view_frames Result Recorded at time: 20.000 robot_1/odom map Broadcaster: /R1_MapAlign Broadcaster: /R0_MapAlign Broadcaster: /Stage Average rate: 10.204 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 20.100 (-0.100 sec old) Most recent transform: 20.100 (-0.100 sec old) Most recent transform: 20.000 (0.000 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.900 sec robot_1/map robot_0/map robot_1/base_footprint Broadcaster: /robot_0/Mapper Broadcaster: /Stage Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 20.000 (0.000 sec old) Most recent transform: 20.000 (0.000 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec robot_0/offset robot_1/base_link Broadcaster: /robot_0/Mapper Broadcaster: /Stage Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 20.000 (0.000 sec old) Most recent transform: 20.000 (0.000 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec robot_0/odom robot_1/base_laser_link Broadcaster: /Stage Average rate: 10.204 Hz Most recent transform: 20.000 (0.000 sec old) Buffer length: 4.900 sec robot_0/base_footprint Broadcaster: /Stage Average rate: 10.204 Hz Most recent transform: 20.000 (0.000 sec old) Buffer length: 4.900 sec robot_0/base_link Broadcaster: /Stage Average rate: 10.204 Hz Most recent transform: 20.000 (0.000 sec old) Buffer length: 4.900 sec robot 0/base laser link