

Gradient Descent Algorithm:-

Cost function:-

$$\hat{y} = \hat{\theta}_0 + \hat{\theta}_1 x_1 + \hat{\theta}_2 x_2 + \hat{\theta}_3 x_3 + \dots + \hat{\theta}_k x_k$$

$$\hat{y} = \hat{\theta}_0 x_0 + \hat{\theta}_1 x_1 + \hat{\theta}_2 x_2 + \dots + \hat{\theta}_k x_k$$

SL No	x_0	x_1	x_2	...	x_k
1.	1	$x_1^{(1)}$	$x_2^{(1)}$...	$x_k^{(1)}$
2.	1	$x_1^{(2)}$	$x_2^{(2)}$...	$x_k^{(2)}$
3.	1	$x_1^{(3)}$	$x_2^{(3)}$...	$x_k^{(3)}$
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots
$m-1$	1	$x_1^{(m-1)}$	$x_2^{(m-1)}$...	$x_k^{(m-1)}$
m	1	$x_1^{(m)}$	$x_2^{(m)}$...	$x_k^{(m)}$

$x_0 = 1$ for all rows.

for any row i

$$\begin{bmatrix} \overset{1}{\cancel{x_0^{(i)}}}, x_1^{(i)}, x_2^{(i)}, \dots, x_k^{(i)} \end{bmatrix}$$

$$\vec{x}^{(i)} = \begin{bmatrix} 1, x_1^{(i)}, x_2^{(i)}, \dots, x_k^{(i)} \end{bmatrix}$$

SL No.	x_0	x_1	x_2	...	x_k	y
1.	1	$x_1^{(1)}$	$x_2^{(1)}$...	$x_k^{(1)}$	$y^{(1)}$
2.	1	$x_1^{(2)}$	$x_2^{(2)}$...	$x_k^{(2)}$	$y^{(2)}$
3.	1	$x_1^{(3)}$	$x_2^{(3)}$...	$x_k^{(3)}$	$y^{(3)}$
⋮	⋮	⋮	⋮	⋮	⋮	⋮
m.	1	$x_1^{(m)}$	$x_2^{(m)}$...	$x_k^{(m)}$	$y^{(m)}$

target.

$m \rightarrow$ total number of training samples.

$k \rightarrow$ number of features.

$$\hat{y}^{(i)} = \hat{\theta}_0 x_0^{(i)} + \hat{\theta}_1 x_1^{(i)} + \hat{\theta}_2 x_2^{(i)} + \dots + \hat{\theta}_k x_k^{(i)} = \sum_{j=0}^k \hat{\theta}_j x_j^{(i)}$$

$$= [\hat{\theta}_0, \hat{\theta}_1, \hat{\theta}_2, \dots, \hat{\theta}_k] \cdot [x_0^{(i)}, x_1^{(i)}, x_2^{(i)}, \dots, x_k^{(i)}]$$

$$\boxed{\hat{y}^{(i)} = \vec{\hat{\theta}} \cdot \vec{x}^{(i)}}$$

$\vec{\hat{\theta}} \rightarrow$ Estimated model parameter vector.

$\vec{x}^{(i)} \rightarrow i^{\text{th}}$ observation (datapoint) vector.

$\hat{y}^{(i)}$ \rightarrow Predicted value of $y^{(i)}$. \rightarrow Actual value.

$e^{(i)} = \hat{y}^{(i)} - y^{(i)} \rightarrow$ Error for i^{th} observati

Residual Sum of Square (RSS)

$$RSS = \sum_{i=1}^m [e^{(i)}]^2 = \sum_{i=1}^m [\hat{y}^{(i)} - y^{(i)}]^2$$

Cost function: $J = \frac{1}{2m} (RSS)$.

$$\therefore J = \frac{1}{2m} \sum_{i=1}^m \left(\underbrace{\hat{y}^{(i)}}_{\sum_{j=0}^k \hat{\theta}_j x_j^{(i)}} - y^{(i)} \right)^2 = \frac{1}{2m} \sum_{i=1}^m \left(\sum_{j=0}^k \hat{\theta}_j x_j^{(i)} - y^{(i)} \right)^2$$

$$J = \frac{1}{2m} \sum_{i=1}^m \left(\underbrace{\sum_{j=0}^k \hat{\theta}_j \cdot x_j^{(i)}}_{z^{(i)}} - y^{(i)} \right)^2$$

$\nearrow \hat{y}^{(i)}$

$$J = \frac{1}{2m} \sum_{i=1}^m (z^{(i)})^2$$

$$z^{(i)} = \underbrace{\sum_{j=0}^k \hat{\theta}_j \cdot x_j^{(i)}}_{x^{(i)}} - y^{(i)}$$

$$\frac{\partial J}{\partial \hat{\theta}_j} = \frac{\partial J}{\partial z^{(i)}} \cdot \frac{\partial z^{(i)}}{\partial \hat{\theta}_j}$$

$$\vdots \quad \frac{\partial z^{(i)}}{\partial \hat{\theta}_j} = x_j^{(i)}$$

$$= \frac{1}{m} \sum_{i=1}^m z^{(i)} \cdot x_j^{(i)}$$

$$= \frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)}) x_j^{(i)}$$

$$\Delta \hat{\theta}_j = -\alpha \frac{\partial J}{\partial \hat{\theta}_j} \quad \& \quad \hat{\theta}_j(t+1) = \hat{\theta}_j(t) + \Delta \hat{\theta}_j$$

Gradient descent update rule.

$$\underline{\Delta \hat{\theta}_j} = -\frac{\alpha}{m} \sum_{i=1}^m \left(\hat{y}^{(i)} - y^{(i)} \right) \underline{x_j^{(i)}}$$

$$\| \Delta \hat{\theta}_j \|$$

$$\hat{y}^{(i)} = \hat{\theta} \cdot x^{(i)}$$

$$\hat{\theta}_{k \times 1}$$

$$\hat{\theta}_{1 \times k}$$

$$X_{\text{train}} = \begin{bmatrix} \vec{x}^{(1)} \\ \vec{x}^{(2)} \\ \vdots \\ \vec{x}^{(i)} \\ \vdots \\ \vec{x}^{(m)} \end{bmatrix}_{m \times k}$$

$$X_{\text{train}} =$$

$x_1^{(1)}$	$x_2^{(1)}$	\dots	\dots	$x_k^{(1)}$	$\rightarrow \vec{x}^{(1)}$
$x_1^{(2)}$	$x_2^{(2)}$			$x_k^{(2)}$	
\vdots	\vdots			\vdots	
$x_1^{(i)}$	$x_2^{(i)}$			$x_k^{(i)}$	$\rightarrow \vec{x}^{(i)}$
\vdots	\vdots			\vdots	
$x_1^{(m)}$	$x_2^{(m)}$			$x_k^{(m)}$	

$m \times k$

$$\hat{y} = \hat{\theta}_{1 \times k} \cdot (X_{\text{train}})^T$$

$$\begin{matrix} (1 \times k) \times (k \times m) \\ 1 \times m \end{matrix}$$