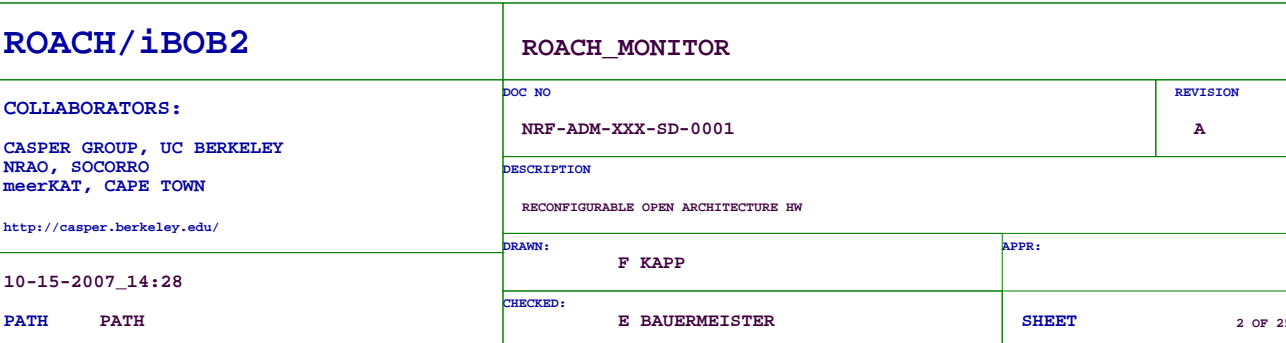


[illegible][illegible]

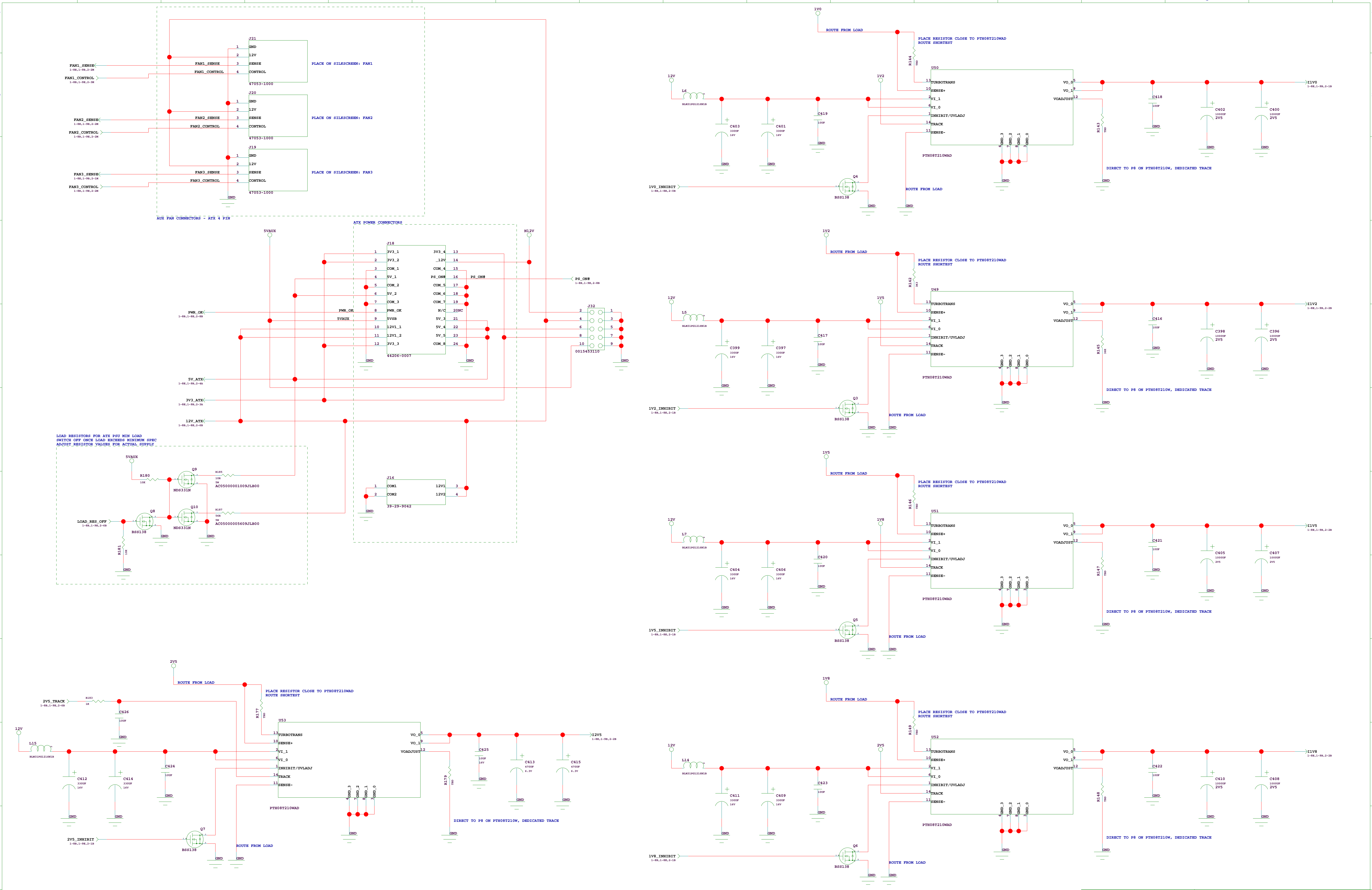
The diagram shows a linear DNA molecule. On the left, a green line represents the DNA, with a segment labeled "GATC" in red. A red line extends from the "GATC" site to a series of eight EcoRI restriction sites. Each EcoRI site is represented by a red circle with a blue "E" inside, followed by the sequence "5'GTCGAC3'". The sites are arranged vertically, with a red line connecting them. The first site is labeled "E1" and the last is labeled "E8".

STIERNE SAUERKNEISTER  
HENRY COEN  
STEVE DURAND  
FRANCOIS KAPP  
ALAN LANGMAN  
GEORGE PECK  
MIKE REYNELL  
RAYDEN SO  
DAN WERTHIMER

ROACH/iBOB2		ROACH_TOP		REVISION	
COLLABORATORS:		DOC NO		A	
CASPER GROUP, UC BERKELEY		NRP-ADM-XXX-SD-0001			
WRAG, GORDON		DESCRIPTION			
MEERCAT, CAPE TOWN		RECONFIGURABLE OPEN ARCHITECTURE HW			
<a href="http://casper.berkeley.edu/">http://casper.berkeley.edu/</a>		NAME:		APP:	
10-15-2007_14:28		P KAPP			
PATH PATH		CHECKED: E BAUMEISTER		SHEET	
				1 OF 2	

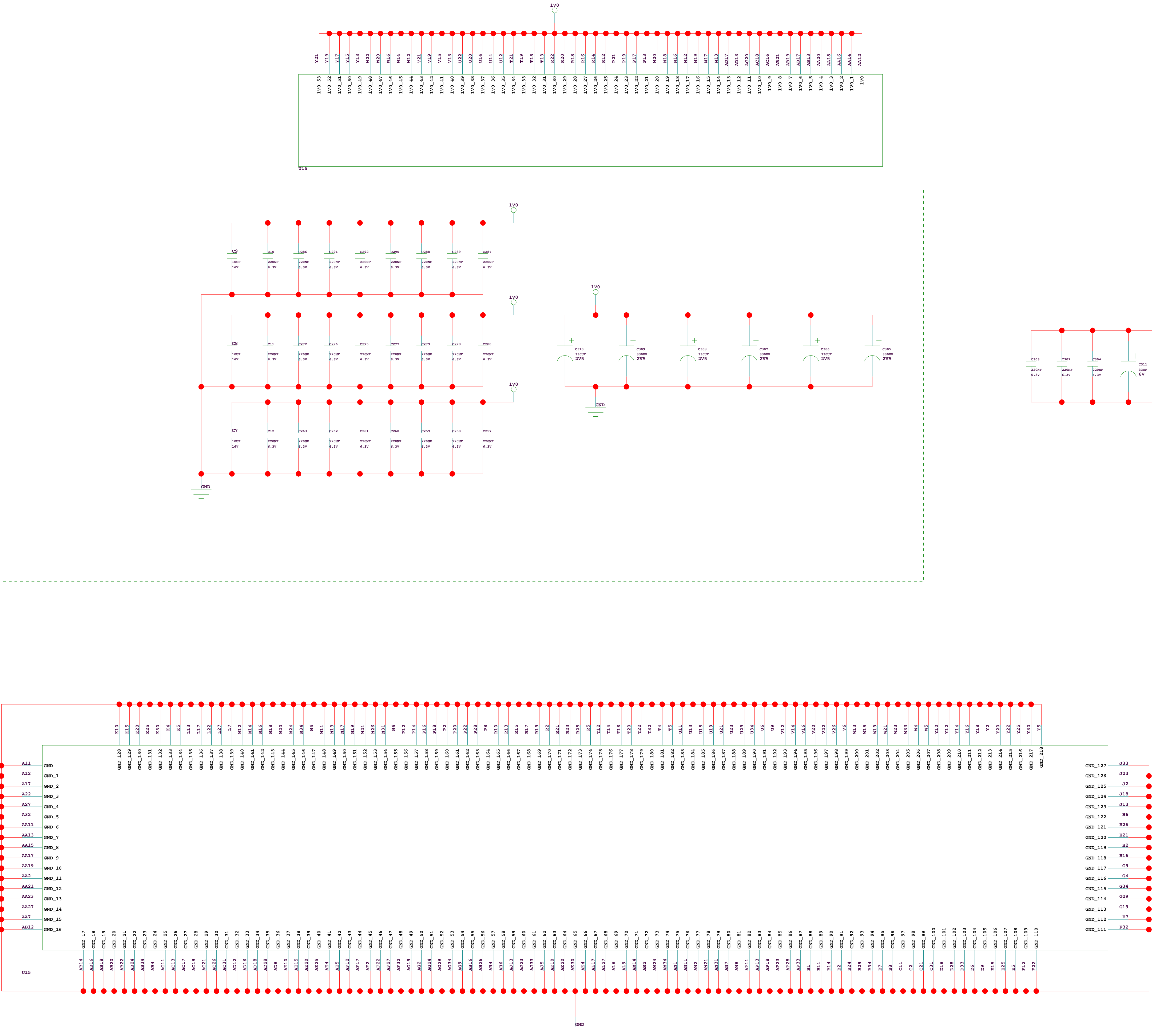


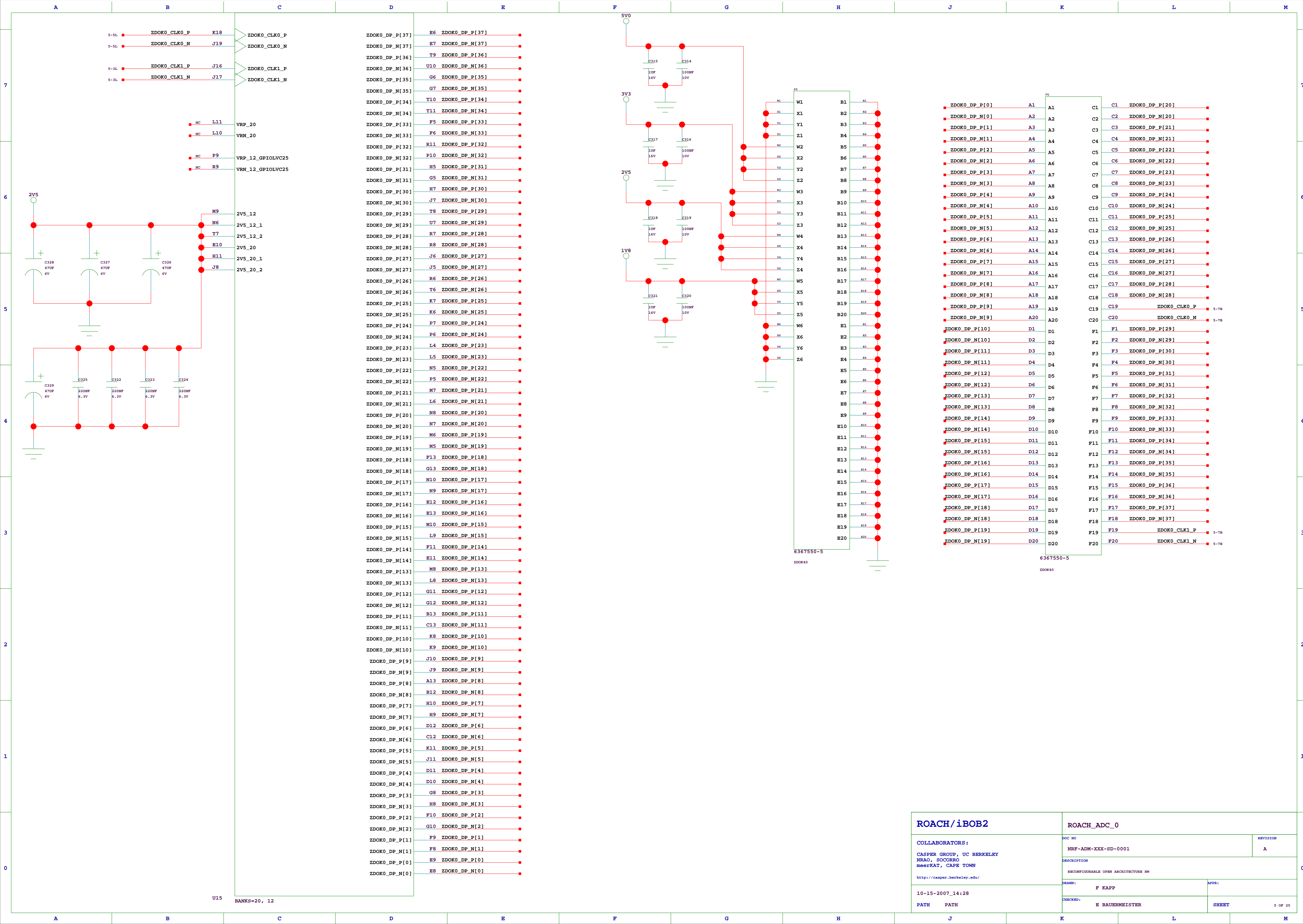




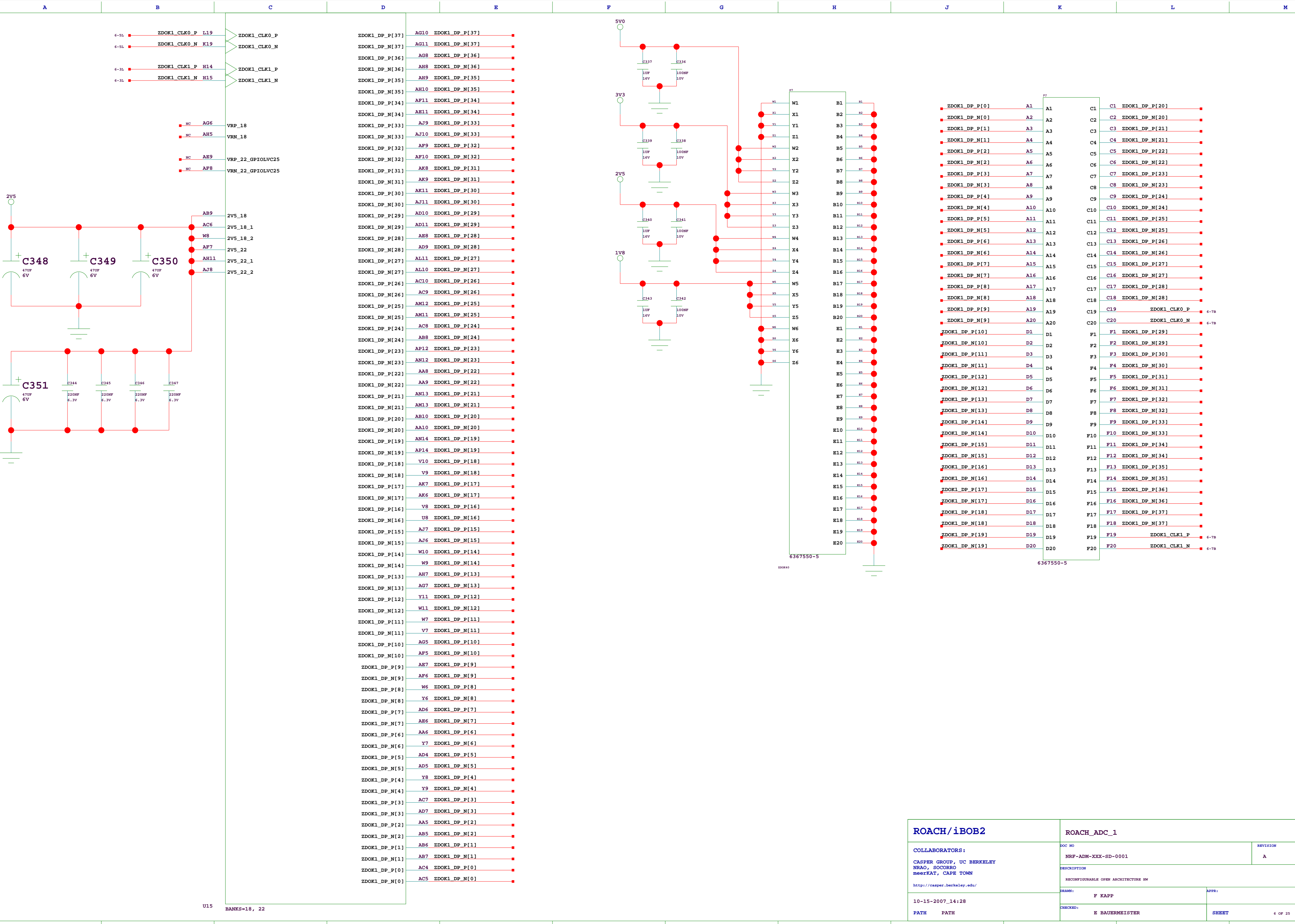
ADJUSTMENT AND T2 RESISTOR VALUES TBD  
SOURCE VOLTAGES TO BE SELECTED

ROACH/iBOB2		ROACH_PSU	
COLLABORATORS:		DOC NO	REVISION
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-BD-0001	A
NRAO, SOONERO		DESCRIPTION	
BeeEAT, CAPE TOWN		RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/		DRAWN:	APPD:
10-15-2007_14:28		F KAPP	
PATH	PATH	CHECKED: R BAUERNISTE	
		SHEET	
		3 OF 25	

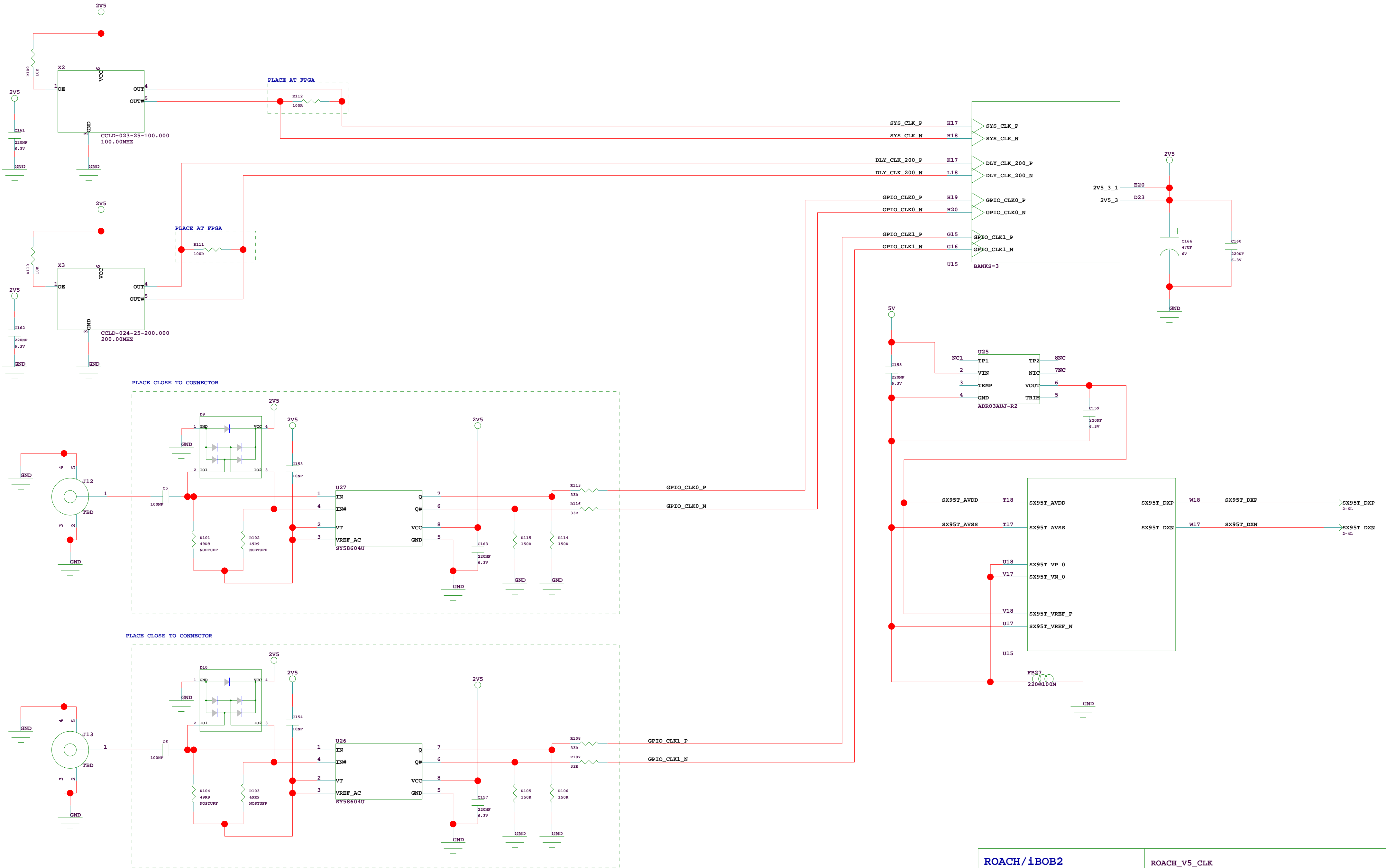




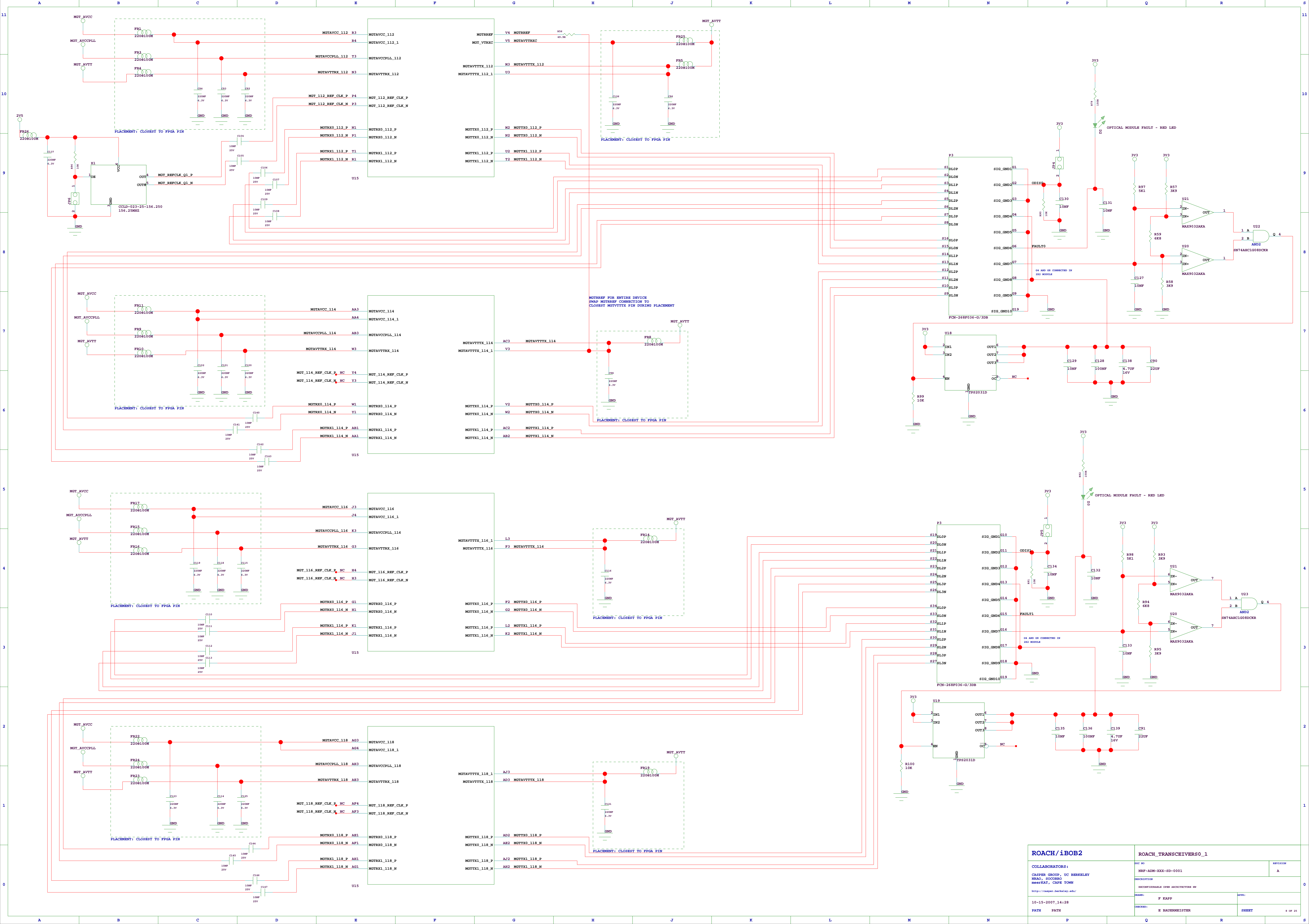




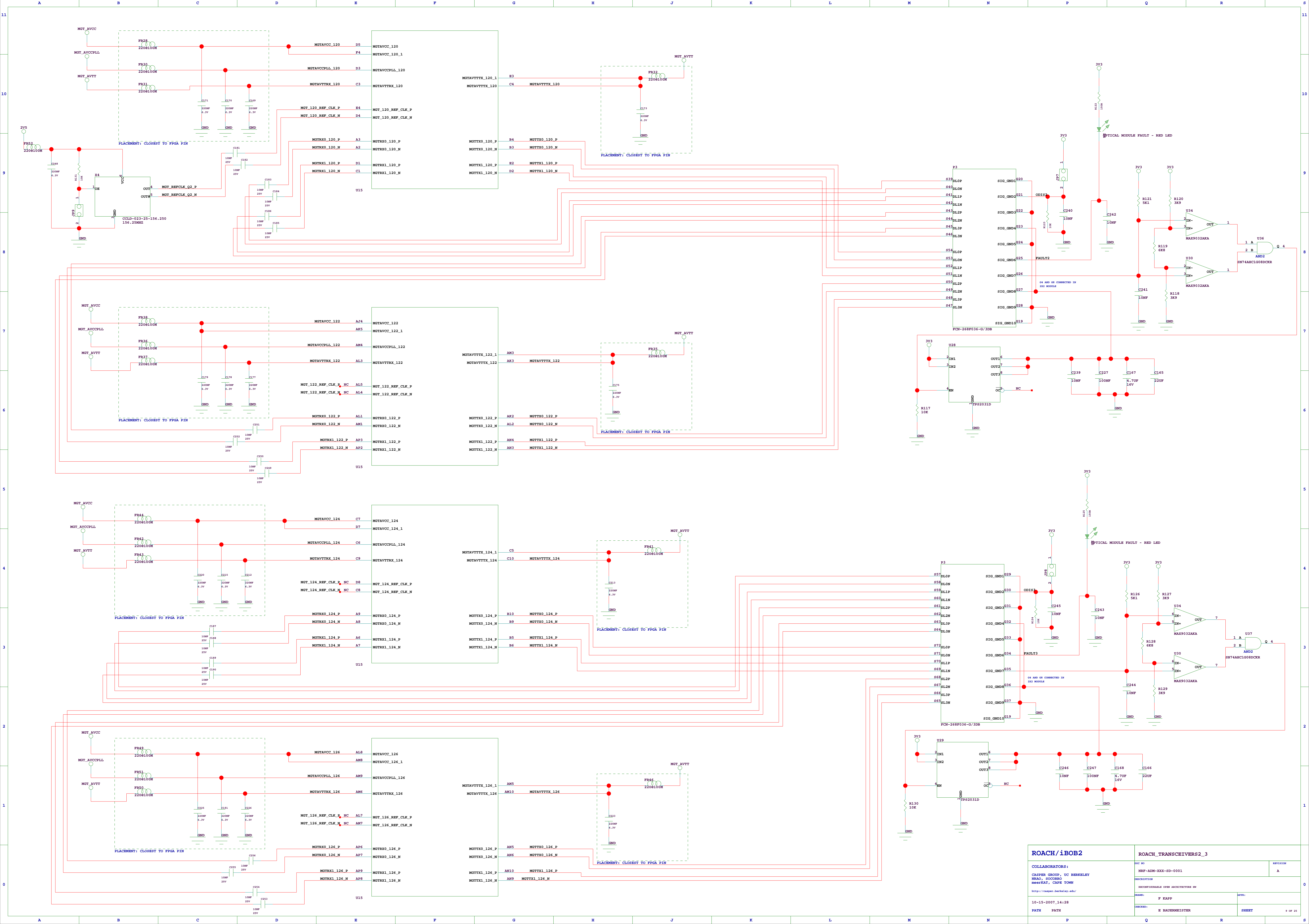
ROACH/iBOB2		ROACH_ADC_1	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN  http://casper.berkeley.edu/	DOC NO NRF-ADM-XXX-SD-0001		REVISION A
	DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW		
	DRAWN: F KAPP	APPR:	
10-15-2007_14:28	CHECKED: E BAUERMEISTER		SHEET 6 OF 25

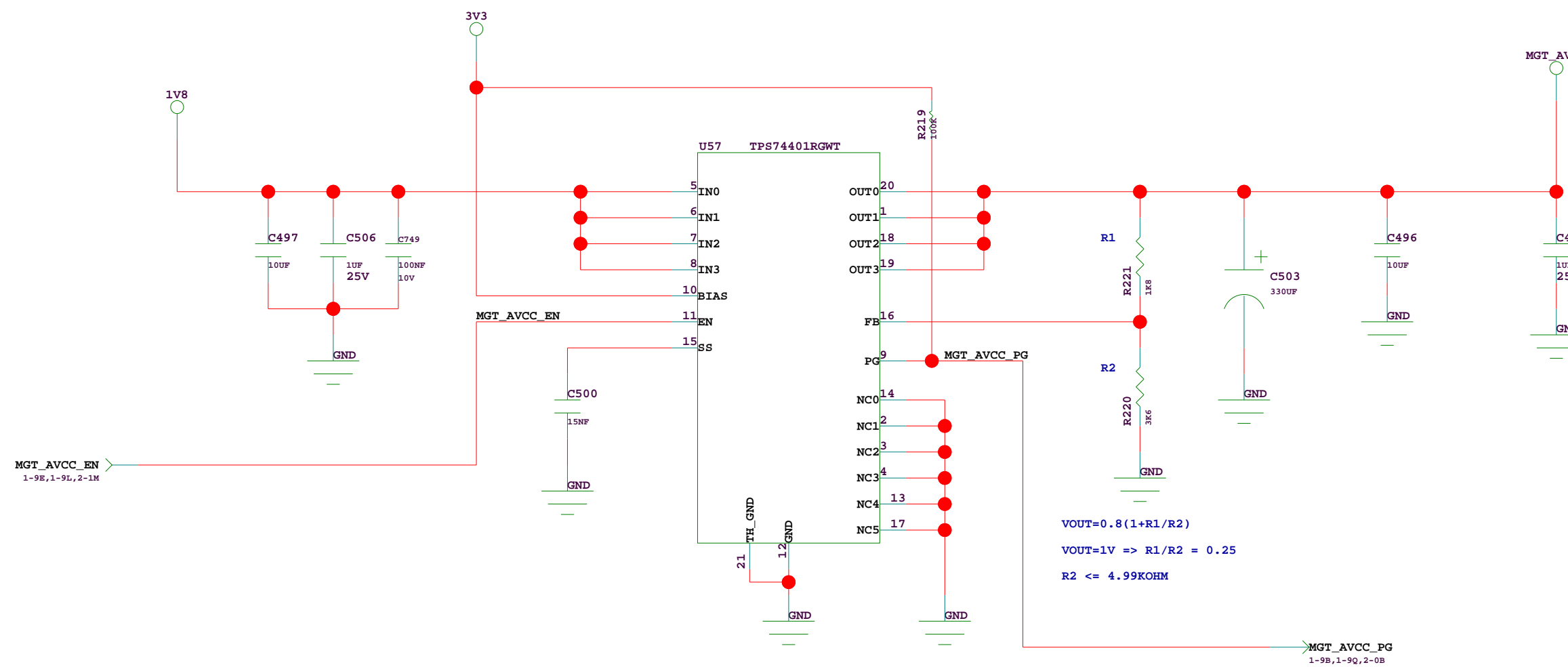
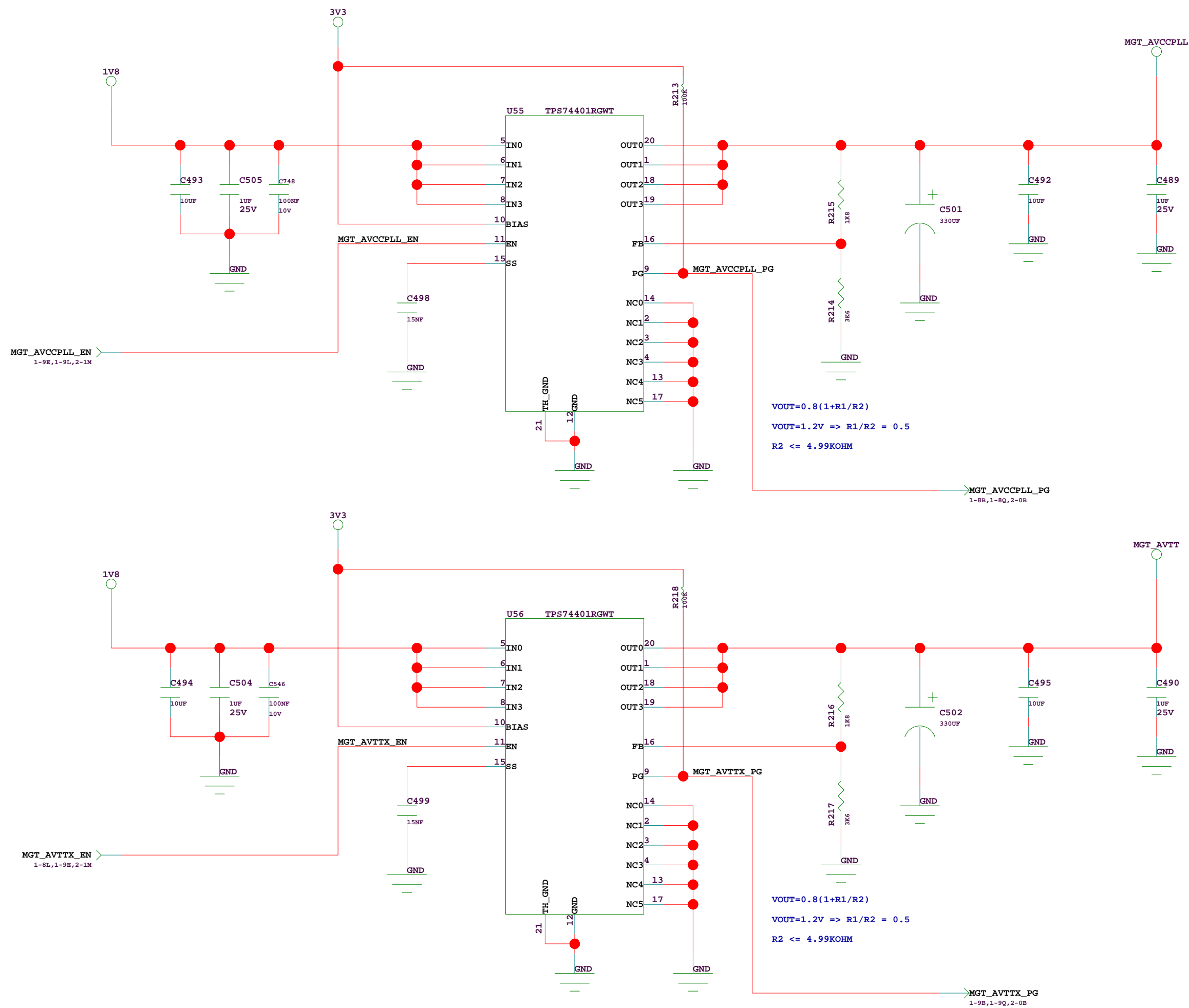


ROACH/iBOB2		ROACH_V5_CLK	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN  <a href="http://casper.berkeley.edu/">http://casper.berkeley.edu/</a>		DOC NO NRF-ADM-XXX-SD-0001	REVISION A
		DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW	
		DRAWN: F KAPP	APPR:
10-15-2007_14:28		CHECKED: E BAUERMEISTER	SHEET
PATH	PATH		7 OF 25

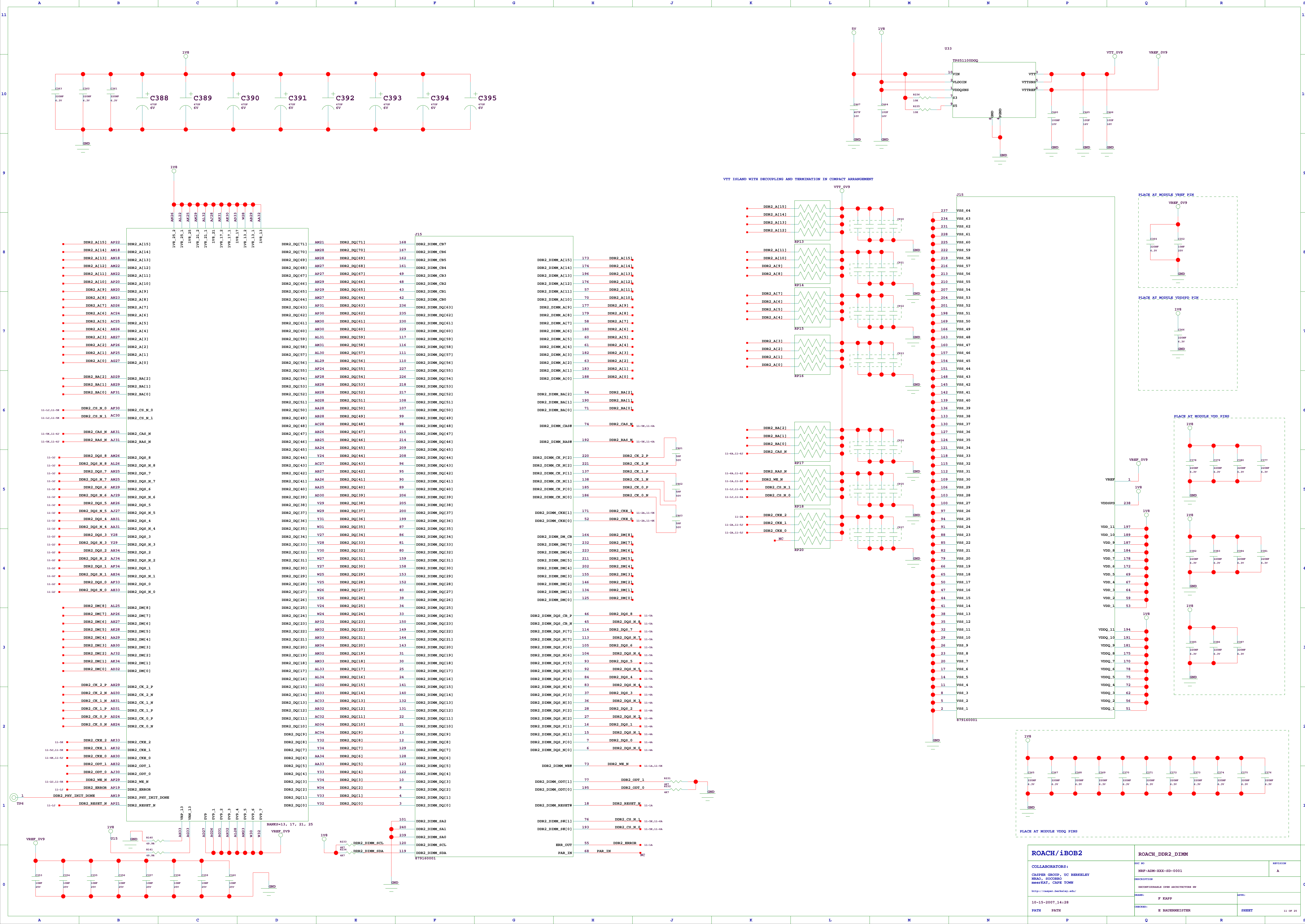




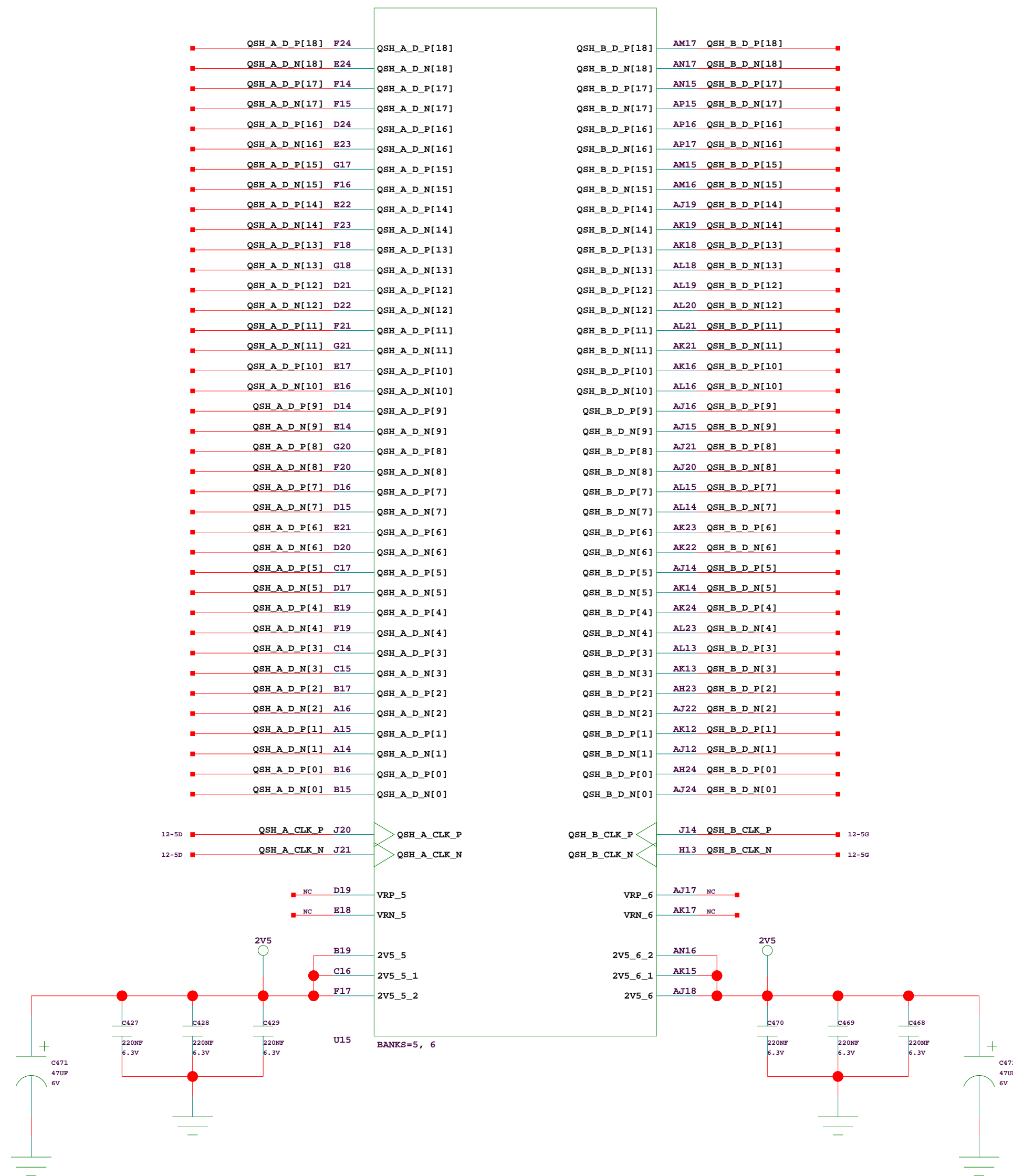




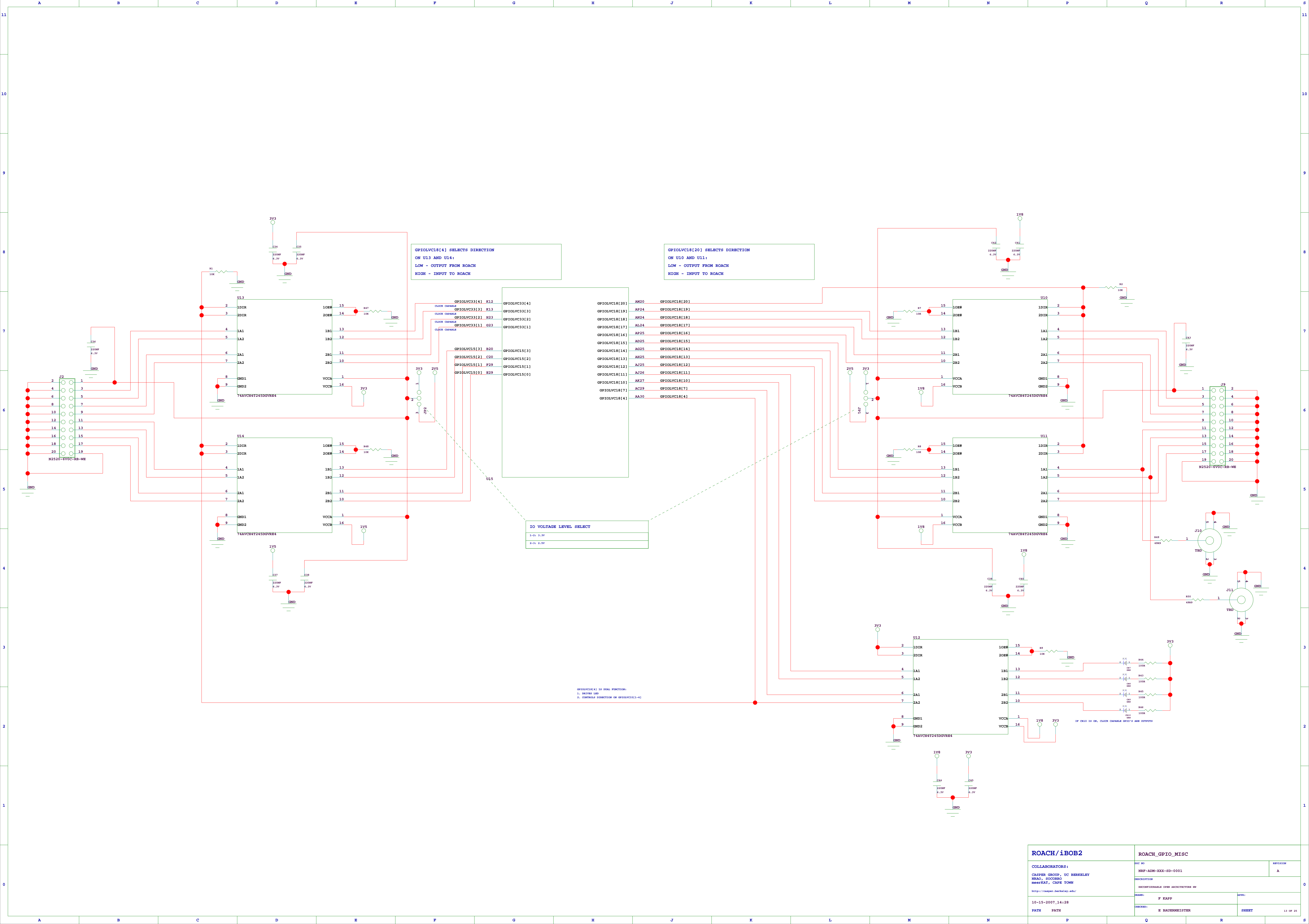
ROACH/iBOE2		ROACH_TRANSCEIVERS_PSU	
COLLABORATORS:		DOC NO	REVISION
CASPER GROUP, UC BERKELEY MRSAD, SCSOCHRO meerKAT, CAPE TOWN		NRF-ADM-XXX-SD-0001	A
DESCRIPTION		RECONFIGURABLE OPEN ARCHITECTURE HW	
<a href="http://casper.berkeley.edu/">http://casper.berkeley.edu/</a>		DRN:	APP:
10-15-2007_14:28		F KAPP	
PATH	PATH	CHECKED:	SHEET
		E BAUERMEISTER	10 OF 25







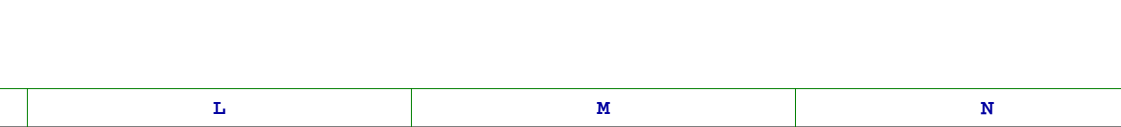
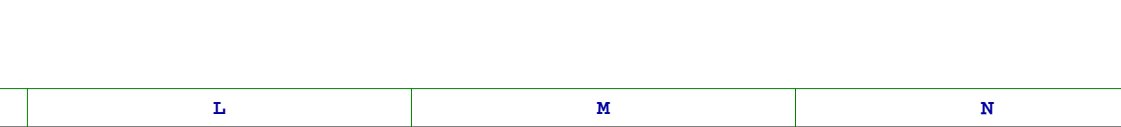
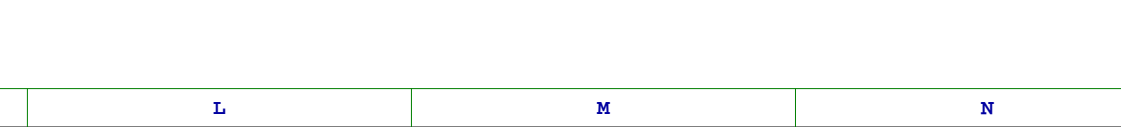
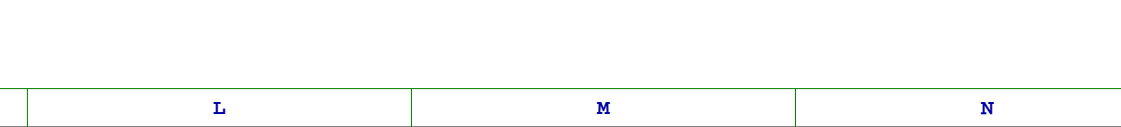
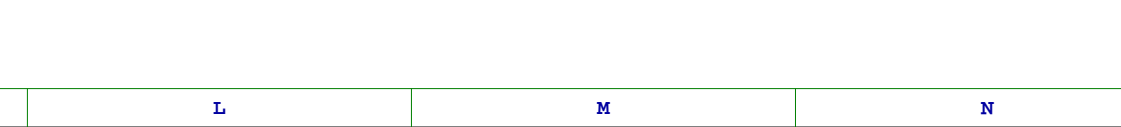
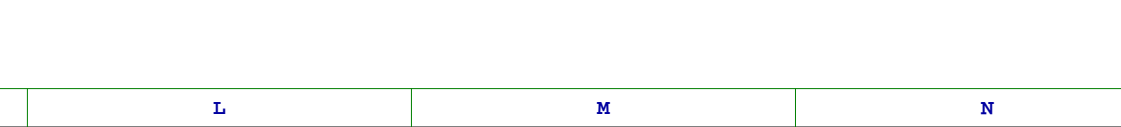
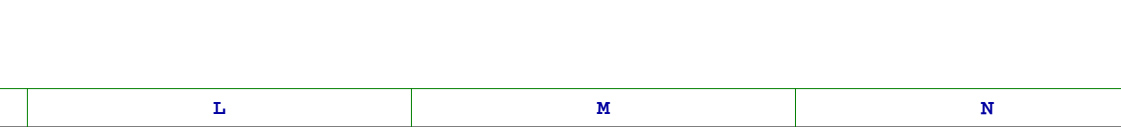
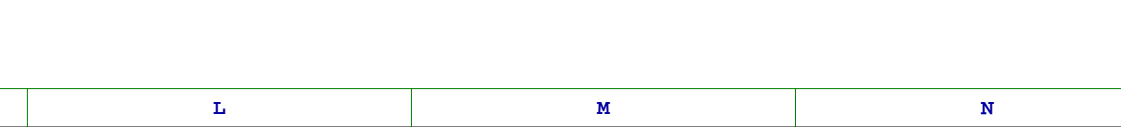
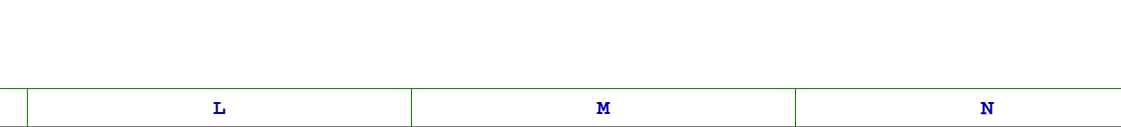
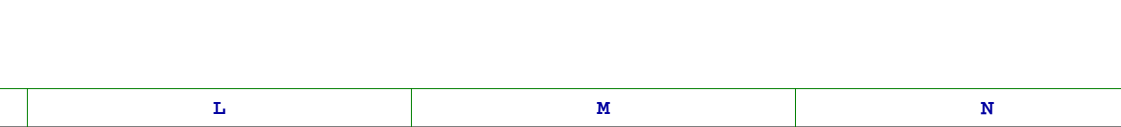
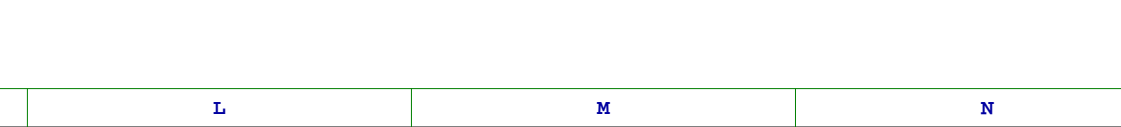
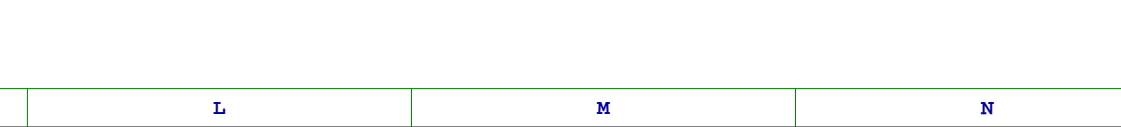
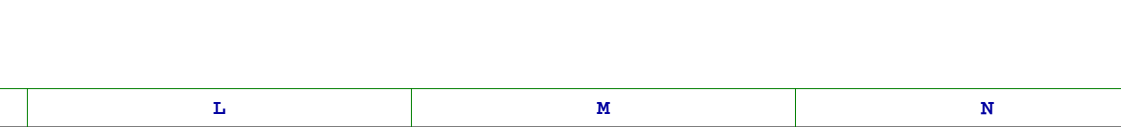
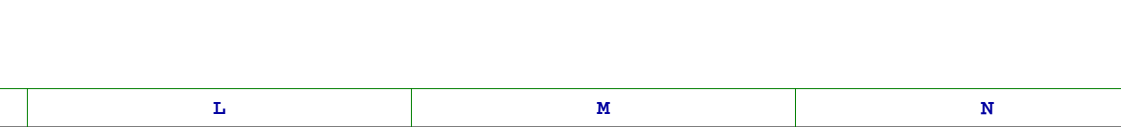
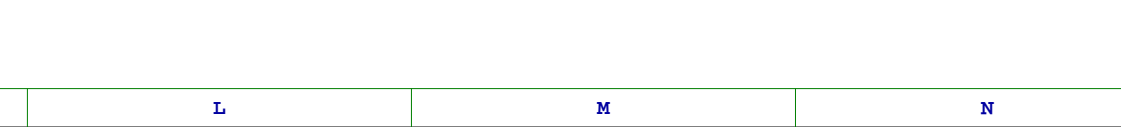
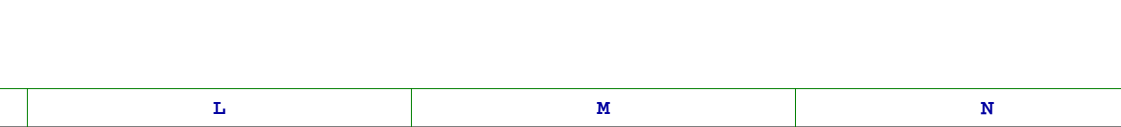
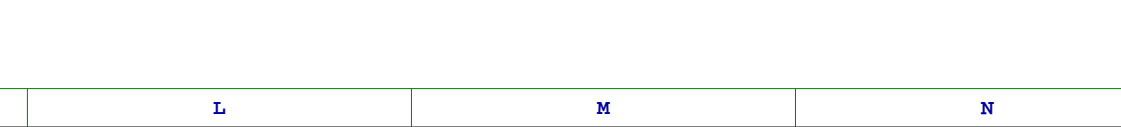
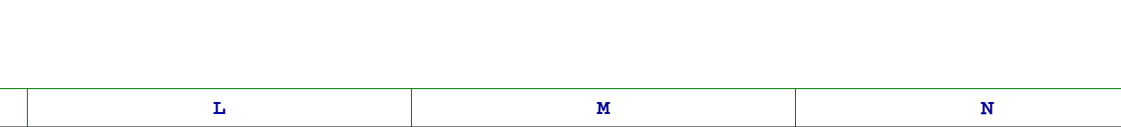
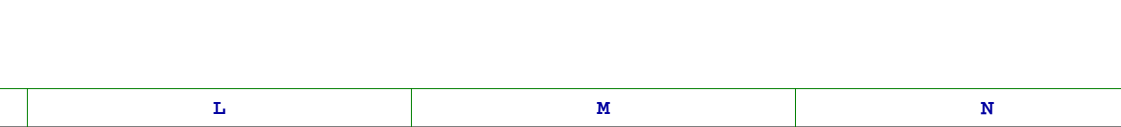
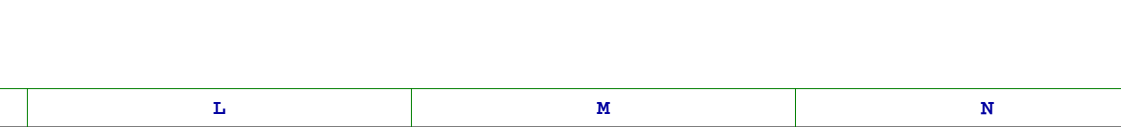
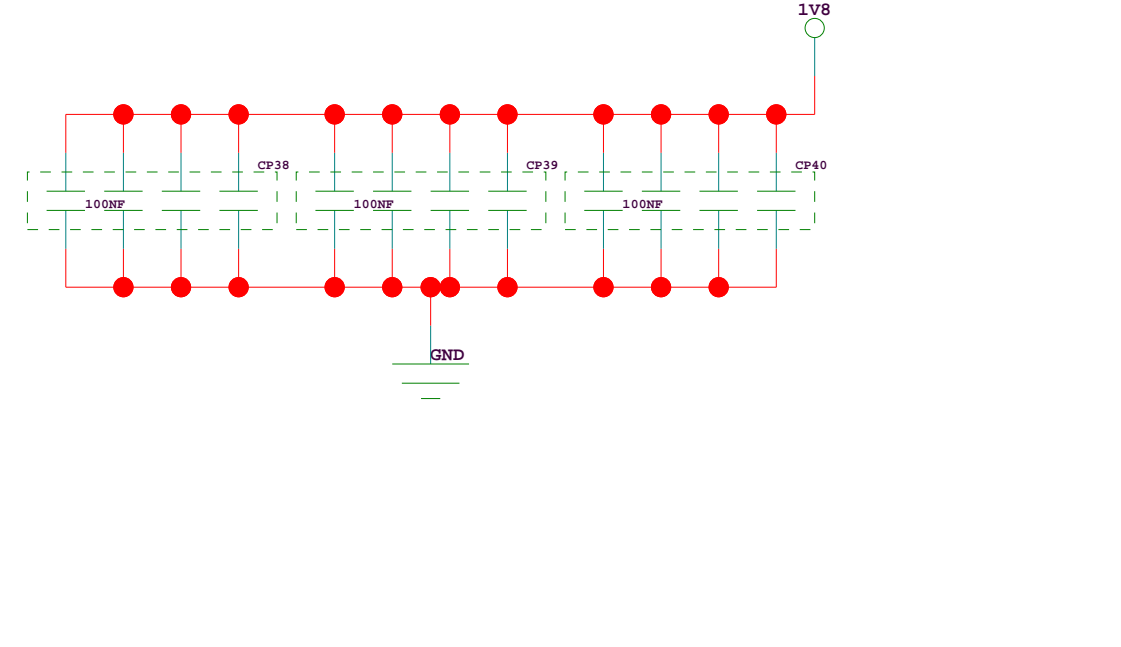
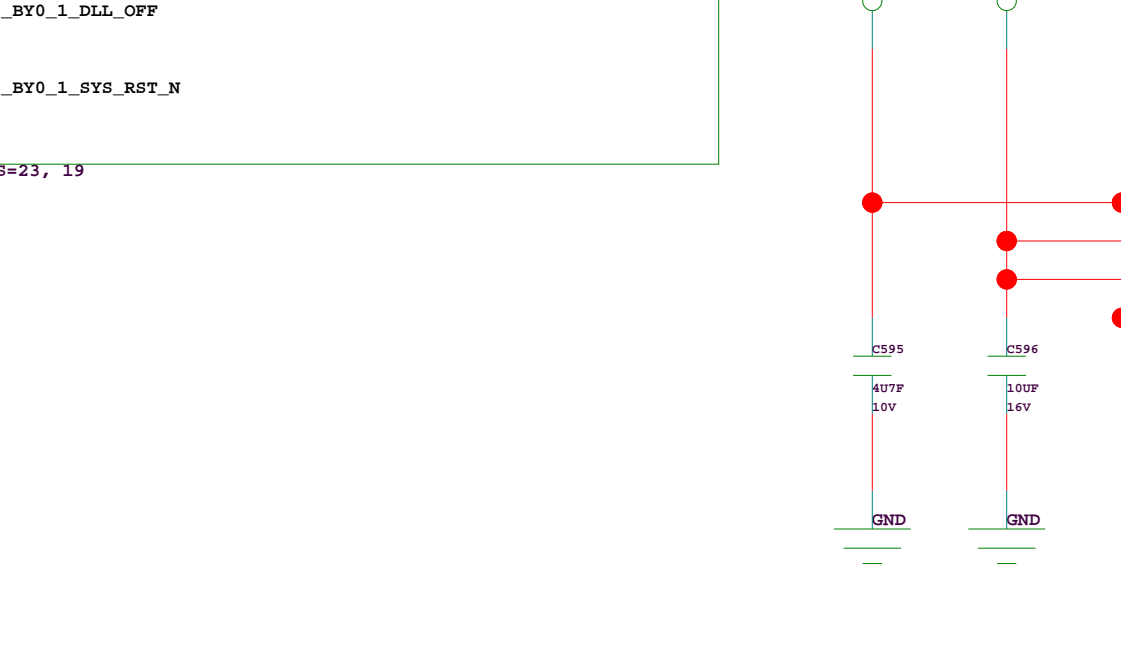
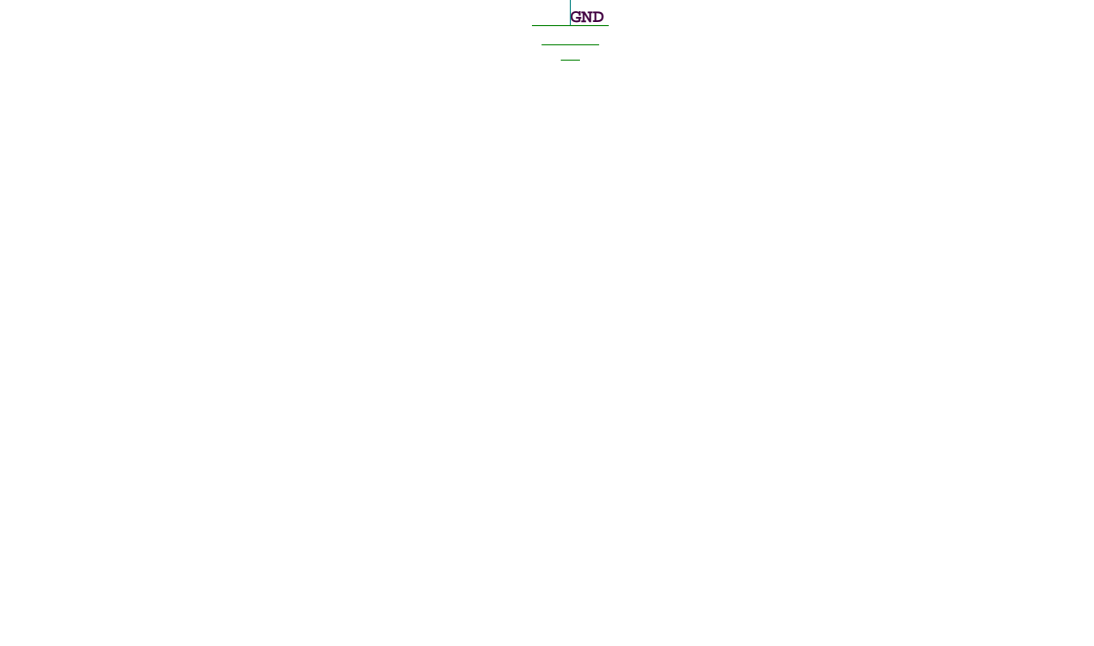
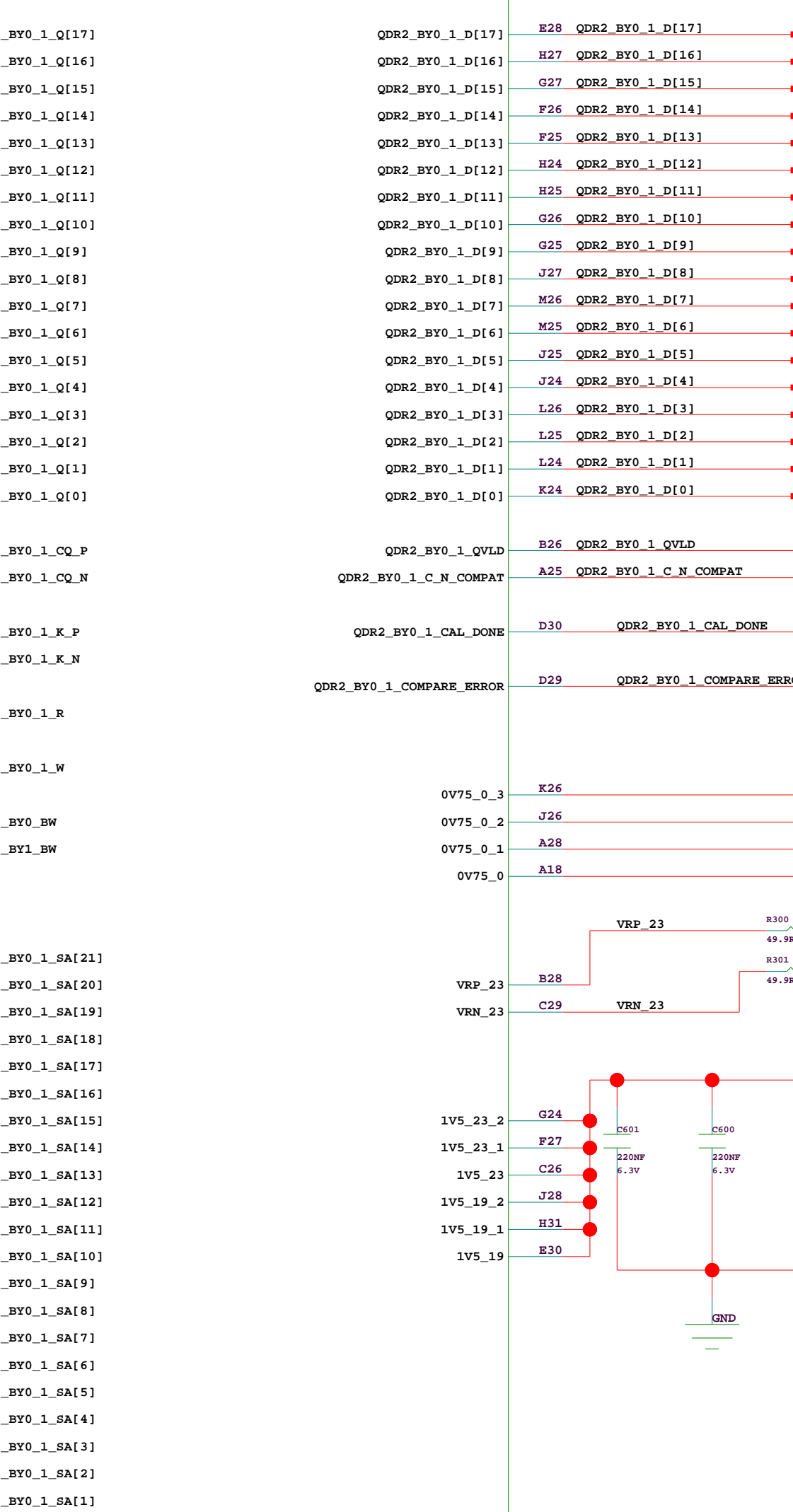
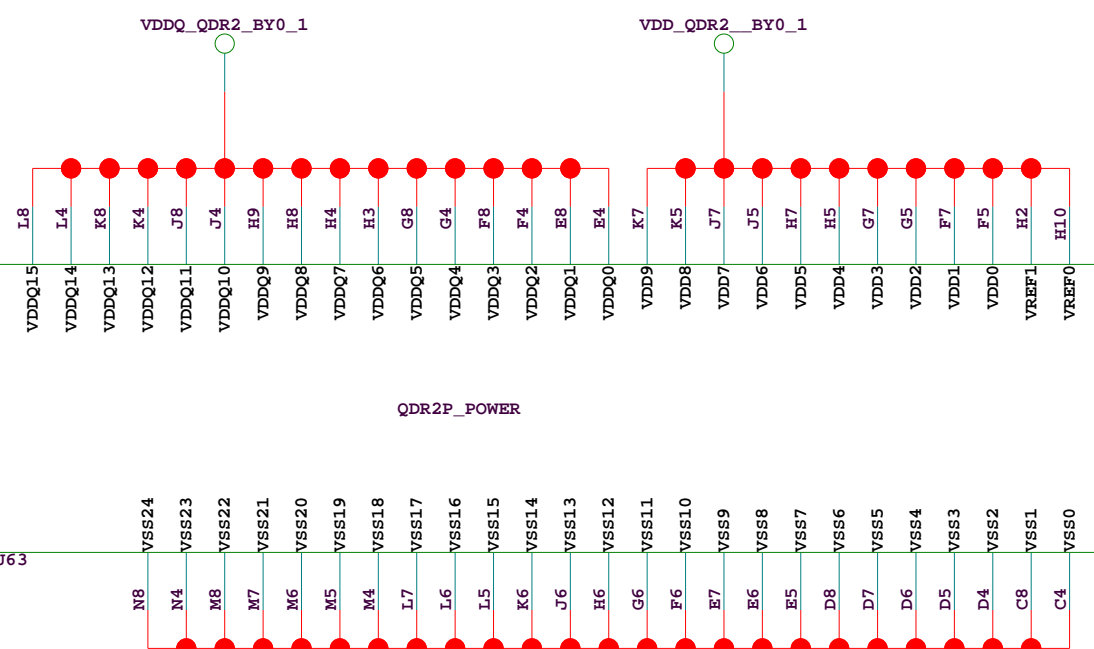
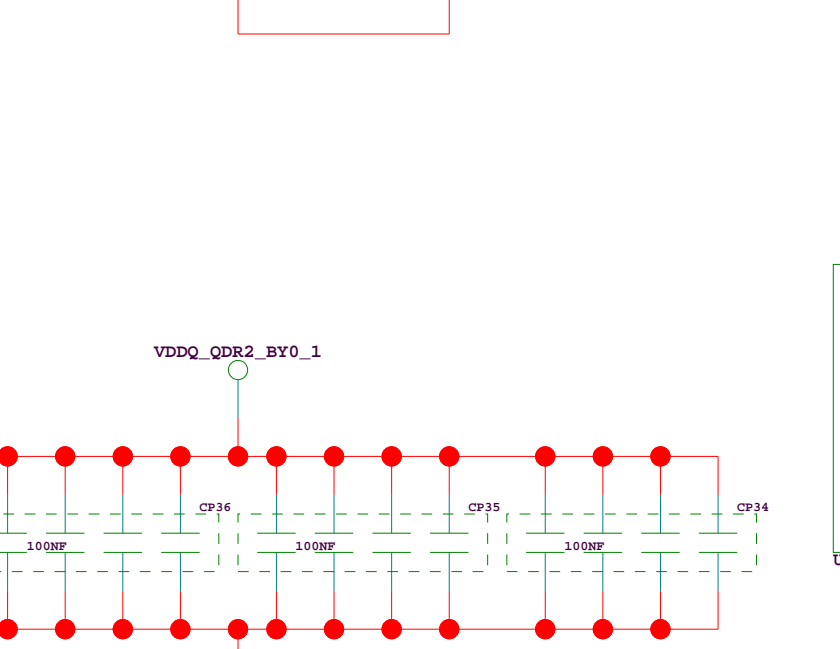
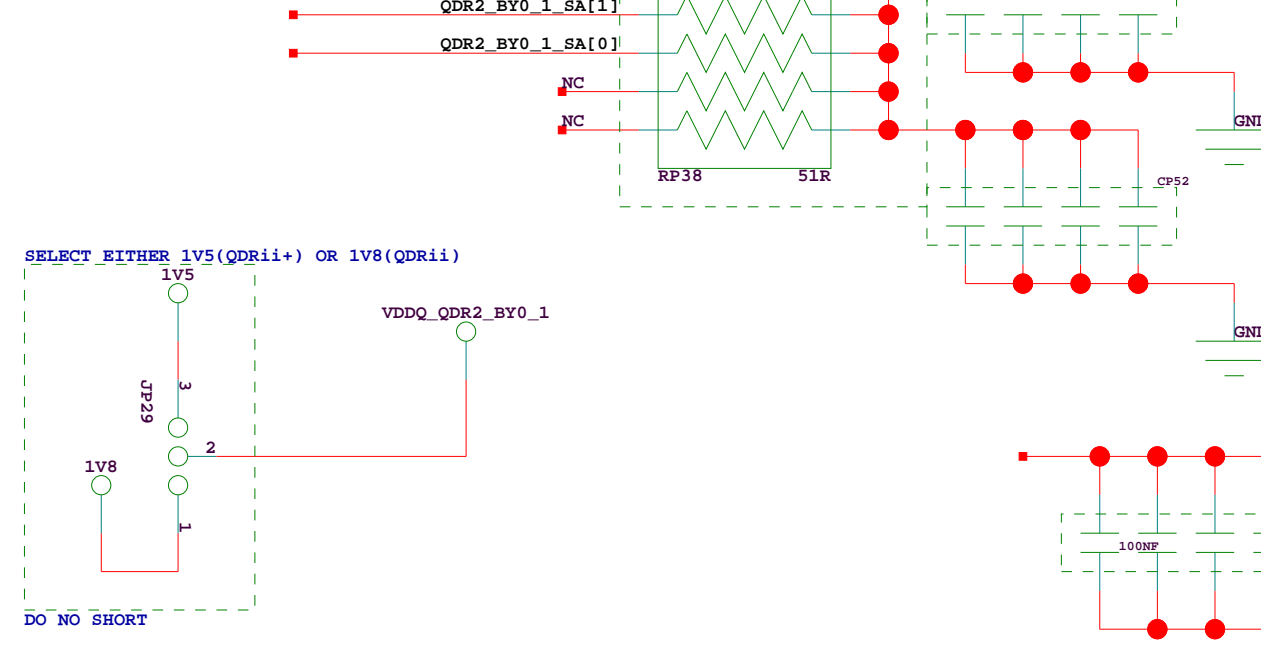
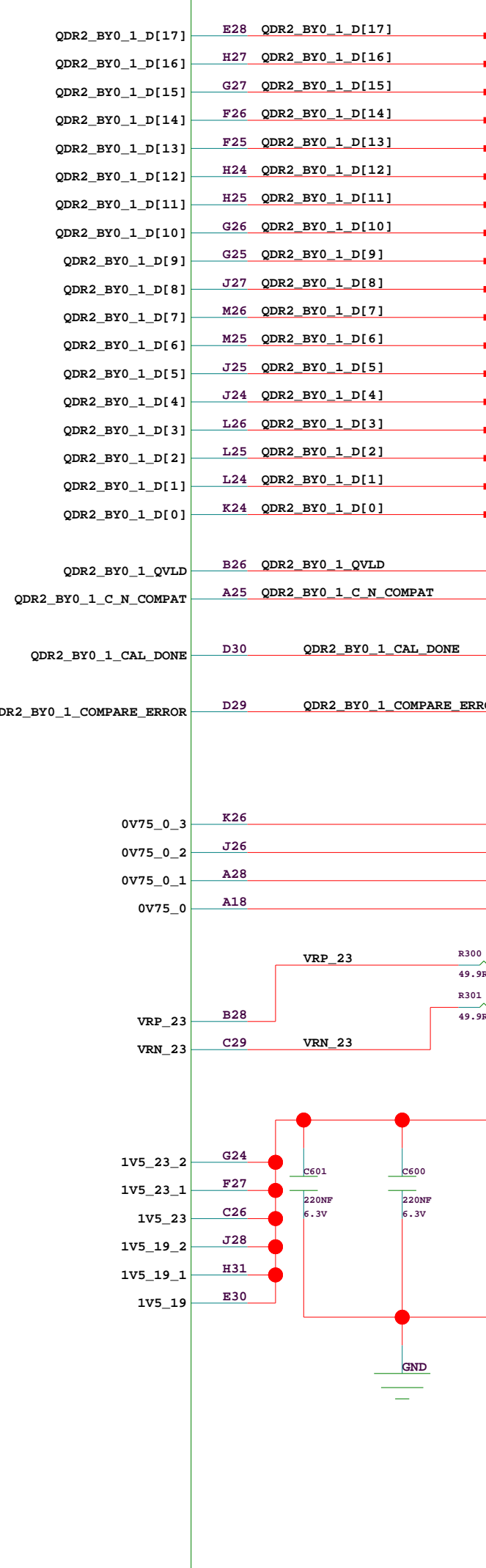
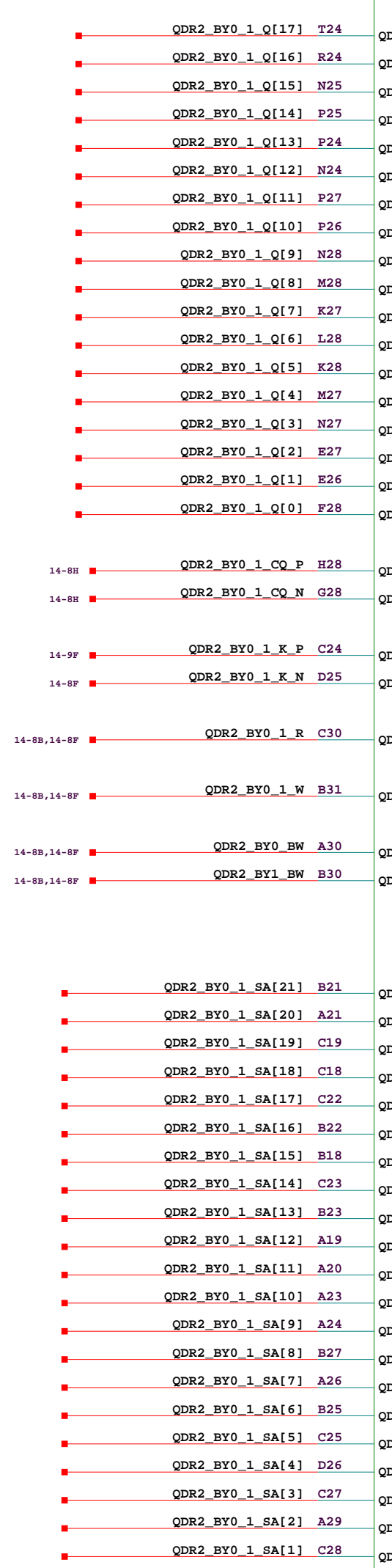
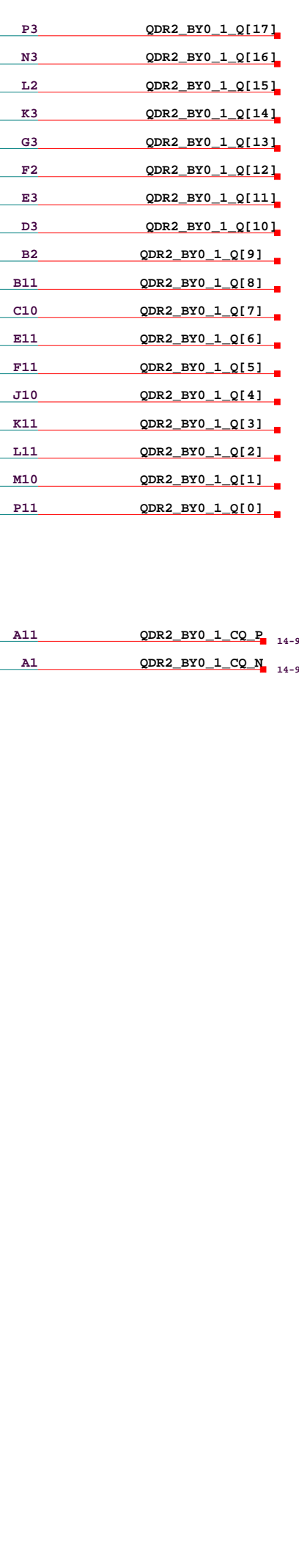
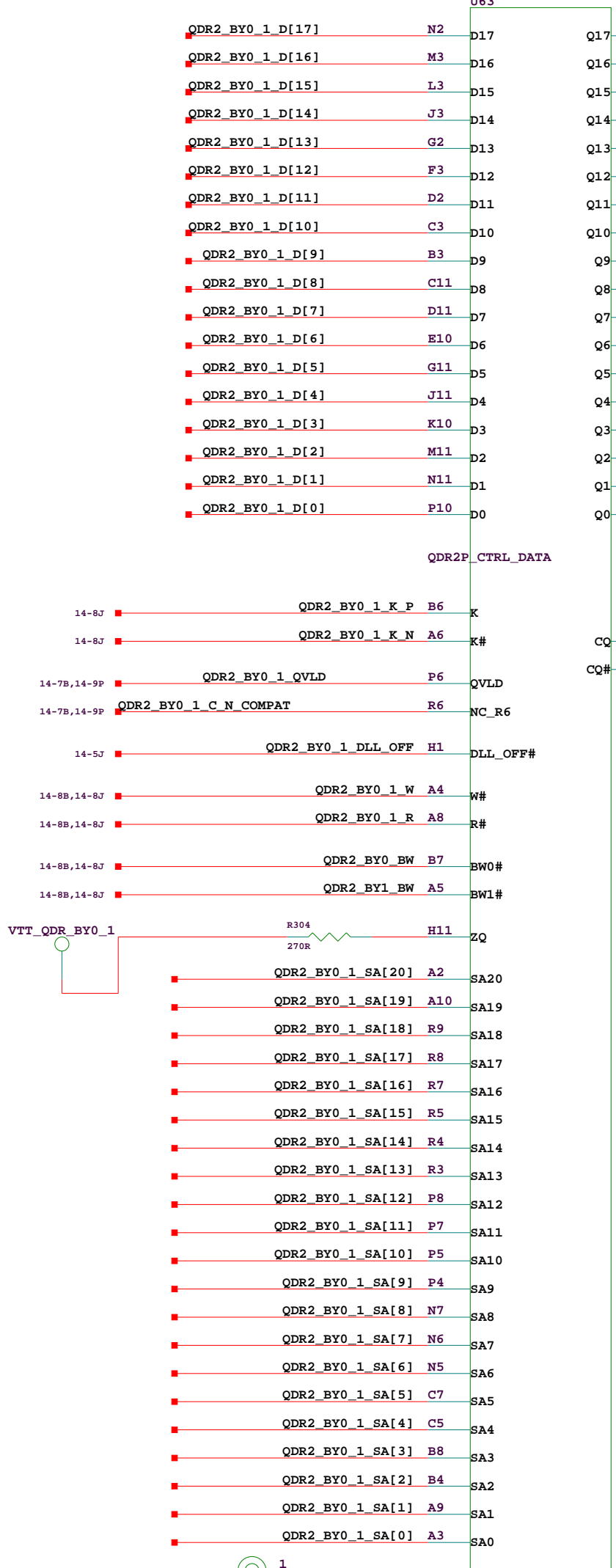
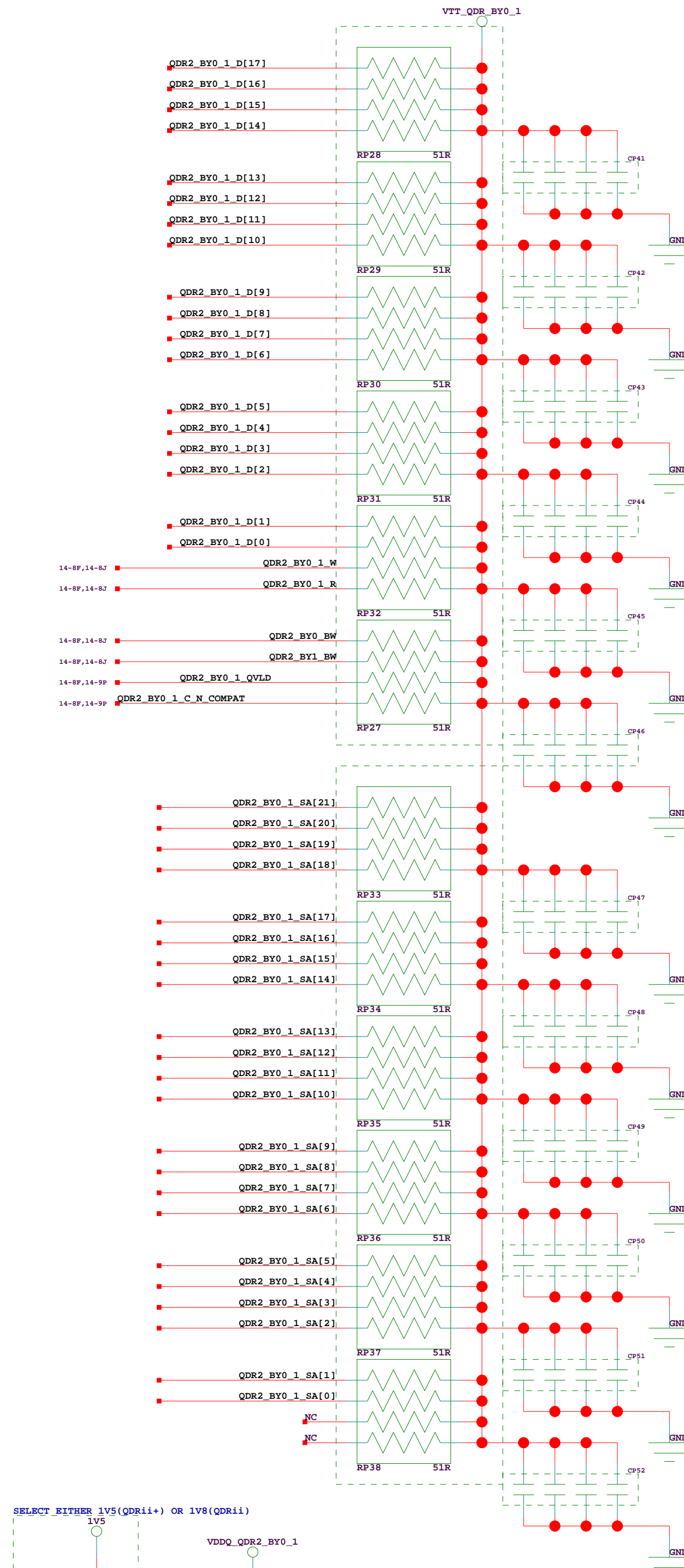
ROACH/iBOB2		ROACH_DIFF_GPIO	
COLLABORATORS:		DOC NO	REVISION
CAPPER GROUP, UC BERKELEY		HRP-ADM-XXX-ED-0001	A
MEMO, SECURITY		DESCRIPTION	
HARVEST, CAPE TOWN		RECONFIGURABLE OPEN ARCHITECTURE HW	
<a href="http://capper.berkeley.edu/">http://capper.berkeley.edu/</a>		ISSUE:	APPROVAL:
10-15-2007-14:28		F KAPP	
PATH PATH		E BAUMHEISTER	SHEET
			12 OF 2



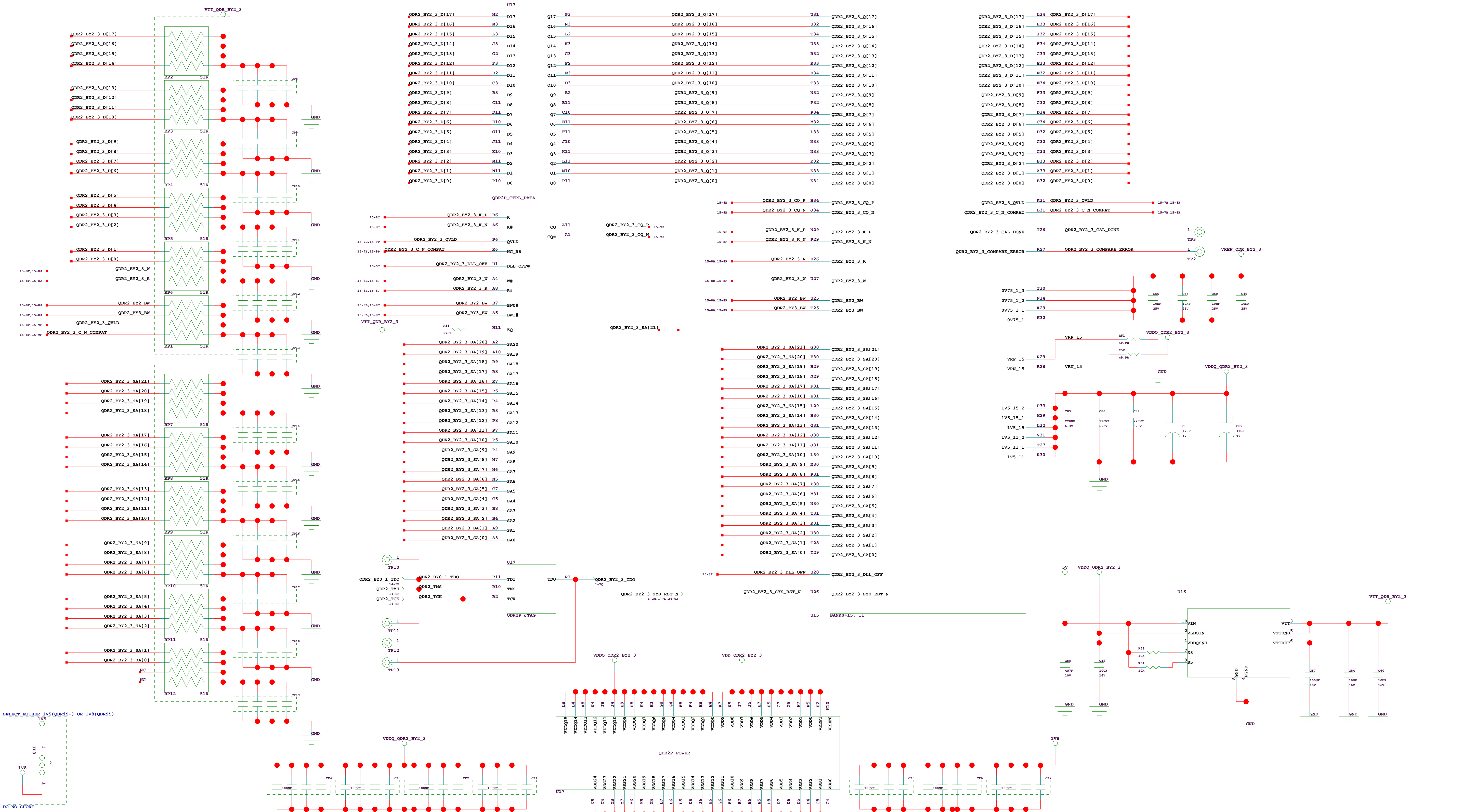
ROACH/iBOE2		ROACH_GPIO_MISC	
COLLABORATORS:		DOC NO	REVISION
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-SD-0001	A
DESCRIPTION		DESCRIPTION	
NRAO, SOONERO		RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/		ISSUED:	ISSUE:
10-15-2007_14:28		F KAPP	
PATH	PATH	R BAUERNBIESTER	
		CHECKED:	SHEET

GPIOVC18[4] IS DUAL FUNCTION:  
1. OUTPUTS ARE  
2. CONTROLS DIRECTION ON GPIOVC18[1-4]

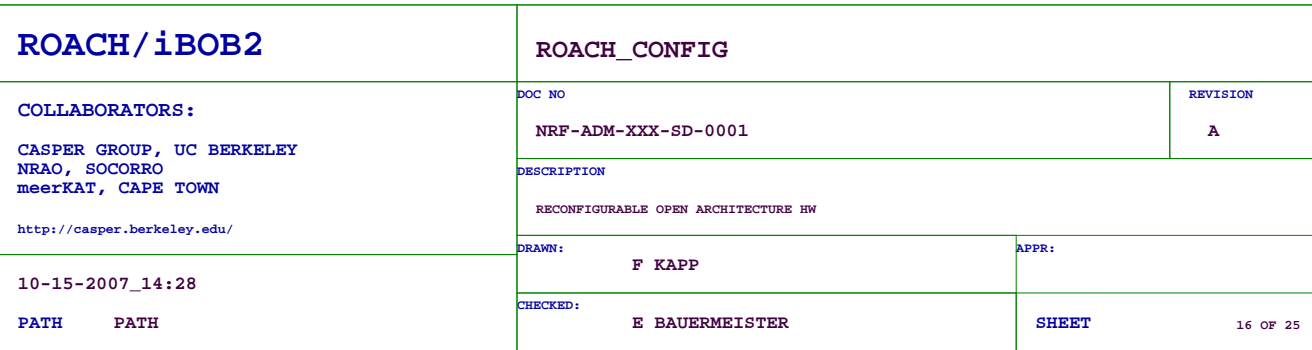
IF CN10 IS ON, CLOCK CAPABLE GPIO'S ARE OUTPUTS

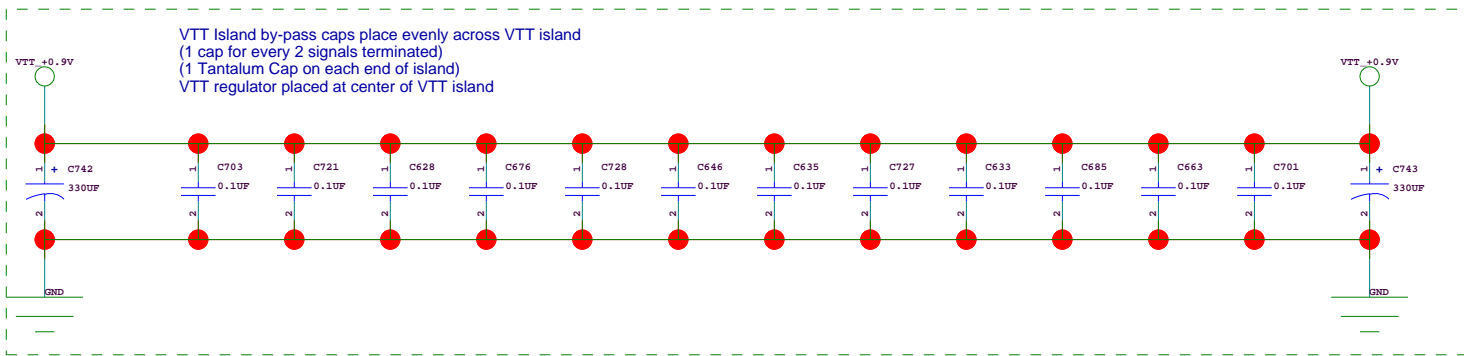
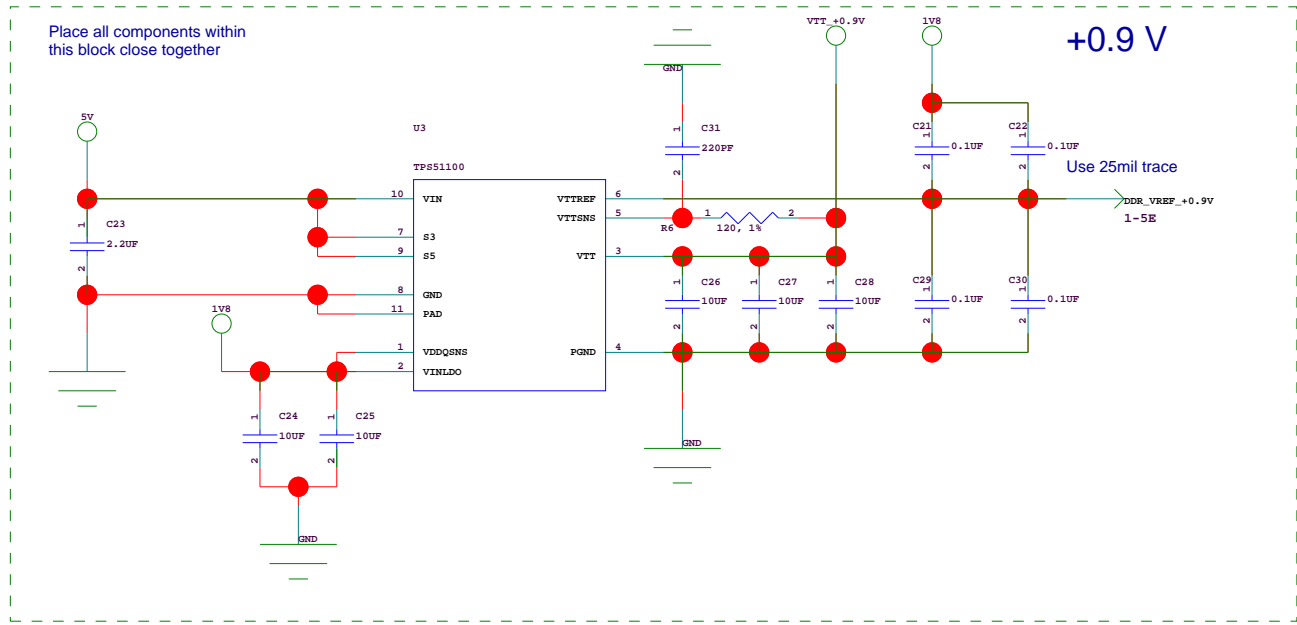
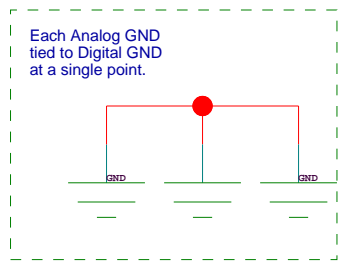
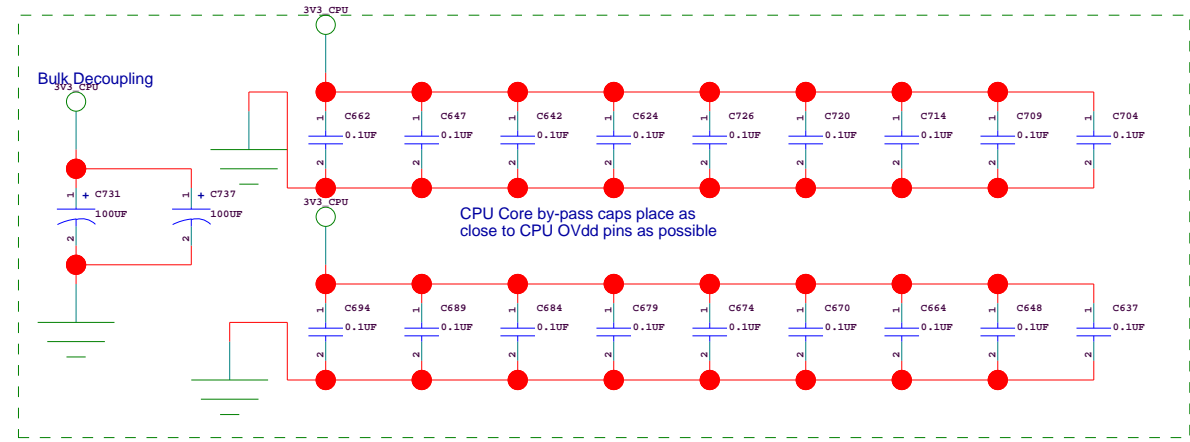
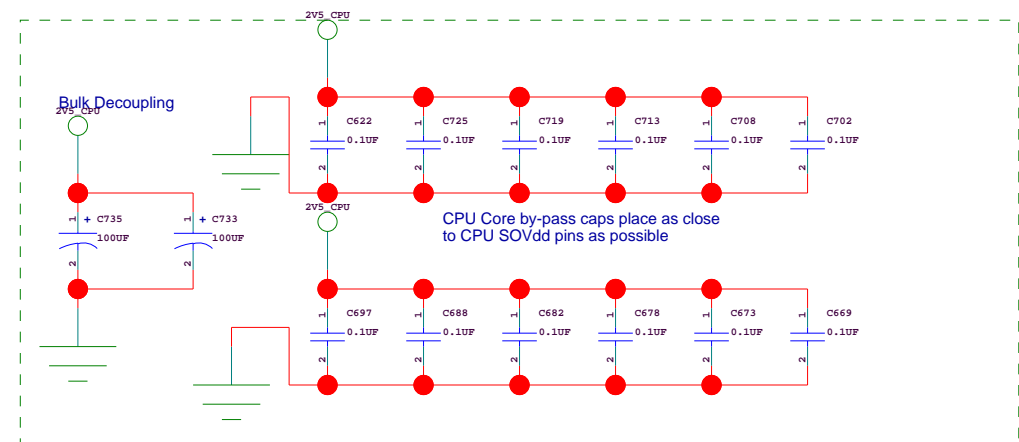
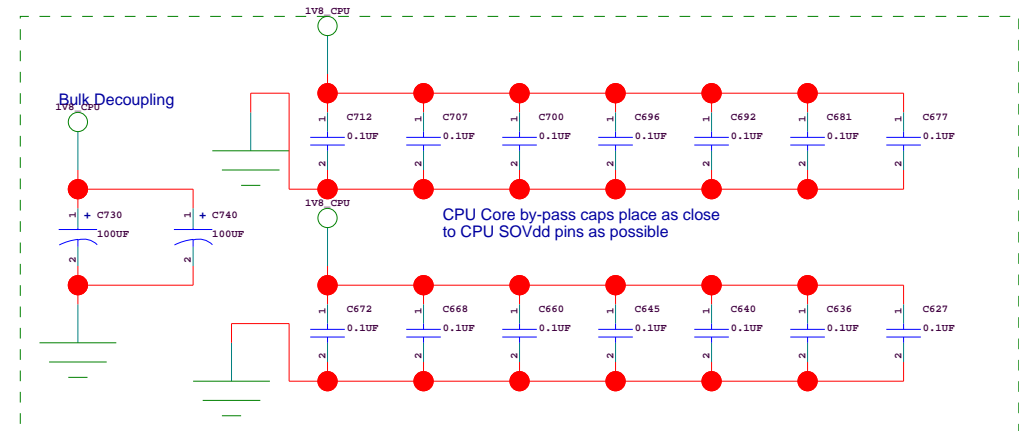
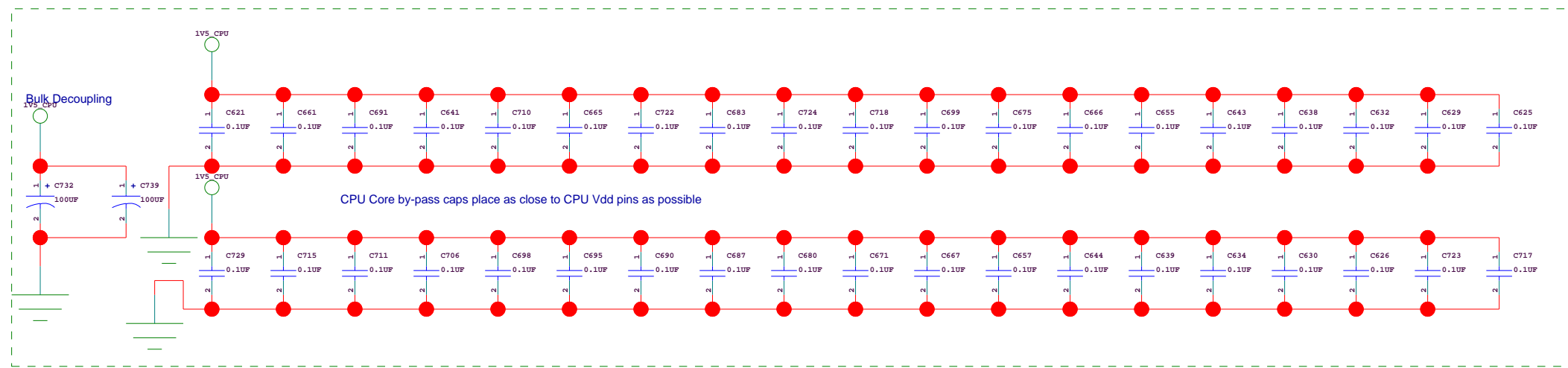
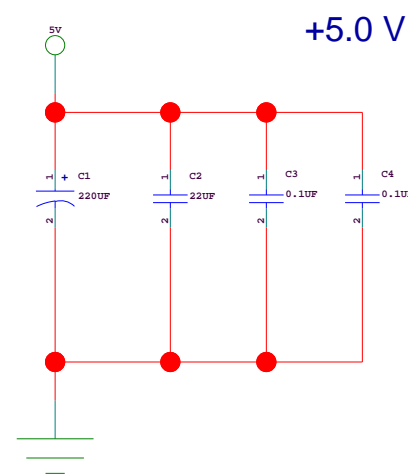
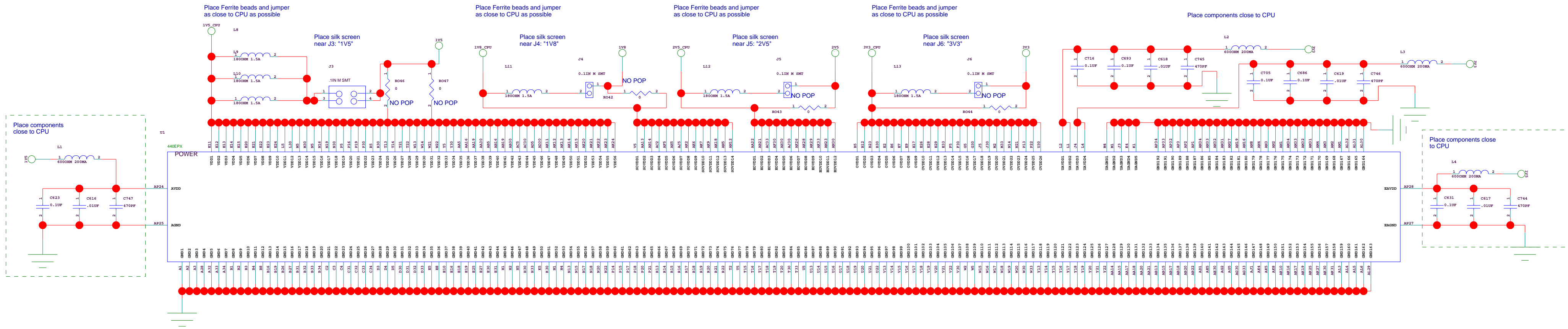






VALID CONFIGURATION MODES			
Configuration Mode	M[2:0]	Bus Width	CCLK Direction
Master Serial	000	1	Output
Master SPI	001	1	Output
Master BPI-Up	010	8, 16	Output
Master BPI-Down	011	8, 16	Output
Master SelectMAP	100	8, 16	Output
JTAG	101	1	Input (TCK)
Slave SelectMAP	110	8, 16, 32	Input
Slave Serial	111	1	Input





ROACH/iBOE2

COLLABORATORS:  
CASPER GROUP, UC BERKELEY  
NRAO, SOONERO  
BAAERAT, CAPE TOWN

10-15-2007\_14:28

PATH PATH

ROACH\_PPC\_POWER\_1

DOC NO: NRP-ADM-XXX-BD-0001

DESCRIPTION: RECONFIGURABLE OPEN ARCHITECTURE HW

10-15-2007\_14:28

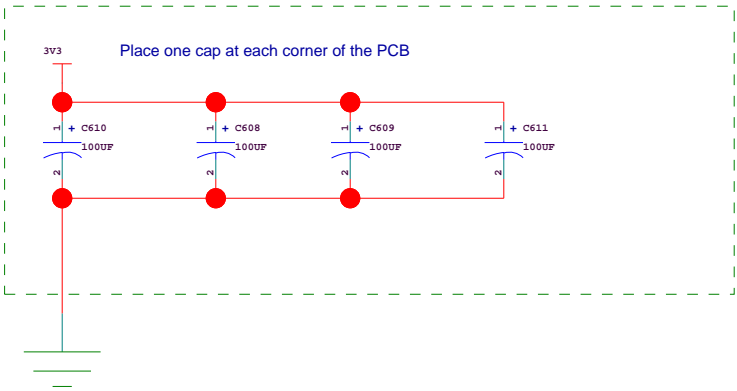
PATH PATH

10-15-2007\_14:28

10-15-2007\_14:28

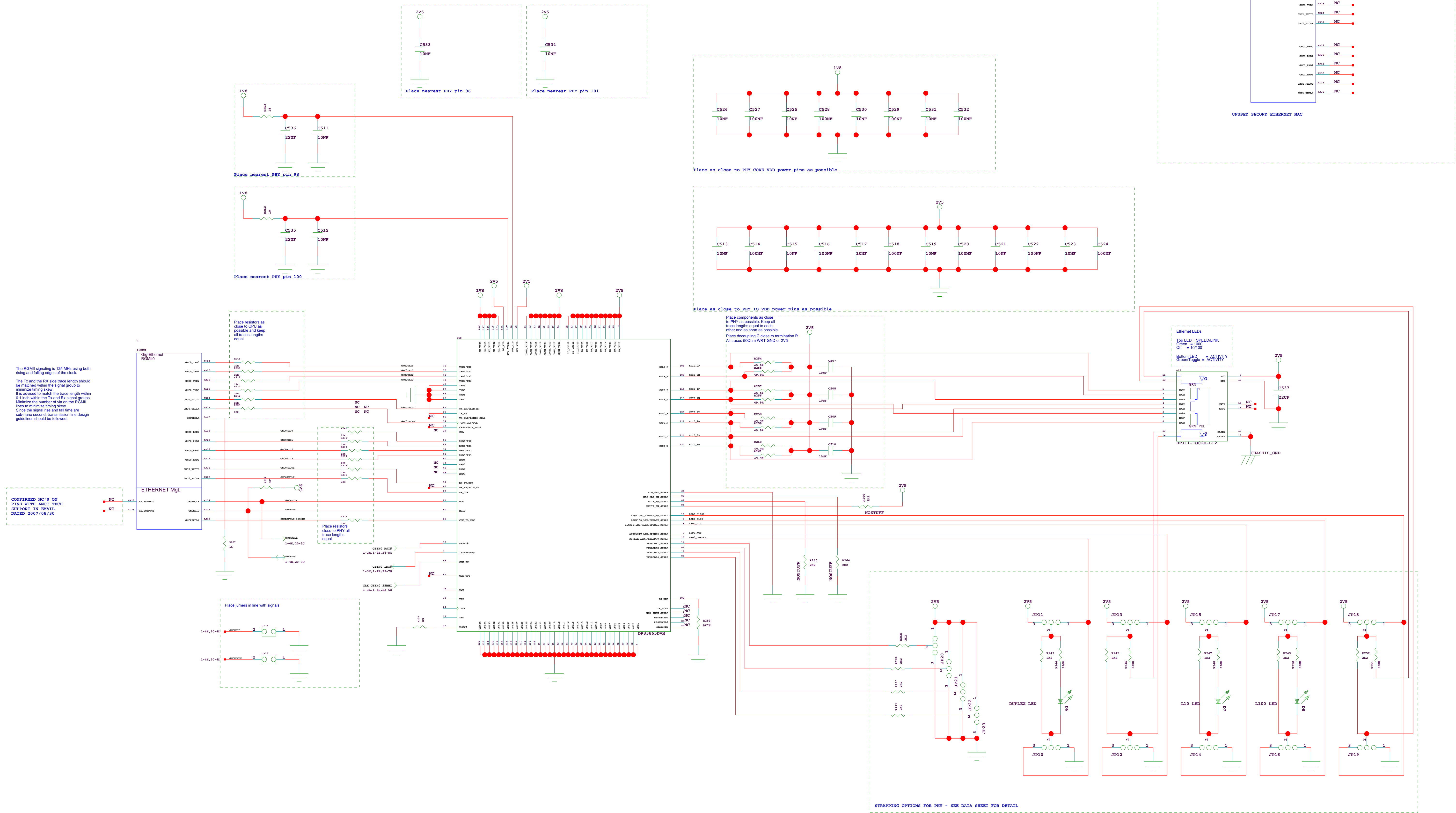


	A	B	C	D	E	F	G	H	J	K	L	M
7												
6			REMOVED 3V3 GENERATION									
5												
4		REMOVED +12V GENERATION			REMOVED -12V GENERATION							
3												
2												
1		REMOVED +1V GENERATION			REMOVED +2V5 GENERATION							
0												
	A	B	C	D	E	F	G	H	J	K	L	M



ROACH/iBOB2	ROACH_PPC_POWER_2	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN  <a href="http://casper.berkeley.edu/">http://casper.berkeley.edu/</a>	DOC NO NRF-ADM-XXX-SD-0001	REVISION A
	DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW	
	DRAWN: 10-15-2007_14:28 F KAPP	APPR: E BAUERMEISTER
PATH	PATH	SHEET 18 OF 25

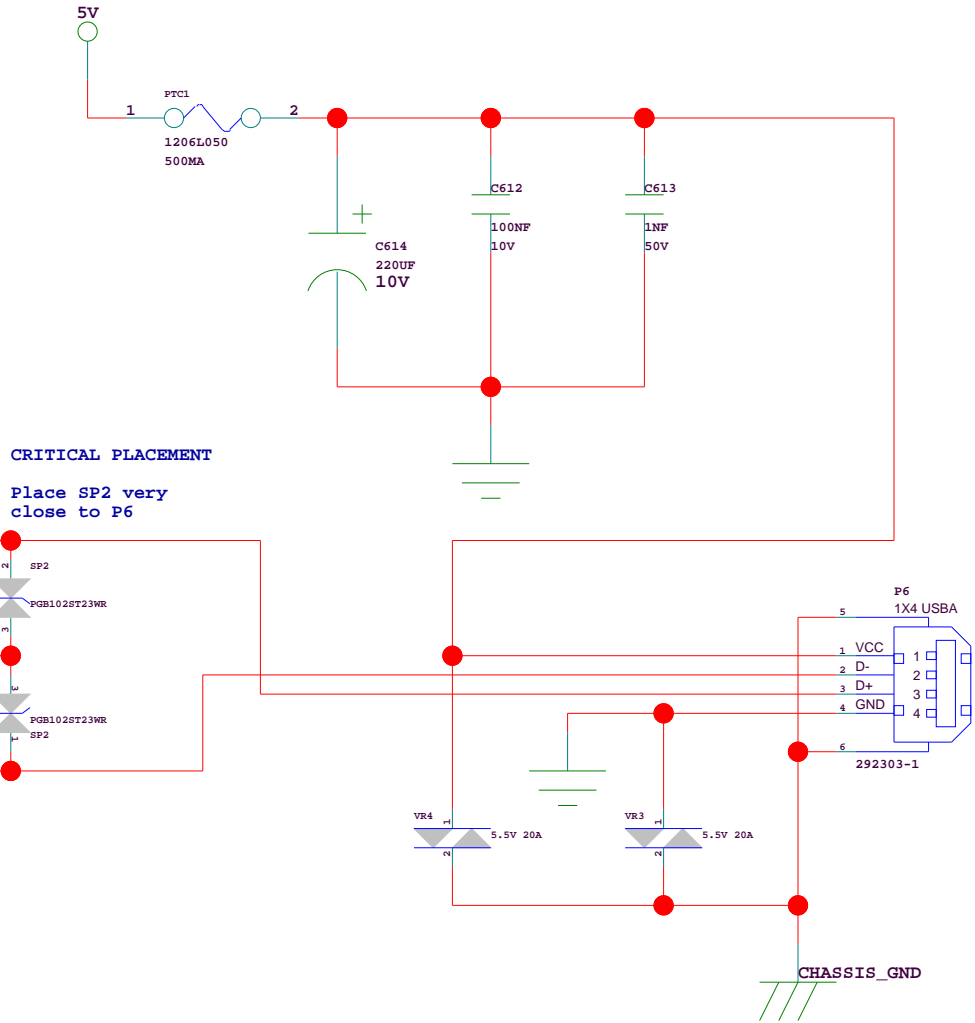
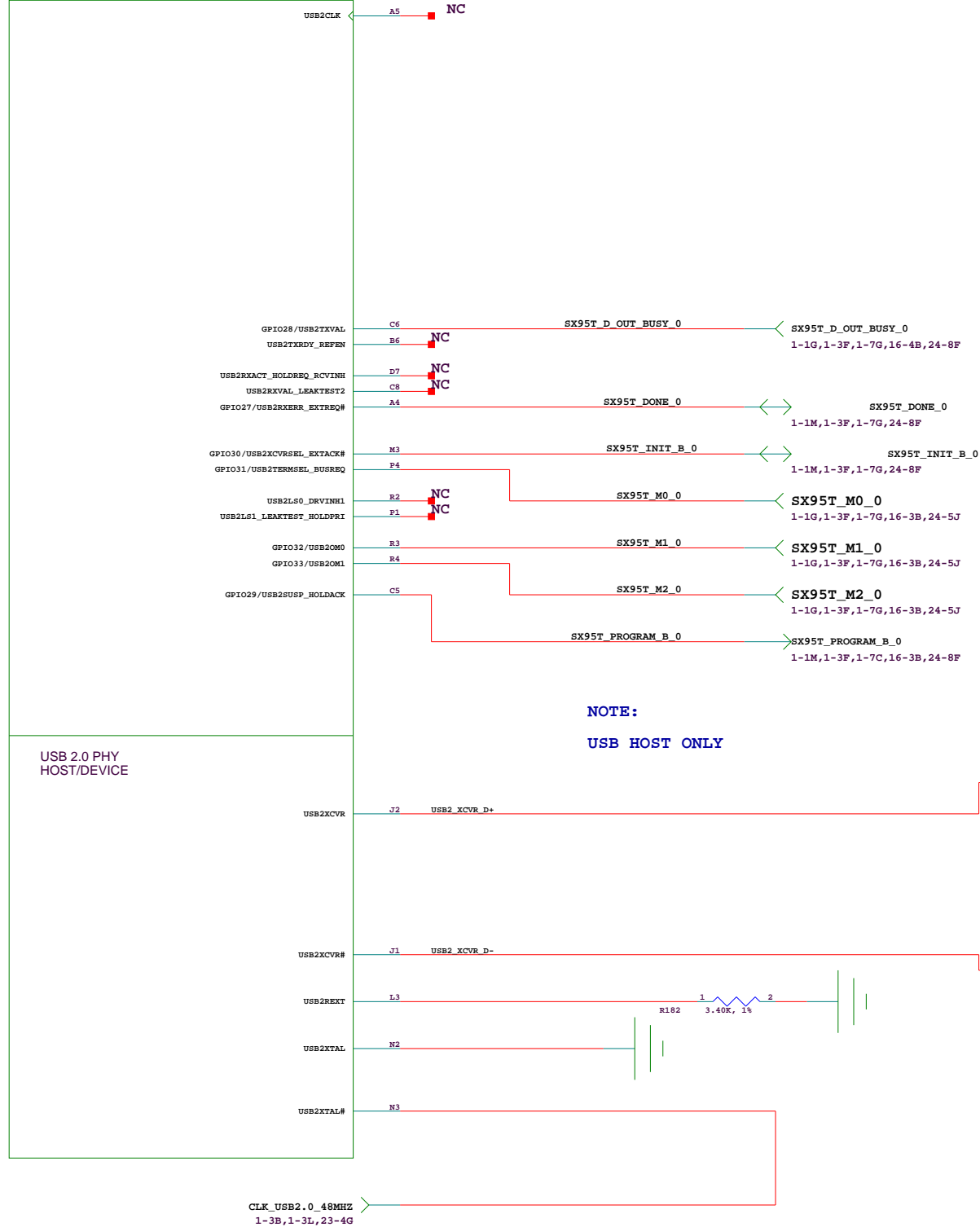




<b>ROACH/iBOB2</b>		<b>ROACH_PFC_ETH1</b>	
COLLABORATORS:		DOC NO	REVISION
CAPSER GROUP, UC BERKELEY BRNO, CROBORG meerkat, CAPS TOWN		NRP-ADM-XXX-ED-0001	A
DESCRIPTION		RECONFIGURABLE OPEN ARCHITECTURE SW	
<a href="http://capsr.berkeley.edu/">http://capsr.berkeley.edu/</a>		ISSUED:	DATE:
10-15-2007.14:28		F KAPP	
PATH PATH		CHECKED:	SHEET
		E BAUMENISTER	20 OF 2



U1  
USB 2.0 DEVICE  
40EPA



## ROACH/iBOB2

### ROACH\_PPC\_USB

COLLABORATORS:  
CASPER GROUP, UC BERKELEY  
NRAO, SOCORRO  
meerKAT, CAPE TOWN  
<http://casper.berkeley.edu/>

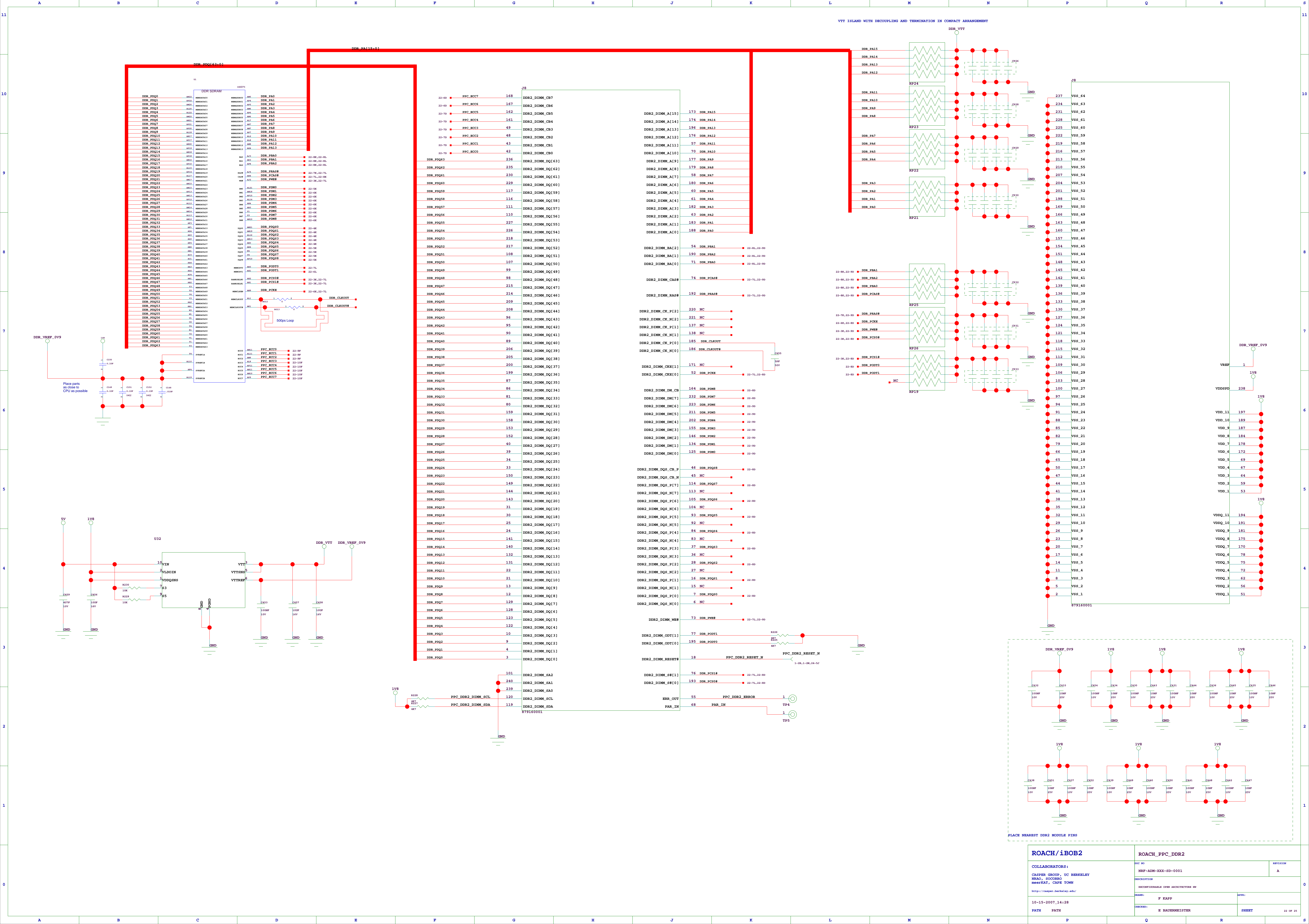
DOC NO  
NRF-ADM-XXX-SD-0001  
DESCRIPTION  
RECONFIGURABLE OPEN ARCHITECTURE HW

REVISION  
A

10-15-2007\_14:28  
PATH PATH

DRAWN: F KAPP  
CHECKED: E BAUERMEISTER

APPR:  
SHEET

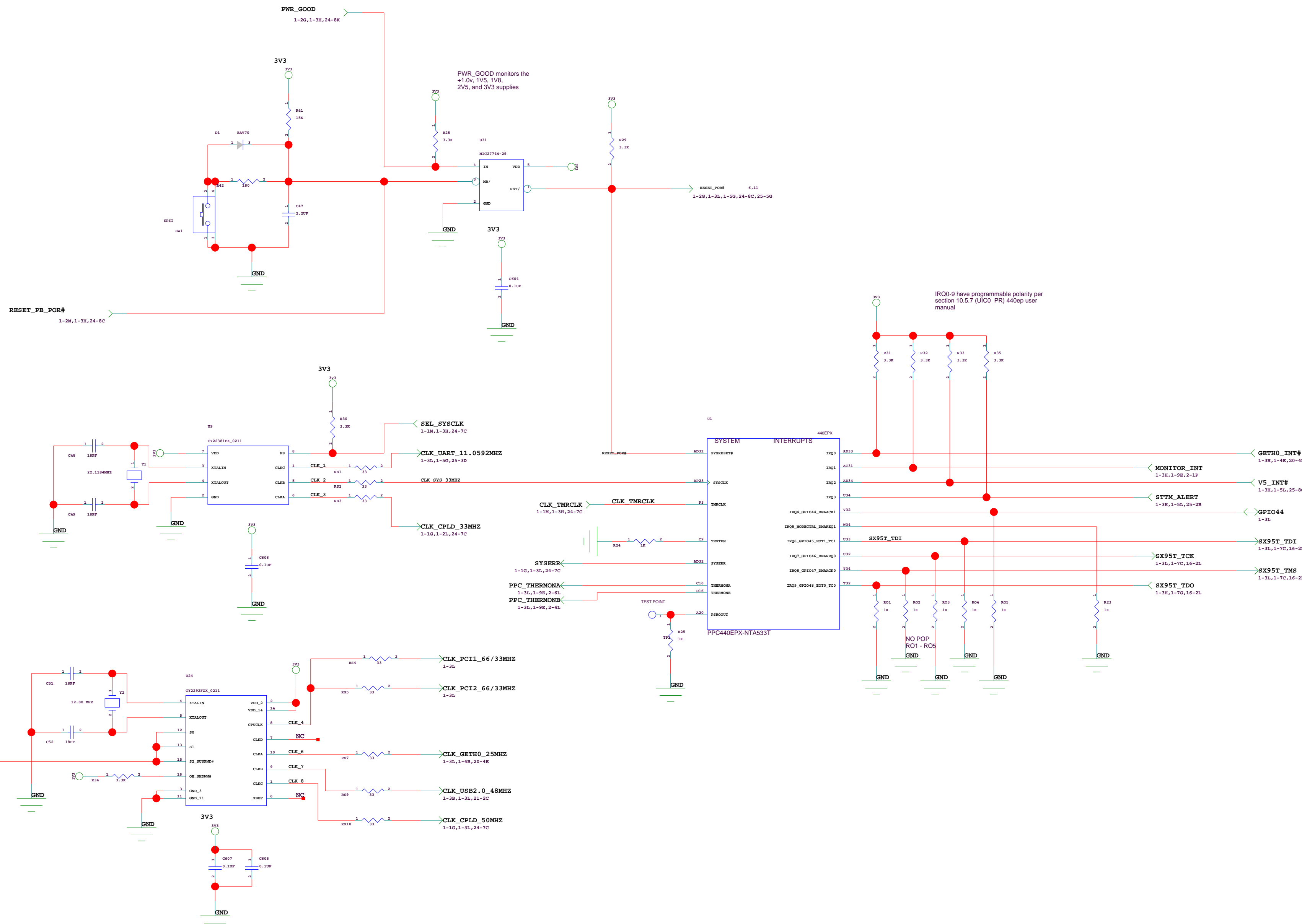


Critical Placement and Route  
Clock Rules:

Clock Rules:  
CLK\_UART\_11.0592MHz = as short as possible  
CLK\_SYS\_33MHz = as short as possible  
CLK\_CPLD\_33MHz = CLK\_SYS\_33MHz

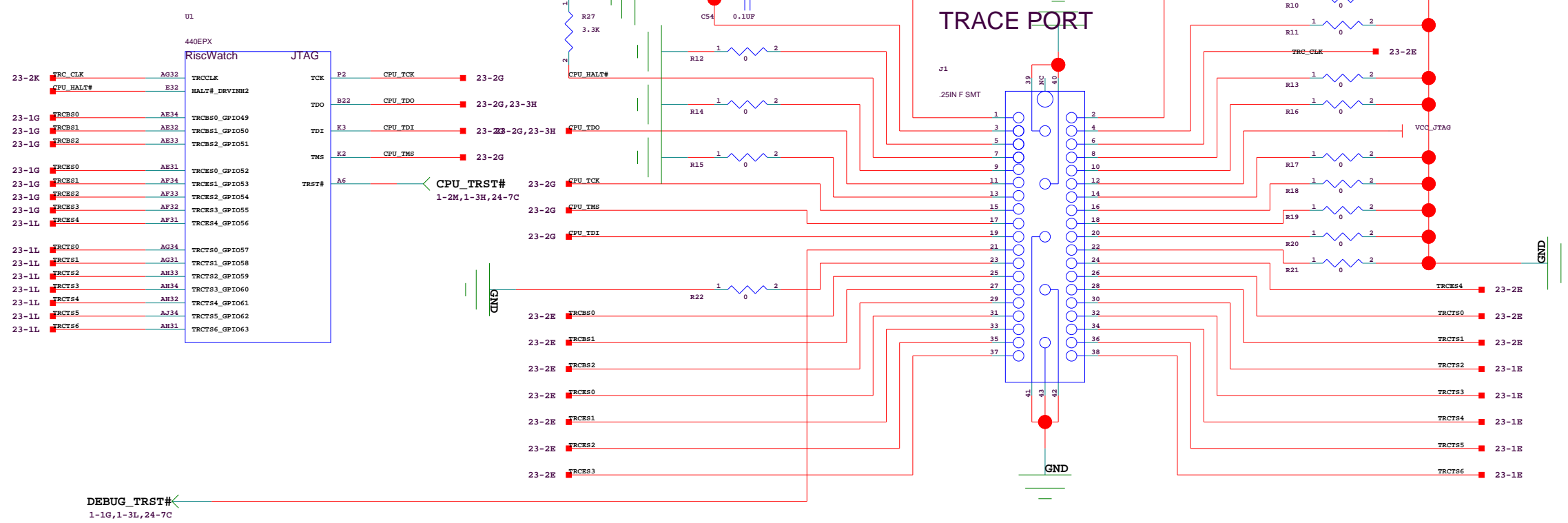
Critical Placement and Route  
Clock Rules:

Clock Rules:  
CLK\_PC13\_66.33MHz = as short as possible  
CLK\_PC12\_66.33MHz = CLK\_PC13\_66.33MHz  
CLK\_PC11\_66.33MHz = CLK\_PC12\_66.33MHz + 2.5°  
CLK\_GETH0\_25MHz = as short as possible  
CLK\_GETH1\_25MHz = CLK\_GETH0\_25MHz  
CLK\_CPLD\_50MHz = as short as possible  
CLK\_USB2\_0\_48MHz = as short as possible  
CLK\_USB2\_0\_12MHz = as short as possible



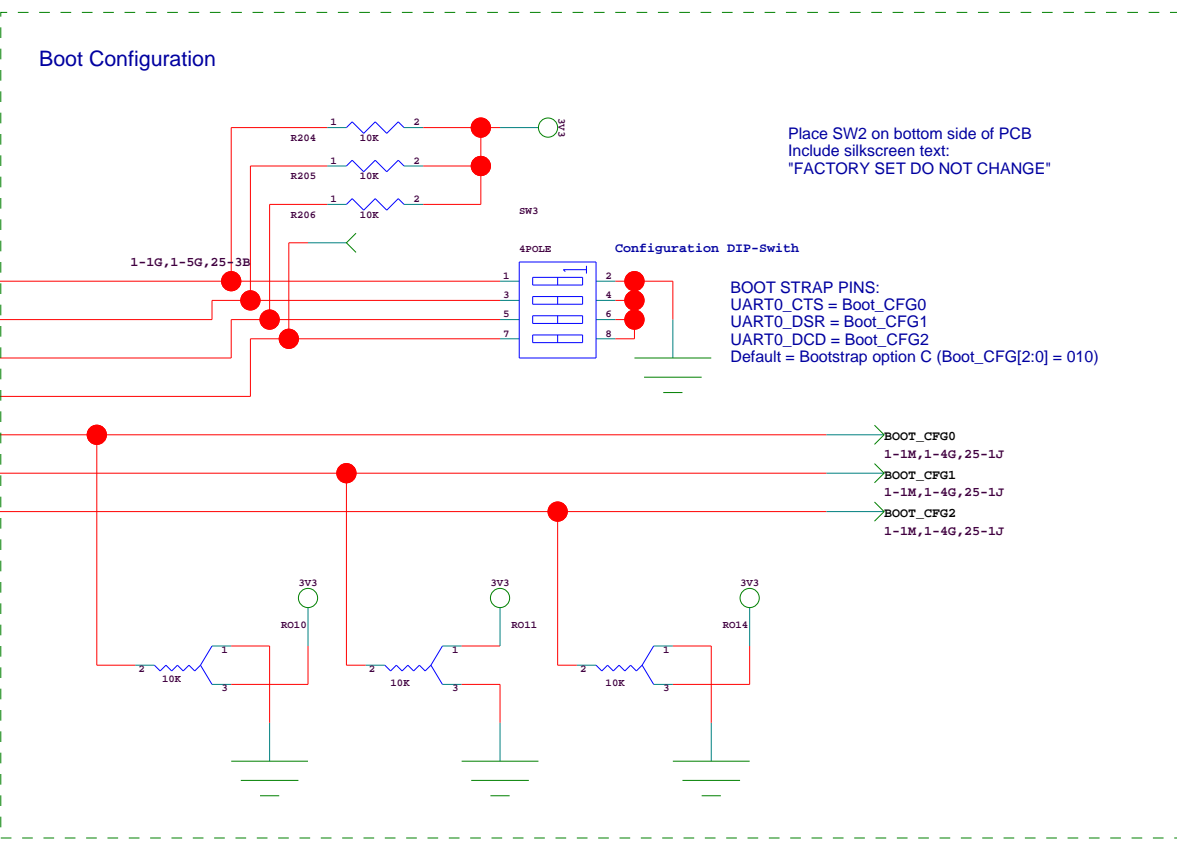
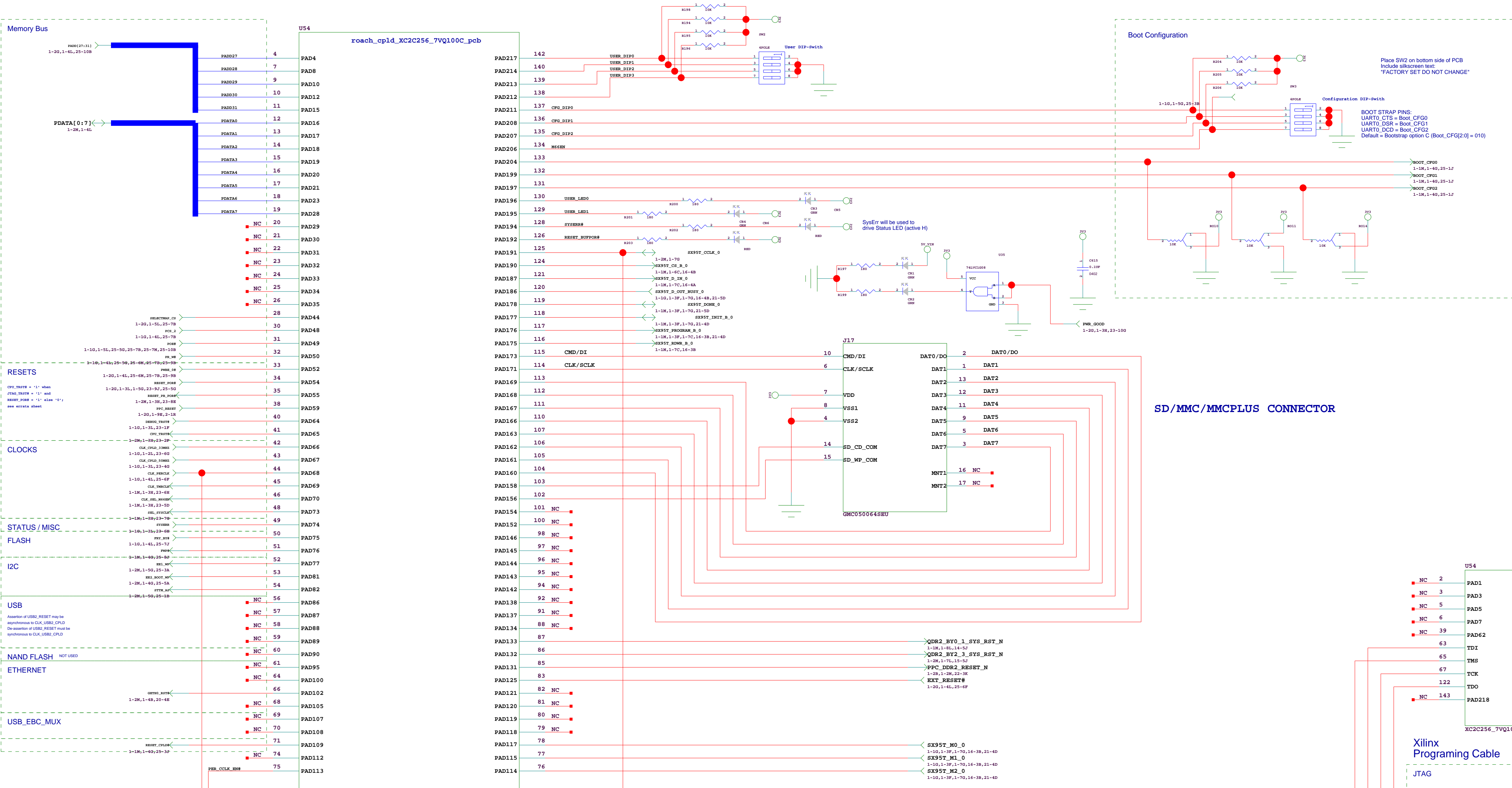
TRACE & JTAG CONNECTORS

Critical placement and routing  
of the Trace connector and nets.  
Up to CPU frequency!

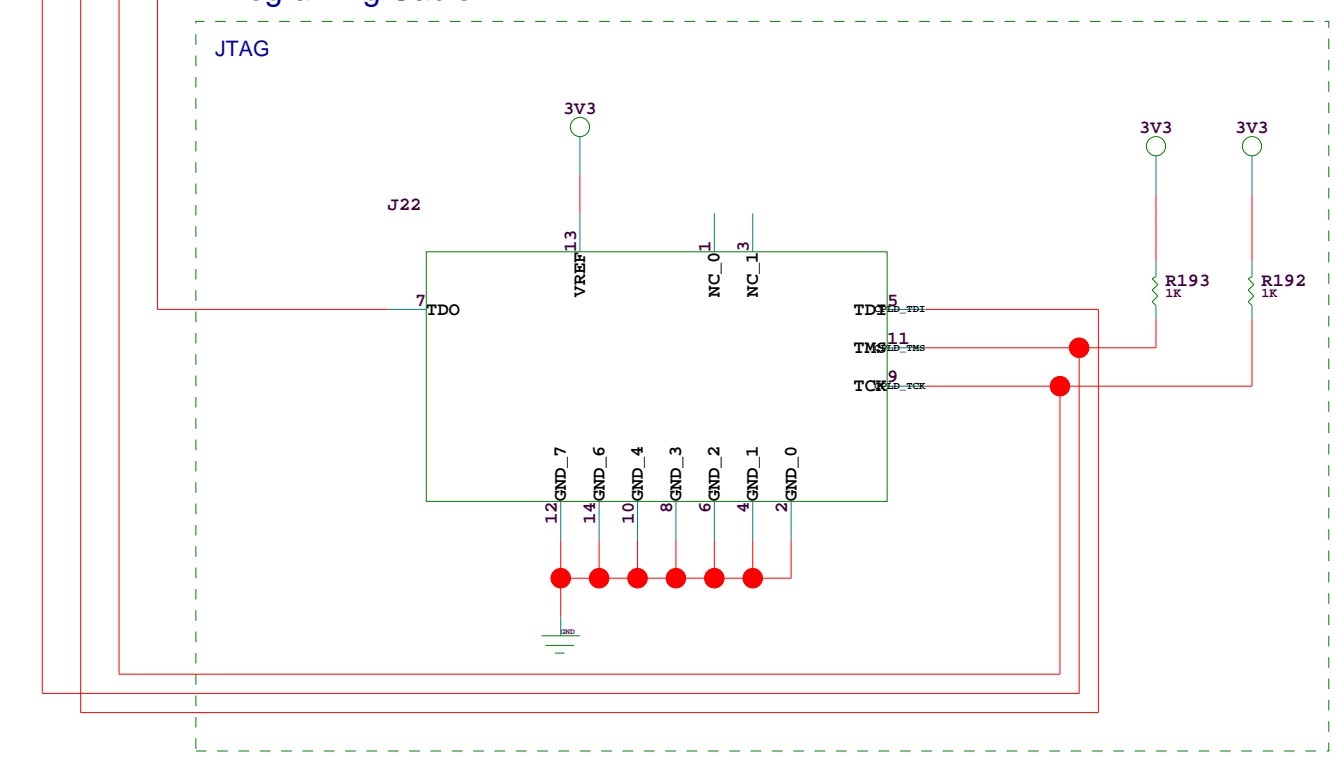
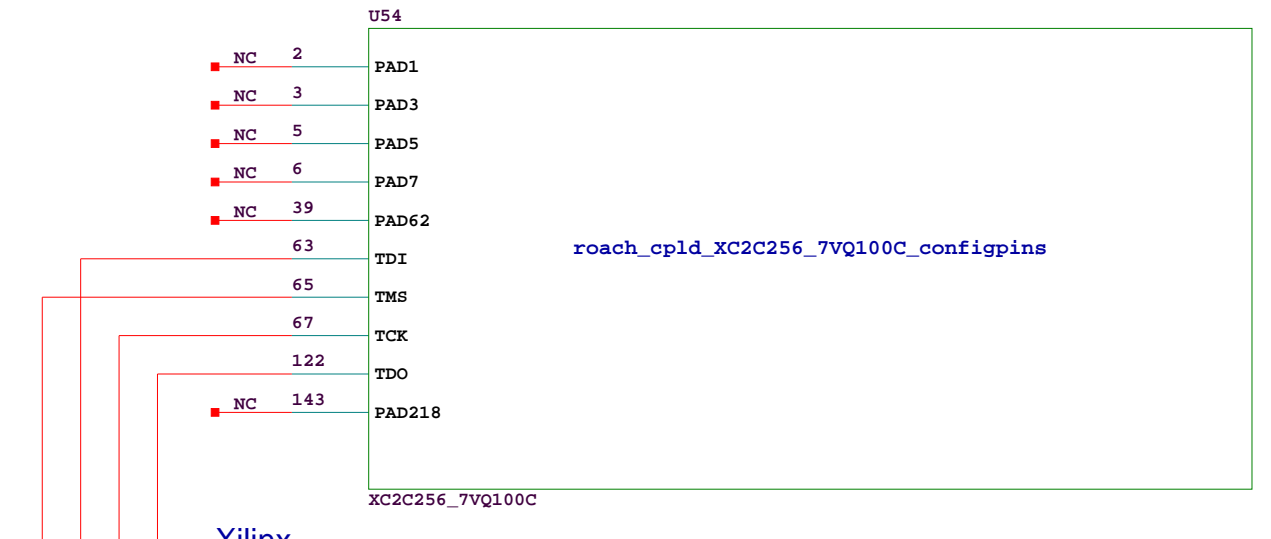


ROACH/iBOE2		ROACH_PPC_TST_CLK_IO	
COLLABORATORS:		DOC NO	REVISION
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-SD-0001	A
HW, ©COCORO		DESCRIPTION	
BARKAT, CAPE TOWN		RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/		DESIGN:	APP:
10-15-2007_14:28		F KAPP	
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		E BAUERMEISTER	23 OF 2

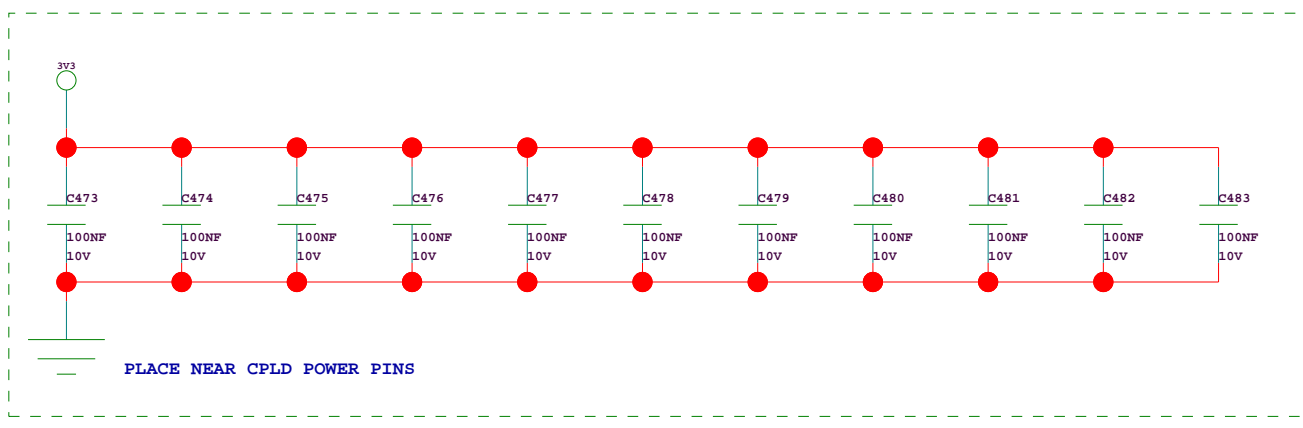
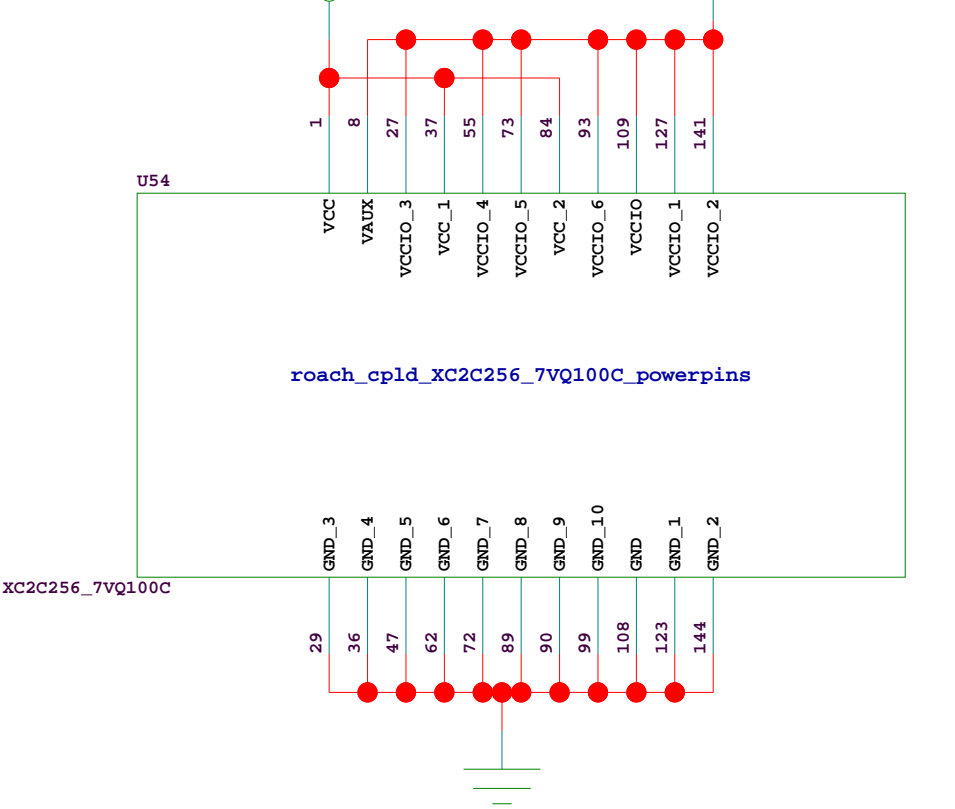
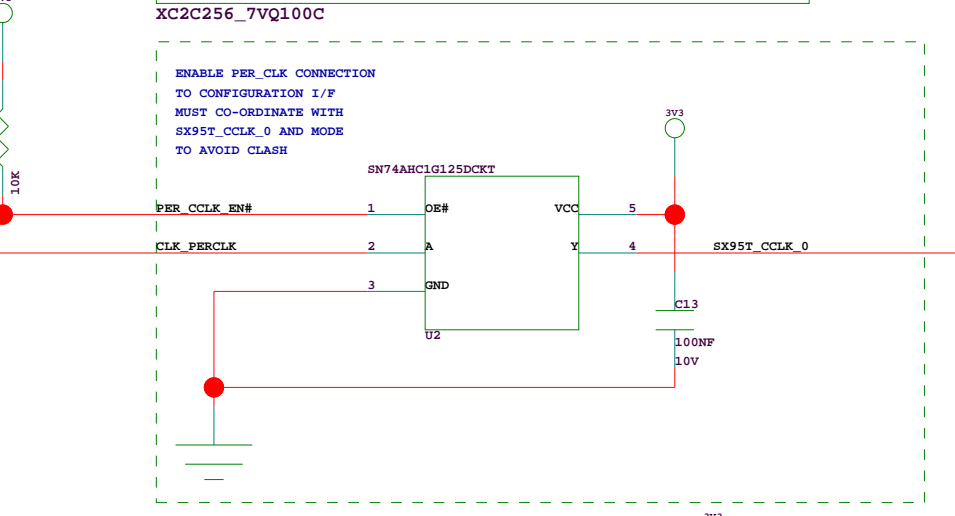




SD/MMC/MMCPLUS CONNECTOR



PLACE NEAR CPLD JTAG CONNECTOR



PLACE NEAR CPLD POWER PINS

ROACH/iBOE2			ROACH_PPC_CPLD	
COLLABORATORS:			DOC NO	REVISION
CASPER GROUP, UC BERKELEY NRAO, SOCCORRO MesaCAT, CAPE TOWN			NRF-ADM-XXX-SD-0001	A
DESCRIPTION			RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/			DESIGNER	APPR
10-15-2007_14:28			F KAPP	
PATH    PATH			CHECKED: R BAUERMEISTER	SHEET
				24 OF 25



