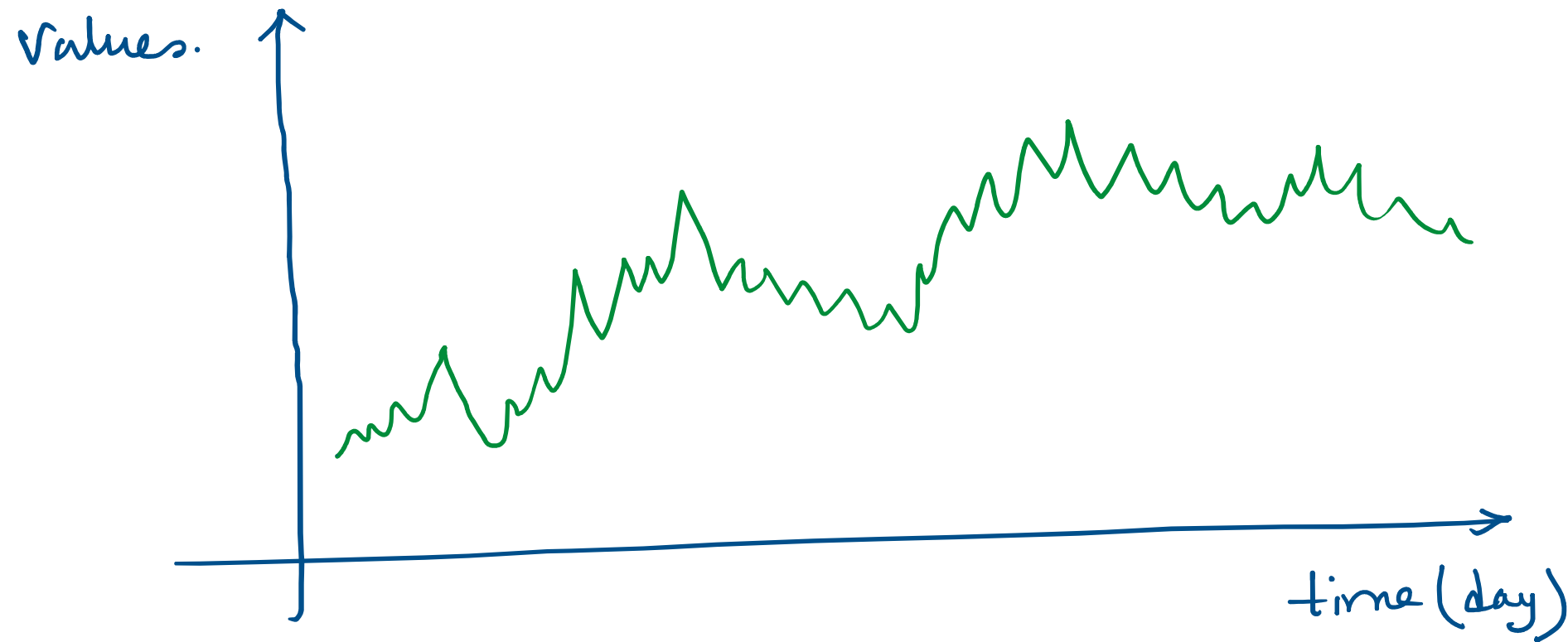


Time Series Resampling :-



During resampling we compress the time series

Ex: From daily data we can compress to weekly, monthly, quarterly, annual data.

freq: -
day → week

day 1	y_1
day 2	y_2
day 3	y_3
⋮	
day 7	y_7

week 1 → aggregate(y_1, y_2, \dots, y_7)

↓
mean, min, max, std,
(sum)

df → pandas dataframe containing time series data.

df.resample(rule).agg()



mean()

min()

max()

std()

sum()

Aggregation functions.

The rule parameter describes the frequency with which we can apply aggregation function.

It is passed using an "offset alias".

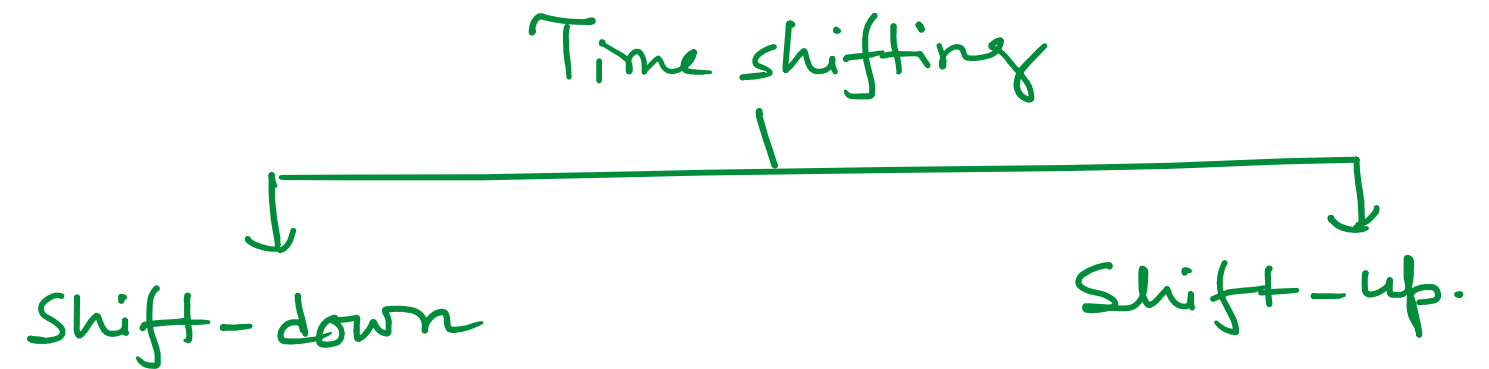
The offset alias is documented in the link:

https://pandas.pydata.org/docs/user_guide/timeseries.html#offset-aliases

Please go through it to understand different kinds of rules to resample the data.

Time Shifting :-

Dates	Values
day 1	y_1
day 2	y_2
day 3	y_3
⋮	⋮
day n	y_n



Shift down:- If someone shifts down the data by '1' day then —

dates	values
day 1	nan (no values)
day 2	y_1
day 3	y_2
day 4	y_3
⋮	⋮
day n	y_{n-1}

If I shift down by 'k' days

<u>dates</u>	<u>values</u>
day 1	nan
day 2	nan
⋮	⋮
day k	nan
<hr/>	
day k+1	y ₁
day k+2	y ₂
⋮	⋮
day n	y _{n-k}

} no values for first 'k' days.

Shifting up by 1 day

<u>dates</u>	<u>values</u>
day 1	y ₂
day 2	y ₃
day 3	y ₄
⋮	⋮
day n-1	y _n
day n	NaN

Shifting up by k days

<u>dates</u>	<u>values</u>
day 1	y _{k+1}
day 2	y _{k+2}
⋮	⋮
day n-k	y _n
day n-k+1	NaN
⋮	⋮
day n	NaN

Time Rolling :-

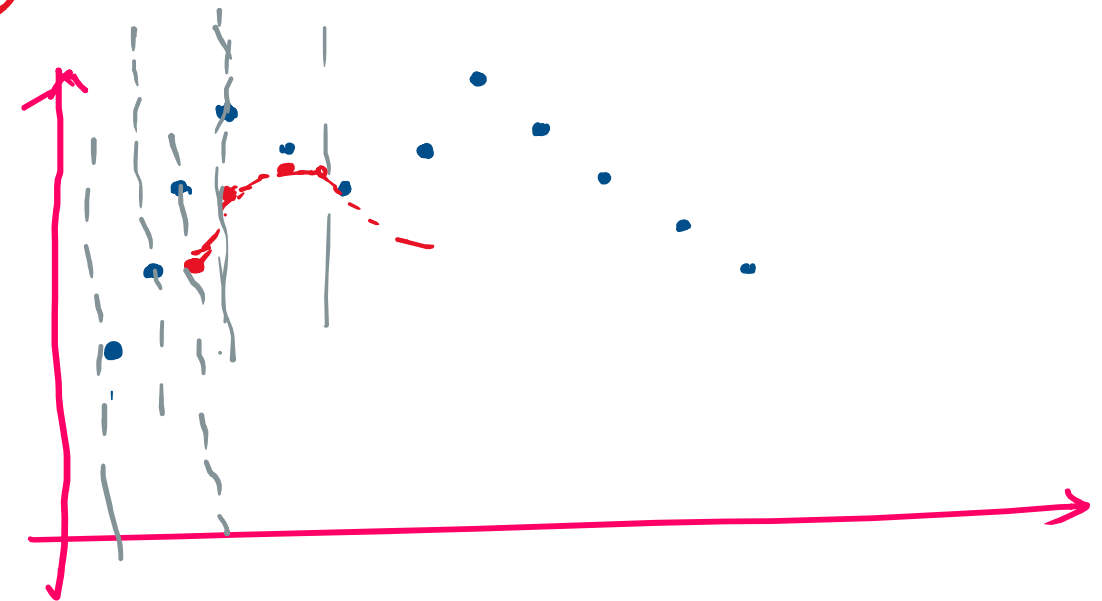
Rolling window = period for which the agg function will be applied.

Aggregate function = what aggregation method we want to calculate.

Rolling window = 3 , agg function = mean() } simple moving average with window = 3

time	values
t_1	y_1
t_2	y_2
t_3	y_3
\vdots	\vdots
t_n	y_n

time	values (rolling)
t_1	Nan
t_2	Nan
t_3	$\frac{y_1 + y_2 + y_3}{3}$
t_4	$\frac{y_2 + y_3 + y_4}{3}$
t_5	$\frac{y_3 + y_4 + y_5}{3}$
\vdots	
t_n	$\frac{y_{n-2} + y_{n-1} + y_n}{3}$



For time rolling with rolling window 'k'

<u>time</u>	<u>values</u>	
t_1	NaN	$agg(--)$ \rightarrow aggregate functions.
t_2	NaN	
t_3	\vdots	
\vdots	\vdots	
t_{k-1}	NaN.	
t_k	$agg(t_1, t_2, \dots, t_k)$	mean()
t_{k+1}	$agg(t_2, t_3, \dots, t_{k+1})$	min()
\vdots	\vdots	max()
t_n	$agg(t_{n-k+1}, t_{n-k+2}, \dots, t_n)$	std()
		sum().

Time Expanding: —

<u>time</u>	<u>values</u>
t_1	y_1
t_2	y_2
t_3	y_3
\vdots	\vdots
t_k	y_k
\vdots	\vdots
t_n	y_n

Only aggregate function is required.

<u>window</u>	<u>q/p value</u>
1	y_1
2	$agg(y_1, y_2)$
3	$agg(y_1, y_2, y_3)$
\vdots	\vdots
k	$agg(y_1, y_2, y_3, \dots, y_k)$
\vdots	\vdots
n	$agg(y_1, y_2, y_3, \dots, y_n)$

$agg()$ \rightarrow aggregate function.

Main components of a time series data :-

<u>time</u>	<u>values</u>
t_1	y_1
t_2	y_2
t_3	y_3
\vdots	\vdots
t_n	y_n

$y_t \rightarrow$ the value of the time series at ' t 'th instance.

Additive model

$$y_t = \tau_t + S_t + C_t + \epsilon_t$$

Multiplicative model

$$y_t = \tau_t \times S_t \times C_t + \epsilon_t$$

we will not use.

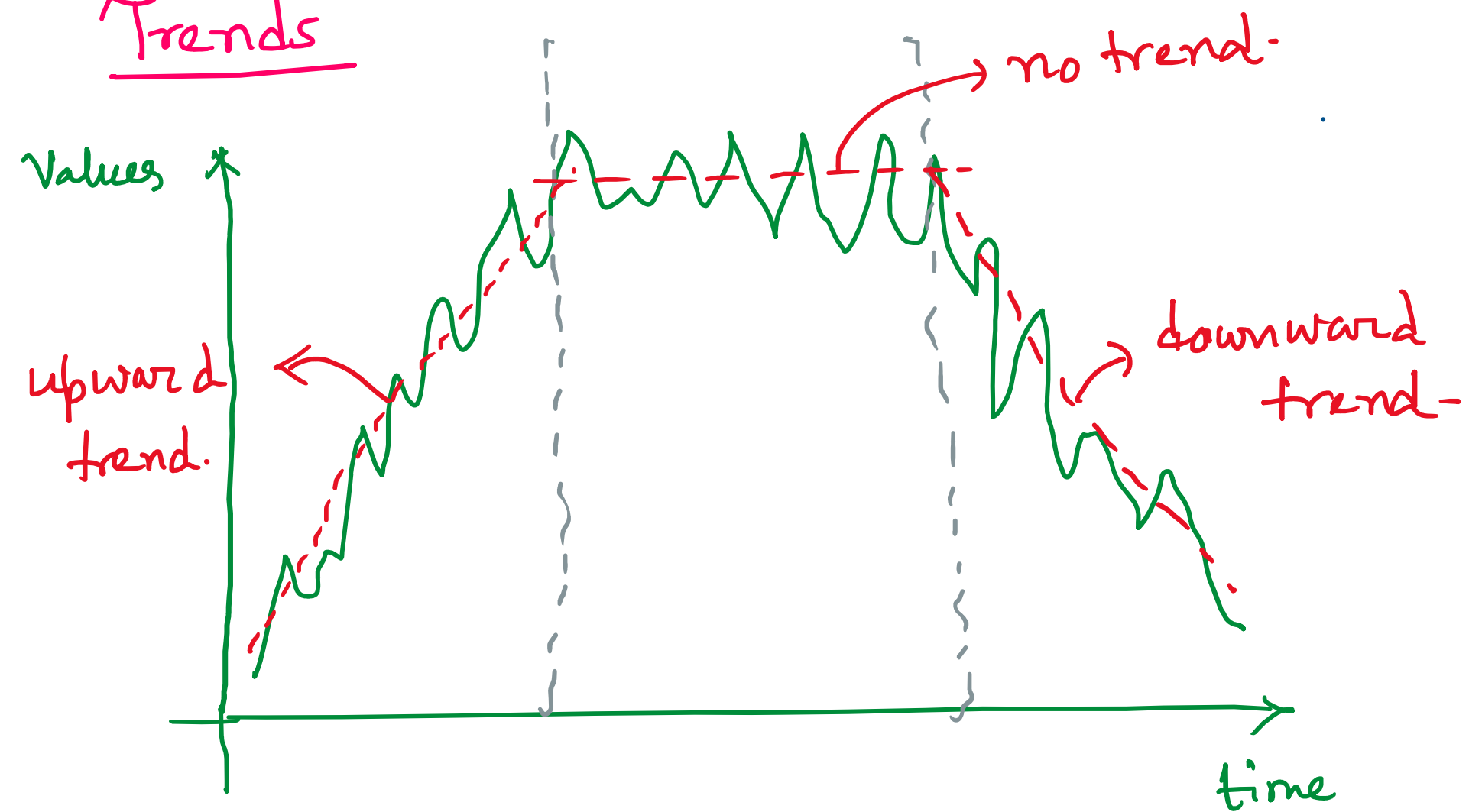
$\tau_t \rightarrow$ trend component

$S_t \rightarrow$ seasonality component (specific period, usually shorter)

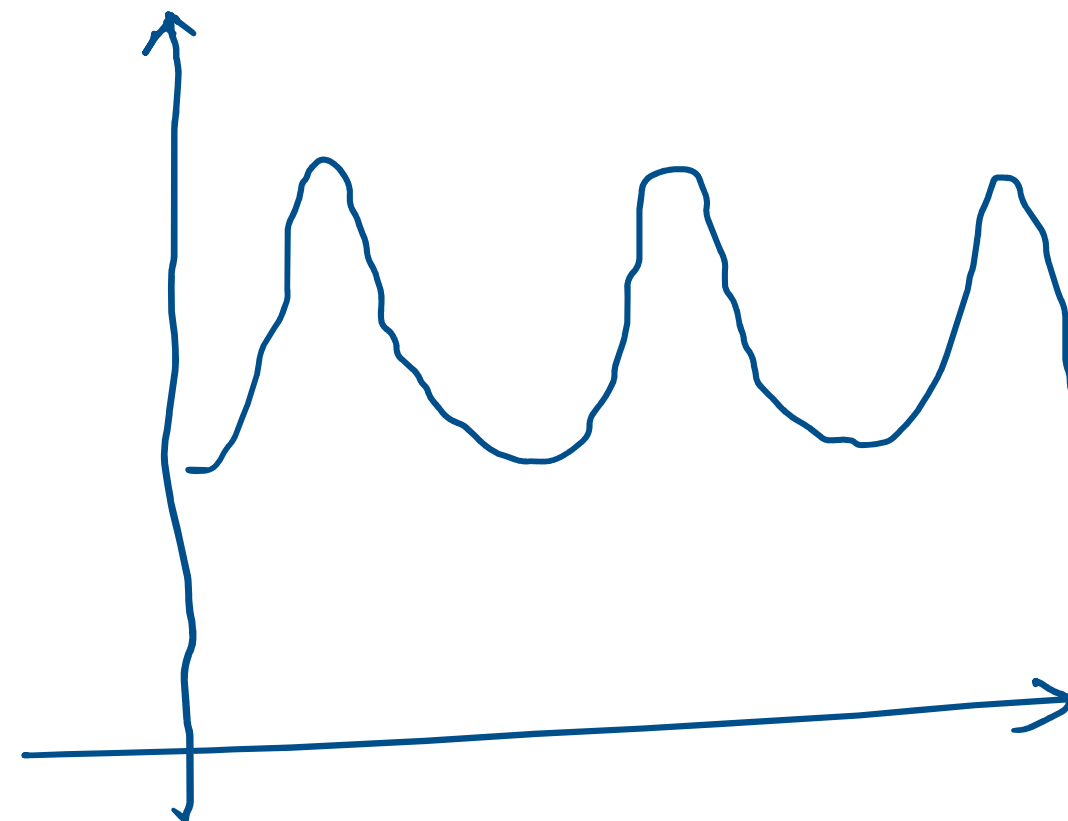
$C_t \rightarrow$ cyclical component (no specific period, usually longer).

$\epsilon_t \rightarrow$ Error component (noise).

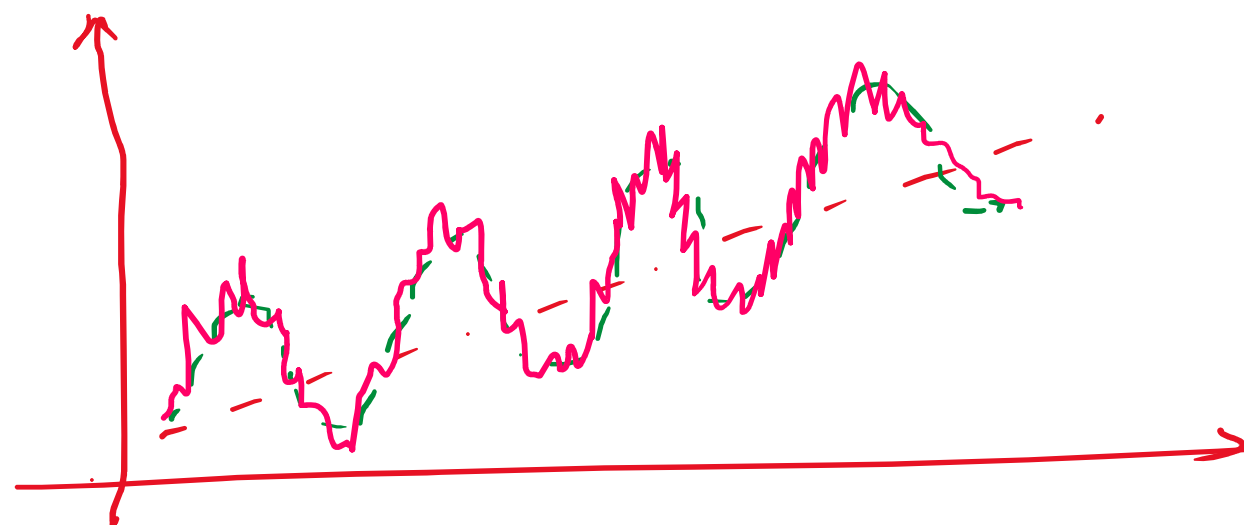
Trends



Seasonality

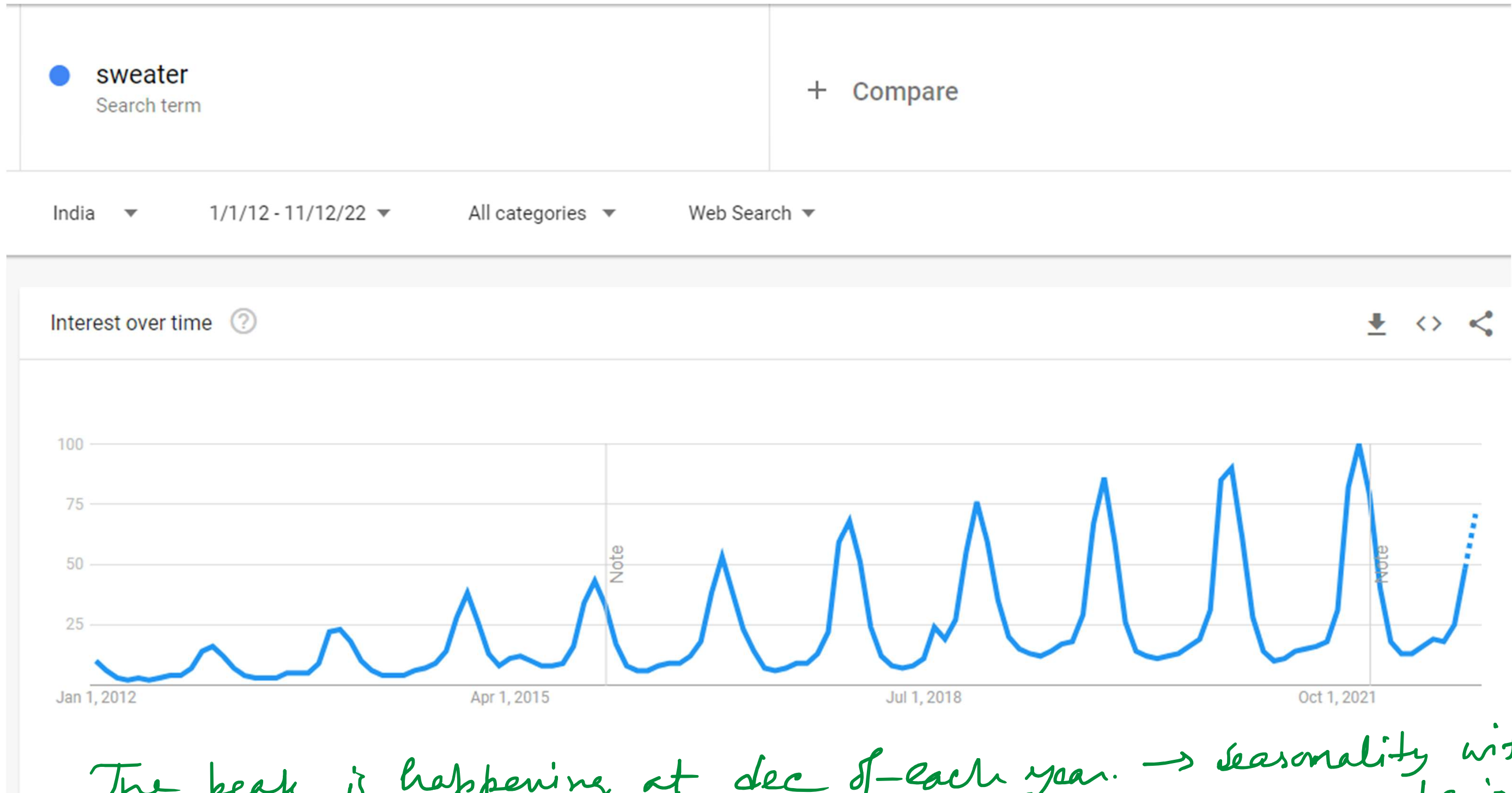


Trend & Seasonality



Example of Seasonal Component in time series

Following is the trend (from google search) of sweater over last 10 years.



The peak is happening at dec of each year. → seasonality with period = 1 year.

Example of Cyclical data:-

The cycles are not of specific time period (longer lasting than seasonal)

Market Summary > S&P 500

3,992.93

+3,853.40 (2,761.70%) ↑ all time

11 Nov, 5:06 pm GMT-5 • Disclaimer

+ Follow

1D | 5D | 1M | 6M | YTD | 1Y | 5Y | Max



Open	3,963.72	Low	3,944.82	52-wk high	4,818.62
High	4,001.48	Prev close	3,956.37	52-wk low	3,491.58

Time Series Decomposition

Time series decomposition is the method by which we can break a time series into its constituent components.

There are various methods :-

(1) Hodrick - Prescott filter: H-P filter

$y_t = T_t + C_t \rightarrow$ This algorithm decomposes the time series into trend component & cyclical component.

(2) ETS (Error - Trend - Seasonality) decomposition

$y_t = E_t + T_t + S_t \rightarrow$ This algorithm decomposes the time series into error, trend & seasonal components.