# Applied modeling with BART: How, Why, and When

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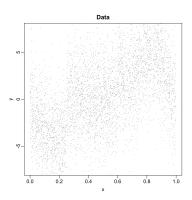
18 May 2024

## Follow along!



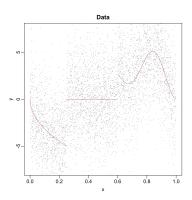
- GitHub Repo: https://go.wisc.edu/0f5xi5
- Slides & code (as RMarkdown documents & R scripts

#### Demo



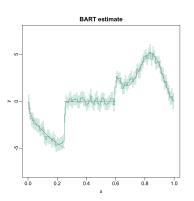
• Where's the signal?

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- Where's the signal?
- BART estimate & uncertainty estimate look pretty good!
- And all we had to was call BART::wbart(x,y)

## Nonparametric regression & classification

- Observed data:  $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$  with  $\mathbf{x}_n \in [0, 1]^p$
- Regression:  $y_n = f(\mathbf{x}_n) + \sigma \epsilon_n$ ;  $\epsilon_n \sim \mathcal{N}(0, 1)$
- Classification (w/ probit link):  $\mathbb{P}(Y = 1) = \Phi(f(x))$
- Simultaneous (and often competing) goals:
  - ▶ Prediction: value of  $f(x^*)$  &  $y^*$
  - ▶ UQ: uncertainty intervals for  $f(x^*)$  &  $y^*$
  - ▶ Variable importance/selection: on which X<sub>j</sub> does f depend?

## Approaches to learning f

- Assume  $f(\mathbf{x}) = \sum_{\mathbf{d}} \beta_{\mathbf{d}} \phi_{\mathbf{d}}(\mathbf{x})$ 
  - ▶ Basis  $\{\phi_d\}$  could be linear, polynomial, splines, Fourier, etc.
  - ▶ Estimate  $\beta_d$ 's with OLS, LASSO, Bayesian linear regression, etc.
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- Classification & regression trees
  - ► Train a single regression tree to approximate f
  - © Interpretable, accurate, avoids pre-specifying form of f
  - Often unstable & non-smooth

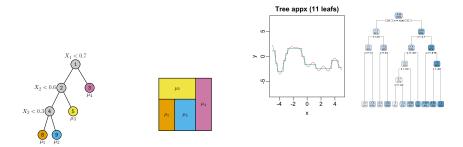
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  - Often unstable & non-smooth
- Ensemble methods
  - ▶ Approximate *f* with a (weighted) average of "weak learners":

$$\hat{f}(\boldsymbol{x}) = \sum_{m=1}^{M} w_m \hat{f}_m(\boldsymbol{x})$$

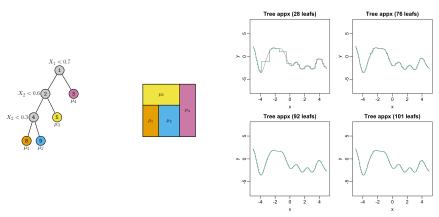
- ▶ Each  $\hat{f}_m$  may not fit data well but together they do
- © Tremendous empirical success (e.g. Netflix Prize, Kaggle)

## Step function approximations



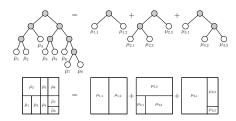
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## Step function approximations



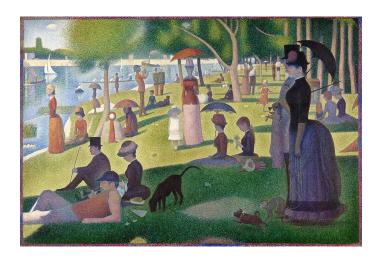
- Step functions are universal function approximators!
- Step functions can be represented as binary regression trees
- $oxed{S}$  Often need very deep tree to appx complicated f well

#### Sums of trees



- Sum of step functions is just another step function!
- Sums of regression trees is a more complicated regression tree!
- Averaging/ensembling introduces certain degree of smoothness

## Digression: Pointillism



A Sunday afternoon on the island of La Grande Jatte, Georges Seurat Source

**Preliminaries** 

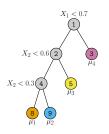
Introducing BART

BART in practice

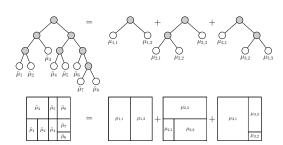
Parting Thoughts

## Bayesian Additive Regression Trees

- Regression:  $y_n = f(\mathbf{x}_n) + \sigma \varepsilon_n$ ;  $\varepsilon_n \sim \mathcal{N}(0,1) \& \mathbf{x}_n \in [0,1]^p$
- Main idea: approximate f(x) with sum of M regression trees
- Prior encourages trees to be "weak learners"
- Gibbs sampler: update each tree conditionally on fit of all others

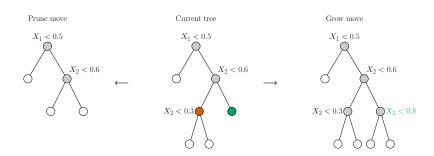






## Posterior computation & implementation

- Metropolis-within-Gibbs: update each tree sequentially fixing others
  - ▶ Update decision tree with MH (randomly grow or prune tree)
  - ▶ Update leaf parameters / tree outputs conditional on tree
- No optimization involved!!



#### Outline

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## Several implementations

- BART: Sparapani, Spanbauer, & McCulloch (2021)
  - Support for many extensions (e.g., classification, survival)
  - ▶ Based on efficient C++ regression tree class & sampler
- **dbarts**: Dorie (2020)
  - ▶ Makes it easy to include a sum-of-trees component in a larger model
  - ► E.g.  $y_i = \mathbf{x}_i^{\top} \beta + f(\mathbf{x}_i) + \sigma \epsilon_i$
- flexBART: available at (GitHub repo)
  - ► Flexibly handle categorical predictors and observations on networks
  - Much faster than BART
  - Still under active development
- bartMachine: Kapelner & Bleich (2014)
  - Core fitting written in Java
  - ⊖ Non-trivial overhead in installing & setting up system
- PyMC-BART: From the PyMC team
  - ▶ Uses sequential Monte Carlo & is rather different than the above

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- Partial dependence plots
  - $\overline{f}_{j}(x) = n^{-1} \sum_{i} f(x_{i,1}, \dots, x_{i,j-1}, x, x_{i,j+1}, \dots, x_{i,p})$
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  - ▶ Implemented in dbarts::pdbart and easy to do by hand
- Linero (2018) modifies BART so that
  - ▶ Split on  $X_i$  with prob.  $\theta_i$  (in prior & in MH transition)
  - $\triangleright$   $\theta$  given a sparsity-inducing Dirichlet prior
  - ▶ Adaptation: more accepted splits on  $X_j \Rightarrow$  more proposed splits on  $X_j$
  - ▶ Select  $X_j$  if more than 50% of ensembles involve a split on  $X_j$

#### BART extensions

- Survival/time-to-event: Sparapani et al. (2016)
- Heteroscedasticity: Pratola et al. (2020)
  - $y_n = f(\mathbf{x}_n) + \sigma(\mathbf{x}_n)\varepsilon_n$ , write  $\log(\sigma^2(\mathbf{x}))$  as a sum-of-trees!
- Monotonic BART: Chipman et al. (2019)
- Smooth functions: Starling et al. (2020); Yee & D. (2024+)
- Varying coefficient models: D. et al. (2020+)
  - $Y = \beta_0(Z) + \beta_1(Z)X_1 + \dots + \beta_p(Z)X_p + \sigma\epsilon$
  - ► E.g. time & demographic varying mediation effects
- Expected runs/points: Yee & D. (2024)
- Conditional density estimates: Orlandi et al. (2024+)
- Causal inference: Hill (2011) & Hahn et al (2020)

## Concluding remarks

- BART: approximate f with sum of regression trees
- Avoids pre-specification of functional form of  $f(x) = \mathbb{E}[Y \mid X = x]$
- Excellent performance off-the-shelf
- Lots still in development ... get in touch!



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## Thanks, y'all!

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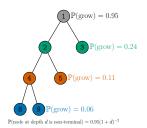
Website: https://skdeshpande91.github.io

Twitter: @skdeshpande91

Workshop Material: https://go.wisc.edu/0f5xi5

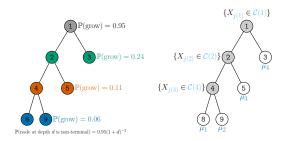


## A prior over regression trees



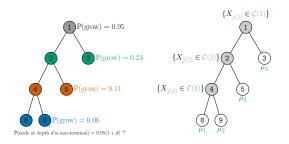
- Branching process prior on graphical structure
- Overwhelming prior prob. that tree depth < 5

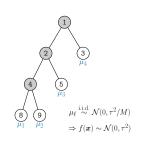
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- Decision rule  $\{X_j \in \mathcal{C}\}$ 
  - $\triangleright$   $X_i$  continuous:  $\mathcal{C}$  is an interval [0,c)
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- Leaf outputs  $\mu_{\ell} \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \tau^2/M)$

## Decision rule prior

- 1. Draw  $j \sim \text{Multinomial}(\theta_1, \dots, \theta_p)$  where  $\theta_i = \mathbb{P}(\text{split on } X_i)$
- 2. Compute set of all available values  $A_i$ 
  - $\triangleright$   $A_i$  determined by rules at ancestors
  - $X_i$  continuous  $o \mathcal{A}$  is an interval
  - $ightharpoonup X_j$  categorical  $ightharpoonup \mathcal{A}$  is discrete set
- 3. Draw random subset  $\mathcal C$  from  $\mathcal A_j$ 
  - ▶  $X_j$  ccontinuous: draw  $c \sim \mathcal{U}(A_j)$  and set C = [0, c)
  - ▶  $X_j$  categorical: assign elements of  $A_j$  to C with probability 0.5

