



# SkePU

<https://skepu.github.io>

## SkePU Framework Introduction & Tutorial

August Ernstsson      Christoph Kessler

{firstname.lastname}@liu.se

Linköping University, Sweden



LINKÖPING  
UNIVERSITY



## Basic Topics

- ▶ Skeleton Programming
- ▶ SkePU Introduction and History
- ▶ Using SkePU
- ▶ Compilation Options and Backend Selection
- ▶ Smart Containers and Consistency Model

## Advanced Topics

- ▶ SkePU in Current Research
  - ▶ Lazy Skeleton Evaluation
  - ▶ Multi-variant User Functions
  - ▶ Deterministic Pseudo-Random Number Generation

## Intermediate Topics

- ▶ Skeletons in depth
  - ▶ Map
  - ▶ Reduce
  - ▶ MapReduce
  - ▶ Scan
  - ▶ MapOverlap
  - ▶ MapPairs
  - ▶ MapPairsReduce
- ▶ Nested User Functions
- ▶ SkePU Standard Library
  - ▶ BLAS
  - ▶ Deterministic PRNG
  - ▶ Image Filters
  - ▶ Utilities

## Other

- ▶ Live Demo
- ▶ Behind the Scenes

- Currently the best information resource on SkePU is August Ernstssons licentiate thesis (2020)
  - <http://liu.diva-portal.org/smash/record.jsf?pid=diva2:1472256>
- See also the user guide on <https://skepu.github.io> for more concrete instructions on e.g. installation.

# Skeleton Programming

## Programming parallel systems is hard!

- Resource utilization
- Synchronization, Communication
- Memory consistency
- Different hardware architectures, heterogeneity

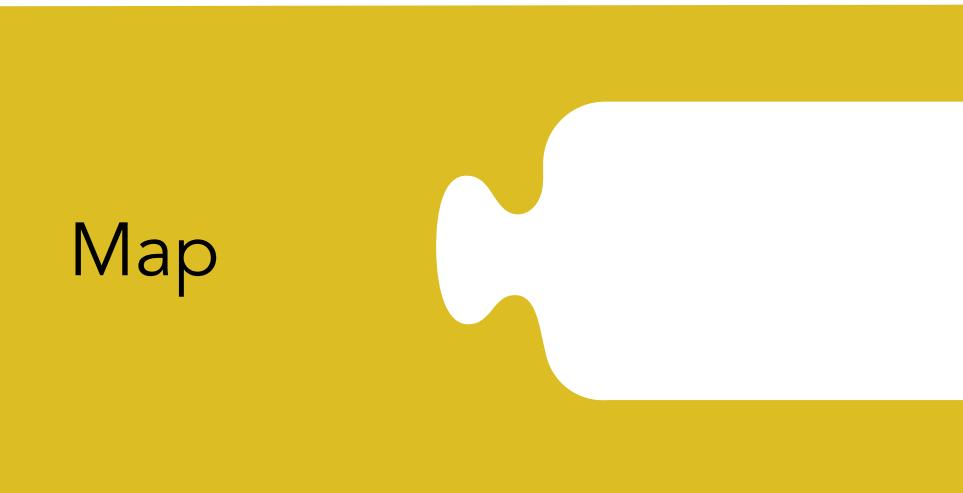
## Skeleton programming (algorithmic skeletons)

- A high-level parallel programming concept
- Inspired by functional programming
- Generic computational patterns
- Abstracts architecture-specific issues

## Skeletons

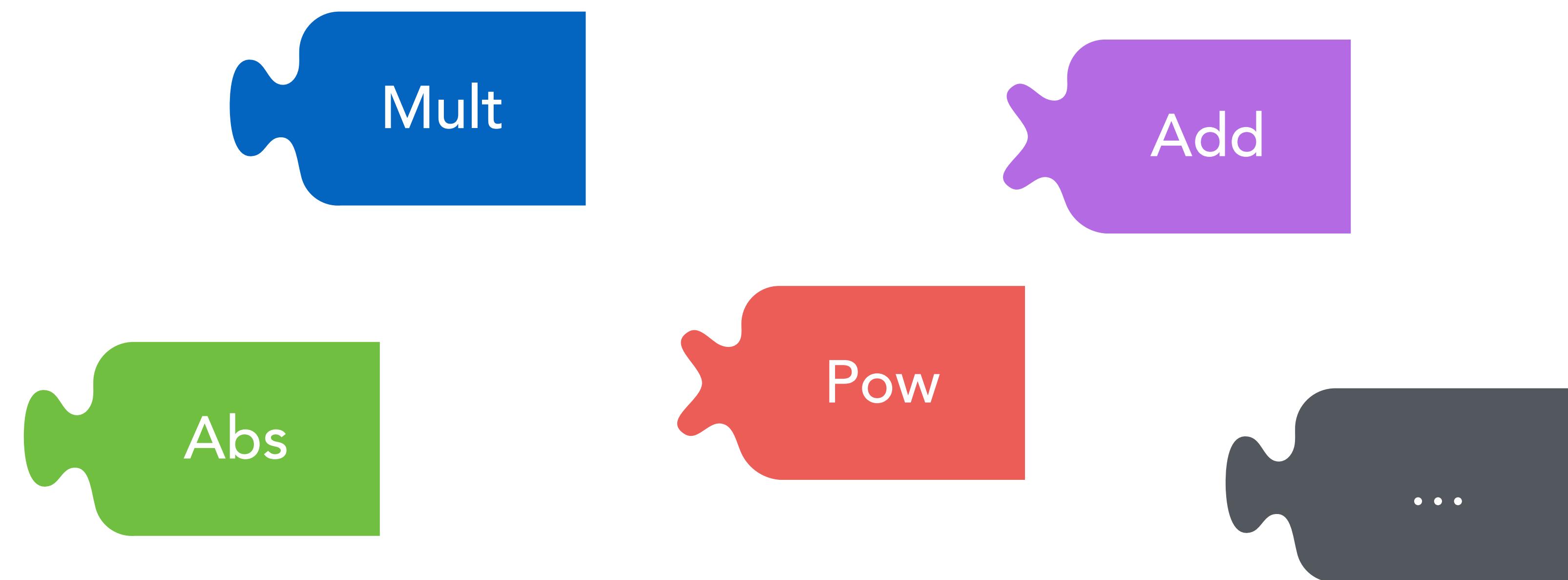
Parametrizable higher-order constructs

- Map
- Reduce
- MapReduce
- Scan
- and others



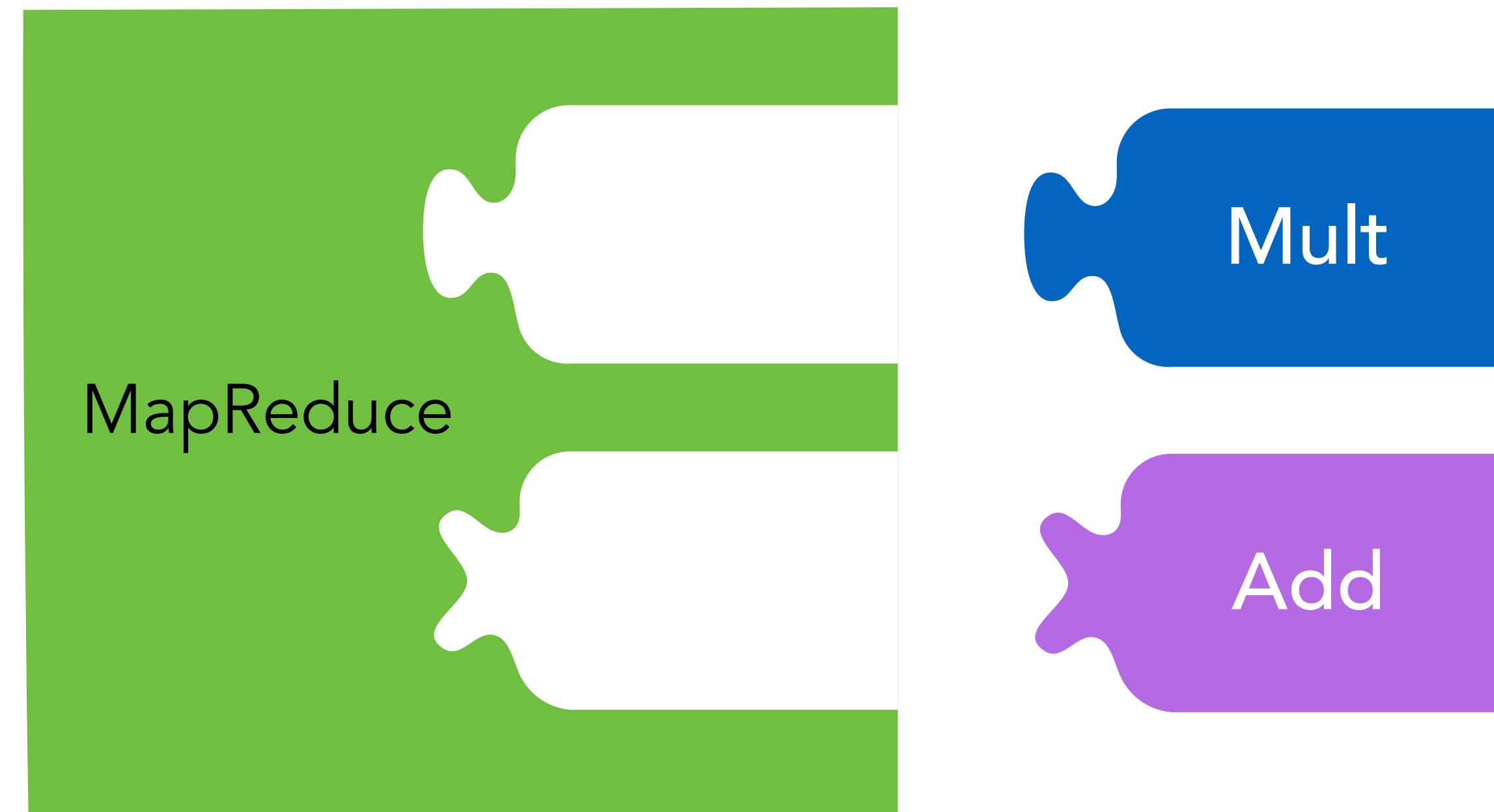
## User functions

User-defined operators



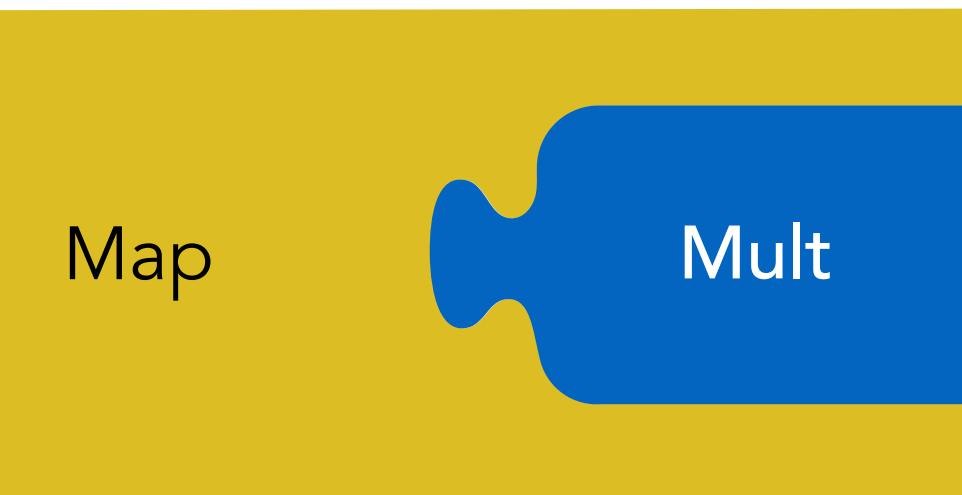
## Skeleton parametrization example

### Dot product operation

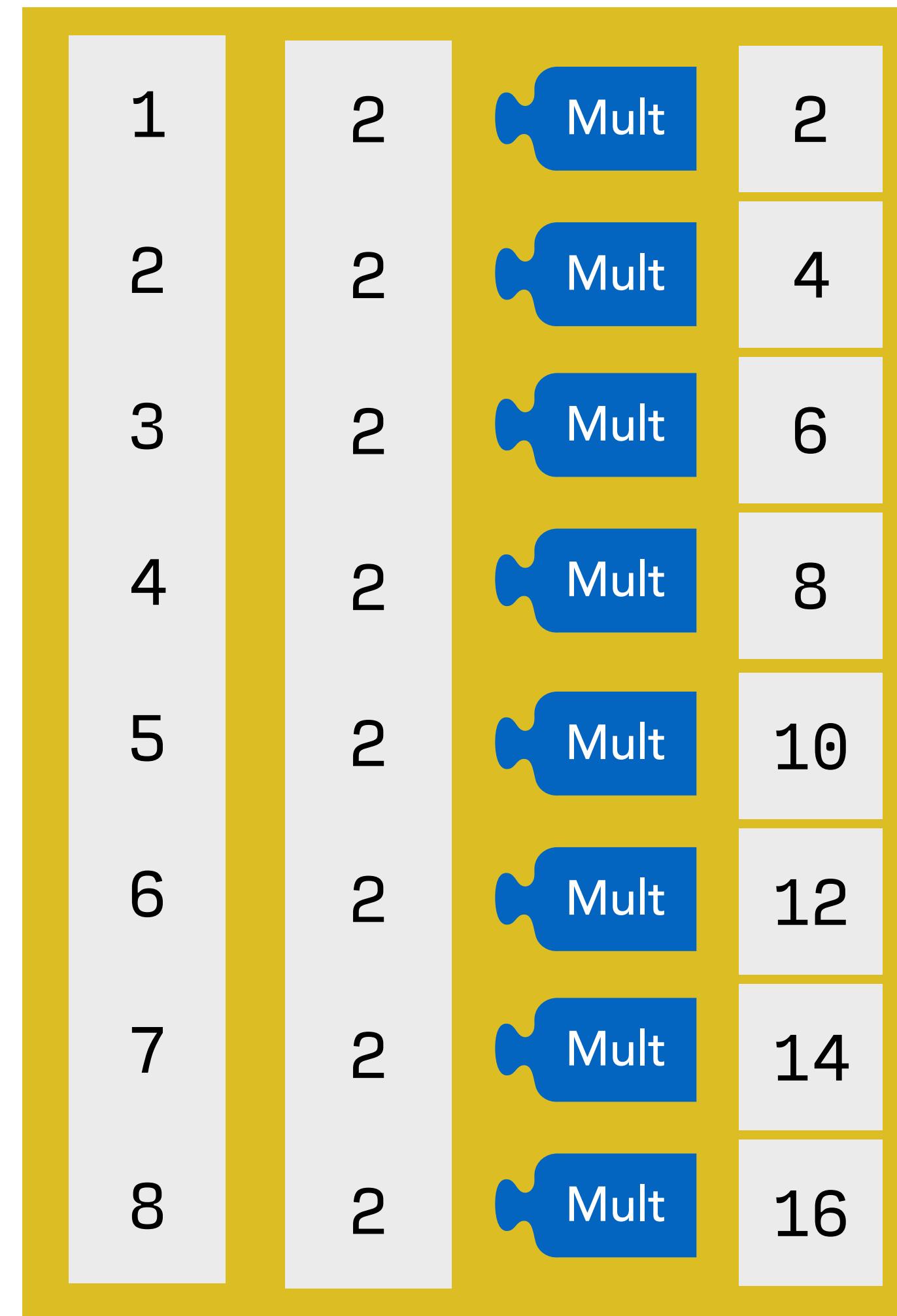


## Sequential algorithm

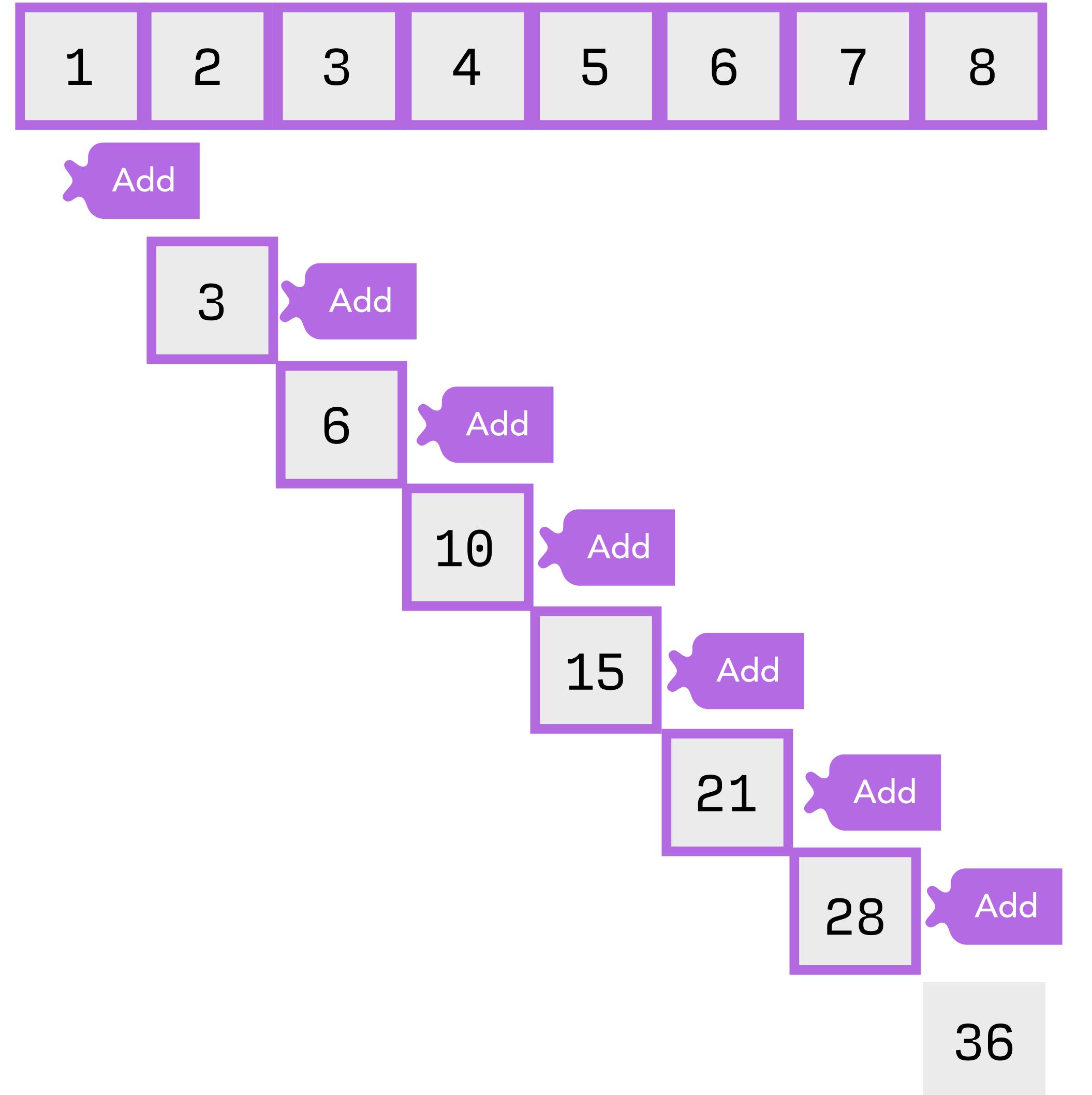
1	2	Mult	2
2	2	Mult	4
3	2	Mult	6
4	2	Mult	8
5	2	Mult	10
6	2	Mult	12
7	2	Mult	14
8	2	Mult	16



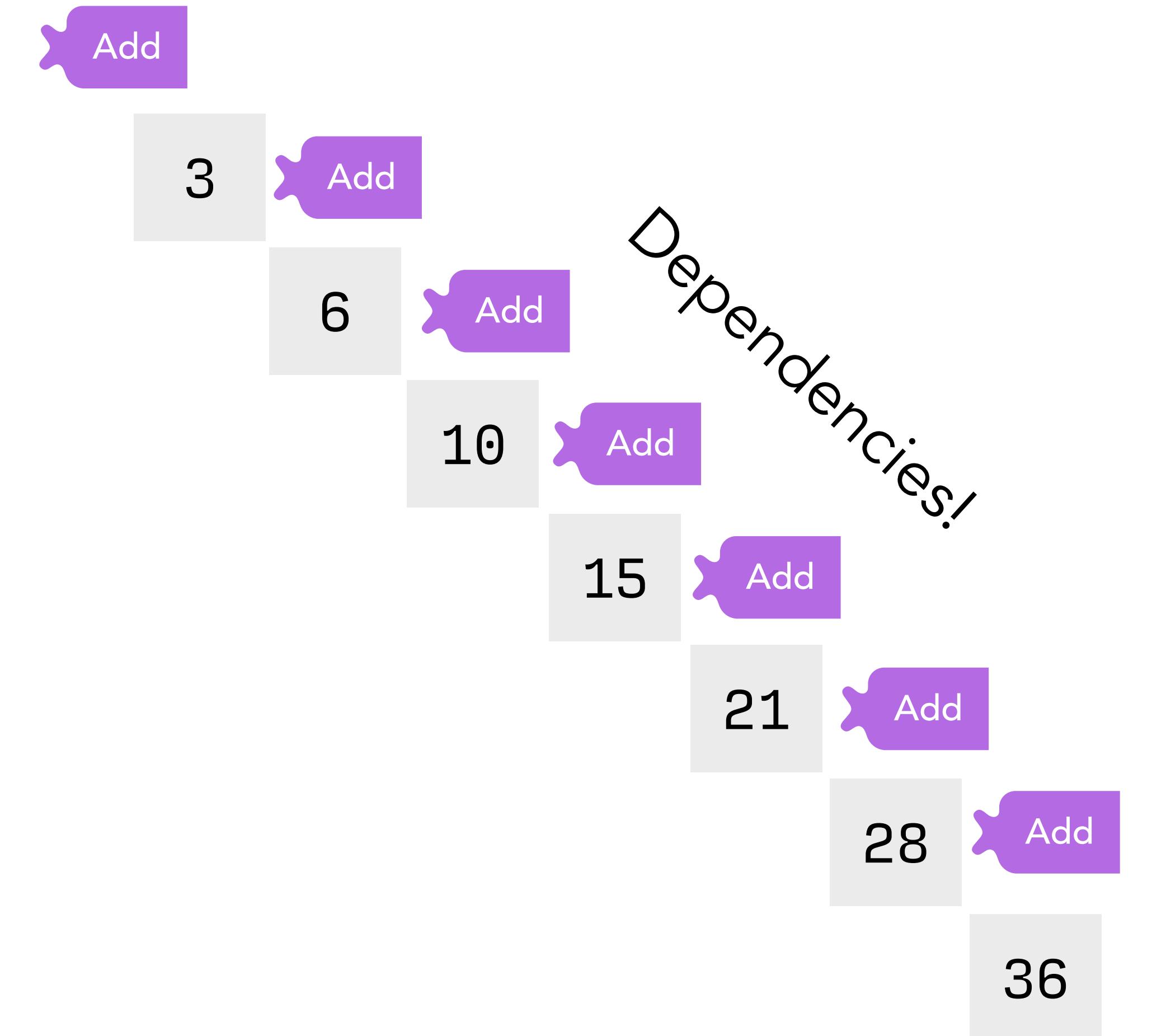
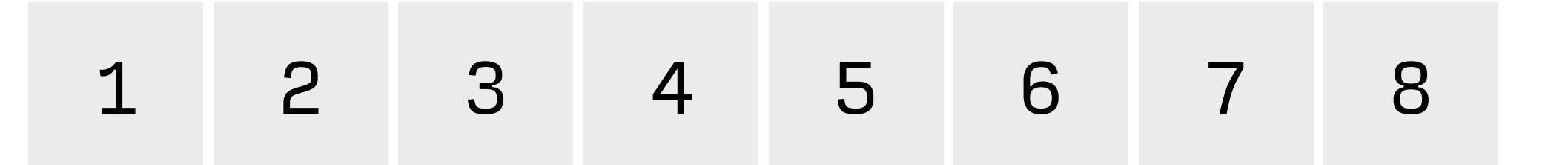
## Parallel algorithm



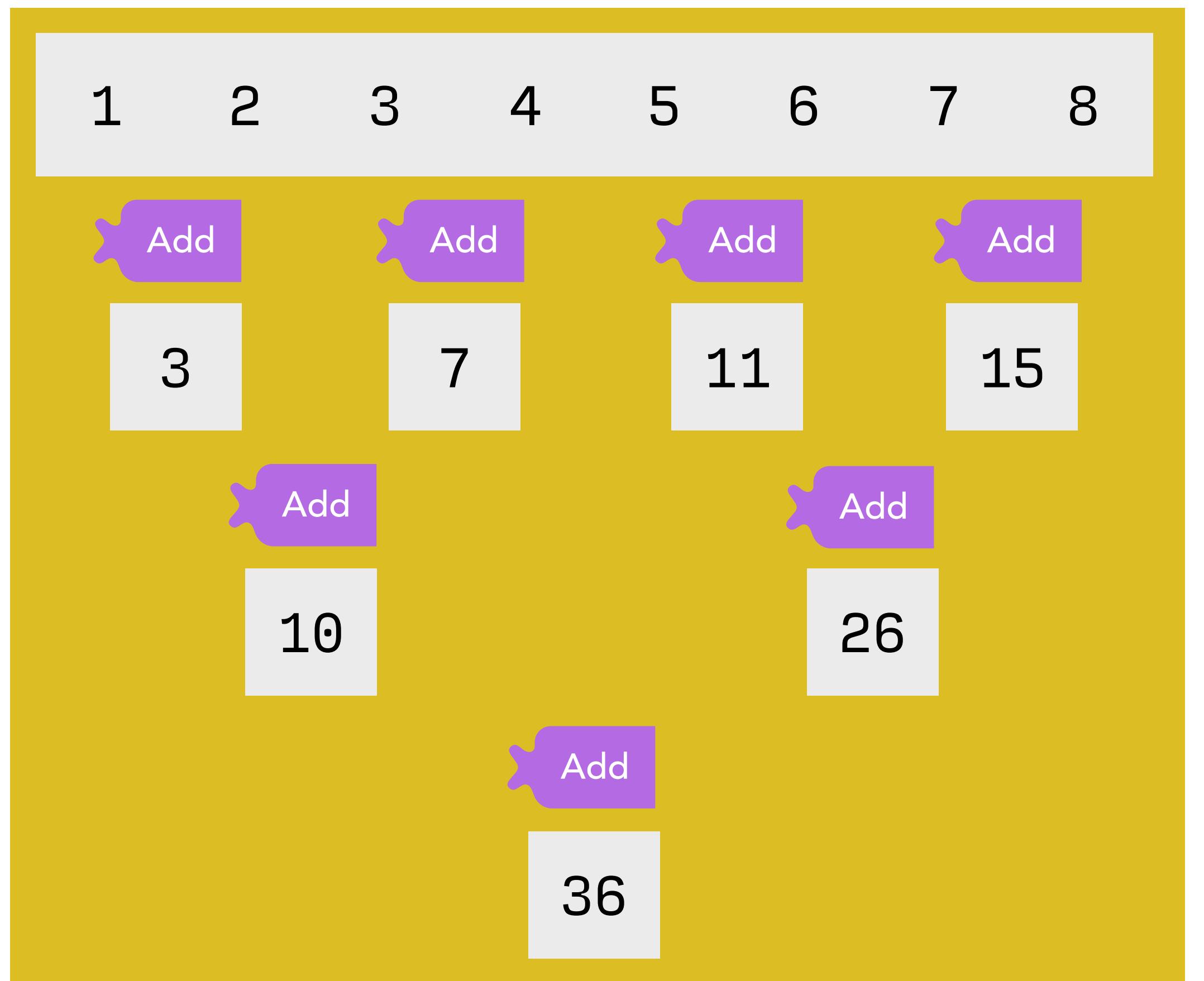
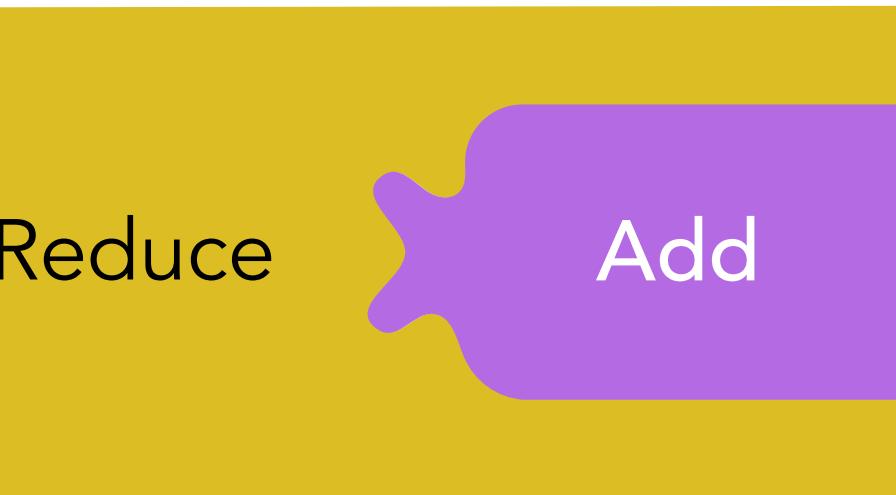
## Sequential algorithm



## Parallel algorithm?



## Parallel algorithm (assuming associativity)



# SkePU Introduction and History

- SkePU uses “modern” C++

```
// "auto" type specifier
auto addOneMap = skepu::Map<1>(addOneFunc);

skepu::Vector<float> input(size), res(size);
input.randomize(0, 9);

// Lambda expression
auto dur = skepu::benchmark::measureExecTime([&
{
    addOneMap(res, input);
});
```

capture by  
reference

- Implementation reliant on variadic templates, template metaprogramming, and other C++11 features

- ✓ Efficient parallel algorithms
- ✓ Accessible interface
- ✓ Memory management and data movement
- ✓ Automatic backend selection and tuning

- **SkePU 1**, public release **2010**

Enmyren, Kessler, HLPP 2010  
<https://doi.org/10.1145/1863482.1863487>  
(See website for more publications)

- C++ template-based interface (limited arity)
- Multi-backend using macro-based code generation

- **SkePU 2**, public release **2016**

Ernstsson, Li, Kessler, Int J Parallel Prog 46, 62–80 (2018)  
<https://doi.org/10.1007/s10766-017-0490-5>

- C++11 variadic template interface (flexible arity)
- Multi-backend using source-to-source precompiler

- **SkePU 2.1 (2017)** Experimental feature: Lazy evaluation

Ernstsson, Kessler,  
Concurrency Computat Pract Exper. 2019; 31:e5003  
<https://doi.org/10.1002/cpe.5003>

- **SkePU 2.2**, public release **2018**

- Hybrid CPU-GPU backends

Öhberg, Ernstsson, Kessler,  
J Supercomput 76, 5038–5056 (2020)  
<https://doi.org/10.1007/s11227-019-02824-7>

- **SkePU 2.3 (2019)** Experimental feature: Multi-variant user functions

Ernstsson, Kessler,  
Parallel Computing: Technology Trends,  
IOS PRESS , 2020, Vol. 36, s. 475-484  
<http://doi.org/10.3233/APC200074>

- **SkePU 3**, public release **2020**: Expanding skeleton set, container set, and expressivity

- MapPairs, MapPairsReduce

Ernstsson, Ahlqvist, Zouzoula, Kessler,  
*Int J Parallel Prog* (2021).

<https://doi.org/10.1007/s10766-021-00704-3>

- Tensor containers (3D and 4D) and new “proxy” containers MatRow, MatCol

- Cluster backend with StarPU-MPI

Panagiotou, Ernstsson, Ahlqvist, Papadopoulos, Kessler, Soudris,  
SCOPES '20 proceedings, Pages 74–77  
<https://doi.org/10.1145/3378678.3391889>

- Improved syntax and memory consistency model

- Dynamic scheduling

Papadopoulos et al.,  
*IEEE Transactions on Parallel and Distributed Systems*  
<https://doi.org/10.1109/TPDS.2021.3104257>

- **SkePU 3.1**, public release **2021**: SkePU “standard library”

- Complex number API

- BLAS (level 1 + dense level 2, 3)

- Deterministic PRNG

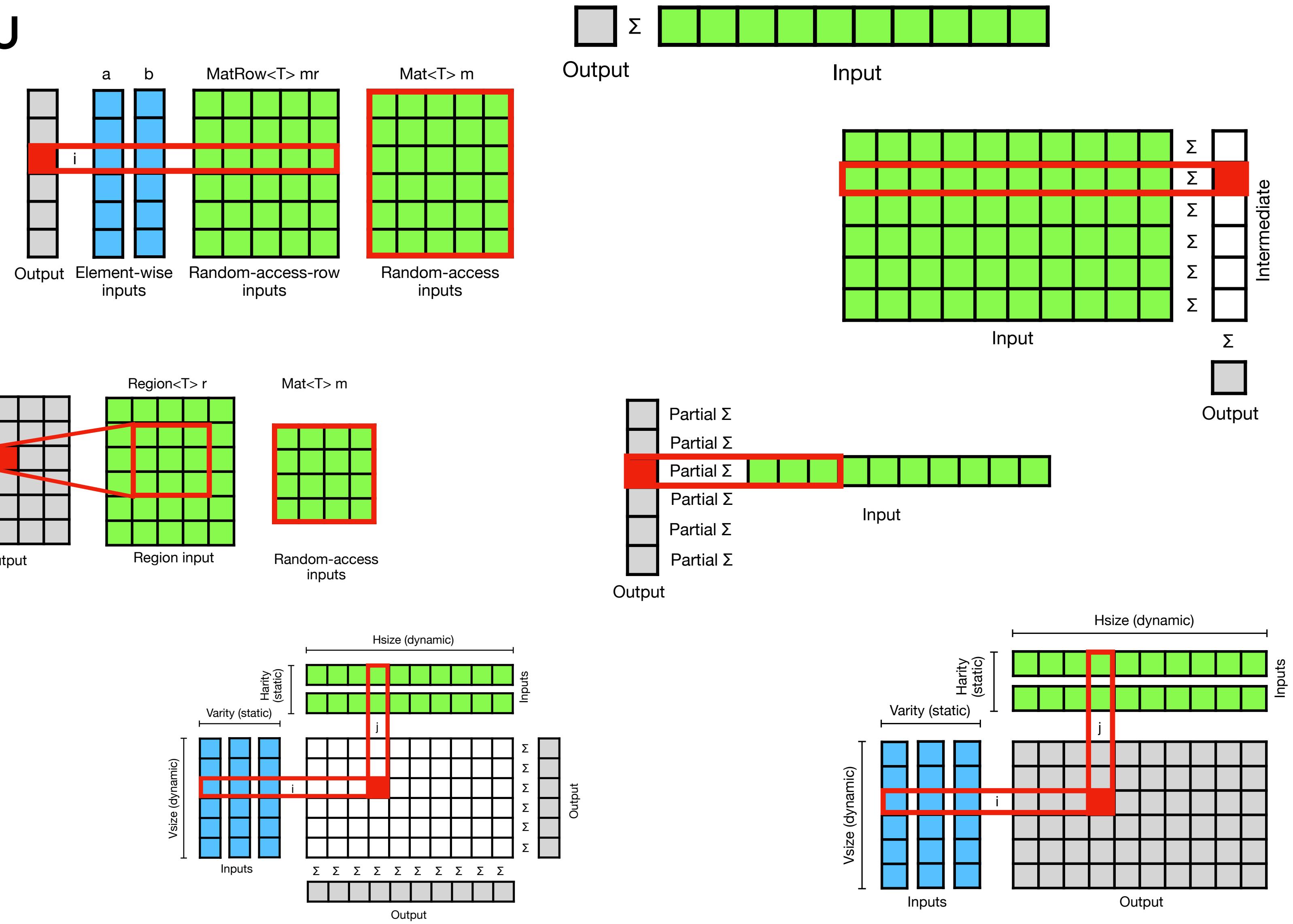
Ernstsson, Kessler, HLPP 2021, to appear.

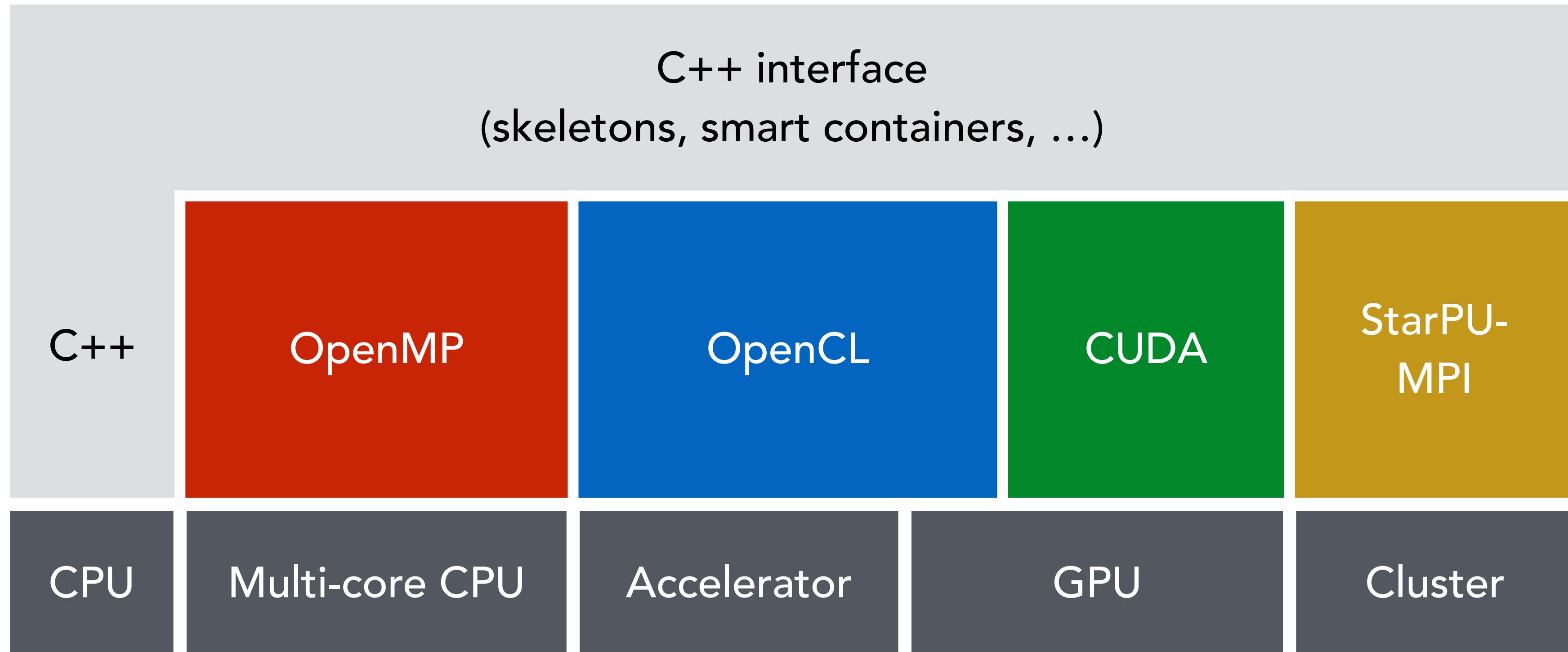
- Strided Map skeletons

- Skeleton programming framework
- C++11 **library** with skeleton and data container classes
- A **Clang**-based source-to-source **pre-compiler**
- Smart containers: `Vector<T>`, `Matrix<T>`, `Tensor3<T>`, `Tensor4<T>`
- In development: `SparseMatrix<T>`
- For **heterogeneous multicore** systems
- Multiple backends
- Active research tool with a number of publications 2010-2021 (see website)

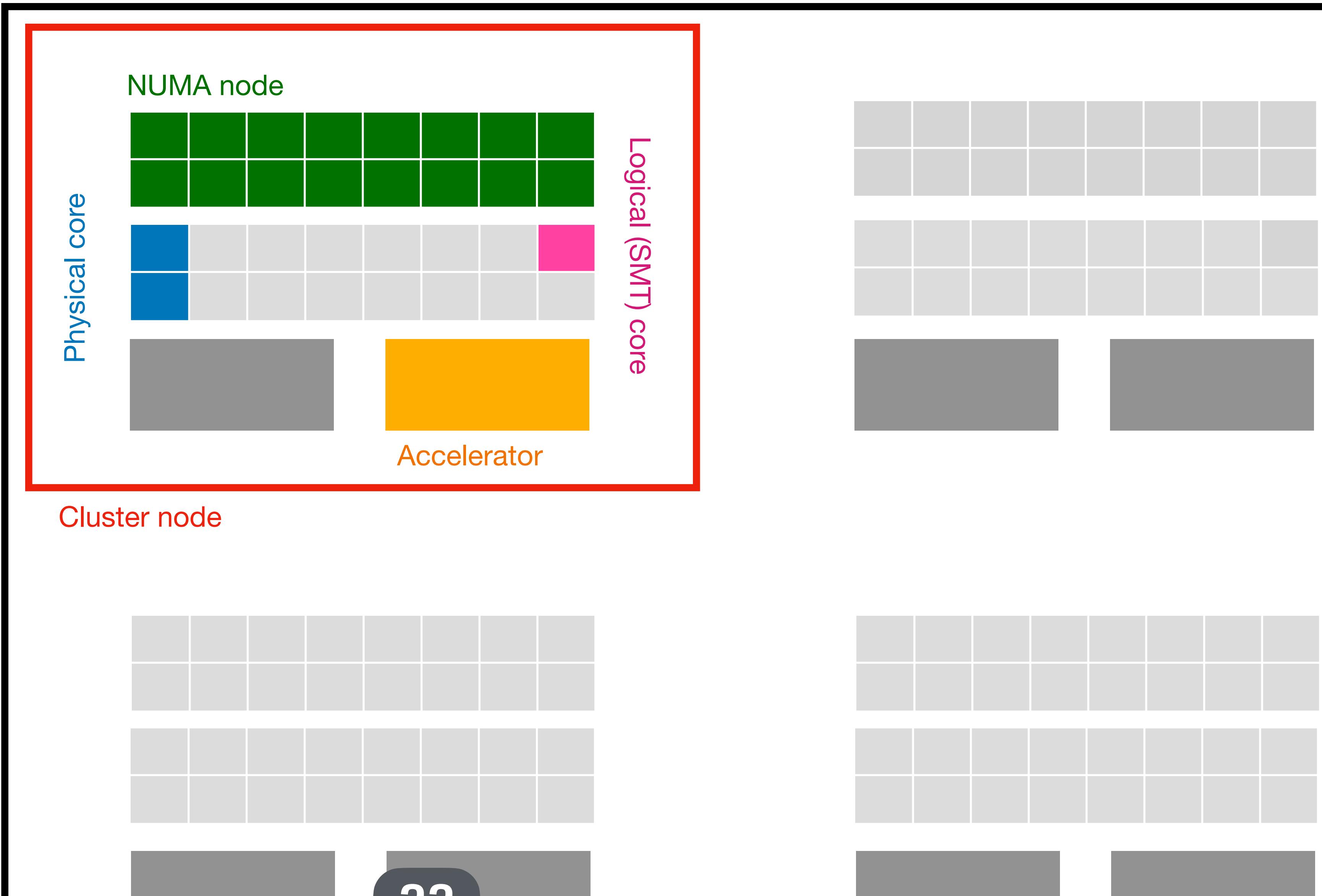
- **Skeletons provided by SkePU**

- Map
- Reduce
- MapReduce
- Scan
- MapOverlap
- MapPairs
- MapPairsReduce





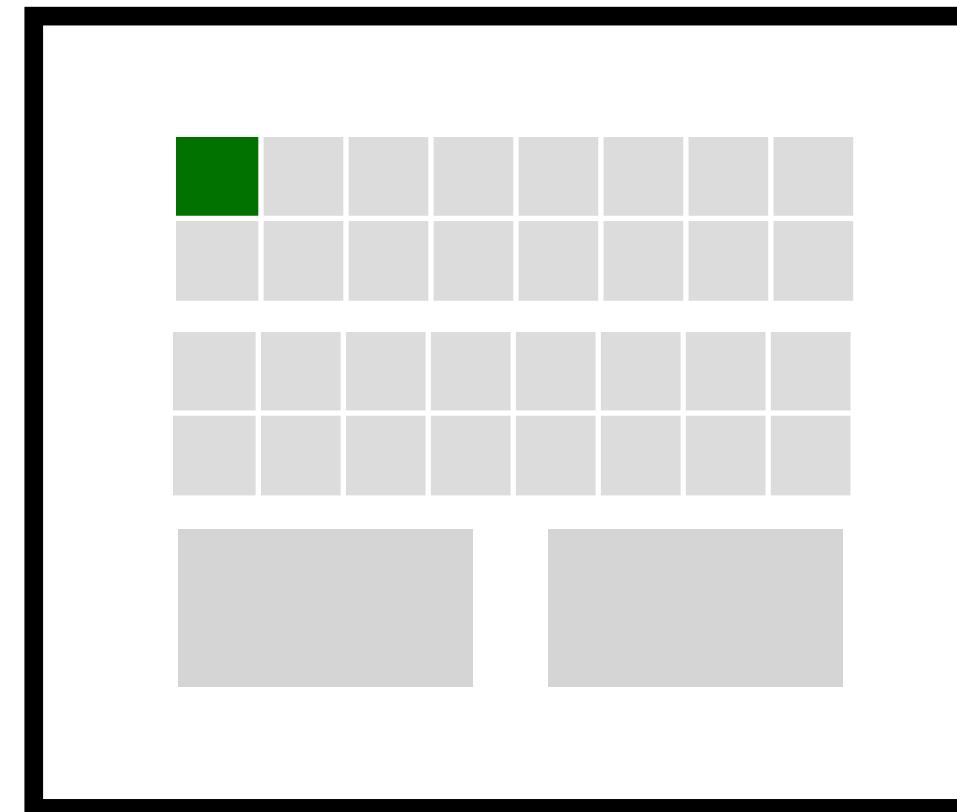
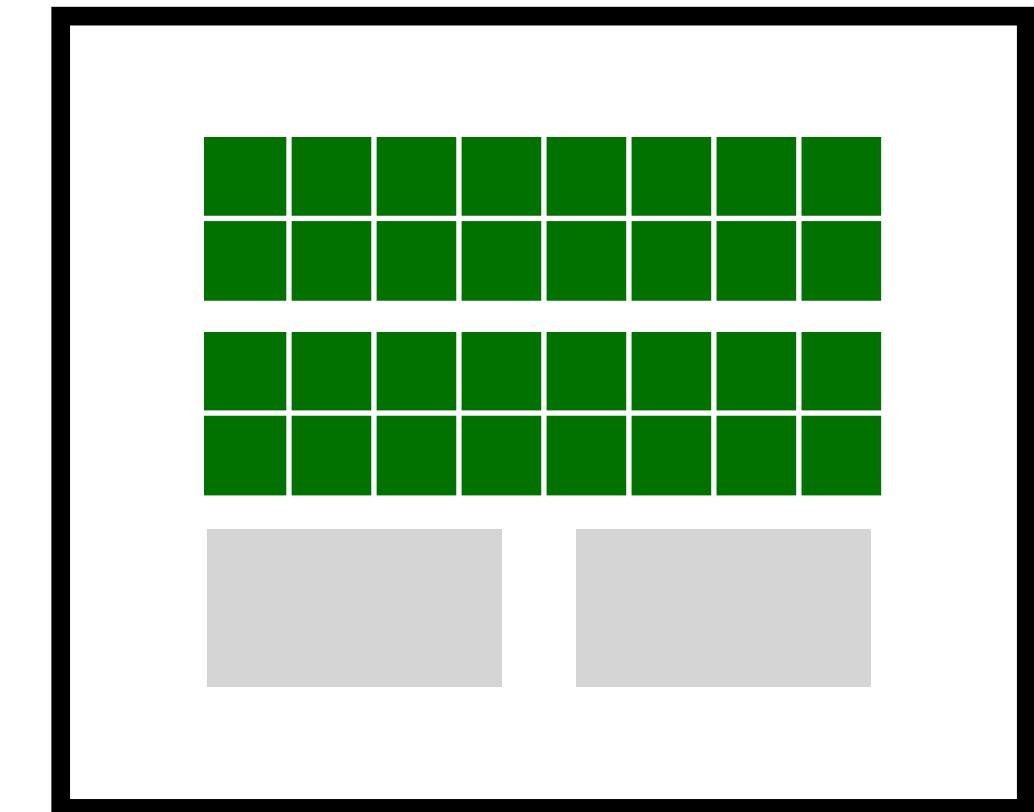
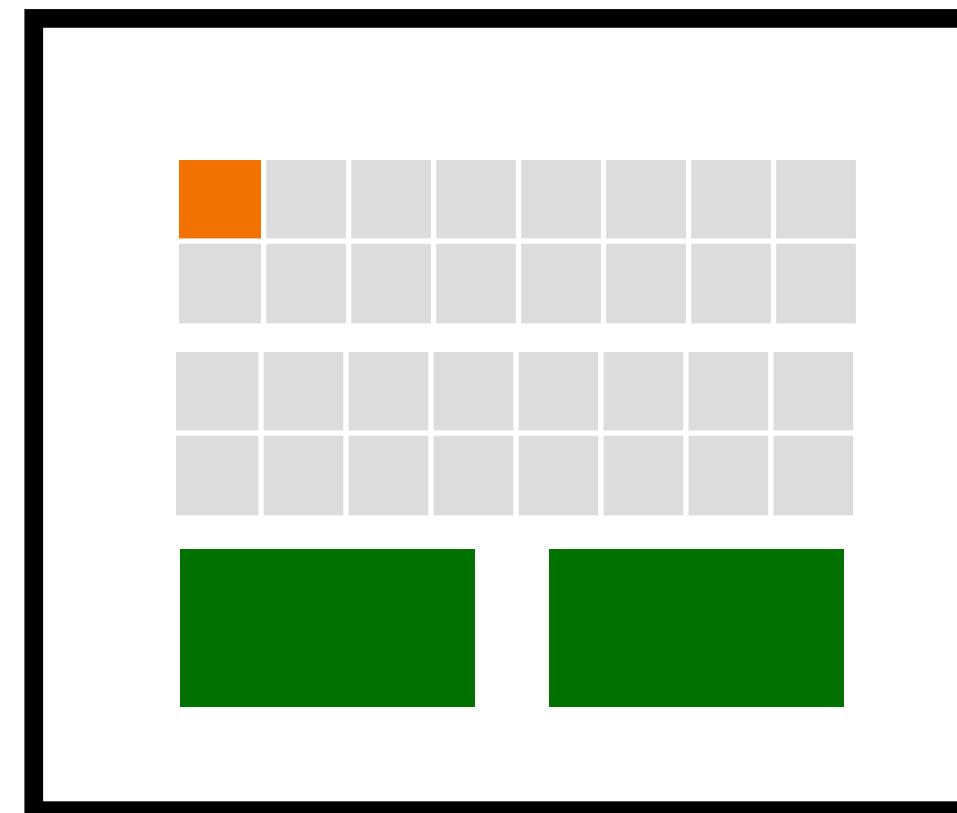
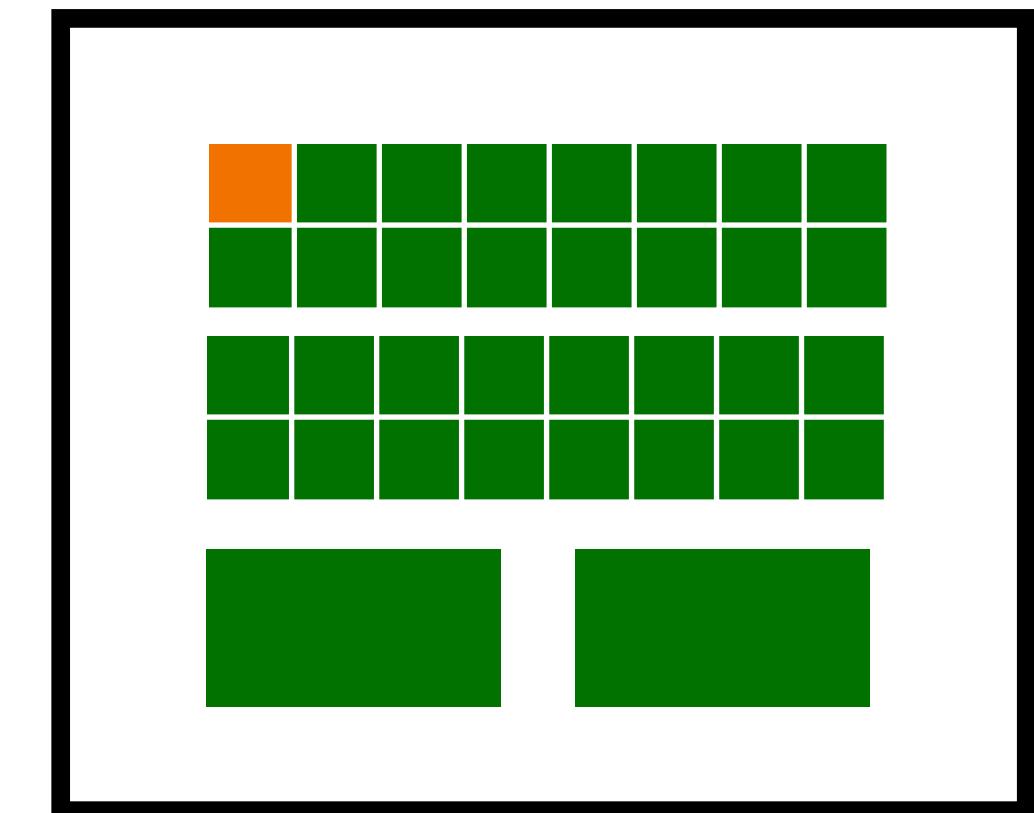
Cluster



Compute

Management

Idle

Backend **CPU**Backend **OpenMP**Backend **OpenCL**  
Backend **CUDA\***Backend **Hybrid**

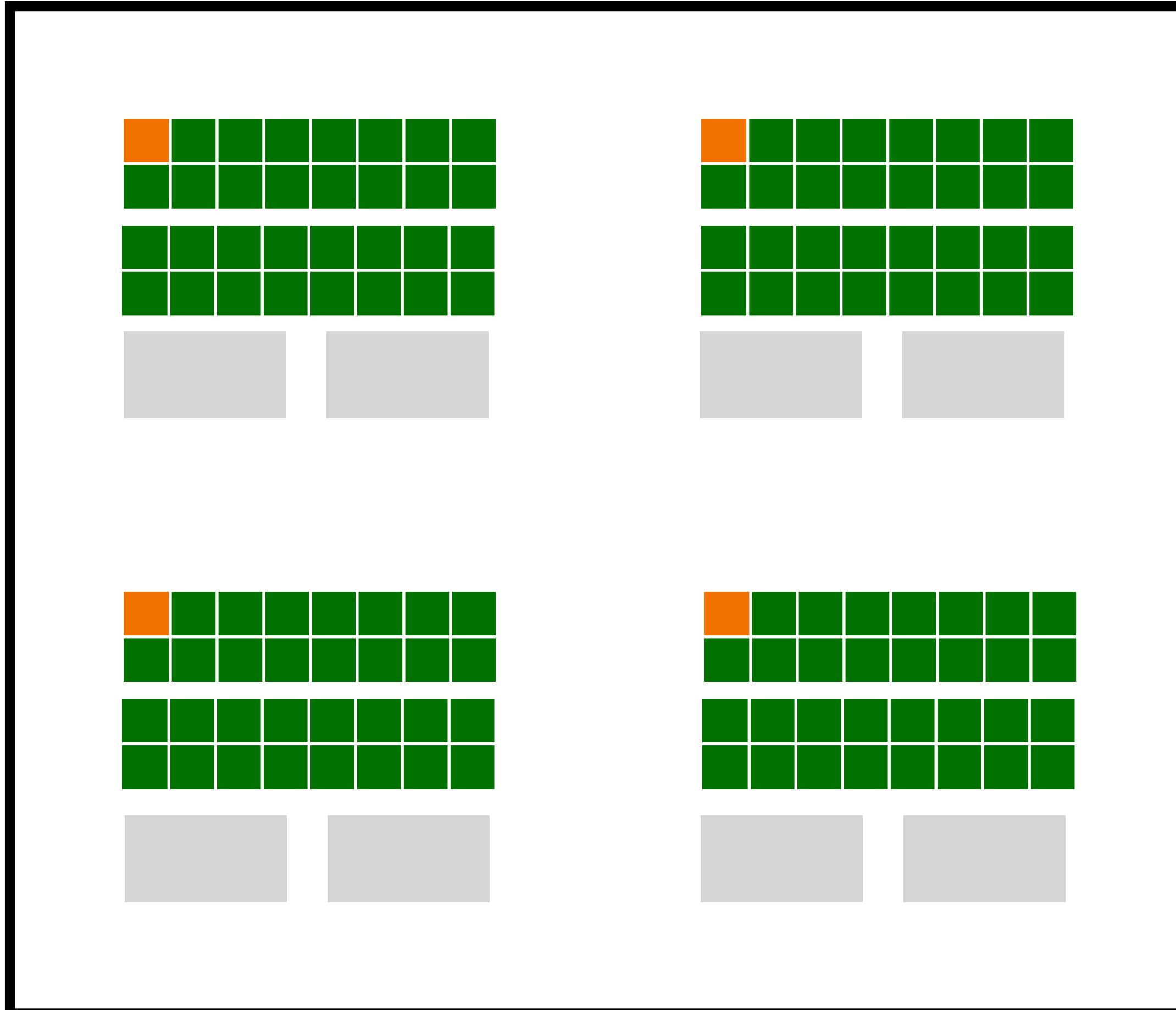
\*) NVIDIA GPU accelerators only

Compute

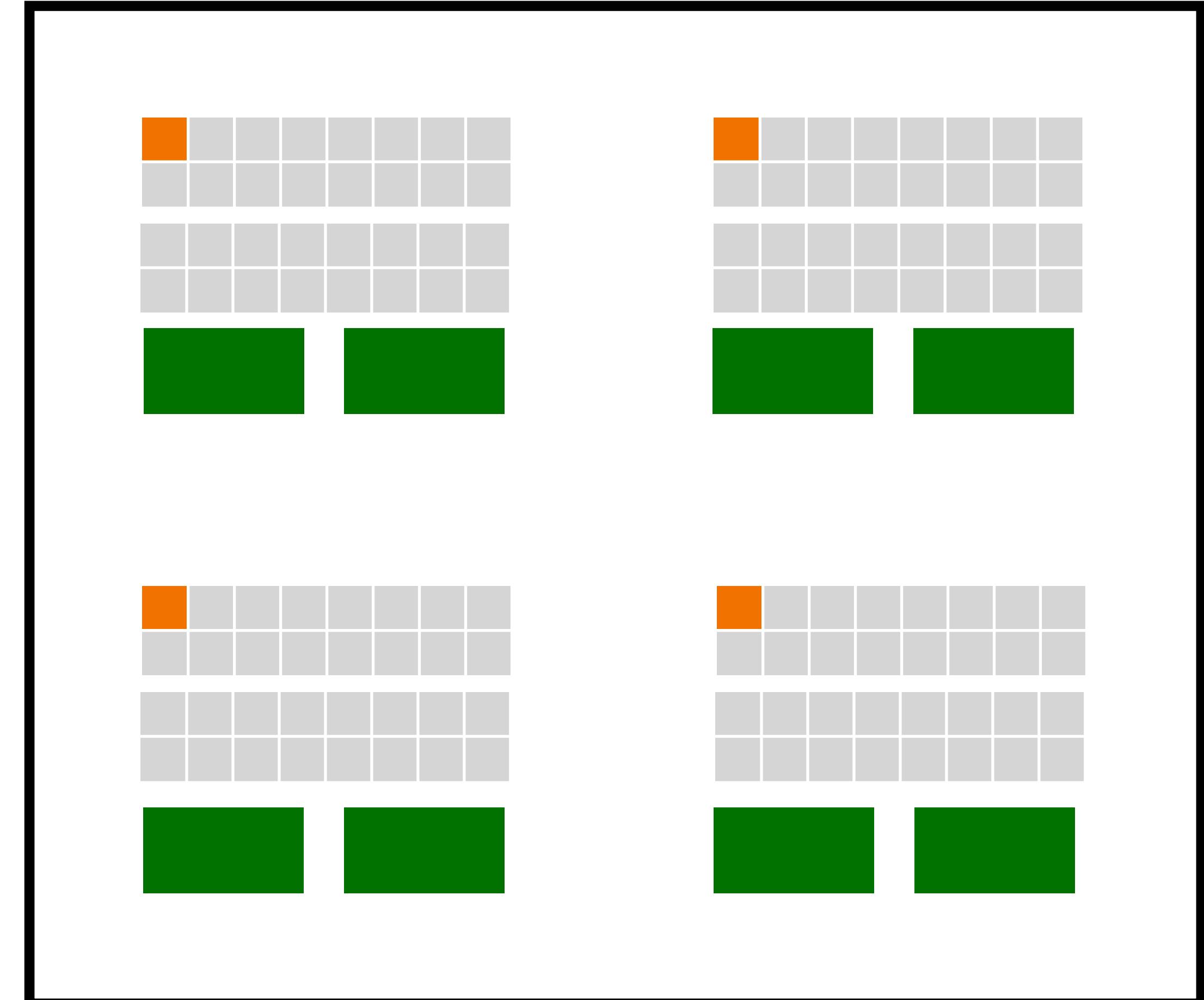
Management

Idle

Backend **StarPU-MPI**



Backend **StarPU-MPI-CUDA\***



\*) NVIDIA GPU accelerators only

**Vector**

i	0	1	2	3	4
0	1	2	3	4	

i	0		1			
j	0	1	2	0	1	2
0	0	1	2	9	10	11
1	3	4	5	12	13	14
2	6	7	8	15	16	17

Tensor3

**Matrix**

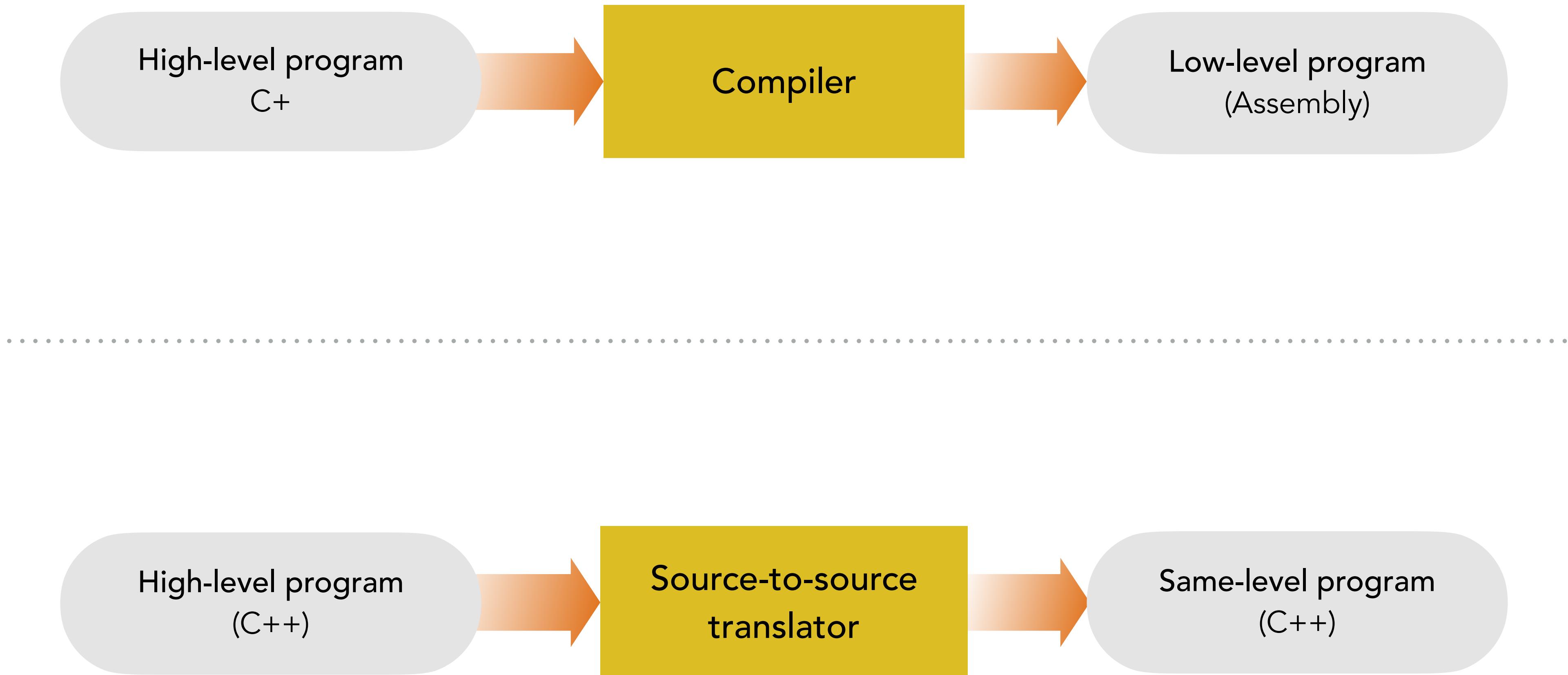
i	j	0	1	2	3	4
0	0	1	2	3	4	
1	5	6	7	8	9	
2	10	11	12	13	14	
3	15	16	17	18	19	
4	20	21	22	23	24	

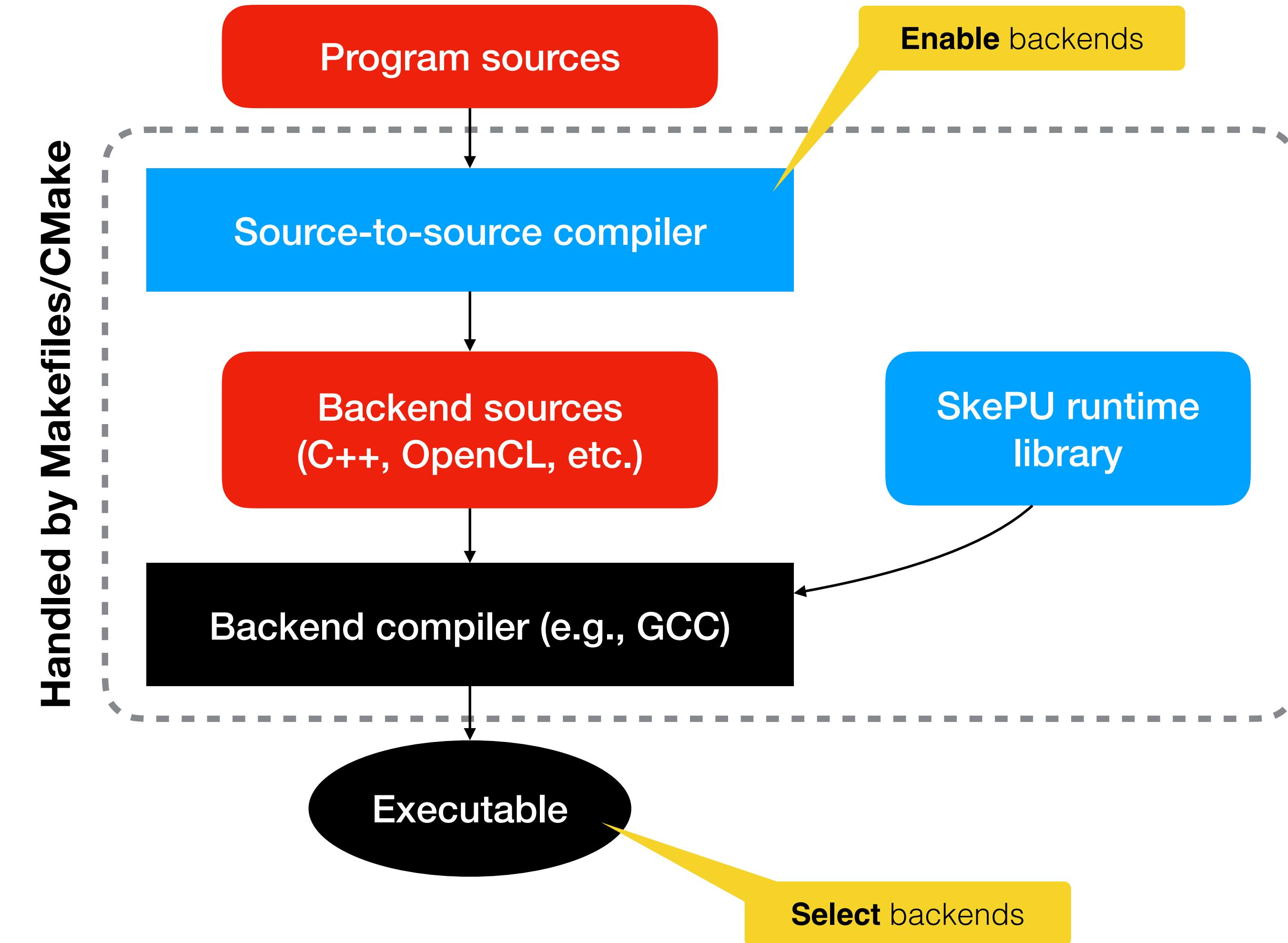
i	j	0	1	2	0	1	2
0	0	1	2	9	10	11	
1	3	4	5	12	13	14	
2	6	7	8	15	16	17	
0	18	19	20	27	28	29	
1	21	22	23	30	31	32	
2	24	25	26	33	34	35	

Tensor4

- C++ template class instance
- Contains:
  - CPU memory buffer **pointer** (alt. StarPU handles)
  - Size information (size, width/height)
  - OpenCL/CUDA/MPI **handles**
  - Consistency states
- Template type can be **custom struct**, but be careful!
  - Data layout not verified across backends/languages

# Using SkePU





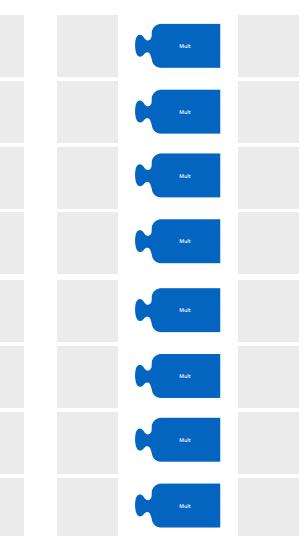
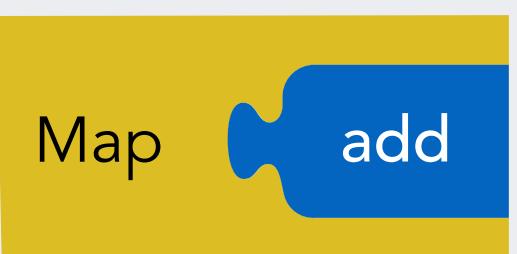
- Two main installation options:
  - Use provided **binary distribution**
    - <https://skepu.github.io/tutorials/escience21/>
    - Built for x86-64 Linux systems
    - Very few dependencies
    - Only a subset of full distribution, built once for this tutorial!
  - **Clone** SkePU GitHub repository, **build** with CMake
    - More flexible, but takes time (~30 min).

See website: <https://skepu.github.io>

```
int add(int a, int b, int m)
{
    return (a + b) % m;
}
```



```
auto vec_sum = Map<2>(add);
vec_sum(result, v1, v2, 5);
```



- User functions are C++ (rather, C) functions
- The signature is analyzed by the pre-compiler to extract the skeleton signature
- Each skeleton has their own expected patterns for UF parameters (but the general structure is shared)
- The UF body is **side-effect free** C (compatible with CUDA/OpenCL)
  - No communication/synchronization
  - No memory allocation
  - No disk IO

```
int add(int a, int b, int m)
{
    return (a + b) % m;
}
```

- **Variable arity** on Map and MapReduce skeletons
- **Index** argument (of current Map'd container element)
- **Uniform** arguments
- Smart container arguments accessible **freely** inside user function
  - **Read**-only / **write**-only / **read-write** copy modes
- User function **templates**

```
template<typename T>
T abs(T input)
{
    return input < 0 ? -input : input;
}

template<typename T>
T user_function(Index1D row, const Mat<T> m, const Vec<T> v)
{
    T res = 0;
    for (size_t i = 0; i < v.size; ++i)
        res += m(row.i * m.cols + i) * v(i);

    return abs(res);
}
```

- Multi-variant user function **specialization**
  - Targeting backend
- Custom **types**
- **Chained** user functions
- In-line **lambda** syntax for user functions
- “**Intrinsic**” functions

Some functions exist in the standard library of all SkePU backends.  
**Examples:**  $\sin(x)$ ,  $\text{pow}(x, e)$

```
auto vec_sum = skepu::Map([](int a, int b)
{
    return a + b;
});

// ...

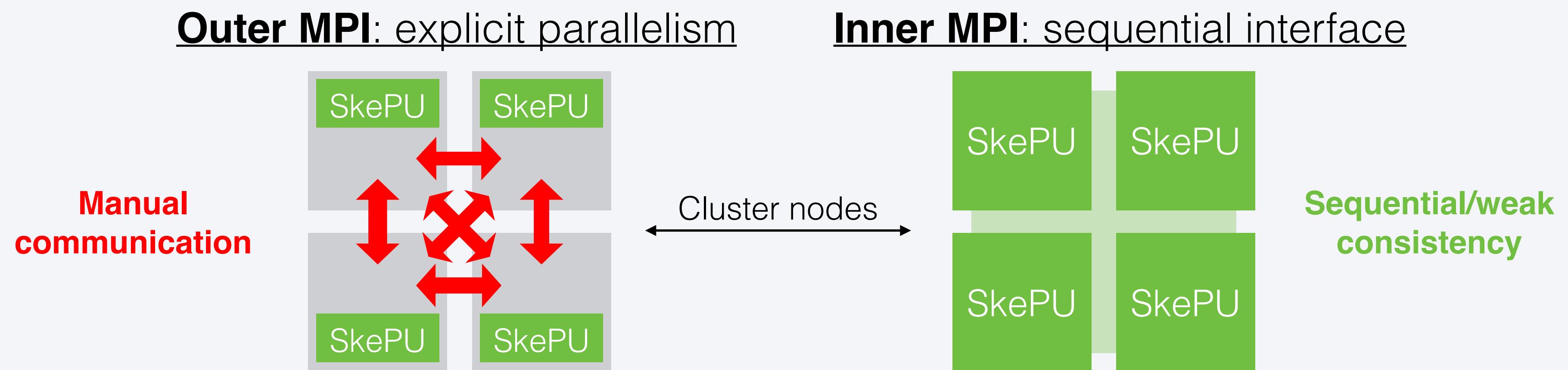
vec_sum(result, v1, v2);
```

# Compilation Options and Backend Selection

- Precompiler options
  - skepu-tool
    - map.cpp**
    - name map\_precompiled**
    - dir bin**
    - openmp -opencl**
    - [Clang flags]**
  - Handled by Makefiles in the binary tutorial distribution
  - Handled by CMake in standard SkePU repository
  - Clang flags:
    - Include path to Clang language-headers
    - Include path to SkePU headers
    - Optional OS-specific paths and settings

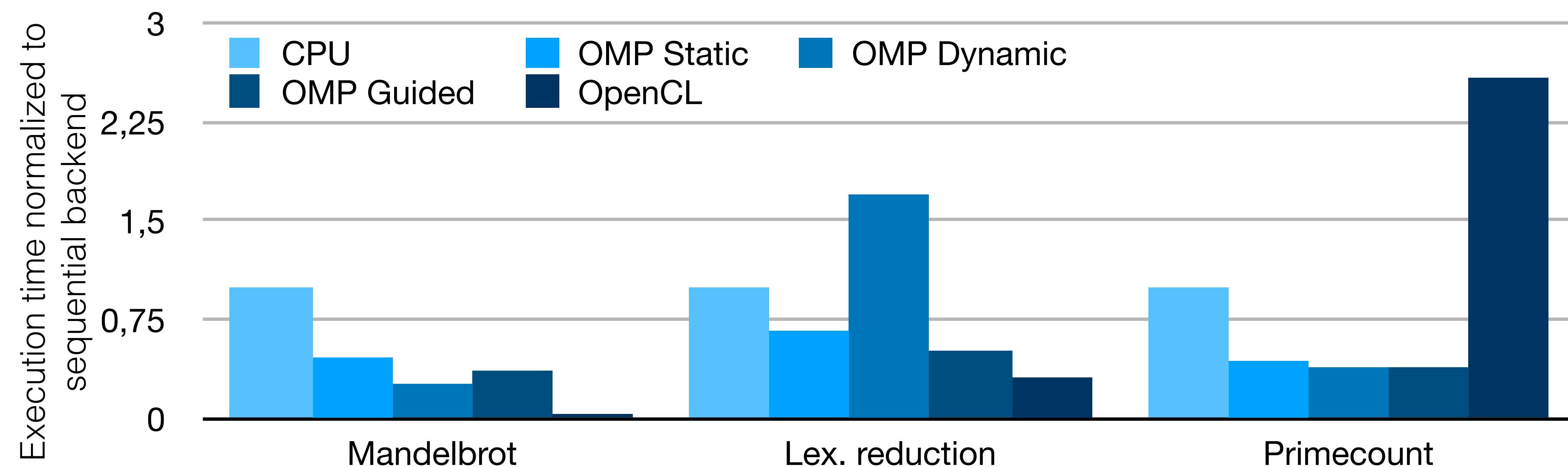
- `auto spec = skepu::BackendSpec{argv[2]};`
  - Sets the **run-time backend** from a string, must match any of:
    - “CPU”, “OpenMP”, “OpenCL”, “CUDA”, “Hybrid”
    - Cluster backend is a **compile-time** selection due to SPMD model
      - Uses OpenMP on node level by default
      - Optional GPU backend selection
    - Global backend spec for all skeletons, overridden by instance-specific spec.
    - `skepu::setGlobalBackendSpec(spec);`

- SkePU can **target clusters**
  - Any valid SkePU 3 program needs not be syntactically changed to use the cluster backend ("inner MPI mode")
  - SkePU can also run on clusters by using skeletons locally on each node ("outer MPI mode": MPI+SkePU)
- Implementation atop *StarPU*
- Challenges: SPMD-style; C-level APIs (*StarPU* + MPI)



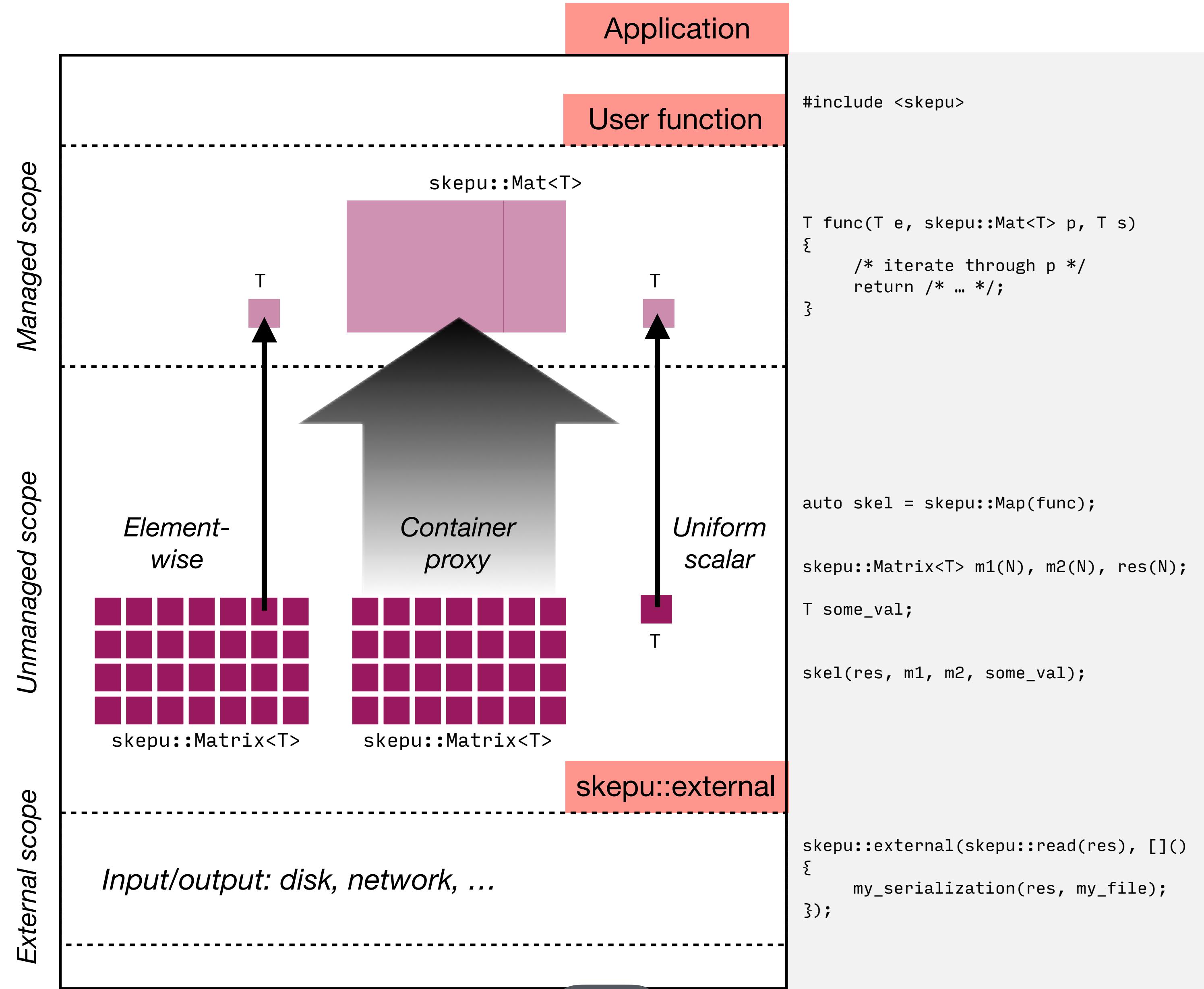
- **Backend specifications** can furthermore contain execution parameters
  - Number of **threads**
  - Number of **GPUs**
  - GPU block size, thread count hinting
  - OpenMP **scheduling** mode
    - Static (default) / dynamic / guided / auto
    - Chunk size for dynamic scheduling
  - **Partition ratio** for Hybrid backend

- Three benchmarks that illustrate the effects of dynamic scheduling in OpenMP backend
- All variants are SkePU backend executions
  - Sequential CPU and OpenCL included for reference



# Smart Containers & Consistency Model

- SkePU provides three different “scopes” with different syntax and consistency rules
- Inside a user function: **Managed scope**
  - C-style syntax allowed, no global synchronization (compare with GPU kernel code)
- Outside user function: **Unmanaged scope**
  - Regular single-threaded C++-land with smart container objects providing weak consistency
- For global side effects: **External scope**
  - In SPMD model (clusters), the C++ program does not run single-threaded
  - External construct wraps file read/write, logging, etc.



- `container.flush();`
  - Flushes and ensures that the CPU buffer contains up-to-date values.
- `container(i) = value;`
  - Direct element access into the raw CPU buffer.
  - Weak consistency, unless compile-time flag enabled (optional for debugging purposes)
- `skepu::external(skepu::read(particles), [&]{  
 save_step(particles, outfile);  
});`
  - Manages IO and other external operations in SPMD mode

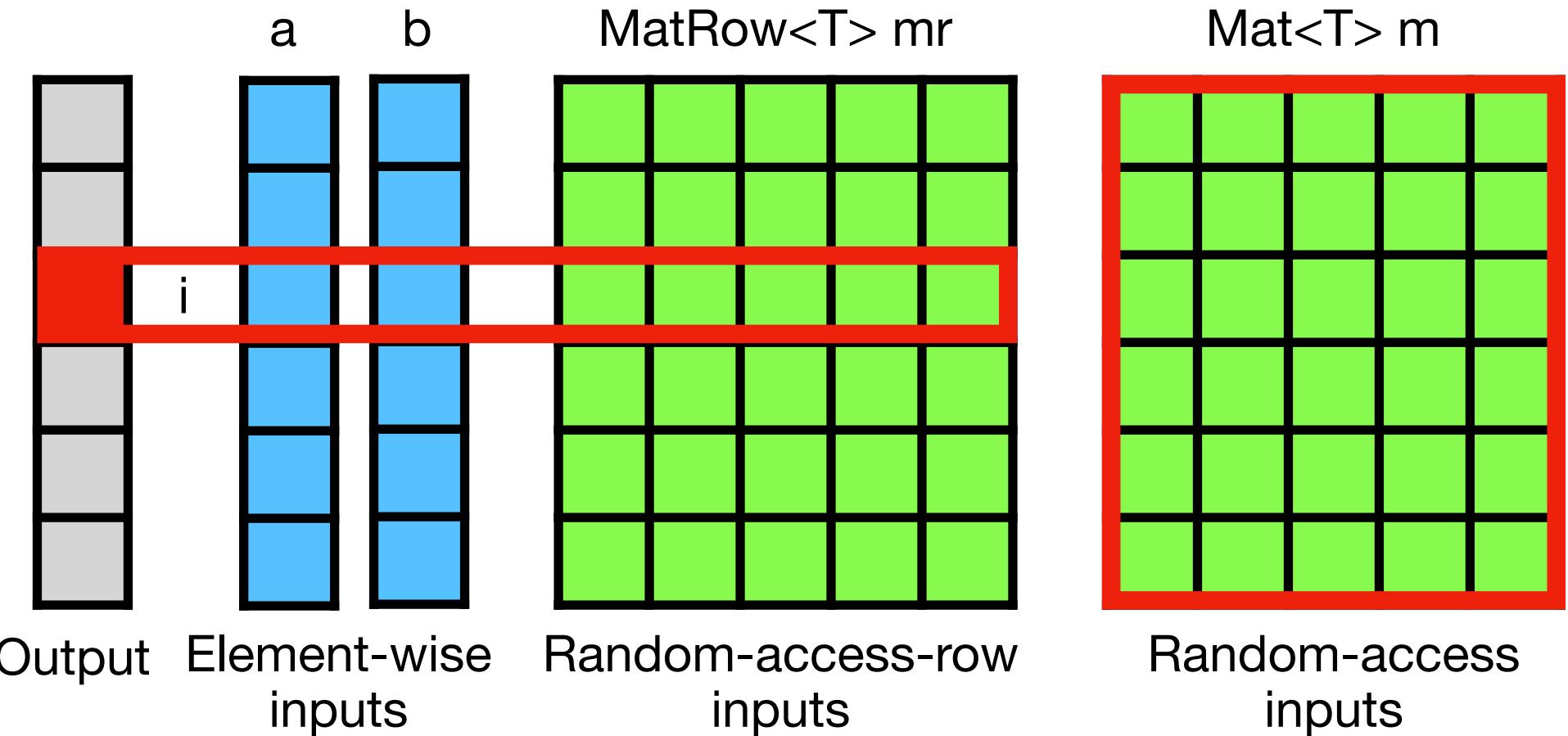
# SkePU **DEMO**

# Skeletons In Depth

Feature \ Skeleton	Map	MapPairs	MapOverlap	Reduce	Scan	MapReduce	MapPairsReduce	
<b>Elwise dimension in</b>	1–4	1	1–4	1–4**	1	1–2	1	
<b>Elwise dimension out</b>	Same as <i>in</i>	2	Same as <i>in</i>	0–1	1	0	1	
<b>Indexed</b>	Yes	Yes	Yes	-	-	Yes	Yes	
<b>Multi-return</b>	Yes	Yes	Yes	-	-	Yes	Yes	
<b>Elwise parameters</b>	Variadic	Variadic x2	1***	*	*	Variadic	Variadic x2	
<b>Full proxy parameters</b>	Variadic	Variadic	Variadic	-	-	Variadic	Variadic	
<b>Uniform parameters</b>	Variadic	Variadic	Variadic	-	-	Variadic	Variadic	
<b>Region proxy</b>	-	-	Yes	-	-	-	-	
<b>MatRow/MatCol proxy</b>	Yes	Yes	-	-	-	Yes	Yes	
<b>Footnotes</b>								
*	Parameters to the user functions can be raw elements from the container or partial results, depending on evaluation order.							
**	Dimensions higher than 2 are linearized in the current implementation.							
***	A region of elements surrounding the current index is supplied.							

# Map

- Three groups of user function parameters:
  - **Element-wise**  
Only one element per user function call
  - **Random-access containers**  
Replicated for each memory space (e.g. GPUs)  
Proxy types `Vec<T>` and `Mat<T>` in user function
  - **Uniform scalars**  
Same values everywhere
- Argument groups are variadic (flexible count, including 0)
- Above order must be obeyed (element-wise first etc.)
- The parallelism/number of user function invocations is always determined by the return container (first argument), also in case of element-wise arity of 0.
- Also applies to **MapReduce**, **MapOverlap**, **MapPairs**, **MapPairsReduce**!



```
float sum(float a, float b)
{
    return a + b;
}

Vector<float> vector_sum(Vector<float> &v1, Vector<float> &v2)
{
    auto vsum = Map<2>(sum);
    Vector<float> result(v1.size());
    return vsum(result, v1, v2);
}
```

- Map (and MapReduce) can index containers in a **strided fashion**
  - `instance.setStride(...);`
- Positive strides indicate length of jump **between elements**
- Negative strides in addition **reverses** indexing order
- Unit, non-unit, and negative strides can be mixed in call

```
auto addr = skepu::Map(add);
auto addrsum = skepu::MapReduce(add, add);

constexpr size_t N{8};
skepu::Vector<int> v1(N*4), v2(N*3), r(N*2), r2(N);

// MAP, POSITIVE STRIDES
addr.setStride(2, 4, 3);
addr(r, v1, v2);

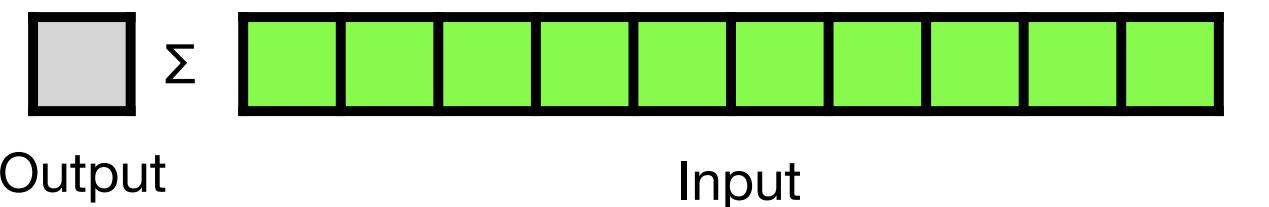
// MAPREDUCE, POSITIVE STRIDES
addrsum.setStride(4, 3);
int res = addrsum(v1, v2);

// MAP, NEGATIVE STRIDES
addr.setStride(2, -4, -3);
addr(rc, v1, v2);
```

- Optionally, use iterators with Map (or MapReduce):
  - `mapper(r.begin(), r.end(), v1.begin(), v2.begin());`

# Reduce

- # • 1D Reduce

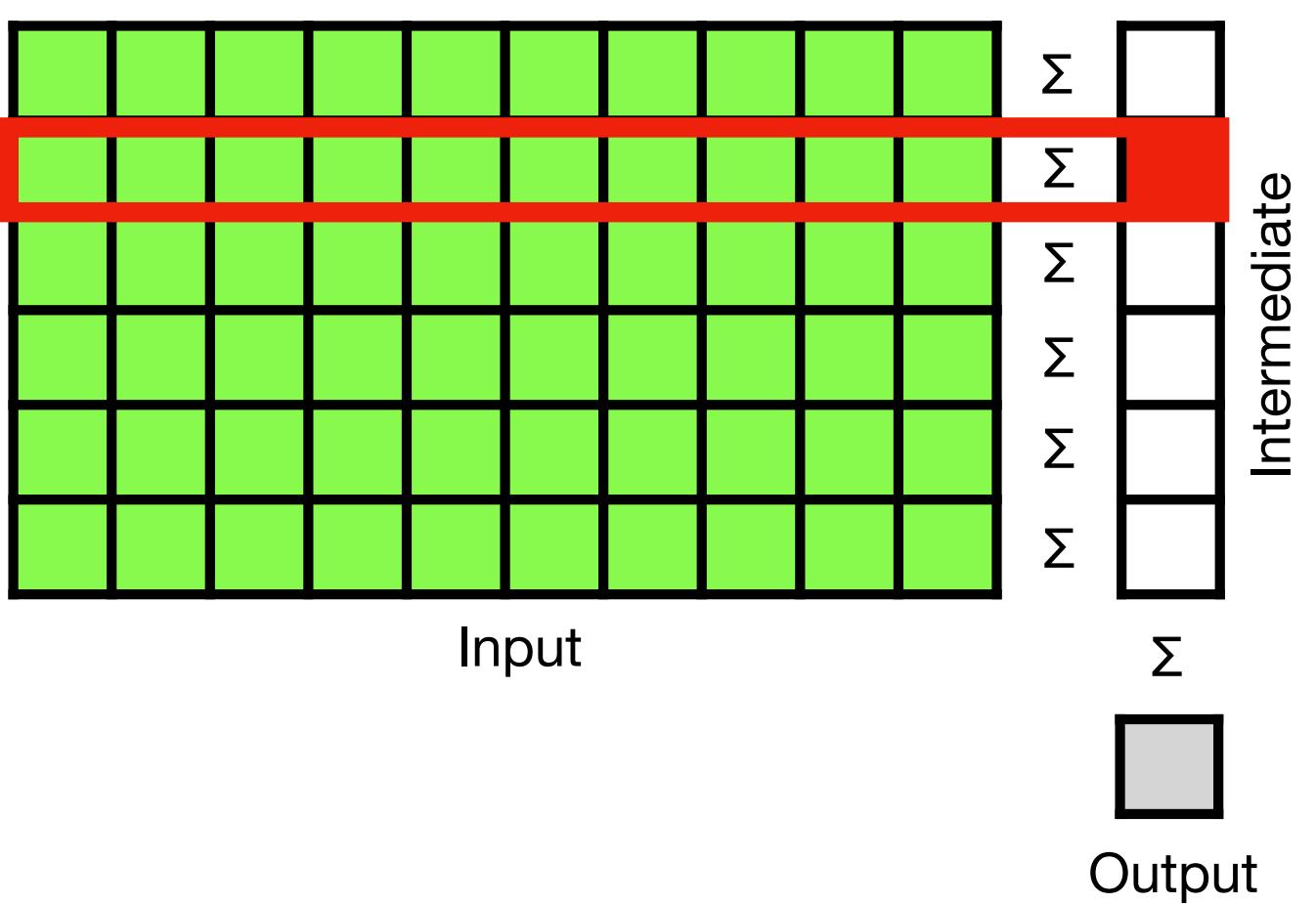


- Regular Vector
  - Matrix RowWise (returns Vector)
  - Matrix ColWise (returns Vector)

- “2D” Reduce

```
instance.setReduceMode(ReduceMode::RowWise) // default  
instance.setReduceMode(ReduceMode::ColWise)
```

- Regular Matrix (treated as a vector)
  - `instance.setStartValue(value)`
  - Set Reduction start value. Defaults to 0-infinity



```
float min_f(float a, float b)
{
    return (a < b) ? a : b;
}

float min_element(Vector<float> &v)
{
    auto min_calc = Reduce(min_f);
    return min_calc(v);
}
```

```
float plus_f(float a, float b)
{
    return a + b;
}

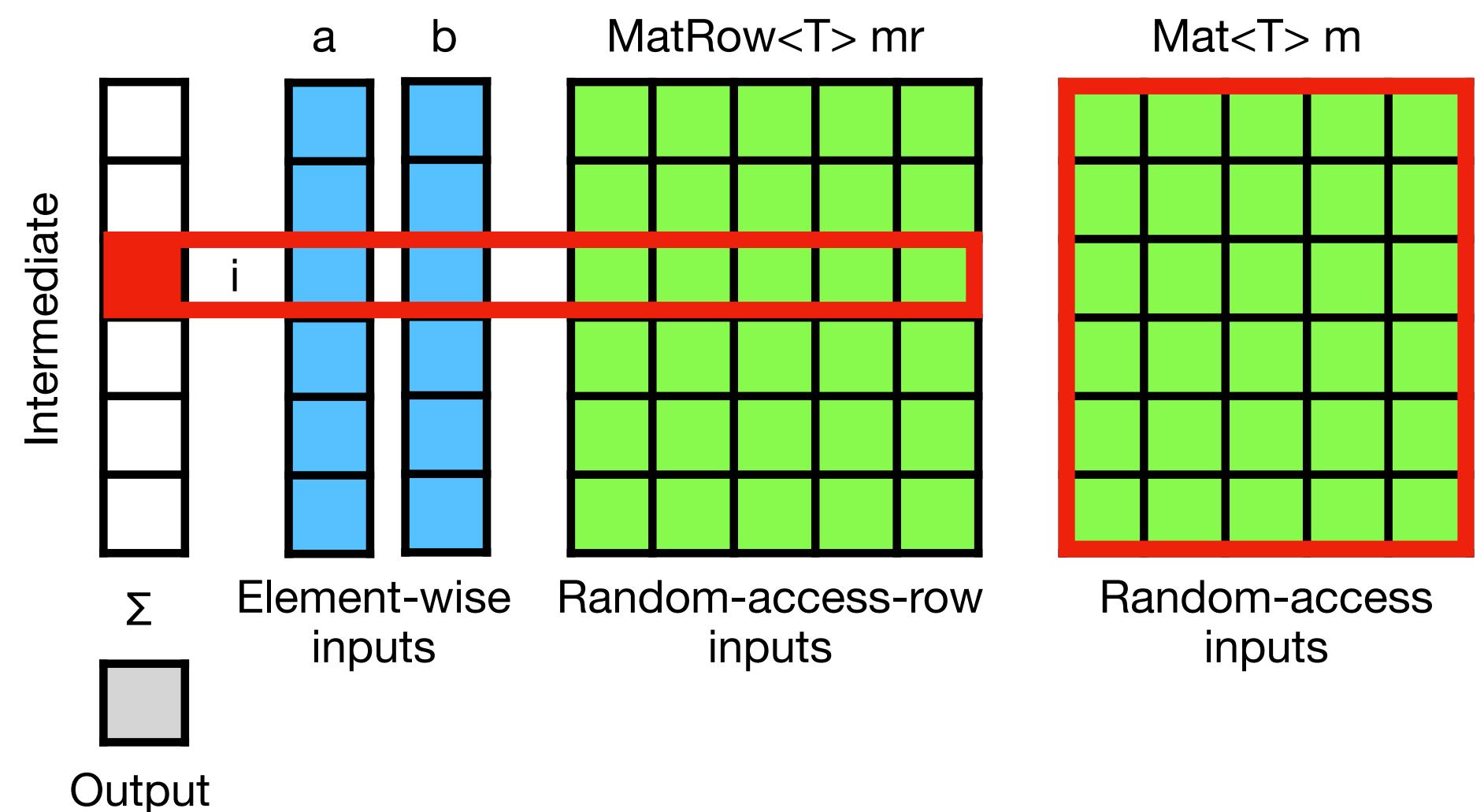
float max_f(float a, float b)
{
    return (a > b) ? a : b;
}

auto max_sum = skepu::Reduce(plus_f, max_f);

max_sum.setReduceMode(skepu::ReduceMode::RowWise);
r = max_sum(m);
```

# MapReduce

- `instance.setDefaultSize(size_t)`
  - When the element-wise arity is 0, this controls the number of user function invocations  
(That is, the size of the “virtual” temporary container in between the Map and Reduce steps)
- `instance.setStartValue(value)`
  - Set Reduction start value. Defaults to 0-initialized.



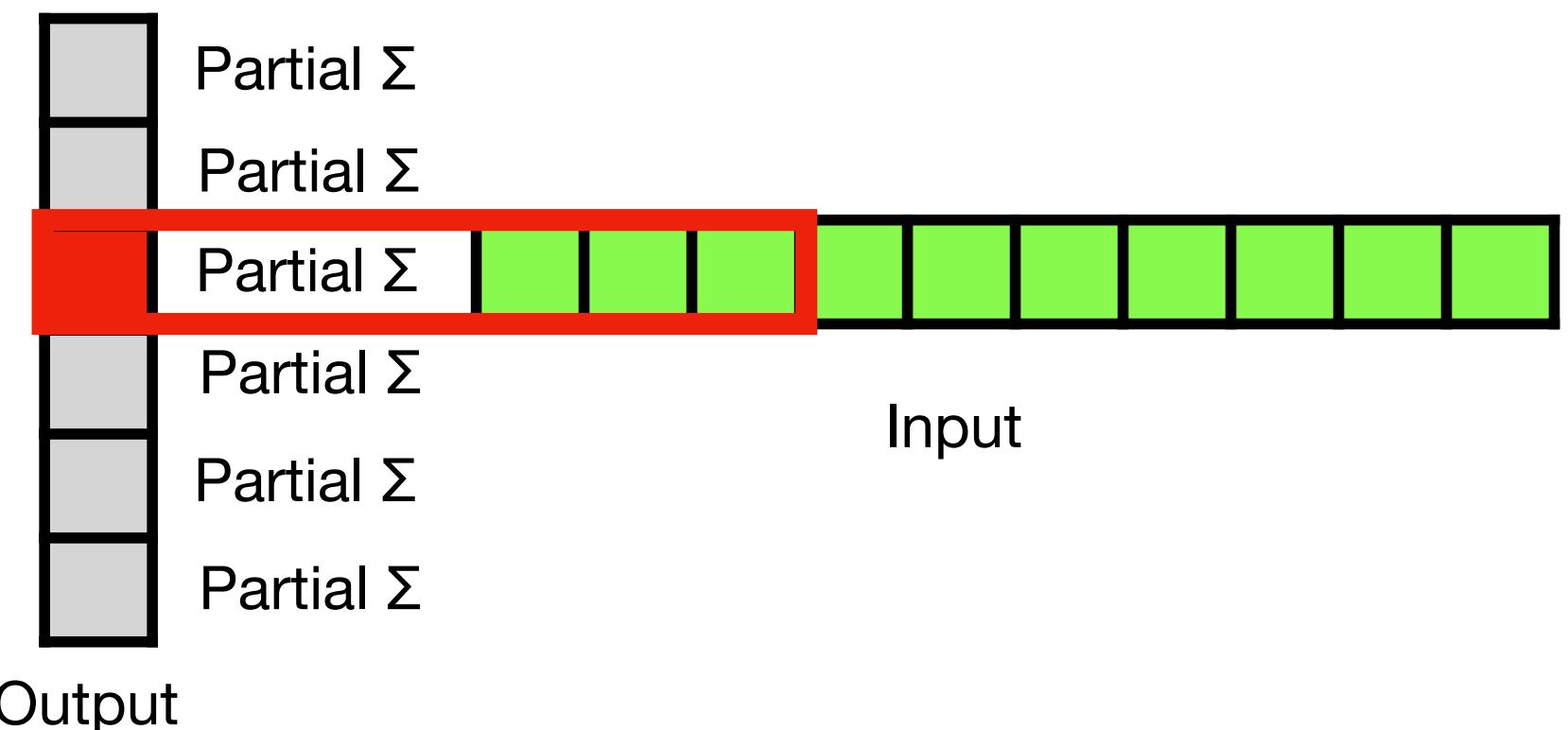
```
float add(float a, float b)
{
    return a + b;
}

float mult(float a, float b)
{
    return a * b;
}

float dot_product(Vector<float> &v1, Vector<float> &v2)
{
    auto dotprod = MapReduce<2>(mult, add);
    return dotprod(v1, v2);
}
```

# Scan

- `instance.setScanMode(mode)`
  - Set the scan mode:  
`ScanMode::Inclusive` (default)  
`ScanMode::Exclusive`
  
- `instance.setStartValue(value)`
  - Set start value of scans. Defaults to 0-initialized.

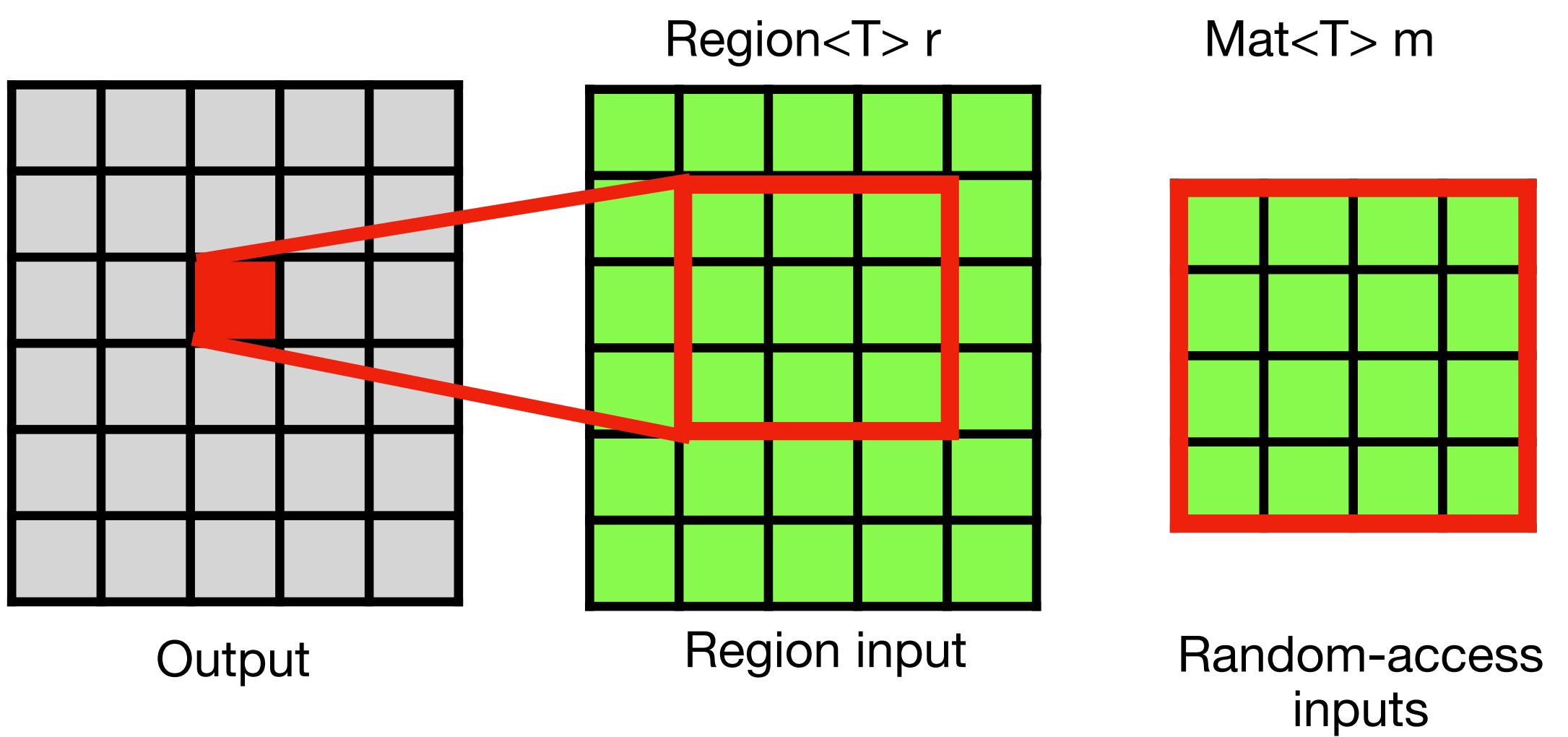


```
float max_f(float a, float b)
{
    return (a > b) ? a : b;
}

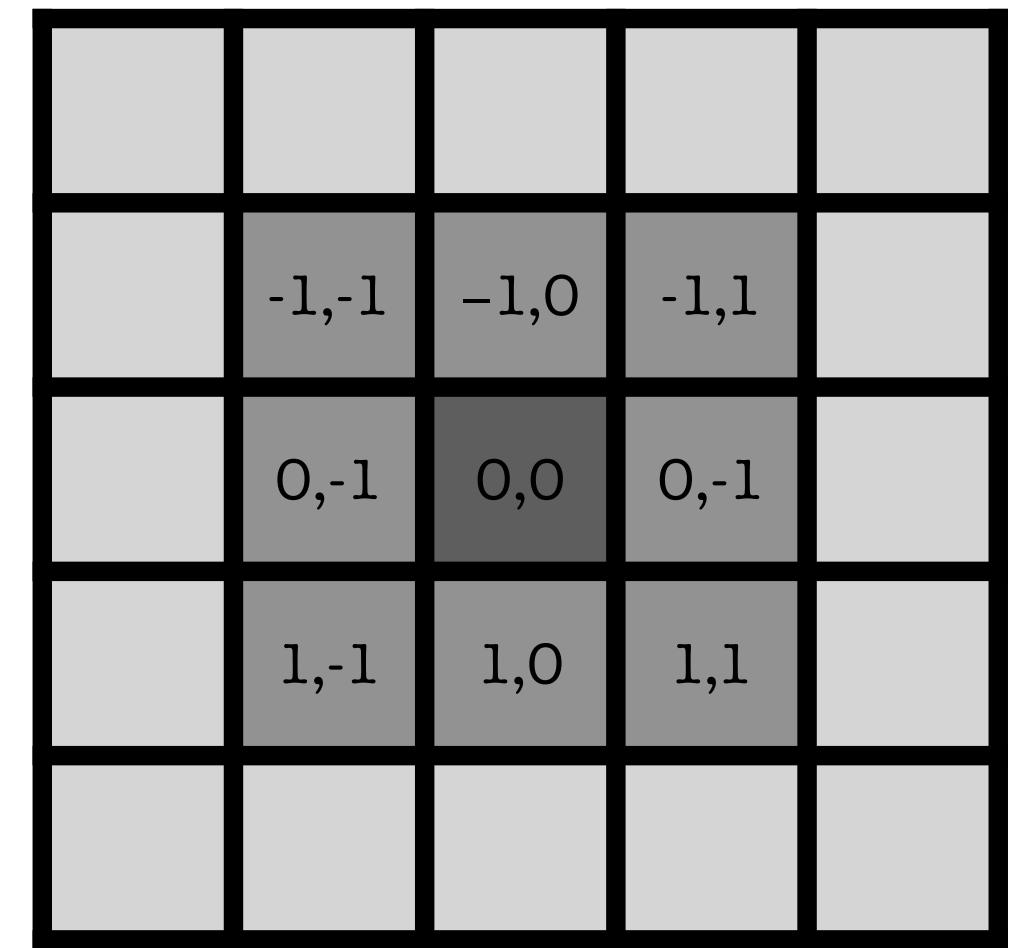
Vector<float> partial_max(Vector<float> &v)
{
    auto premax = Scan(max_f);
    Vector<float> result(v.size());
    return premax(result, v);
}
```

# MapOverlap

- Region of the input container accessible in user function
- In addition to optional full random-access parameters



- Region indexing is 0-centered in each dimension



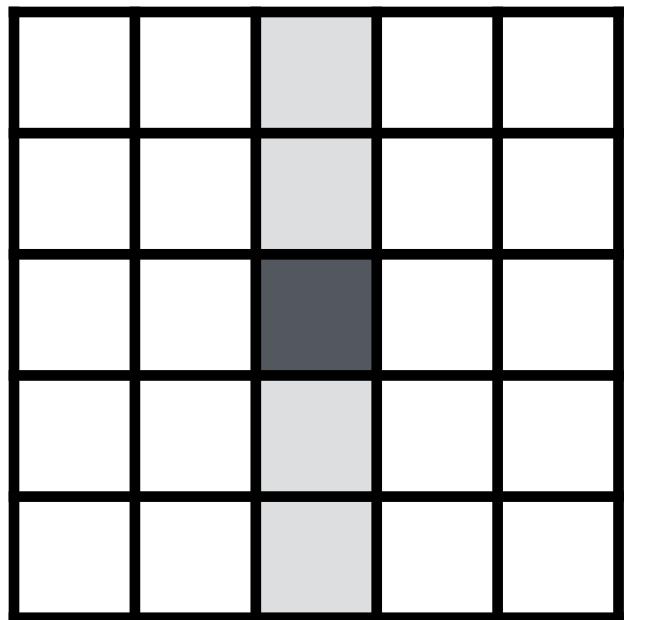
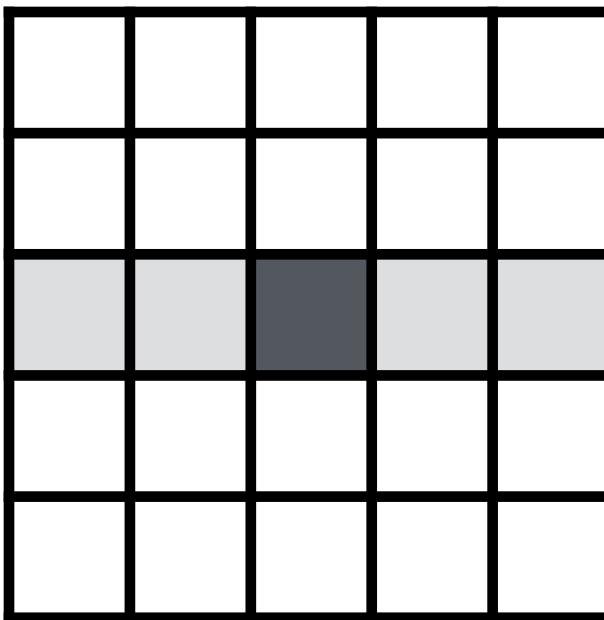
- **1D MapOverlap**



- Regular Vector

- Matrix RowWise

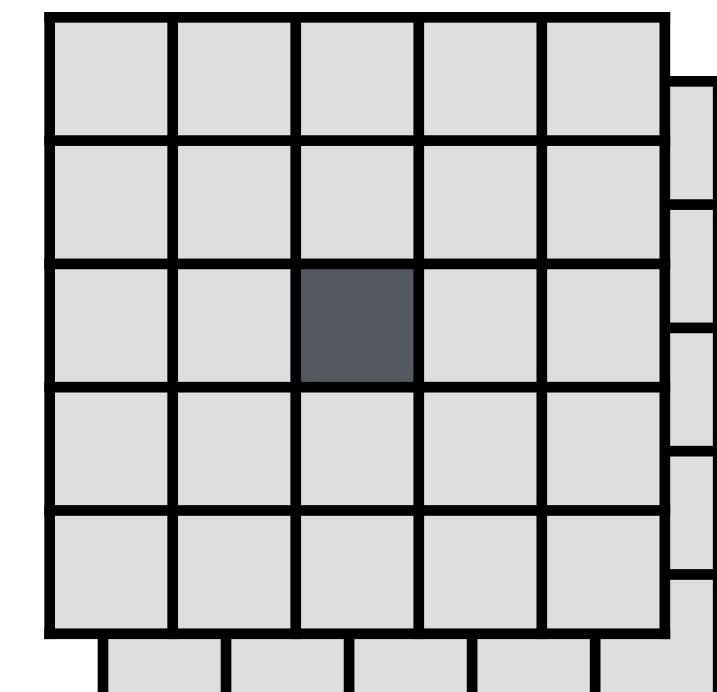
```
instance.setOverlapMode(Overlap::RowWise) // default
```



- Matrix ColWise

```
instance.setOverlapMode(Overlap::ColWise)
```

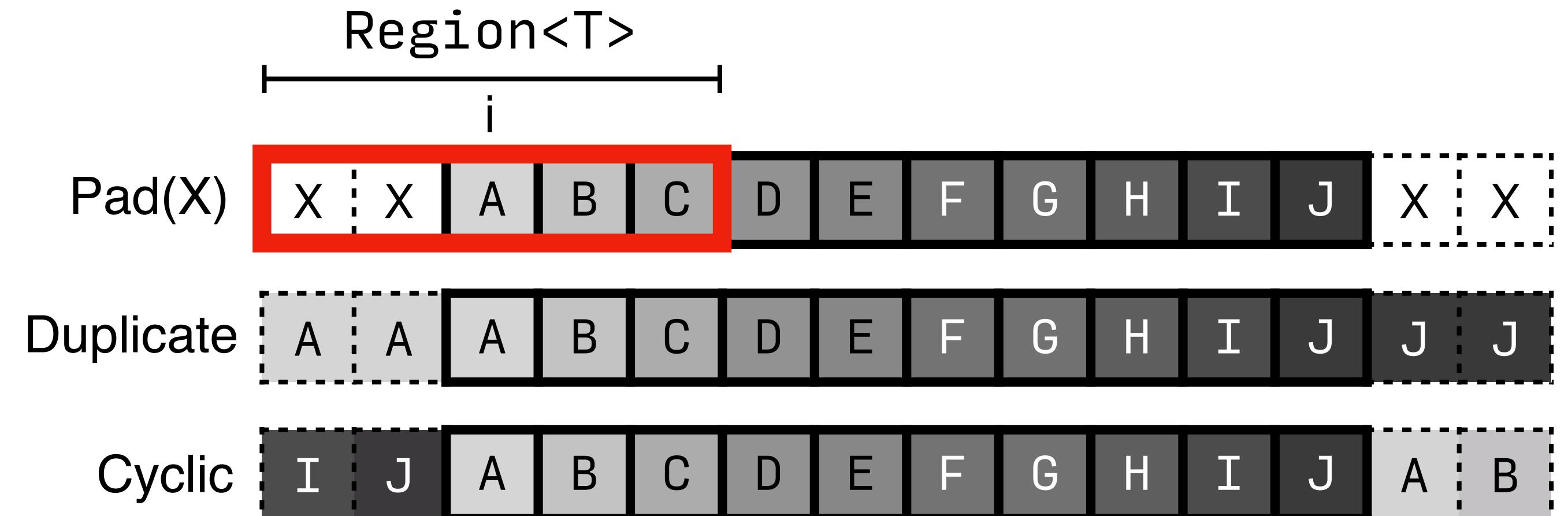
- **2D MapOverlap** on Matrix



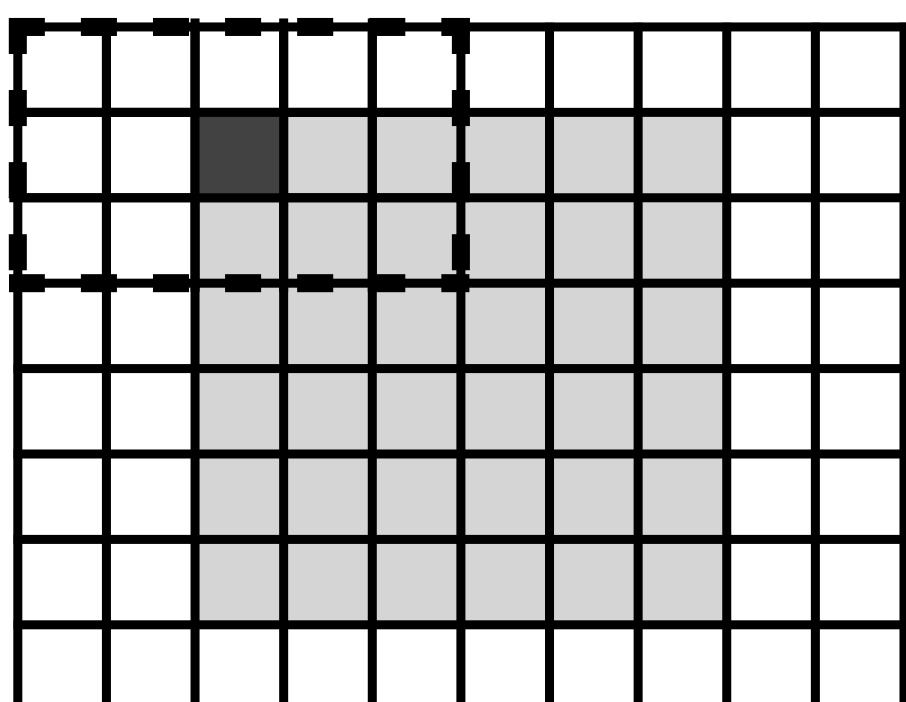
- **3D MapOverlap** on Tensor3

- **4D MapOverlap** on Tensor4

- `instance.setOverlap(i [, j [, k [, l]]])`
  - Set overlap radius in each dimension
- `instance.setEdgeMode(mode)`
  - `Edge::Pad`
    - `instance.setPad(pad)` – set padding value
  - `Edge::Duplicate` (default for 1D)
  - `Edge::Cyclic`
  - `Edge::None` (default for other dimensions)



None: Updates only "safe" elements



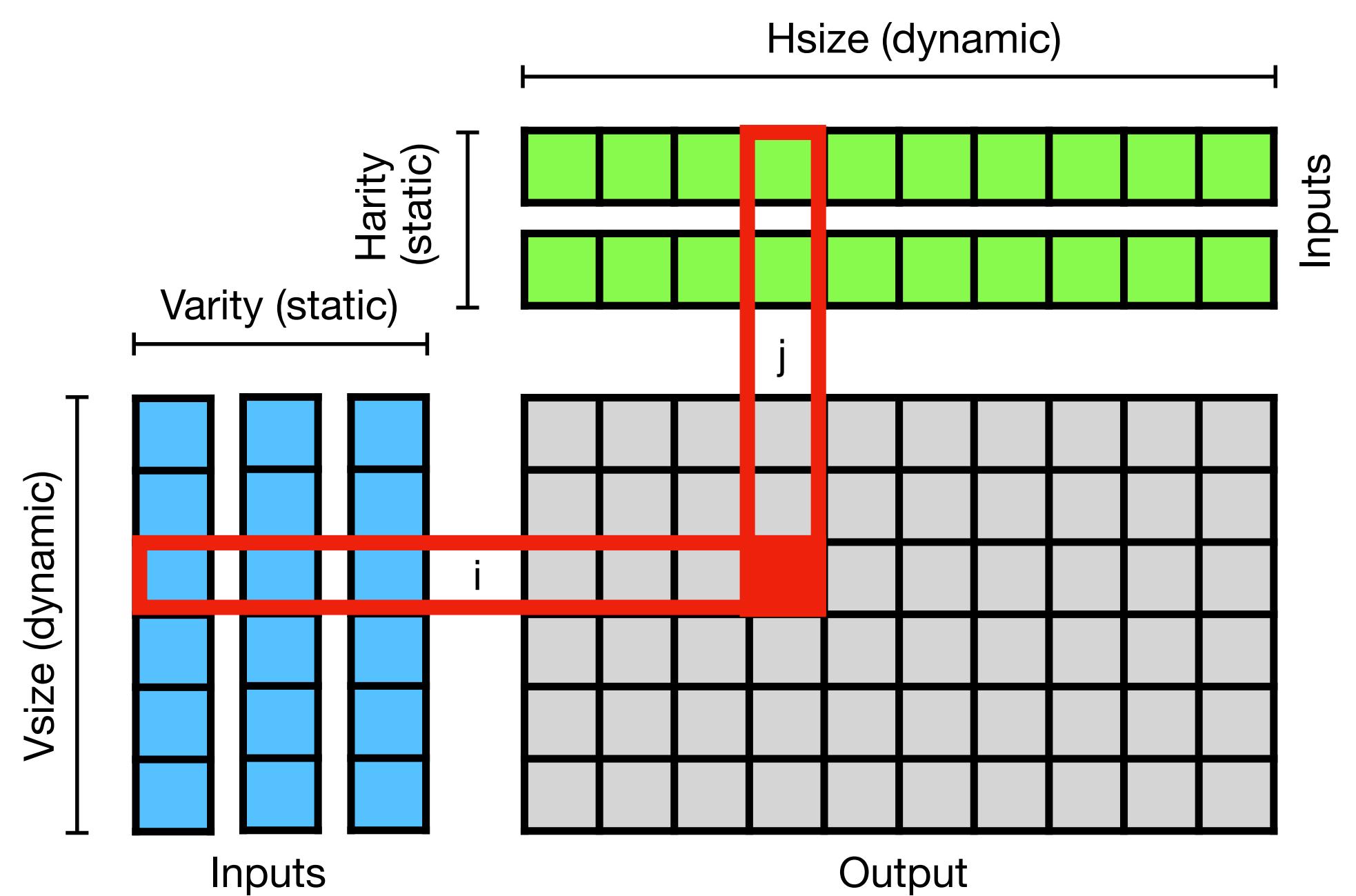
```
float conv(skepu::Region1D<float> r, int scale)
{
    return (r(-2)*4 + r(-1)*2 + r(0) + r(1)*2 + r(2)*4) / scale;
}

Vector<float> convolution(Vector<float> &v)
{
    auto convol = MapOverlap(conv);
    Vector<float> result(v.size());
    convol.setOverlap(2);
    return convol(result, v, 10);
}
```

```
float over_2d(skepu::Region2D<float> r, const skepu::Mat<float> stencil)
{
    float res = 0;
    for (int i = -r.oi; i <= r.oi; ++i)
        for (int j = -r.oj; j <= r.oj; ++j)
            res += r(i, j) * stencil(i + r.oi, j + r.oj);
    return res;
}
```

# MapPairs

- Generalized cartesian product / outer product of vectors
- Always results in a Matrix
- Syntactically, Map extended with another variadic elwise parameter group

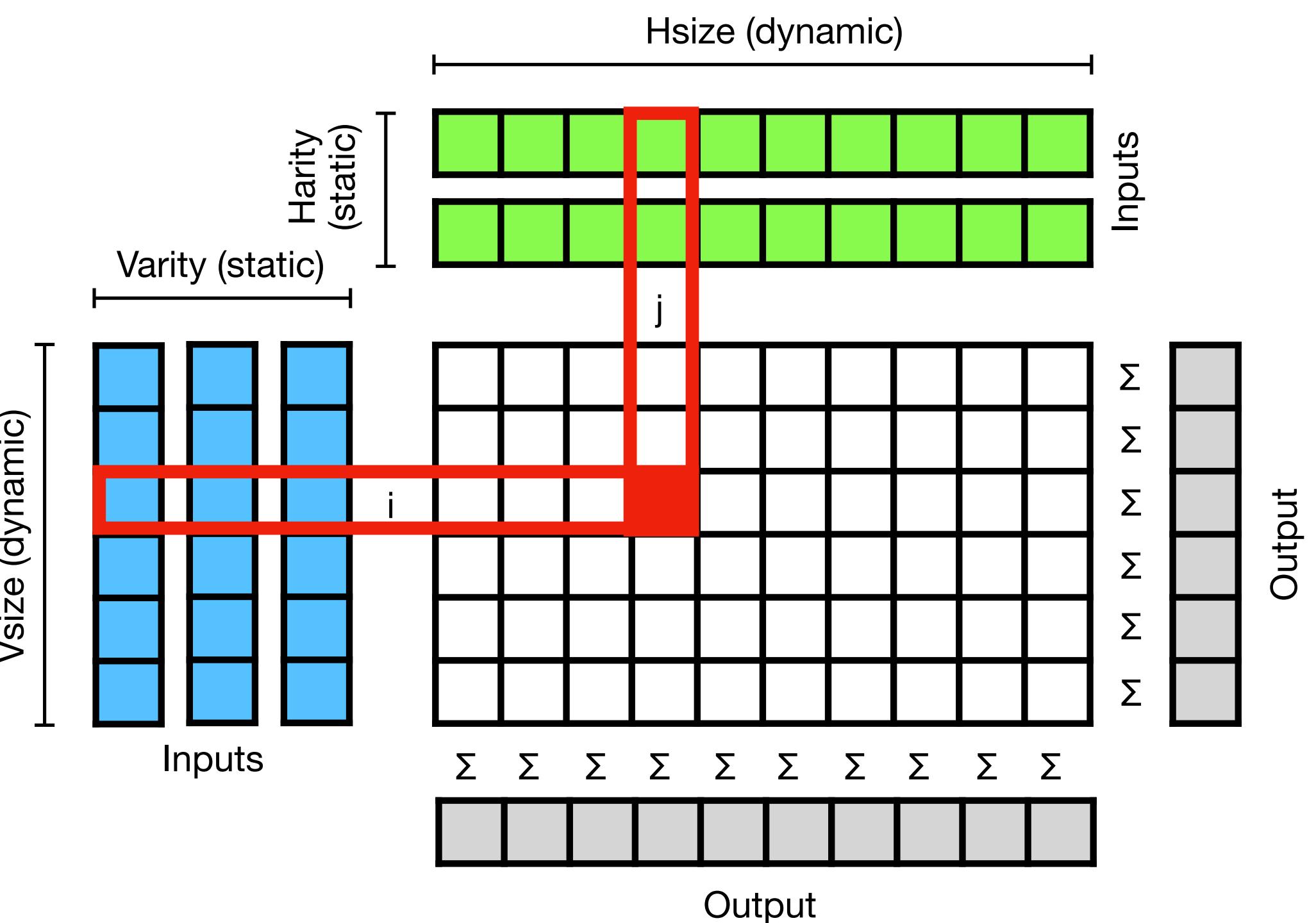


```
float ger_uf(float x, float y, float alpha)
{
    return alpha * x * y;
}

void outer_product(
    float alpha,
    Vector<float>& x,
    Vector<float>& y,
    Matrix<float>& A,
)
{
    auto skel = skepu::MapPairs<1, 1>(ger_uf);
    skel(A, x, y, alpha);
}
```

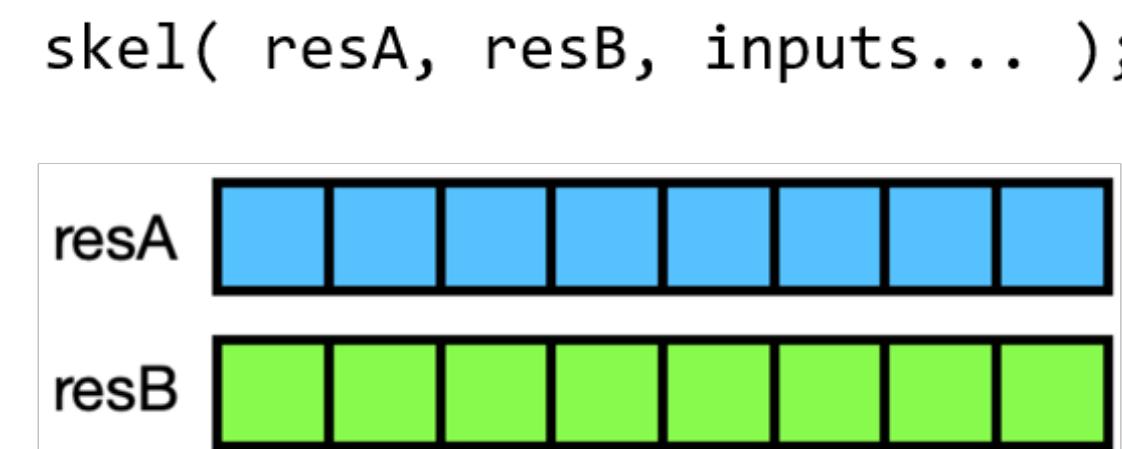
# MapPairsReduce

- MapPairs chained with reduction along rows or columns of the matrix
- Efficient: matrix need not be allocated in full



# Variadic Return

- Map\*\*\* skeletons optionally can return tuples of elements from the user function
- Compared to custom struct types, this stores results in several disjoint arrays



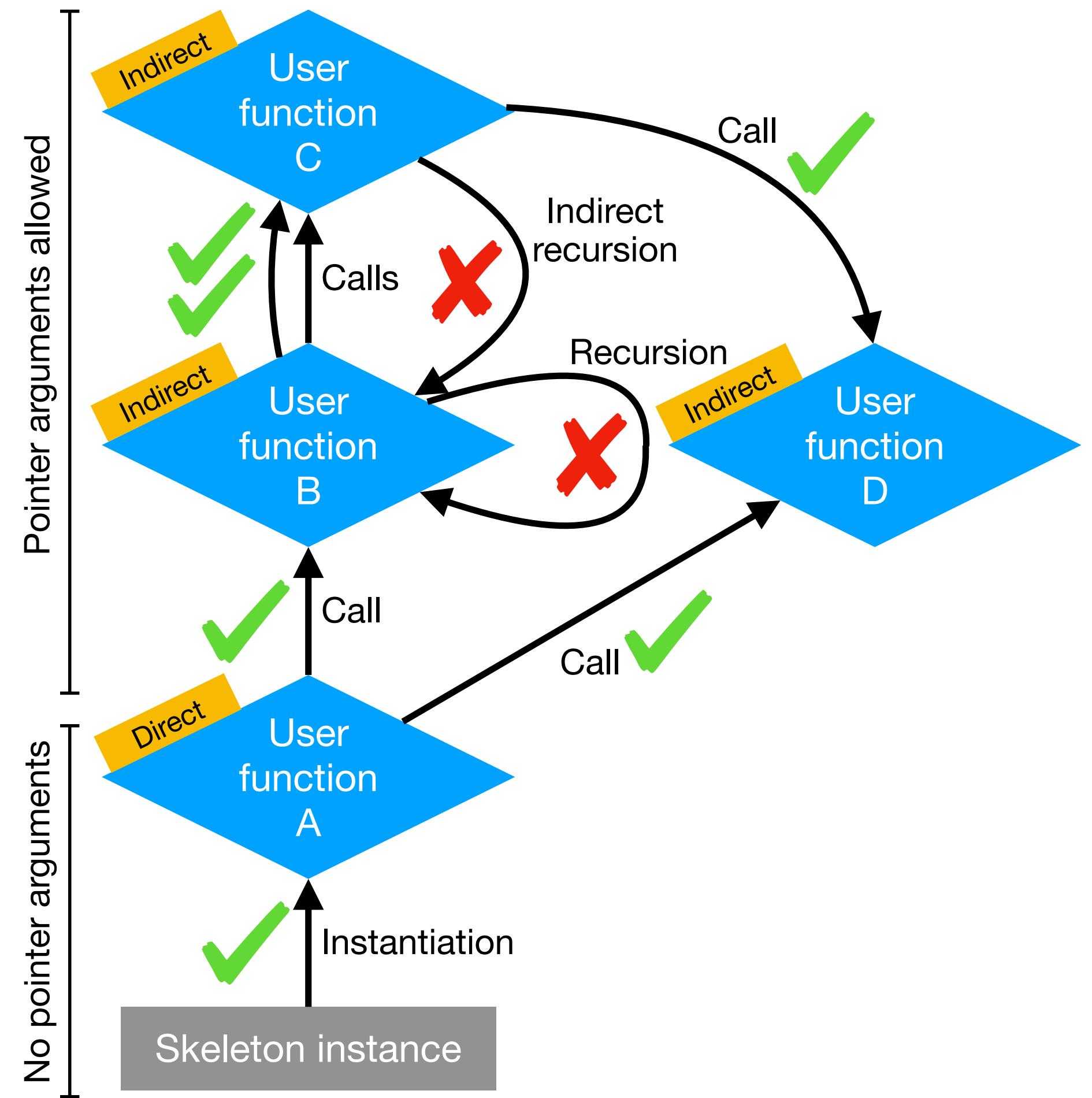
```
skepu::multiple<int, float>
test_f(skepu::Index1D index, int a, int b,
skepu::Vec<float> c, int d)
{
    return skepu::ret(a * b, (float)a / b);
}

// ...

auto test = skepu::Map<2>(test_f);
test(r1, r2, v1, v2, e, 10);
```

# Nested User Functions

- User functions may call other functions
- The callee will be processed as its own user function by the precompiler
- Some restrictions are relaxed over the uf-uf barrier: pointers may be allowed



# SkePU Standard Library

NB: Very new and subject to changes!

- SkePU “standard” library is a collection of **supporting APIs** to further simplify SkePU programming by eliminating the need for common boilerplate code.
- Some parts have framework integration, but most is implemented at **user-level** and can be used as reference for SkePU application programming.

 random	 complex	blas.hpp	filter.hpp	io.hpp	benchmark.hpp	util.hpp
skepu::Random<N> skepu::PRNG  Deterministic PRNG	skepu::complex<float> skepu::complex<double>  Complex number type, functions, and operator overloads	skepu::blas::axpy skepu::blas::gemv skepu::blas::gemm ...  Dense level 1-3 BLAS implementation	skepu::filter::blur skepu::filter::edge skepu::filter::downsample ...  Image filtering routines RGB + grayscale modes	skepu::io::cout skepu::io::cin skepu::io::cerr  I/O built on top of skepu::external	Lambda expression- based time measurement  Statistical processing  Automated backend alternation and measurement	skepu::util::add skepu::util::mul skepu::util::identity ...  Common user functions

\* Language/precompiler integration

- SkePU-accelerated BLAS implementation
  - User functions and multi-backend code generation “behind the scenes”
- Full coverage of level 1 BLAS
- Coverage of dense parts of level 2 + level 3
- Slightly modernized C++ function signatures
  - Otherwise argument-compatibility with CBLAS

## ● Conjugate gradient computation in SkePU-BLAS

```
#include <skepu>
#include <skepu-lib/blas.hpp>

template<typename T>
void conjugate_gradient(skepu::Matrix<T> BLAS_CONST& A, skepu::Vector<T> BLAS_CONST& b, skepu::Vector<T> &x)
{
    size_t N = b.size();
    assert(A.size_i() == N && A.size_j() == N && x.size() == N);
    skepu::Vector<T> p(N), r(N), Ap(N);

    // Set up initial r and p
    skepu::blas::copy(N, b, 1, r, 1);
    skepu::blas::gemv(skepu::blas::Op::NoTrans, N, N, -1.f, A, N, x, 1, 1.f, r, 1);
    skepu::blas::copy(N, r, 1, p, 1); // p := r

    float rTr = skepu::blas::dot(N, r, 1, r, 1); // rTr = r * r

    for (size_t k = 0; k < N; ++k)
    {
        // Compute alpha
        skepu::blas::gemv(skepu::blas::Op::NoTrans, N, N, 1.f, A, N, p, 1, 0.f, Ap, 1); // Ap := A * p
        float tmp = skepu::blas::dot(N, p, 1, Ap, 1); // tmp := p * Ap = p * A * p
        float alpha = rTr / tmp;

        // Update x
        skepu::blas::axpy(N, alpha, p, 1, x, 1); // x := x + alpha * p

        // Update r
        skepu::blas::axpy(N, -alpha, Ap, 1, r, 1); // r := r - alpha * Ap

        // Compute beta
        float rTr_new = skepu::blas::dot(N, r, 1, r, 1); // rTr_new := r * r
        float beta = rTr_new / rTr;

        // Early exit condition
        if (sqrt(rTr_new) < 1e-10f)
            return;

        // Update p
        skepu::blas::scal(N, beta, p, 1); // p := beta * p
        skepu::blas::axpy(N, 1.f, r, 1, p, 1); // p := r + p

        rTr = rTr_new;
    }
}
```

- `skepu::Random<N>` as user function parameter

- Always first in parameter list
- Maximum of one such parameter may be present
- `.get()` extracts integers in [0, MAX)
- `.getNormalized()` extracts real numbers in [0, 1)

- `skepu::PRNG`

- Outside user functions
- Represents individual PRNG streams  
to bind to skeleton instances

- Monte-Carlo Pi calculation

```
#include <iostream>
#include <skepu>

int monte_carlo_sample(skepu::Random<2> &random)
{
    float x = random.getNormalized();
    float y = random.getNormalized();
    // check if (x,y) is inside region:
    return ((x*x + y*y) < 1) ? 1 : 0;
}

int add(int lhs, int rhs) { return lhs + rhs; }

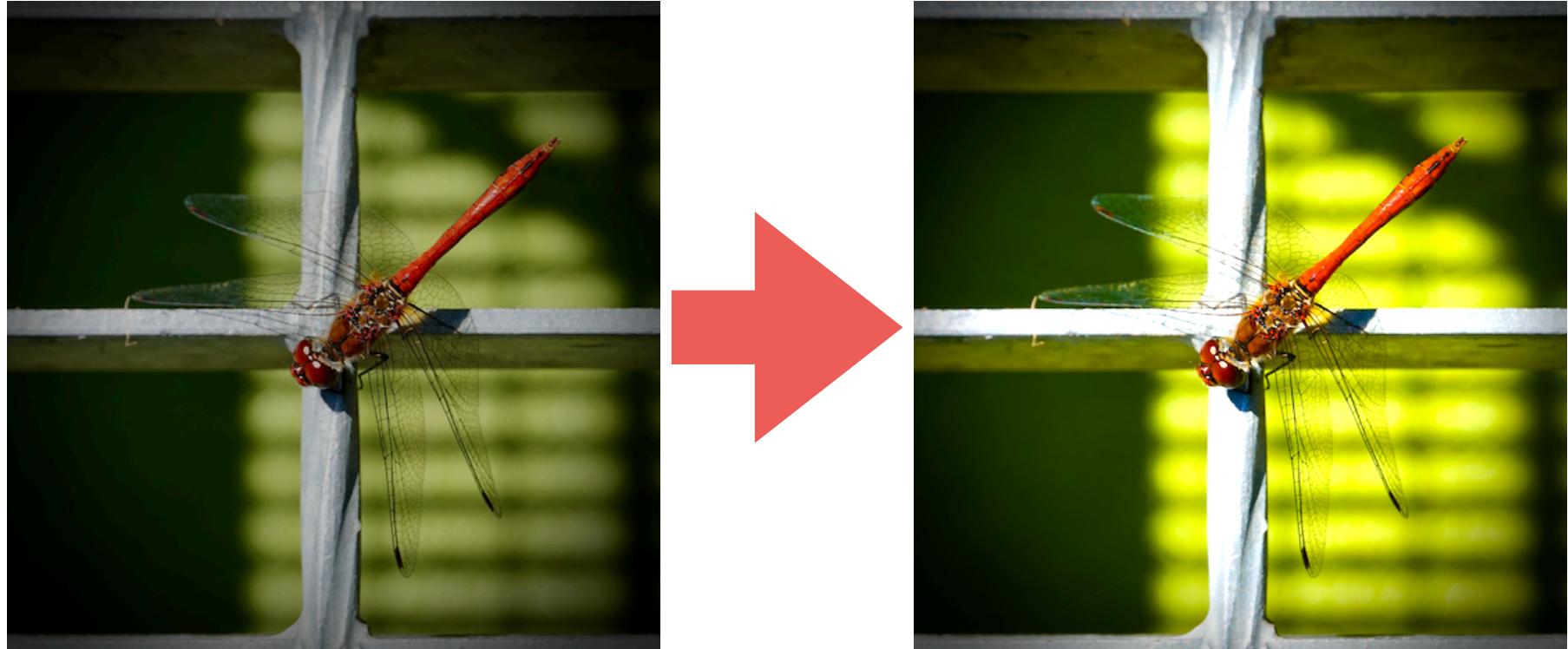
int main(int argc, char *argv[])
{
    auto montecarlo = skepu::MapReduce<0>(monte_carlo_sample, add);

    skepu::PRNG prng(0);          // seed
    montecarlo.setPRNG(prng);

    const size_t samples = atoi(argv[1]);
    montecarlo.setDefaultSize(samples);

    double pi = (double)montecarlo() / samples * 4;
    std::cout << pi << "\n";
}
```

- SkePU is well-suited for image processing with its **Map** and **MapOverlap** skeletons and **GPU** backends
- Image processing is also useful for **visualizing** unrelated HPC applications, e.g. heat diffusion
- Standard library includes **image filtering** primitives



- Data types for **pixels** in various formats
  - Grayscale, RGB, RGBA, HSV, HSVA
- **Filter kernel** user functions, e.g.
  - Pixel conversions
  - Channel adjustments (brightness, contrast, ...)
  - Convolutions (blurs, edge detection, ...)

```
#include <skepu>
#include <skepu-lib/filter.hpp>

skepu::Matrix<skepu::filter::RGBPixel> image;
// (Load image from file here)

auto lighten = skepu::Map<1>(skepu::filter::lighten_rgb);
auto saturate = skepu::Map<1>(skepu::filter::saturate_rgb);

lighten(image, image, 0.5); // In-place update
saturate(image, image, 0.5); // In-place update
```

- SkePU standard library includes frequently seen user functions in the `skepu::util` namespace
  - Arithmetic operations
  - Identity mapping, type conversions
  - Max, min, ...

```
#include <skepu>
#include <skepu-lib/util.hpp>

skepu::Vector<float> a(N), b(N);

auto dotproduct = skepu::MapReduce(skepu::util::mul<float>, skepu::util::add<float>);

float res = dotproduct(a, b);
```

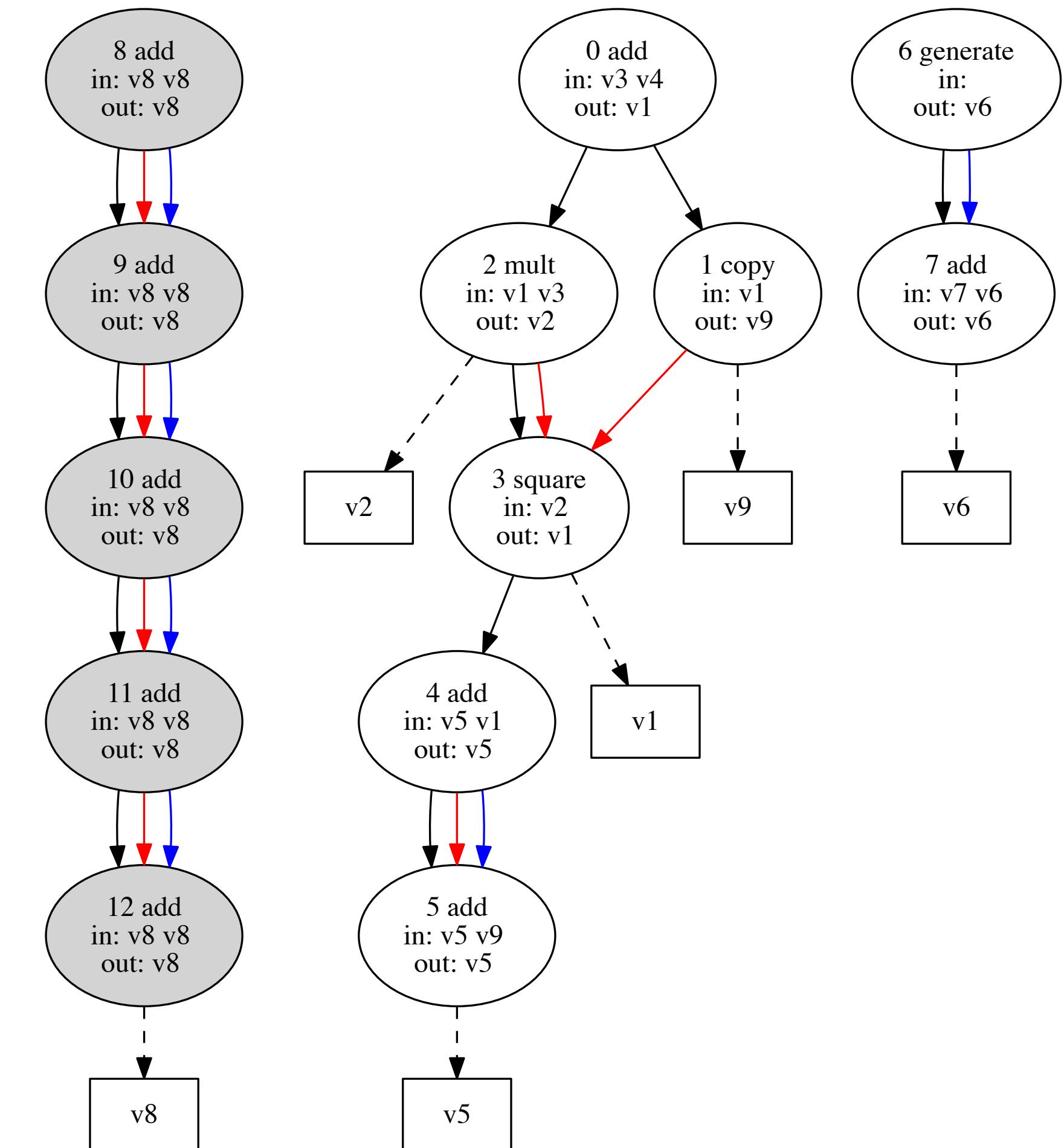
# SkePU in **Current Research**

# Lazy Skeleton Evaluation

- SkePU extended with **lazy evaluation** of the Map skeleton
- No change in syntax, lineage graph built automatically at run-time
- Existing smart containers extended with some of the RDD semantics
- Non-Map operations cause lineage to be evaluated
  - Possibly out of order, while satisfying dependencies
- Run-time dataflow information can assist backend selection

```

add(v1, v3, v4);
copy(v9, v1);
mult(v2, v1, v3);
square(v1, v2);
add(v5, v5, v1);
add(v5, v5, v9);
add(v6, v7, generate(v6, 5.f));
for (int i = 0; i < 5; i++)
    add(v8, v8, v8);
  
```



SkePU lineage graph from program

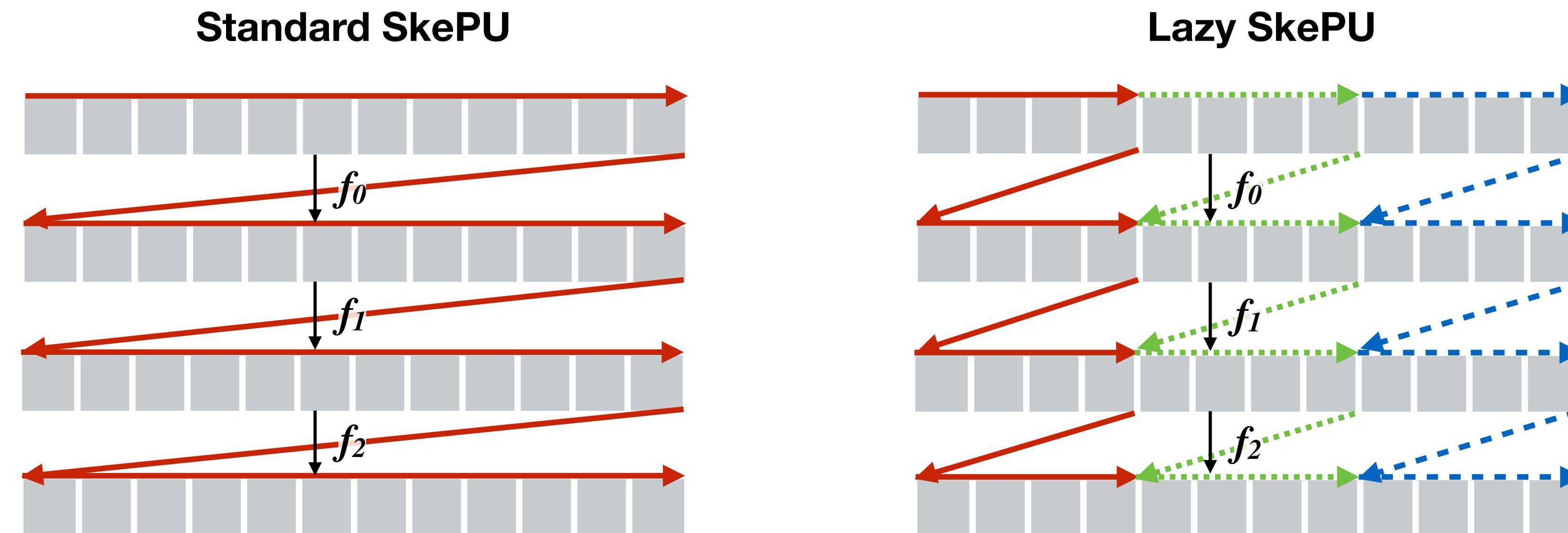
**Compile-time**

SkePU precompiler  
with transformations  
Static dataflow information

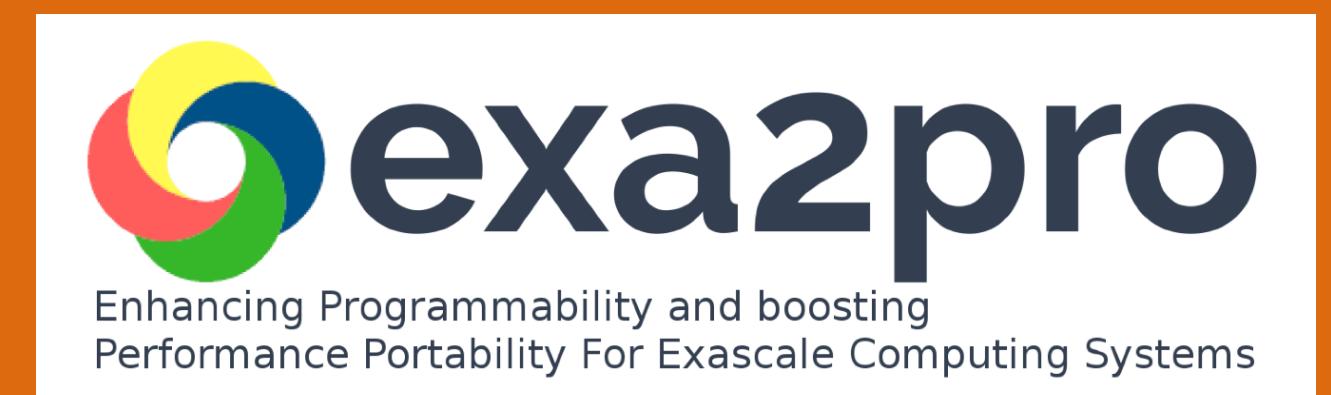
**Run-time**

Auto-tuning  
Smart containers  
Dynamic dataflow information

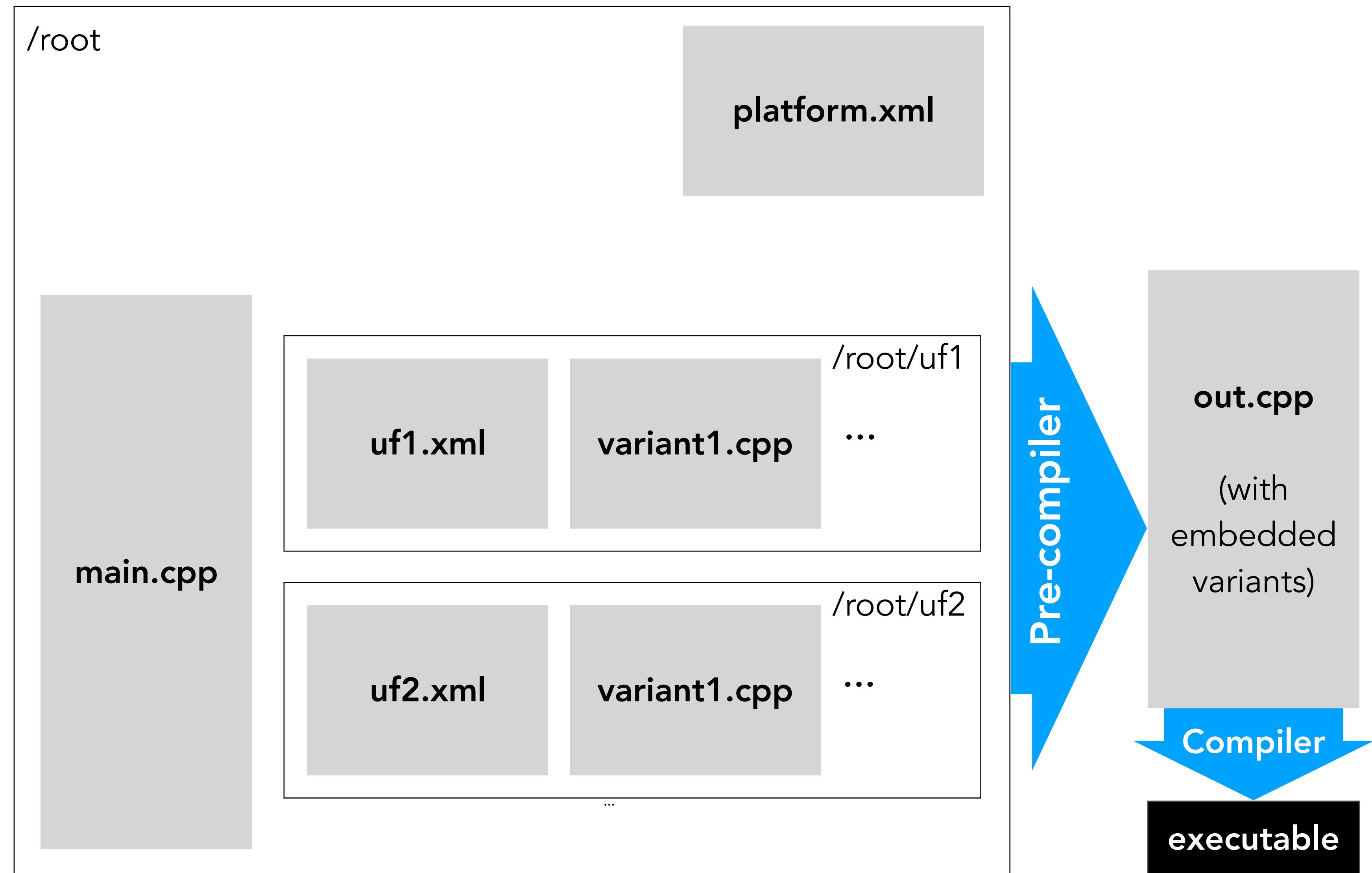
- Lineages evaluated by **tiling** computations
  - Efficient cache utilization on CPU
  - Using accelerators with limited memory space
  - Any situation where cached data is important for performance



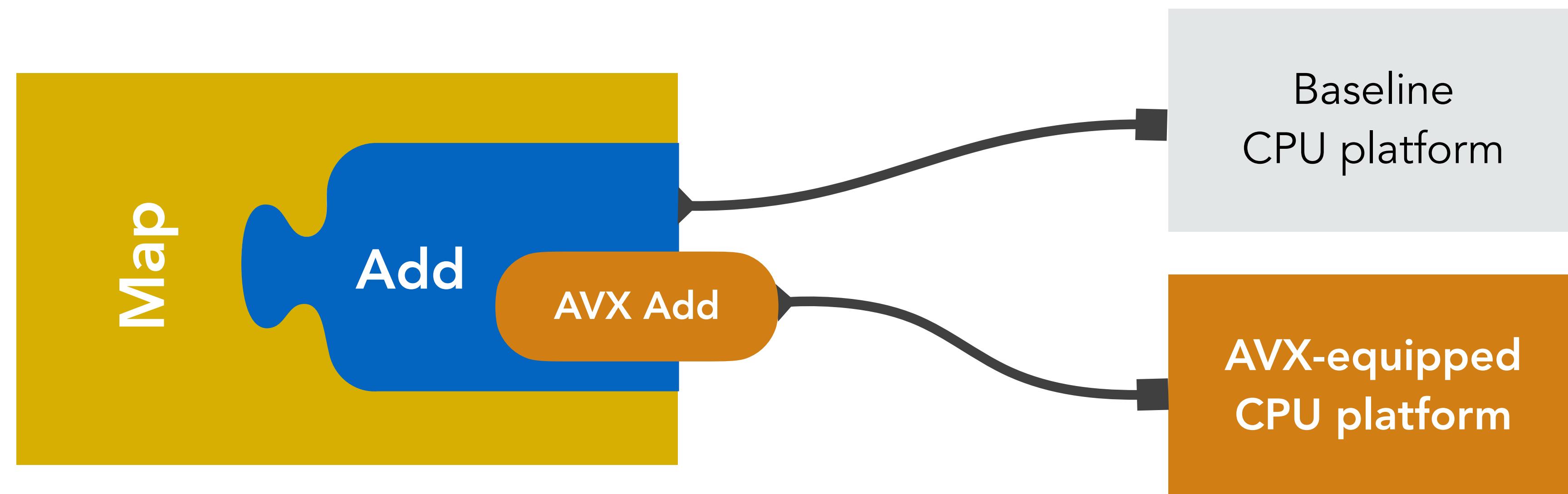
# Multi-Variant User Functions



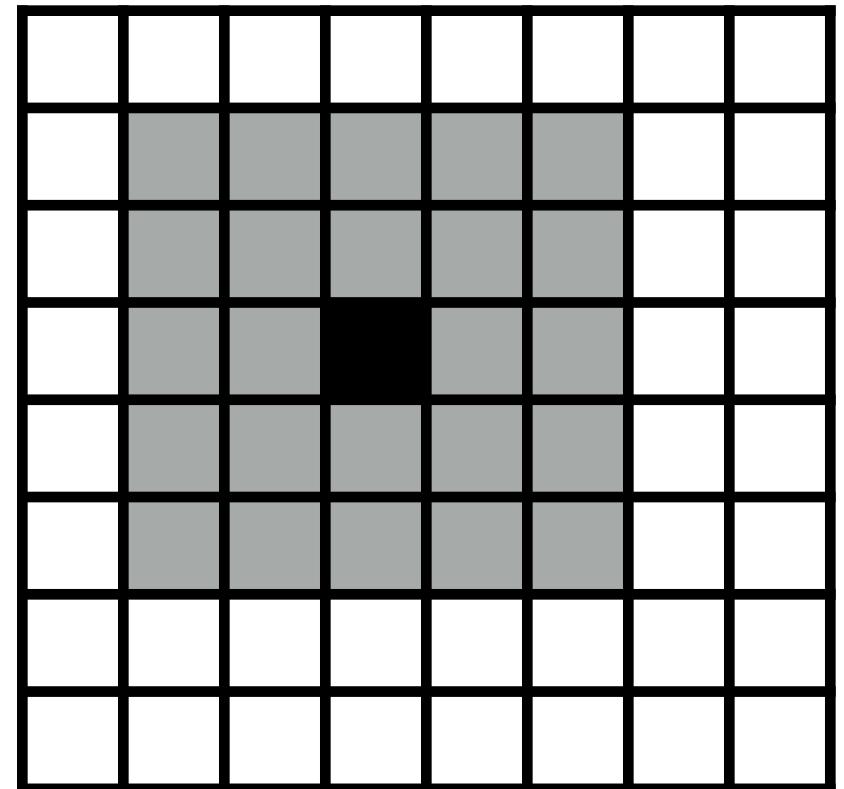
- Single-source, in-line user function definitions are **easy to use**
- **But:** might not always be **performance optimal** approach across backends!
- **Idea:** Leverage multi-variant component approach in Exa2Pro also on skeleton/SkePU level
  - Let each user function have multiple *implementation* variants conforming to the same *interface*
  - Algorithmic variants
  - Hardware/ISA optimizations (vectorize, crypto, ...)
  - External library acceleration, ...
- Each variant only selectable when the target system **supports** it  
=> platform-aware (XPDL) source-to-source compilation



- Data-parallel algorithms using Map skeleton
- Archetype of skeleton programming: element-wise vector sum
- To increase the complexity, also do element-wise multiplication of complex numbers

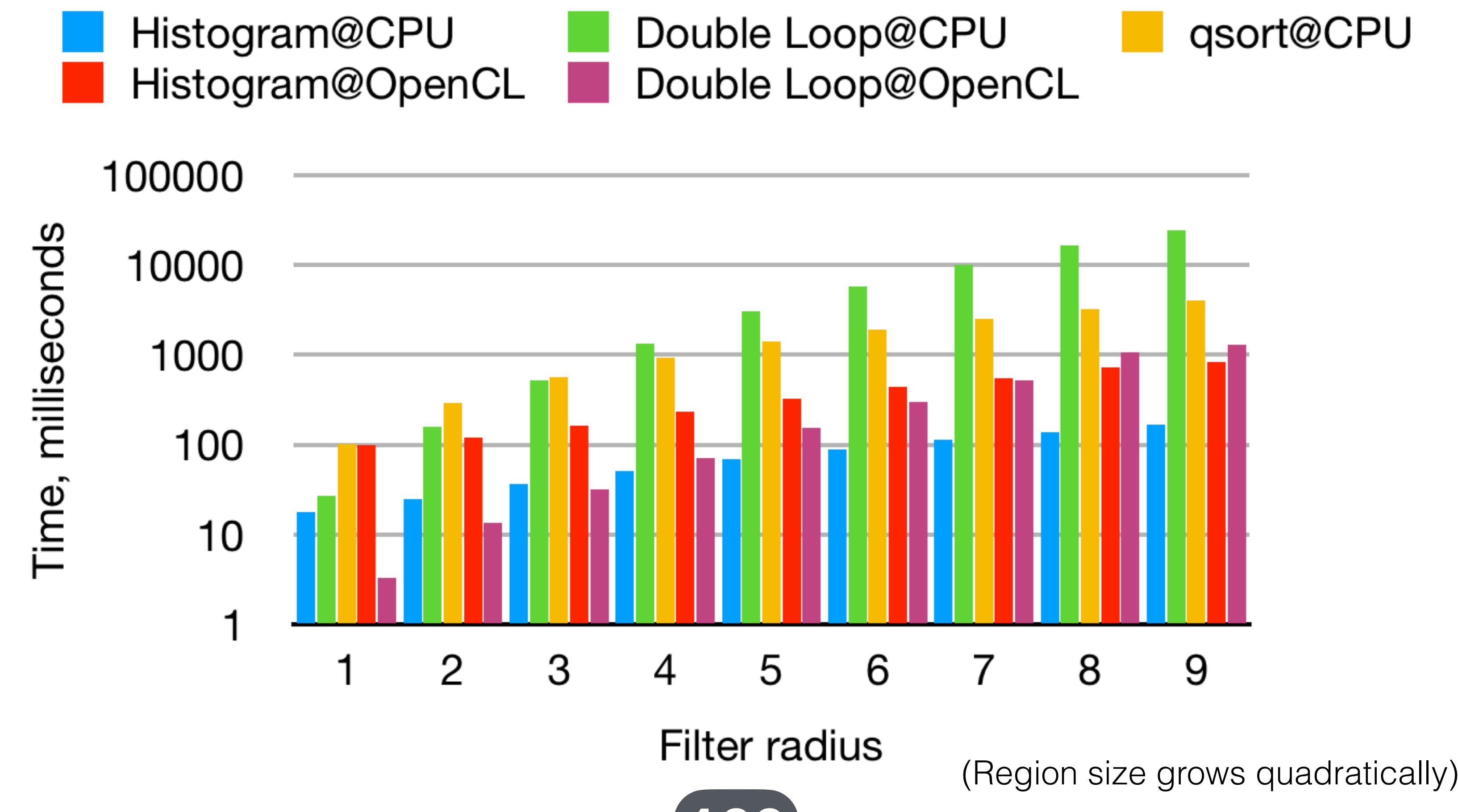


- Median filtering: a blurring **image filter** with MapOverlap
- Data-parallel in the “outer” dimensions
- **Multiple algorithmic** approaches in the “inner” dimensions
  - Naive nested-loop comparison
  - Sorting
  - Histogram (note: data independent)



Variant	Time complexity	Memory complexity	Dependencies
Double loop	$\mathcal{O}(n^2)$	$\mathcal{O}(1)$	None
Histogram	$\mathcal{O}(n +  D )$	$\mathcal{O}( D )$	None
qsort	$\mathcal{O}(n \log n)$	$\mathcal{O}(n)$	C standard library

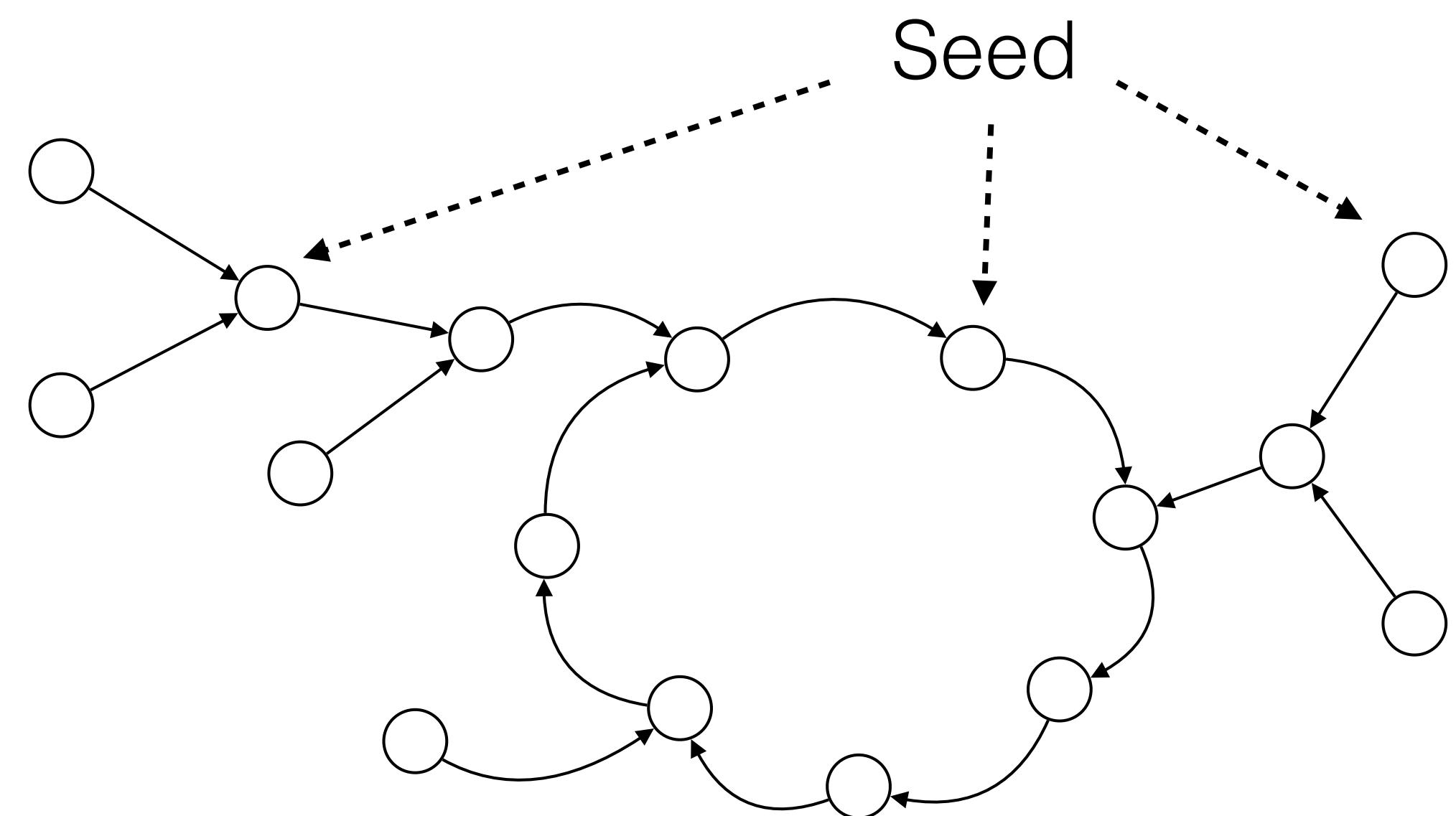
Variant	Time complexity	Memory complexity	Dependencies
Double loop	$\mathcal{O}(n^2)$	$\mathcal{O}(1)$	None
Histogram	$\mathcal{O}(n +  D )$	$\mathcal{O}( D )$	None
qsort	$\mathcal{O}(n \log n)$	$\mathcal{O}(n)$	C standard library



# Deterministic Pseudo- Random Number Generation



- Pseudo-random number generator (PRNG)
- **Finite state automaton**
  - `rand()` produces a pseudo-“random” number from its internal state  $S(n)$  and transitions to new state  $S(n+1)$
  - Inherently **sequential**
  - Naturally **deterministic**:  
State  $S(n)$  depends only on state  $S(0)$  and  $n$
  - Input: **seed** (determines initial state)



```
void my_parallel_function(...)  
{  
    int rand_val = rand(); // library function  
}
```

Pseudocode

- **Race conditions**
  - Corrupted state
  - Repeated outputs
  - Loss of determinism



Bad statistical quality!

## Global synchronization

```
void my_parallel_function(...)  
{  
    mutex_lock(...);  
    int rand_val = rand(); // library function  
    mutex_unlock(...);  
}
```

Pseudocode

## Pre-generated buffers

```
void my_parallel_function(int randvals[], ...)  
{  
    int i = my_thread_id();  
    int rand_val = randvals[i++];  
}
```

Pseudocode

- Flexible

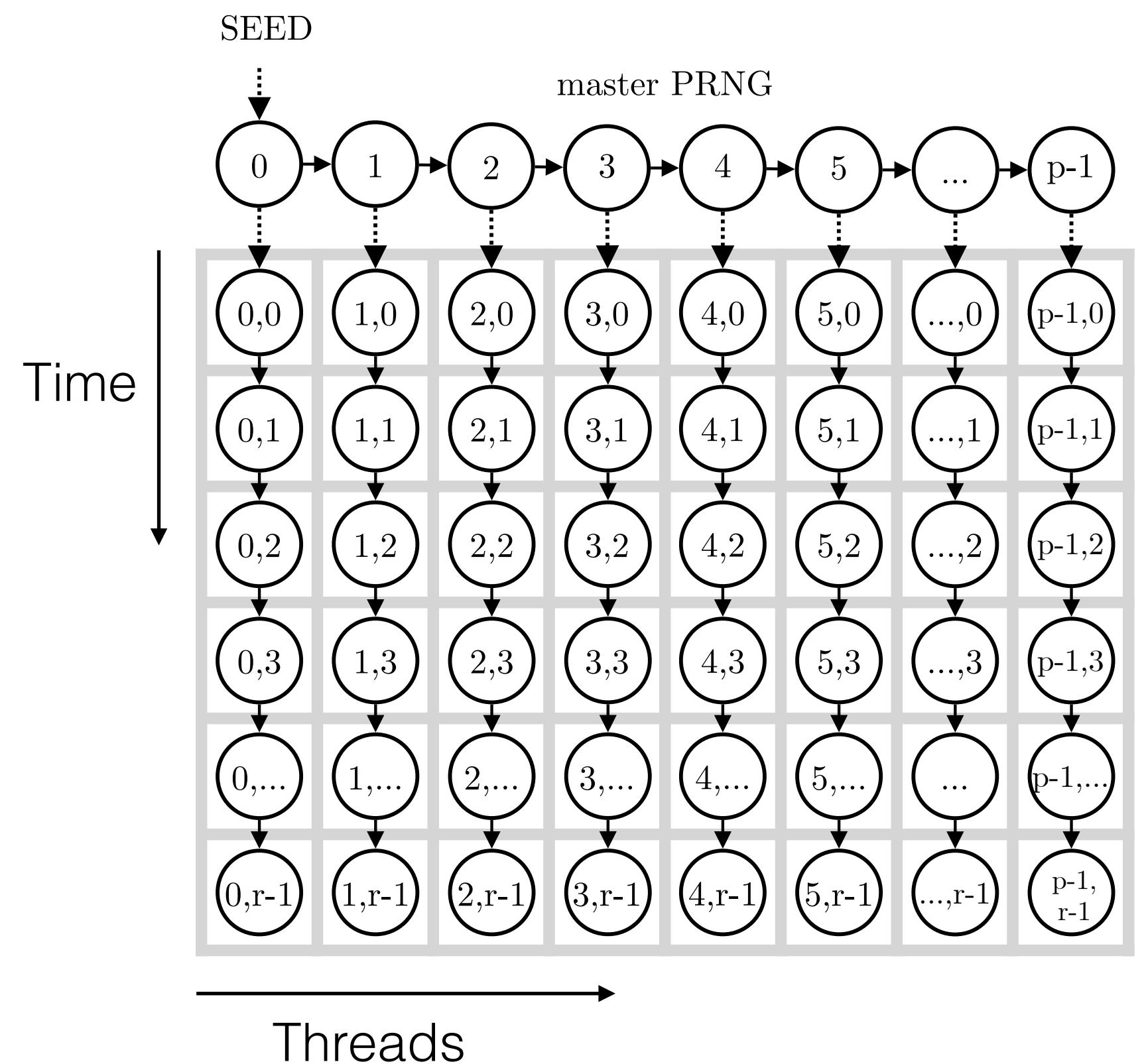
- Simple: works like any data buffer
- Widely supported

- Sequentialization
- Non-determinism
- Might not be supported (e.g. SkePU)
- Synchronization overhead

- Not really parallel
- Manual pre-allocation of numbers
- Data movement costs

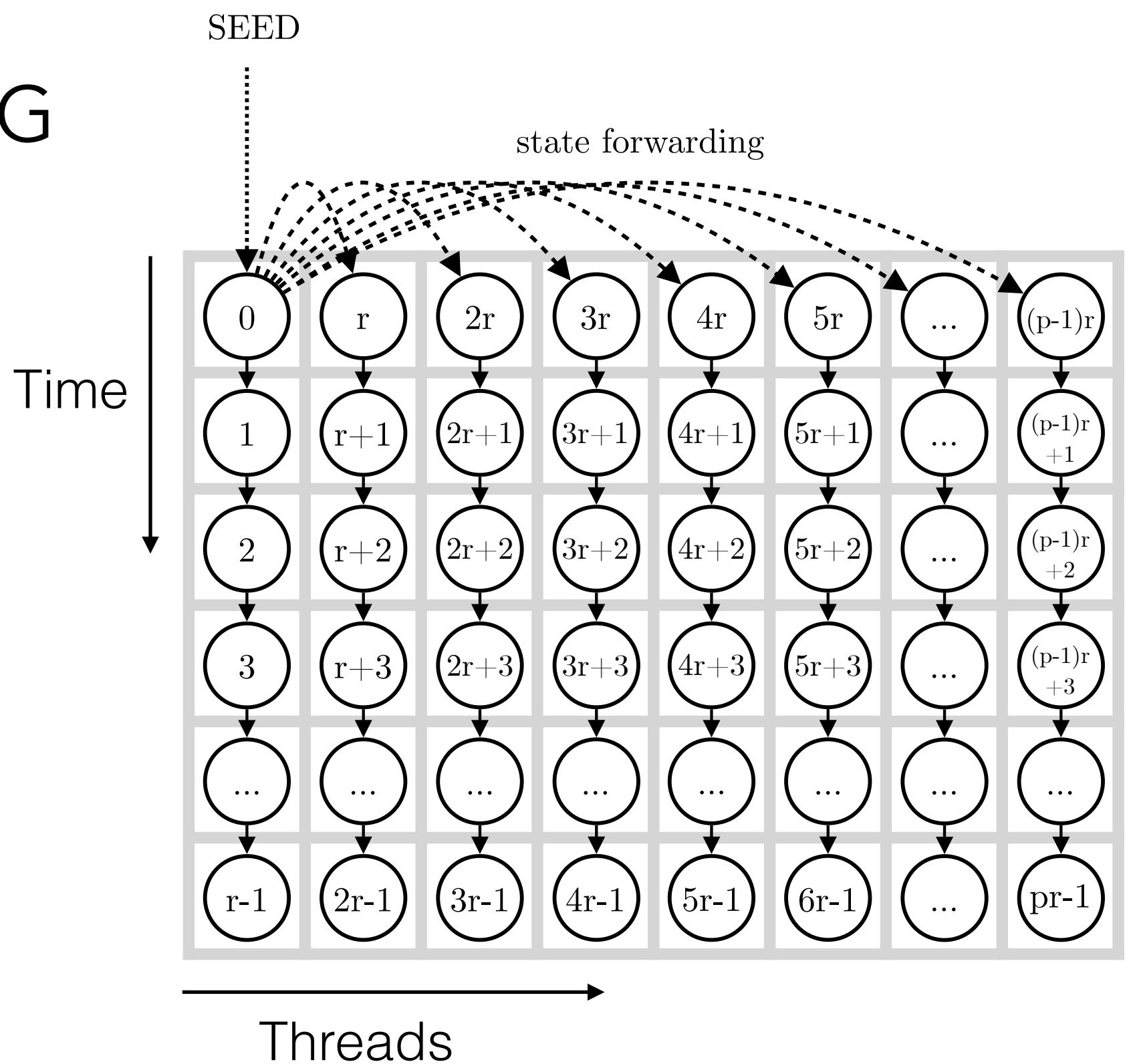
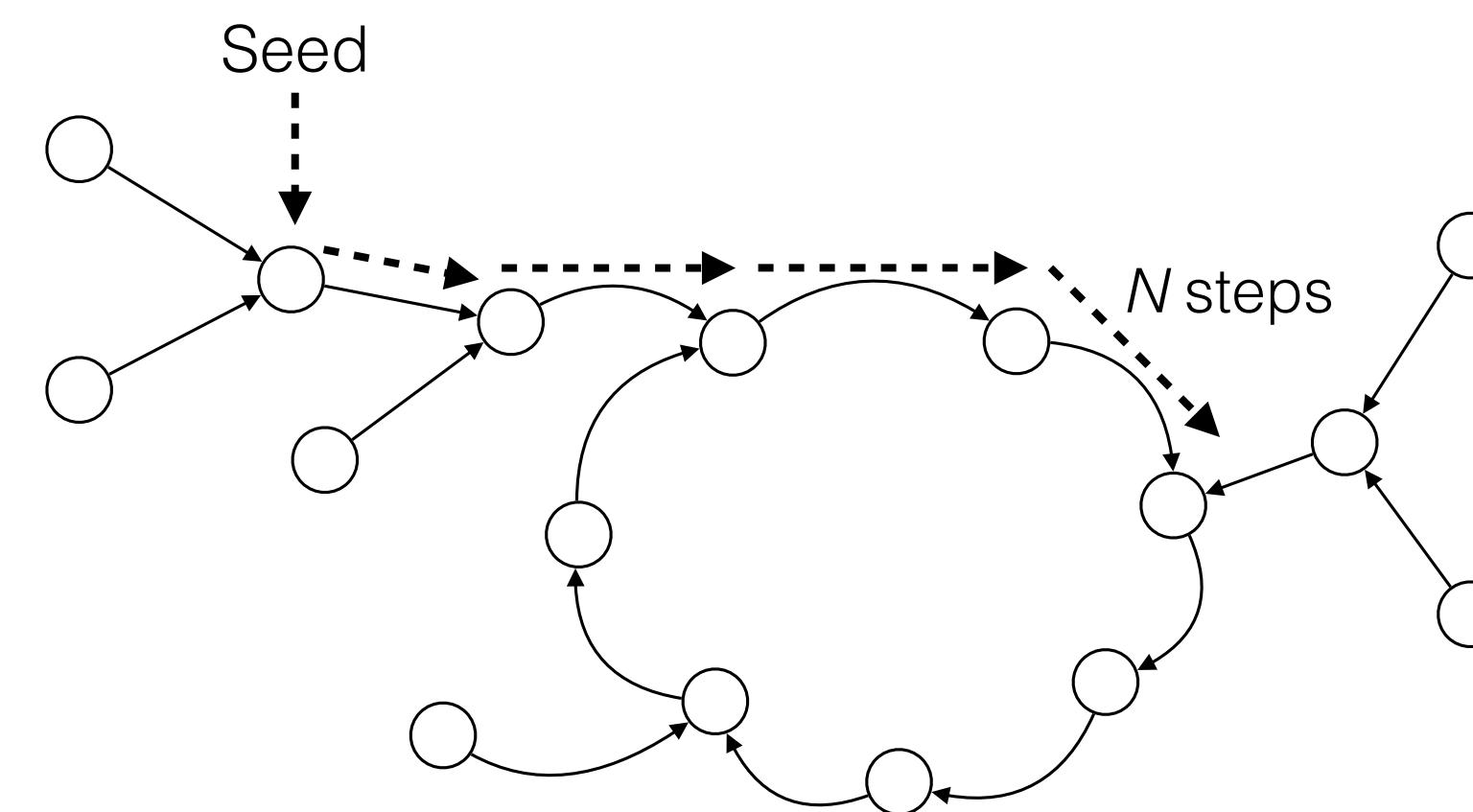
... we can do better!

- Basic idea: Give each worker thread a **separate** independent PRNG state
  - No synchronization needed
  - PRNG generation in parallel – no bulk data movement
- Individual PRNGs are **independent**
- Loss of original single-PRNG structure
- Need  $p$  seeds
  - Hierarchical seeding: **master PRNG** producing seeds
- This was roughly the approach for the first SkePUized LQCD prototype



... we can go further!

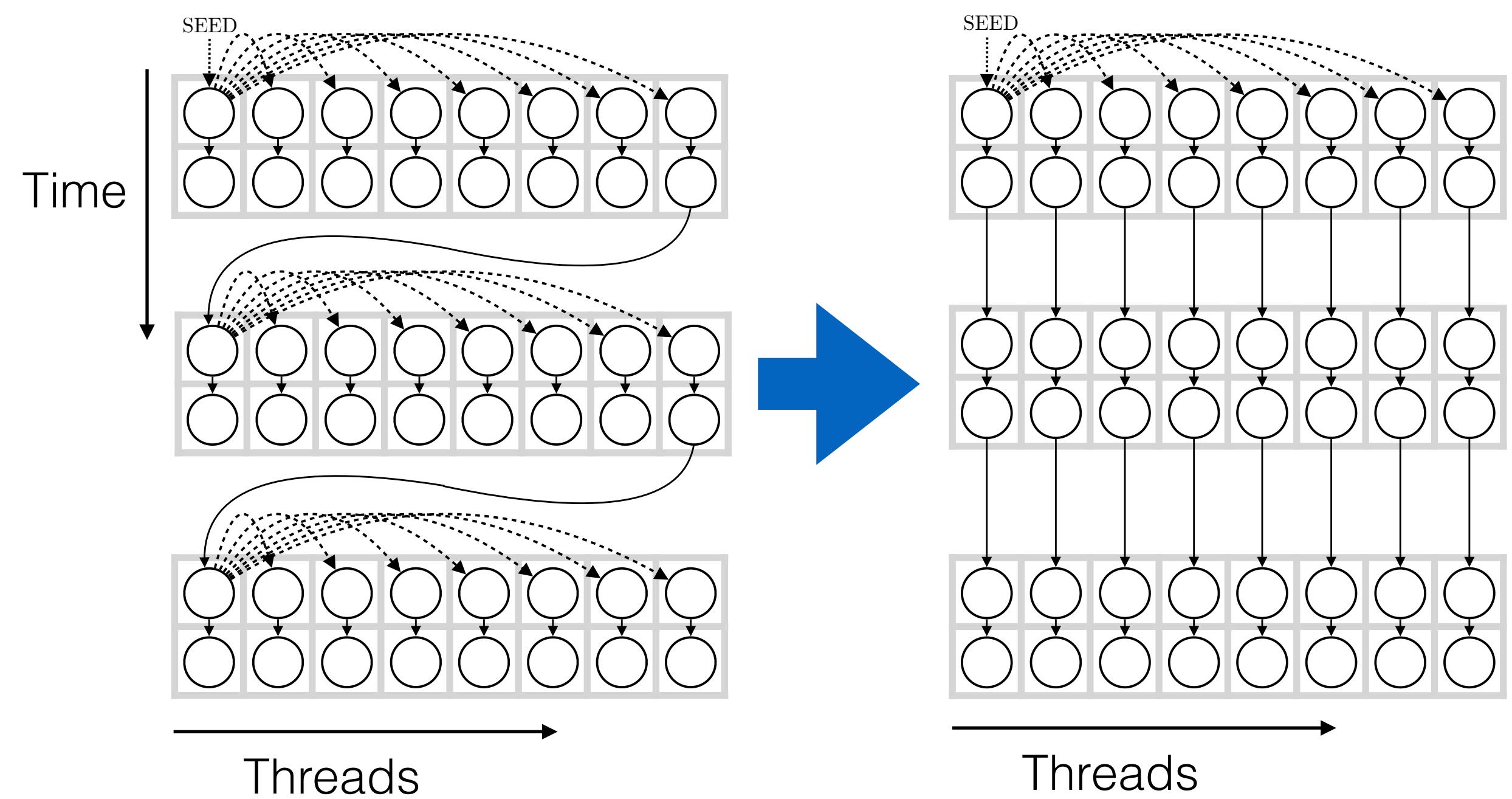
- **Goals:**
  - Retain the advantages of “stream splitting” approach
  - Reclaim structure and determinism from sequential PRNG
- **Recall:** PRNG state automaton
  - We can **advance** the state  $N$  steps at any point!
  - As long as we know #calls to PRNG in each thread



- Forwarding step incurs some overhead
- For **sequences** of skeleton calls, including **iterative** computations, we want to forward as few times as possible
- **Pre-forward approach** for sequences of skeletons when program flow is known ahead of execution-time
  - Static analysis
  - Lineage building
  - Programmer annotation

Ernstsson, Kessler, HLPP 2017  
<https://doi.org/10.1002/cpe.5003>

```
for (int i = 0; i < N; ++i)
{
    my_skeleton_instance(..);
}
```



# Behind the Scenes

- SkePU is now **open-source on GitHub**: [skepu.github.io](https://skepu.github.io)
  - Permissive modified BSD-license
  - Systematic automated testing
  - Continuously improving user guide, tutorials, etc.
- SkePU is a key framework in the H2020 EXA2PRO research project
- SkePU is actively used in **teaching** (parallel programming courses at LiU)

