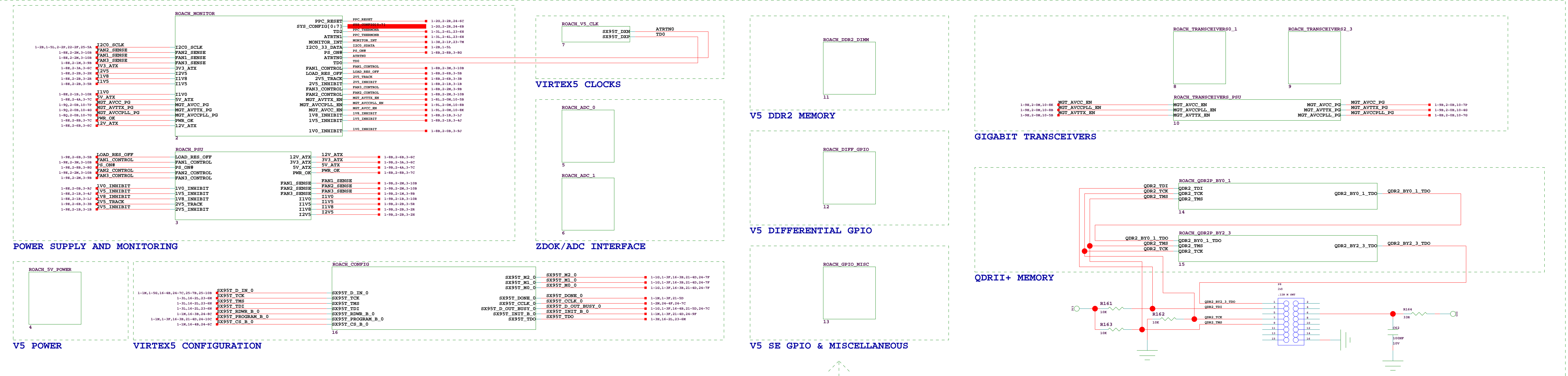
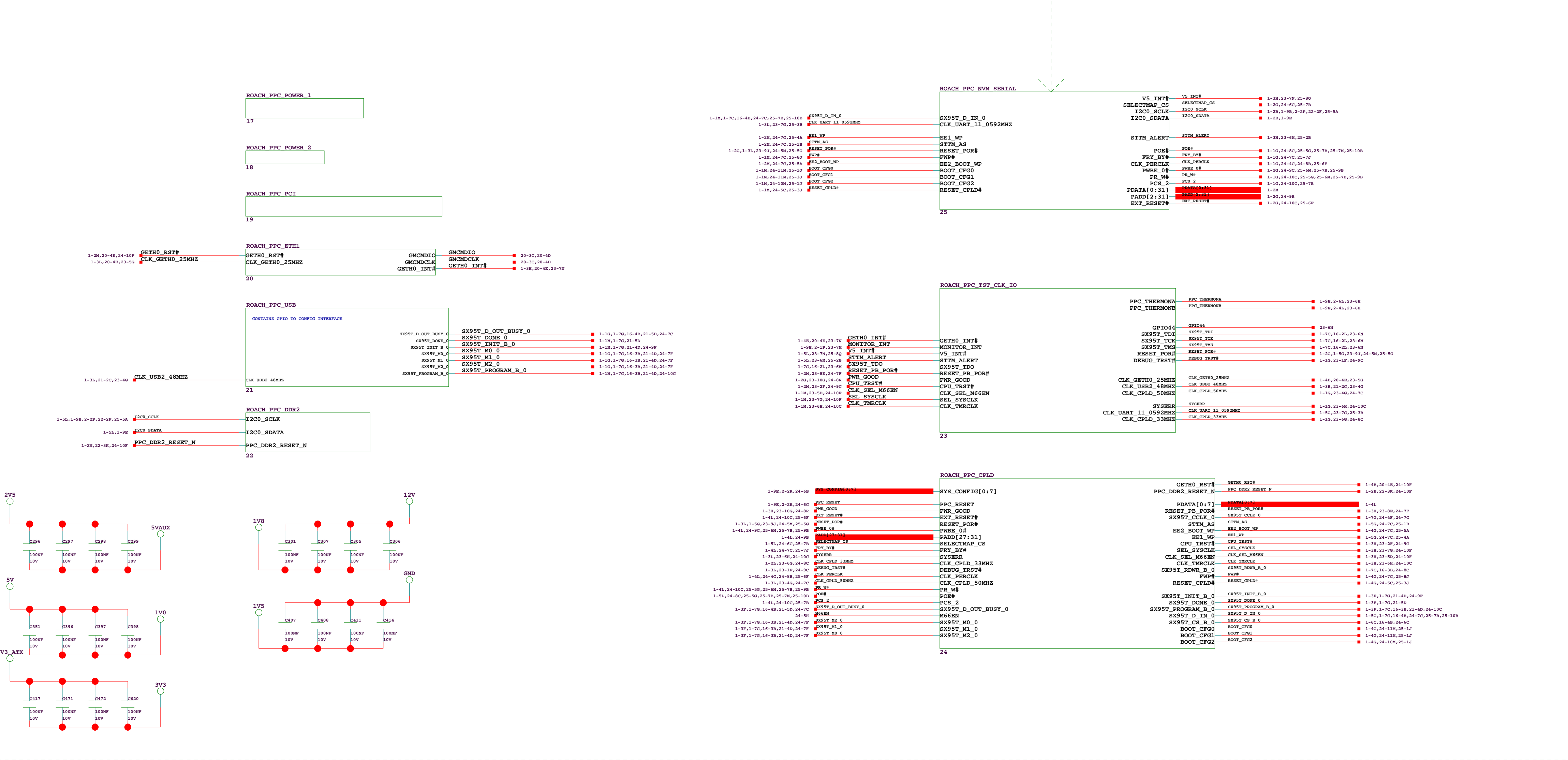


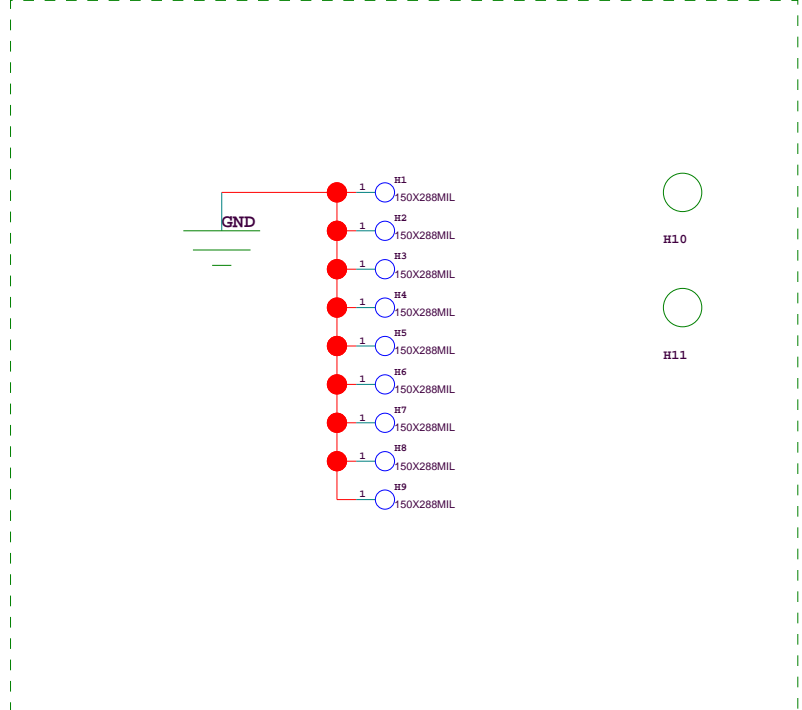
## VIRTEX5



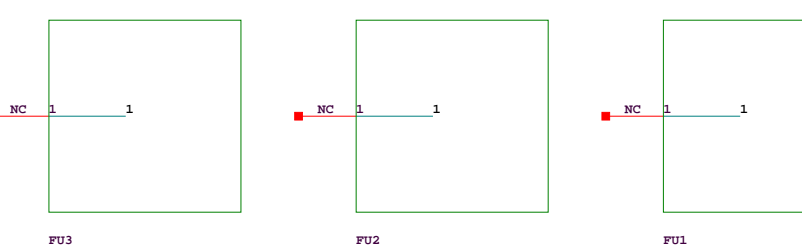
## PPC



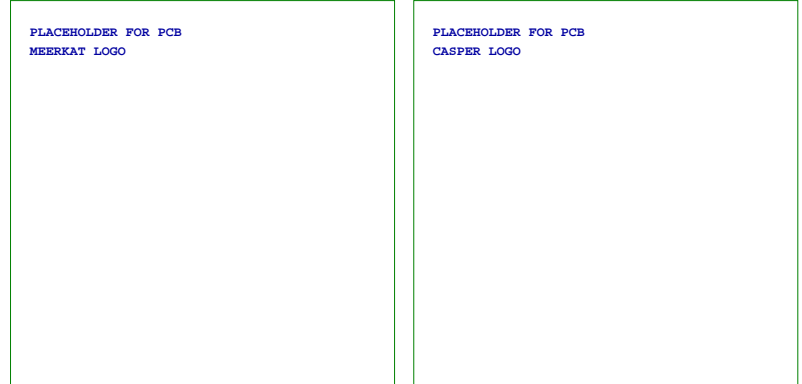
## MECHANICAL



## BOARD FIDUCIALS



## LOGO'S

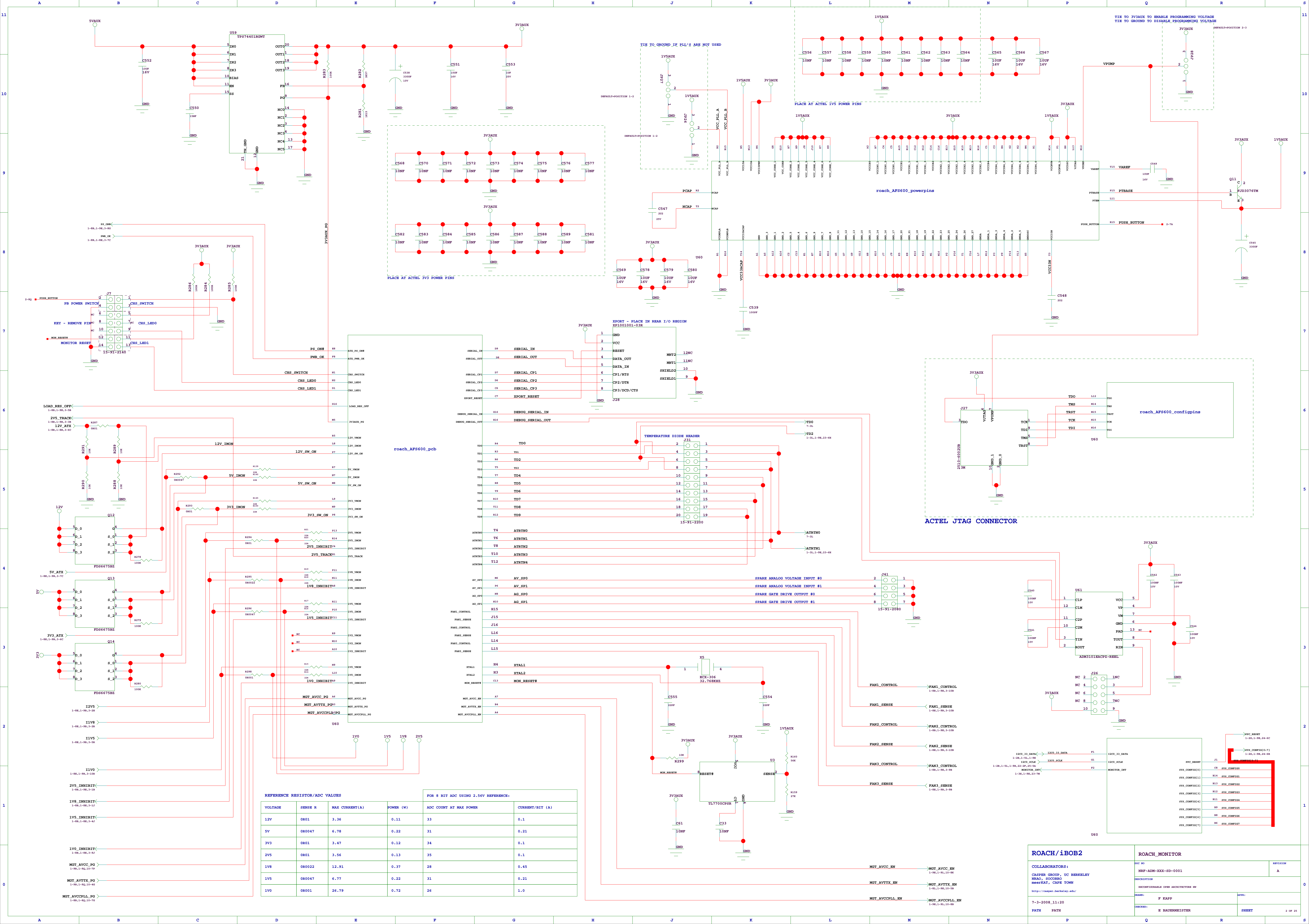


### CONTRIBUTORS

STEVEN BAUMGARTNER  
FRANCIS KAPP  
ALAN LAMANN  
GORDON PECK  
MIKE RYAN  
DAN NEUTSCHER

### ROACH/iBOB2

COLLABORATORS:		ROACH_TOP	REV
MRF-ADM-XXX-SD-0001		ROACH_TOP	A
RECONFIGURABLE OPEN ARCHITECTURE HW		ROACH_TOP	
http://casper.lamarkley.edu/		ROACH_TOP	
7-3-2008.11.20		ROACH_TOP	
PATH		ROACH_TOP	
F KAPP		ROACH_TOP	
R BAUMGARTNER		ROACH_TOP	
SHEET		ROACH_TOP	



REFERENCE RESISTOR/ADC VALUES					FOR 8 BIT ADC USING 2.56V REFERENCE:	
VOLTAGE	SENSE R	MAX CURRENT(A)	POWER (W)	ADC COUNT AT MAX POWER	CURRENT/BIT (A)	
12V	0R01	3.36	0.11	33	0.1	
5V	0R0047	6.78	0.22	31	0.21	
3V3	0R01	3.47	0.12	34	0.1	
2V5	0R01	3.56	0.13	35	0.1	
1V8	0R0022	12.91	0.37	28	0.45	
1V5	0R0047	6.77	0.22	31	0.21	
1V0	0R001	26.79	0.72	26	1.0	

Roach/iBOE2

COLLABORATORS:  
CASPER GROUP, UC BERKELEY  
NRAO, SOCCORRO  
BARRACAT, CAPE TOWN  
<http://casper.berkeley.edu/>  
7-3-2008\_11:20  
PATH PATH

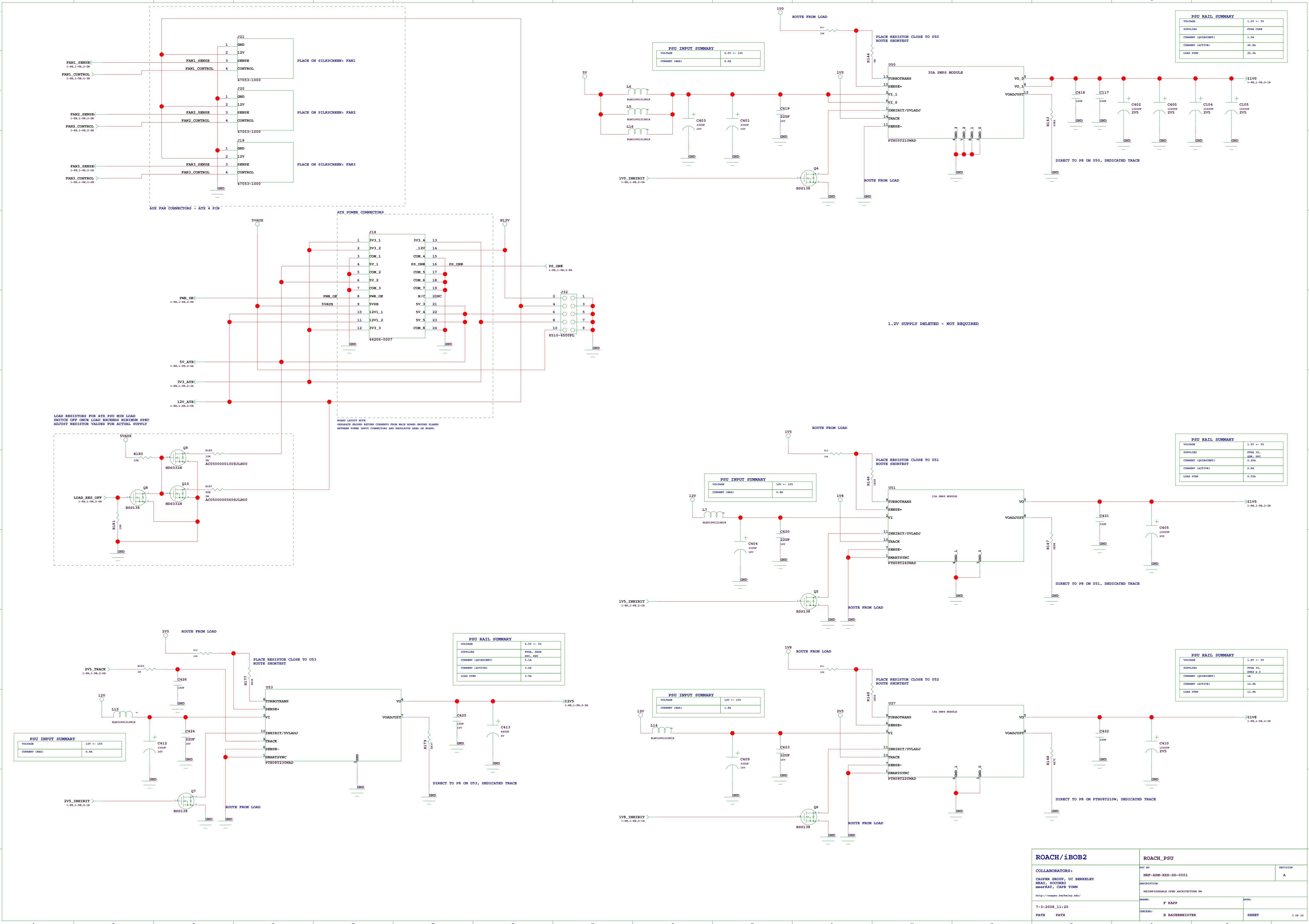
Roach Monitor

DOC NO  
NRF-ADM-XXX-SD-0001  
DESCRIPTION  
RECONFIGURABLE OPEN ARCHITECTURE HW  
DESIGN:  
F KAPP  
CHECKED:  
R BAUERMBISTER

REVISION  
A  
SHEET

2 OF 25





PSU RAIL SUMMARY	
VOLTAGE	1.0V +- 5%
SUPPLIES	PPDA CORR
CURRENT (QUIESCENT)	1.5A
CURRENT (ACTIVE)	26.8A
LOAD STEP	25.3A

PSU INPUT SUMMARY	
VOLTAGE	5.0V +- 10%
CURRENT (MAX)	4.0A

PSU RAIL SUMMARY	
VOLTAGE	1.5V +- 5%
SUPPLIES	PPDA 10V, 20%_PSC
CURRENT (QUIESCENT)	0.25A
CURRENT (ACTIVE)	4.8A
LOAD STEP	4.55A

PSU INPUT SUMMARY	
VOLTAGE	12V +- 10%
CURRENT (MAX)	0.8A

PSU RAIL SUMMARY	
VOLTAGE	1.8V +- 5%
SUPPLIES	PPDA 10V, 100%_P_2
CURRENT (QUIESCENT)	1A
CURRENT (ACTIVE)	12.9A
LOAD STEP	11.9A

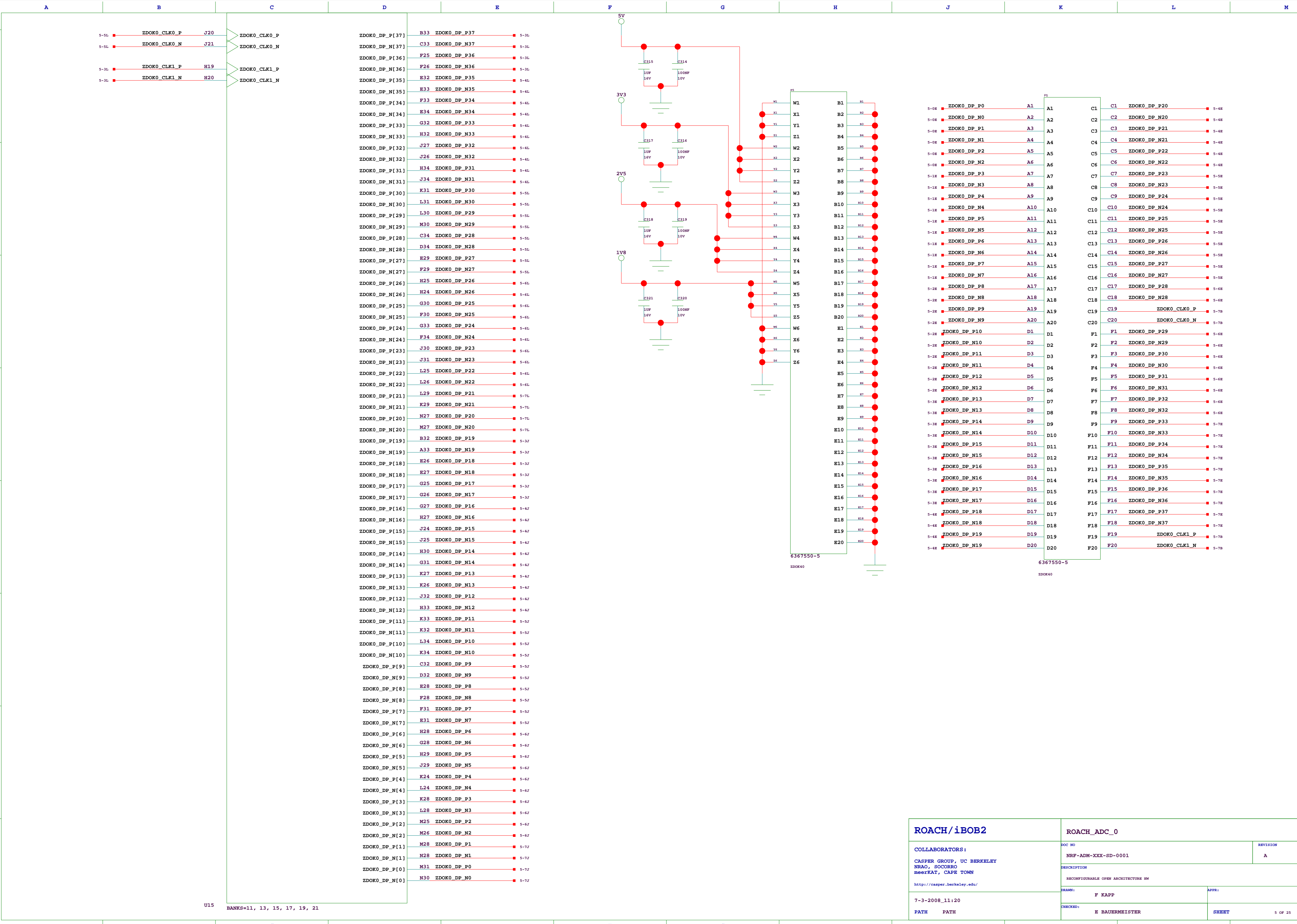
PSU INPUT SUMMARY	
VOLTAGE	12V +- 10%
CURRENT (MAX)	1.8A

PSU RAIL SUMMARY	
VOLTAGE	2.5V +- 5%
SUPPLIES	PPDA, BIRD, PSC_PHY
CURRENT (QUIESCENT)	9.1A
CURRENT (ACTIVE)	3.6A
LOAD STEP	3.5A

PSU INPUT SUMMARY	
VOLTAGE	12V +- 10%
CURRENT (MAX)	6.8A

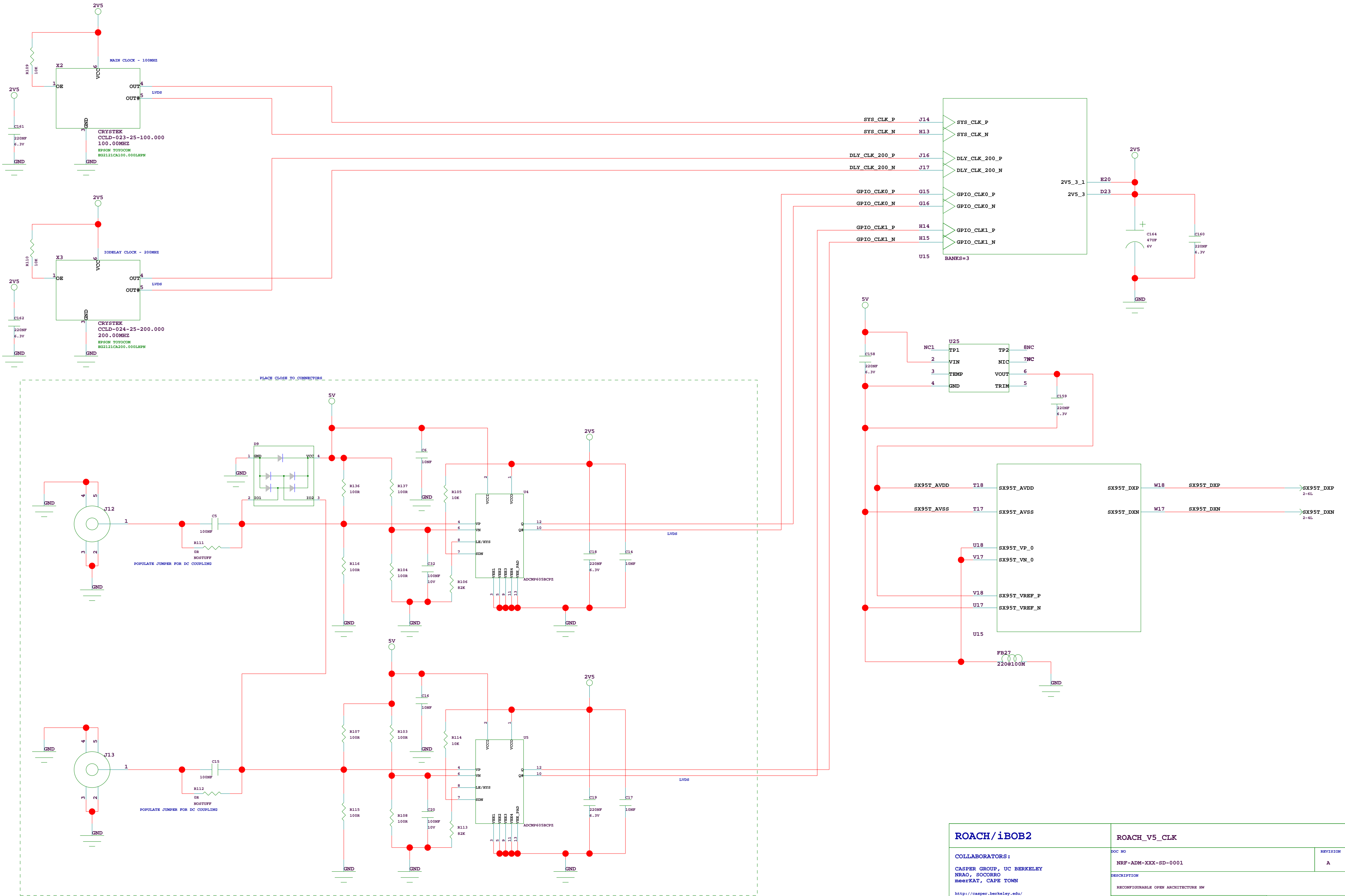
ROACH/iBOE2		ROACH_PSU	
COLLABORATORS:		DOC NO	REVISION
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-SD-0001	A
NRAO, SOONERO		DESCRIPTION	
BAAEFAT, CAPE TOWN		RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/		DRWN:	APPD:
7-3-2008.11.20		F KAPP	
PATH PATH		CHECKED:	SHEET
		R BAUERMBISTER	



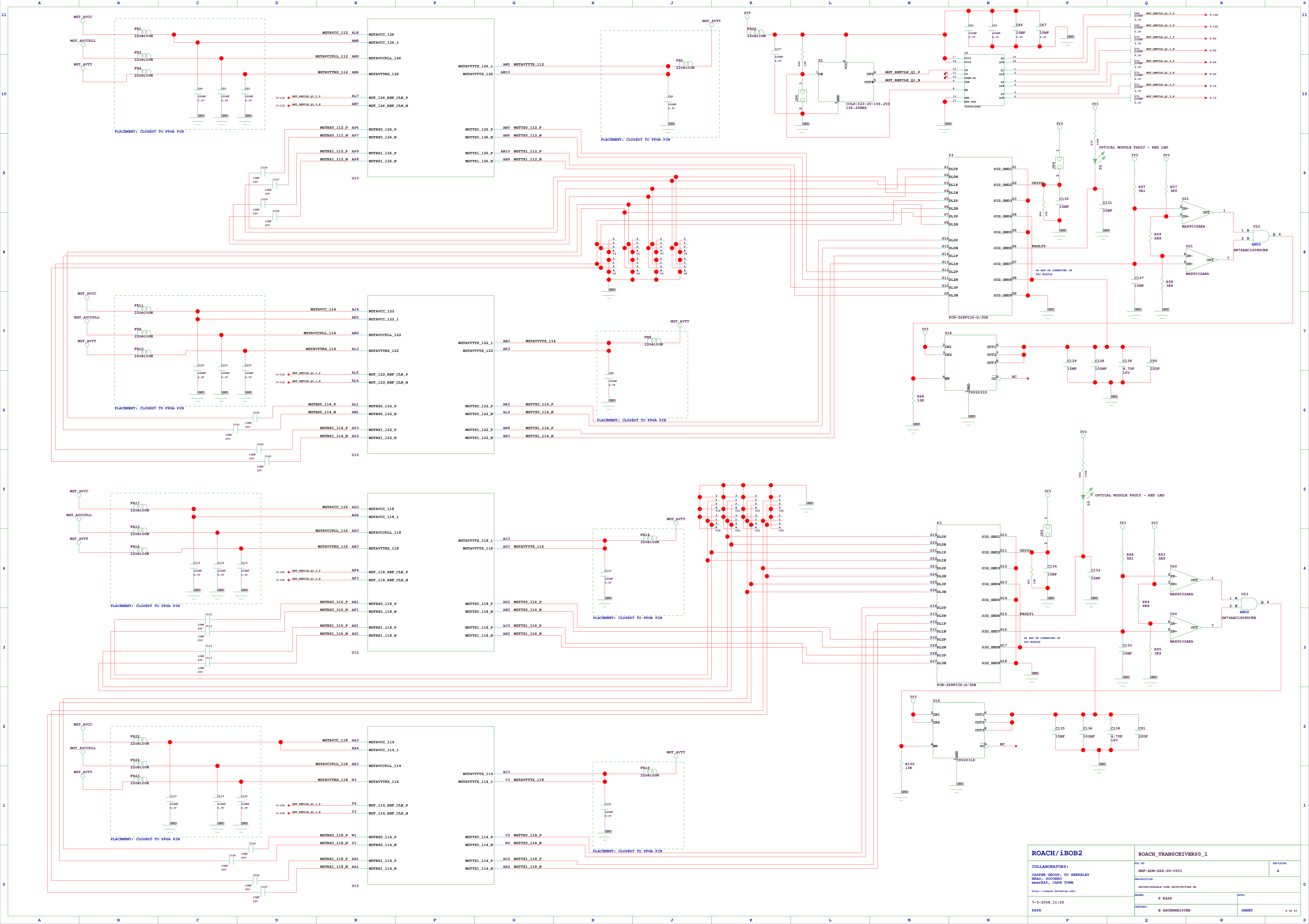




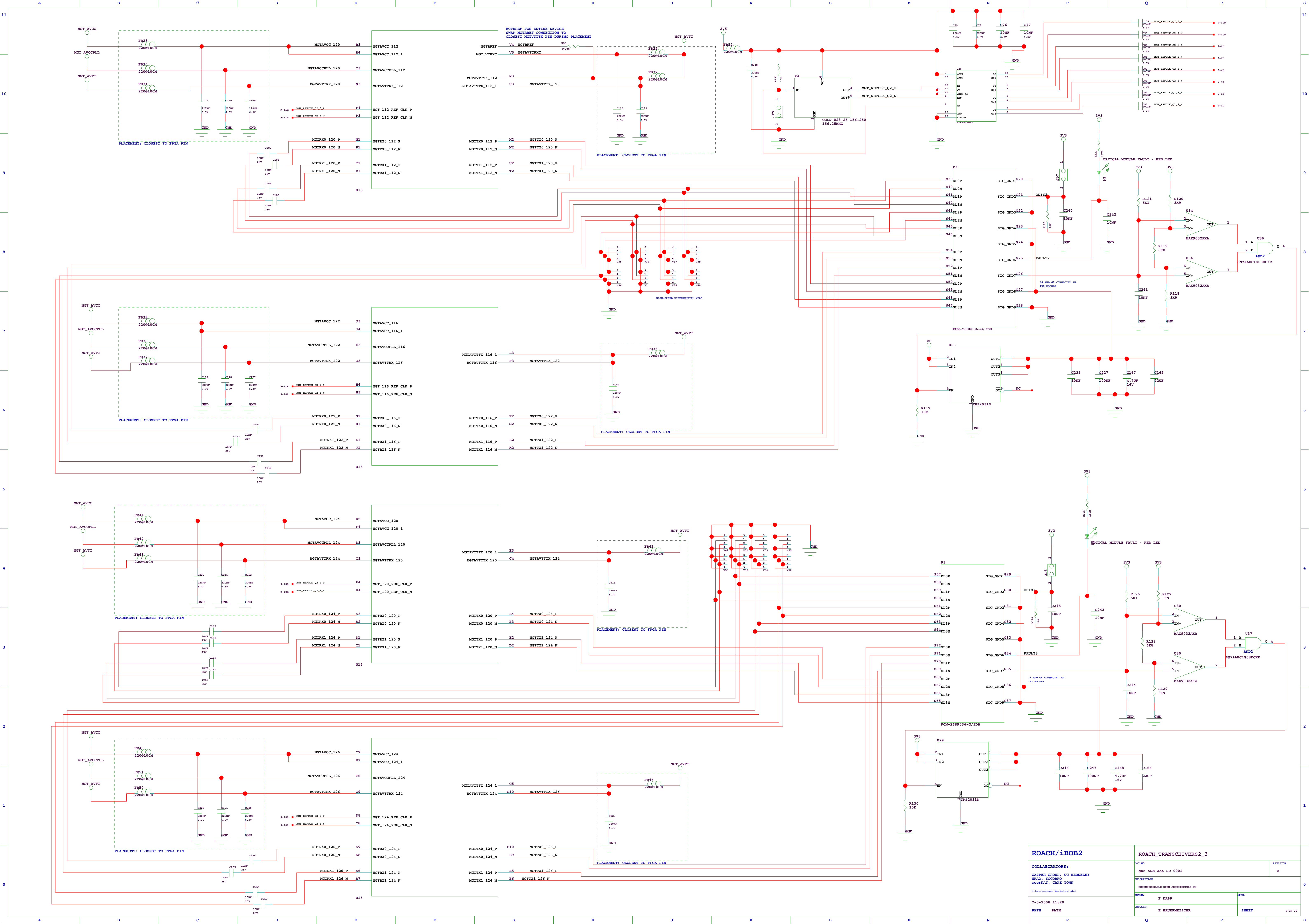




ROACH/iBOB2		ROACH_V5_CLK	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN  <a href="http://casper.berkeley.edu/">http://casper.berkeley.edu/</a>		DOC NO	REVISION
		NRF-ADM-XXX-SD-0001	A
		DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW	
7-3-2008_11:20		DRAWN: F KAPP	APPR:
PATH PATH		CHECKED: E BAUERMEISTER	SHEET 7 OF 25







ROACH/iBOE2

COLLABORATORS:

CASPER GROUP, UC BERKELEY

NRAO, SOONERO

RECONFIGURABLE OPEN ARCHITECTURE HW

7-3-2008\_11:20

PATH PATH

ROACH\_TRANSCEIVERS2\_3

DOC NO

NRF-ADM-XXX-SD-0001

DESCRIPTION

RECONFIGURABLE OPEN ARCHITECTURE HW

7-3-2008\_11:20

PATH PATH

REV

A

DESCRIPTION

RECONFIGURABLE OPEN ARCHITECTURE HW

7-3-2008\_11:20

PATH PATH

REV

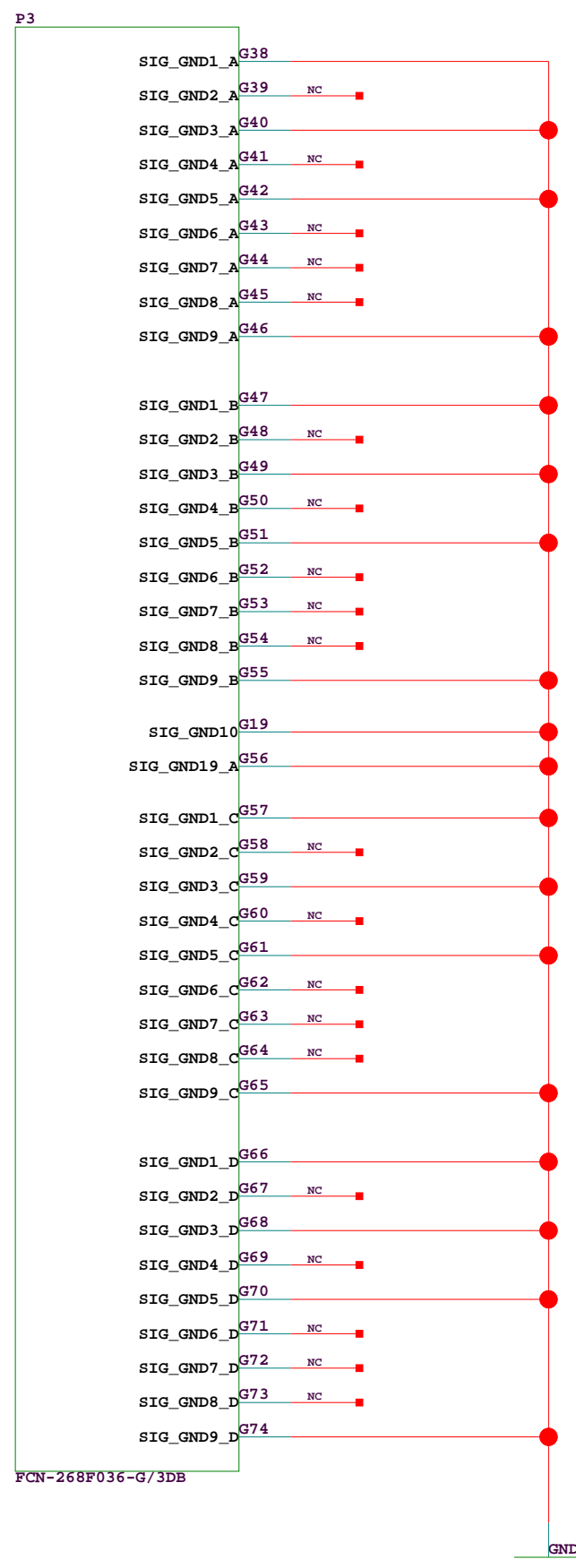
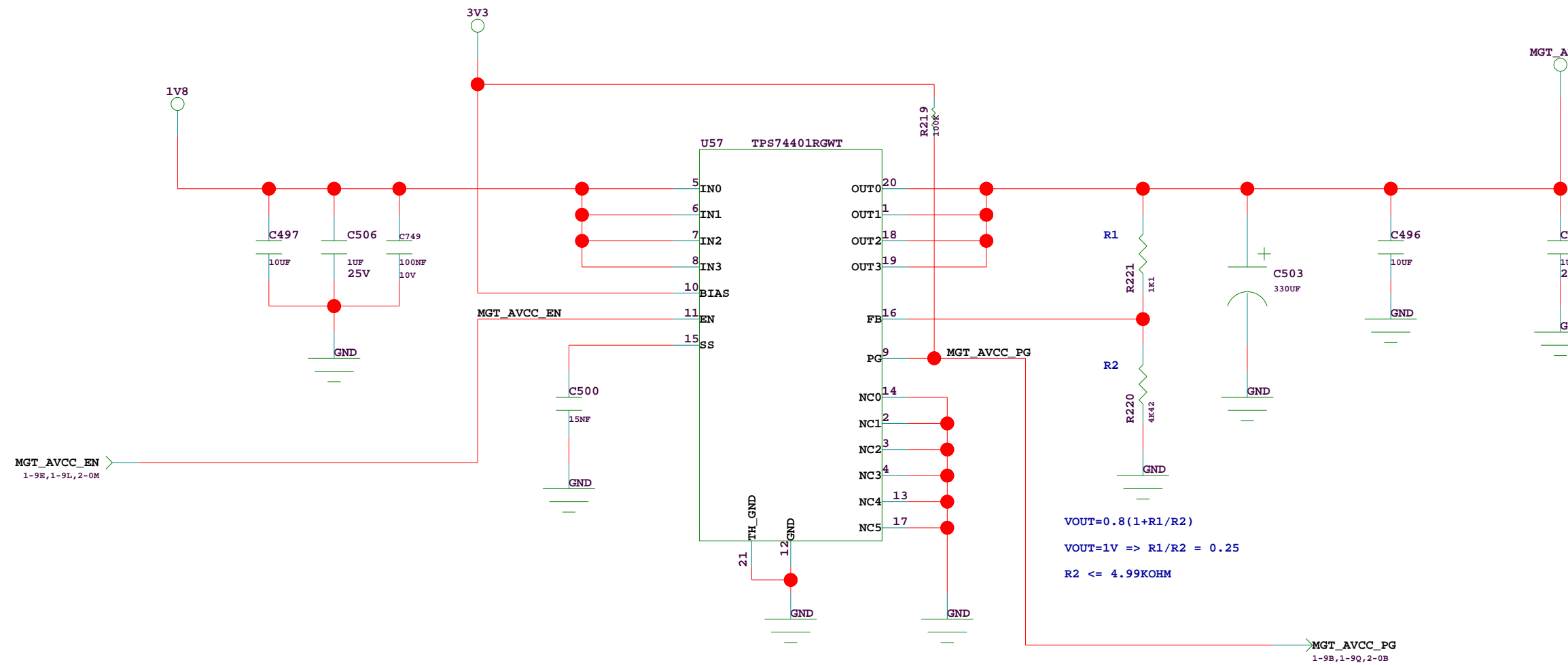
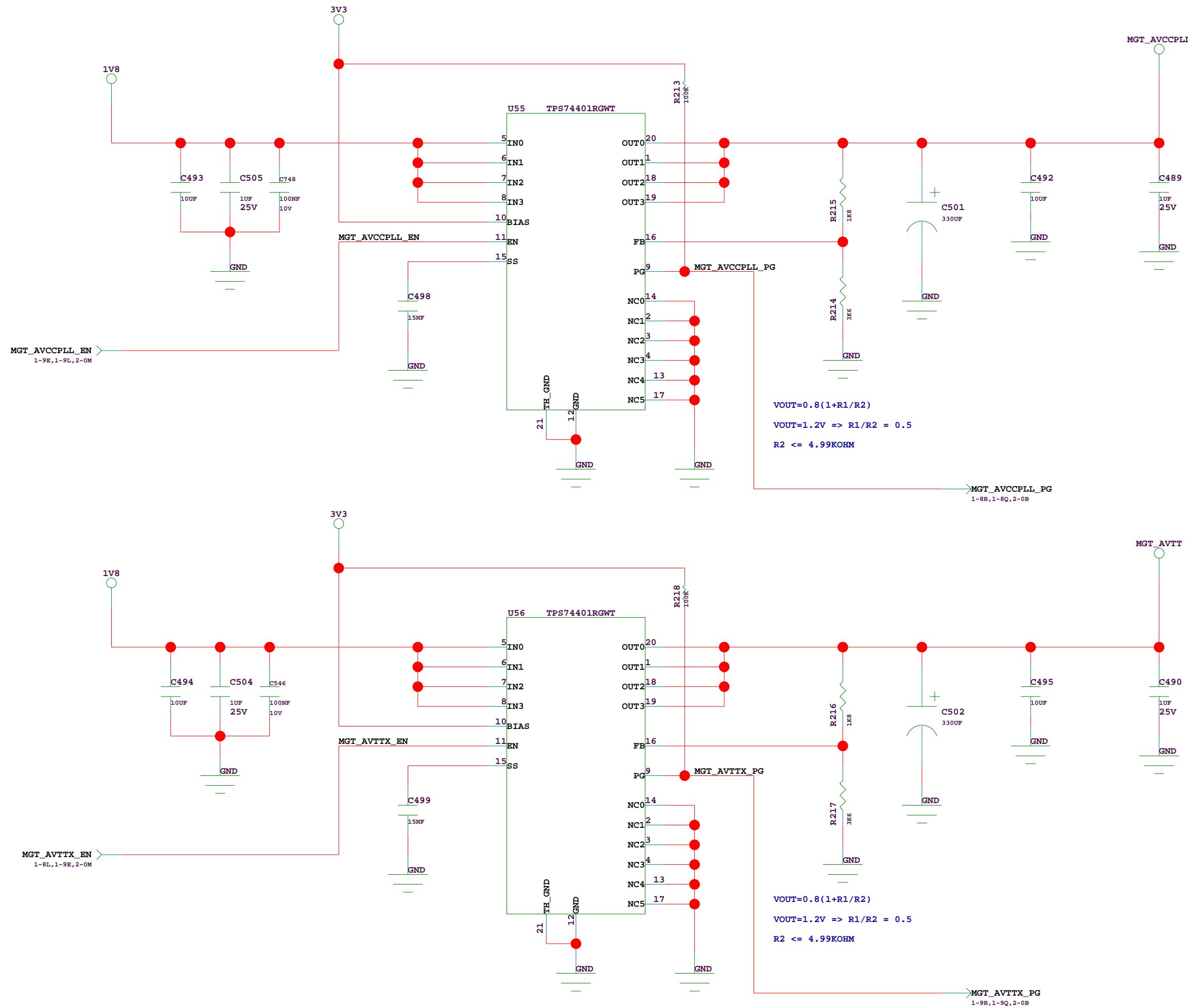
A

DESCRIPTION

RECONFIGURABLE OPEN ARCHITECTURE HW

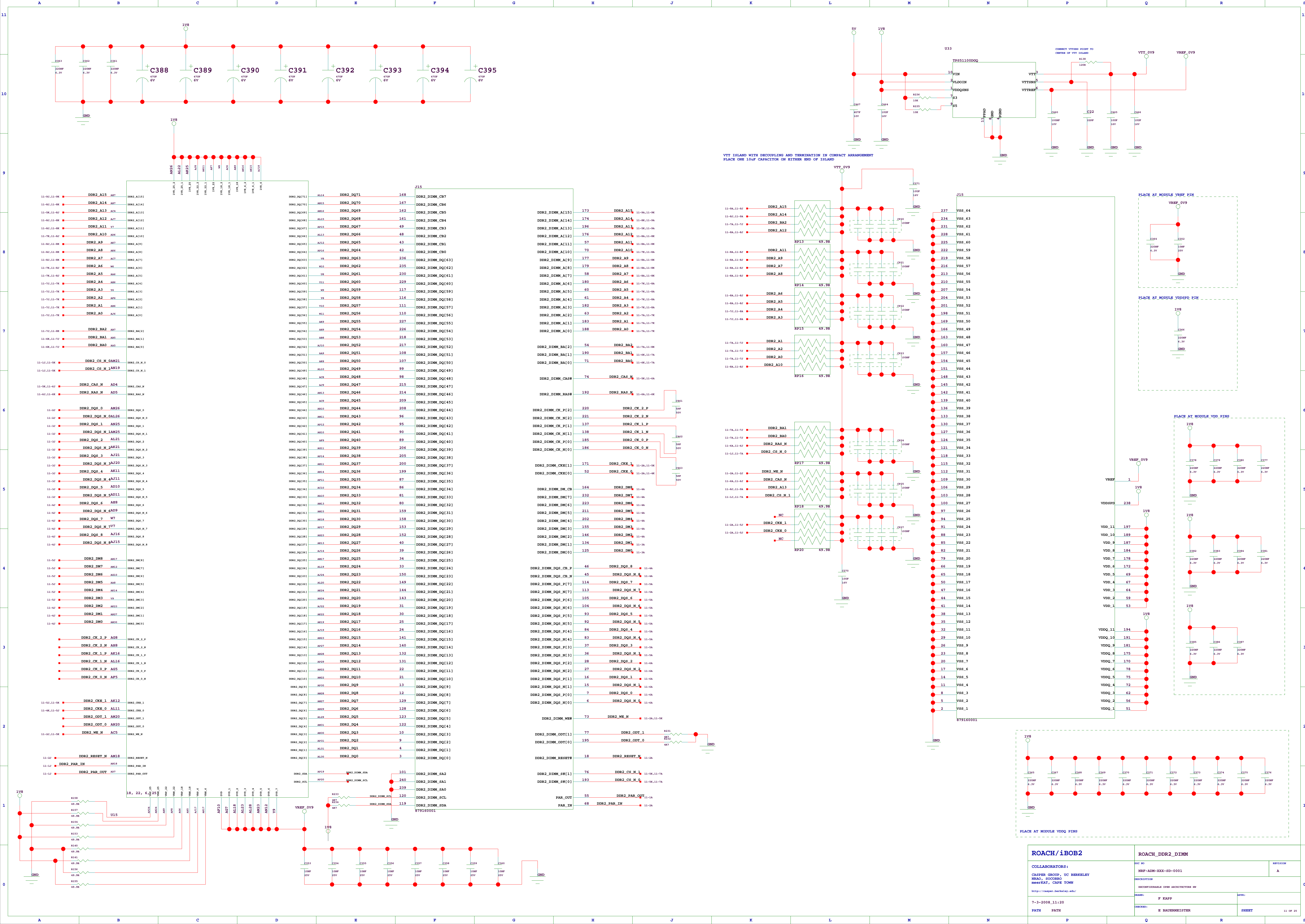
7-3-2008\_11:20

PATH PATH

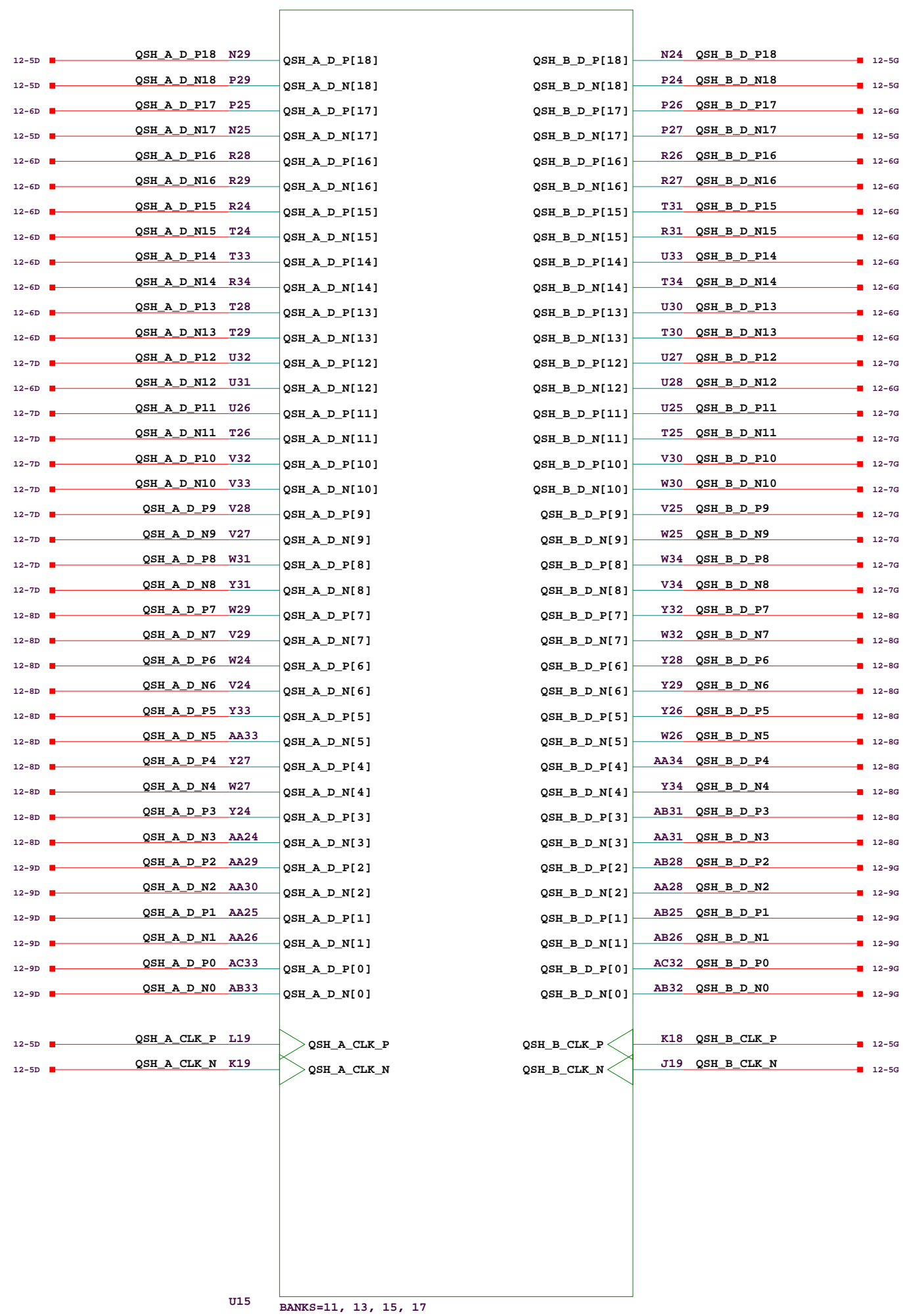
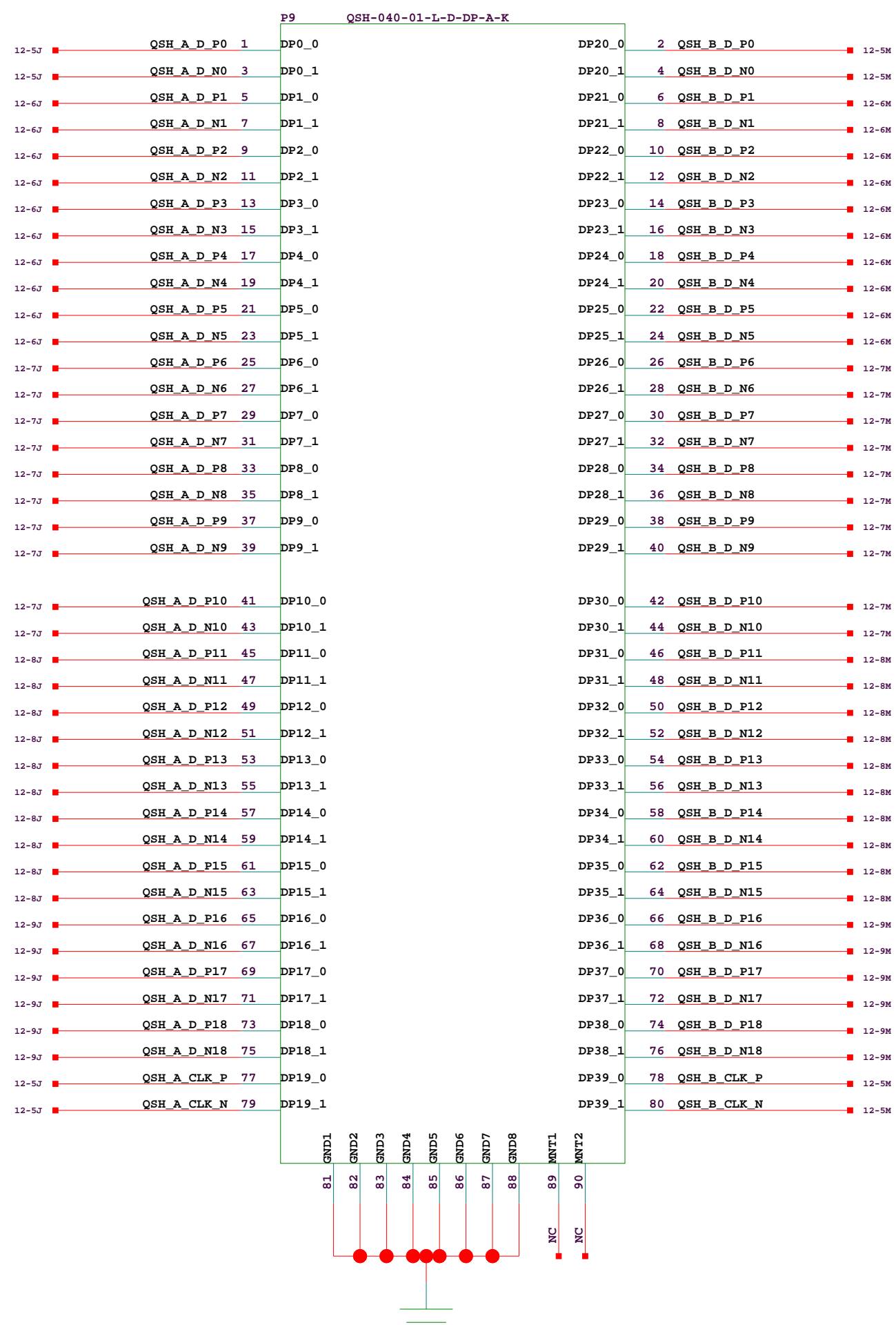


ROACH/iBOE2		ROACH_TRANSCEIVERS_PSU	
COLLABORATORS:		DOC NO	REVISION
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-SD-0001	A
NRAO, SCORCRO		DESCRIPTION	
MEEFAT, CAPE TOWN		RECONFIGURABLE OPEN ARCHITECTURE HW	
<a href="http://casper.berkeley.edu/">http://casper.berkeley.edu/</a>		DRAWN:	APPD:
7-3-2008_11:20		F KAPP	
PATH PATH		CHECKED: E BAUERMEISTER	SHEET
			10 OF 25

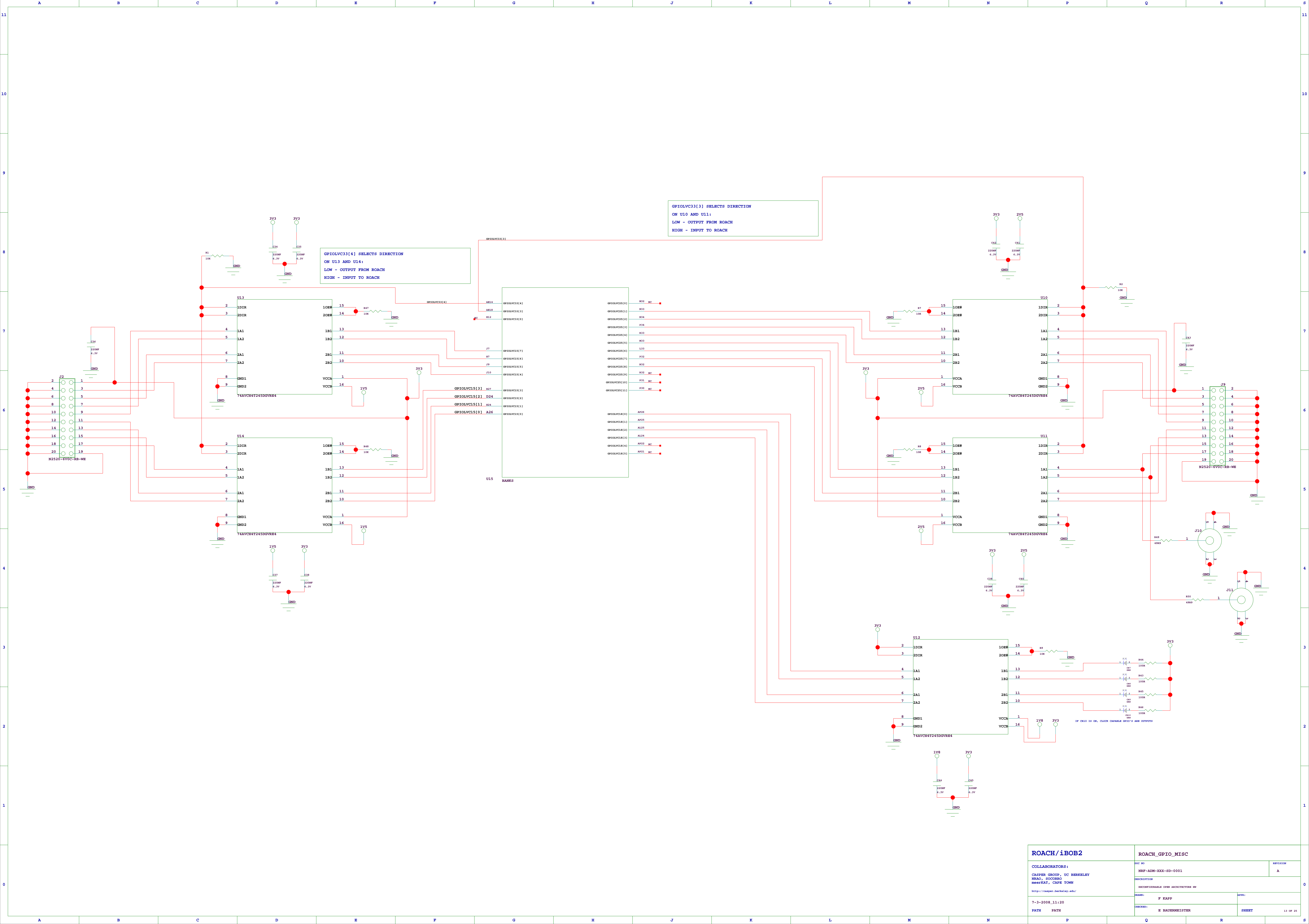




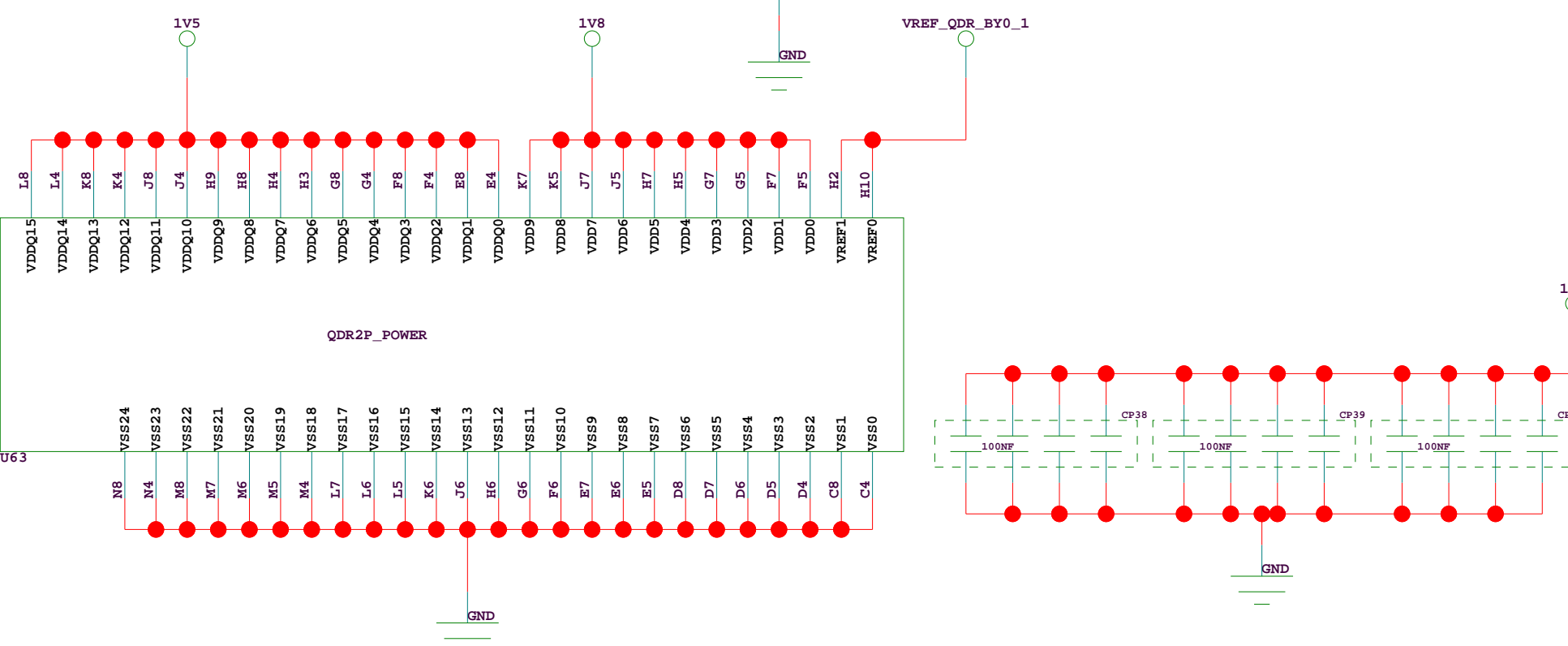
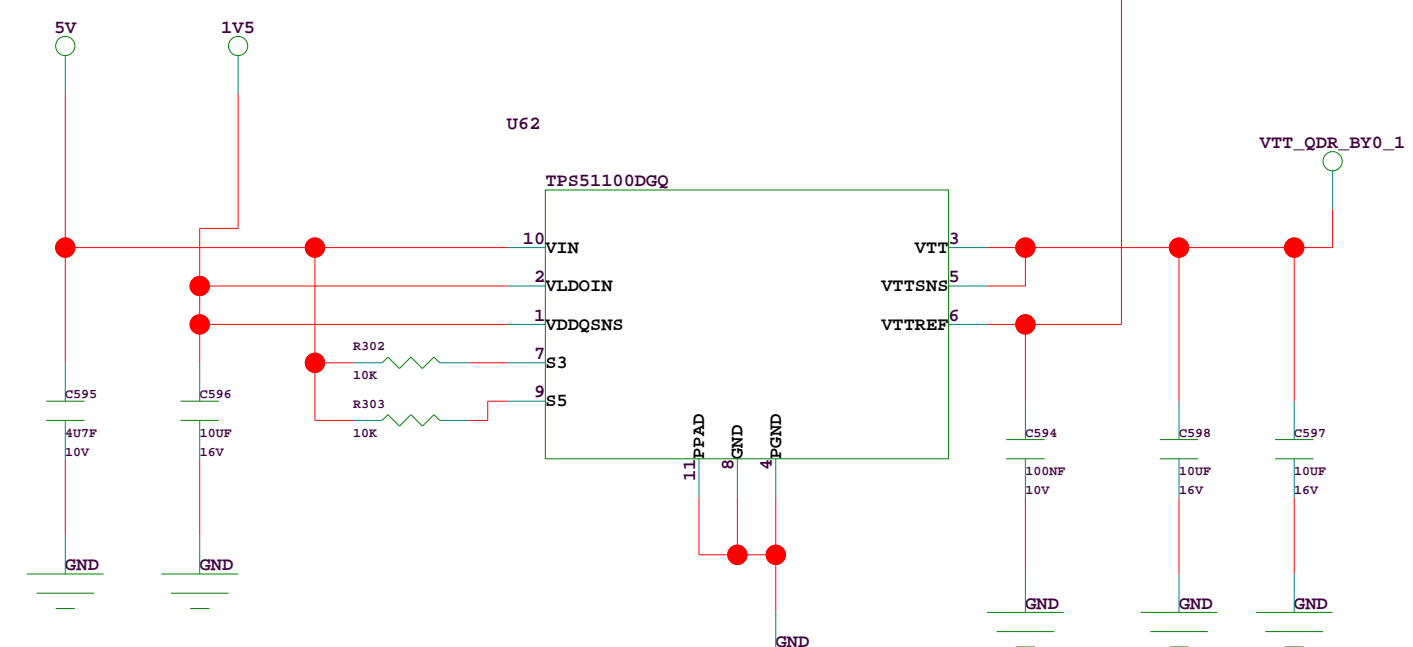
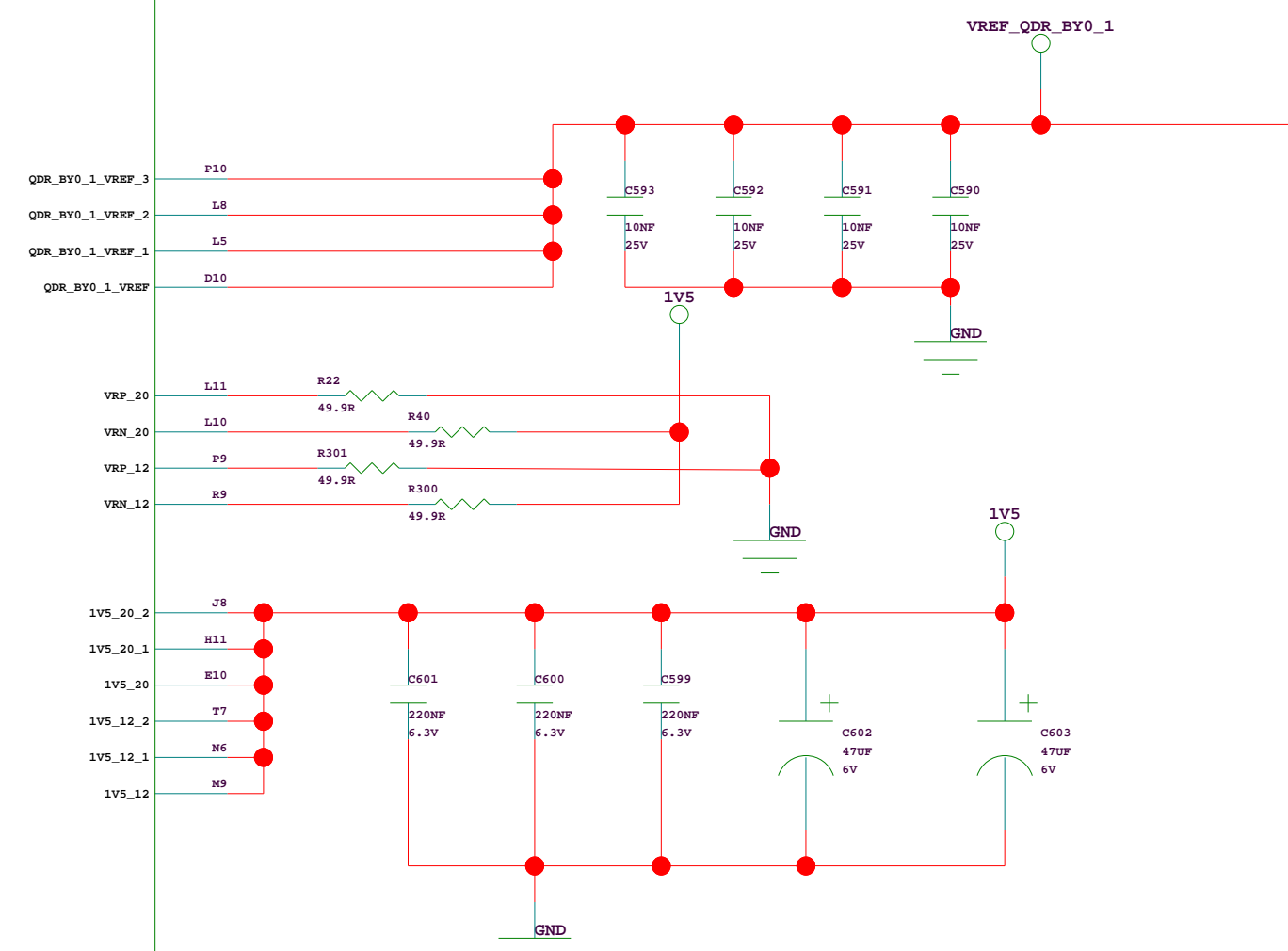
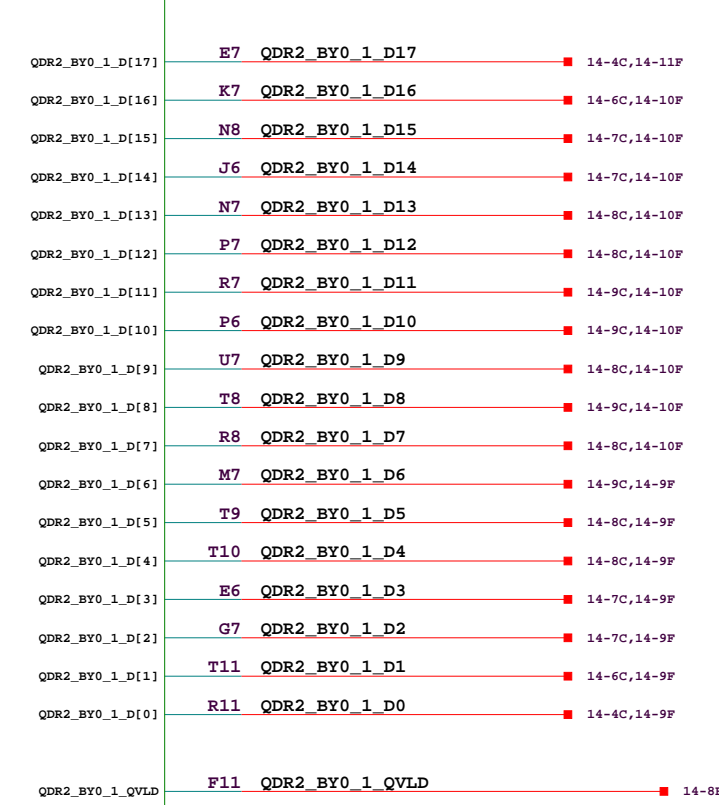
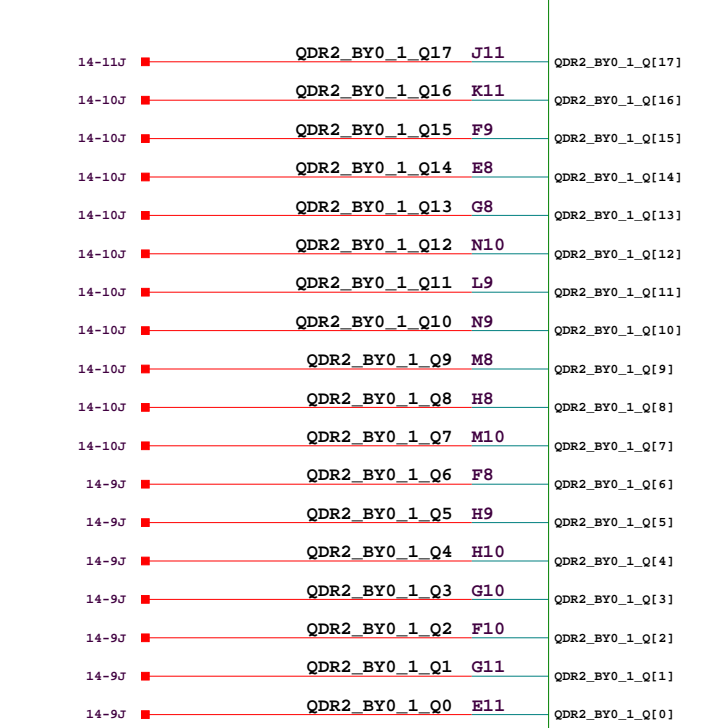
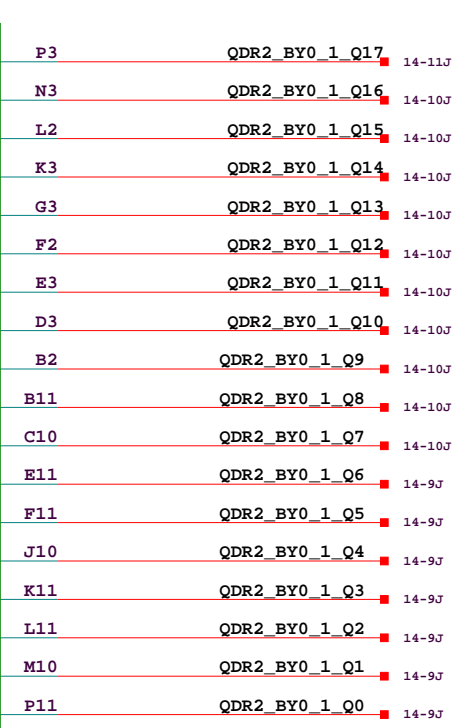
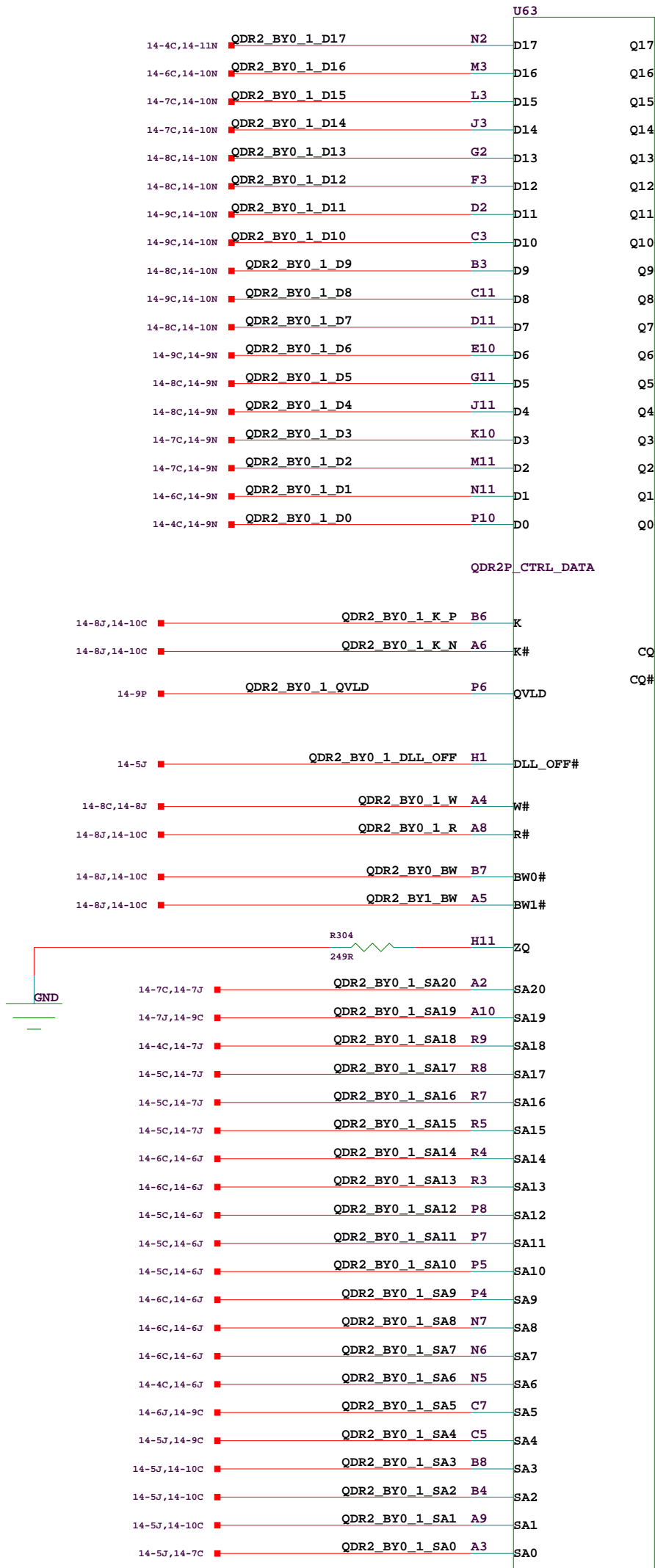
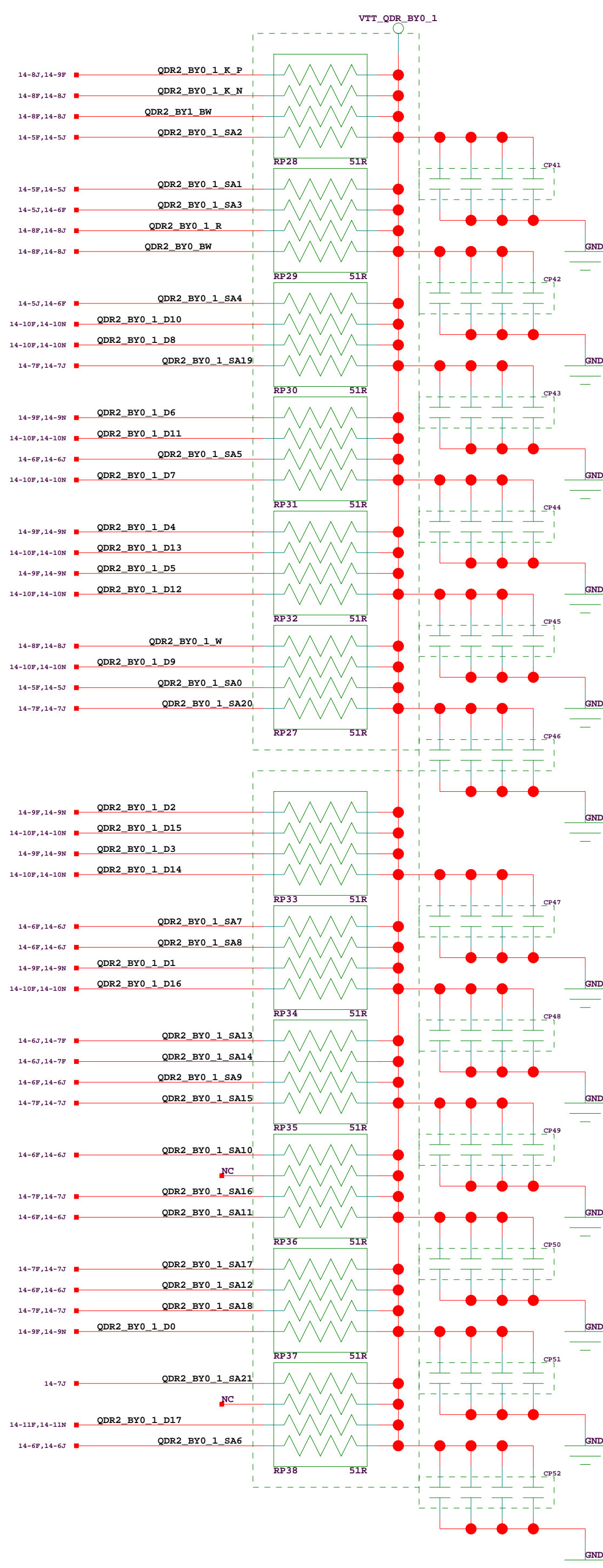




ROACH/iBOE2		ROACH_DIFF_GPIO		REVISION	
COLLABORATORS:		DOC NO		A	
CASPER GROUP, UC BERKELEY		NEP-ADM-XXX-ED-0001			
MAD, SCSOORD		DESCRIPTION			
MEERKAT, CAPE TOWN		RECONFIGURABLE OVER ARCHITECTURE RM			
<a href="http://casper.berkeley.edu/">http://casper.berkeley.edu/</a>		NAME:		APP:	
7-3-2008 11:20		F KAPP			
PATH PATH		CHECKED:		SHEET	
		E BAUERMEISTER		12 OF 2	

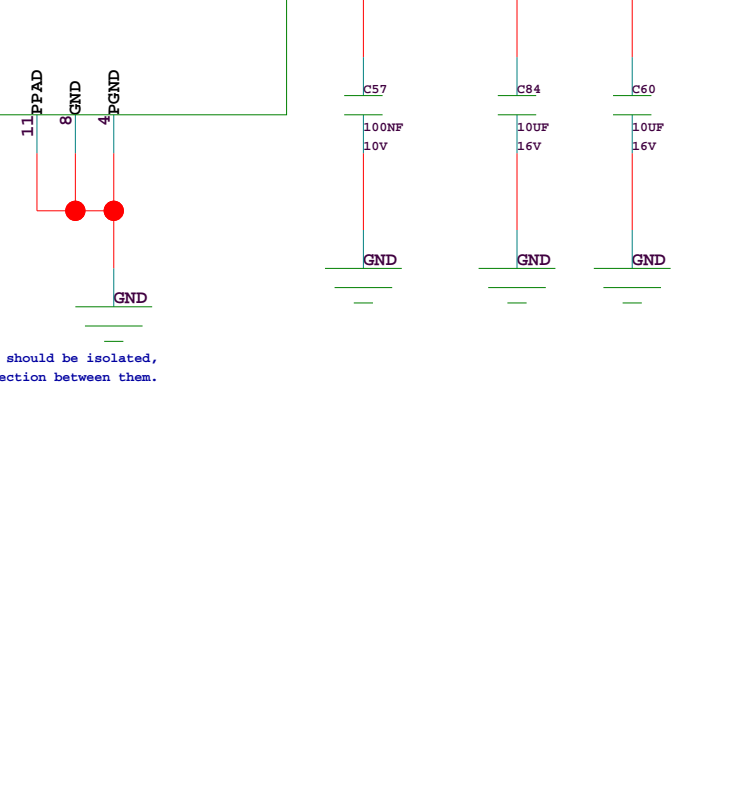
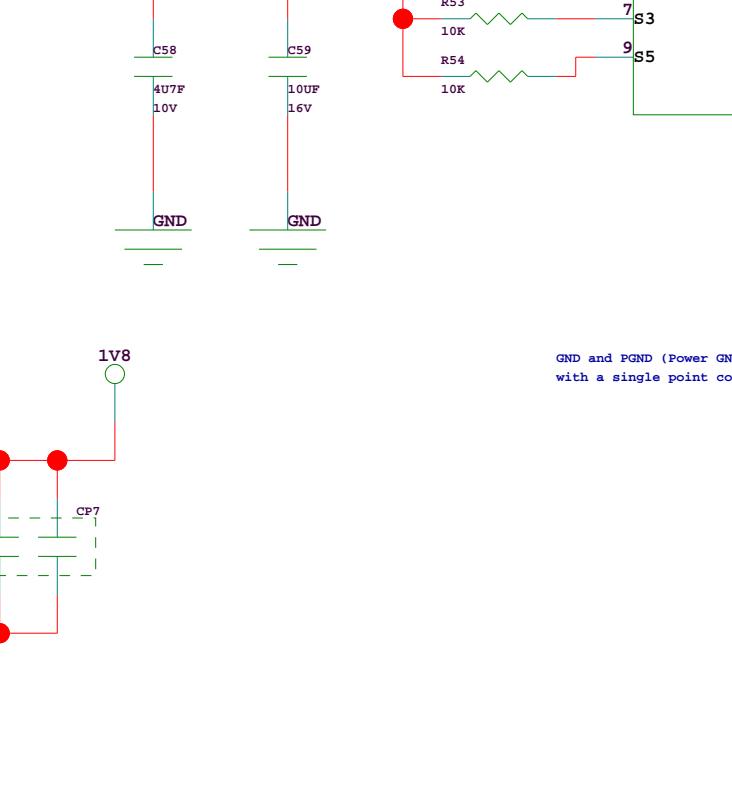
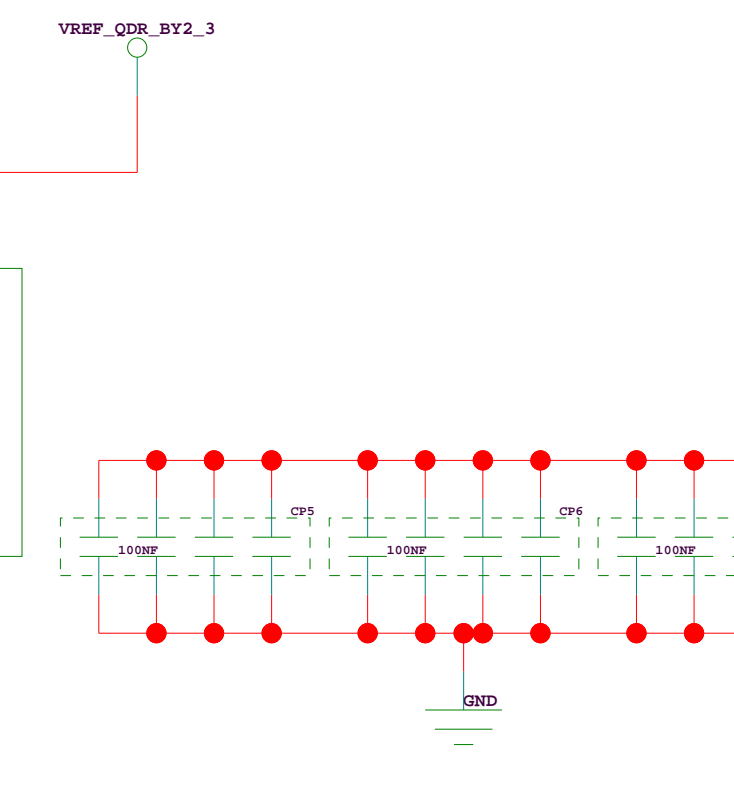
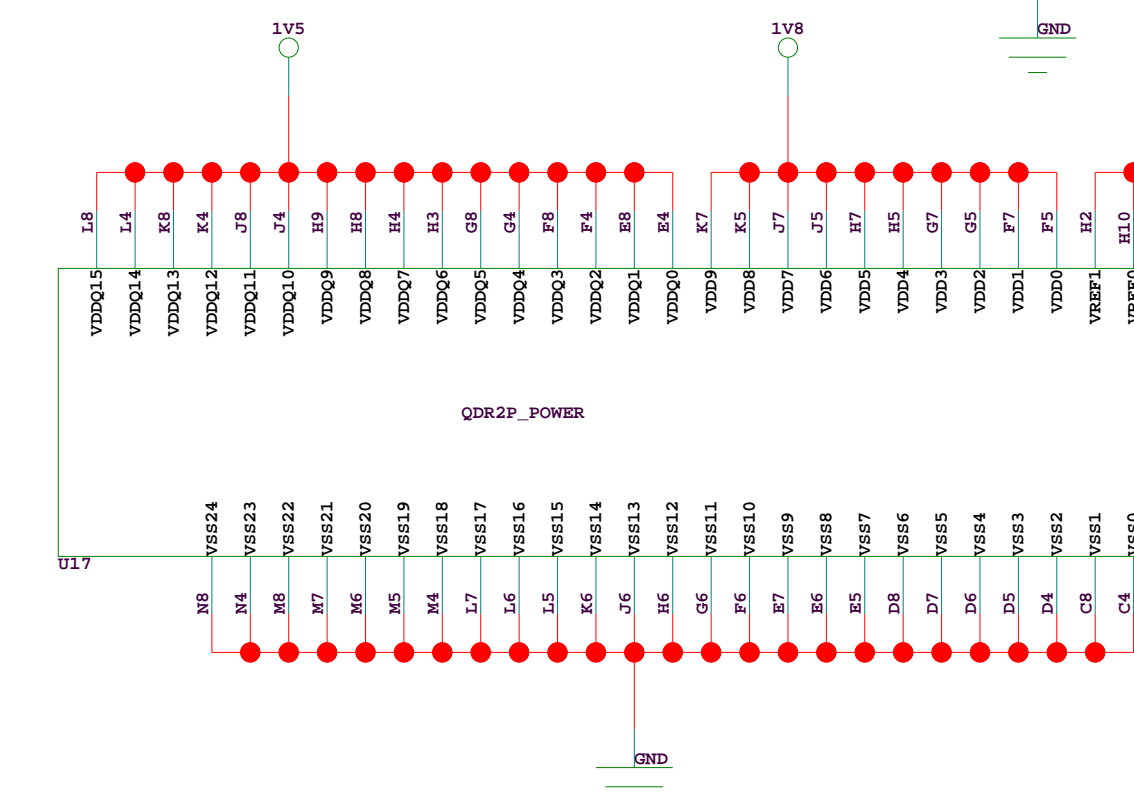
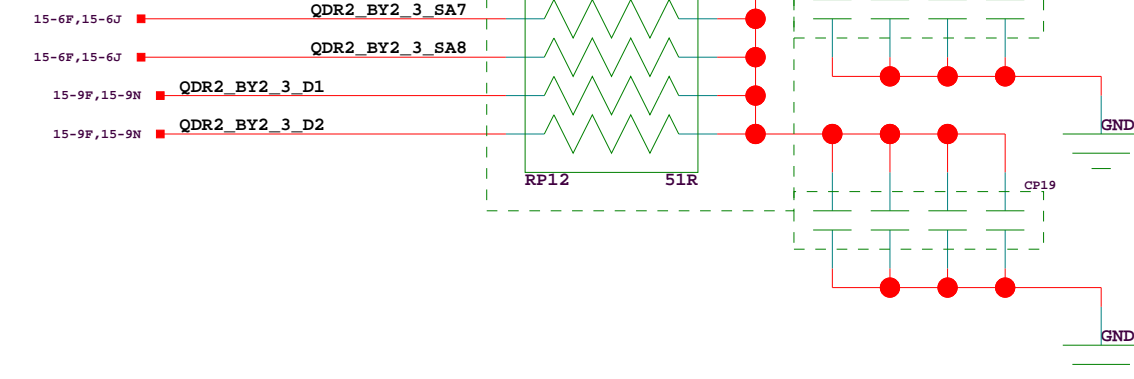
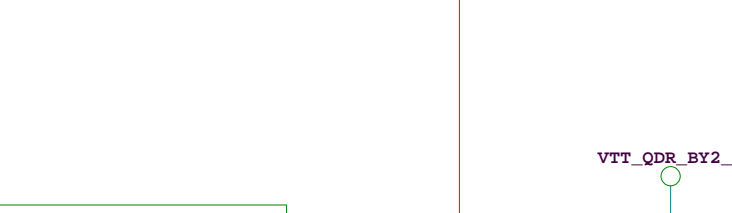
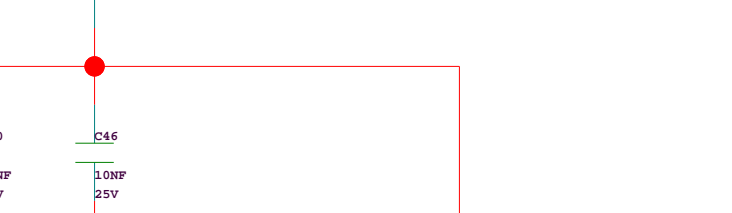
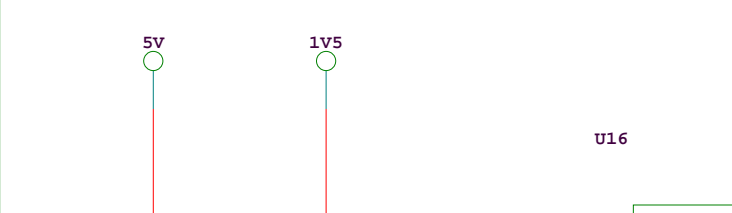
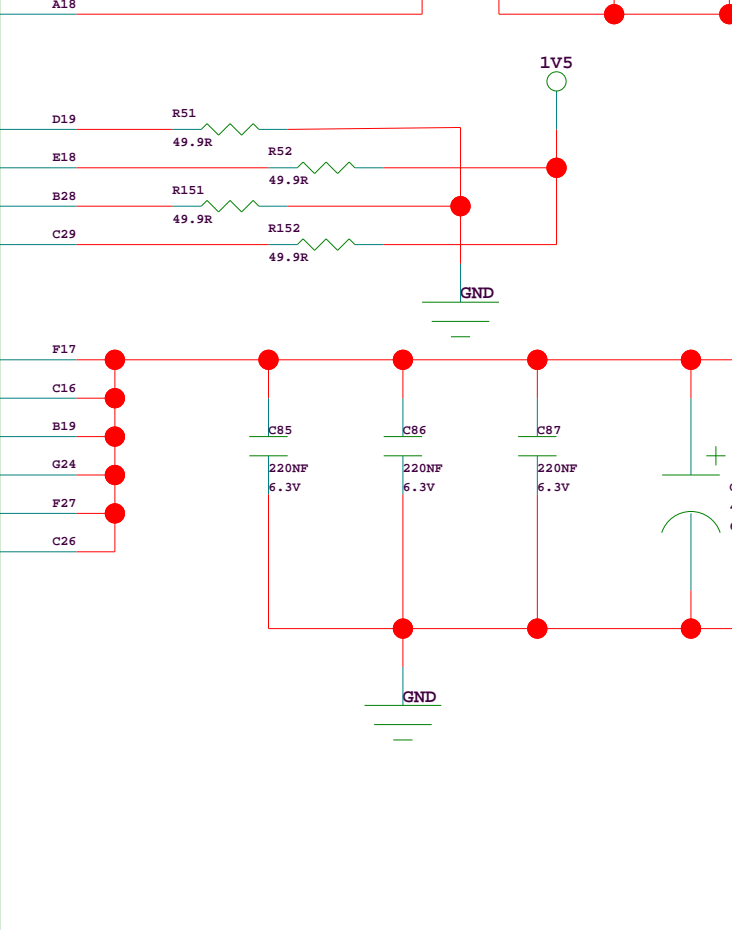
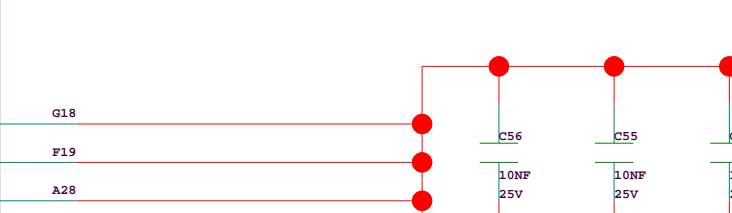
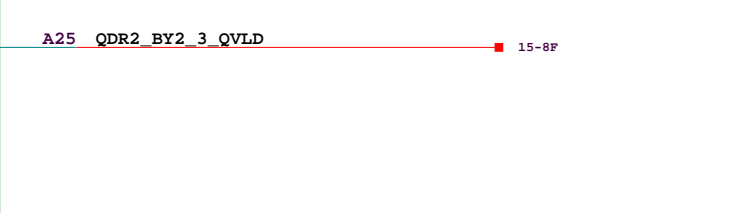
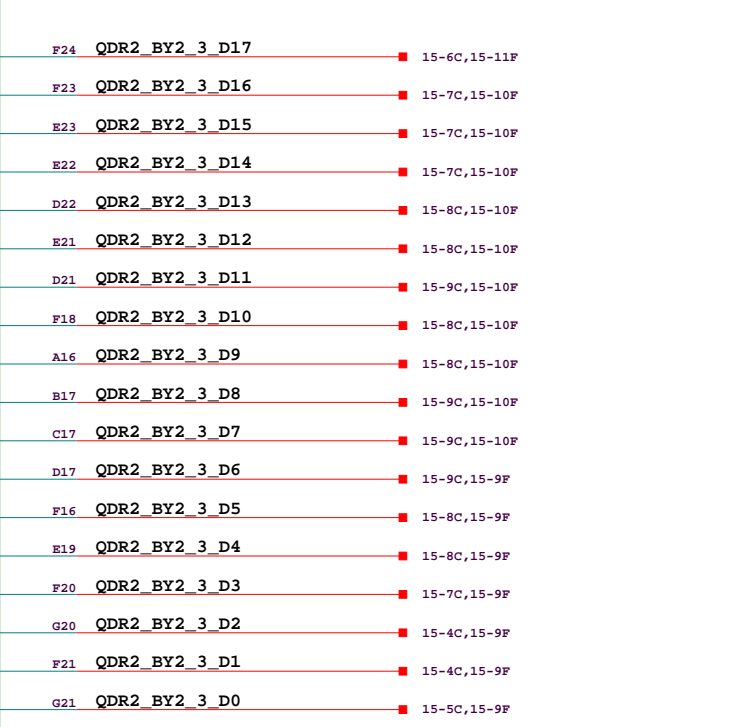
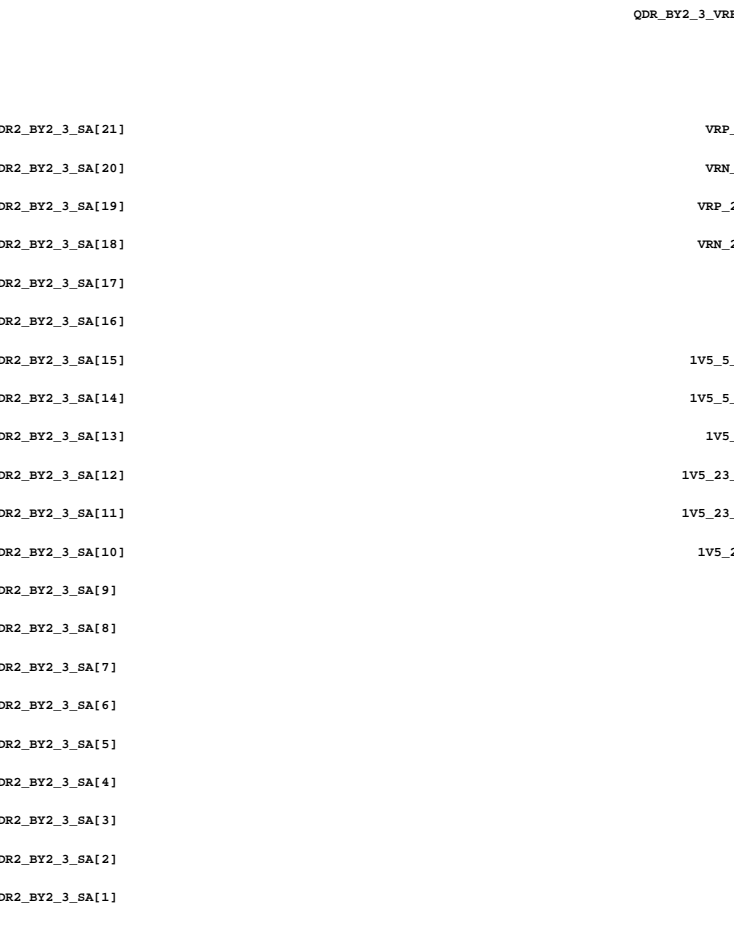
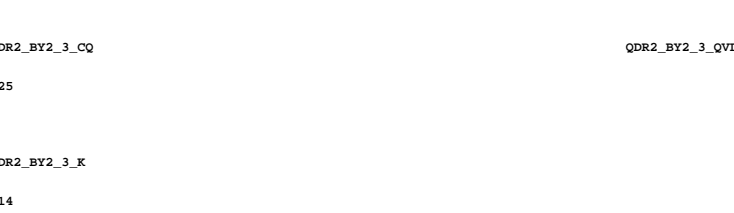
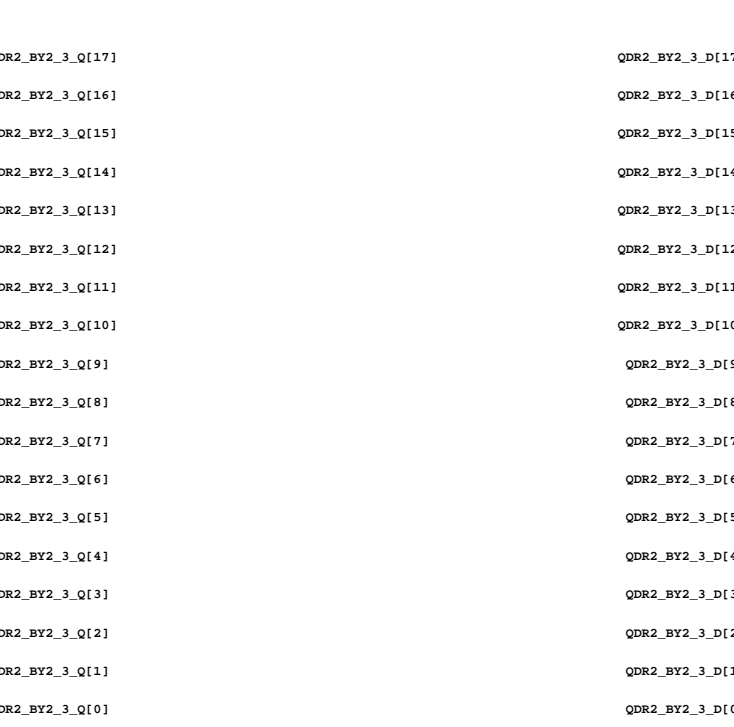
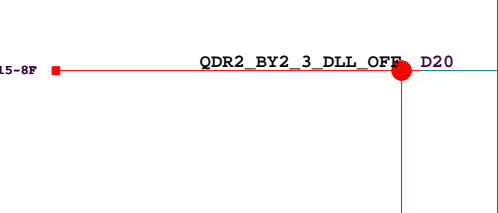
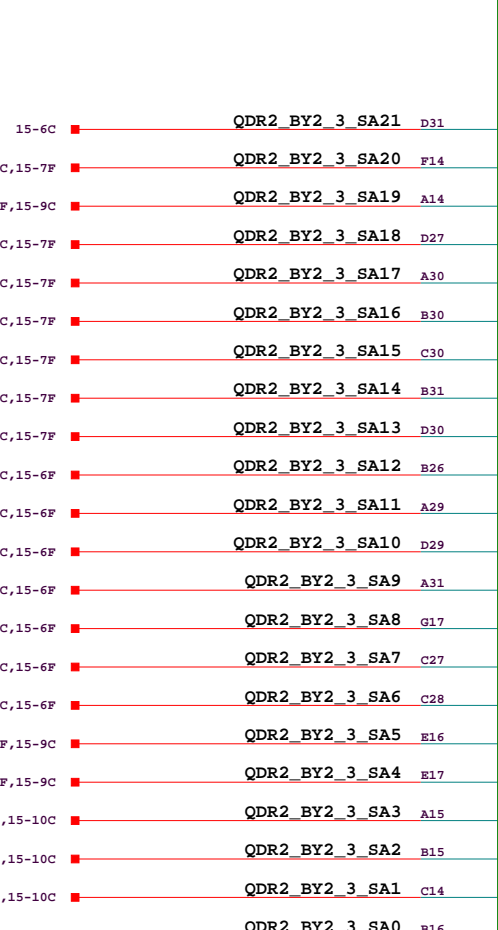
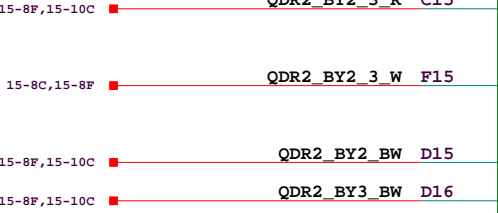
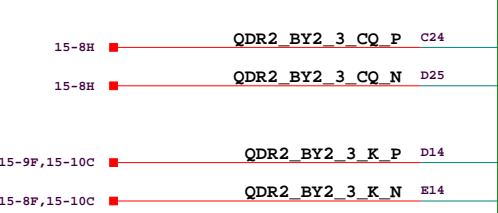
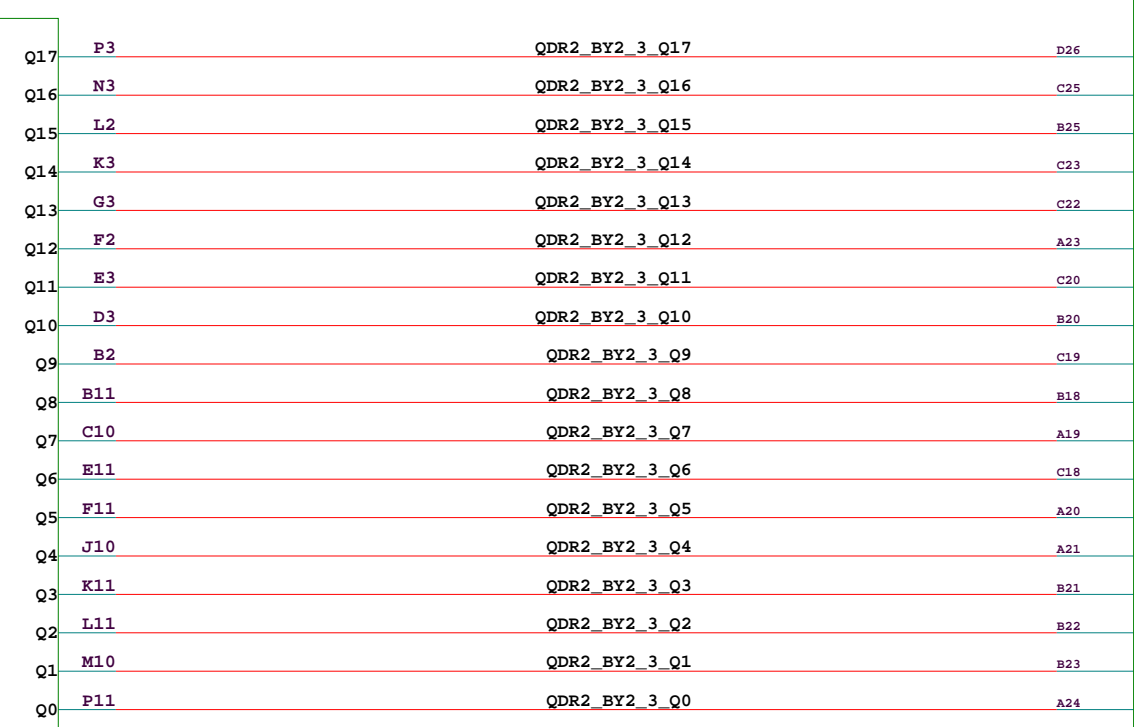
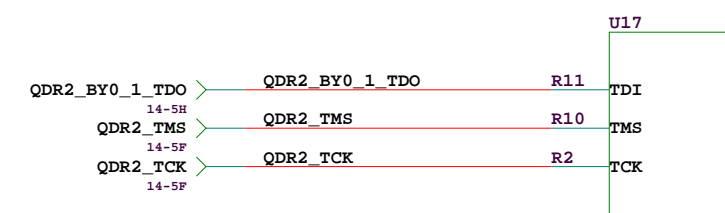
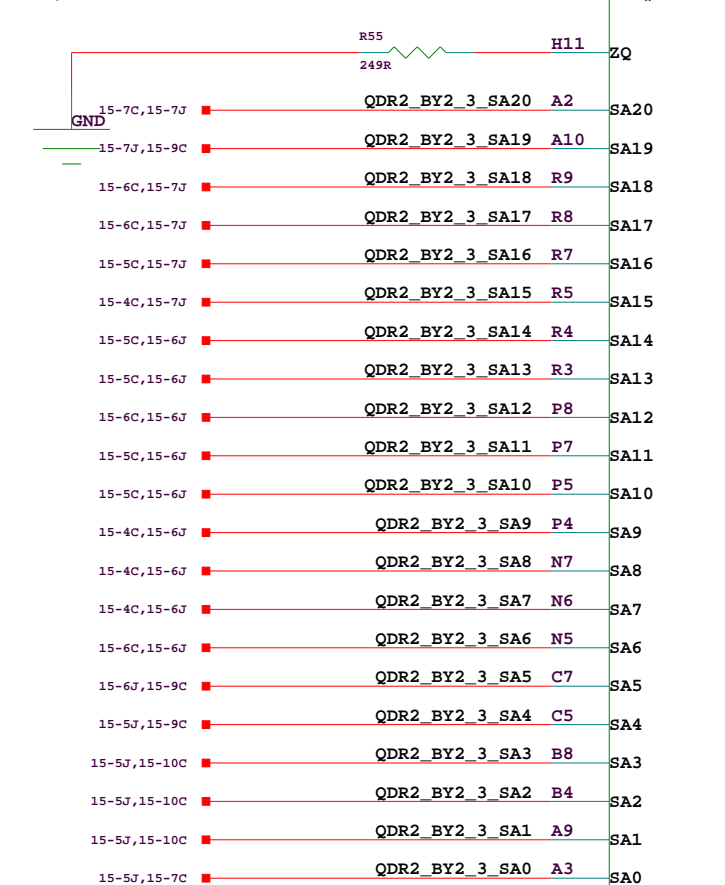
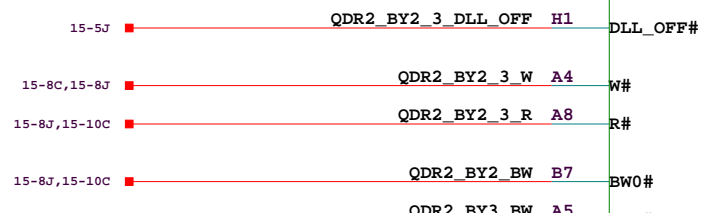
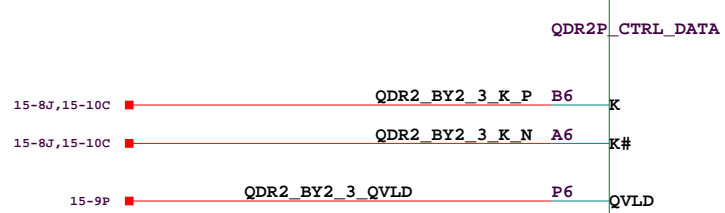
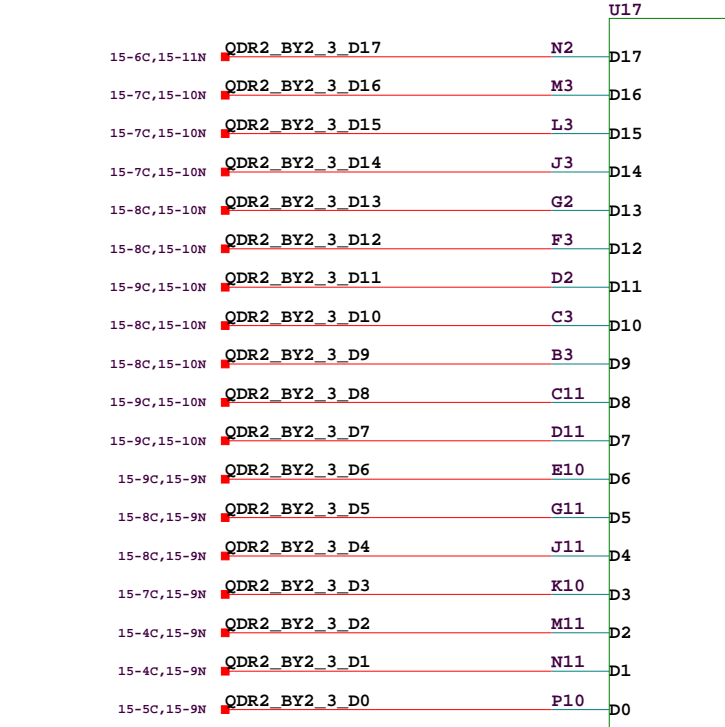
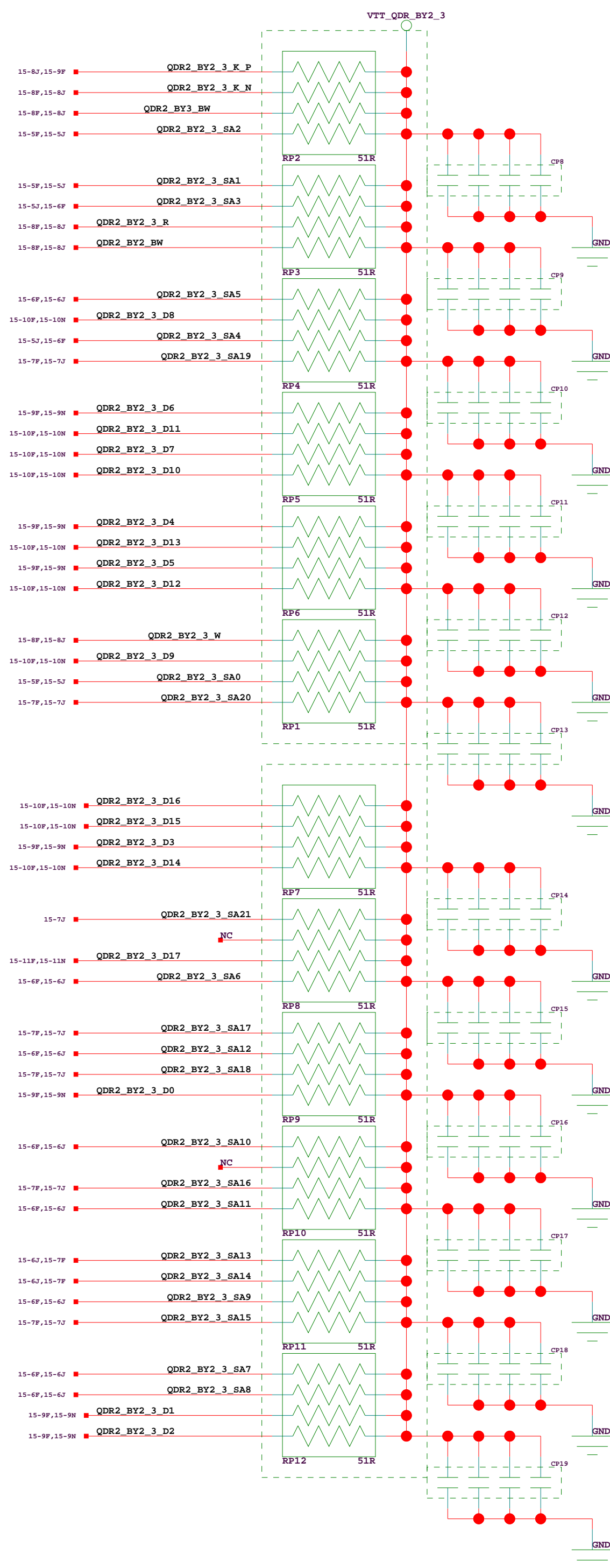


ROACH/iBOE2		ROACH_GPIO_MISC	
COLLABORATORS:		DWG NO	REVISION
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-BD-0001	A
DESCRIPTION			
NRAO, SOCCORRO			
MAMERAT, CAPE TOWN			
RECONFIGURABLE OPEN ARCHITECTURE HW			
http://casper.berkeley.edu/		DRAWN:	APPD:
7-3-2008_11:20		F KAPP	
PATH	PATH	R BAUERMISTROT	
		CHECKED:	SHEET



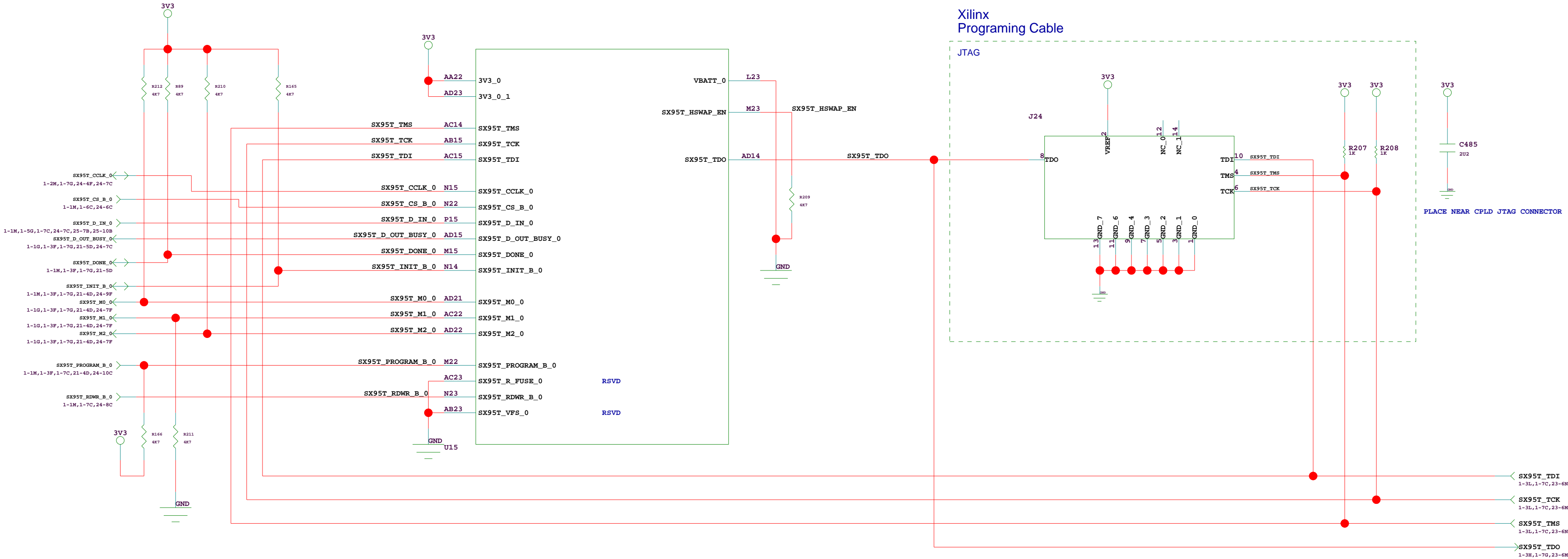
<b>ROACH/iBOB2</b>		<b>ROACH_QDR2P_BY0_1</b>	
COLLABORATORS: CASPER GROUP, UC BERKELEY WRAJ, ECOHARD meerCAT, CAPE TOWN		DOC NO: NRP-ADM-XXX-SD-0001	REVISION A
<a href="http://casper.berkeley.edu/">http://casper.berkeley.edu/</a>		DESCRIPTION: SECOND/FORMAL USER ARCHITECTURE IM	
7-3-2008 11:20		NAME: F KAPP	APPR:
PATH	PATH	WORKED BY: E BAUERMEISTER	SHEET 14 OF 2



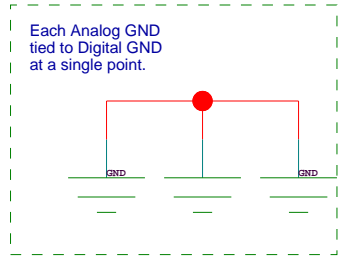
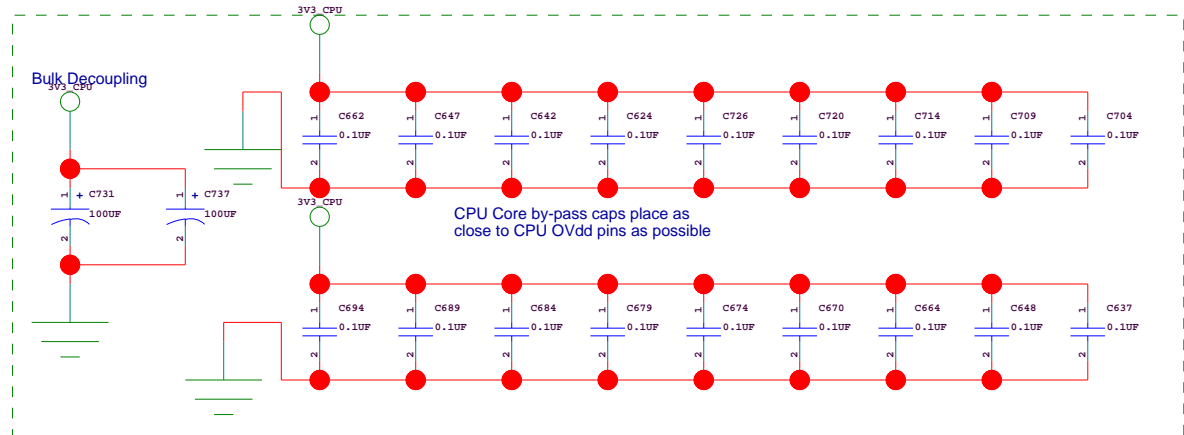
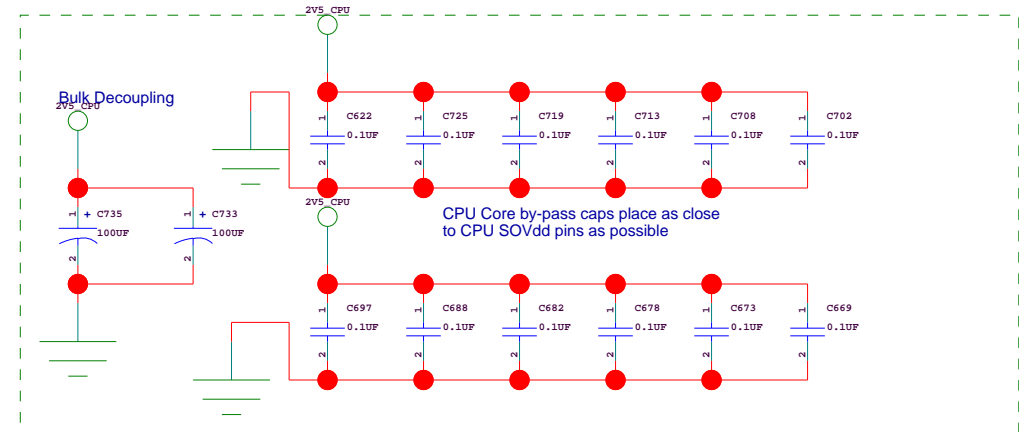
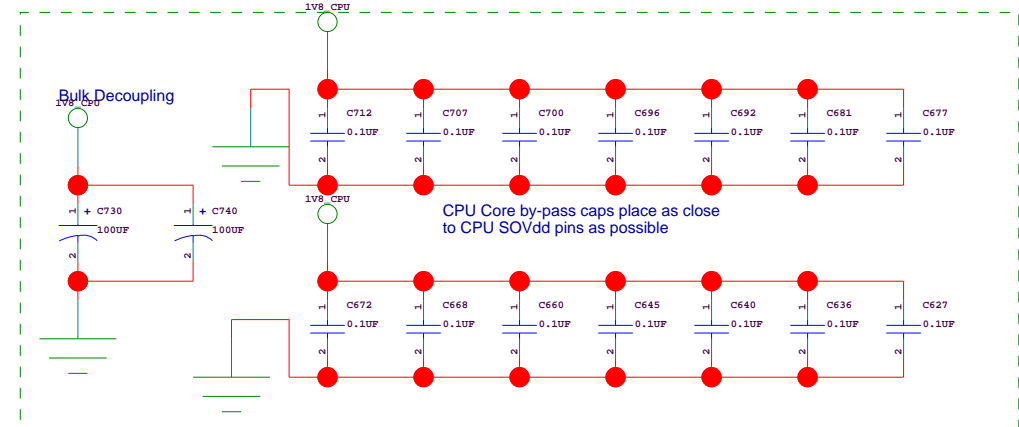
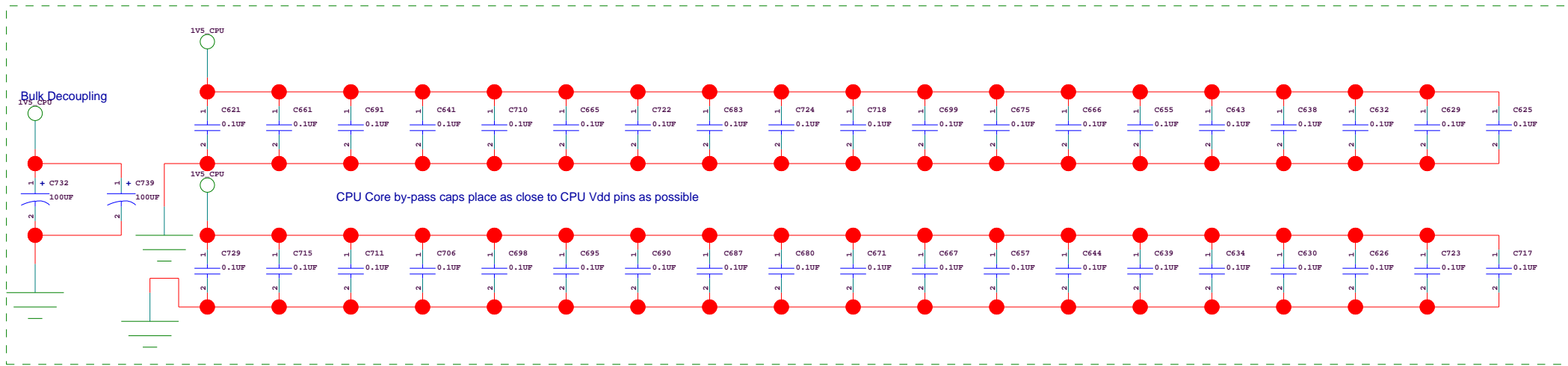
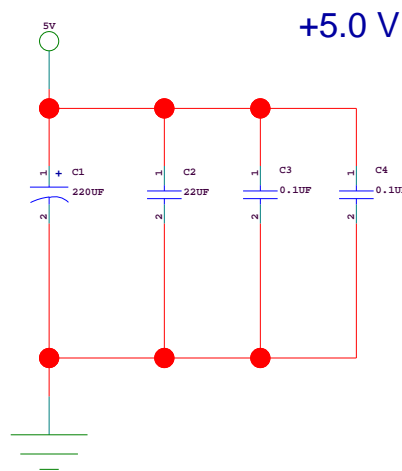
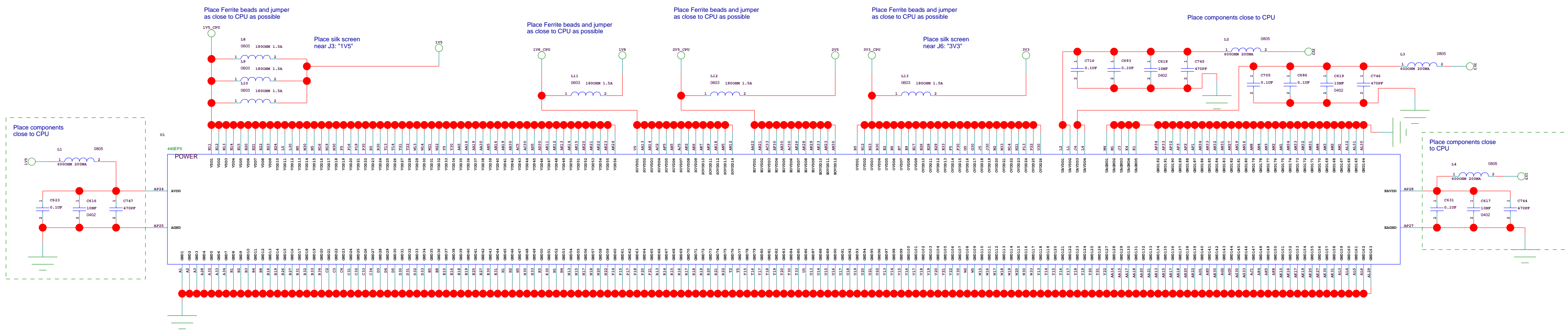


ROACH/iBOB2		ROACH_QDR2P_BY2_3	
COLLABORATORS:		SOC NO	REVISION
CASPER GROUP, UC BERKELEY HEAD, COORDINATOR MEERKAT, CAPE TOWN		NRF-ADM-XXX-SD-0001	A
http://casper.berkeley.edu/		DESCRIPTION	
		RECONSTRUCTIBLE OVER ARCHITECTURE SW	
7-3-2008_11:20		NAME:	APP:
PATH PATH		F KAPP	
CHECKED:		E BAUERMEISTER	SHEET
			15 OF 21

VALID CONFIGURATION MODES			
Configuration Mode	M[2:0]	Bus Width	CLK Direction
Master Serial	000	1	Output
Master SPI	001	1	Output
Master BPI-Up	010	8, 16	Output
Master BPI-Down	011	8, 16	Output
Master SelectMAP	100	8, 16	Output
Master JTAG	101	1	Input (TCK)
Slave SelectMAP	110	8, 16, 32	Input
Slave Serial	111	1	Input



ROACH/iBOB2		ROACH_CONFIG	
COLLABORATORS:  CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN  <a href="http://casper.berkeley.edu/">http://casper.berkeley.edu/</a>		DOC NO	REVISION
		NRF-ADM-XXX-SD-0001	A
		DESCRIPTION	
		RECONFIGURABLE OPEN ARCHITECTURE HW	
7-3-2008_11:20		DRAWN:	APPR:
		F KAPP	
PATH PATH		CHECKED:	
		E BAUERMEISTER	SHEET 16 OF 25

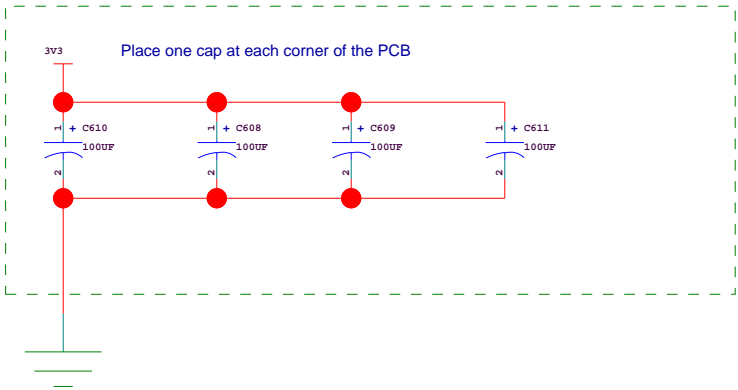


REMOVED 1.8V AND 1.5V REGULATORS, CONNECTED TO V5 RAILS

REMOVED VTT AND VREF - INCLUDED ON ROACH\_PPC\_DDR2

ROACH/iBOE2		ROACH_PPC_POWER_1	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOONRO BaeKAT, CAPE TOWN  http://casper.berkeley.edu/  7-3-2008.11:20  PATH PATH	DOC NO NRF-ADM-XXX-SD-0001		REVISION A
	DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW		
	DRAWN: F KAPP		CHECKED: R BAUERMEISTER
	SHEET		17 OF 25



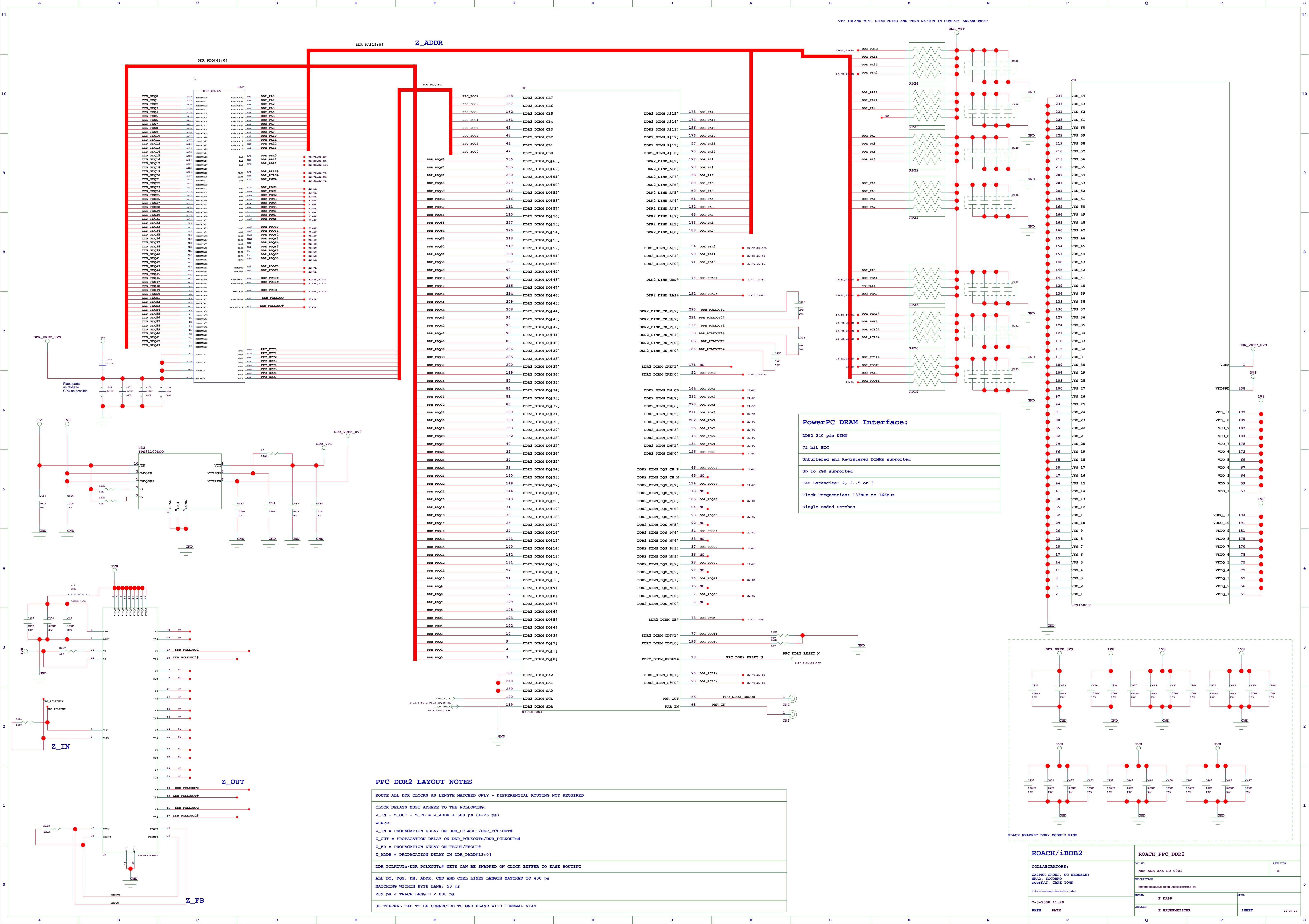
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7											7																		
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0	<table><tr><td colspan="2">ROACH/iBOB2</td><td colspan="2">ROACH_PPC_POWER_2</td></tr><tr><td colspan="2" rowspan="2">COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN  http://casper.berkeley.edu/</td><td>DOC NO  NRF-ADM-XXX-SD-0001</td><td>REVISION  A</td></tr><tr><td colspan="2">DESCRIPTION  RECONFIGURABLE OPEN ARCHITECTURE HW</td></tr><tr><td colspan="2">7-3-2008_11:20</td><td>DRAWN:  F KAPP</td><td>APPR:  </td></tr><tr><td>PATH</td><td>PATH</td><td>CHECKED:  E BAUERMEISTER</td><td>SHEET  18 OF 25</td></tr></table>										ROACH/iBOB2		ROACH_PPC_POWER_2		COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN  http://casper.berkeley.edu/		DOC NO  NRF-ADM-XXX-SD-0001	REVISION  A	DESCRIPTION  RECONFIGURABLE OPEN ARCHITECTURE HW		7-3-2008_11:20		DRAWN:  F KAPP	APPR:  	PATH	PATH	CHECKED:  E BAUERMEISTER	SHEET  18 OF 25	0
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ROACH/iBOB207 25







Critical Placement and Route  
Clock Rules:

Clock Rules:  
CLK\_UART\_11\_0592MHz = as short as possible  
CLK\_SYS\_33MHz = as short as possible  
CLK\_CPLD\_33MHz = CLK\_SYS\_33MHz

Critical Placement and Route  
Clock Rules:

Clock Rules:  
CLK\_PC13\_6633MHz = as short as possible  
CLK\_PC12\_6633MHz = CLK\_PC13\_6633MHz  
CLK\_PC11\_6633MHz = CLK\_PC12\_6633MHz + 2.5°  
CLK\_GETH0\_25MHz = as short as possible  
CLK\_GETH1\_25MHz = CLK\_GETH0\_25MHz  
CLK\_CPLD\_50MHz = as short as possible  
CLK\_USB2\_0\_48MHz = as short as possible  
CLK\_USB2\_0\_12MHz = as short as possible

TRACE & JTAG CONNECTORS

Critical placement and routing  
of the Trace connector and nets.  
Up to CPU frequency!

TRACE PORT

ROACH/iBOE2

ROACH\_PPC\_TST\_CLK\_IO

COLLABORATORS:

CASPER GROUP, UC BERKELEY  
NRAO, SOONERO  
Bharat, CAPE TOWN

http://casper.berkeley.edu/

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