A computer-based educational tool for generating experimental design examples

Abstract

In this article, challenges in designing example problems of multifactorial experiments for an academic purpose are identified, and an algorithm for simulating multifactorial experiments is presented. It is based on a proposed mathematical function that is not concave, mimics a physical system, can be employed for any number of finite factors, and contains a unique peak. The proposed algorithm is implemented on an application developed with JavaScript, HTML and CSS, which has been tested in the teaching of the Response Surface Methodology.

Keywords

Experimental design, educational tool, generating examples, problem-based learning, multifactorial model.

1. Introduction

Almost all the fields involving experimentation use experimental design [1]–[4]. It is part of various undergraduate and graduate curriculum, ranging from engineering to biological sciences. The objective of experimental design is to minimize cost and time of experiments and maximize its yield. As an example, it can be used to find the values of factors such as pH, oxygen concentration, sugar concentration, with which the enzyme production is maximized. Different techniques can be employed to find the minimum number of experiments [5] . On the other hand, an improper experimental design may lead to inaccurate or false conclusions, as well as a loss of money, material, and time [6].

Solving numerical examples helps students to learn statistics or mathematics [7] , or to develop insight into a particular topic [8] . Moreover, students obtain good learning experience using visual numerical examples of experiments [9] . On the other hand, solving optimization problems and finding the most accurate mathematical model for a process in experimental design involves performing various experiments with different combinations of factors. Usually, conducting experiments on a real system is not feasible due to any of the following limitations: 1) experiments on a real system can be costly, 2) a considerable amount of time may take each experiment, and 3) a great variety of experiments is difficult to be carried out. Hence, a computer program, that generates responses for some specific factors, is an excellent alternative to mimic physical systems, and to develop experimental design.

In this article, a computer-based educational tool for generating experimental design examples is proposed. It generates a unique process that takes into account factor limits selected by the user, and outputs experimental data for a given combinations of parameters. Teachers may adopt this educational tool in order to generate numerical examples, with which they highlight all the characteristics that want to present to students. Moreover, the proposed educational tool allows teachers to evaluate the knowledge acquired by students during a course, and to implement problem-based learning. In this pedagogy, a student learns the topic while solving a problem given by the teacher. The core of the educational tool is a novel mathematical function that finds the optimal solution of an experiment. In contrast to most of the optimization functions, that find a local maximum of the system response based on the initial base value, the proposed function is designed to provide a unique peak of an experiment subjected to a number of finite factors, thus providing the optimal solution of an experiment.

The paper has the following structure. Section 2 describes a multi-response model. The proposed mathematical function, employed by the computer-education tool, is presented in Section 3. The implementation of the proposed function is mentioned in Section 4. Section 5 describes the algorithm that generates an experiment of a multi-factorial process. Section 6 shows an application used to implement this algorithm. The paper ends with some concluding remarks.

1. Multi-response mathematical model

A numerical example for an experimental design is a multi-response mathematical model representing a physical process. This model is a set of static functions, i.e., it does not have derivative or integral terms, which maps the factors to the responses, and it is given by

|  |  |  |
| --- | --- | --- |
|  |  | (1) |

where ,  are responses, ,  are factors, ,  are nonlinear functions mapping the  factors to the  responses, and ,  are zero mean random noise. All factors, , are constrained by upper and lower limits. Numerical examples should produce unique optimal responses, , for a set of factors within its limits.

The algorithm developed in this paper uses a single response mathematical model, which is described by a proposed function presented in the next section. Several functions of this kind are used to mimic a multi-response system, since a set of  singe response systems can represent a multi-response system.

1. Proposed mathematical function

A static mathematical function with a single peak is achieved by any of the following functions.

|  |  |  |  |
| --- | --- | --- | --- |
|  |  | (2) | |
|  |  | (3) | |
|  | . | (4) |

Functions  and are a quadratic polynomial and a multivariable Gaussian function, respectively. Function is obtained by replacing the multiplication operator with a summation one. Figures 1, 2 and 3 respectively represent functions, , and  for a two variable case. These functions have the following limitations:

1. Function  has a property that its slope increases as it moves far away from the optimal point, thus the selection of a new base value is required.
2. Functions  and are concave functions, which have the property that the response of all the points between any two arbitrary points is always greater than the responses at these arbitrary points [14]. This property is not recommended because it also makes the selection of the next base value easy.
3. Response surface methodology uses a second order fit algorithm. Hence, reaching an optimal solution for a system based on  requires very less effort, which is not recommended as a practice problem.
4. The solution to , , and  does not contain the terms of other factors where . Multi factorial example problems based on these functions are easy to solve, because optimizing one factor after another factor will work in these cases.

Adding a nonlinear term to the  function gives the following proposed novel mathematical function:

|  |  |  |
| --- | --- | --- |
|  |  | (5) |

where ,, , and matrix  has full rank.

Figure 4 and 5 depict  with ,  and , , respectively. The gradient of  is given by

|  |  |  |
| --- | --- | --- |
|  |  | (6) |

where . Since  is positive definite, matrix  is also positive definite . Moreover, matrix $P^{T}P$ is positive semidefinite. Therefore, matrix $M$ in equation (6) is positive definite, and as a consequence, a unique peak at ,  is guaranteed.

The proposed mathematical function (5) has the following properties:

1. Its gradient is not proportional to the distance from its optimum combination.
2. It has a unique maximum value at , provided that  is a nonsingular matrix.
3. It is not a concave function.
4. The optimal value of an arbitrary factor is not constant throughout the factorial space.

In the next section, a method is presented to adapt the function, defined at (5), in order to generate random experiments.

1. Implementation of the proposed function

A scaled version of the proposed function  in (5) is given by

|  |  |  |
| --- | --- | --- |
|  |  | (7) |
|  | , | (8) |
|  | , | (9) |
|  | , | (10) |
|  | , | (7) |
|  | , | (8) |
|  | , | (13) |
|  | , | (14) |
|  | , | (15) |
|  |  | (16) |
|  |  | (17) |

with ,  ,  is a random variable such that  and , where  denotes expected value. Moreover,  is a random variable with the properties  and. On the other hand  is the function range,  is a noise factor,  is difficulty factor,  are the optimal combination of factors, where function  reaches its maximum value,  and  are lower and upper limits of the  factor,  and  are padding constants that, respectively, limit the maximum value of the function  and the optimal combination within the desired region.

It is worth mentioning that function, shown in (7), preserves all the mathematical properties of function. Moreover, multiplying function  in (9) by a negative number transforms the single-peak function to a single-dip (opposite to a peak) function; this transformation requires modifying (8) and (9) such that the upper and lower limits are preserved.

Next section presents an algorithm that implements the proposed procedure.

5. Algorithm

The objective of the algorithm is to generate experiment results by simulating a multi-factorial process. Teacher gives the parameters required by the multi-factorial process, and students perform experiments at different factors. The algorithm generates responses for the given  inputs using the equations and inequalities shown from (7) to (17). The student objective is to minimize the number of experiments conducted in order to achieve the optimum value of the process.

Figure 6 shows the flowchart of the proposed algorithm. The teacher should define the values of  and , where  and  should be less than 0.5. Based on our experience, It is recommended to use .  is the difficulty factor, the bigger the value is assigned, the harder it is to reach the optimum value. It is recommended to use a value of . The noise factor  introduces noise into the system. It is important to mention that this algorithm can be implemented in any programming language.

6. Application

The triad of JavaScript (JS), Hypertext markup language (HTML) and Cascading Style Sheets (CSS) is used to create the application presented at the web page [16]. JS is used to implement the algorithm discussed in the previous section.

This application is executed with , , , , , , , , , and , , . It calculates, , , , , and . The application does not give access to the optimum values. Figure 7 shows the surface plot of . Figure 8 and 9 show, respectively, the contour plot and surface plot of the function  without the noise term i.e., considering. The Response Surface Methodology is applied to find the optimal values of  and . Results of each iteration are also superimposed over the plots. The application contains a distance tool to provide how far the optimum value is from any set of the given factors. This tool also allows verifying if the factors have arrived to the optimum result.

Master students of the Biological Sciences Faculty, Universidad Autónoma de Coahuila, are instructed to use this application. Figure 10 shows the screenshot of the application. It is used in classroom, at homework, and in projects related to the learning of Response Surface Methodology. It motivates the interaction between professor and students, and allows teachers to implement the problem-based learning, or to assign a unique problem to each student. It also helps students to work in groups to discuss its functionality.

7. Conclusions

This article presented a computed educational tool, designed in HTML, CSS, and JavaScript, in order to generate random processes with factors provided by a teacher. It is based on a novel single response, unique peak multivariable mathematical function, denoted as. This function mimics a physical process designed for experiments, is adapted to generate experimental data for a selected range of factors, and can generate a multiple response system using several functions. It was shown that has the advantage over three mathematical functions, employed for optimization problems, that it has only one peak, i.e., the optimal value is a maximum value. Students that learn the topic of Response Surface Methodology use the proposed education tool. However, teachers may employ it to teach any other optimization techniques such as the Taguchi methods.

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