

2.6 Discrete Time Markov Chain

$\{X_n: n=0,1,2,3\}$ is a stochastic process that takes on a finite \mathcal{H} of states

- If $X_n = i$, then the process is in state i at time n
- When process is in state i , there is a fixed prob. of transitioning from state i to state j - P_{ij}

$$P(X_{n+1}=j | X_n=i, X_{n-1}=i_{n-1}, X_{n-2}=i_{n-2}, \dots, X_0=i_0)$$

Markov Property

$$= P(X_{n+1}=j | X_n=i) = P_{ij}$$

The probability of going from one state to another can be represented by a state transition diagram and matrix.

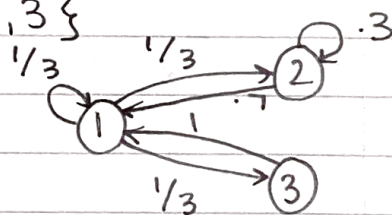
- rows represent the current state
- columns represent the future state

EX: 8.2 State Variable $X_n \in \{1,2,3\}$

$$X_n=1 \quad X_{n+1}=1,2,3 \quad \begin{matrix} 1/3 \\ 1/3 \\ 1/3 \end{matrix}$$

$$X_n=2 \quad X_{n+1}=1 \quad .7 \quad X_{n+1}=2 \quad .3$$

$$X_n=3 \quad X_{n+1}=1 \quad 1$$



matrix:

$$P = \begin{matrix} & \begin{matrix} 1 & 2 & 3 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{bmatrix} .33 & .33 & .33 \\ .7 & .3 & 0 \\ 1 & 0 & 0 \end{bmatrix} \end{matrix}$$

Suppose $X_0 = 1$ - calculate the prob of being in each state after 2 steps

$$\begin{array}{lcl} X_0 = 1 & \begin{array}{l} \swarrow 1/3 \\ \searrow 1/3 \\ \swarrow 1/3 \end{array} & \begin{array}{l} X_1 = 1 \begin{array}{l} \xrightarrow{.33} X_2 = 1 \\ \xrightarrow{.33} X_2 = 2 \\ \xrightarrow{.33} X_2 = 3 \end{array} \\ X_1 = 2 \begin{array}{l} \xrightarrow{.7} X_2 = 1 \\ \xrightarrow{.3} X_2 = 2 \end{array} \\ X_1 = 3 \xrightarrow{1} X_2 = 1 \end{array} \end{array}$$

$$P(X_2=1) = .677\bar{7}$$

$$P(X_2=2) = .211\bar{1}$$

$$P(X_2=3) = .111\bar{5}$$

$\vec{\pi}_2 \equiv$ the probability vector for each state at
step 2

$$\vec{\pi}_2 = [.6777, .2111, .1115]$$

$$\sum_0 = 1$$

$$\vec{\pi}_0 = [1 \ 0 \ 0]$$

$$\vec{\pi}_1 = [1 \ 0 \ 0] \begin{bmatrix} 1/3 & 1/3 & 1/3 \\ .7 & 0.3 & 0 \\ 1 & 0 & 0 \end{bmatrix} = [1/3 \ 1/3 \ 1/3] = \vec{\pi}_1$$

then do again for state 2

SEE R matrixPower

There is some limiting probability...

- Steady State Probability

$$\lim_{n \rightarrow \infty} \vec{\pi}_0 P^n = \vec{\pi}_* \text{ - steady state probability}$$

see R LSN 28