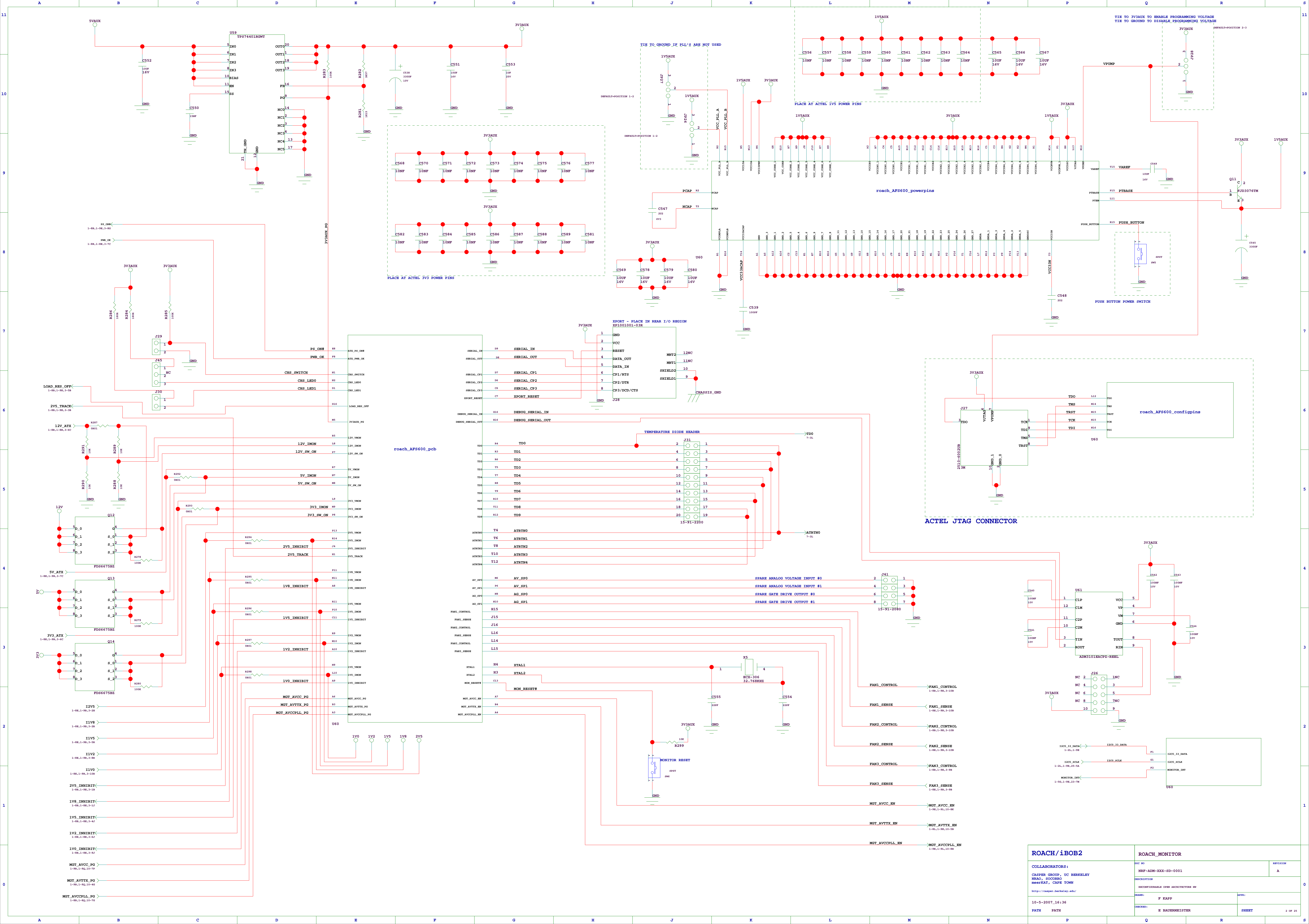
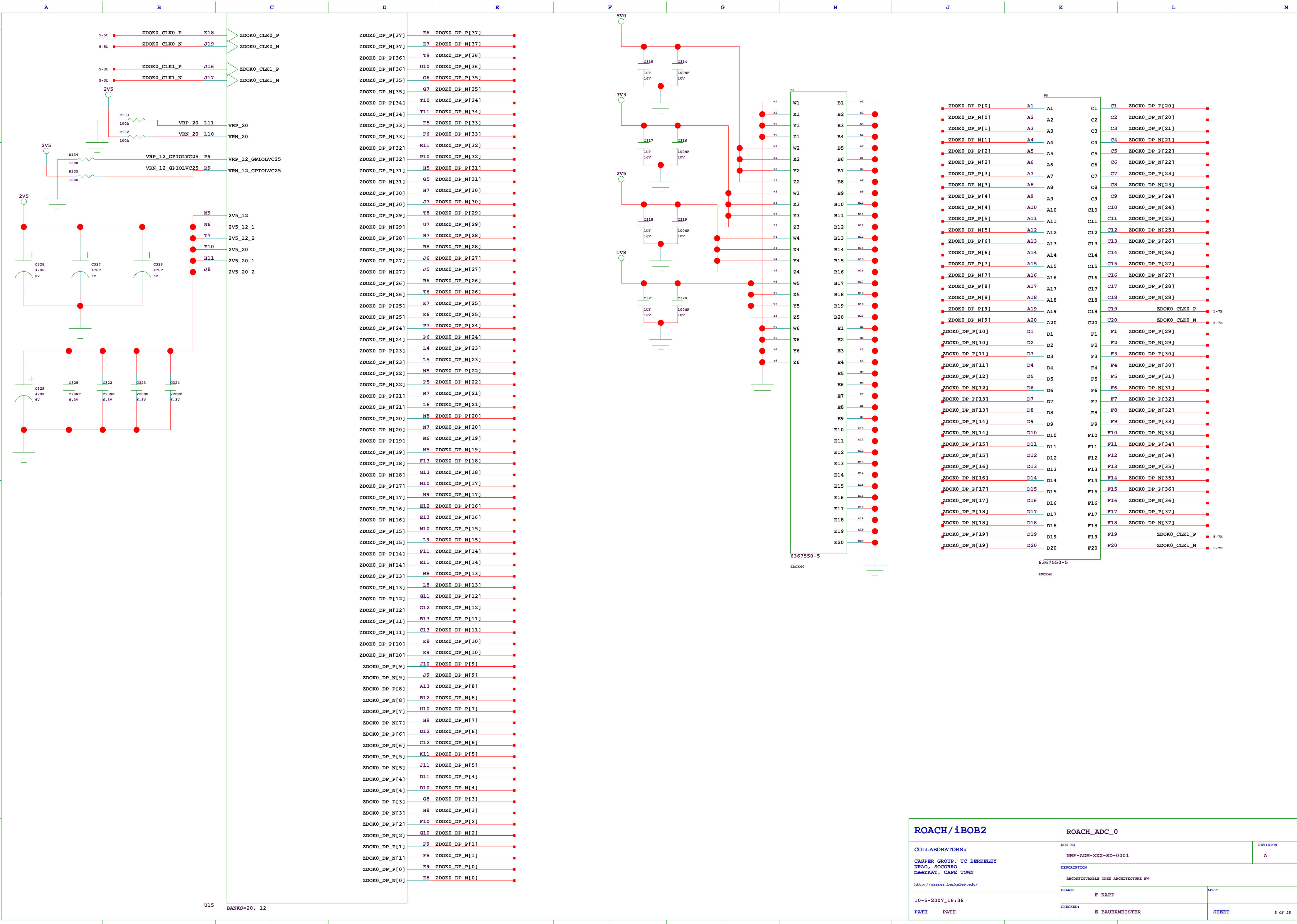
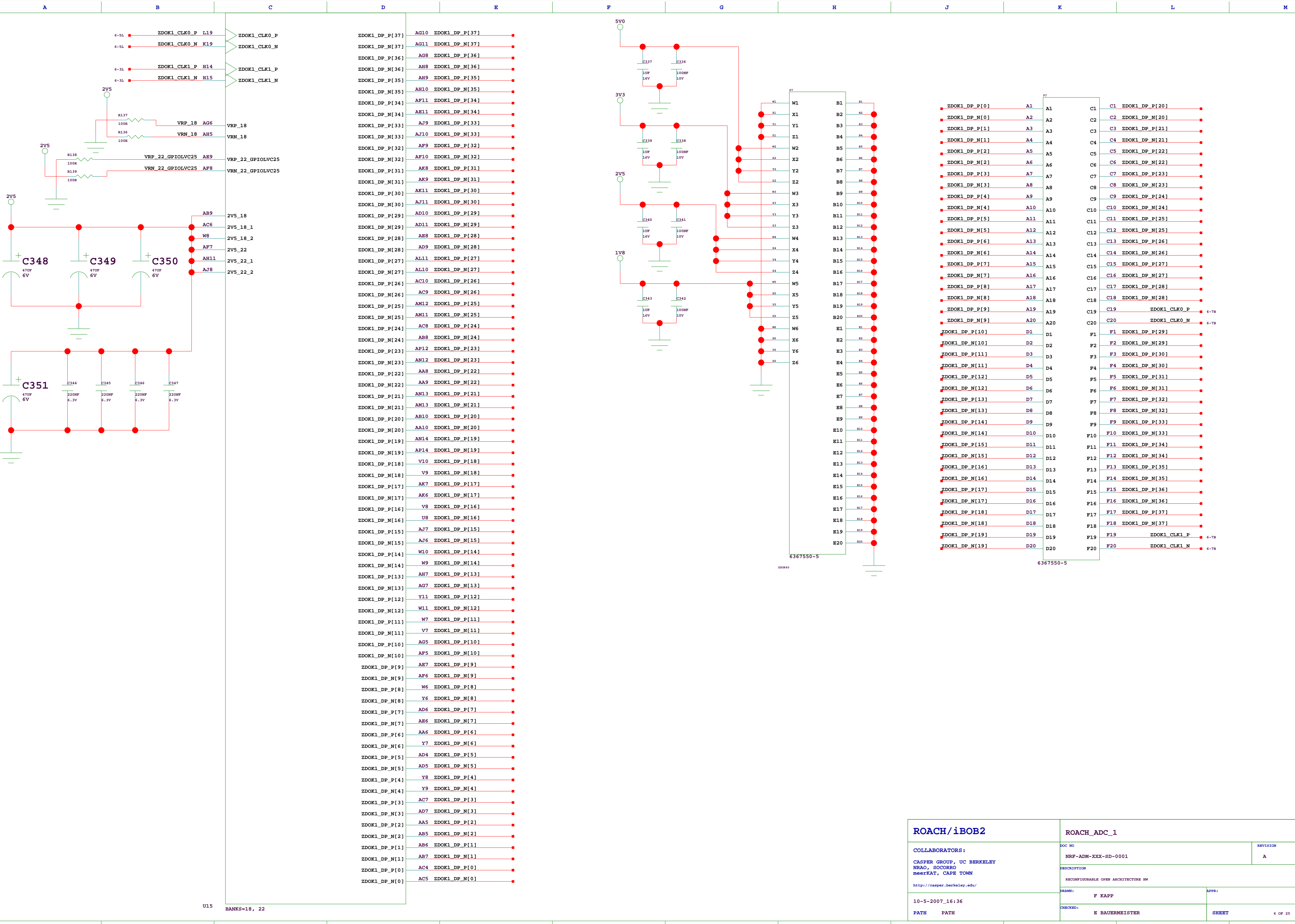


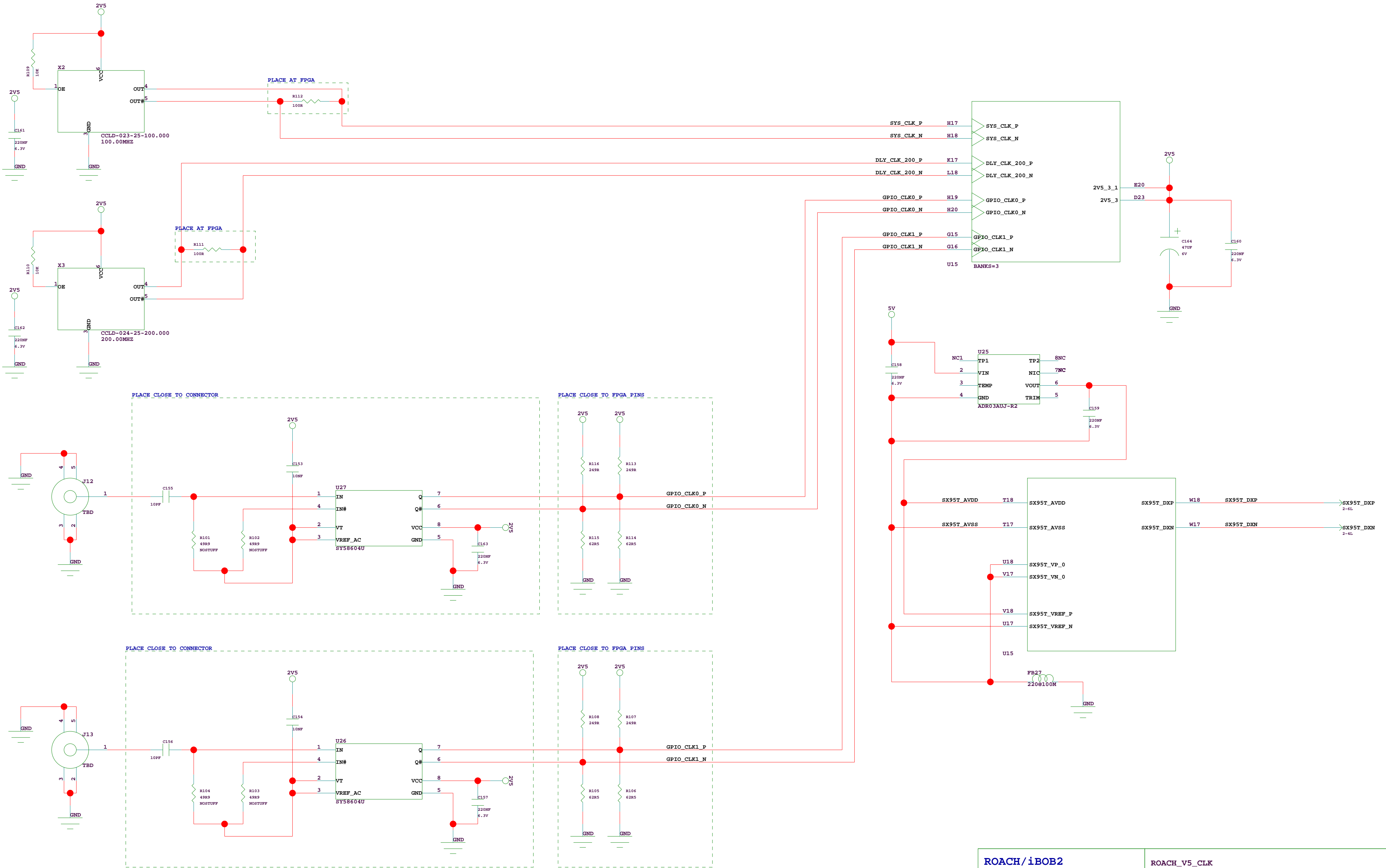
STIENNE BAUSERMKISTER
HENRY CHEN
STEVE DURAND
FRANCOIS KAPP
ALAN LANGMAN
GEORGE PECK
MIKE REYNELL
HAYDEN SO
DAN WERTHNER

ROACH/iBOB2		ROACH_TOP	
COLLABORATORS:		REVISION	
CASPER GROUP, UC BERKELEY HEAD, COORDINATOR MEETKAT, CAPE TOWN		A	
http://casper.berkeley.edu/		DESCRIPTION	
		RECONFIGURABLE OPEN ARCHITECTURE HW	
10-5-2007 16:36		NAME:	
PATH PATH		F KAPP	
		APPR:	
		CHECKED:	
		E BAUMEISTER	
		SHORT	
		1 OF 1	

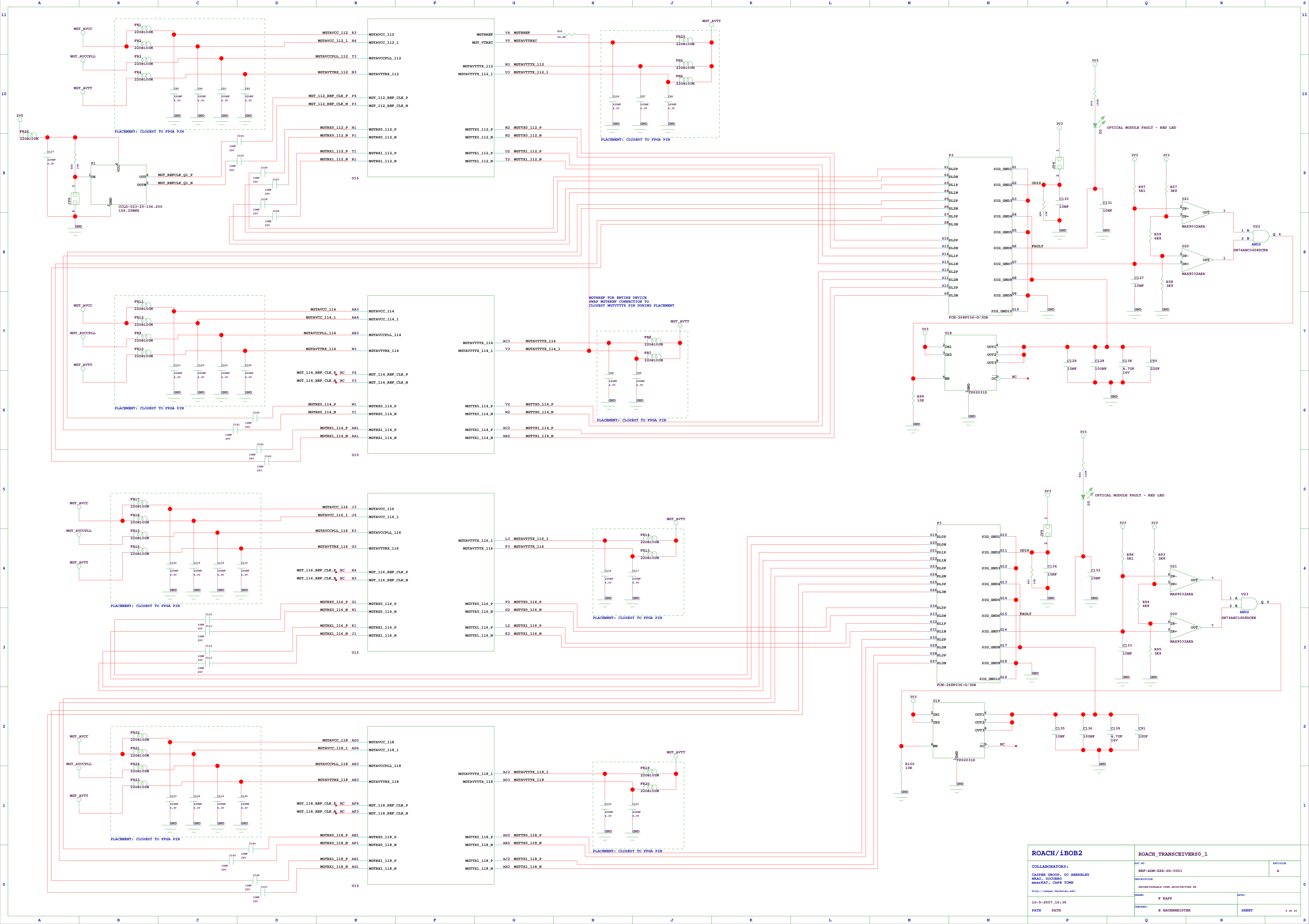


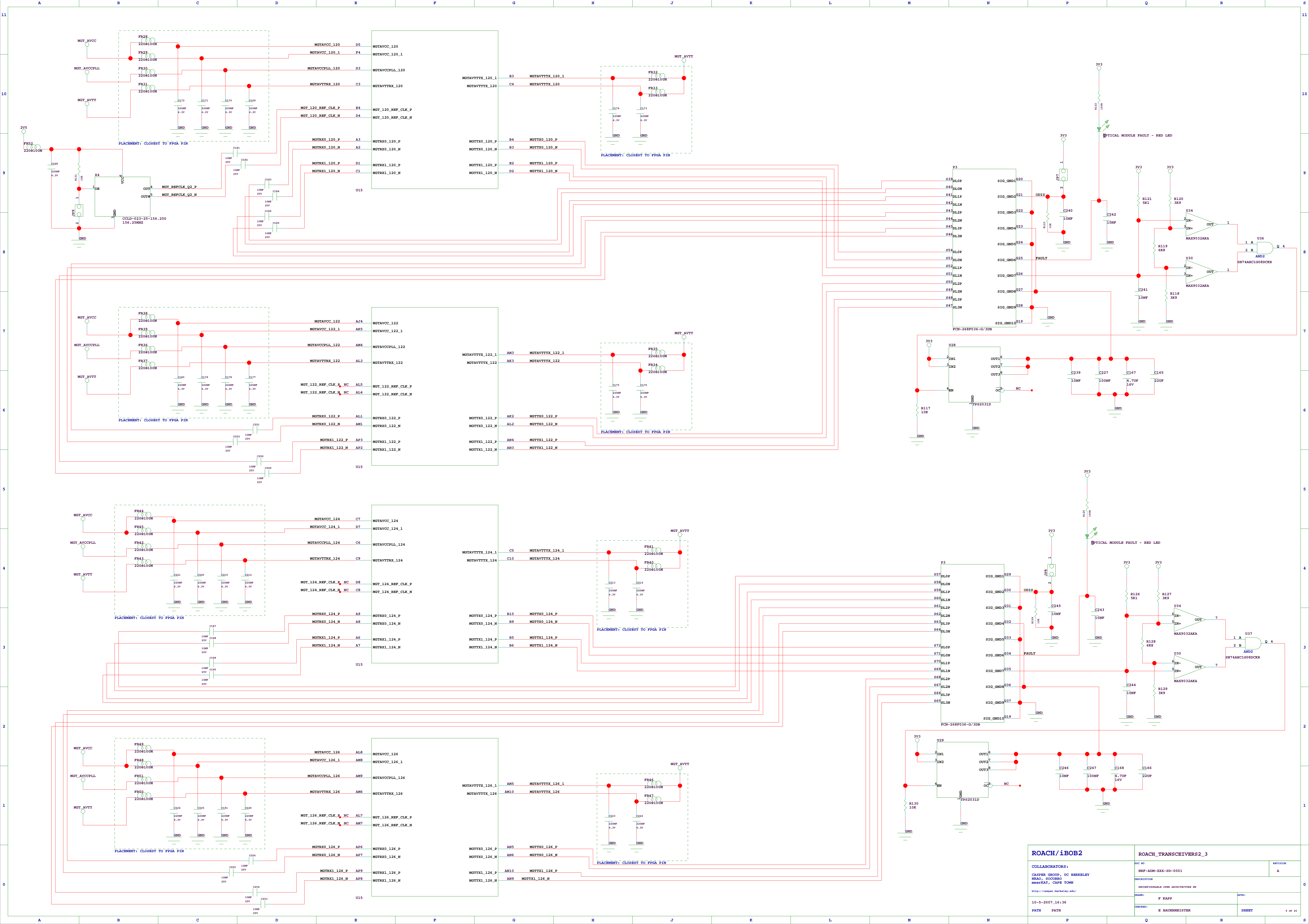


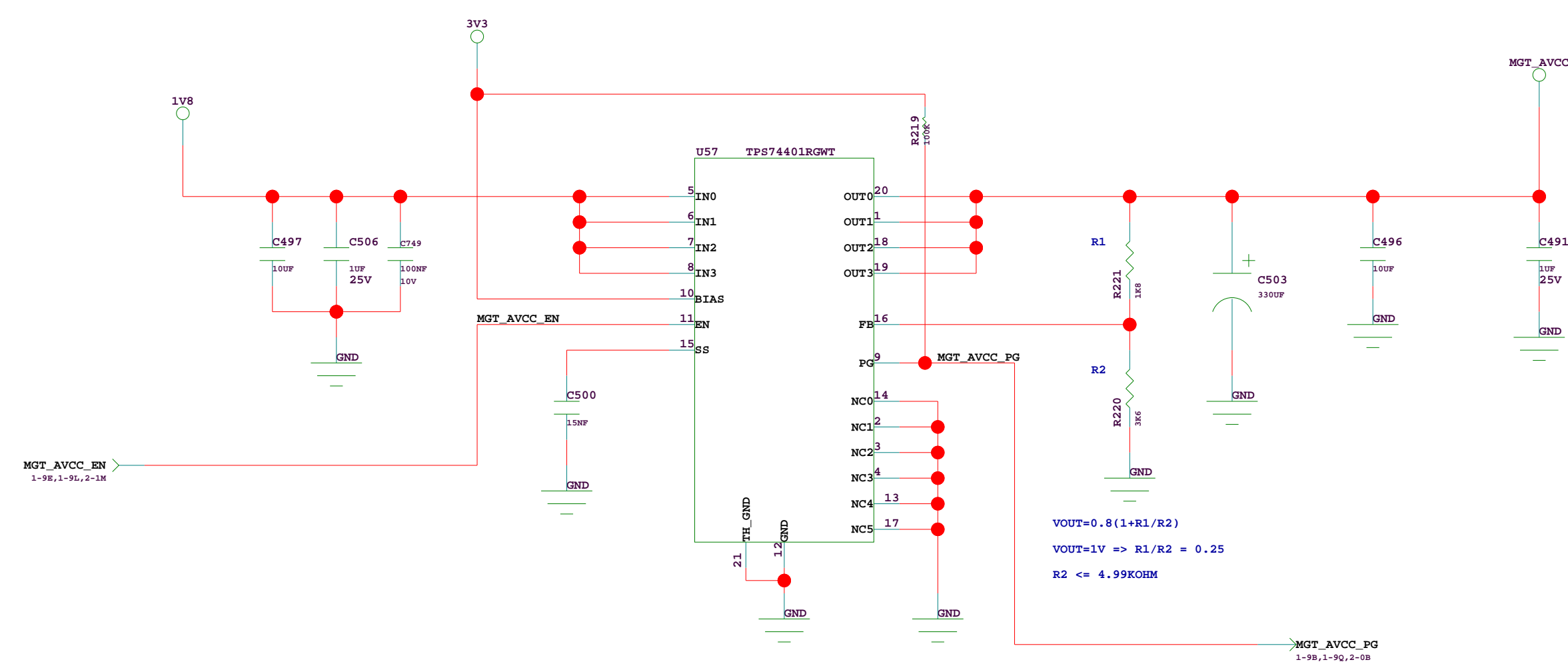
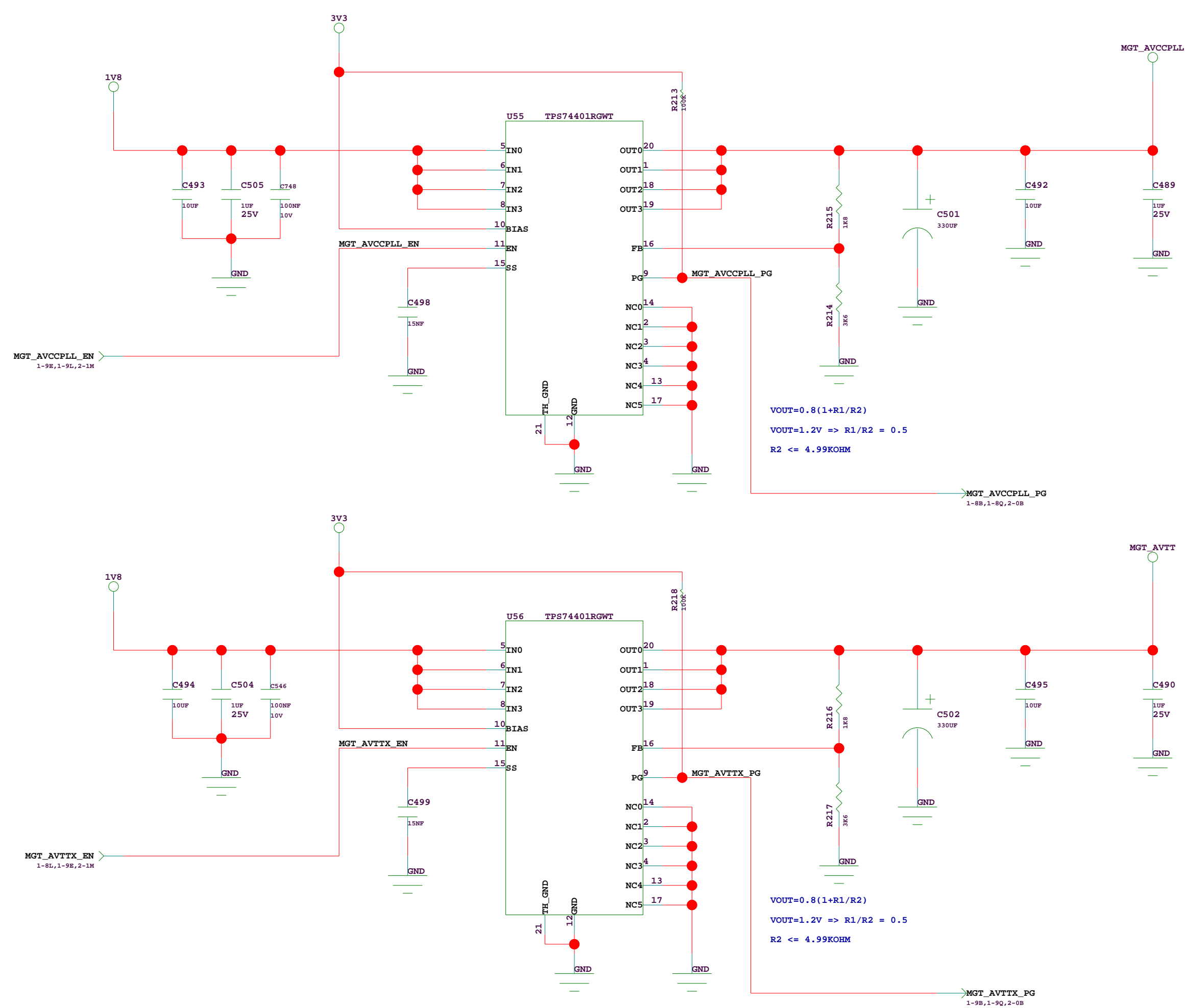




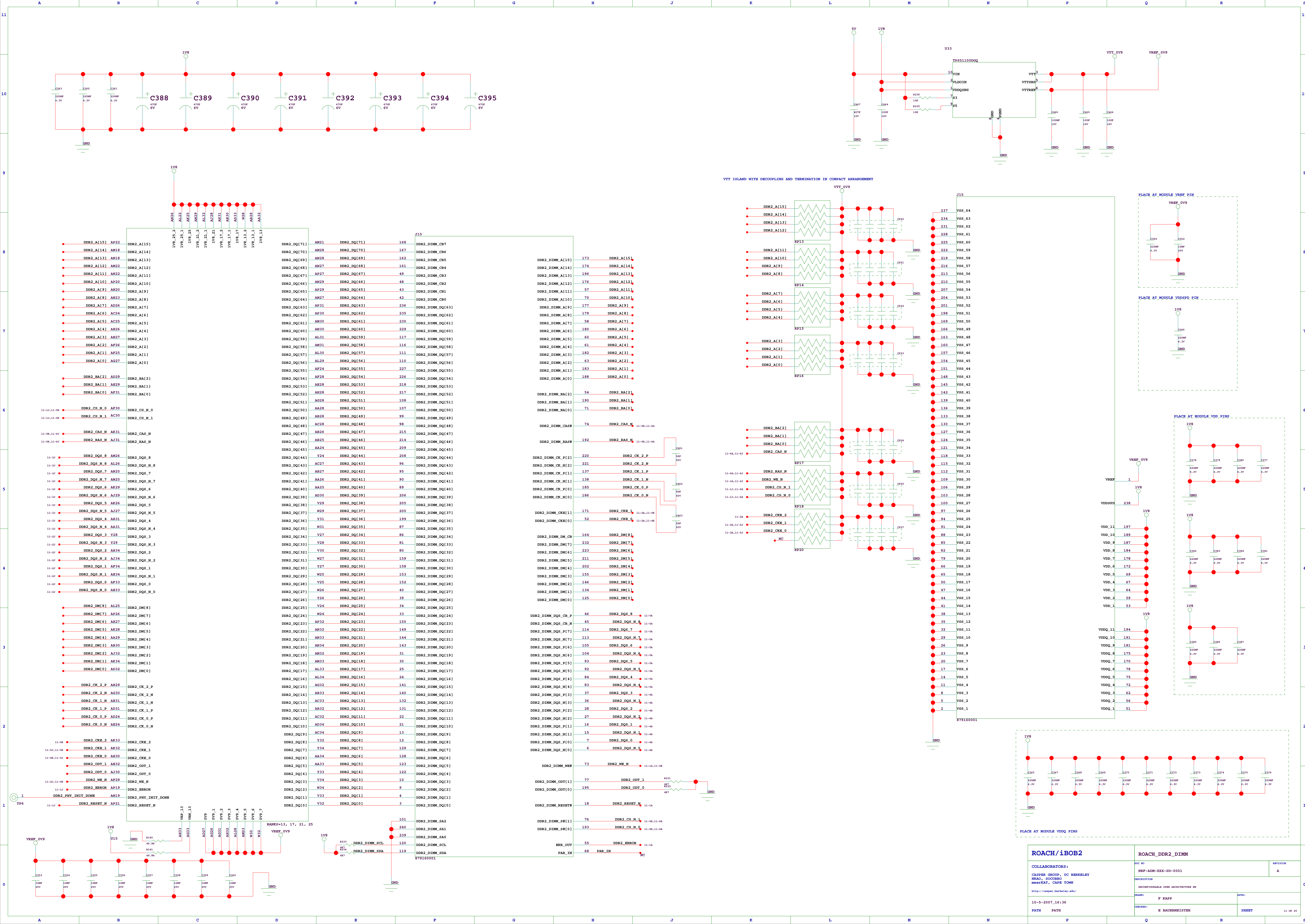
ROACH/iBOB2		ROACH_V5_CLK	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN http://casper.berkeley.edu/		DOC NO NRF-ADM-XXX-SD-0001	REVISION A
		DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW	
		DRAWN: F KAPP	APPR:
10-5-2007_16:36		CHECKED: E BAUERMEISTER	SHEET
PATH	PATH		7 OF 25

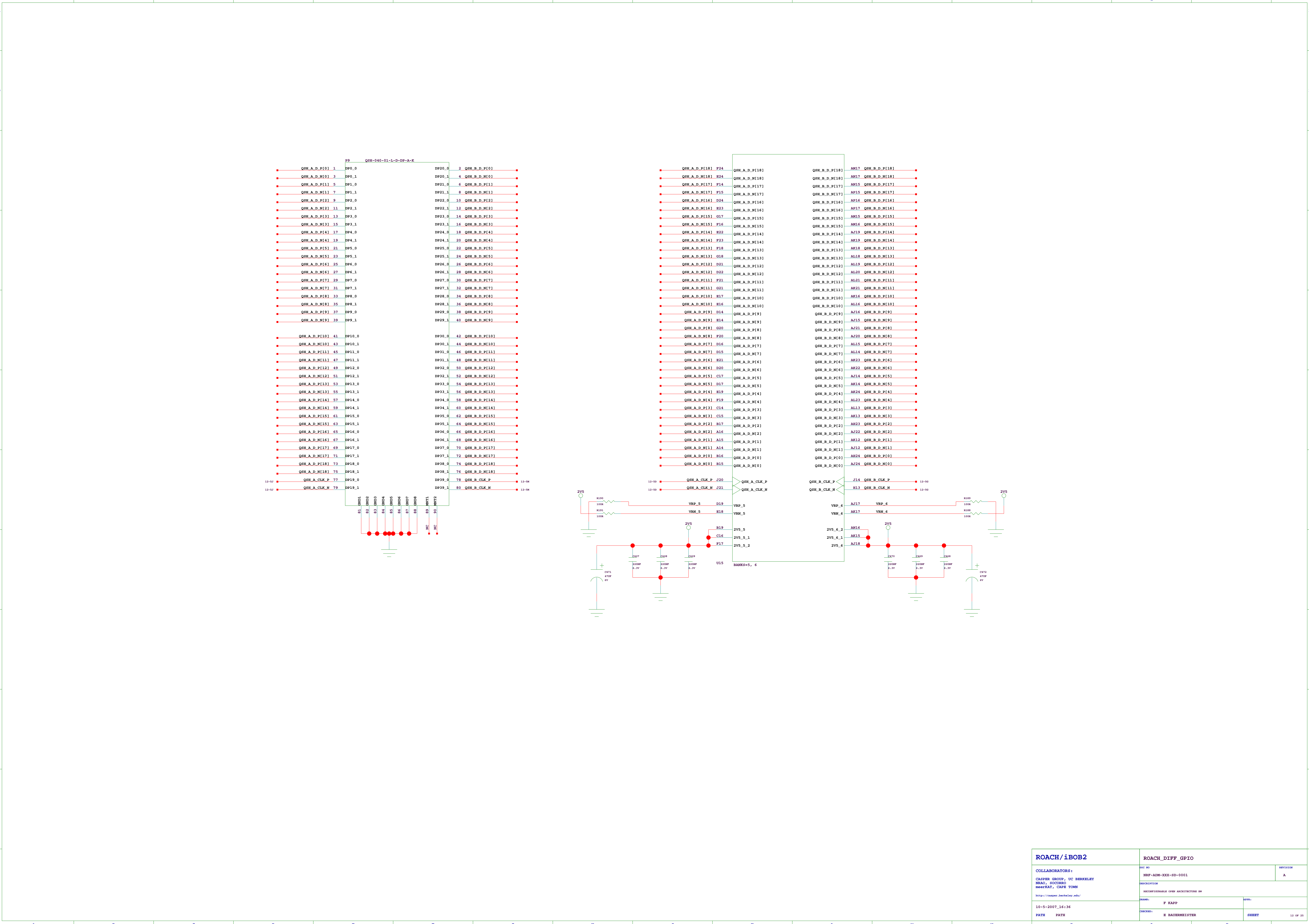




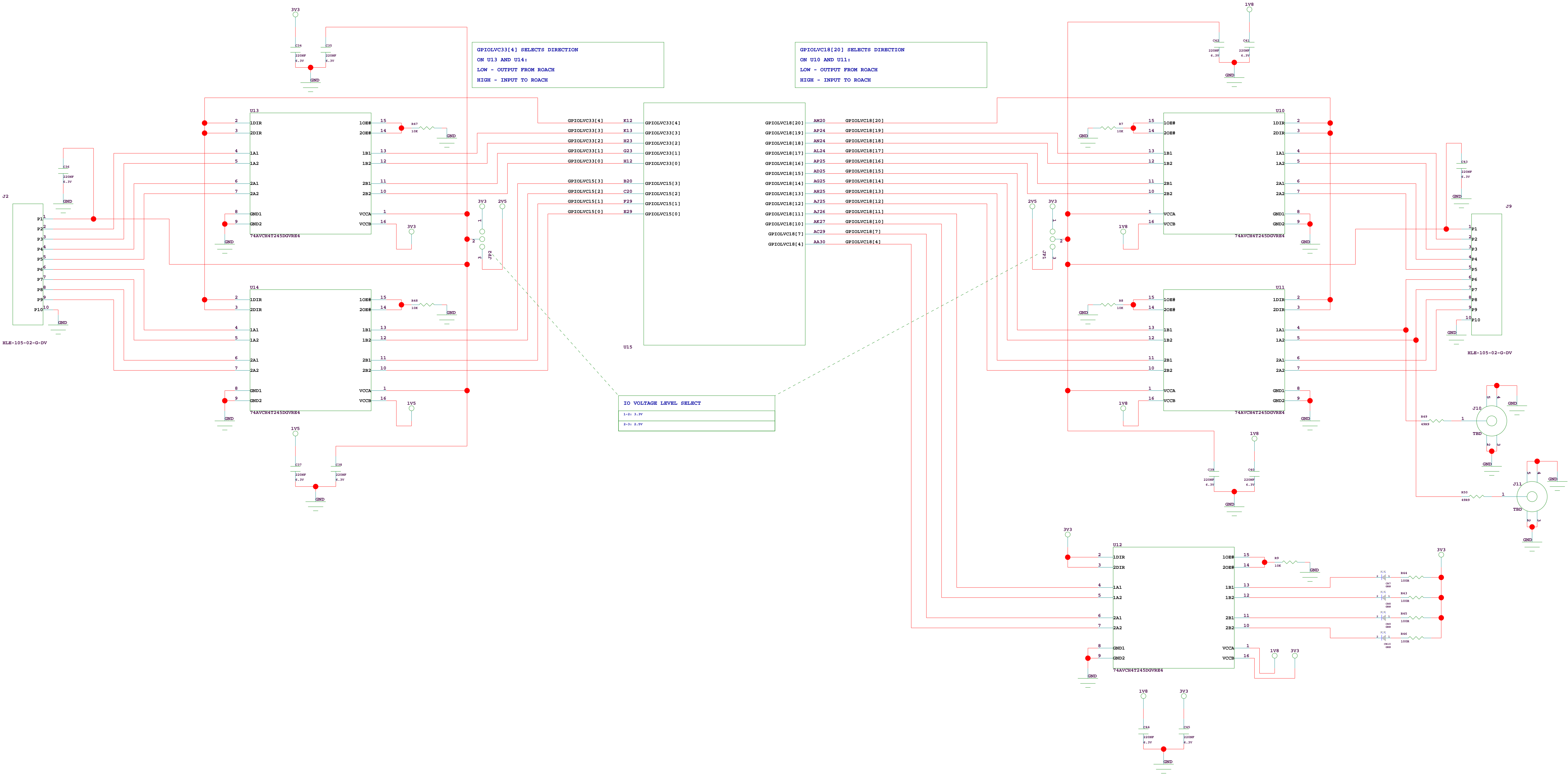


ROACH/iBOB2		ROACH_TRANSCEIVERS_PSU	
COLLABORATORS:		DOC NO	REVISION
CAPSER GROUP, UC BERKELEY HEAD, SCORED MEMERAT, CAPE TOWN		REF-ADM-XXX-SD-0001	A
http://capers.berkeley.edu/		DESCRIPTION	
10-5-2007_16:136		RECONFIGURABLES OPEN ARCHITECTURE SW	
PATH PATH		NAME:	APPS:
		F KAPP	
		CHECKED:	SHEET
		E BAUMHEISTER	10 OF 2

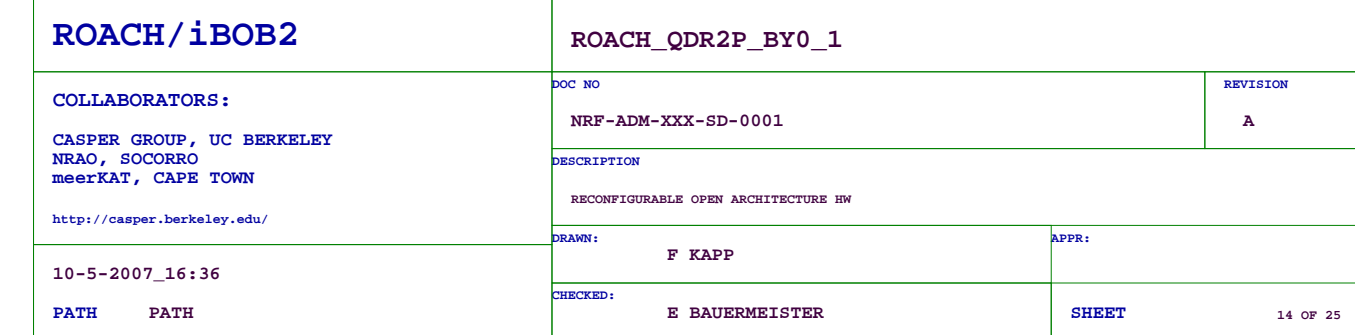
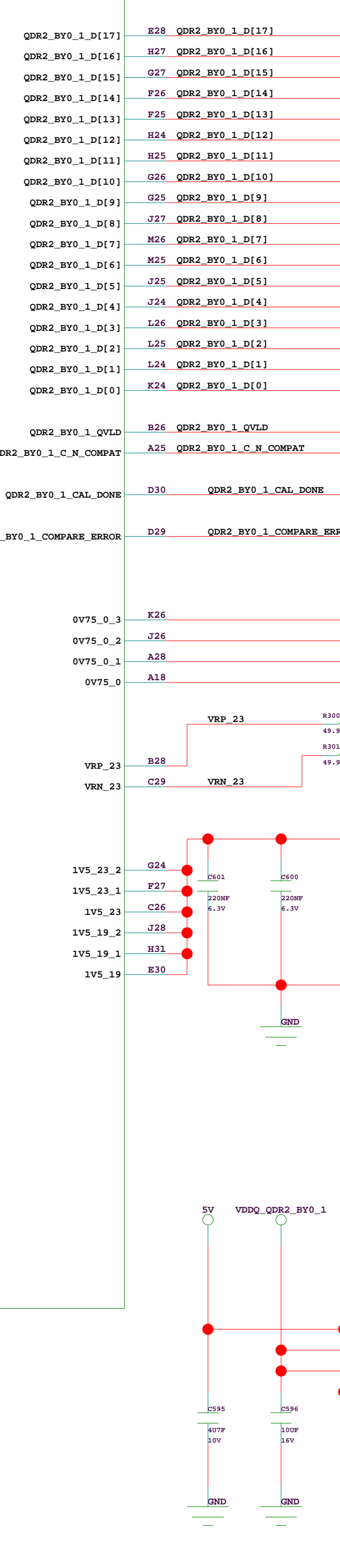
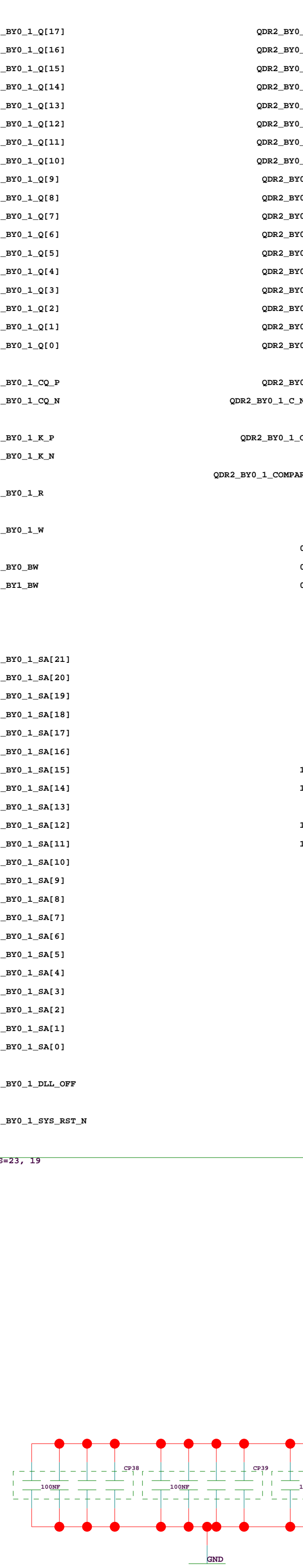
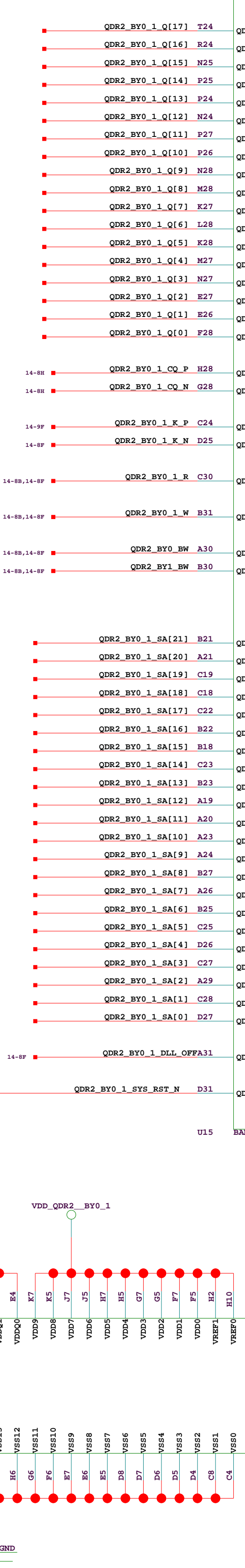
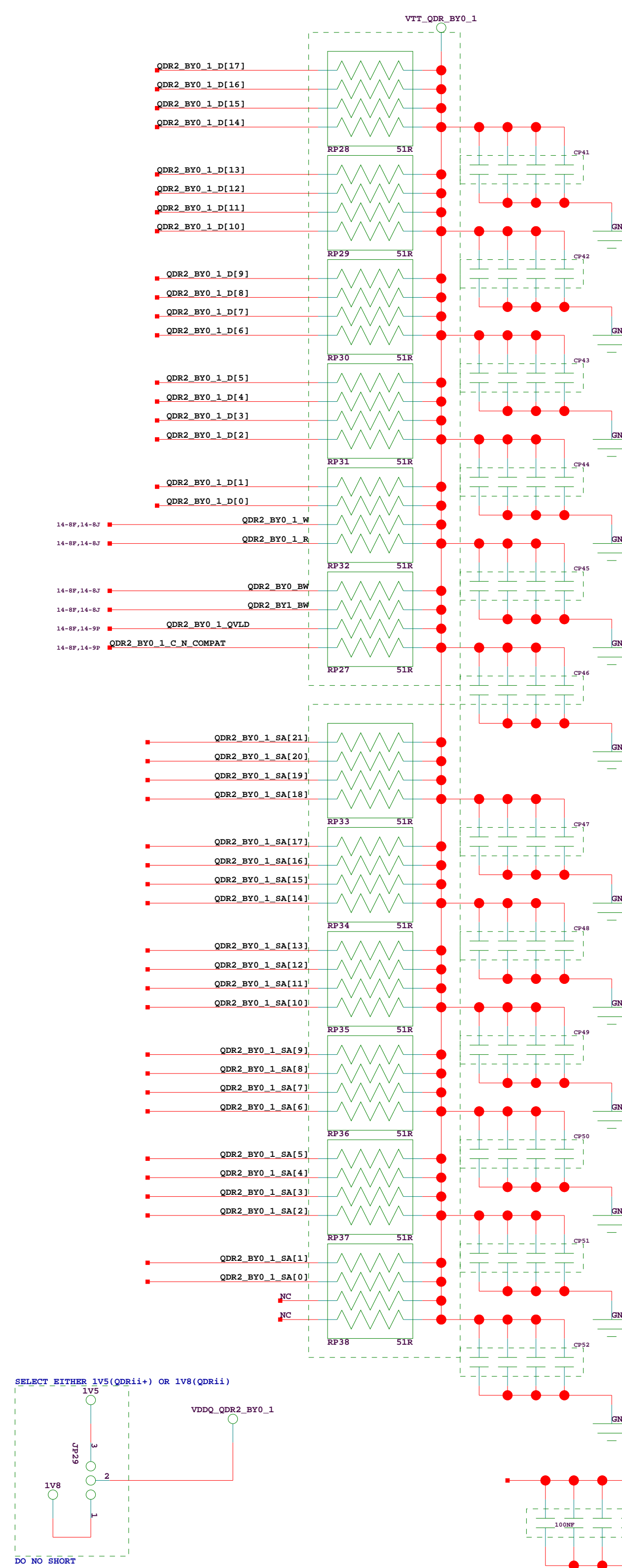


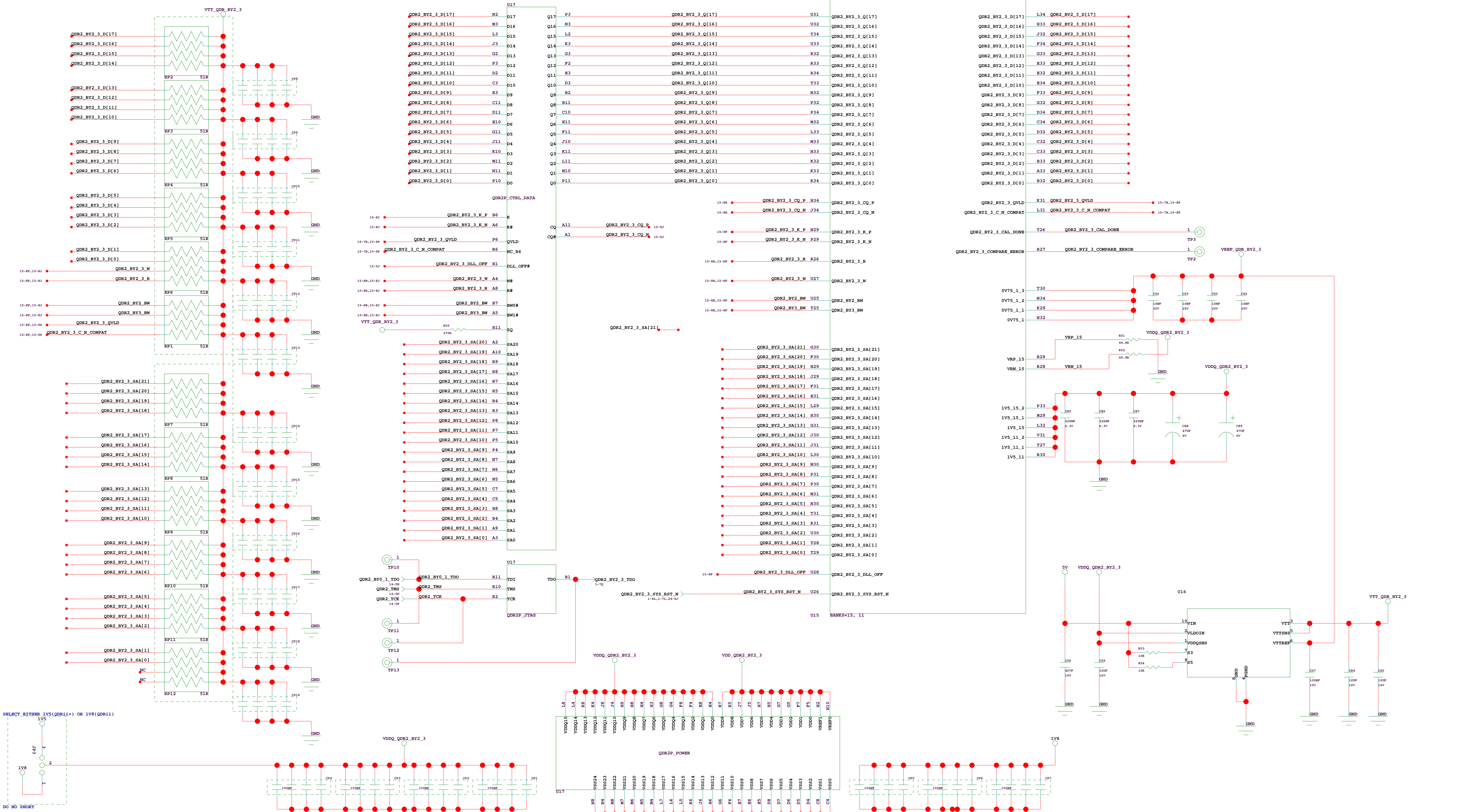


ROACH/iBOE2			ROACH_DIFF_GPIO		
COLLABORATORS:			DOC NO:		REVISION
CASPER GROUP, UC BERKELEY NRAO, SOCCORO BrewerCAT, CAPE TOWN			NRF-ADM-XXX-SD-0001		A
DESCRIPTION			RECONFIGURABLE OPEN ARCHITECTURE HW		
http://casper.berkeley.edu/			DESIGN:		APP:
10-5-2007 16:36			F KAPP		
PATH PATH			CHECKED:		SHEET
			E BAUERMEISTER		12 OF 25



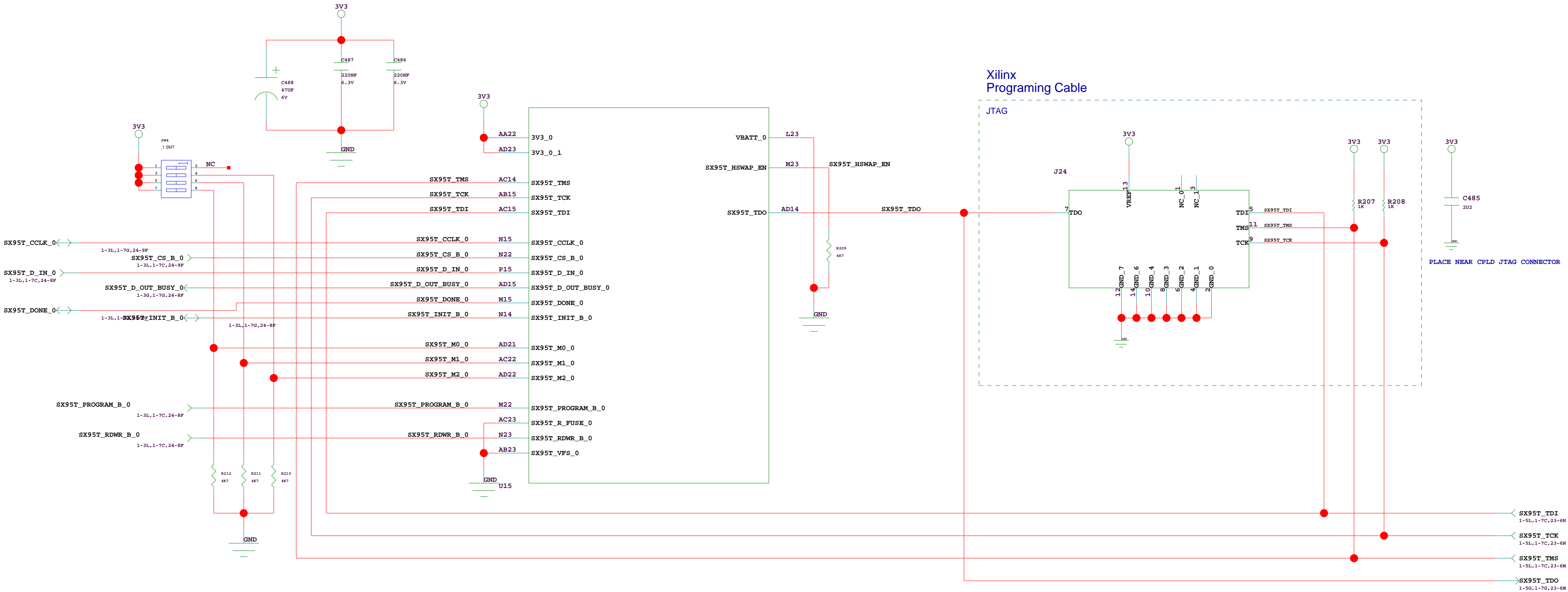
ROACH/iBOE2		ROACH_GPIO_MISC	
COLLABORATORS:		DOC NO:	REVISION:
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-SD-0001	A
NRAO, SOCCORRO		DESCRIPTION:	
MARCAT, CAPE TOWN		RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/		DRAWN:	APPD:
10-5-2007 16:36		F KAPP	
PATH	PATH	CHECKED:	SHEET
		K BAUERMEISTER	13 OF 2



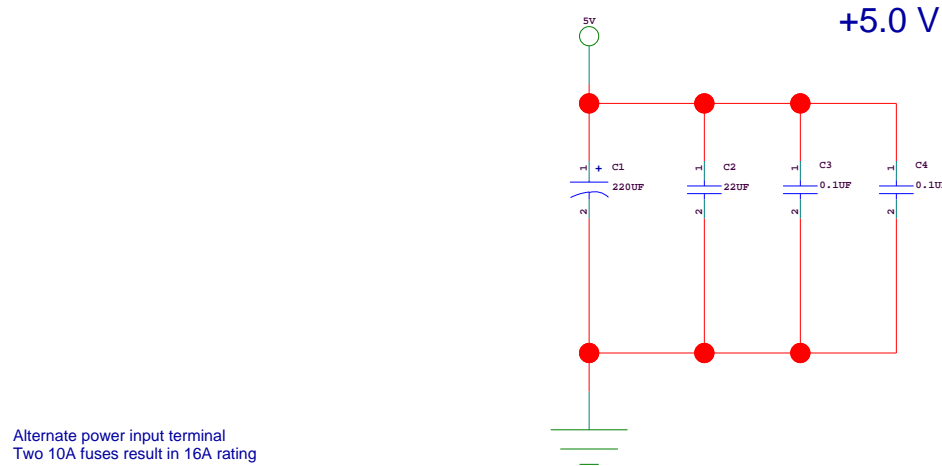
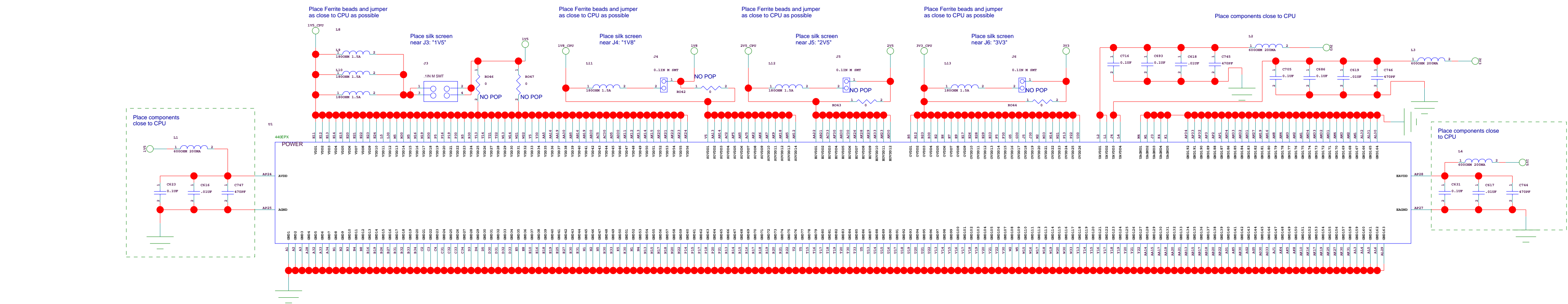


TBD

VALID CONFIGURATION MODES			
Configuration Mode	M[2:0]	Bus Width	CCLK Direction
Master Serial	000	1	Output
Master SPI	001	1	Output
Master BPI-Up	010	8, 16	Output
Master BPI-Down	011	8, 16	Output
Master SelectMAP	100	8, 16	Output
JTAG	101	1	Input (TCK)
Slave SelectMAP	110	8, 16, 32	Input
Slave Serial	111	1	Input

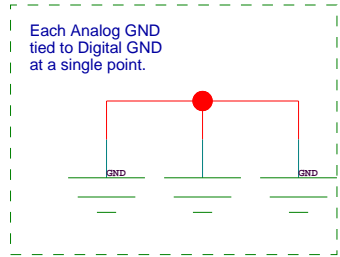
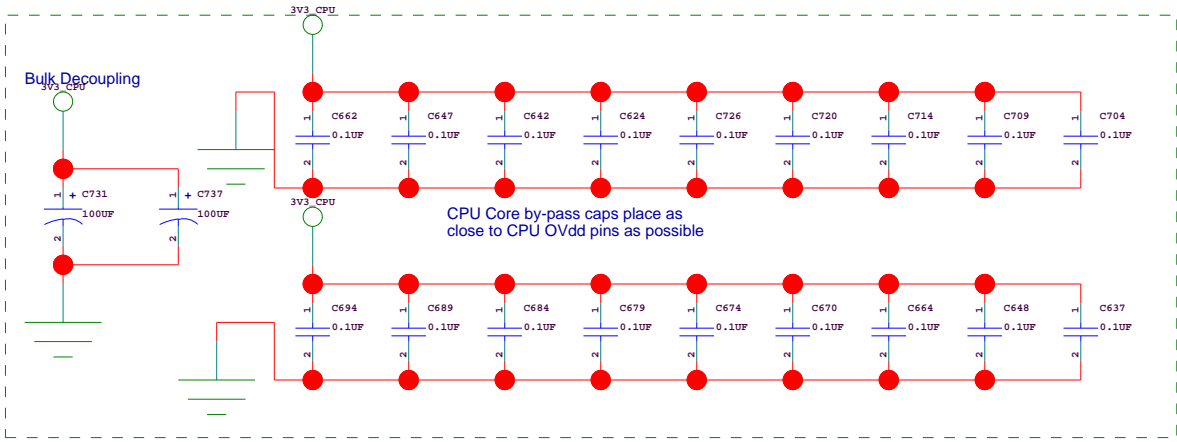
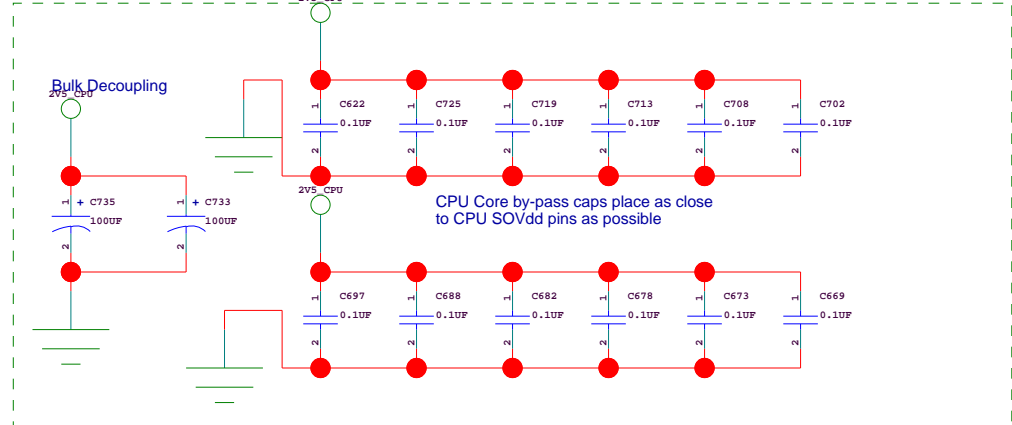
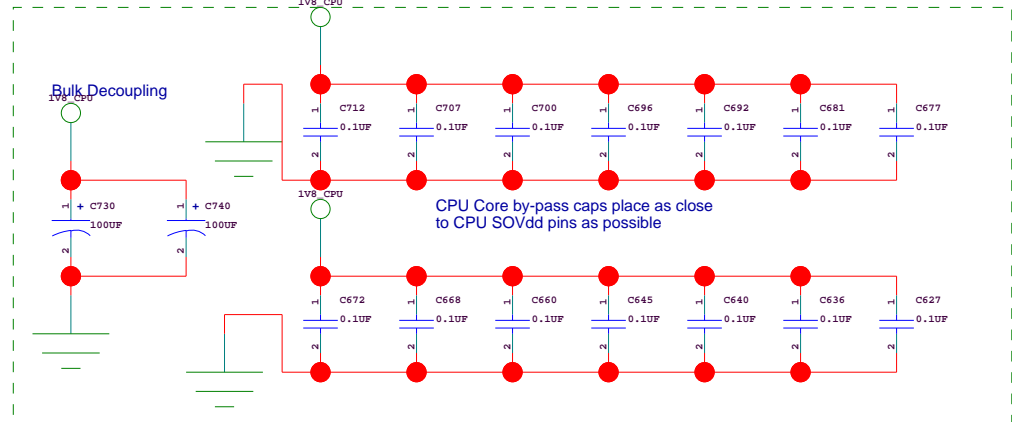
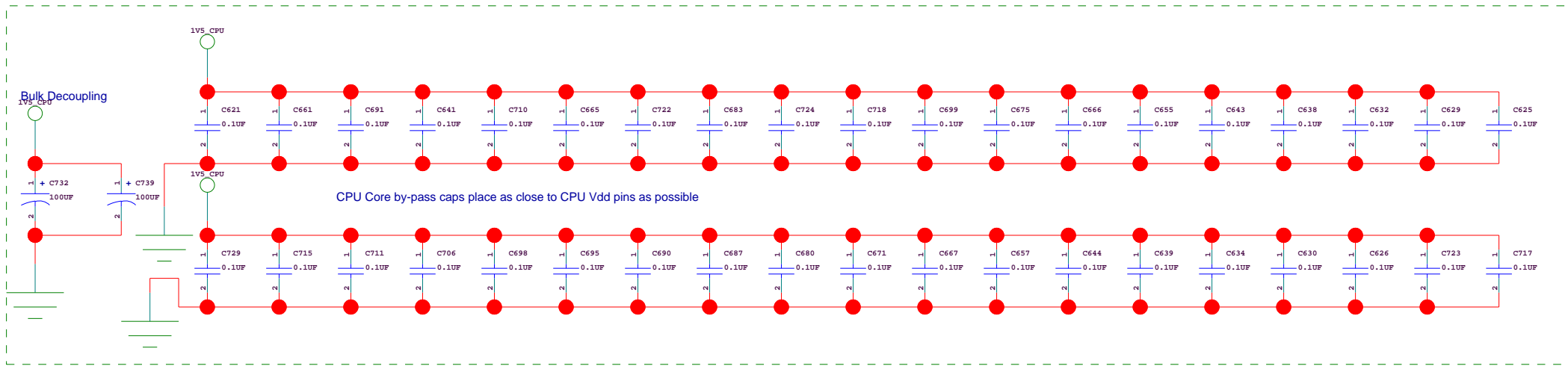
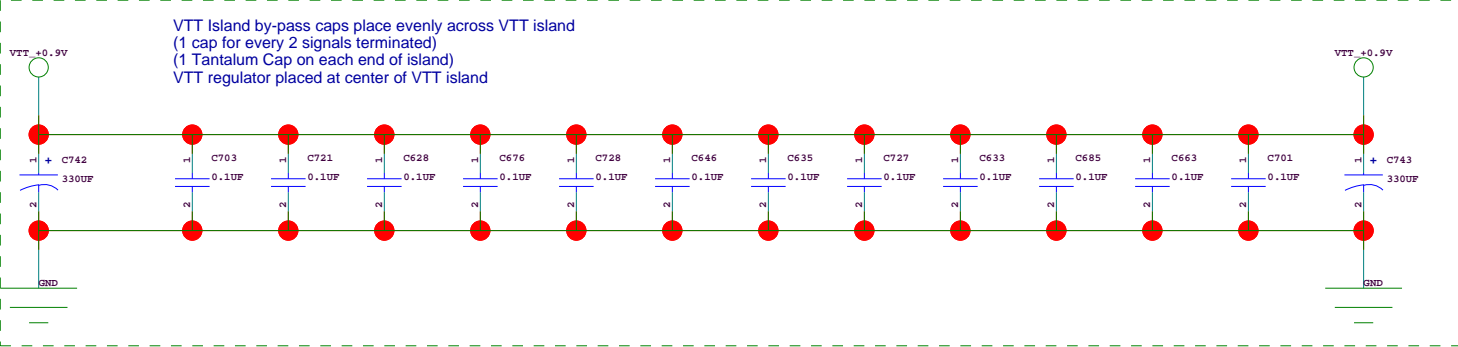
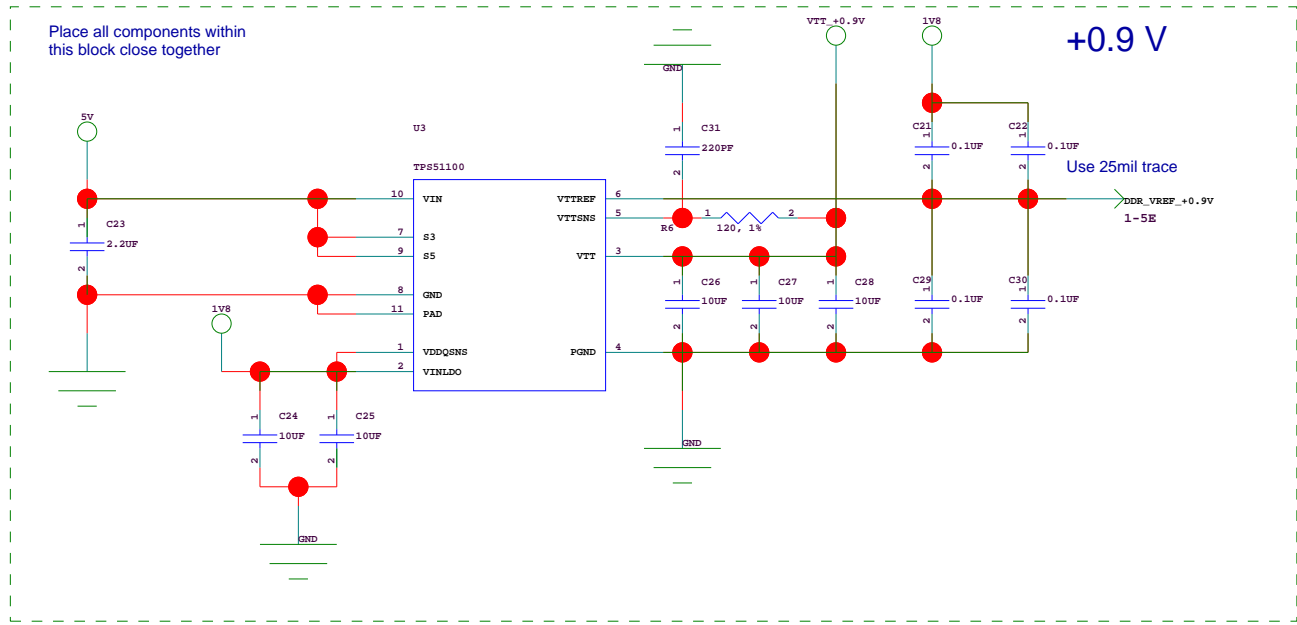
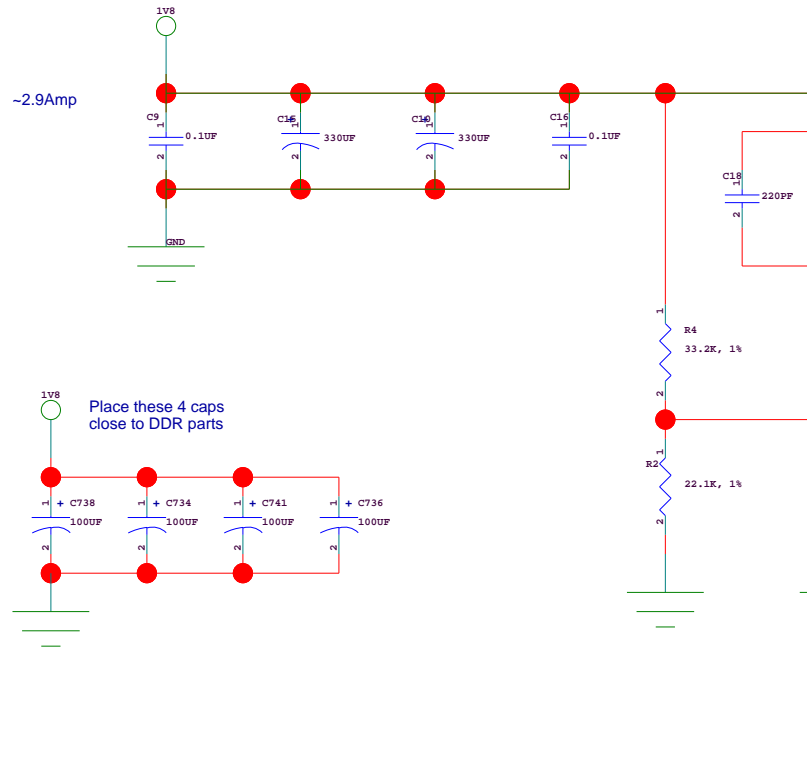


ROACH/iBOB2		ROACH_CONFIG	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN http://casper.berkeley.edu/	DOC NO NRF-ADM-XXX-SD-0001		REVISION A
	DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW		
	10-5-2007_16:36	DRAWN: F KAPP	APPR:
PATH	PATH	CHECKED: E BAUERMEISTER	SHEET 16 OF 25



+1.8 V

Place all components within this block close together



ROACH/iBOE2

COLLABORATORS:
CASPER GROUP, UC BERKELEY
NRAO, SOONERO
BEEFAT, CAPE TOWN
<http://casper.berkeley.edu/>

10-5-2007 16:36
PATH PATH

ROACH_PPC_POWER_1

DOC NO

NRF-ADM-XXX-SD-0001

DESCRIPTION

RECONFIGURABLE OPEN ARCHITECTURE HW

10-5-2007 16:36

PATH PATH

REV/ISSN

A

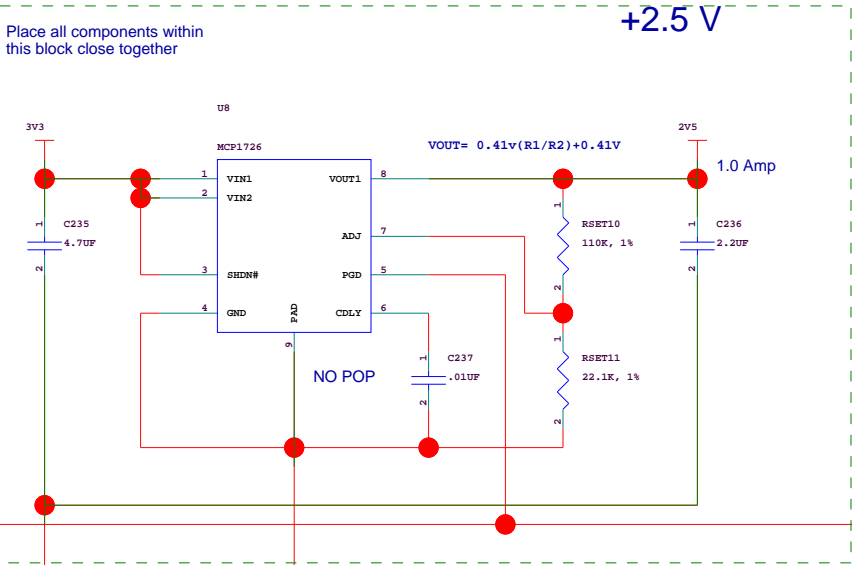
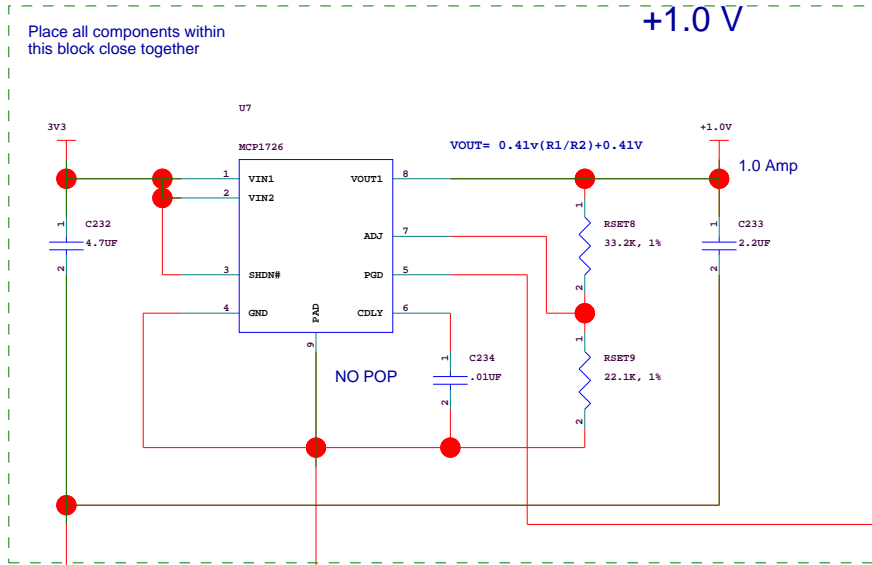
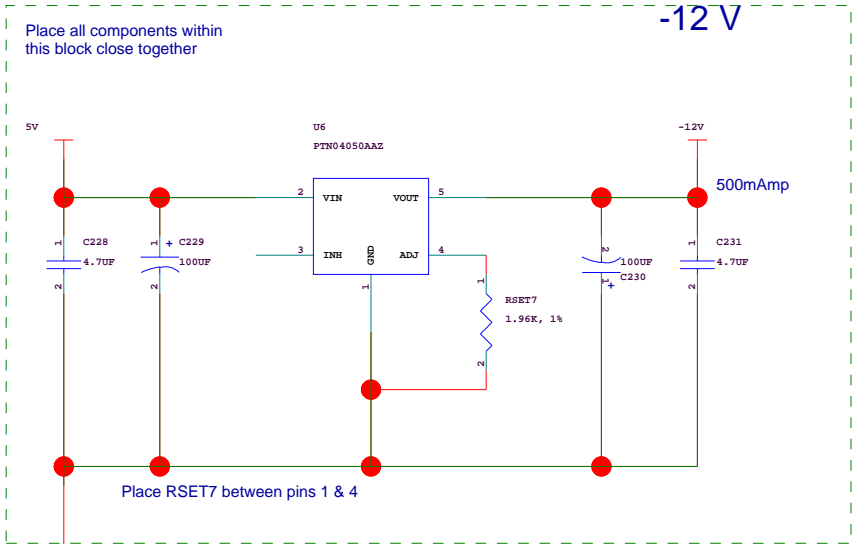
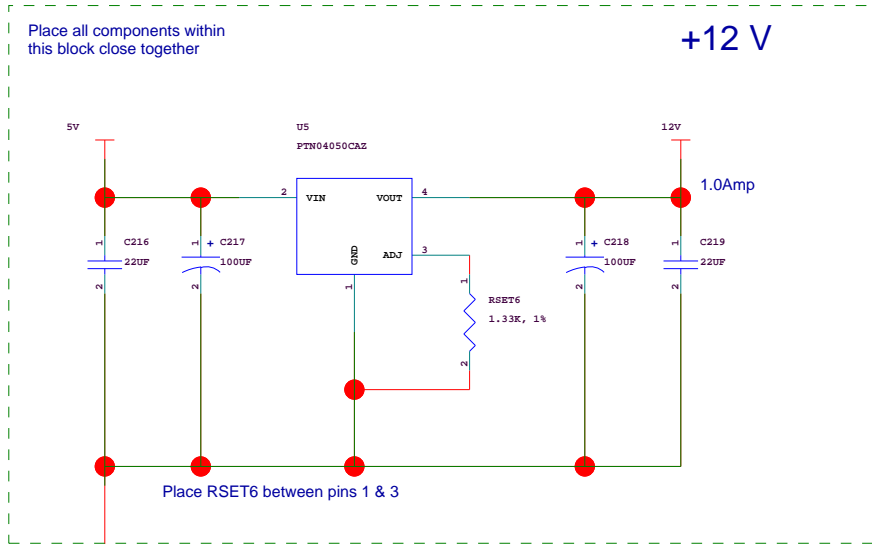
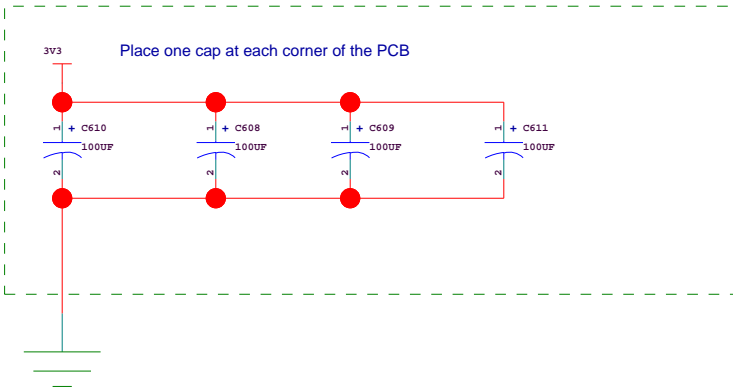
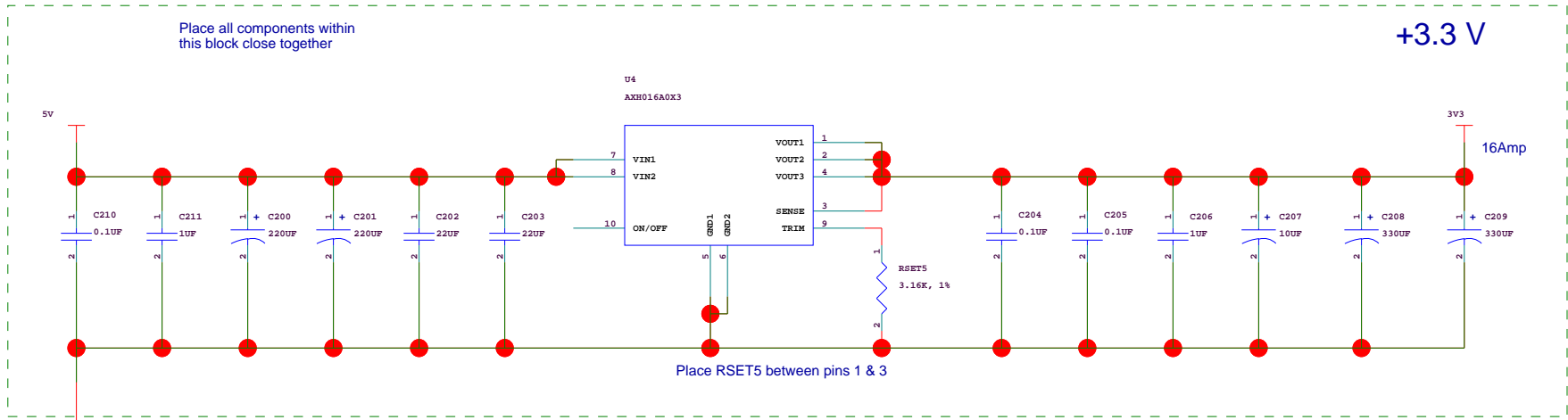
DESCRIPTION

RECONFIGURABLE OPEN ARCHITECTURE HW

10-5-2007 16:36

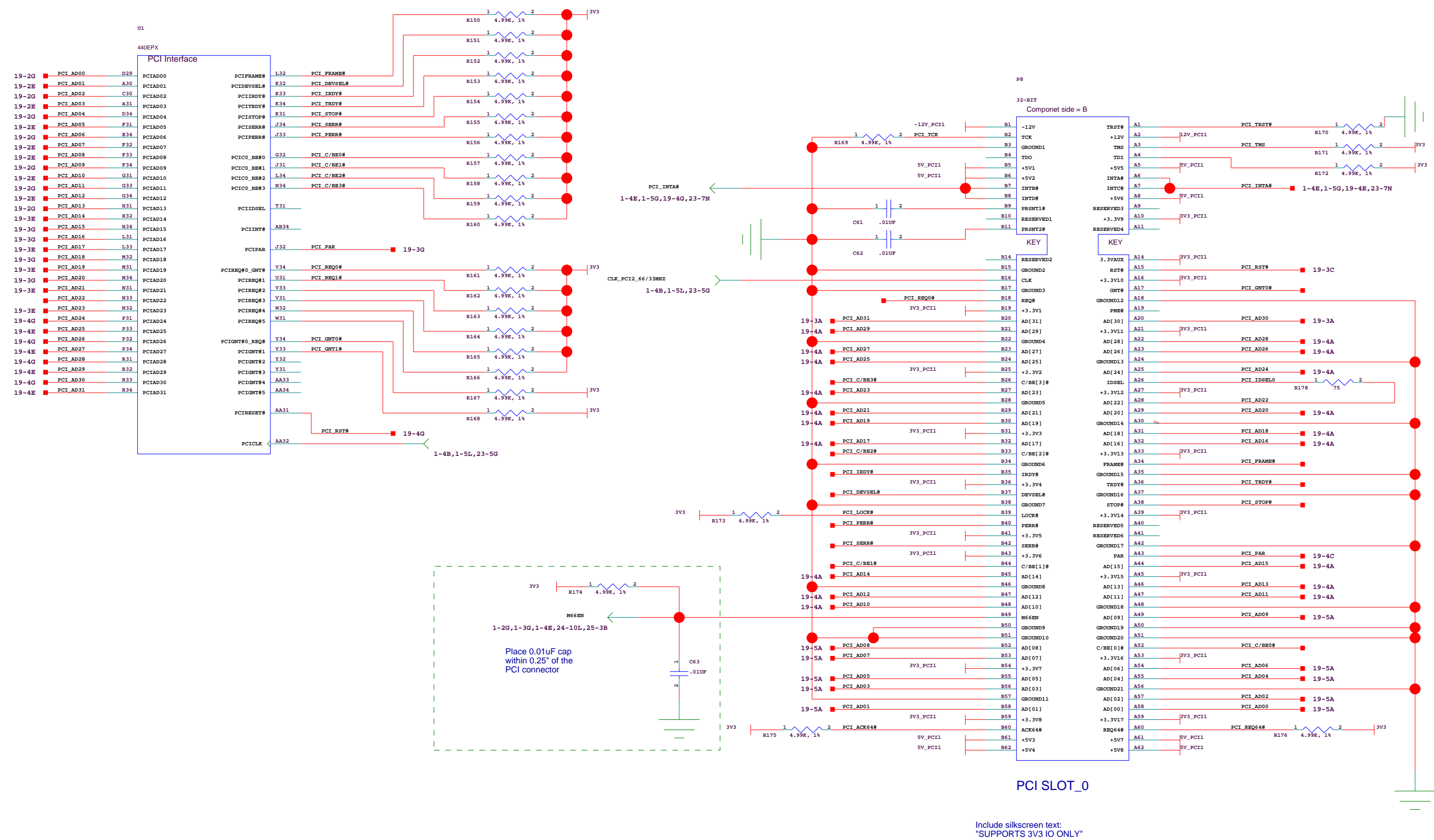
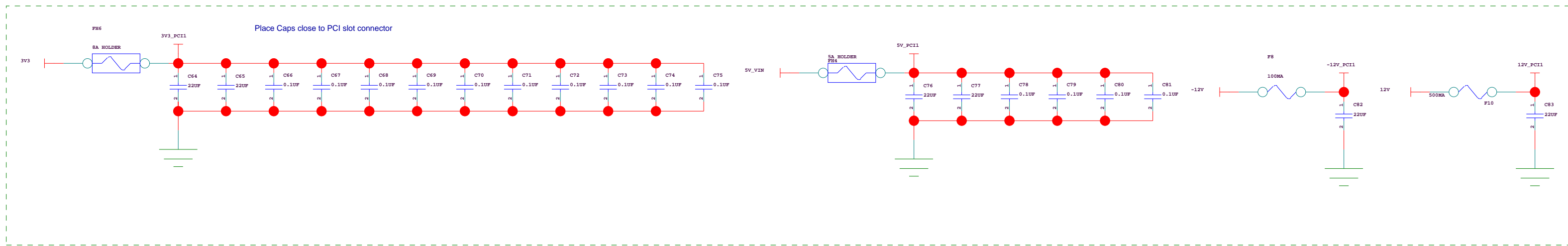
PATH PATH

17 OF 25



1-4D,1-4G,1-5E,1-5G,17-3F,23-10G,24-8K

ROACH/iBOB2		ROACH_PPC_POWER_2	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerKAT, CAPE TOWN http://casper.berkeley.edu/	DOC NO NRF-ADM-XXX-SD-0001		REVISION A
	DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW		
	DRAWN: 10-5-2007_16:36	F KAPP	APPR:
PATH	PATH	CHECKED: E BAUERMEISTER	SHEET 18 OF 25

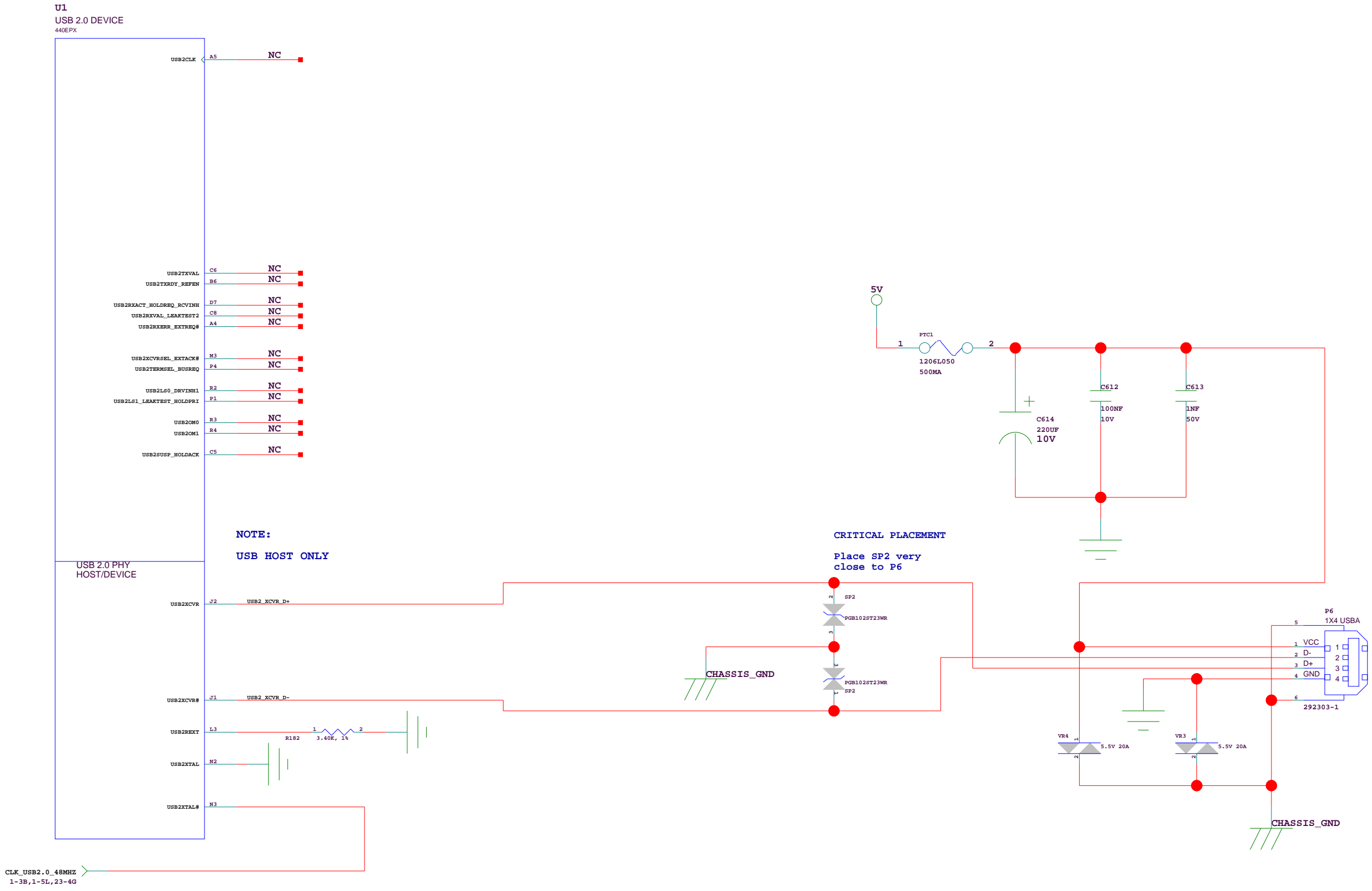


Optional PRSNT signals are not used, max 25W is available		
PRSNT1#	PRSNT2#	Expansion Configuration
Open	Open	No expansion board present
Ground	Open	Expansion board present, 25 W maximum
Open	Ground	Expansion board present, 15 W maximum
Ground	Ground	Expansion board present, 7.5 W maximum

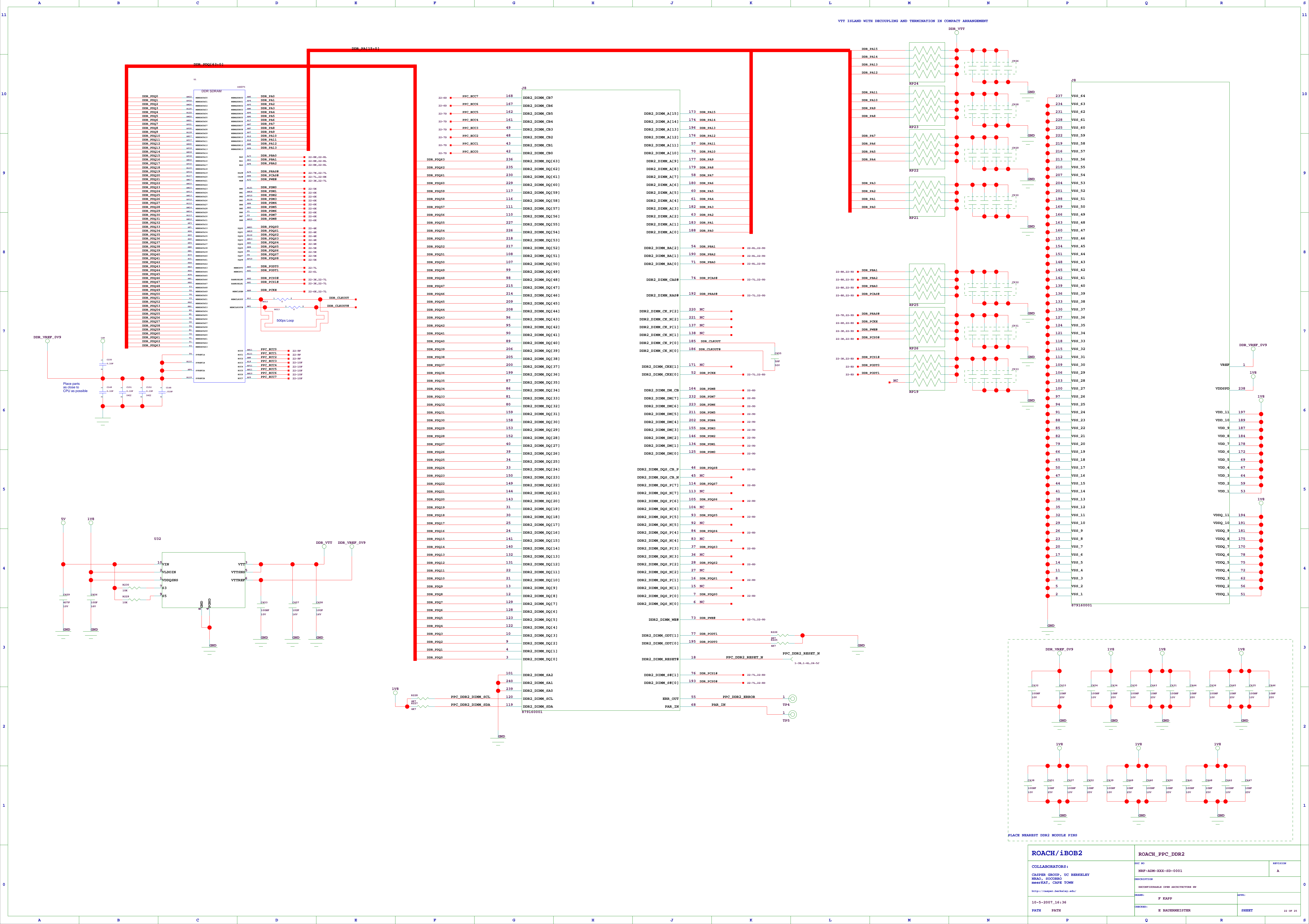
ROACH/iBOB2		ROACH_PPC_PCI	
COLLABORATORS:		DOC NO NRF-ADM-XXX-SD-0001	REVISION A
CASPER GROUP, UC BERKELEY NRAO, SOCCERO meerKAT, CAPE TOWN http://casper.berkeley.edu/		DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW	
10-5-2007_16:36		DRAWN: F KAPP	APPR:
PATH PATH		CHECKED: E BAUERMEISTER	SHEET 19 OF 25



ROACH/iBOB2		ROACH_PPC_ETH1	
COLLABORATORS:		DOC NO	REVISION
CAPSER GROUP, UC BERKELEY NRAD, SOCOERO MOUNTAIN, CAPE TOWN		NRP-ADM-KXX-GD-0001	A
		DESCRIPTION	
		RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/		ISSUED:	APPRO:
10-5-2007_16:36		F KAPP	
PATH	PATH	CHECKED:	SHEET
		K BAUMHEISTER	20 OF 2



ROACH/iBOB2		ROACH_PPC_USB	
COLLABORATORS: CASPER GROUP, UC BERKELEY NRAO, SOCORRO meerkAT, CAPE TOWN http://casper.berkeley.edu/ 10-5-2007_16:36 PATH PATH	DOC NO NRF-ADM-XXX-SD-0001		REVISION A
	DESCRIPTION RECONFIGURABLE OPEN ARCHITECTURE HW		
	DRAWN: F KAPP		APPR:
	CHECKED: E BAUERMEISTER		SHEET 21 OF 25

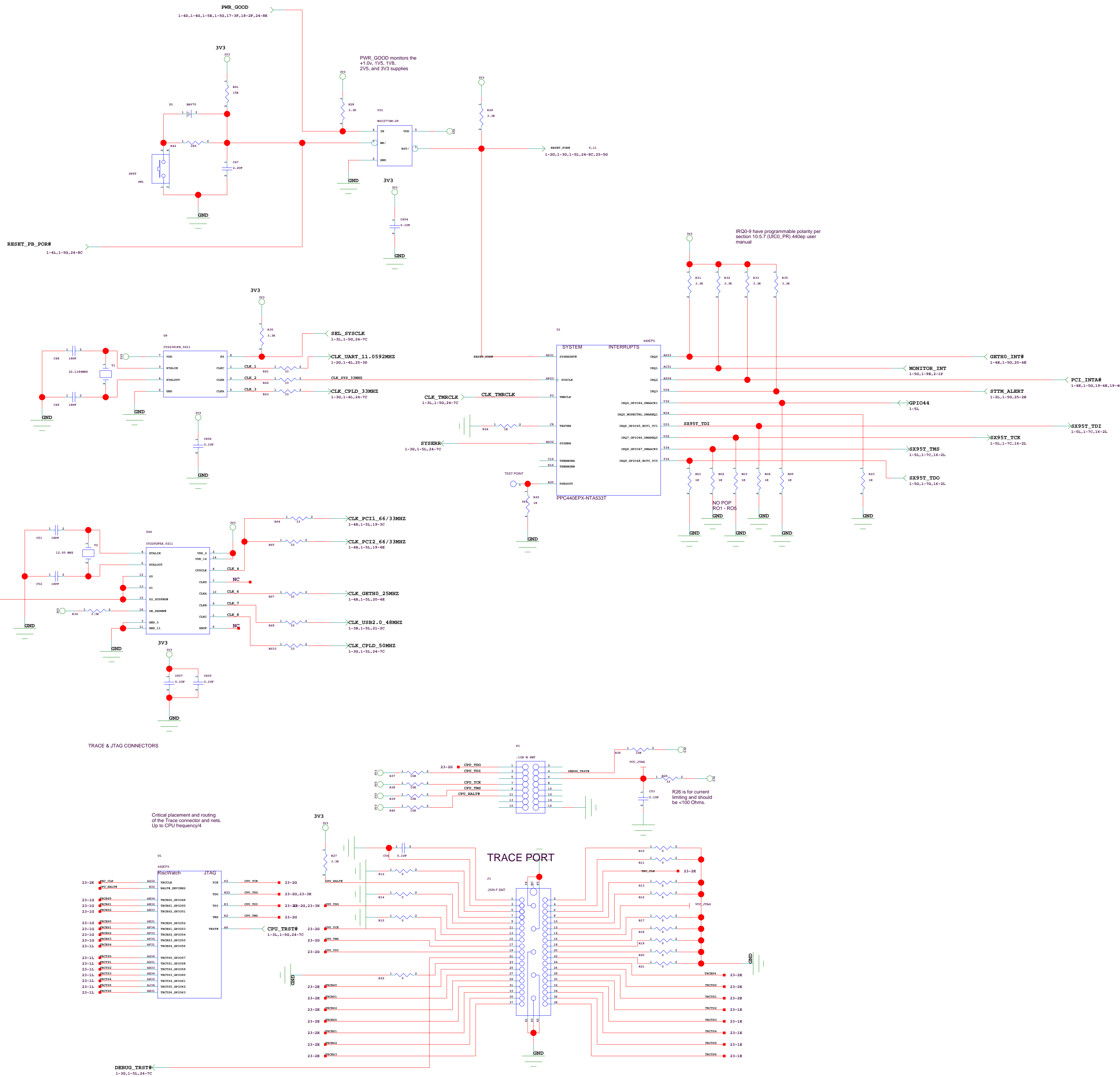


Critical Placement and Route
Clock Rules:

Clock Rules:
CLK_UART_11.0592MHz = as short as possible
CLK_SYS_33MHz = as short as possible
CLK_CPLD_33MHz = CLK_SYS_33MHz

Critical Placement and Route
Clock Rules:

Clock Rules:
CLK_PC13_66/33MHz = as short as possible
CLK_PC12_66/33MHz = CLK_PC13_66/33MHz
CLK_PC11_66/33MHz = CLK_PC12_66/33MHz + 2.5°
CLK_GETH0_25MHz = as short as possible
CLK_GETH1_25MHz = CLK_GETH0_25MHz
CLK_CPLD_50MHz = as short as possible
CLK_USB2_0_48MHz = as short as possible
CLK_USB2_0_12MHz = as short as possible



ROACH/iBOE2		ROACH_PPC_TST_CLK_IO	
COLLABORATORS:		DOC NO	REVISION
CASPER GROUP, UC BERKELEY		NRF-ADM-XXX-SD-0001	A
HW, ©COURTESY		DESCRIPTION	
BERKELEY, CALIF. TOWN		RECONFIGURABLE OPEN ARCHITECTURE HW	
http://casper.berkeley.edu/		DESIGN:	APP:
10-5-2007 16:36		F KAPP	
PATH	PATH	CHECKED:	SHEET
		E BAUERMEISTER	23 OF 25

