Applied modeling with BART: How, Why, and When

Sameer K. Deshpande

University of Wisconsin–Madison

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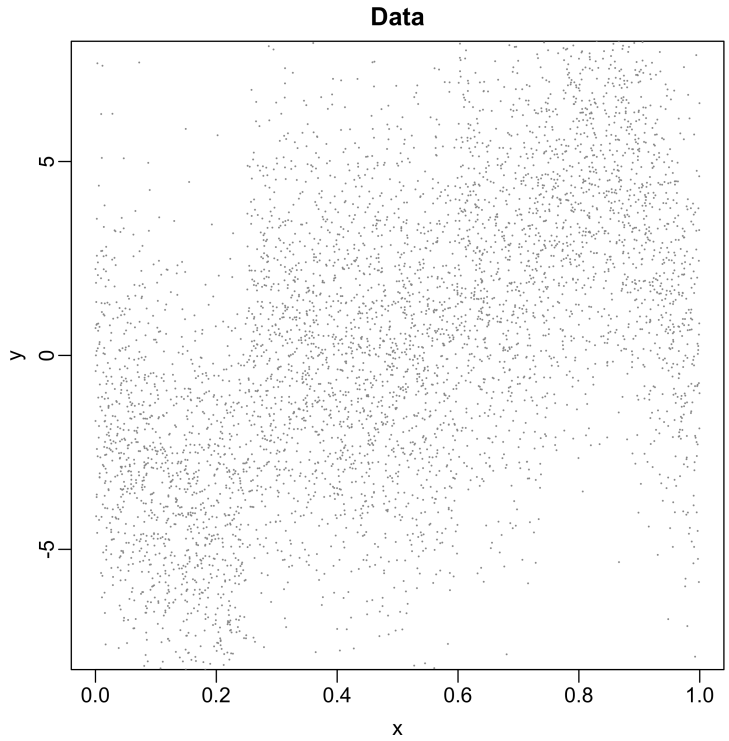
Follow along!

- GitHub Repo: https://go.wisc.edu/0f5xi5
- Slides & code (as RMarkdown documents & R scripts

Demo



- Where's the signal?

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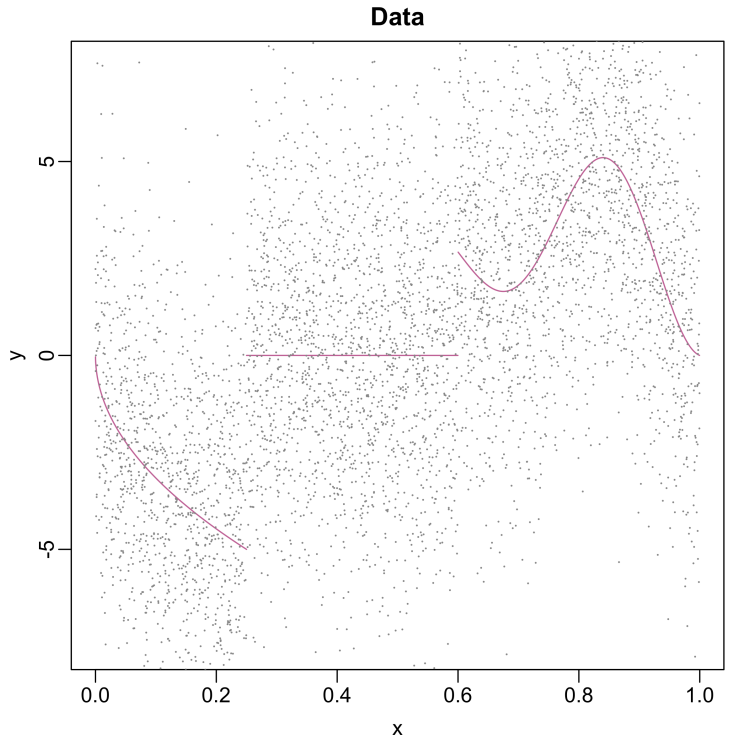

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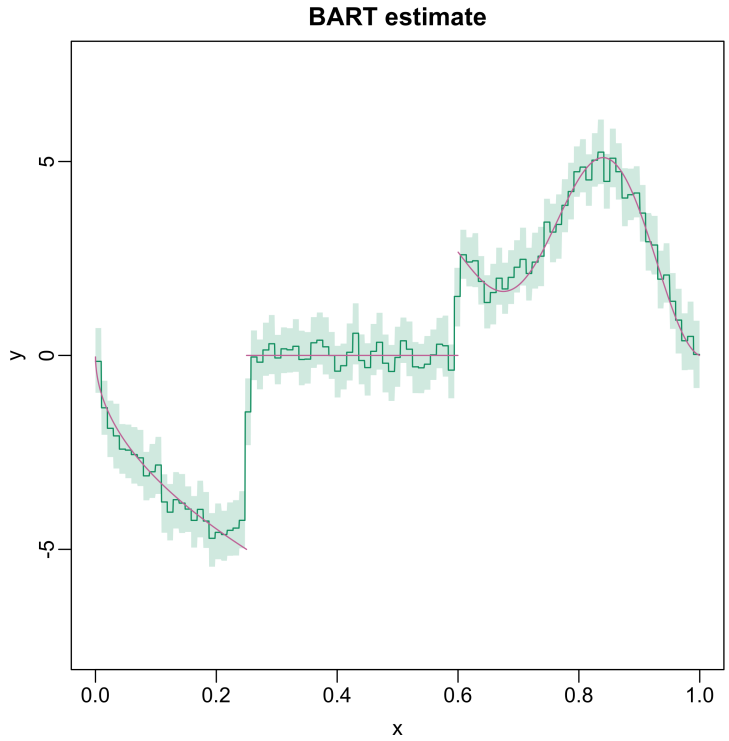

- Where's the signal?
- ☺ BART estimate & uncertainty estimate look pretty good!
- ☺ And all we had to was call `BART::wbart(x,y)`

Nonparametric regression & classification

- Observed data: $(\boldsymbol{x}_1, y_1), \ldots, (\boldsymbol{x}_n, y_n)$ with $\boldsymbol{x}_n \in [0,1]^p$
- Regression: $y_n = f(\boldsymbol{x}_n) + \sigma\epsilon_n; \epsilon_n \sim \mathcal{N}(0,1)$
- Classification (w/ probit link): $\mathbb{P}(Y = 1) = \Phi(f(\boldsymbol{x}))$
- Simultaneous (and often competing) goals:
  - Prediction: value of $f(\boldsymbol{x}^\star)$ & $y^\star$
  - UQ: uncertainty intervals for $f(\boldsymbol{x}^\star)$ & $y^\star$
  - Variable importance/selection: on which X_j does f depend?

Approaches to learning f

- Assume $f(\boldsymbol{x}) = \sum_d \beta_d \phi_d(\boldsymbol{x})$
  - Basis $\{\phi_d\}$ could be linear, polynomial, splines, Fourier, etc.
  - Estimate β_d's with OLS, LASSO, Bayesian linear regression, etc.
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- Classification & regression trees
  - Train a single regression tree to approximate f
  - 🙂 Interpretable, accurate, avoids pre-specifying form of f
  - ☹ Often unstable & non-smooth

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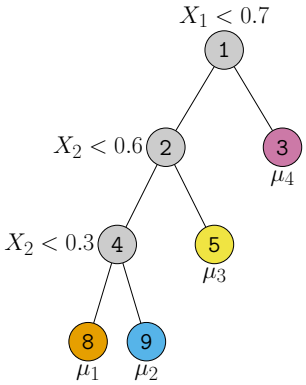
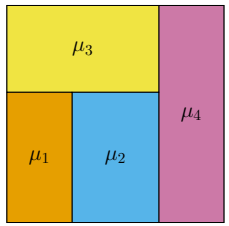
  - ☹ Often unstable & non-smooth
- Ensemble methods
  - Approximate f with a (weighted) average of "weak learners":

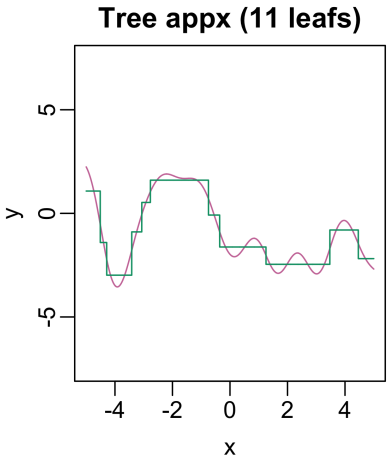
$$\hat{f}(\boldsymbol{x}) = \sum_{m=1}^{M} w_m \hat{f}_m(\boldsymbol{x})$$

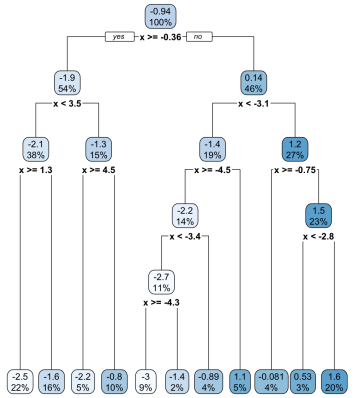
  - Each $\hat{f}_m$ may not fit data well but together they do
  - ☺ Tremendous empirical success (e.g. Netflix Prize, Kaggle)

Step function approximations



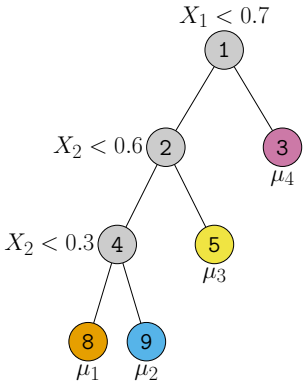


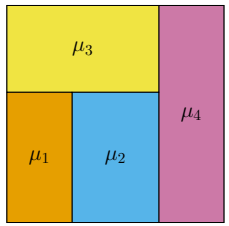


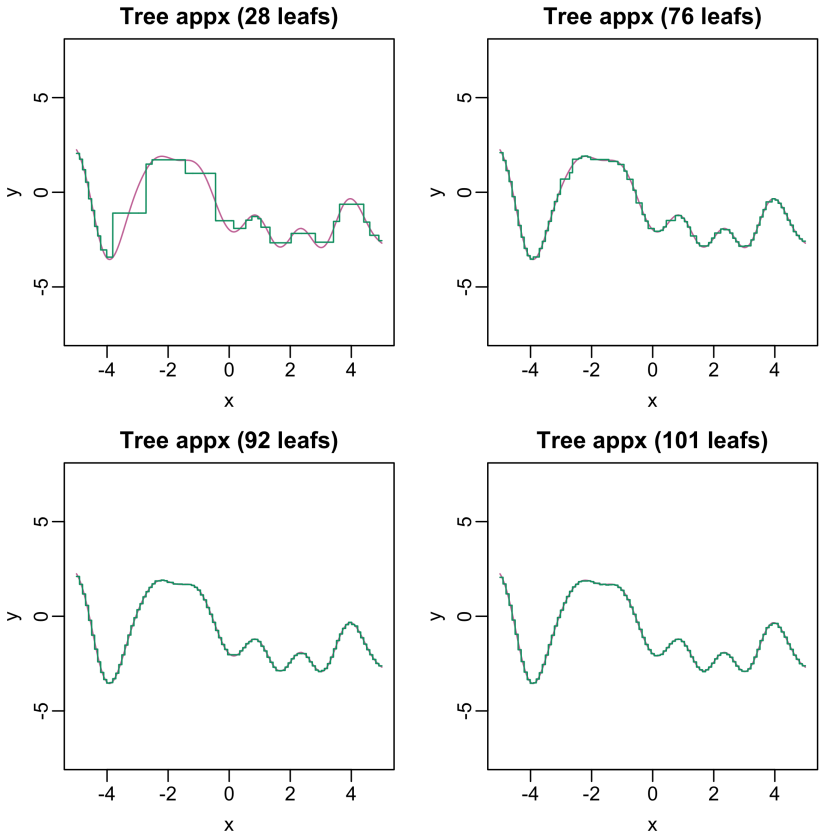


- Step functions are universal function approximators!
- Step functions can be represented as binary regression trees

Step function approximations







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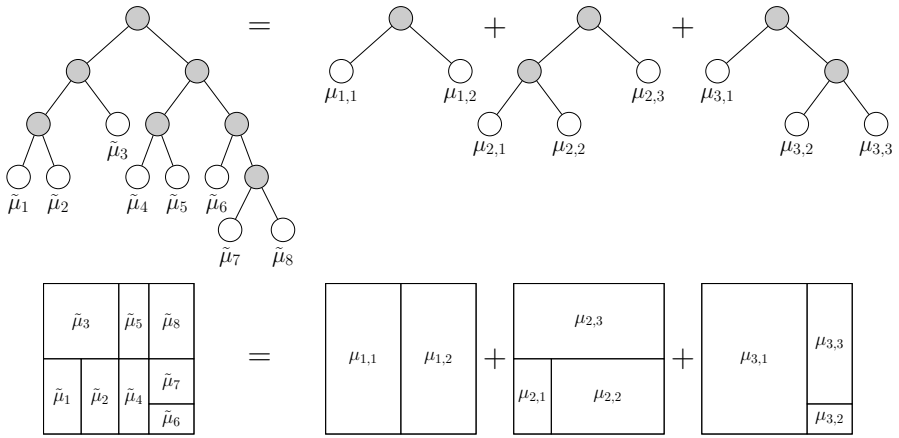
- Step functions can be represented as binary regression trees

☙ Often need very deep tree to appx complicated f well

Sums of trees



- Sum of step functions is just another step function!
- Sums of regression trees is a more complicated regression tree!
- ☺ Averaging/ensembling introduces certain degree of smoothness

Digression: Pointillism

A Sunday afternoon on the island of La Grande Jatte, Georges Seurat

Source

Preliminaries

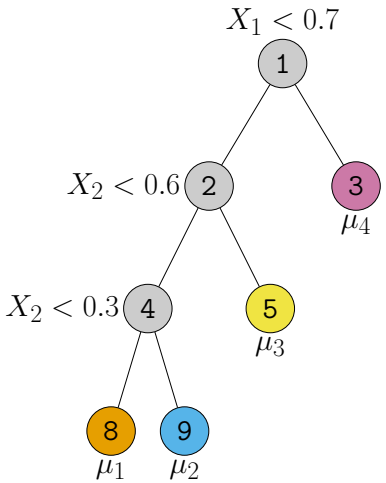
Introducing BART

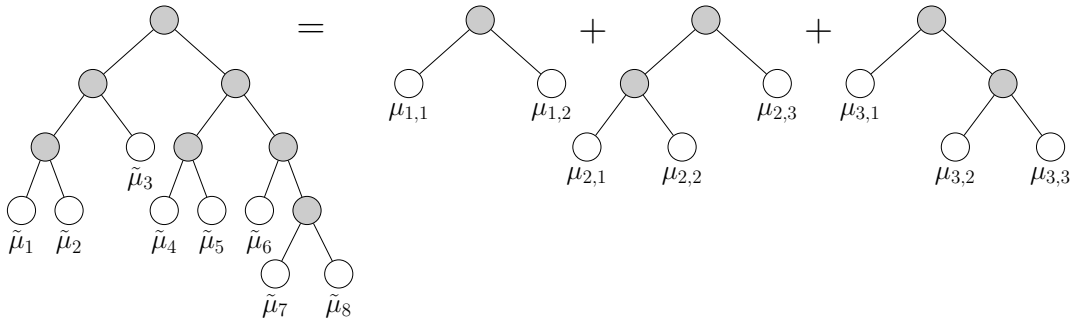
BART in practice

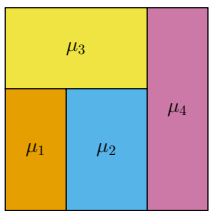
Parting Thoughts

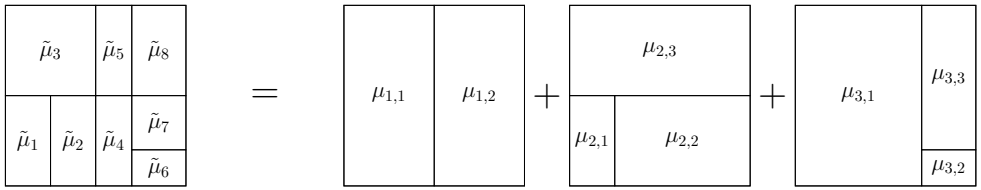
Bayesian Additive Regression Trees

- Regression: $y_n = f(\boldsymbol{x}_n) + \sigma\varepsilon_n; \varepsilon_n \sim \mathcal{N}(0,1)$ & $\boldsymbol{x}_n \in [0,1]^p$
- Main idea: approximate $f(\boldsymbol{x})$ with sum of M regression trees
- Prior encourages trees to be "weak learners"
- Gibbs sampler: update each tree conditionally on fit of all others



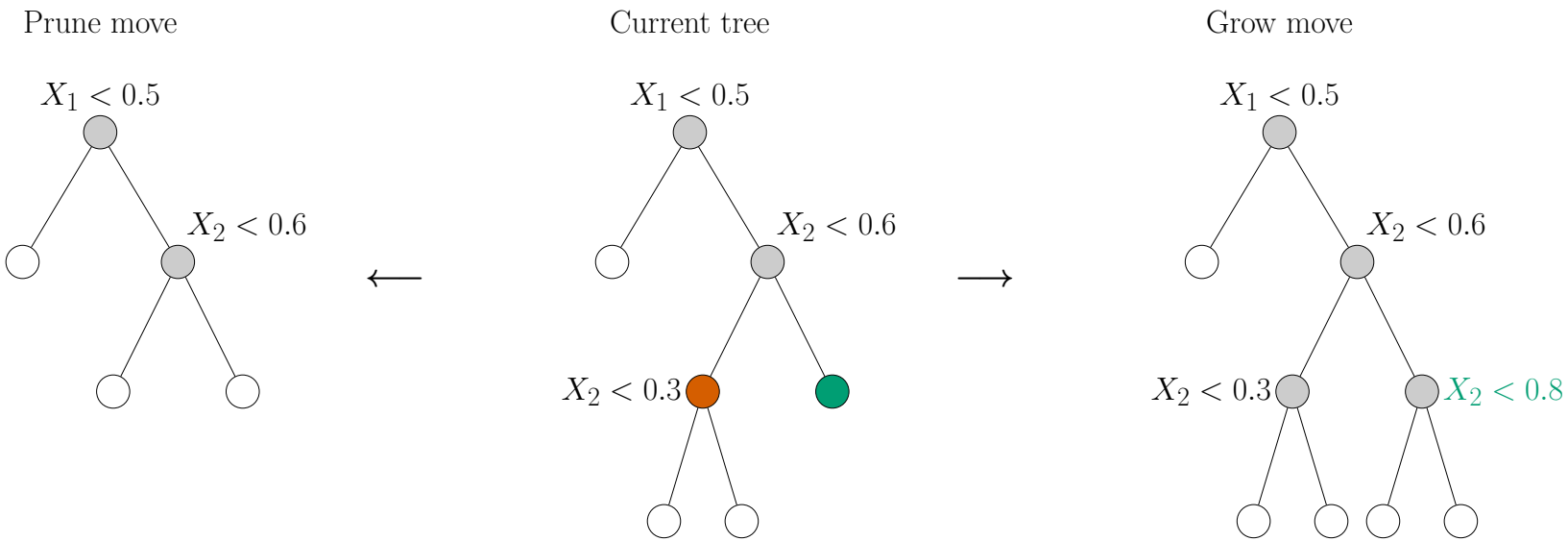






Posterior computation & implementation

- Metropolis-within-Gibbs: update each tree sequentially fixing others
  - Update decision tree with MH (randomly grow or prune tree)
  - Update leaf parameters / tree outputs conditional on tree
- No optimization involved!!



Outline

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Several implementations

- **BART**: Sparapani, Spanbauer, & McCulloch (2021)
  - Support for many extensions (e.g., classification, survival)
  - Based on efficient C++ regression tree class & sampler
- **dbarts**: Dorie (2020)
  - Makes it easy to include a sum-of-trees component in a larger model
  - E.g. $y_i = \boldsymbol{x}_i^\top \beta + f(\boldsymbol{x}_i) + \sigma\epsilon_i$
- **flexBART**: available at (GitHub repo)
  - Flexibly handle categorical predictors and observations on networks
  - Much faster than **BART**
  - Still under active development
- **bartMachine**: Kapelner & Bleich (2014)
  - Core fitting written in Java
  - 😑 Non-trivial overhead in installing & setting up system
- **PyMC-BART**: From the PyMC team
  - Uses sequential Monte Carlo & is rather different than the above

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- Partial dependence plots
  - $\overline{f}_j(x) = n^{-1} \sum_i f(x_{i,1}, \ldots, x_{i,j-1}, x, x_{i,j+1}, \ldots, x_{i,p})$
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  - Implemented in `dbarts::pdbart` and easy to do by hand
- Linero (2018) modifies BART so that
  - Split on X_j with prob. θ_j (in prior & in MH transition)
  - $\boldsymbol{\theta}$ given a sparsity-inducing Dirichlet prior
  - Adaptation: more accepted splits on $X_j \Rightarrow$ more proposed splits on X_j
  - Select X_j if more than 50% of ensembles involve a split on X_j

BART applications & extensions

- Expected runs & strike probs.: Yee & D. (2024)
- Survival/time-to-event: Sparapani et al. (2016)
- Heteroscedasticity: Pratola et al. (2020)
  - $y_n = f(\boldsymbol{x}_n) + \sigma(\boldsymbol{x}_n)\varepsilon_n$, write $\log(\sigma^2(\boldsymbol{x}))$ as a sum-of-trees!
- Monotonic BART: Chipman et al. (2019)
- Smooth functions: Starling et al. (2020); Yee & D. (2024+)
- Varying coefficient models: D. et al. (2020+)
  - $Y = \beta_0(Z) + \beta_1(Z)X_1 + \cdots + \beta_p(Z)X_p + \sigma\epsilon$
  - E.g. time & demographic varying mediation effects
- Conditional density estimates: Orlandi et al. (2024+)
- Causal inference: Hill (2011) & Hahn et al (2020)

Concluding remarks

- BART: approximate f with sum of regression trees
- Avoids pre-specification of functional form of $f(\boldsymbol{x})$
- Excellent performance off-the-shelf
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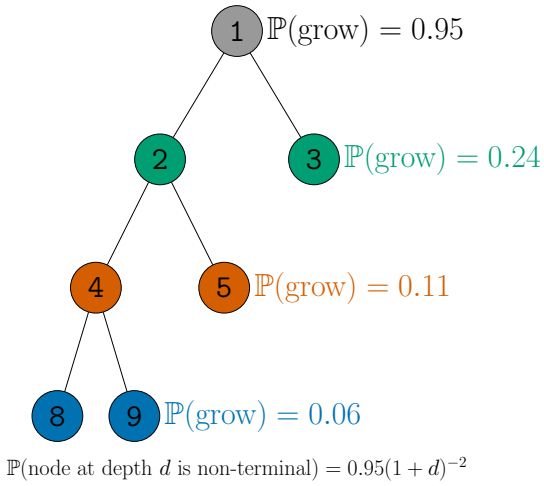
Thanks, y'all!

Email: sameer.deshpande@wisc.edu
Website: https://skdeshpande91.github.io
Twitter: @skdeshpande91
Workshop Material: https://go.wisc.edu/0f5xi5

A prior over regression trees



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- Overwhelming prior prob. that tree depth < 5

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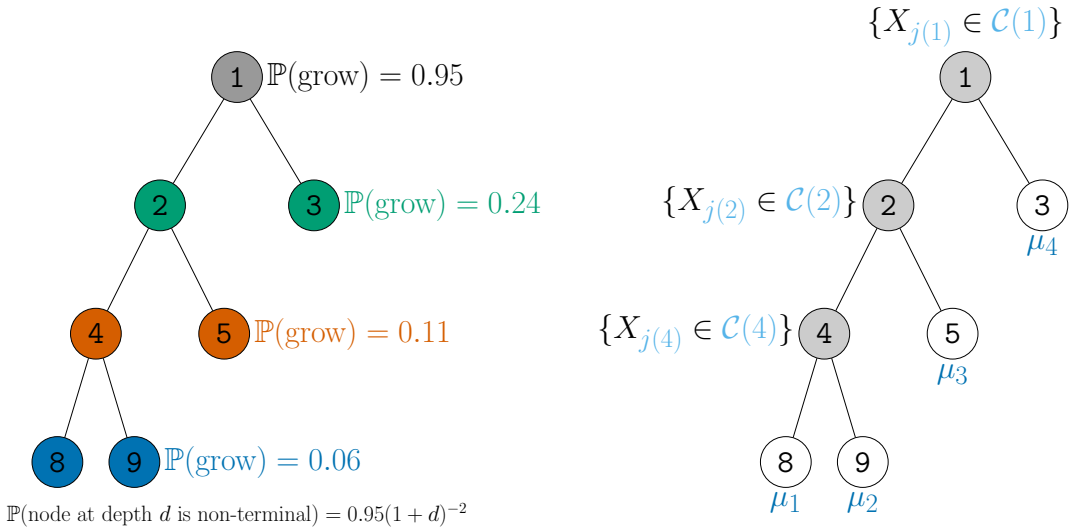

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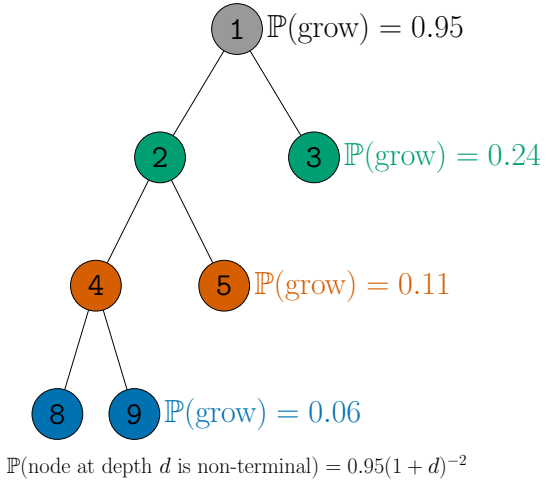
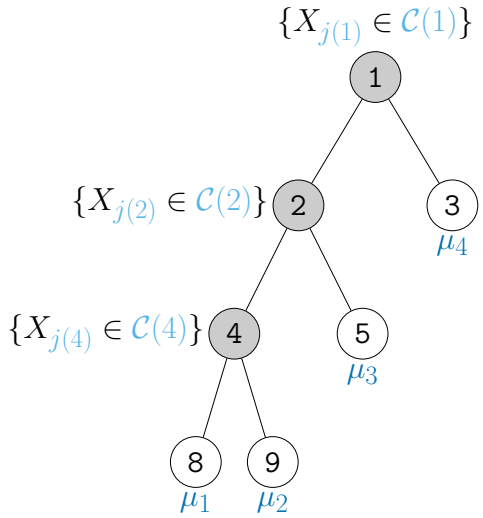
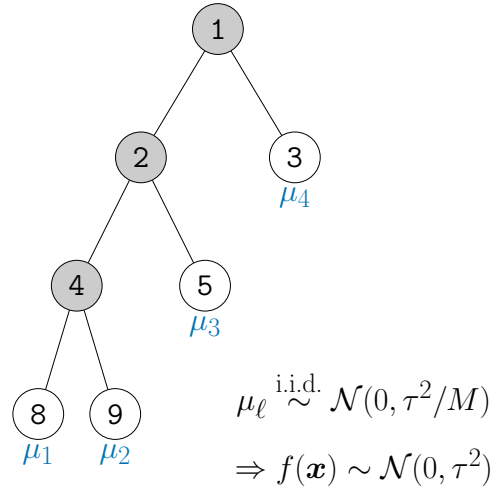
- Decision rule $\{X_j \in \mathcal{C}\}$
  - X_j continuous: $\mathcal{C}$ is an interval $[0, c)$
  - X_j categorical: $\mathcal{C}$ is a discrete subset of X_j's levels

A prior over regression trees







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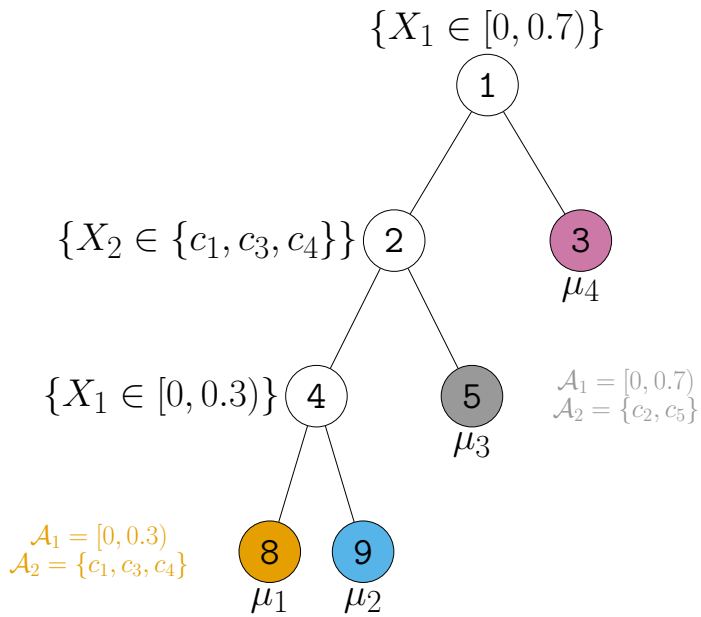
- Leaf outputs $\mu_\ell \overset{\text{i.i.d.}}{\sim} \mathcal{N}(0, \tau^2/M)$

Decision rule prior

1. Draw $j \sim \text{Multinomial}(\theta_1, \ldots, \theta_p)$ where $\theta_j = \mathbb{P}(\text{split on } X_j)$
2. Compute set of all available values $\mathcal{A}_j$
   - $\mathcal{A}_j$ determined by rules at ancestors
   - X_j continuous $\rightarrow$ $\mathcal{A}$ is an interval
   - X_j categorical $\rightarrow$ $\mathcal{A}$ is discrete set
3. Draw random subset $\mathcal{C}$ from $\mathcal{A}_j$
   - X_j ccontinuous: draw $c \sim \mathcal{U}(\mathcal{A}_j)$ and set $\mathcal{C} = [0, c)$
   - X_j categorical: assign elements of $\mathcal{A}_j$ to $\mathcal{C}$ with probability 0.5