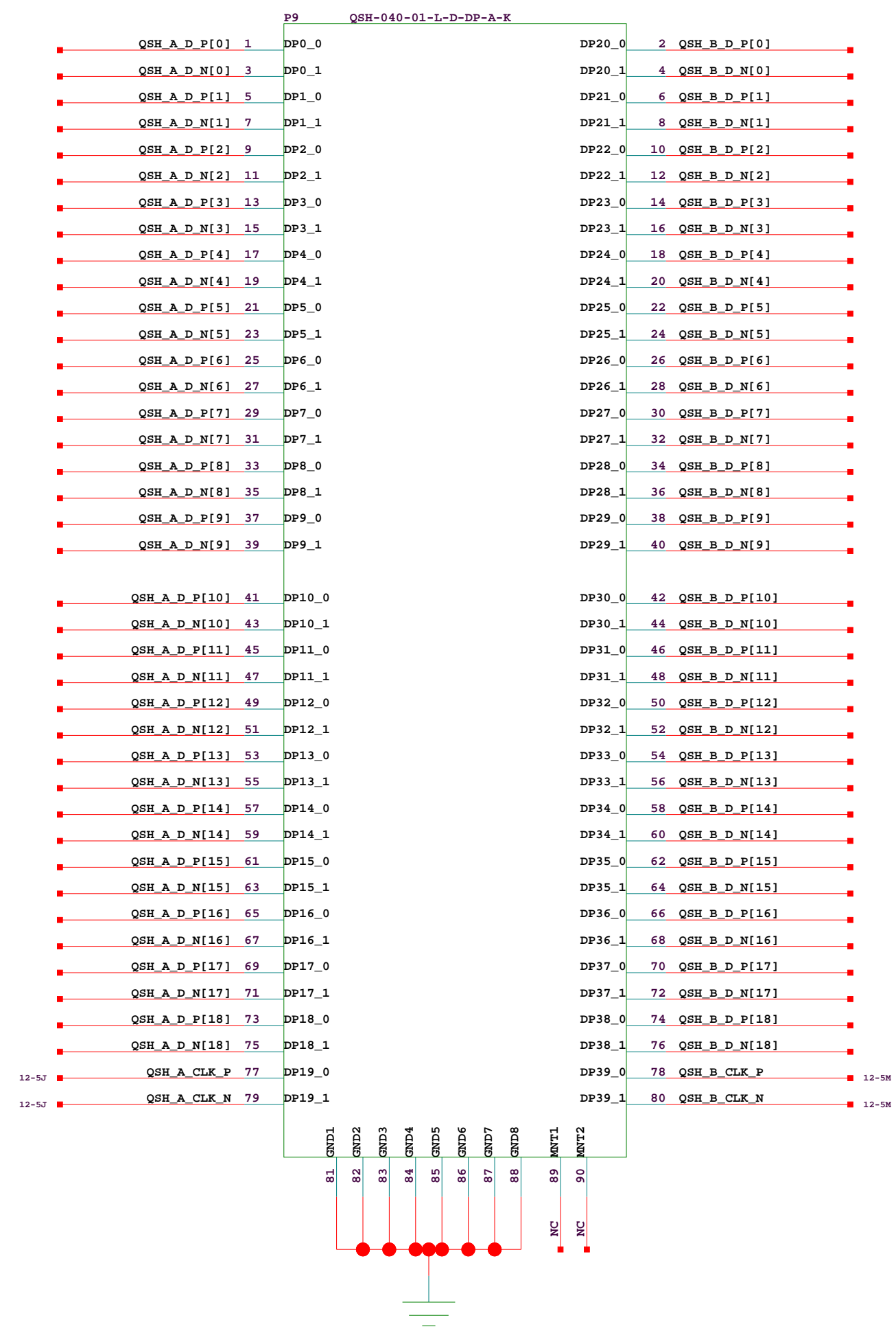
10-15-2007_17:29

PATH PATH

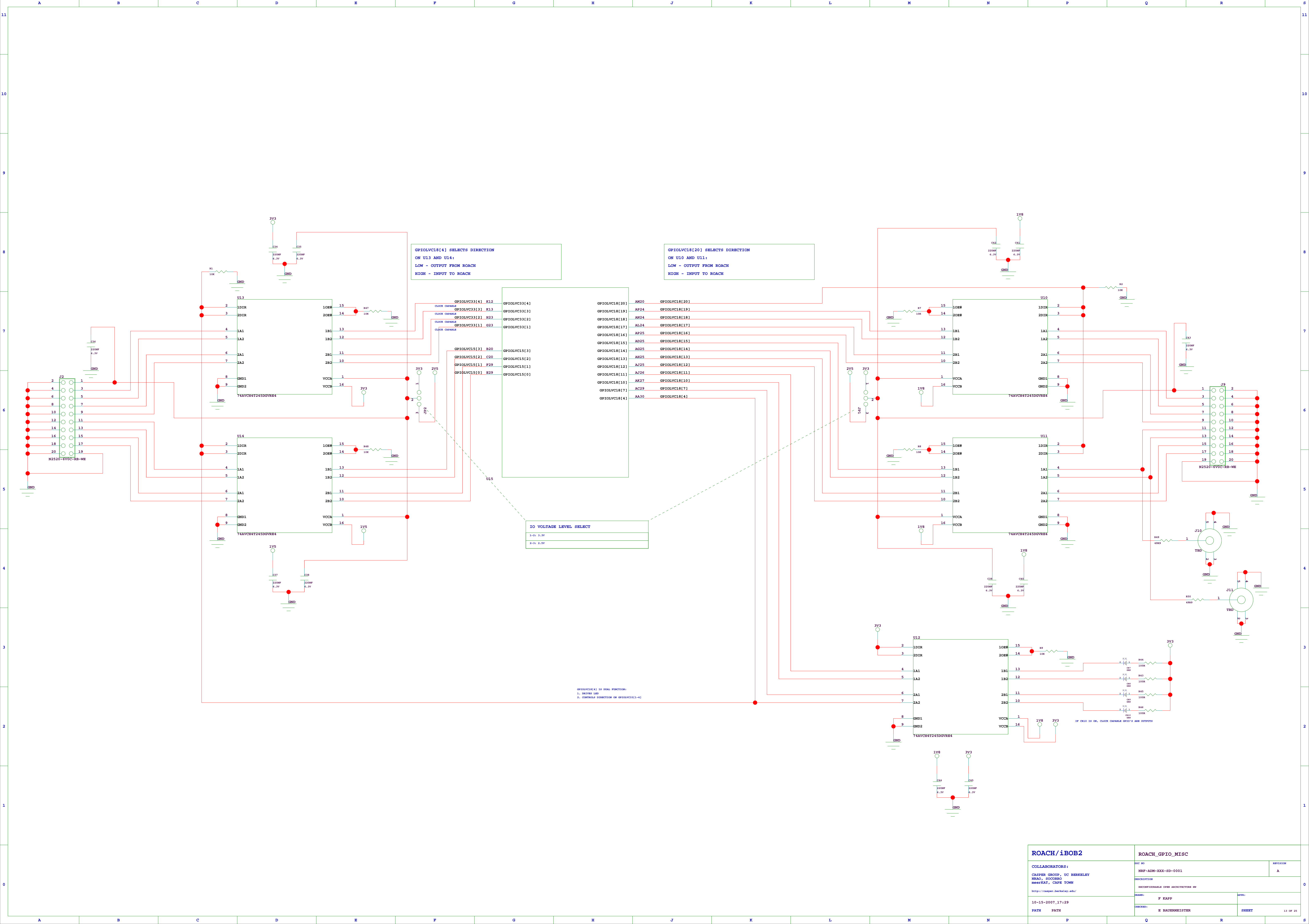


ROACH/iBOB2	ROACH_TRANSCEIVERS_PSU	
COLLABORATORS: CASPER GROUP, UC BERKELEY NEMO, SECURIO MAKEFAST, CAPE TOWN http://casper.berkeley.edu/	DOC NO NRP-ADM-XXX-ED-0001 DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE SW	REVISION A
10-15-2007: 17:29	ISSUED: F KAPP	APPRO:
PATH PATH	ISSUED: K BAUMHEISTER	SHEET
		10 OF 2

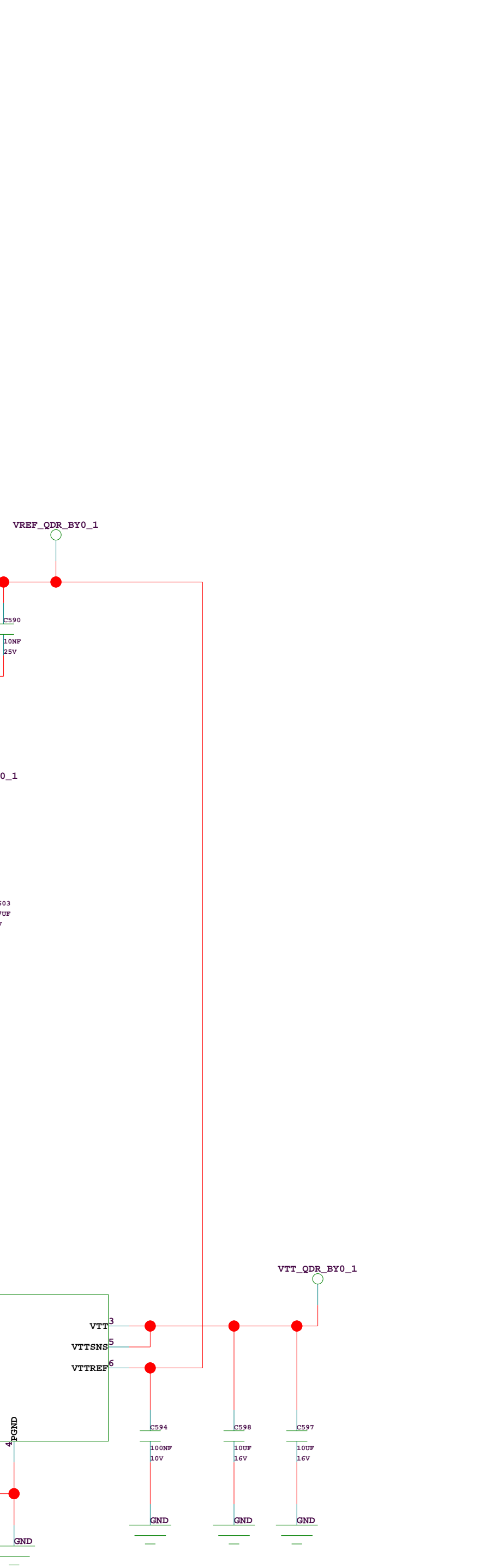
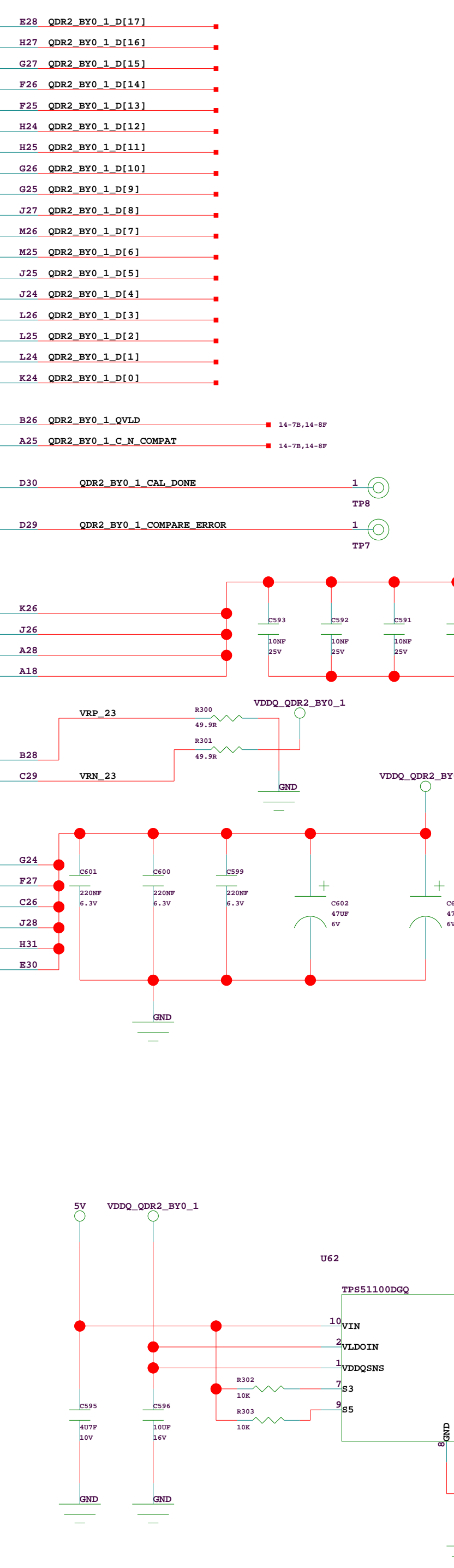
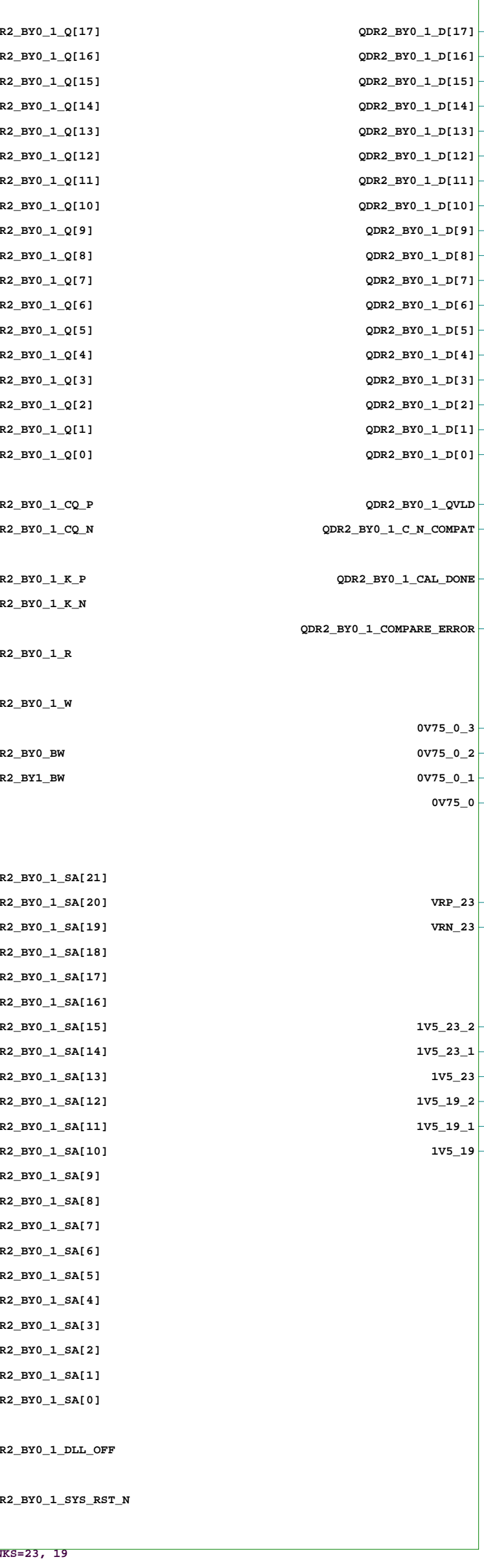
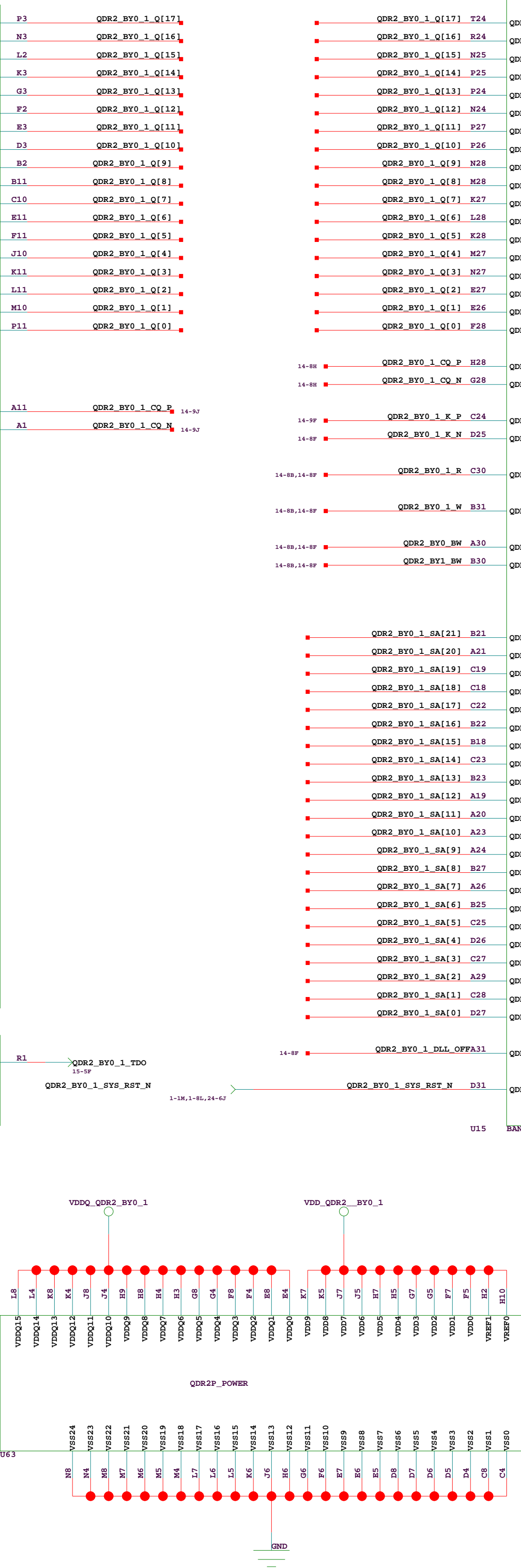
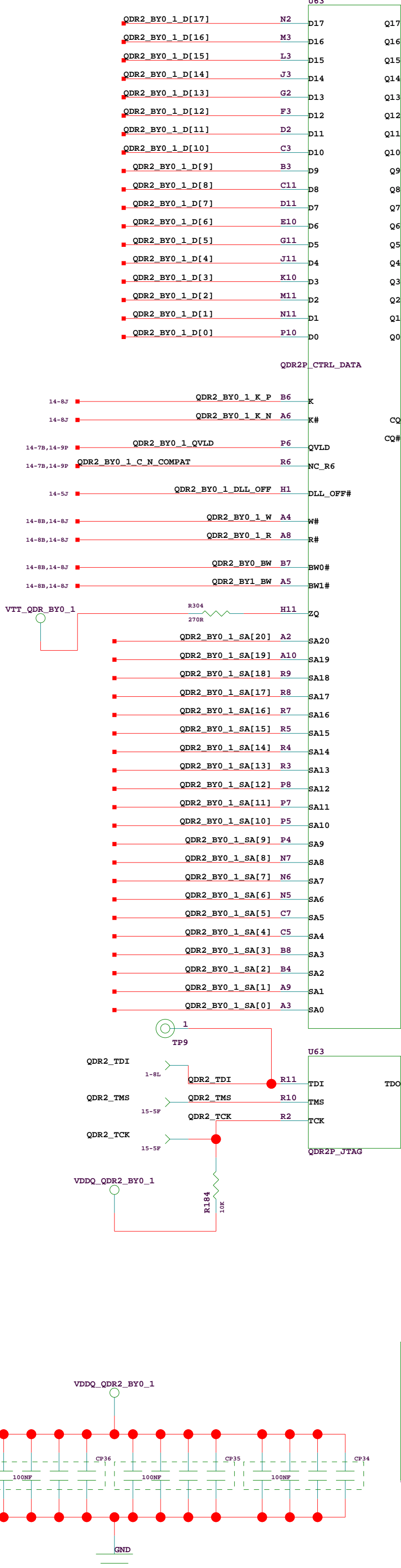
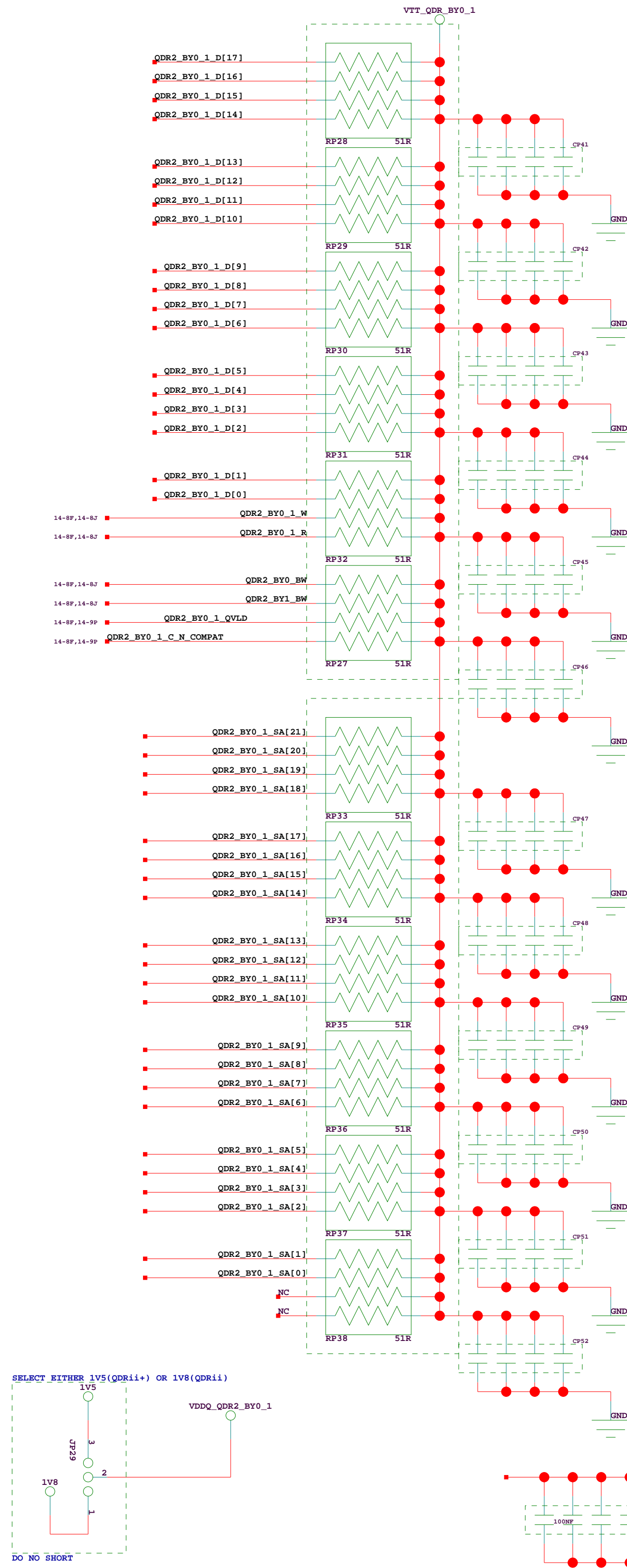




ROACH/iBOB2		ROACH_DIFF_GPIO	
COLLABORATORS:		DOC NO	REVISION
CASPER GROUP, UC BERKELEY MRSO, ACCORDO MRS&AT, CAPE TOWN		RMF-ADM-XXX-ID-0001	A
DESCRIPTION		RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/		ISSUE:	APPR:
10-15-2007-17:29		F KAPP	
PATH PATH		E BAUERMEISTER	SHEET
		12 OF 2	

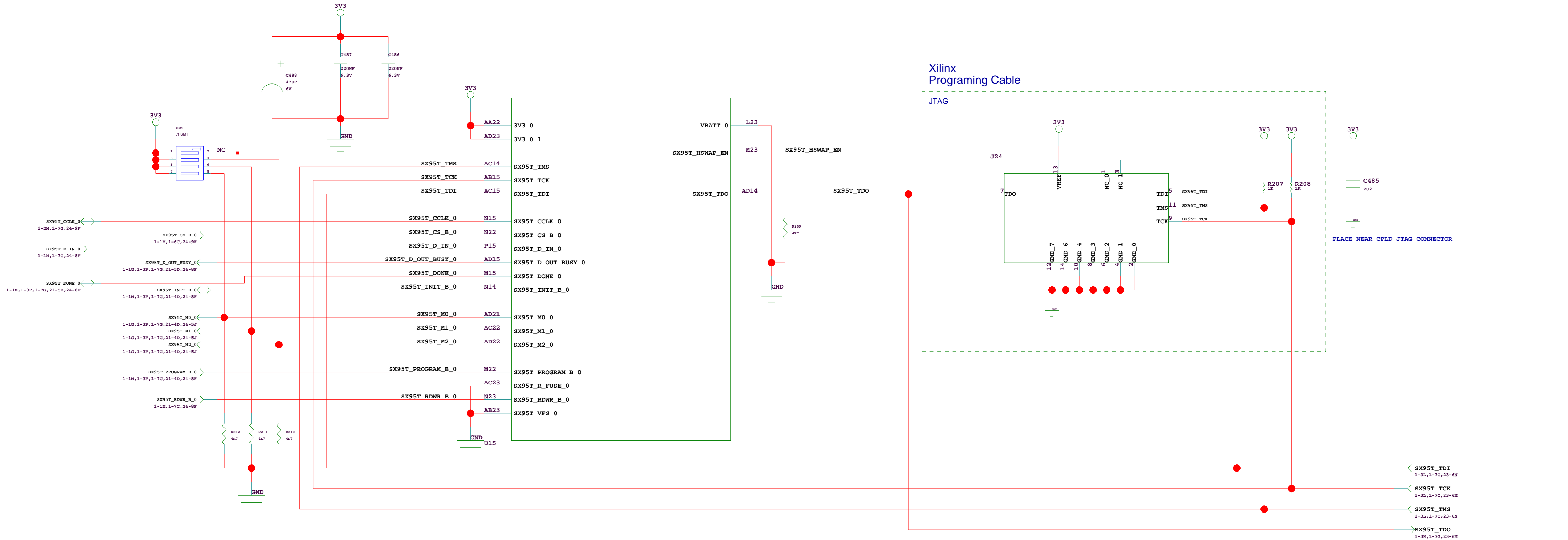


ROACH/iBOE2		ROACH_GPIO_MISC	
COLLABORATORS:		DCC NO	REVISION
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-BD-0001	A
DESCRIPTION			
NRAO, SOONERO			
MAREKAT, CAPE TOWN			
RECONFIGURABLE OPEN ARCHITECTURE HW			
http://casper.berkeley.edu/		DESIGNER	APPR
10-15-2007_17:29		F KAPP	
PATH	PATH	R BAUERNBIESTER	
		CHECKED	SHEET

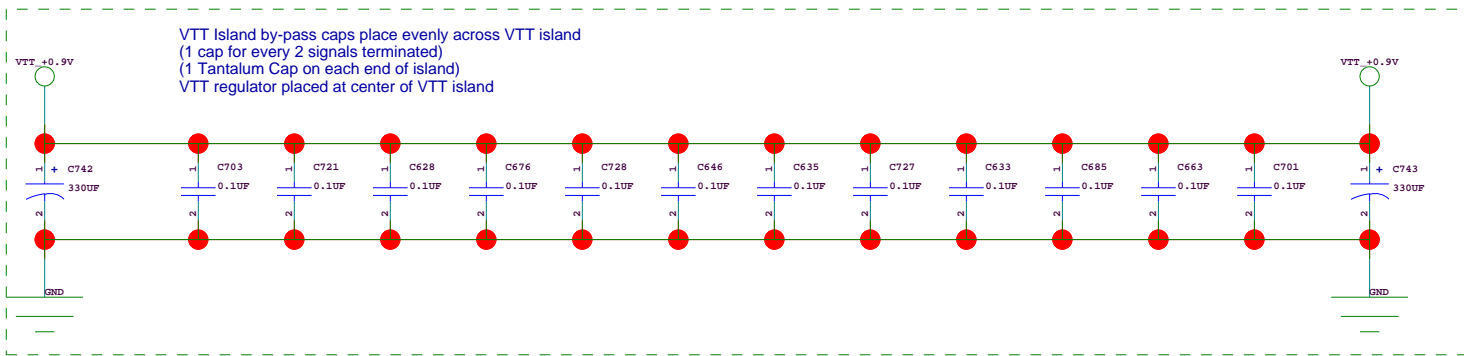
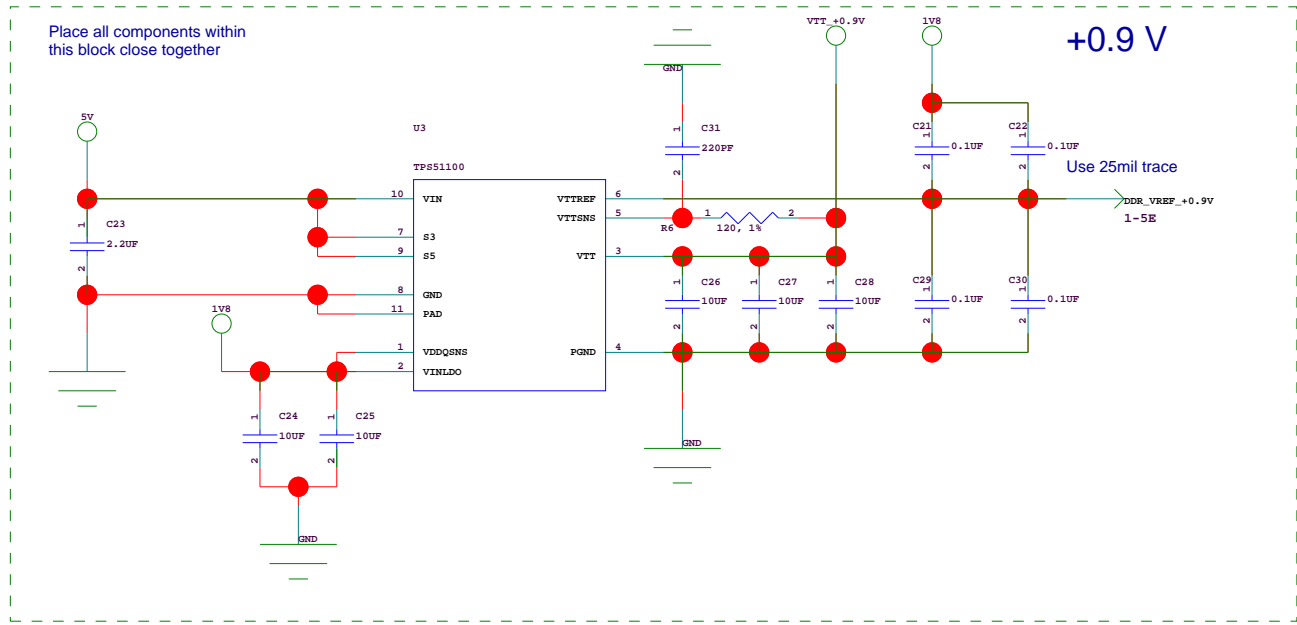
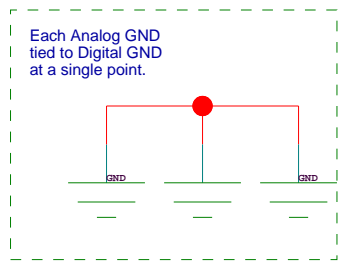
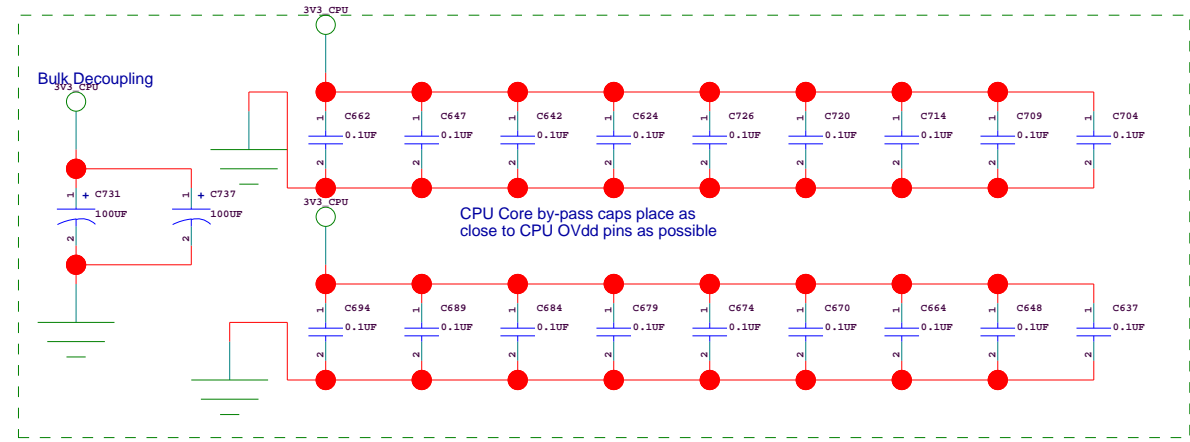
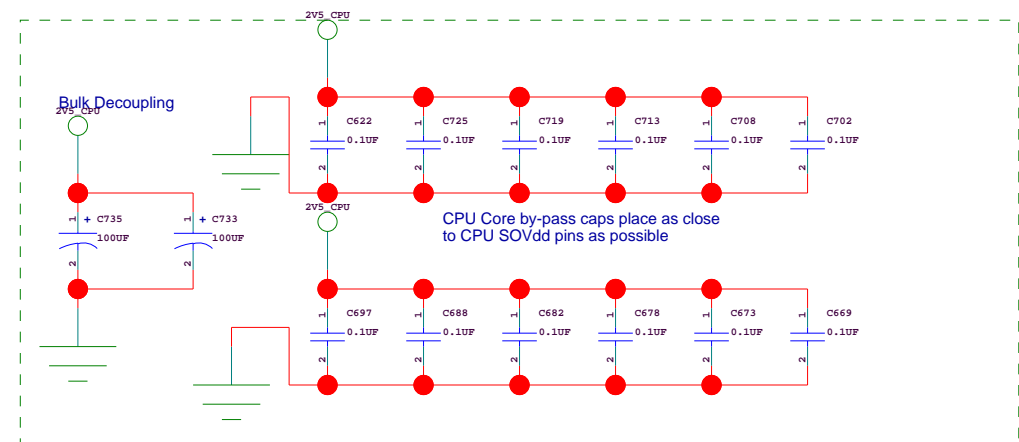
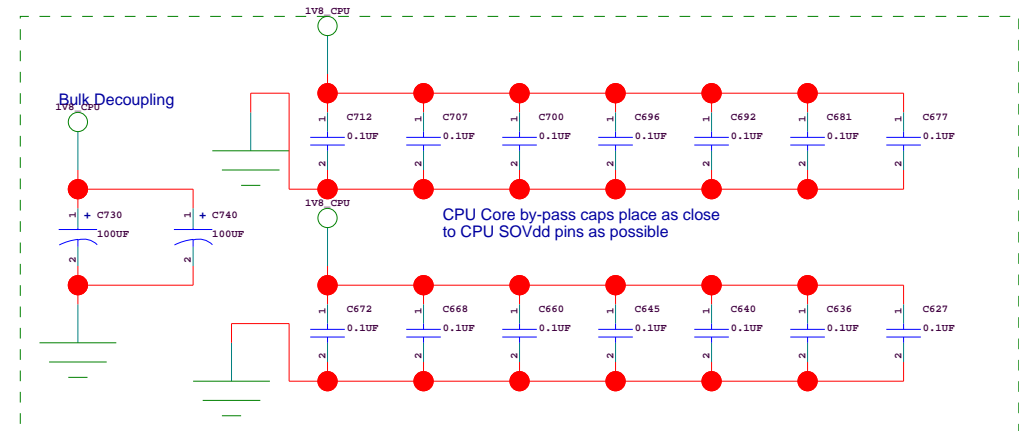
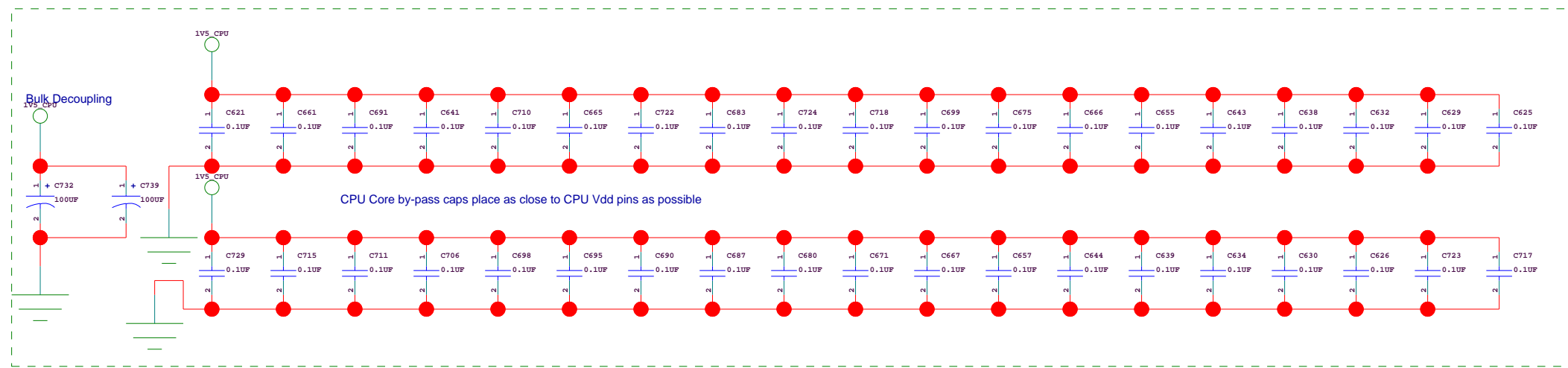
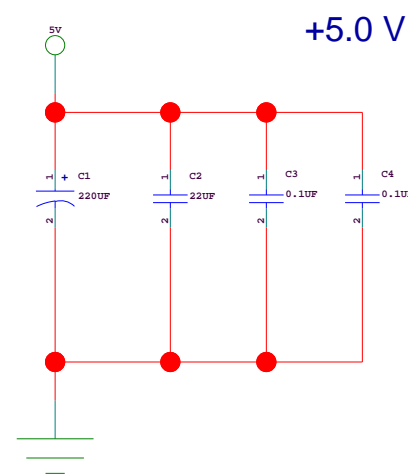
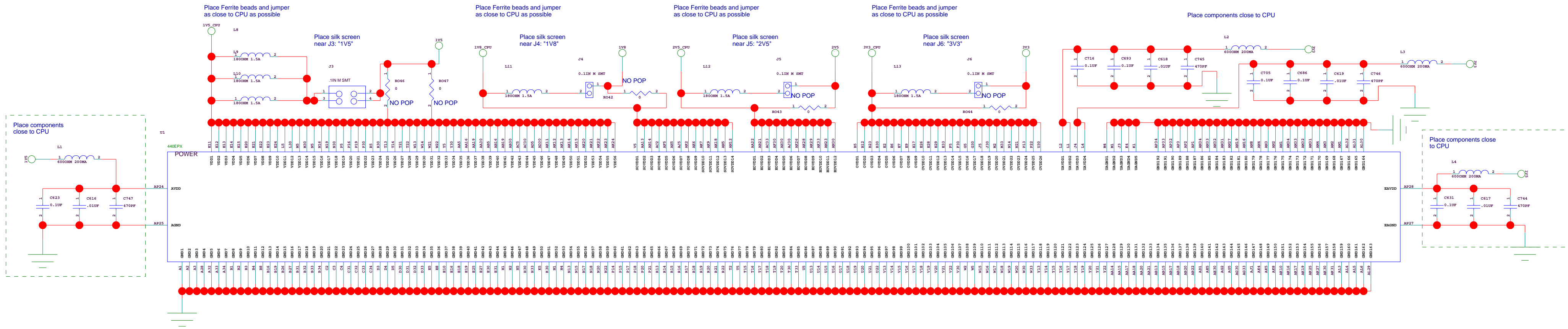


TBD

VALID CONFIGURATION MODES			
Configuration Mode	M[2:0]	Bus Width	CCLK Direction
Master Serial	000	1	Output
Master SPI	001	1	Output
Master BPI-Up	010	8, 16	Output
Master BPI-Down	011	8, 16	Output
Master SelectMAP	100	8, 16	Output
JTAG	101	1	Input (TCK)
Slave SelectMAP	110	8, 16, 32	Input
Slave Serial	111	1	Input



ROACH/iBOB2		ROACH_CONFIG	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN http://casper.berkeley.edu/		DOC NO NRF-ADM-XXX-SD-0001 DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW	REVISION A
10-15-2007_17:29		DRAWN: F KAPP	APPR:
PATH PATH		CHECKED: E BAUERMEISTER	SHEET 16 OF 25



ROACH/iBOE2

COLLABORATORS:
CASPER GROUP, UC BERKELEY
NRAO, SOONERO
BaeKAT, CAPE TOWN
<http://casper.berkeley.edu/>

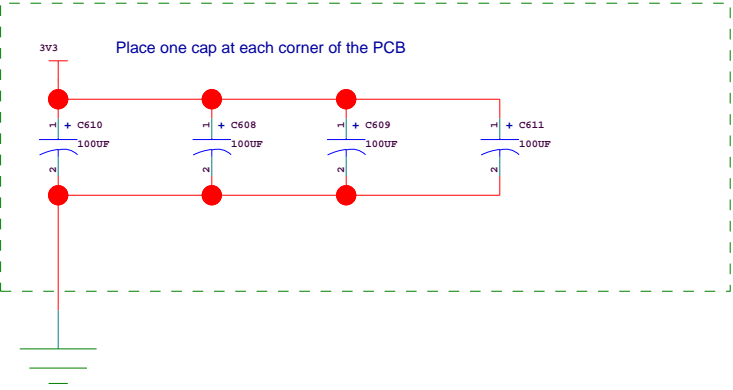
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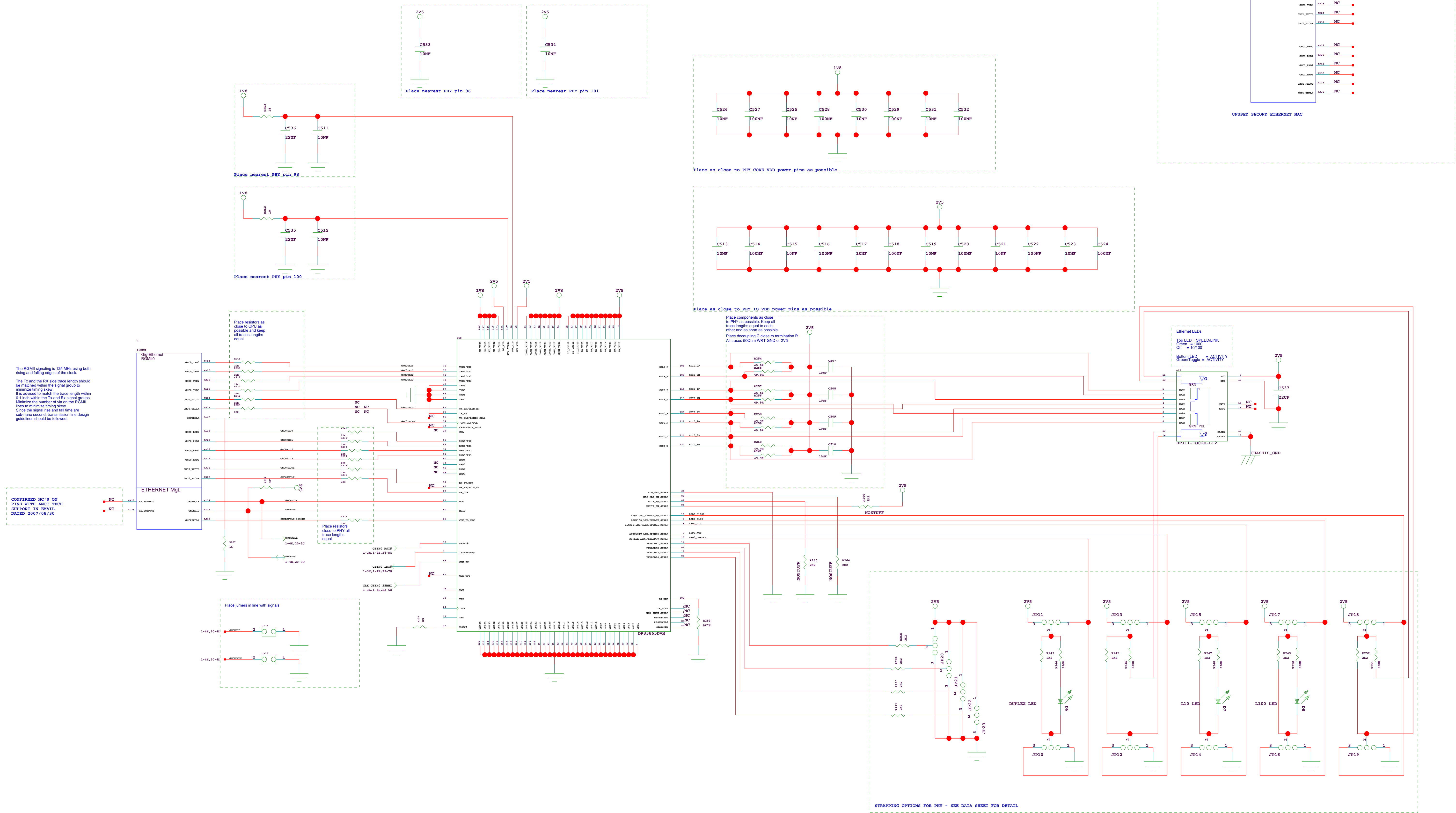
ROACH_PPC_POWER_1

DOC NO: NRP-ADM-XXX-BD-0001
REVISION: A

DESCRIPTION: RECONFIGURABLE OPEN ARCHITECTURE HW

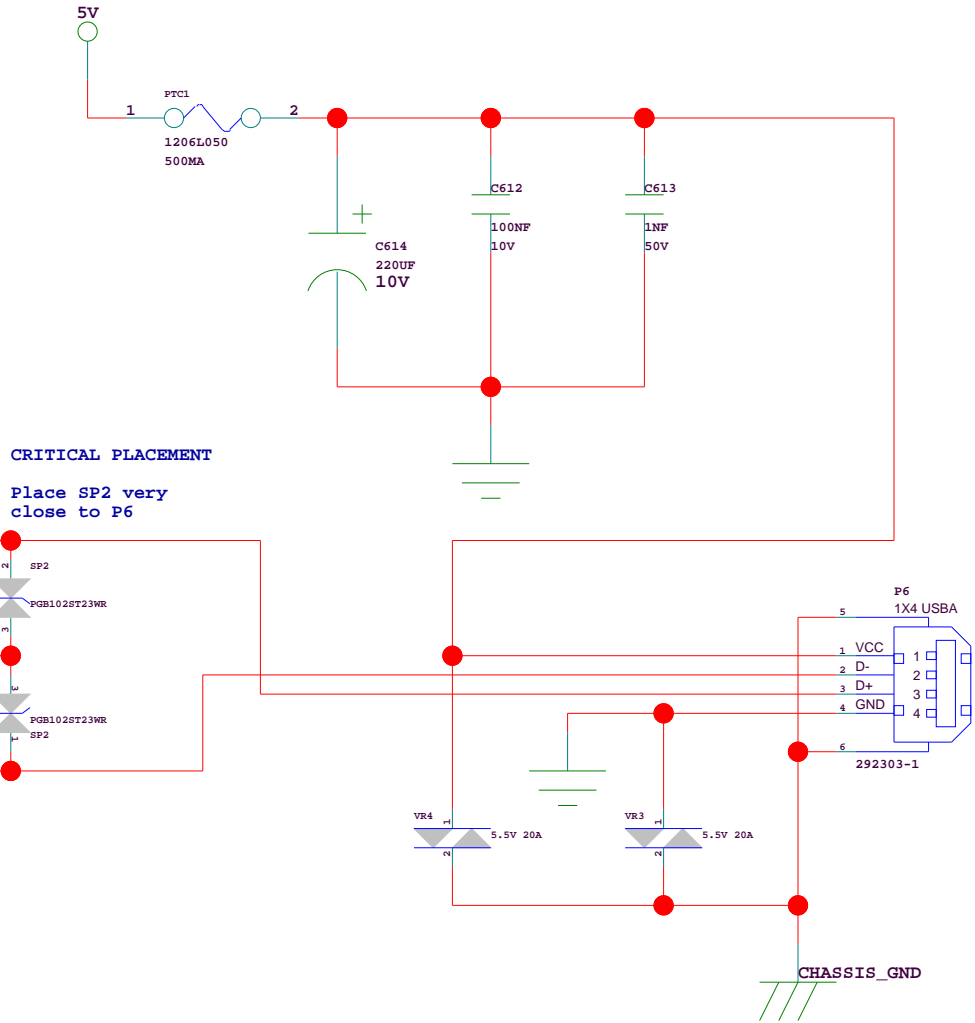
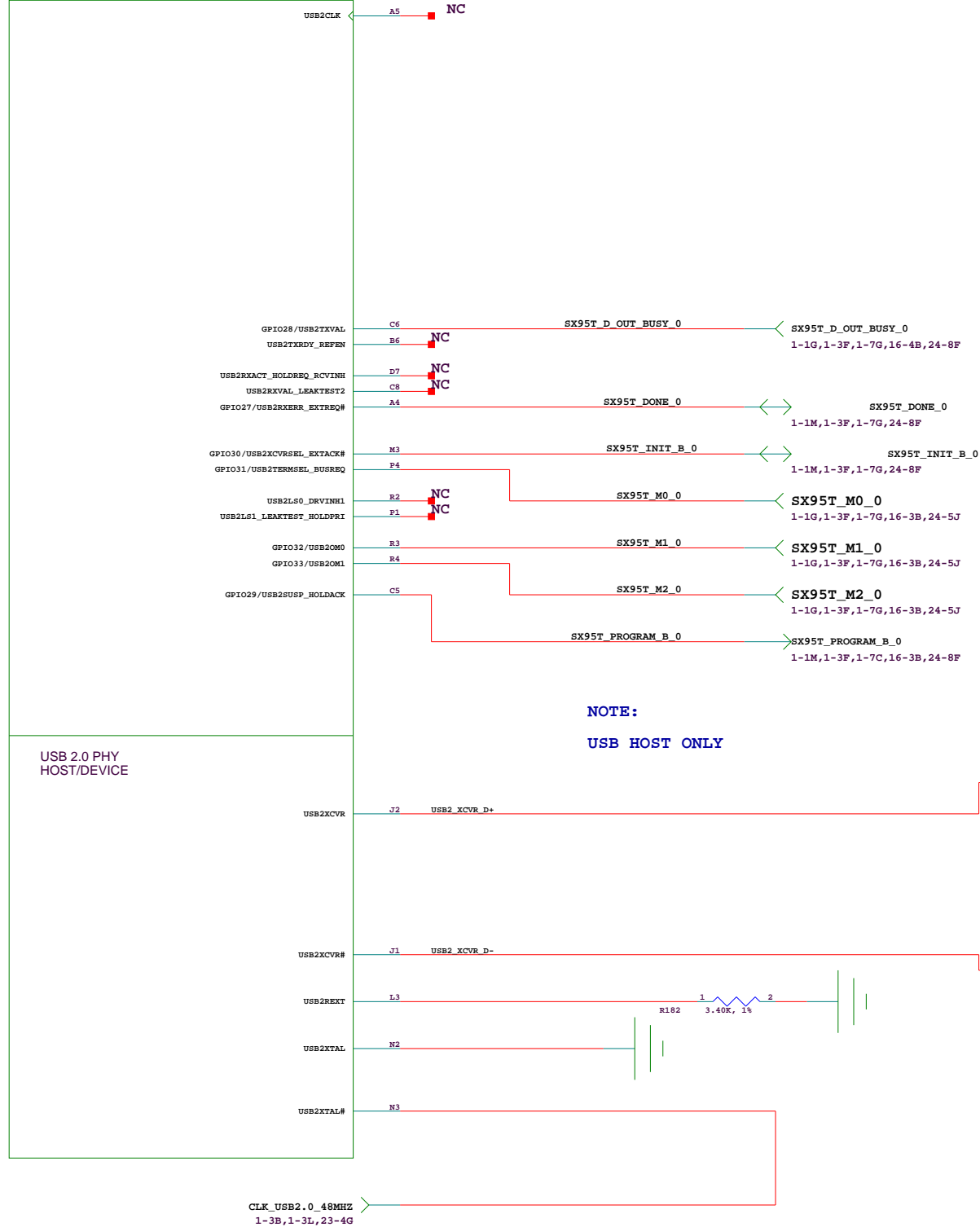
DESIGNER: F KAPP
CHECKED: R BAUERMEISTER
SHEET: 17 OF 25

A	B	C	D	E	F	G	H	J	K	L	M																		
7											7																		
6	<div>REMOVED 3V3 GENERATION</div> <div></div>										6																		
5											5																		
4	<div>REMOVED +12V GENERATION</div> <div>REMOVED -12V GENERATION</div>										4																		
3											3																		
2											2																		
1	<div>REMOVED +1V GENERATION</div> <div>REMOVED +2V5 GENERATION</div>										1																		
0	<table><tr><td colspan="2">ROACH/iBOB2</td><td colspan="2">ROACH_PPC_POWER_2</td></tr><tr><td colspan="2" rowspan="2">COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN http://casper.berkeley.edu/</td><td>DOC NO NRF-ADM-XXX-SD-0001</td><td>REVISION A</td></tr><tr><td colspan="2">DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW</td></tr><tr><td colspan="2">10-15-2007_17:29</td><td>DRAWN: F KAPP</td><td>APPR:</td></tr><tr><td>PATH</td><td>PATH</td><td>CHECKED: E BAUERMEISTER</td><td>SHEET 18 OF 25</td></tr></table>										ROACH/iBOB2		ROACH_PPC_POWER_2		COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN http://casper.berkeley.edu/		DOC NO NRF-ADM-XXX-SD-0001	REVISION A	DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW		10-15-2007_17:29		DRAWN: F KAPP	APPR:	PATH	PATH	CHECKED: E BAUERMEISTER	SHEET 18 OF 25	0
ROACH/iBOB2		ROACH_PPC_POWER_2																											
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN http://casper.berkeley.edu/		DOC NO NRF-ADM-XXX-SD-0001	REVISION A																										
		DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW																											
10-15-2007_17:29		DRAWN: F KAPP	APPR:																										
PATH	PATH	CHECKED: E BAUERMEISTER	SHEET 18 OF 25																										
A	B	C	D	E	F	G	H	J	K	L	M																		

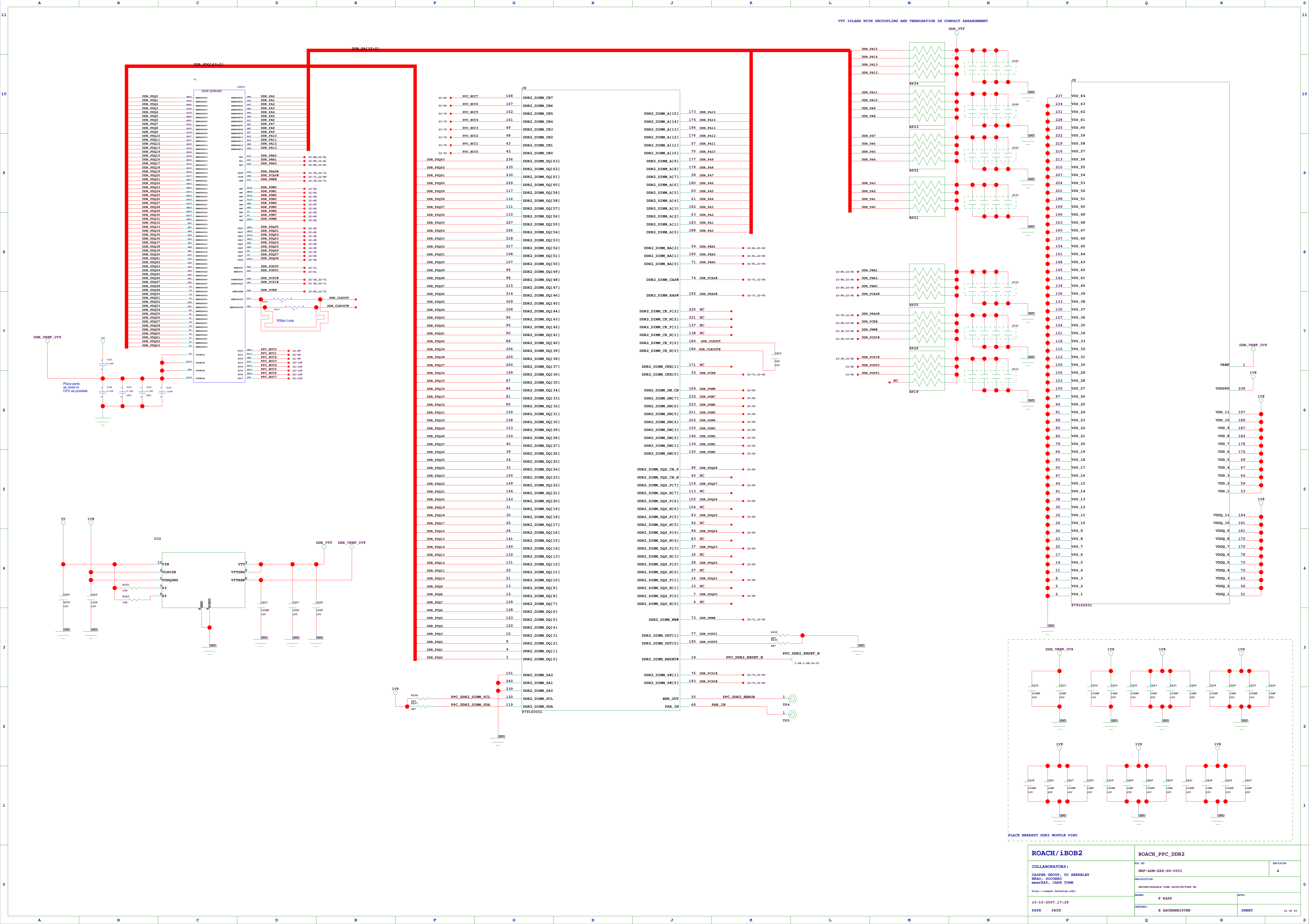


ROACH/iBOB2		ROACH_PPC_ETH1	
COLLABORATORS: CAPSER GROUP, UC BERKELEY BRAD, FOSCHRO meaeKAT, CAPS TOWN http://capers.berkeley.edu/		DOC NO NRP-ADM-XXX-ED-0001 DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE SH	REVISION A
10-15-2007_17:29 PATH PATH		NAME: F KAPP CHECKED: K BAUERMISTER	APPR: SHEET
		20 OF 2	

U1
USB 2.0 DEVICE
40EPA



ROACH/iBOB2		ROACH_PPC_USB	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN http://casper.berkeley.edu/	DOC NO NRF-ADM-XXX-SD-0001		REVISION A
	DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW		
	DRAWN: F KAPP		APPR:
10-15-2007_17:29	CHECKED: E BAUERMEISTER		SHEET 21 OF 25
PATH	PATH		

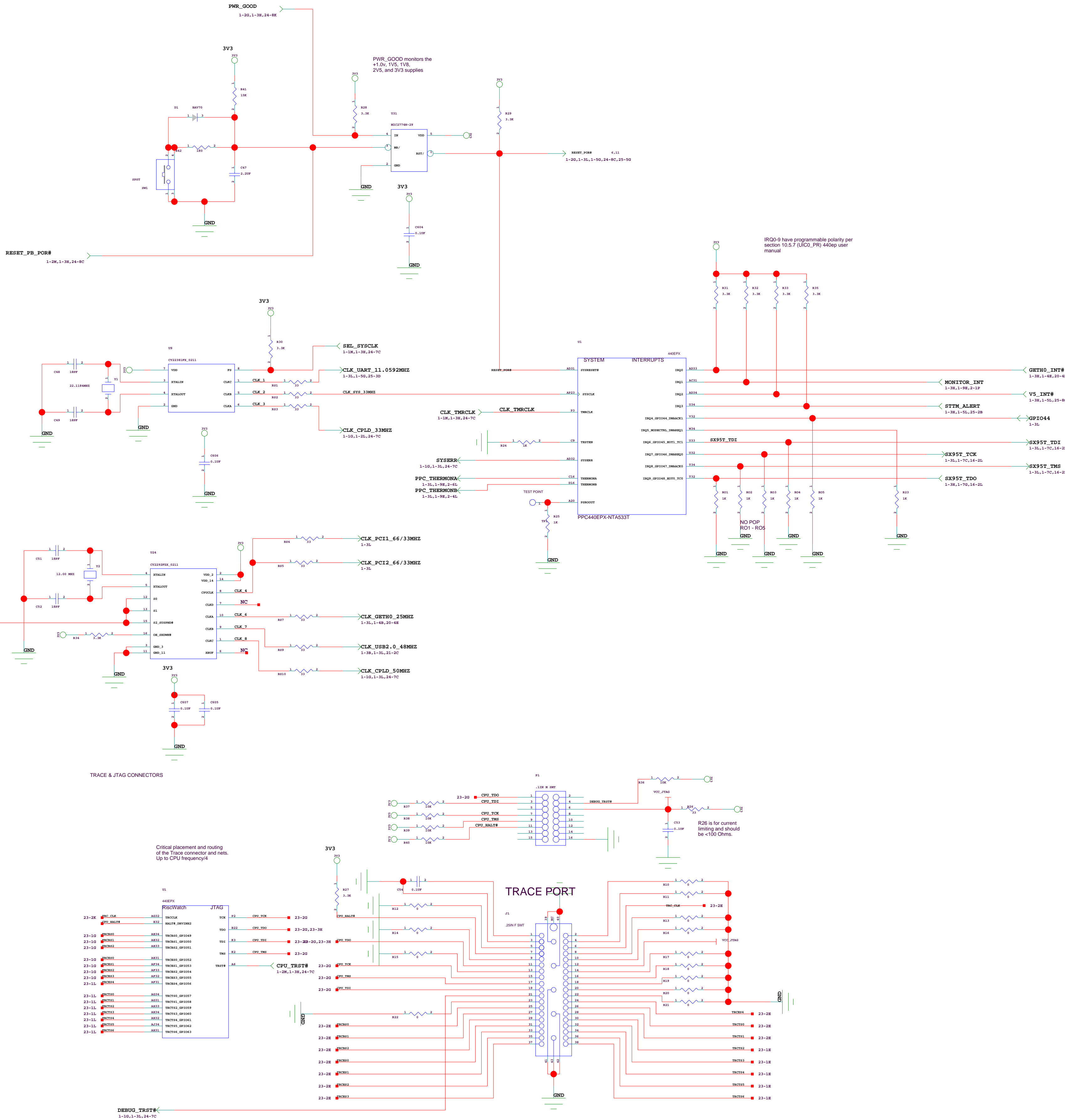


Critical Placement and Route
Clock Rules:

Clock Rules:
CLK_UART_11.0592MHz = as short as possible
CLK_SYS_33MHz = as short as possible
CLK_CPLD_33MHz = CLK_SYS_33MHz

Critical Placement and Route
Clock Rules:

Clock Rules:
CLK_PC13_66.33MHz = as short as possible
CLK_PC12_66.33MHz = CLK_PC13_66.33MHz
CLK_PC11_66.33MHz = CLK_PC12_66.33MHz + 2.5°
CLK_GETH0_25MHz = as short as possible
CLK_GETH1_25MHz = CLK_GETH0_25MHz
CLK_CPLD_50MHz = as short as possible
CLK_USB2_0_48MHz = as short as possible
CLK_USB2_0_12MHz = as short as possible



ROACH/iBOE2		ROACH_PPC_TST_CLK_IO	
COLLABORATORS:		DOC NO	REVISION
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-SD-0001	A
HW#, @COCORD		DESCRIPTION	
BARKERAT, CAPE TOWN		RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/		DESIGN:	APP:
10-15-2007_17:29		F KAPP	
PATH PATH		CHECKED:	SHEET
		E BAUERMEISTER	23 OF 2

ROACH/iBOB2		ROACH_PPC_CPLD	
COLLABORATORS: CASPER GROUP, UC BERKELEY BRAD, GORDON MEECEAT, CAPE TOWN http://casper.berkeley.edu/		DOC NO NRP-ADM-XXX-ED-0001 DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE RM	REVISION A
NAME: 10-15-2007_17:29		F KAPP	APP:
CHECKED: PATH PATH		F BAUMHOLSTER	SHEET 24 OF 2

