$$G(s) = \frac{\beta^2}{s^2 + \beta_1 s + \beta_0}$$

$$\downarrow Discretized plant model:  $y(k) = \theta_1 y(k-1) + \theta_2 y(k-2) + \theta_3 u(k-1) + \theta_4 u(k-2) = \phi^T(k)\theta,$ 

$$\theta(k) = [\theta_1, \theta_2, \theta_3, \theta_4]^T,$$

$$\phi(k) = [\theta_1(k), \hat{\theta}_2(k), \hat{\theta}_3(k), \hat{\theta}_4(k)]^T,$$

$$T_S \text{ is sampling time,}$$

$$P(0) = P_0 = P_0^T > 0, P_0 = \rho \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$$$

 $\mathbf{x}(k+1) = \hat{\mathbf{A}}_d \mathbf{x}(k) + \hat{\mathbf{B}}_d u(k)$ 

 $y(k+1) = \hat{\mathbf{C}}_d \mathbf{x}(k)$ 

 $y(t) = \widehat{\mathbf{C}}_c \mathbf{x}(t)$ 

Output y(t)

Plant

Discretized plant model in state space

where 
$$\hat{\mathbf{A}}_d = \begin{bmatrix} 0 & 1 \\ -\hat{\theta}_2 & -\hat{\theta}_1 \end{bmatrix}, \qquad \hat{\mathbf{B}}_d = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \qquad \hat{\mathbf{C}}_d = [\hat{\theta}_4, \ \hat{\theta}_3]$$

. Estimated continuous model is: 
$$\dot{\mathbf{x}}(t) = \widehat{\mathbf{A}}_c x(t) + \widehat{\mathbf{B}}_c u(t)$$

where

Excitation

$$\widehat{\mathbf{A}}_{c} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = \frac{2}{T} \mathbf{R} \left[ \mathbf{I}_{2x2} - \frac{8}{21} \mathbf{R}^2 - \frac{4}{105} \mathbf{R}^4 \right] \left[ \mathbf{I}_{2x2} - \frac{5}{7} \mathbf{R}^2 \right]^{-1}$$

$$\widehat{\mathbf{B}}_{c} = \begin{bmatrix} b_{11} \\ b_{21} \end{bmatrix} = \widehat{\mathbf{A}}_{c} \left[ \widehat{\mathbf{A}}_{d} - \mathbf{I}_{2x2} \right]^{-1} \widehat{\mathbf{B}}_{d}, \qquad \widehat{\mathbf{C}}_{c} = [c_{11}, c_{12}] = \widehat{\mathbf{C}}_{d}$$

$$\mathbf{R} = \left[ \widehat{\mathbf{A}}_{d} - \mathbf{I}_{2x2} \right] \left[ \widehat{\mathbf{A}}_{d} + \mathbf{I}_{2x2} \right]^{-1}$$

So, we calculate:

$$\hat{\beta}_0(k) = a_{11}a_{22} - a_{12}a_{21}, \quad \hat{\beta}_1 = -(a_{11} + a_{22}), \quad \hat{\beta}_2 = c_{11}(b_{21}a_{12} - b_{11}a_{22}) + c_{12}(b_{11}a_{21} - b_{21}a_{11})$$