## **GAN Debugging Notebook**

This notebook is provided to help you debug your code. We provide you with small discriminator and generator networks that you can train on the MNIST dataset. This small GAN can be trained quickly on MNIST and will help you verify that your loss functions and training code is correct.

```
In [ ]: import torch
        import torch.nn as nn
        from torchvision import datasets
        from torchvision import transforms
        from torch.utils.data import DataLoader
        from torchvision.datasets import ImageFolder
        import numpy as np
        import matplotlib.pyplot as plt
        import matplotlib.gridspec as gridspec
        %matplotlib inline
        plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
        plt.rcParams['image.interpolation'] = 'nearest'
        plt.rcParams['image.cmap'] = 'gray'
        %load ext autoreload
        %autoreload 2
In [ ]: | from gan.train import train
        from gan.utils import sample noise, show images, deprocess img, preprocess img
        from gan.losses import discriminator loss, generator loss, ls discriminator lo
        ss, ls_generator_loss
In [ ]: device = torch.device("cuda:0" if torch.cuda.is_available() else "cpu")
```

## **MNIST Dataset**

## **Discriminator and Generator**

```
In [ ]: class Flatten(nn.Module):
            def forward(self, x):
                N, C, H, W = x.size() \# read in N, C, H, W
                return x.view(N, -1) # "flatten" the C * H * W values into a single v
        ector per image
In [ ]: | def discriminator():
            Initialize and return a simple discriminator model.
            model = torch.nn.Sequential( Flatten(),
                                         torch.nn.Linear(784, 256),
                                         torch.nn.LeakyReLU(),
                                         torch.nn.Linear(256, 256),
                                         torch.nn.LeakyReLU(),
                                         torch.nn.Linear(256, 1)
            return model
In [ ]: def generator(noise_dim=NOISE_DIM):
            Initialize and return a simple generator model.
            model = nn.Sequential(
                torch.nn.Linear(noise_dim, 1024),
                torch.nn.ReLU(),
                torch.nn.Linear(1024, 1024),
                torch.nn.ReLU(),
                torch.nn.Linear(1024, 784),
                torch.nn.Tanh()
            )
            return model
```

Test to make sure the number of parameters in the generator is correct:

## **Train**

The simple model provided will train on MNIST in only a few minutes. You should expect results that resemble the following if your loss function and training loop implementations are correct:

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```
In []: # original GAN
    D = discriminator().to(device)
    G = generator().to(device)

D_optimizer = torch.optim.Adam(D.parameters(), lr=1e-3, betas = (0.5, 0.999))
    G_optimizer = torch.optim.Adam(G.parameters(), lr=1e-3, betas = (0.5, 0.999))

train(D, G, D_optimizer, G_optimizer, discriminator_loss, generator_loss, train_loader=loader_train, num_epochs=10, device=device)
```

```
In []: # LSGAN
D_LS = discriminator().to(device)
G_LS = generator().to(device)

D_LS_optimizer = torch.optim.Adam(D_LS.parameters(), lr=1e-3, betas = (0.5, 0.999))
G_LS_optimizer = torch.optim.Adam(G_LS.parameters(), lr=1e-3, betas = (0.5, 0.999))

train(D_LS, G_LS, D_LS_optimizer, G_LS_optimizer, ls_discriminator_loss, ls_generator_loss, train_loader=loader_train, num_epochs=10, device=device)
```

```
In [ ]:
```