

Improving Boundary Condition Stability in PHASTA

1 INTRODUCTION

2 INITIAL OUTLINE OF PHASTA

PHASTA begins execution at `main`, located in `phSolver/[in]compressible`, depending on which branch is desired. This function initializes MPI, and then calls `phasta`, located in `/phSolver/common`. Here, inputs are read and computed in `input`, and then the solver is run by calling `proces`, a Fortran routine. Within `proces`, `gendat` generates geometry and BC data.

Routines followed by an asterisk (*) are outlined in further detail separately.

INCOMPRESSIBLE ONLY, and we ignore cardiovascular impedance and RCR boundary stuff.

■ `main`

- initialize MPI
- `phasta`
 - initialize PETSc
 - set input data paths
 - `input` — populate data structures with problem set-up and solver parameters
 - `readnblk` — read and blocks data
 - ▶ read `numstart.dat` and finds appropriate `restart.dat` files
 - ▶ read geometry from Posix or SyncIO files using `phio_readheader`
 - ▶ calculate maximum number of boundary element nodes
 - ▶ initialize constants like `ndof`, `ndofBC`, `ndiBCB`, and `ndBCB`
 - ▶ `genblk` — read and block connectivity
 - ▶ read BC mapping array into `nBC`
 - ▶ read temporary boundary condition code into `iBCtmp`
 - ▶ read BC data into `BCinp`
 - ▶ read periodic BC data into `iperread`
 - ▶ `genbkb` — generate boundary element blocks and traces for gather/scatter operations
 - ▶ read restart data into diffusive flux vector `qold`, primitive variables `uold`, and accelerations `acold`
 - echo global information
 - assert valid input constants (e.g. `icoord`, `navier`, `iexec`) defined in `common.h`
 - echo solver and integration information
 - `genint` — generate integration information
 - estimate number of nonzero globals
 - compute fluid thermodynamic properties
 - `proces` — generate problem data and calls the solution driver

- `gendat` — generate geometry and BC data
 - ▶ `getshp` — generate the interior nodal mapping
 - ▶ `geniBC` — generate boundary condition codes
 - ▶ `genBC` — generate the essential boundary conditions
 - ▶ work with Dirichlet-to-Neumann BCs (?)
 - ▶ `genshpb` — generate boundary element shape functions
 - ▶ `genini` — read initial values in primitive (\underline{U}) form, satisfies BCs, and converts to \underline{Y} form, filling the \underline{y} vector
- `setper` and `perprep` — store inverse of sum of one and number of slaves in `rcount`
- LES-specific routines `keeplhsG` and `setrls` called as needed
- `initStats` — allocate arrays to store flow statistics
- RANS-specific routine `initTurb`
- cardiovascular-specific routine `initSponge`
- adjust BCs to interpolate from file `inlet.dat`, if it exists
- set up eddy-viscosity ramp specific to NGC/Duct case
- `itrdrv*` — iterate the discrete solution using the predictor multi-corrector algorithm
- finalize PETSc
- finalize MPI

Numerical solution of the time-integrated unsteady Navier-Stokes equations occurs within `itrdrv`. Working arrays are listed in Table 2.

■ `itrdrv`

- `initTimeSeries` — initialize time series collection to `varts.*.dat` files using `xyzts.dat` input
- initialize `istep` and `ifuncs(:)` to zero, and set `yold = y` and `acold = ac`
- `initEQS` — initialize equation solver (look into this later *)
- `do itsq = 1, ntseq` — main loop over time sequences
 - set `itseq = itsq`
 - set iteration-specific variables for `nstep`, `niter`, `loctim`, and `deltol`
 - `itrsetup` — set up time integration parameters
 - calculate α_m , α_f , and γ as functions of ρ_∞
 - set global time increment inverse `Dtgl` and CFL data `CFLfl`
 - calculate number of flow solves per step, store in `nitr`
 - `do istp = 1, nstp` — main loop over time steps
 - `asbwmod` — set traction BCs if turbulence wall model is set (`itwmod`)
 - `itrPredict*` — predict primitive variables at time $n + 1$
 - `itrBC*` — satisfy BCs on the primitive variables; returns a modified \underline{y}
 - `itrBCSclr*` — satisfy BCs on the scalar `isclr`; returns a modified \underline{y}
 - `do istepc = 1, seqsize` — loop over individual solves of flow and scalar
 - ▶ `icode = stepseq(istepc)` — get sequence code
 - ▶ `if` this is a flow solve
 - ▷ `SolFlow*` — perform a flow solve
 - ▶ `else if` this is a scalar solve
 - ▷ `SolSclr` — perform a scalar solve

- ▶ `else` this is an update
 - ▷ `itrCorrect*` and `itrBC*` — update flow if desired
 - ▷ `itrCorrectSclr` and `itrBCSclr` — update scalar if desired
 - `stsGetStats` — obtain time averaged statistics
 - find solution at end of time step and move it to old solution variables
 - increment `istep` and `lstep`
 - `Bflux` — compute the consistent boundary flux if desired
- deallocate variables and close files
- deallocate variables and close files

Iteration routines...

■ `itrPredict` — predict solution variables at time $n + 1$

- `if (ipred .eq. 1)` — we are using same-velocity prediction, as discussed in class
 - set $\underline{Y}^{n+1(i)} = \underline{Y}^n$
 - set $\underline{Y}_{,t}^{n+1(i)} = (1 - 1/\gamma)\underline{Y}_{,t}^n$
- other prediction methods (zero-acceleration, same-acceleration, and same-delta) are also supported with different values of `ipred`

Boundary conditions are set with the `iBC` and `BC` arrays. The bits of `iBC`, in increasing order, indicate whether the following BCs are set: ρ , T , p , u_1 , u_2 , u_3 , scalars 1–4, periodicity, scaled plane extraction (SPEBC), axisymmetry, and deformable wall (for cardiovascular cases). This means for each global node, `iBC` has at least 14 bits. Note that `ibits(i,a,l)` extracts bits `a+1` through `a+l` of the integer `i`, and returns the base-10 integer. This routine is used to help identify and process boundary condition flags held in `iBC`.

■ `itrBC` — satisfy BCs on the primitive variables

- impose limits on \underline{Y} , using the `ylimit` data structure of dimension `(3, nflow)`, whose first index contains limit flag, lower limit, and upper limit for each flow variable.
- velocity BCs
 -
- pressure BCs
 -
- local periodic BCs
- global periodic BCs

Symbol	Dimension	Description
<code>nshg</code>		# global shape functions (<code>ngsh = nnp</code> if piecewise linear)
<code>nnp</code>		# global nodal points
<code>npro</code>		# elements, indexed by e
<code>nshl</code>		# nodes per element, indexed by a
<code>ndof</code>		# degrees of freedom, including scalars for turbulence models
<code>nflow</code>		# flow variables (4 incompressible, 5 compressible)
<code>ntseq</code>		# time sequences (?)
<code>nstep</code>		# time steps requested for current run
<code>lstep</code>		current time step
<code>lstep0</code>		first time step solved by current run, initialized to <code>lstep+1</code>
<code>istep</code>		step number relative to start of run
<code>iter</code>		iteration number
<code>niter</code>	(MAXTS)	# multi-corrector iterations per time step
<code>loctim</code>	(MAXTS)	local time stepping flag (?)
<code>deltol</code>	(MAXTS, 2)	velocity and pressure delta ratios
<code>impl</code>	(MAXTS)	heat, flow, and scalar solver flags (1's, 10's and 100's places)
<code>iturb</code>		indicates which turbulence model to use
<code>ifunc</code>		function evaluation counter, <code>niter*(lstep-lstep0)+iter</code>
<code>ifuncs</code>	(6)	function evaluation counter (?)
<code>y</code>	(<code>nshg</code> , <code>ndof</code>)	\underline{Y} variables
<code>x</code>	(<code>nshg</code> , <code>nsd</code>)	node coordinates
<code>iBC</code>	(<code>nshg</code>)	BC codes
<code>BC</code>	(<code>nshg</code> , <code>ndofBC</code>)	BC constraint parameters
<code>shp</code>	(<code>nshape</code> , <code>ngauss</code>)	element shape functions at Gauss points (interior)
<code>shb</code>	(<code>nshapeb</code> , <code>ngaussb</code>)	element shape functions at Gauss points (boundary)
<code>shgl</code>	(<code>nsd</code> , <code>nshape</code> , <code>ngauss</code>)	local shape function gradients at Gauss points (interior)
<code>shglb</code>	(<code>nsd</code> , <code>nshapeb</code> , <code>ngaussb</code>)	local shape function gradients at Gauss points (boundary)
<code>iper</code>	(<code>nshg</code>)	periodicity table

3 LIFE'S PERSISTENT PHASTA QUESTIONS

- Is `gold`, allocated in `readnblk.f` ever deallocated? Can't find it.
- Why do most of the time step parameters have dimension `MAXTS`?
 - It also seems that some parameters are indexed by `itseq`, but don't change from step to step.
- When is it the case that `ndof` \neq `nflow`? For example during its limit-imposing stage, `itrbc` loops over `nflow` when indexing `y`'s dimension of size `ndof`.