

# The classes P and NP

## Reading

Section 7.2

Practice problems (page 294):

## The class P

Computational problems are considered “tractable”, if their running time is polynomial. While a polynomial can grow with  $n$ , it does so in much more reasonable ways than an exponential.

The class  $P$  consists of all languages that are decidable in polynomial time by a deterministic single-tape Turing Machine.

A number of well-known problems belong to the class  $P$ , and looking back at algorithms you have learned in your other classes you can find more examples.

We will now consider several popular members of the class  $P$

## The Path problem

The path problem is represented by the language:

$$\text{PATH} = \{ \langle G, s, t \rangle \mid G \text{ is a directed graph and has a directed path from } s \text{ to } t \}$$

$$\text{PATH} \in P$$

One relevant question is how we represent the graph  $G$ . There are various ways, and they all involve space polynomial in the number of nodes  $n$ . Since the class  $P$  is effectively invariant under such transformations, we can consider  $n$  to be the “size” of our problem.

A “naive” approach to solving this problem would attempt to consider all possible “paths”, which are  $m^m$  if we denote by  $m$  the number of edges. This would not be polynomial ( $m$  is essentially  $O(n^2)$ ).

But of course there are more efficient ways, essentially involving marking of the vertices:

1. Start by marking the vertex  $s$ .

2. Repeat until nothing new is marked:

- Go through the edge list.
- If the source is marked and the target is not, mark the target.

3. See if  $t$  is marked.

Clearly the time-intensive portion is the second part. It will have to run once for each vertex (because each time it must mark a new vertex or we are done), and it takes time  $O(m)$  to run through the edge list. So its total running time is  $O(n^3)$ , polynomial.

## Relatively prime numbers

Another popular polynomial-time problem is the determination of whether two numbers are relatively prime or not. An important consideration here is the size of the input.

A number  $N$  is stored in base 2 using  $n = O(\log N)$  space, by simply using the base-2 representation of  $N$ .

Now consider the problem:

$$\text{RELPRIME} = \{ \langle x, y \rangle \mid x, y \text{ are relatively prime} \}$$

$$\text{RELPRIME} \in P$$

The size of the input is here  $O(\log N)$  where  $N$  is the largest of the two numbers. This is important to keep in mind. For instance a naive approach would be to go through each number  $d$  up to  $x, y$  and divide into them to see if it is a common factor. But this would take too long: There are in general  $O(N)$  such numbers, and  $N = 2^{O(n)}$  is exponential in the size of the input. Essentially, it would take too long.

Instead we will perform the well-known Euclidean division algorithm:

$E =$  On input  $\langle x, y \rangle$ :

A. Repeat until  $y = 0$ : 1. Compute  $x = x \bmod y$  2. Swap  $x$  and  $y$  B. The resulting  $x$  is the greatest common divisor of  $x, y$ . If it is 1 then we accept, otherwise we reject.

The key intuition here is that each repetition is effectively cutting the size of the inputs  $x, y$  by at least a half every second time through the loop. So the number of A steps needed is  $O(\log N)$ . Each of those steps is also polynomial in  $\log N$ , the length of the representations of  $x, y$ .

TODO: Work in progress