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HONOURS THESIS

Quantised Calculus in One Dimension

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Declaration of Authorship

I, Edward McDONALD, declare that this thesis titled, 'Quantised Calculus in One Dimension' and the work presented in it are my own. I confirm that:

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- Where any part of this thesis has previously been submitted for a degree or any other qualification at this University or any other institution, this has been clearly stated.
- Where I have consulted the published work of others, this is always clearly attributed.
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“Some Literary Quote ”

A person

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Abstract

Faculty of Science
School of Mathematics and Statistics

Honours

Quantised Calculus in One Dimension

by Edward McDONALD

In his 1994 book *Noncommutative geometry* Alain Connes introduced the quantised calculus. This is a means of doing calculus which makes sense in a high degree of generality, and has many properties analogous to the classical notion of “infinitesimal calculus”. This thesis is an in-depth study of quantised calculus in two cases: on the real line and on the circle.

Acknowledgements

Acknowledgements go here.

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Chapter 1

Introduction

1.1 Classical Infinitesimals

According to the mathematicians of the 17th century, an “infinitesimal” is a quantity x that is smaller than any positive magnitude. In other words, for all $\varepsilon > 0$,

$$|x| < \varepsilon. \tag{1.1}$$

Mathematicians manipulated infinitesimals as though they were real numbers: addition, multiplication and division of infinitesimals were permitted.

Numerous definitions relied on the use of infinitesimals. For example, a function $f : \mathbb{R} \rightarrow \mathbb{R}$ was said to be continuous at x if $f(x+h) - f(x)$ is infinitesimal for all infinitesimals h .

Another example is that f was said to be differentiable when the quantity

$$\frac{df}{dx} := \frac{f(x+h) - f(x)}{h} \tag{1.2}$$

exists for all infinitesimals h , and does not depend on h .

Mathematicians distinguished between infinitesimals of different “sizes”, and if x is infinitesimal, then x^2 was said to be smaller than x , and algebraic manipulations could be performed with “sufficiently small infinitesimals ignored”.

However, as we are now aware, the condition in equation 1.1 implies that $x = 0$, so all manipulations involving infinitesimals are either trivial or impossible. Hence, the use of infinitesimals was banned from mathematics and their role in analysis was replaced with the concept of a *limit*.

Despite the difficulties with giving a non-contradictory definition of infinitesimals, there are numerous reasons that the concept is appealing. Using infinitesimals makes some

definitions in analysis seem simpler, for example the above given definition of continuity. Infinitesimals can also be more intuitive than limits. For these reasons, some mathematicians have attempted to revive the concept of infinitesimals by defining them in a rigorous manner. Most famously, one can use model theory to define and analyse a field of *hyperreal numbers* which strictly contains the real numbers, and includes a plentiful supply of infinitesimals. This is called non-standard analysis, see [1] for details. Other approaches to rigorously defining infinitesimals include smooth infinitesimal analysis, which is simply the observation that infinitesimals in the classical sense are not self-contradictory objects if certain axioms of logic are ignored, see [2] for an introduction to this approach. A third approach is the Levi-Civita field [3].

A comprehensive history of the use of infinitesimals prior to the 19th century is [4].

1.2 Compact Operators as Infinitesimals

A relatively new approach to rigorously defining infinitesimals comes from non-commutative geometry. In this setting, all objects of interest such as functions, vector fields, differential forms, etc., are thought of as operators on a Hilbert space.

In what follows, let \mathcal{H} be a complex separable Hilbert space.

Suppose we wish to find a good definition of an “infinitesimal operator” on \mathcal{H} . A preliminary definition would be to say that an operator T is infinitesimal if for every $\varepsilon > 0$,

$$\|T\| < \varepsilon. \quad (1.3)$$

This definition is useless, as it implies that $T = 0$. However, we can get something close

Definition 1.1. Let $T \in \mathcal{B}(\mathcal{H})$. We say that T is *infinitesimal* if for every $\varepsilon > 0$, there is a finite dimensional subspace E such that

$$\|T|_{E^\perp}\| < \varepsilon. \quad (1.4)$$

(here $T|_{E^\perp}$ denotes the restriction of T to the orthogonal complement of E .)

Remark 1.2. Recall that the ideal of compact operators $\mathcal{K}(\mathcal{H}) \subseteq \mathcal{B}(\mathcal{H})$ is the closure of the set of finite rank operators. It is easy to see that T is infinitesimal (in the sense of definition 1.1) if and only if T is compact.

We require a way of measuring the “size” of an infinitesimal. According to definition 1.1, an infinitesimal is “zero modulo finite dimensional subspaces”, and it is sensible to consider the “size” of the infinitesimal as being measured by the speed at which the dimension of the subspaces E must increase as ε moves towards zero. To this end, we define the singular values.

Definition 1.3. Let $T \in \mathcal{B}(\mathcal{H})$, and $n \geq 0$. Define

$$\mu_n(T) := \inf\{\|T - F\| : \text{rank}(F) \leq n\}. \quad (1.5)$$

Then $\mu_n(T)$ is called the n th singular value of T , and the sequence $\{\mu_n(T)\}_{n=0}^\infty$ is called the sequence of singular values.

Remark 1.4. For any operator T , the sequence $\{\mu_n(T)\}_{n=0}^\infty$ is strictly non-increasing. If T is compact, the sequence of singular values of T is decreasing and approaches 0.

We shall regard the *size* of T as being given by the *rate of decay* of $\{\mu_n(T)\}_{n=0}^\infty$.

1.3 Expected Properties of infinitesimals

According to 17th century mathematicians, infinitesimals were supposed to have a number of remarkable properties:

1. There exist non-zero infinitesimals.
2. Infinitesimals can be added, subtracted, multiplied and divided just like real numbers.
3. A real number multiplied by an infinitesimal produces an infinitesimal.
4. Infinitesimals can be split into “sizes”, and we can work modulo a particular size of infinitesimal.
5. If x is an infinitesimal, then x^2 is a smaller infinitesimal.
6. Given a function $f : \mathbb{R} \rightarrow \mathbb{R}$, there is a function df representing the infinitesimal variation in f , that is $df(x) = f(x + \delta) - f(x)$ for some fixed infinitesimal δ .
7. If a function f is smoother than a function g , then df is smaller than dg .
8. If f is a smooth function of x , we can write

$$df = f'(x)dx \quad (1.6)$$

provided that sufficiently small infinitesimals are ignored.

If we interpret compact operators as infinitesimals, we see that analogues of these statements remain true:

1. There indeed exist non-zero compact operators.

2. Compact operators can be added and subtracted like numbers, they can also be multiplied (although multiplication is not commutative). We cannot divide by a compact operator on an infinite dimensional Hilbert space. However it is true that if $XT = YT$ for operators $X, Y \in \mathcal{B}(\mathcal{H})$ for all $T \in \mathcal{K}(\mathcal{H})$, then $X = Y$.
3. $\mathcal{K}(\mathcal{H})$ forms an ideal of $\mathcal{B}(\mathcal{H})$, so a bounded operator multiplied by a compact operator produces a compact operator.
4. We can measure the size of a compact operator by the rate of decay of its sequence of singular values.

For item 5, we need the following lemma,

Lemma 1.5. *Let $T \in \mathcal{K}(\mathcal{H})$. Then for $n \geq 0$,*

$$\mu_n(T^2) \leq \|T\| \mu_n(T). \quad (1.7)$$

Proof. By definition,

$$\mu_n(T^2) = \inf\{\|T^2 - F\| : \text{rank}(F) \leq n\}. \quad (1.8)$$

Since if F has rank n , TF has rank not exceeding n , we have

$$\mu_n(T^2) \leq \inf\{\|T^2 - TF\| : \text{rank}(F) \leq n\} \quad (1.9)$$

$$\leq \inf\{\|T\| \|T - F\| : \text{rank}(F) \leq n\} \quad (1.10)$$

$$= \|T\| \mu_n(T). \quad (1.11)$$

□

Hence we have property 5: if T is infinitesimal, then the singular values of T^2 decay more rapidly than those of T .

Now for properties 6, 7 and 8, we need a way of defining df . This is precisely the role played by the quantised differential.

1.4 Quantised Differentials

The following definition may at first glance seem strange and unmotivated,

Definition 1.6. Consider the operator $\mathcal{D} = \frac{1}{i} \frac{d}{dx}$ of differentiation on \mathbb{R} (or $\mathcal{D} = \frac{1}{2\pi i} \frac{d}{d\theta}$ on \mathbb{T}). By the Borel functional calculus, we can define $F := \text{sgn}(\mathcal{D})$. F is called the Hilbert transform. For a function $f \in L^1(\mathbb{R})$ (resp. $f \in L^1(\mathbb{T})$) we have the pointwise

multiplication operator M_f considered as an operator on $L^2(\mathbb{R})$ (resp. $L^2(\mathbb{T})$), M_f may be a densely defined unbounded operator when $f \notin L^\infty(\mathbb{R})$ (resp. $f \notin L^\infty(\mathbb{T})$).

The operator

$$\bar{d}f := [F, M_f] \quad (1.12)$$

is an operator on $L^2(\mathbb{R})$ (resp. $L^2(\mathbb{T})$) called the *quantised differential* of f .

$\bar{d}f$ is supposed to play the role of df in 17th century analysis. We use the symbol $\bar{d}f$ instead of df since in modern mathematics the symbol df is very often used to denote the exterior differential of f . It must be emphasised that the exterior differential df and the quantised differential $\bar{d}f$ are very different objects.

Similar to the case of functions $f : \mathbb{R} \rightarrow \mathbb{C}$, we can also study functions on the circle. Let

$$\mathbb{T} := \{z \in \mathbb{C} : |z| = 1\}. \quad (1.13)$$

Then we have a differentiation operator

$$\mathcal{D} := \frac{1}{2\pi i} \frac{d}{d\theta}, \quad (1.14)$$

and $F := \text{sgn}(\mathcal{D})$. Then we can define quantised differentials $\bar{d}f := [F, M_f]$.

Remark 1.7. We have chosen to call the quantity $[F, M_f]$ a quantised differential, and to denote it $\bar{d}f$.

This terminology is not universal. In particular, the book [5] calls $[F, M_f]$ a quantised derivative and denotes it df .

We shall use the notation $\bar{d}f$ to prevent confusion with the exterior derivative df , and we call it a differential to be consistent with the idea of an “infinitesimal increment”.

It is not easy to motivate the definition $\bar{d}f := [F, M_f]$. Instead, we shall show that $\bar{d}f$ satisfies all the properties anticipated for a differential.

The two questions that we shall attempt to answer are as follows:

1. In what sense is it true that if f is smoother than g , then $\bar{d}f$ is smaller than $\bar{d}g$?
This will be answered in Chapter ??
2. In what sense is it true that if φ is a function that is smooth on the range of a function f , then $\bar{d}\varphi(f) = \varphi'(f)\bar{d}f$? This will be answered in Chapter ??.

In order to answer those questions, it is informative to give an explanation of the origin of the definition of $\bar{d}f$.

1.5 Non-commutative geometry

1.5.1 Introduction to the non-commutative world

Non-commutative geometry is a relatively new topic in mathematics. Non-commutative geometry is best thought of not as a collection of results, but instead as a perspective on mathematics.

It is difficult to give a completely satisfying general definition of non-commutative geometry, but one can say that non-commutative geometry is the study of non-commutative algebras which are somehow similar to algebras of functions on geometric spaces, using the methods and language of geometry.

The key idea which underlies most of non-commutative geometry is the duality between geometric spaces and algebras.

Example 1.1. *Let X be a compact Hausdorff space. Let $C(X)$ be the algebra of continuous complex valued functions on X . $C(X)$ naturally carries the structure of a commutative unital C^* -algebra. In fact, for any commutative unital C^* -algebra \mathcal{A} , there is a compact Hausdorff space K such that \mathcal{A} is isometrically $*$ -isomorphic to $C(K)$.*

Given a continuous function $f : X \rightarrow Y$ between compact Hausdorff spaces X and Y , there is a pull-back function $f_ : C(Y) \rightarrow C(X)$ defined by $f_*(h) = h \circ f$ for $h \in C(Y)$. Since $\text{id}_X = \text{id}_{C(X)}$, and $(f \circ g)_* = g_* \circ f_*$, the mapping $X \mapsto C(X)$ is a functor.*

*Let **CHTop** be the category of compact Hausdorff spaces with morphisms as continuous functions, and let **CUC*Alg** be the category of commutative unital C^* -algebras with morphisms as continuous $*$ -algebra homomorphisms.*

Thus we have a contravariant functor,

$$C : \mathbf{CHTop} \rightarrow \mathbf{CUC^*Alg}. \quad (1.15)$$

This effects an equivalence of categories,

$$\mathbf{CUC^*Alg} \cong \mathbf{CHTop}^{Op}. \quad (1.16)$$

*Let **UC*Alg** be the category of unital C^* -algebras, which are not necessarily commutative. Inspired by the duality between commutative unital C^* -algebras and compact Hausdorff spaces, we define the category of (potentially) non-commutative compact Hausdorff spaces to be **UC*Alg**^{Op}.*

1.5.2 A brief introduction to Quantum Mechanics

Non-commutative geometry can be thought of simply as the study of non-commutative algebras using geometric language. However, much research in non-commutative geometry is inspired by quantum mechanics. It is therefore instructive to give a brief description of quantum mechanics.

Definition 1.8. A *quantum mechanical system* is a pair $(\mathcal{A}, \mathcal{H})$ where \mathcal{H} is a complex separable Hilbert space and \mathcal{A} is a $*$ -algebra of (possibly densely defined and unbounded) operators on \mathcal{H} . Denote the inner product on \mathcal{H} by (\cdot, \cdot) and $\|\psi\|^2 := (\psi, \psi)$.

A self-adjoint element of \mathcal{A} is called an *observable*. The elements of \mathcal{H} are called *states*.

Typically, we identify together elements of \mathcal{H} which differ by a nonzero scale factor, and the element $0 \in \mathcal{H}$ is ignored entirely. So technically we work over the *projective Hilbert space* $\mathbb{P}\mathcal{H}$.

To specify *the state of the system* $(\mathcal{A}, \mathcal{H})$ is the same as specifying some $\psi \in \mathcal{H}$.

We think of $(\mathcal{A}, \mathcal{H})$ as encoding a physical system. Typically we think of an observable as a measurable property of a system. The states correspond to potential configurations of the system.

Given an observable A , the potential range of values that can be measured for the corresponding physical quantity is the spectrum $\sigma(A)$. Unlike in classical mechanics, quantum mechanics can only make predictions that are probabilistic. The second difference to classical mechanics is that the act of observation changes the state of the system.

The link between $\sigma(A)$ and A is provided by the spectral theorem, [CITE]

Theorem 1.9 (The Spectral Theorem). *Let $(\mathcal{A}, \mathcal{H})$ be a quantum mechanical system. Let $A \in \mathcal{A}$ be an observable. Then there is a projection valued measure E_A on $\sigma(A)$ such that*

$$A = \int_{\sigma(A)} \lambda dE_A(\lambda).$$

Using the spectral theorem, we may state our first postulate.

Postulate 1.10. *Let $(\mathcal{A}, \mathcal{H})$ be a quantum mechanical system, in a state ψ .*

Let $A \in \mathcal{A}$ be an observable, with associated spectral measure E_A .

For some Borel set $\Delta \subseteq \sigma(A)$, the probability that the observed value of A lies in Δ is given by

$$P_A(\Delta; \psi) := \frac{(\psi, E_A(\Delta)\psi)}{\|\psi\|^2} = \frac{\|E_A(\Delta)\psi\|^2}{\|\psi\|^2}.$$

(Note that this is the same for any scalar multiple of ψ , and is undefined for $\psi = 0$.)

Suppose that A is now observed, and the value is known to lie in the set $\Delta \subseteq \sigma(A)$. Then the state of the system changes to

$$\frac{E_A(\Delta)\psi}{\|E_A(\Delta)\psi\|}.$$

Remark 1.11. There are two extraordinary features of this postulate.

1. The state of the system changes upon observation.
2. The order of observation is important, since for any observables A and B , and $\Sigma \times \Delta \subseteq \sigma(A) \times \sigma(B)$, in general,

$$\frac{E_A(\Sigma)E_B(\Delta)\psi}{\|E_A(\Sigma)E_B(\Delta)\psi\|} \neq \frac{E_B(\Delta)E_A(\Sigma)\psi}{\|E_B(\Delta)E_A(\Sigma)\psi\|}.$$

Remark 1.12. This discussion of quantum mechanics is far from comprehensive. The treatment here is based on ??, and the text ?? goes into further detail on this topic.

1.5.3 Non-commutative spaces

Inspired by quantum mechanics, quantum mechanics can be thought of as the study of spaces with coordinates such that the order of observation of coordinates is important.

Accordingly, a general non-commutative space can be defined as a pair $(\mathcal{A}, \mathcal{H})$, just as a quantum mechanical system. The elements of \mathcal{A} are “coordinate functions”, and their action on the elements of \mathcal{H} quantifies how the “geometry” changes under observation.

Chapter 2

Quantised Differentials on \mathbb{R} and \mathbb{T}

2.1 The Quantised Differential on \mathbb{T}

We shall introduce a Fourier analytic description of the quantised differential of a function on the circle. Let $\mathbb{T} = \{\zeta \in \mathbb{C} : |\zeta| = 1\}$ be the unit circle in the complex plane, which is a compact group equipped with a normalised Haar measure, which we denote \mathbf{m} .

When we write function spaces $L^p(\mathbb{T})$, we shall implicitly mean $L^p(\mathbb{T}, \mathbf{m})$.

We write $z : \mathbb{T} \rightarrow \mathbb{T}$ for the identity function, $z = \text{id}_{\mathbb{T}}$.

For $f \in L^1(\mathbb{T})$ and $n \in \mathbb{Z}$, we write the n th Fourier coefficient as,

$$\hat{f}(n) = \int_{\mathbb{T}} z^{-n} f \, d\mathbf{m}. \quad (2.1)$$

A review of elementary Fourier analysis and notation is given in [Appendix A](#).

Recall that we have the operator \mathcal{D} that acts on functions on \mathbb{T} , defined by $\mathcal{D}(z^n) = nz^n$.

We also have $F := \text{sgn}(\mathcal{D})$, which acts by $F(z^n) = \text{sgn}(n)z^n$.

By definition, $H^2(\mathbb{T}) := \mathbf{P}_+ L^2(\mathbb{T})$.

The important operator \mathbf{P}_+ is given by $\mathbf{P}_+(z^n) := \max \text{sgn}(n), 0 z^n$.

Proposition 2.1. *For $\varphi \in L^1(\mathbb{T})$, the quantised differential of φ is the (potentially unbounded, densely defined) linear operator*

$$\bar{d}\varphi := 2[\mathbf{P}_+, M_\varphi]. \quad (2.2)$$

Proof. This is a consequence of the observation that $F = 2\mathbf{P}_+ - \mathbf{1}$, where $\mathbf{1}$ is the identity operator. \square

In this chapter, we will discuss alternative descriptions of $\bar{d}\varphi$.

Since $H^2(\mathbb{T})$ is a closed subspace of $L^2(\mathbb{T})$, being the image of $L^2(\mathbb{T})$ under a bounded projection, it has an orthogonal complement which we denote $H_-^2(\mathbb{T})$.

Hence, we may consider the quantised derivative $\bar{d}\varphi$ as an operator on the Hilbert space $H^2(\mathbb{T}) \oplus H_-^2(\mathbb{T})$.

Lemma 2.2. *Let $\varphi \in L^2(\mathbb{T})$ and define $\varphi_+ := \mathbf{P}_+\varphi$ and $\varphi_- := \mathbf{P}_-\varphi$. Then $\bar{d}\varphi : H^2(\mathbb{T}) \oplus H_-^2(\mathbb{T}) \rightarrow H^2(\mathbb{T}) \oplus H_-^2(\mathbb{T})$ may be written as*

$$\bar{d}\varphi(f \oplus g) = 2(\mathbf{P}_+M_{\varphi_+})g \oplus -2(\mathbf{P}_-M_{\varphi_-})f \quad (2.3)$$

for $f \in H^2(\mathbb{T})$ and $g \in H_-^2(\mathbb{T})$.

Proof. This is a simple computation. Let $f \in H^2(\mathbb{T})$ and $g \in H_-^2(\mathbb{T})$. Then,

$$\bar{d}\varphi(f + g) = 2[\mathbf{P}_+, M_{\varphi_+} + M_{\varphi_-}](f + g). \quad (2.4)$$

Hence,

$$\begin{aligned} \bar{d}\varphi(f + g) &= 2[\mathbf{P}_+, M_{\varphi_+}]f + 2[\mathbf{P}_+, M_{\varphi_-}]f + 2[\mathbf{P}_+, M_{\varphi_+}]g + 2[\mathbf{P}_+, M_{\varphi_-}]g \\ &= 2(\mathbf{P}_+M_{\varphi_-})f + 2(\mathbf{P}_+M_{\varphi_+})g - 2M_{\varphi_-}f \end{aligned}$$

since $\mathbf{P}_+f = f$ and $\mathbf{P}_+g = 0$.

By the identity $\mathbf{P}_+ = \mathbf{1} - \mathbf{P}_-$, we find

$$\bar{d}\varphi(f + g) = 2(\mathbf{P}_+M_{\varphi_+})g - 2(\mathbf{P}_-M_{\varphi_-})f. \quad (2.5)$$

\square

The problem of determining the boundedness of $\bar{d}\varphi$ is then reduced to the problem of determining the boundedness of operators of the form $\mathbf{P}_+M_\psi : H_-^2(\mathbb{T}) \rightarrow H^2(\mathbb{T})$ and $\mathbf{P}_-M_\psi : H^2(\mathbb{T}) \rightarrow H_-^2(\mathbb{T})$ for $\psi \in L^2(\mathbb{T})$. We may simplify this further with the following lemma:

Lemma 2.3. *Let $\psi \in L^2(\mathbb{T})$. Then*

$$(\mathbf{P}_+M_\psi)^* = \mathbf{P}_-M_{\bar{\psi}}. \quad (2.6)$$

and therefore \mathbf{P}_+M_ψ is bounded if and only if $\mathbf{P}_-M_{\bar{\psi}}$ is.

Proof. Let $e_k(z) = z^k$.

This is again a simple computation. Let $m, n \in \mathbb{Z}$ with $m \geq 0$ and $n < 0$. Then,

$$\begin{aligned} \langle (\mathbf{P}_+ M_\psi) e_n, e_m \rangle &= \int_{\mathbb{T}} \sum_{k > -n} \hat{\psi}(k) \zeta^{k+n-m} d\mathbf{m}(\zeta) \\ &= \hat{\psi}(m-n). \end{aligned}$$

Similarly,

$$\begin{aligned} \langle e_n, (\mathbf{P}_- M_{\bar{\psi}}) e_m \rangle &= \int_{\mathbb{T}} \sum_{k > m} \hat{\varphi}(k) \zeta^{n-m+k} d\mathbf{m}(\zeta) \\ &= \hat{\psi}(m-n). \end{aligned}$$

Hence, $(\mathbf{P}_+ M_\psi)^* = \mathbf{P}_- M_{\bar{\psi}}$.

□

For $\psi \in L^2(\mathbb{T})$, define

$$H_\psi := \mathbf{P}_- M_\psi : H^2 \rightarrow H_-^2. \quad (2.7)$$

In other words, we may write $d\varphi : H^2(\mathbb{T}) \oplus H_-^2(\mathbb{T}) \rightarrow H^2(\mathbb{T}) \oplus H_-^2(\mathbb{T})$ as a matrix,

$$d\varphi = 2 \begin{pmatrix} 0 & -H_{\varphi+}^* \\ H_{\varphi-} & 0 \end{pmatrix} \quad (2.8)$$

Therefore, we only need to study operators of the form H_ψ .

We study these operators using the Fourier transform. Use the standard basis $\{z^n\}_{n \geq 0}$ on $H^2(\mathbb{T})$ and the standard basis with negative indices $\{z^{-n}\}_{n \geq 0}$ on $H_-^2(\mathbb{T})$.

Let $\psi \in L^2(\mathbb{T})$. Then in the bases above, H_ψ has matrix representation with (n, k) th entry $\hat{\psi}(-n-k)$.

This means that H_ψ is represented by a *Hankel matrix*. So we require results on Hankel matrices. This is covered in Chapter 3.

2.2 Integral representation of the quantised differential on \mathbb{T}

In the preceding section we have realised the quantised differential as a Hankel operator. Now we present an alternative description of the quantised differential as an integral operator. The representation as an integral operator is well known and was extensively used by A. Connes in [5].

Lemma 2.4.

$$\text{p.v.} \int_{\mathbb{T}} \frac{1}{\tau - 1} d\mathbf{m}(\tau) = -\frac{1}{2} \quad (2.9)$$

where the principal value is defined to be

$$\lim_{\varepsilon \rightarrow 0} \int_{|\tau-1|>\varepsilon} \frac{1}{\tau - 1} d\mathbf{m}(\tau). \quad (2.10)$$

Proof. Note that

$$\text{p.v.} \int_{\mathbb{T}} \frac{1}{\tau - 1} d\mathbf{m}(\tau) = \text{p.v.} \int_{\text{Im}(\tau)>0} \frac{1}{\bar{\tau} - 1} + \frac{1}{\tau - 1} d\mathbf{m}(\tau). \quad (2.11)$$

Now split up the integral into upper and lower semicircular parts,

$$\text{p.v.} \int_{\mathbb{T}} \frac{1}{\tau - 1} d\mathbf{m}(\tau) = \text{p.v.} \int_{\text{Im}(\tau)>0} 2 \text{Re} \left(\frac{1}{\tau - 1} \right) d\mathbf{m}(\tau). \quad (2.12)$$

However, if $\tau = \exp(i\theta) \neq 1$, then

$$\begin{aligned} \text{Re} \left(\frac{1}{\tau - 1} \right) &= \text{Re} \left(\frac{e^{-i\theta/2}}{2i \sin(\theta/2)} \right) \\ &= -\frac{1}{2}. \end{aligned}$$

Hence,

$$\text{p.v.} \int_{\mathbb{T}} \frac{1}{\tau - 1} d\mathbf{m}(\tau) = 2 \text{p.v.} \int_{\text{Im}(\tau)>0} -\frac{1}{2} d\mathbf{m}(\tau) = -\frac{1}{2}. \quad (2.13)$$

□

Theorem 2.5. Let $\varphi \in L^2(\mathbb{T})$. Then

$$\mathbf{P}_+ \varphi(\zeta) = \text{p.v.} \int_{\mathbb{T}} \frac{\varphi(\tau)}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau) + \frac{1}{2} \varphi(\zeta) \quad (2.14)$$

and hence,

$$F\varphi(\zeta) = 2 \text{p.v.} \int_{\mathbb{T}} \frac{\varphi(\tau)}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau). \quad (2.15)$$

where in both equations, the principal value means that the integral is to be taken along the set $\{\tau \in \mathbb{T} : |\tau - \zeta| > \varepsilon\}$ and then consider the limit $\varepsilon \rightarrow 0$.

Proof. First we check this for $\varphi = \zeta^n$ for $n \in \mathbb{Z}$.

First let $n \geq 0$. Then

$$\text{p.v.} \int_{\mathbb{T}} \frac{\tau^n}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau) = \text{p.v.} \int_{\mathbb{T}} \frac{z^n \tau^n}{1 - \bar{\tau}} d\mathbf{m}(\tau) \quad (2.16)$$

by translation invariance. Hence,

$$\begin{aligned}
\text{p.v.} \int_{\mathbb{T}} \frac{\tau^n}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau) &= \zeta^n \text{p.v.} \int_{\mathbb{T}} \frac{\tau^{n+1}}{\tau - 1} d\mathbf{m}(\tau) \\
&= \zeta^n \text{p.v.} \int_{\mathbb{T}} \frac{\tau^{n+1} - 1}{\tau - 1} + \frac{1}{\tau - 1} d\mathbf{m}(\tau) \\
&= \zeta^n \text{p.v.} \int_{\mathbb{T}} 1 + \tau + \tau^2 + \cdots + \tau^n d\mathbf{m}(\tau) + \zeta^n \text{p.v.} \int_{\mathbb{T}} \frac{1}{\tau - 1} d\mathbf{m}(\tau) \\
&= \zeta^n + \zeta^n \text{p.v.} \int_{\mathbb{T}} \frac{1}{\tau - 1} d\mathbf{m}(\tau) \\
&= \frac{1}{2} \zeta^n
\end{aligned}$$

where the last step follows from lemma 2.4.

Suppose $n > 0$, then

$$\text{p.v.} \int_{\mathbb{T}} \frac{\tau^{-n}}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau) = \zeta^{-n} \text{p.v.} \int_{\mathbb{T}} \frac{\tau^{1-n}}{\tau - 1} d\mathbf{m}(\tau) \quad (2.17)$$

by translation invariance. Hence,

$$\begin{aligned}
\text{p.v.} \int_{\mathbb{T}} \frac{\tau^{-n}}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau) &= z\zeta^{-n} \text{p.v.} \int_{\mathbb{T}} \frac{1}{\tau^n - \tau^{n-1}} d\mathbf{m}(\tau) \\
&= \zeta^{-n} \text{p.v.} \int_{\mathbb{T}} \frac{\tau^n}{1 - \tau} \\
&= -\frac{1}{2} \zeta^{-n}.
\end{aligned}$$

Hence,

$$\text{p.v.} \int_{\mathbb{T}} \frac{\tau^n}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau) = \begin{cases} \frac{1}{2} \zeta^n & \text{if } n \geq 0 \\ -\frac{1}{2} \zeta^n & \text{if } n < 0. \end{cases} \quad (2.18)$$

Hence we have

$$F\varphi(\zeta) = 2 \text{p.v.} \int_{\mathbb{T}} \frac{\varphi(\tau)}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau). \quad (2.19)$$

for $\varphi = z^n$. To extend this to arbitrary $\varphi \in L^2(\mathbb{T})$, we see that $\varphi = \sum_{n \in \mathbb{Z}} \hat{\varphi}(n) z^n$, which converges in the L^2 sense. Since $\sum_{n \in \mathbb{Z}} \hat{\varphi}(n) z^n$ converges in the L^2 sense, it converges in the L^1 sense.

Now fix $\varepsilon > 0$. By the dominated convergence theorem, we have

$$\int_{|\tau - \zeta| > \varepsilon} \frac{\varphi(\tau)}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau) = \sum_{n \in \mathbb{Z}} \hat{\varphi}(n) \int_{|\tau - \zeta| > \varepsilon} \frac{\tau^n}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau). \quad (2.20)$$

Now we take the limit $\varepsilon \rightarrow 0$. Again by the dominated convergence theorem for sums, the result follows.

□

So we have the following integral form of the quantised derivative. Let $\varphi, f \in L^2(\mathbb{T})$. Then

$$\bar{d}\varphi(f)(\zeta) = ([F, M_\varphi]f)(\zeta) \quad (2.21)$$

$$= F(\varphi f) - \varphi(F(f)) \quad (2.22)$$

$$= \text{p.v.} \int_{\mathbb{T}} \frac{\varphi(\tau)f(\tau)}{1 - \bar{\tau}\zeta} - \frac{\varphi(\zeta)f(\tau)}{1 - \bar{\tau}\zeta} d\mathbf{m}(\tau) \quad (2.23)$$

$$= \text{p.v.} \int_{\mathbb{T}} \frac{\varphi(\tau) - \varphi(\zeta)}{1 - \bar{\tau}\zeta} f(\tau) d\mathbf{m}(\tau). \quad (2.24)$$

for almost all $\zeta \in \mathbb{T}$.

2.3 The Cayley Transform

2.3.1 Notation

$\mathbb{H} = \{z \in \mathbb{C} : \Im(z) > 0\}$ denotes the upper half plane, and $\mathbb{D} = \{z \in \mathbb{C} : |z| < 1\}$ denotes the open unit ball. $\mathbb{T} = \{z \in \mathbb{C} : |z| = 1\}$.

We use normalised Haar measure on \mathbb{T} , denoted \mathbf{m} . Lebesgue measure on \mathbb{R} is denoted λ , and two dimensional Lebesgue measure on \mathbb{C} is denoted \mathbf{m}_2 .

Throughout these notes, ω denotes the *Cayley transform*. $\omega : \mathbb{C} \setminus \{1\} \rightarrow \mathbb{C}$, and

$$\omega(\zeta) = i \frac{1 + \zeta}{1 - \zeta}, \quad \zeta \in \mathbb{D}. \quad (2.25)$$

For a Banach space E , and a measure space (X, Σ, μ) , we define

$$\|f\|_{L^p(X;E)} = \left(\int_X \|f\|_E^p d\mu \right)^{1/p} \quad (2.26)$$

for $p \in (0, \infty)$, and

$$\|f\|_{L^\infty(X;E)} = \inf\{C > 0 : \mu\{x \in X : \|f(x)\|_E > C\} = 0\} \quad (2.27)$$

for a weakly measurable $f : X \rightarrow E$. We define $L^p(X;E)$ as the set of measurable $f : X \rightarrow E$ with $\|f\|_{L^p(X;E)} < \infty$. As usual, we identify together functions on a measure space (X, Σ, μ) which agree μ -almost everywhere.

$L^0(X;E)$ denotes the set of all (μ -almost everywhere equivalence classes of) weakly measurable functions from X to E .

When X is a set with counting measure, we denote $L^p(X; E)$ as $\ell^p(X; E)$.

Suppose $\zeta \in \mathbb{T}$. Provided that $\zeta \neq 1$, we see that $\omega(\zeta)$ is defined, and ω maps $\mathbb{T} \setminus \{1\}$ smoothly to \mathbb{R} . Thus for $f \in L^0(\mathbb{R}; E)$, we can define $\tilde{f} \in L^0(\mathbb{T}; E)$ by

$$\tilde{f} := f \circ \omega^{-1}. \quad (2.28)$$

Thus we can define the important operator $U : L^0(\mathbb{T}; E) \rightarrow L^0(\mathbb{R}; E)$,

$$(Uf)(x) = \frac{1}{\sqrt{\pi}} \frac{(f \circ \omega^{-1})(x)}{x + i}. \quad (2.29)$$

2.3.2 Images under the Cayley Transform

Proposition 2.6. *Let $\mathcal{D}_{\mathbb{T}}$ denote the differentiation operator on the circle, and let $\mathcal{D}_{\mathbb{R}}$ denote differentiation on the line. Then $\text{sgn}(\mathcal{D}_{\mathbb{T}})$ and $\text{sgn}(\mathcal{D}_{\mathbb{R}})$ are unitarily equivalent, with the equivalence being given by the Cayley transform U .*

Remark 2.7. Let $f \in L^1(\mathbb{T})$. Then M_f is a linear operator on $L^2(\mathbb{T})$. M_{Uf} is a linear operator on $L^2(\mathbb{T})$.

Proposition 2.8. *Let $\varphi \in \text{BMO}(\mathbb{T})$. Then $Ud\varphi U^{-1} = dU\varphi$.*

Chapter 3

Basic Properties of Hankel Operators

3.1 Definition of a Hankel matrix

A Hankel matrix is an infinite matrix $\{M_{j,k}\}_{j,k \geq 0}$ whose (j,k) th entry depends only on $j+k$. If $a = \{a_j\}_{j \geq 0}$, Let $M_a = \{a_{j+k}\}_{j,k \geq 0}$ be the Hankel matrix with (j,k) th entry a_{j+k} . That is,

$$M_a = \begin{pmatrix} a_0 & a_1 & a_2 & a_3 & \cdots \\ a_1 & a_2 & a_3 & a_4 & \cdots \\ a_2 & a_3 & a_4 & a_5 & \cdots \\ a_3 & a_4 & a_5 & a_6 & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}.$$

An infinite matrix does not necessarily define an operator on $\ell^2(\mathbb{N})$, however any infinite matrix can be identified with a linear operator on the dense subset $c_{00}(\mathbb{N}) \subset \ell^2(\mathbb{N})$ of sequences of finite support.

For a sequence $a \in c_{00}(\mathbb{N})$, and an infinite matrix $M = (M_{j,k})_{j,k \geq 0}$, we define $Ma \in c_{00}(\mathbb{N})$ as $Ma = \{\sum_{k=0}^{\infty} M_{j,k} a_k\}_{j=0}^{\infty}$.

Hence we shall interchangeably talk about infinite matrices and linear operators $c_{00}(\mathbb{N}) \rightarrow c_{00}(\mathbb{N})$.

Since $c_{00}(\mathbb{N})$ is dense in $\ell^2(\mathbb{N})$, if an infinite matrix considered as an operator on $c_{00}(\mathbb{N})$ is bounded on $c_{00}(\mathbb{N})$ in the ℓ^2 -norm, then the matrix extends uniquely to an operator on $\ell^2(\mathbb{N})$. Conversely, any operator on $c_{00}(\mathbb{N})$ which extends to a bounded operator on $\ell^2(\mathbb{N})$ is bounded on $c_{00}(\mathbb{N})$ in the ℓ^2 -norm, and the extension to $\ell^2(\mathbb{N})$ is unique.

Denote the inner product on $\ell^2(\mathbb{N})$ as $(a, b) := \sum_{n=0}^{\infty} \overline{a_n} b_n$, which we note is linear in the second argument.

See Appendix A for the elementary properties of the Fourier transform.

A *polynomial* on \mathbb{T} is a finite linear combination of the *monomials* $\{z^n\}_{n \in \mathbb{Z}}$. We call the space of polynomials $P(\mathbb{T})$. An *analytic polynomial* is a polynomial consisting only of non-negative powers of z , we denote $P_A(\mathbb{T})$ for the space of analytic polynomials.

It is easy to see that the Fourier transform gives a vector space isomorphism between $P(\mathbb{T})$ and $c_{00}(\mathbb{Z})$, and $P_A(\mathbb{T})$ and $c_{00}(\mathbb{N})$.

3.2 Bounded Hankel operators

It is of interest to determine when a Hankel operator defines a bounded linear operator on $\ell^2(\mathbb{N})$. This is answered completely by the *Nehari theorem*, which we cover now.

Theorem 3.1. *Let $a = \{a_j\}_{j=0}^\infty$ be a sequence. Then the associated Hankel matrix M_a defines a bounded linear operator on $\ell^2(\mathbb{N})$ if and only if there exists $\psi \in L^\infty(\mathbb{T}, \mathbf{m})$ such that*

$$\hat{\psi}(m) = a_m$$

for $m \geq 0$.

Proof. Suppose first that there is $\psi \in L^\infty(\mathbb{T})$ such that $\hat{\psi}(m) = a_m$ for $m \geq 0$.

Choose $f, h \in P_A(\mathbb{T})$, so that $\hat{f}, \hat{h} \in c_{00}(\mathbb{N})$.

Let $g \in P_A(\mathbb{T})$ be given by $g = \sum_{n=0}^\infty \overline{\hat{g}(n)} z^n$. Let $q = fg$.

Then we compute,

$$\begin{aligned} (\hat{h}, M_a \hat{f}) &= \sum_{j,k \geq 0} \overline{\hat{h}(j)} a_{j+k} \hat{f}(k) \\ &= \sum_{j,k \geq 0} \overline{\hat{h}(j)} \hat{\psi}(j+k) \hat{f}(k) \\ &= \sum_{j \geq 0} \hat{\psi}(j) \sum_{k=0}^j \hat{g}(j-k) \hat{f}(k) \\ &= \sum_{j \geq 0} \hat{\psi}(j) \hat{q}(j) \\ &= \int_{\mathbb{T}} \psi(\zeta) q(\bar{\zeta}) d\mathbf{m}(\zeta). \end{aligned}$$

Hence,

$$\begin{aligned} |(\hat{h}, M_a \hat{f})| &\leq \|\psi\|_\infty \|q\|_1 \\ &\leq \|\psi\|_\infty \|f\|_2 \|h\|_2 \\ &= \|\psi\|_\infty \|\hat{f}\|_2 \|\hat{h}\|_2. \end{aligned}$$

And thus M_a is bounded on $\ell^2(\mathbb{N})$.

Conversely, suppose that M_a is bounded on $\ell^2(\mathbb{N})$.

Let \mathcal{L} be the linear functional on $P(\mathbb{T})$ defined by

$$\mathcal{L}(q) := \sum_{n \geq 0} a_n \hat{q}(n).$$

If $a \in \ell^1(\mathbb{N})$, then \mathcal{L} is bounded on $H^1(\mathbb{T})$, since the inverse fourier transform of a is in $L^\infty(\mathbb{T})$. Now let us prove in this case that $\|\mathcal{L}\| \leq \|M_a\|$.

Let $q \in H^1(\mathbb{T})$, with $\|q\|_1 \leq 1$. Then $q = fg$ for some $f, g \in H^2(\mathbb{T})$ with $\|f\|_2, \|g\|_2 \leq 1$.

Then we can compute,

$$\begin{aligned} |\mathcal{L}(q)| &= \left| \sum_{n=0}^{\infty} a_n \sum_{m=0}^n \hat{f}(m) \hat{g}(n-m) \right| \\ &= \sum_{n,m \geq 0} a_{n+m} \hat{f}(n) \hat{g}(m) \\ &= (M_a \hat{f}, \hat{g}). \end{aligned}$$

And hence,

$$|\mathcal{L}(q)| \leq \|M_a\| \|f\|_2 \|g\|_2 \leq \|M_a\|.$$

So $\mathcal{L}(q)$ is bounded on $H^1(\mathbb{T})$ whenever $a \in \ell^1(\mathbb{N})$.

Now we consider a to be an arbitrary sequence such that M_a is bounded. Let $r \in (0, 1)$ and

$$a^{(r)} = \{r^j a_j\}_{j \geq 0}.$$

Then $a^{(r)} \in \ell^1(\mathbb{N})$,

Now we can see that $M_{a^{(r)}} = D_r M_a D_r$, where D_r is multiplication by the sequence $\{r^j\}_{j \geq 0}$. Since $\|D_r\| \leq 1$, we must have $\|M_{a^{(r)}}\| \leq \|M_a\|$. Since $a^{(r)} \in \ell^1(\mathbb{N})$, we have that the linear functional

$$\mathcal{L}_r(q) := \sum_{n=0}^{\infty} a_n r^n \hat{q}(n)$$

is bounded on $H^1(\mathbb{T})$, and the functionals $\{\mathcal{L}_r\}_{r \in (0,1)}$ converge strongly to \mathcal{L} , and are uniformly bounded. Hence \mathcal{L} is continuous on $H^1(\mathbb{T})$.

Now by the Hahn-Banach theorem, since \mathcal{L} is a linear functional on the subspace $H^1(\mathbb{T})$ which has norm bounded by $\|M_a\|$, it is the restriction of a linear functional on $L^1(\mathbb{T})$, with norm bounded by $\|M_a\|$. Hence $\mathcal{L}(q) = (\psi, q)$ for some $\psi \in L^\infty(\mathbb{T})$ with $\|\psi\|_\infty \leq \|M_a\|$. This proves the result. \square

The key idea of this theorem is that it relates the sequence defining a Hankel operator with a function on \mathbb{T} . We can state this in a slightly more elegant way using the following result of Fefferman, which can be found in [6],

Proposition 3.2. *The space $\text{BMO}(\mathbb{T})$ is defined as the set of measurable functions f on \mathbb{T} (modulo almost-everywhere equivalence) such that*

$$\sup_I \int_I \left| f - \frac{1}{m(I)} \int_I f \, d\mathbf{m} \right| d\mathbf{m} < \infty$$

where I is taken over all arcs in \mathbb{T} .

Then

$$\text{BMO}(\mathbb{T}) = L^\infty(\mathbb{T}) + \mathbf{P}_+ L^\infty(\mathbb{T}) = \{f + \mathbf{P}_+ g : f, g \in L^\infty(\mathbb{T})\}.$$

Using this description of $\text{BMO}(\mathbb{T})$, we can prove the following,

Corollary 3.3. *Let $a = \{a_j\}_{j=0}^\infty$ be a sequence. Then M_a defines a bounded operator on $\ell^2(\mathbb{N})$ if and only if*

$$\varphi := \sum_{n=0}^{\infty} a_n z^n \in \text{BMO}(\mathbb{T}) \cap H^1(\mathbb{T}).$$

Proof. By theorem 3.1, M_a is bounded if and only if $\varphi = \mathbf{P}_+ \psi$ for some $\psi \in L^\infty(\mathbb{T})$. Hence if M_a is bounded, then $\varphi \in \text{BMO}(\mathbb{T}) \cap H^1(\mathbb{T})$.

Conversely, if $\varphi \in \text{BMO}(\mathbb{T}) \cap H^1(\mathbb{T})$, then $\varphi = f + \mathbf{P}_+ g$ for $f, g \in L^\infty$. Thus $\varphi = \mathbf{P}_+ \varphi = \mathbf{P}_+(f + g)$, so M_a is bounded. \square

From now on, we are no longer interested in Hankel matrices M_a defined by an arbitrary sequence a , we are only interested in those matrices M_a such that a arises from the fourier transform of a function.

Definition 3.4. Let $\varphi \in H^1(\mathbb{T})$. Let Γ_φ be the Hankel matrix with (i, j) th entry $\hat{\varphi}(i + j)$.

3.3 Finite Rank Hankel operators

The strongest condition that we can put on a Hankel matrix Γ_φ is that it is a finite rank operator on $\ell^2(\mathbb{N})$. The problem of determining φ such that Γ_φ is finite rank was solved by Kronecker, as follows.

Theorem 3.5. *Let $\varphi \in H^1(\mathbb{T})$, and Γ_φ be the associated Hankel matrix. Then Γ_φ defines a bounded operator on $\ell^2(\mathbb{N})$ if and only if φ is a rational function.*

Proof. Suppose that $\text{rank}(\Gamma_\varphi) = n$. Then the first $n + 1$ columns of the matrix of Γ_φ are linearly dependent. Let B denote the backward shift operator, $B(a_0, a_1, \dots) := (a_1, a_2, \dots)$ and let F be the forward shift operator, $F(a_0, a_1, \dots) := (0, a_0, a_1, \dots)$. Let $a = \hat{\varphi}$.

Hence there exist complex scalars $\{c_0, c_1, \dots, c_n\}$ not all equal to zero such that

$$c_0 a + c_1 B a + \dots + c_n B^n a = 0.$$

Now let $n, k \geq 0$. It is elementary that

$$F^n B^k a = F^{n-k} a - F^{n-k}(a_0, a_1, \dots, a_{k-1}, 0, 0, \dots).$$

So hence we have,

$$\begin{aligned} 0 &= F^n \sum_{k=0}^n c_k B^k a \\ &= \sum_{k=0}^n c_k F^n B^k a \\ &= \sum_{k=0}^n c_k F^{n-k} a - p \end{aligned}$$

where p is a finitely supported sequence.

Let $q = (c_n, c_{n-1}, \dots, c_0, 0, 0, \dots)$. Then we have,

$$0 = q * a - p.$$

Where the $*$ is convolution. Therefore, if we take the inverse fourier transform,

$$\varphi \check{a} = \check{p}.$$

And hence φ is a quotient of two polynomials.

Conversely, suppose that φ is a rational function. Suppose that $\varphi = p/q$, where $p, q \in P(\mathbb{T})$. Let $n = \max\{\deg p, \deg q\}$. If

$$q = \sum_{k=0}^n c_{n-k} z^k$$

then since $\varphi q = p$, we have

$$\sum_{k=0}^n c_k F^{n-k} a = p.$$

Now multiply by B^n ,

$$\begin{aligned} B^n \sum_{k=0}^n c_k F^{n-k} a &= \sum_{k=0}^n c_k B^k a \\ &= 0. \end{aligned}$$

Let $m \leq n$ be the largest number for which $c_m \neq 0$. Then $B^m a$ is a linear combination of the $B^k a$ with $k \leq m-1$,

$$B^m a = \sum_{k=0}^{m-1} d_k B^k a$$

for some coefficients d_k .

We now proceed by induction to show that any row is a linear combination of the first n rows.

Let $k > m$. Then we have,

$$\begin{aligned} B^k a &= B^{k-m} B^m a \\ &= \sum_{j=0}^{m-1} d_j B^{k-m+j} a. \end{aligned}$$

Since $k-m+j < k$, we have that the terms on the right hand side are linear combinations of the first m rows by the inductive hypothesis. Hence $\text{rank}(\Gamma_\varphi) \leq m$. \square

3.4 Compactness of Hankel Operators

If $\varphi \in L^1(\mathbb{T})$, we are interested in conditions on φ such that Γ_φ is compact.

Our first result shows that Hankel matrices are continuous in their symbol.

Proposition 3.6. *Let $\varphi \in L^\infty(\mathbb{T})$, then*

$$\|\Gamma_\varphi\| \leq \|\varphi\|_\infty.$$

and therefore if $\varphi \in C(\mathbb{T})$, then Γ_φ is compact.

Proof. It was shown in the proof of theorem 3.1 that if g, f are sequences of finite support, then

$$|(g, \Gamma_\varphi f)| \leq \|\varphi\|_\infty \|g\|_2 \|f\|_2.$$

Hence $\|\Gamma_\varphi\| \leq \|\varphi\|_\infty$. \square

Corollary 3.7. *If $\varphi \in C(\mathbb{T})$, then Γ_φ is compact.*

Proof. Since Γ_φ is finite rank for φ a polynomial, and $\|\Gamma_\varphi\| \leq \|\varphi\|_\infty$, the result follows. \square

To complete our characterisation of compact Hankel operators, we require the following result of Fefferman, found in [6]:

Proposition 3.8. *The class $\text{VMO}(\mathbb{T})$ is the set of measurable functions $f : \mathbb{T} \rightarrow \mathbb{C}$ such that*

$$\lim_{\mathbf{m}(I) \rightarrow 0} \int_I \left| f - \frac{1}{\mathbf{m}(I)} \int_I f \, d\mathbf{m} \right| d\mathbf{m} = 0$$

where the limit is over all arcs $I \subseteq \mathbb{T}$.

It is a result of Fefferman [6] that,

$$\text{VMO}(\mathbb{T}) = C(\mathbb{T}) + \mathbf{P}_+ C(\mathbb{T}).$$

So we have the following:

Proposition 3.9. *Let $\varphi \in \text{VMO}(\mathbb{T})$. Then Γ_φ is compact.*

Proof. if $\varphi \in \text{VMO}(\mathbb{T})$, then by proposition 3.8, $\varphi = f + \mathbf{P}_+ g$ for $f, g \in C(\mathbb{T})$. Hence, $\mathbf{P}_+ \varphi = \mathbf{P}_+(f + g)$. Hence, there exists $h \in C(\mathbb{T})$ with $\Gamma_\varphi = \Gamma_h$, simply by choosing $h = f + g$. Hence by corollary 3.7, we see that Γ_φ is compact. \square

3.5 Hankel Operators of Trace Class

We recall the definition of the \mathcal{L}^1 norm on $\mathcal{B}(\mathcal{H})$,

Definition 3.10. Let \mathcal{H} be a separable Hilbert space, and let $T \in \mathcal{B}(\mathcal{H})$. For a non-negative integer n , we define the n th singular value,

$$s_n(T) := \inf\{\|T - F\| : F \in \mathcal{B}(\mathcal{H}), \text{rank}(F) \leq n\}.$$

For $p \in (0, \infty)$, we define the \mathcal{L}^p norm of T as

$$\|T\|_p = \left(\sum_{n=0}^{\infty} |s_n(T)|^p \right)^{1/p}$$

with the convention that $\|T\|_p = \infty$ if the sum does not converge. The space \mathcal{L}^p is the set of $T \in \mathcal{B}(\mathcal{H})$ such that $\|T\|_p < \infty$.

In particular we are interested in the case $p = 1$. We are interested in finding conditions on a function φ holomorphic in the unit disc such that Γ_φ is in \mathcal{L}^1 .

Lemma 3.11. *Let \mathcal{H} be a separable Hilbert space. Suppose that $x, y \in \mathcal{H}$, and let T be the rank one operator defined by $T(\zeta) = \langle x, \zeta \rangle y$. Then $\|T\|_1 = \|x\| \|y\|$.*

The answer is provided by the *Besov classes*. Many different definitions of Besov spaces can be found, but the one of most relevance to us is given below.

Definition 3.12. We define a sequence of polynomials $\{W_n\}_{n \in \mathbb{Z}} \subset P(\mathbb{T})$ as follows. First,

$$W_0 = z^{-1} + 1 + z.$$

And now for $n > 0$, we define W_n by asserting that $\widehat{W}(2^n) = 1$, $\widehat{W}(2^{n-1}) = 0$, $\widehat{W}(2^{n+1}) = 0$, and \widehat{W} is a linear increasing function between 2^{n-1} and 2^n , and a linear decreasing function between 2^n and 2^{n+1} . We assert that $\widehat{W}(n)$ is symmetric in n , and is zero for all values not already defined.

Now, for $p, q > 0$, and $s \geq 0$, we define the *Besov class* $B_{pq}^s(\mathbb{T})$ to be the space of distributions f on \mathbb{T} such that

$$\sum_{n \geq 0} 2^{nsq} \|W_n * f\|_p^q < \infty.$$

We shall denote B_{pp}^s as B_p^s .

In particular, we are going to prove that if $\varphi \in B_1^1(\mathbb{T})$, then $\Gamma_\varphi \in \mathcal{L}^1$. First, we need a lemma.

Lemma 3.13. *Let $f \in P_A(\mathbb{T})$ be an analytic polynomial of degree at most m . Then,*

$$\|\Gamma_f\|_1 \leq (m+1) \|f\|_1.$$

Proof. Let $\zeta \in \mathbb{T}$, now define the following elements of $\ell^2(\mathbb{N})$,

$$x_\zeta(j) = \begin{cases} \zeta^j, & 0 \leq j \leq m, \\ 0, & j > m \end{cases}$$

$$y_\zeta(j) = \begin{cases} f(\zeta) \zeta^{-k}, & 0 \leq k \leq m, \\ 0, & k > m. \end{cases}$$

That is, $x_\zeta = (1, \zeta, \zeta^2, \dots, \zeta^m, 0, 0, \dots)$ and $y_\zeta = f(\zeta) \overline{x_\zeta}$.

Let A_ζ be the rank one operator, $A_\zeta(x) = (x_\zeta, x) y_\zeta$, so that $\|A_\zeta\|_1 = \|x_\zeta\|_2 \|y_\zeta\|_2 = (m+1) |f(\zeta)|$

Then we have a componentwise equality of infinite matrices,

$$\Gamma_f = \int_{\mathbb{T}} A_\zeta d\mathbf{m}(\zeta).$$

Hence, $\|\Gamma_f\|_1 \leq (m+1)\|f\|_1$ by the triangle inequality. \square

Theorem 3.14. *Let $\varphi \in B_1^1$. Then $\Gamma_\varphi \in \mathcal{L}^1$.*

Proof. We have the following L^∞ -convergent sequence,

$$\varphi = \sum_{n \geq 0} W_n * \varphi.$$

Hence,

$$\Gamma_\varphi = \sum_{n \geq 0} \Gamma_{W_n * \varphi}.$$

So since the degree of W_n is 2^{n+1} , we have

$$\|\Gamma_\varphi\|_1 \leq \sum_{n \geq 0} 2^{n+1} \|W_n * \varphi\|_1.$$

\square

This proves the sufficiency of the condition $\varphi \in B_1^1$ so that Γ_φ is trace class. The proof of the necessity of this condition is more difficult,

Theorem 3.15. *Let φ be a function holomorphic in the unit disc. Then if $\Gamma_\varphi \in \mathcal{L}^1$, then $\varphi \in B_1^1$.*

Proof. Define a pair of sequences of polynomials $\{Q_n\}_{n=0}^\infty$ as follows,

$$\widehat{Q}_n(k) = \begin{cases} 0, & k \leq 2^{n-1} \\ 1 - \frac{|k-2^n|}{2^{n-1}}, & 2^{n-1} \leq k \leq 2^n + 2^{n-1}, \\ 0 & k \geq 2^n + 2^{n-1}. \end{cases}$$

and a sequence $\{R_n\}_{n=0}^\infty$,

$$\widehat{R}_n(k) = \begin{cases} 0, & k \leq 2^n \\ 1 - \frac{|k-2^n-2^{n-1}|}{2^{n-1}}, & 2^n \leq k \leq 2^{n+1} \\ 0, & k \geq 2^{n+1}. \end{cases}$$

This is a decomposition of the sequence $\{W_n\}_{n=0}^\infty$, given by $W_n = Q_n + \frac{1}{2}R_n$.

First we prove that

$$\sum_{n \geq 0} 2^{2n+1} \|Q_{2n+1} * \varphi\|_1 < \infty.$$

To this end, we wish to construct an operator B such that

$$\langle \Gamma \varphi, B \rangle = \sum_{n \geq 0} 2^{2n} \|Q_{2n+1} * \varphi\|_1.$$

Now define the sequence of squares, for $n \geq 1$,

$$S_n = [2^{2n-1}, 2^{2n-1} + 2^{2n} - 1] \times [2^{2n-1} + 1, 2^{2n-1} + 2^{2n}].$$

Note that this sequence is pairwise disjoint.

Let $\{\psi_n\}_{n=0}^\infty$ be a sequence in $L^\infty(\mathbb{T})$, yet to be defined with $\|\psi_n\|_\infty \leq 1$. Now we define the matrix $B = \{B_{j,k}\}_{j,k \geq 0}$ by

$$B_{j,k} = \begin{cases} \widehat{\psi}_n(j+k), & (j,k) \in S_n, n \geq 1, \\ 0, & (j,k) \notin \bigcup_{n \geq 1} S_n. \end{cases}$$

We wish to prove that B is bounded, and in fact $\|B\| \leq 1$. Let $\{e_n\}_{n \geq 0}$ be the standard basis for $\ell^2(\mathbb{N})$, with $e_n(m) = \delta_{n,m}$. Define the subspaces

$$\begin{aligned} \mathcal{H}_n &= \{e_j : 2^{2n-1} \leq j \leq 2^{2n-1} + 2^{2n} - 1\}, \\ \mathcal{H}'_n &= \{e_j : 2^{2n-1} + 1 \leq j \leq 2^{2n-1} + 2^{2n}\}. \end{aligned}$$

Let P_n and P'_n be the orthogonal projection onto \mathcal{H}_n and \mathcal{H}'_n respectively. So that

$$B = \sum_{n \geq 1} P'_n \Gamma_{\psi_n} P_n,$$

where P_n and P'_n are the orthogonal projections onto \mathcal{H}_n and \mathcal{H}'_n respectively.

Now since the spaces $\{\mathcal{H}_n\}_{n \geq 1}$ are pairwise orthogonal, as are the spaces $\{\mathcal{H}'_n\}_{n \geq 1}$, we have

$$\begin{aligned} \|B\| &\leq \sup_{n \geq 1} \|P'_n \Gamma_{\psi_n} P_n\| \\ &\leq \sup_n \|\Gamma_{\psi_n}\| \\ &\leq \sup_n \|\psi_n\|_\infty \\ &\leq 1. \end{aligned}$$

Now, we compute

$$\begin{aligned}
\langle \Gamma_\varphi, B \rangle &= \sum_{n \geq 1} \langle \Gamma_\varphi, P'_n \Gamma_{\psi_n} P_n \rangle \\
&= \sum_{n \geq 1} \sum_{j=2^{2n}}^{2^{2n}+2^{2n+1}} (2^{2n} - |j - 2^{2n+1}| \widehat{\bar{\varphi}}(j) \widehat{\psi_n}(j)) \\
&= \sum_{n \geq 1} 2^{2n} (Q_{2n+1} * \varphi, \psi_n).
\end{aligned}$$

Now, using the sharpness of Hölder's inequality, we can choose a sequence $\{\psi_n\}_{n=0}^\infty$ so that $\langle Q_{2n+1} * \varphi, \psi_n \rangle$ is arbitrarily close to $\|Q_{2n+1} * \varphi\|_1$. Hence,

$$\sum_{n \geq 1} 2^{2n+1} \|Q_{2n+1} * \varphi\|_1 = 2 \langle \Gamma_\varphi, B \rangle \leq 2 \|\Gamma_\varphi\|_1.$$

In exactly the same way, we may prove that

$$\sum_{n \geq 1} 2^{2n} \|Q_{2n} * \varphi\|_1 < \infty$$

that

$$\sum_{n \geq 0} 2^{2n+1} \|R_{2n+1} * \varphi\|_1 < \infty$$

and

$$\sum_{n \geq 1} 2^{2n} \|R_{2n} * \varphi\|_1 < \infty$$

and therefore that $\varphi \in B_1^1$. □

Remark 3.16. We thus conclude that

$$\frac{1}{6} \sum_{n \geq 1} 2^n \|W_n * \varphi\|_1 \leq \|\Gamma_\varphi\|_1 \leq 2 \sum_{n \geq 0} 2^n \|W_n * \varphi\|_1.$$

3.6 Interpolation

The following is proved in [7]:

Lemma 3.17. *Let K be the real interpolation functor, described in [8]. Let $p, q \in (0, \infty]$. Then*

$$K(\mathcal{L}^1, \mathcal{K})_{\theta, q} = \mathcal{L}_{p, q}.$$

for $p = (1 - \theta)^{-1}$.

Corollary 3.18. *Hence, we have that $\Gamma_\varphi \in \mathcal{L}_{p, q}$ if $\varphi \in K(B_1^1, \text{VMO})_{\theta, q}$, where $p = (1 - \theta)^{-1}$.*

3.7 Extrapolation

We have determined sufficient conditions for $\Gamma_\varphi \in \mathcal{L}_{p,q}$. We now turn our attention to more exotic ideals of $\mathcal{B}(\ell^2(\mathbb{N}))$. The Macaev-Dixmier ideal $\mathcal{M}_{1,\infty}$ is described in detail Appendix E.

Most important for our purposes is the equivalence of norms,

$$\|x\|_{\mathcal{M}_{1,\infty}} = \sup_{s \in (0,1)} s \|x\|_{\mathcal{L}_{s+1}}. \quad (3.1)$$

Hence, we have

Proposition 3.19. *Let φ be a function on \mathbb{T} such that $\sup_{s \in (0,1)} s \|\varphi\|_{B_{s+1,s+1}^{1/(s+1)}} < \infty$. Then $d\varphi \in \mathcal{M}_{1,\infty}$.*

Chapter 4

Operator Ideal Membership of Quantised Differentials

4.1 Transference from Hankel Operators to Quantised differentials

Let $\varphi \in L^2(\mathbb{T})$. We consider $\bar{d}\varphi$ as an operator on $H^2(\mathbb{T}) \oplus H_-^2(\mathbb{T})$. Then we have the description,

$$\bar{d}\varphi = 2 \begin{pmatrix} 0 & -H_{\varphi_+}^* \\ H_{\varphi_-} & 0 \end{pmatrix} \quad (4.1)$$

Hence, to determine when $\bar{d}\varphi$ falls into some ideal of operators, it frequently suffices to check $H_{\varphi_+}^*$ and H_{φ_-} .

4.1.1 Bounded Quantised Differentials

The weakest condition that we can place on an operator is that it be bounded. The Nehari theorem 3.1 gives us necessary and sufficient conditions for a quantised differential to be bounded.

Proposition 4.1. *Let $\varphi \in L^1(\mathbb{T})$. Then $\bar{d}\varphi$ defines a bounded linear operator on $L^2(\mathbb{T})$ if and only if $\varphi \in \text{BMO}(\mathbb{T})$.*

Proof. The operator H_f is a Hankel operator, with (j, k) th entry $\hat{f}(-j - k)$, so by theorem 3.1, we have that $\bar{d}\varphi$ is bounded if and only if $\varphi_-^-, \varphi_+ \in \text{BMO}(\mathbb{T})$.

By the description of $\text{BMO}(\mathbb{T})$ as the set of all $\varphi \in L^1(\mathbb{T})$ such that

$$\sup_I \int_I |f - \int_I f \, d\mathbf{m}| \, d\mathbf{m}, \quad (4.2)$$

it is clear that $f \in \text{BMO}(\mathbb{T})$ if and only if $\bar{f} \in \text{BMO}(\mathbb{T})$.

By the Fefferman decomposition, given in [6],

$$\text{BMO}(\mathbb{T}) = L^\infty(\mathbb{T}) + \mathbf{P}_+ L^\infty(\mathbb{T}) \quad (4.3)$$

it follows that $f \in \text{BMO}(\mathbb{T})$ if and only if $\mathbf{P}_+ f, \mathbf{P}_- f \in \text{BMO}(\mathbb{T})$.

Thus, $\bar{d}\varphi$ is bounded if and only if $\varphi \in \text{BMO}(\mathbb{T})$. \square

4.1.2 Finite Rank Quantised Differentials

On the other hand, the *strongest* condition that one can place on an operator is that it be finite rank. Kronecker's theorem 3.5 gives us conditions for a quantised differential to be finite rank.

Proposition 4.2. *Let $\varphi \in L^1(\mathbb{T})$. Then the operator $\bar{d}\varphi$ on $L^2(\mathbb{T})$ is finite rank if and only if φ is a rational function.*

Proof. By theorem 3.5, it is necessary and sufficient that $\overline{\varphi_+}$ and φ_- are rational functions. Hence it is necessary and sufficient that φ is rational. \square

4.1.3 Compact Quantised Differentials

Recall from chapter 1, that we wished to have some justification of the claim that if f is continuous, then $\bar{d}f$ is infinitesimal. This is totally justified by the following proposition:

Proposition 4.3. *If $\varphi \in \text{VMO}(\mathbb{T})$, then $\bar{d}\varphi \in \mathcal{K}(\mathcal{H})$.*

Proof. By equation 4.1, we need to consider operators of the form H_{φ_-} and $H_{\overline{\varphi_+}}$. Hence we have $\bar{d}\varphi$ is compact if $\overline{\varphi_-}$ and φ_+ in $\text{VMO}(\mathbb{T})$. But since $\text{VMO}(\mathbb{T})$ is closed under the image of \mathbf{P}_+ and conjugation, we see that this is equivalent to $\varphi \in \text{VMO}(\mathbb{T})$. \square

4.1.4 Trace Class Quantised Differentials

There is an alternative characterisation of Besov classes on the circle, which we refer to here.

Proposition 4.4. *Let $\zeta, \tau \in \mathbb{T}$. For a function $f : \mathbb{T} \rightarrow \mathbb{C}$, define*

$$\Delta_\tau f(\zeta) = f(\tau\zeta) - f(\zeta). \quad (4.4)$$

Then, let $s > 0$, $p, q \in [1, \infty]$ and n be an integer $n > s$,

$$B_{pq}^s = \left\{ f \in L^p : \int_{\mathbb{T}} \frac{\|\Delta_{\tau}^n f\|_p^q}{|1 - \tau|^{1+sq}} d\mathbf{m}(\tau) < \infty \right\} \quad (4.5)$$

To complete our description, we need the following:

Lemma 4.5. *Let $\varphi \in L^1(\mathbb{T})$. Then $\varphi \in K(B_{11}^1, \text{VMO})_{\theta, q}$ if and only if $\overline{\varphi_+}, \varphi_- \in K(B_{11}^1, \text{VMO})_{\theta, q}$.*

Proof.

□

So we get the following:

Corollary 4.6. *Let $\varphi \in K(B_{11}^1, \text{VMO})$. Then $\bar{\partial}\varphi \in \mathcal{L}_{p, q}$.*

4.2 Quantised Differentials on \mathbb{R}

Chapter 5

Abstract Differential Algebra and Spectral Triples

5.1 Introduction

For several decades now, mathematicians have been attempting to find analogues of theorems of differential and algebraic geometry in noncommutative algebra. The biggest obstacle to learning this topic is that many of the definitions were arrived at through many years of hard work, and may seem unmotivated at first.

Chapter ?? introduced the concept of a *spectral triple*. We now discuss how to construct the non-commutative analogue of the exterior algebra bundle on a spectral triple. This analogue is called the algebra of *Connes Differentials*.

5.2 Classical Differential Algebra

Let M be an n dimensional manifold. The cotangent bundle $\Omega^1(M)$ is a rank n vector bundle on M . We build higher bundles by wedge products,

$$\Omega^p(M) := \bigwedge_p \Omega^1(M).$$

and define $\Omega^0(M) := C^\infty(M)$. See that $\dim_{\mathbb{R}}(\Omega^p(M)) = \binom{n}{p}$.

The exterior algebra bundle is the direct sum of all the $\Omega^p(M)$,

$$\Omega(M) := \bigoplus_{p=0}^{\infty} \Omega^p(M).$$

$\Omega(M)$ is a *graded algebra*.

In general, if A is an algebra over a ring R , we say that A is \mathbb{N} -graded if there exists a decomposition into submodules $A^{(p)}$,

$$A = \bigoplus_{p=0}^{\infty} A^{(p)}$$

such that $A^{(n)}A^{(m)} \subseteq A^{(n+m)}$.

In the case $A = \Omega(M)$, we have $R = \mathbb{R}$, and $A^{(p)} = \Omega^p(M)$.

The exterior derivative, $d : \Omega(M) \rightarrow \Omega(M)$ acts on the grading by,

$$d : \Omega^p(M) \rightarrow \Omega^{p+1}(M).$$

and $d^2 = 0$. Hence we have a sequence,

$$0 \rightarrow \Omega^0(M) \xrightarrow{d} \Omega^1(M) \xrightarrow{d} \cdots \xrightarrow{d} \Omega^n(M) \xrightarrow{d} 0.$$

Denote d_p as the restriction of d to $\Omega^p(M)$. Then we have the *de Rham cohomology* spaces,

$$H_{dR}^p(M) = \frac{\ker(d_p)}{\operatorname{im}(d_{p-1})}$$

This is a sequence of real vector spaces, and their dimensions are topological invariants of M .

The maps d_p satisfy a graded version of Leibniz's rule, for $a \in \Omega^n(M)$ and $b \in \Omega^m(M)$, we have:

$$d_{n+m}(ab) = d_n(a)b + (-1)^n ad_m(b)$$

5.3 Abstract Differential Algebra

5.3.1 Graded Differential Algebras

We now take the ideas of the previous section and move them to a more abstract setting. Let R be a commutative ring, and let A be an \mathbb{N} -graded algebra over R , with decomposition

$$A = \bigoplus_{p=0}^{\infty} A^{(p)}$$

There is also an R -linear map $d : A \rightarrow A$ such that,

$$d : A^{(p)} \rightarrow A^{(p+1)}.$$

and $d^2 = 0$. If we denote the restriction of d to $A^{(p)}$ as d_p , we require that the maps d_p satisfy a graded Leibniz rule, for $a \in A^{(n)}$ and $b \in A^{(m)}$,

$$d_{n+m}(ab) = d_n(a)b + (-1)^n ad_m(b).$$

A pair (A, d) satisfying these conditions is called a *differential graded algebra*.

Thus we have a sequence,

$$0 \rightarrow A^{(0)} \xrightarrow{d} A^{(1)} \xrightarrow{d} \dots \xrightarrow{d} A^{(n)} \xrightarrow{d} \dots$$

The quotient R -modules,

$$H_{dR}^p(M) := \frac{\ker(d_p)}{\operatorname{im}(d_{p-1})}.$$

are the de Rham cohomology modules for the graded differential algebra (A, d) .

5.3.2 Kähler Differentials

Given an R -algebra A , we would like to be able to build an algebra of differential forms over A , in a manner analogous to how $\Omega^1(M)$ is constructed from $C^\infty(M)$. It turns out that there is a good way of doing this, called the algebra of *Kähler differentials*. This is simplest in the commutative case, which we briefly outline here.

Let R be a commutative ring, and let A be a unital commutative R -algebra. The module $\Omega_{\text{com}}^1(A)$ of Kähler differentials is defined as

$$\Omega_{\text{com}}^1(A) := \frac{A \otimes_R A}{\langle c \otimes (ab) - (ca) \otimes b - (bc) \otimes a \rangle}$$

The idea here is that $\Omega_{\text{com}}^1(A)$ is the left A -module spanned by all symbols of the form adb , where $d(ab) = adb + bda$. We think of $a \otimes b$ as adb .

More precisely, we let $d : A \rightarrow \Omega_{\text{com}}^1(A)$ be given by

$$da := 1_A \otimes a$$

Where 1_A is the unit in A .

The utility of $\Omega_{\text{com}}^1(A)$ is that it allows us to study all derivations on A .

In full abstraction, a derivation on A is a map $\theta : A \rightarrow M$, where M is some left A -module, such that θ satisfies the Leibniz rule,

$$\theta(ab) = a\theta(b) + b\theta(a).$$

We see that d is a derivation on A to the A -module $\Omega_{\text{com}}^1(A)$. It is in fact universal with this property,

Theorem 5.1. *Let A be a unital commutative R -algebra, and let $\theta : A \rightarrow M$ be a derivation to some left A -module M . There exists a unique R -linear map $\Omega(\theta)$ such that the following diagram commutes,*

$$\begin{array}{ccc} A & \xrightarrow{d} & \Omega_{\text{com}}^1(A) \\ & \searrow \theta & \downarrow \Omega(\theta) \\ & & M \end{array}$$

In other words, there is an isomorphism of R -modules,

$$D(A, M) \cong \text{Hom}_R(\Omega_{\text{com}}^1(A), M).$$

Where $D(A, M)$ is the set of derivations from A to M . Note that this universal property defines $\Omega_{\text{com}}^1(A)$ up to unique isomorphism.

Proof. Basically, $\Omega(\theta)$ maps adb to $a\theta(b)$. Checking the universal property is routine. \square

We would now like to create a similar algebra of differentials for a non-commutative associative algebra A over R . In the noncommutative case, we must restrict attention to derivations that take values in A -bimodules, rather than left A modules.

Definition 5.2. Let A be an associative unital algebra over a commutative ring R . Let $m : A \otimes A \rightarrow A$ be the multiplication map. We define

$$\Omega^1(A) = \ker(m)$$

This is an A bimodule.

This the motivation behind this definition is not at all clear. However, this does agree with the commutative case and this provides the appropriate definition for noncommutative Kähler differentials. To see this, we define the map $d : A \rightarrow \Omega^1(A)$, by

$$d(a) = 1_A \otimes a - a \otimes 1_A.$$

We see that d is a derivation. In fact, $\Omega^1(A)$ should be thought of as the space of all linear combinations of terms of the form $ad(b)$.

$\Omega^1(A)$ satisfies the same universal property as Ω_{com}^1 . Namely, if M is an A -bimodule, and $\theta : A \rightarrow M$ is a derivation, then there exists a unique R -linear map $\Omega(\theta)$ such that the following diagram commutes,

$$\begin{array}{ccc}
A & \xrightarrow{d} & \Omega^1(A) \\
& \searrow \theta & \downarrow \Omega(\theta) \\
& & M
\end{array}$$

5.3.3 Universal Differential Algebra

Given an associative unital algebra A over a commutative ring R , we define

$$\Omega^p(A) := \bigotimes_{A,p} \Omega^1(A).$$

And the algebra,

$$\Omega A = \bigoplus_p \Omega^p(A).$$

We extend the function $d : A \rightarrow \Omega^1(A)$ to ΩA by

$$d(ada_1da_2 \cdots da_n) = dada_1da_2 \cdots da_n.$$

Theorem 5.3. ΩA is the “largest” graded differential algebra generated by A .

If (Γ, Δ) is a graded differential algebra, with grading $\Gamma = \bigoplus_n \Gamma^{(n)}$, and $\rho : A \rightarrow \Gamma^{(0)}$ is an algebra homomorphism, then ρ extends uniquely to a morphism $\Omega A \rightarrow \Gamma$ such that the following diagram commutes,

$$\begin{array}{ccc}
\Omega^p(A) & \xrightarrow{\rho} & \Gamma^{(p)} \\
\downarrow d & & \downarrow \Delta \\
\Omega^{p+1}(A) & \xrightarrow{\rho} & \Gamma^{(p+1)}
\end{array}$$

The Insufficiency of Kähler Differentials

We now have a good definition of $\Omega(A)$ for any potentially non-commutative algebra A , and it would seem that this is the final word on generalising the algebra of differential forms to the noncommutative setting.

However, this is incorrect, as the following proposition shows:

Proposition 5.4. *Let $A = C^\infty(\mathbb{R})$. Then if f and g do not satisfy some polynomial relation, then in the algebra of Kähler differentials df and dg are algebraically independent over A . In particular, $d \exp(x) \neq \exp(x)dx$.*

Hence, the usual algebra of differential forms is not isomorphic to the algebra of Kähler differentials, but is instead a quotient of it.

So in order to produce a theory of differential algebra in the noncommutative setting, we need to introduce more structure on the algebra \mathcal{A} . Thus we are led to the concept of a spectral triple.

5.4 Non-commutative Geometry

5.4.1 Spectral Triples

Recall from Chapter 1 that a general non-commutative space should be thought of as a pair $(\mathcal{A}, \mathcal{H})$, where \mathcal{A} is an algebra of operators on a Hilbert space \mathcal{H} .

We shall consider noncommutative spaces equipped with a “Dirac Operator”, $(\mathcal{A}, \mathcal{H}, \mathcal{D})$ such that \mathcal{A} is contained in a semi-finite Von Neumann algebra \mathcal{N} which is contained in $\mathcal{B}(\mathcal{H})$.

A (commutative) example of this is as follows: Let (M, g) be a compact Riemannian manifold, and let $\mathcal{A} = C^\infty(M)$, and $\mathcal{H} = L^2(M, g)$. However this is not enough information to recover the geometry of M . A convenient way to recover the geometry of M from algebraic data is to give a Dirac operator. The definition of a general Dirac operator is given in Appendix D.

Definition 5.5 (Spectral Triple). A (semifinite) spectral triple is a triple $(\mathcal{A}, \mathcal{H}, \mathcal{D})$, where \mathcal{H} is a Hilbert space with $\mathcal{A} \subseteq \mathcal{B}(\mathcal{H})$ a $*$ -algebra of operators.

\mathcal{D} is a densely defined unbounded operator on \mathcal{H} satisfying the following two properties:

1. $[\mathcal{D}, a]$ is densely defined and extends to a bounded operator in \mathcal{N} for all $a \in \mathcal{A}$.
2. $(\lambda - \mathcal{D})^{-1}$ is τ -compact for all $\lambda \in \mathbb{C} \setminus \mathbb{R}$.

A spectral triple $(\mathcal{A}, \mathcal{H}, \mathcal{D})$ can be either *even* or *odd*:

- We say that $(\mathcal{A}, \mathcal{H}, \mathcal{D})$ is even if there exists a $\mathbb{Z}/2\mathbb{Z}$ grading on the linear operators on \mathcal{H} such that \mathcal{A} is even and \mathcal{D} is odd. Equivalently, there is an operator Γ on \mathcal{H} with $\Gamma^2 = 1$ and $\Gamma^* = \Gamma$ such that $a\Gamma = \Gamma a$ for all $a \in \mathcal{A}$ and $\mathcal{D}\Gamma = -\Gamma\mathcal{D}$.
- If no such operator Γ exists, then we say that $(\mathcal{A}, \mathcal{H}, \mathcal{D})$ is odd.

5.4.2 Connes Differentials

Given a spectral triple $(\mathcal{A}, \mathcal{H}, \mathcal{D})$, we would like to construct an “exterior algebra” on \mathcal{A} . Connes does this by identifying the 1-form da with $[D, a]$.

Since $[D, a]$ is a derivation on \mathcal{A} , by the universal property we have a map, $\pi : \Omega\mathcal{A} \rightarrow \mathcal{B}(\mathcal{H})$ given by $\pi(ada_1da_2 \cdots da_n) = a[D, a_1][D, a_2] \cdots [D, a_n]$.

One may then naïvely define the algebra of differential forms as $\pi(\Omega\mathcal{A})$, but this does not work since there exists $a \in \Omega\mathcal{A}$ such that $\pi(a) = 0$ but $\pi(da) \neq 0$. These are called “junk forms” and we must factor them out to get a good differential algebra. Hence, define

Theorem 5.6. *Let J_0 be the graded ideal of $\Omega\mathcal{A}$ defined by*

$$J_0^{(p)} = \{a \in \Omega^p(\mathcal{A}) : \pi(a) = 0\}$$

And define $J^{(p)} = J_0^{(p)} + dJ_0^{(p)}$. Then $J = \bigoplus_p J^{(p)}$.

Now we can define the algebra of Connes’ forms,

$$\Omega_{\mathcal{D}}\mathcal{A} = \frac{\Omega\mathcal{A}}{J} \cong \frac{\pi(\Omega\mathcal{A})}{\pi(dJ_0)}$$

$\Omega_{\mathcal{D}}\mathcal{A}$ is naturally graded by the gradings on $\Omega\mathcal{A}$ and J , with the space of p -forms being $\Omega_{\mathcal{D}}^p\mathcal{A} = \Omega^p(\mathcal{A})/J^{(p)}$.

Since J is a differential ideal, the operator d on $\Omega\mathcal{A}$ extends to $\Omega_{\mathcal{D}}\mathcal{A}$.

Definition 5.7 (Quantum Differentiability). A spectral triple $(\mathcal{A}, \mathcal{H}, \mathcal{D})$ is called QC^k for $k \geq 0$ if \mathcal{A} is contained in the domain of the operator δ^k , where $\delta(a) = [|\mathcal{D}|, a]$.

Definition 5.8 (Summability). A spectral triple $(\mathcal{A}, \mathcal{H}, \mathcal{D})$ is called (p, ∞) summable for $p > 0$ if $(1 + \mathcal{D}^2)^{-1/2} \in \mathcal{L}^{p, \infty}$.

5.5 Quantised Differentials in Noncommutative Geometry

We have already given a thorough description of the quantised differentials $\bar{d}f$ when f is a function on the circle. It so happens that we can find analogous, although weaker, results in far greater generality.

It is in fact easier to move to a setting that is extremely general.

Definition 5.9. Let $(\mathcal{A}, \mathcal{H}, \mathcal{D})$ be a spectral triple, either even or odd. Since \mathcal{D} is a self adjoint operator, by the Borel functional calculus we can define the operator $F := \text{sgn}(\mathcal{D})$. For $a \in \mathcal{A}$, we define

$$\bar{d}a := [F, a]. \tag{5.1}$$

It is here that we see the distinction between *derivatives* and *differentials*. In a spectral triple, the algebra of Connes forms plays the role of derivatives of functions, and the quantised differentials are a different object entirely.

Theorem 5.10. *Let $p \geq 1$, and let $(\mathcal{A}, \mathcal{H}, \mathcal{D})$ be a (p, ∞) summable QC^1 spectral triple such that \mathcal{D} is invertible. Then, for all $a \in \mathcal{A}$*

$$\bar{d}a \in \mathcal{L}^{p,\infty}. \quad (5.2)$$

Proof. Since $\mathcal{D} = |\mathcal{D}|F$, we can compute

$$[\mathcal{D}, a] = |\mathcal{D}|[F, a] + [|\mathcal{D}|, a]F. \quad (5.3)$$

Or in other words,

$$da = |\mathcal{D}|\bar{d}a + \delta(a)F. \quad (5.4)$$

Since \mathcal{D} is invertible, $|\mathcal{D}|$ is invertible. Thus,

$$\bar{d}a = |\mathcal{D}|^{-1}da + |\mathcal{D}|^{-1}\delta(a)F.$$

By assumption, $da, \delta(a) \in \mathcal{B}(\mathcal{H})$. Thus, since $(\mathcal{A}, \mathcal{H}, \mathcal{D})$ is (p, ∞) -summable, $|\mathcal{D}|^{-1} \in \mathcal{L}^{p,\infty}$. Hence, $\bar{d}a \in \mathcal{L}^{p,\infty}$. \square

Chapter 6

Higher Dimensions

6.1 Introduction

Let $d > 0$ be a positive integer. Let \mathcal{A}_λ be the d -dimensional non-commutative torus, introduced in Appendix ??.

\mathcal{A}_λ has a unique normalised trace τ . The Hilbert space $L^2(\mathcal{A}_\lambda, \tau)$ has orthonormal basis $\{u(n)\}_{n \in \mathbb{Z}^d}$ where $u(n) = U_1^{n_1} U_2^{n_2} \cdots U_d^{n_d}$.

Define $\omega_{j,k}$ for $j, k \in \mathbb{Z}^d$ to be such that $u(j)u(k) = \omega_{j,k}u(k+j)$.

Given $f \in L^2(\mathcal{A}_\lambda, \tau)$, we define

$$\hat{f}(n) := \tau(fu(n)^*). \quad (6.1)$$

Then we have

$$f = \sum_{k \in \mathbb{Z}^d} \hat{f}(k)u(k), \quad (6.2)$$

which converges in the L^2 -sense. Note that $\tau(f) = \hat{f}(0)$.

For a function $F : \mathbb{Z}^d \rightarrow \mathbb{R}$, define $F(D)u(k) = F(k)u(k)$ as a densely defined linear operator on $L^2(\mathcal{A}_\lambda, \tau)$.

It is easy to see that $F(D)$ is bounded on $L^2(\mathcal{A}_\lambda, \tau)$ if and only if $F \in \ell^\infty(\mathbb{Z}^d)$, with operator norm $\|F\|_\infty$.

We shall identify $u(n) \in \mathcal{A}_\lambda$ with the multiplication operator $M_{u(n)}f = u(n)f$ for $f \in L^2(\mathcal{A}_\lambda, \tau)$

6.2 Commutators

Let $n \in \mathbb{Z}^d$. We are interested in $[F(D), u(n)]$.

Let $f \in L^2(\mathcal{A}_\lambda, \tau)$.

Then,

$$u(n)f = \sum_{k \in \mathbb{Z}^d} \hat{f}(k)u(n)u(k) \quad (6.3)$$

$$= \sum_{k \in \mathbb{Z}^d} \hat{f}(k)\omega_{n,k}u(n+k). \quad (6.4)$$

Hence,

$$F(D)u(n)f = \sum_{k \in \mathbb{Z}^d} \hat{f}(k)\omega_{n,k}F(n+k)u(n+k). \quad (6.5)$$

Now we compute,

$$u(n)F(D)f = \sum_{k \in \mathbb{Z}^d} \hat{f}(k)F(k)\omega_{n,k}u(n+k). \quad (6.6)$$

Thus,

$$[F(D), u(n)]f = \sum_{k \in \mathbb{Z}^d} \hat{f}(k)(F(n+k) - F(k))\omega_{n,k}u(n+k). \quad (6.7)$$

We can simplify this further,

$$[F(D), u(n)]f = \sum_{k \in \mathbb{Z}^d} \hat{f}(k)(F(n+k) - F(k))u(n)u(k) \quad (6.8)$$

$$= u(n) \sum_{k \in \mathbb{Z}^d} \hat{f}(k)F(n+k)u(k) - u(n) \sum_{k \in \mathbb{Z}^d} \hat{f}(k)F(k)u(k) \quad (6.9)$$

$$= u(n)F(n+D)f - u(n)F(D)f \quad (6.10)$$

$$= u(n)F(n+D)f - u(n)F(D)f \quad (6.11)$$

So $[F(D), u(n)] = u(n)(F(n+D) - F(D))$.

6.3 Hilbert-Schmidt Commutators

It is of interest to ask when $[F(D), u(n)] \in \mathcal{L}^2$. This is equivalent to,

$$\|[F(D), u(n)]\|_2^2 := \sum_{j,k \in \mathbb{Z}^d} |\tau(u(j)^*[F(D), u(n)]u(k))|^2 < \infty. \quad (6.12)$$

So we compute,

$$[F(D), u(n)]u(k) = u(n)F(n+D)u(k) - u(n)F(D)u(k) \quad (6.13)$$

$$= u(n)F(n+k)u(k) - u(n)F(k)u(k) \quad (6.14)$$

$$= (F(n+k) - F(k))u(n)u(k). \quad (6.15)$$

Hence,

$$|\tau(u(j)^*[F(D), u(n)]u(k))| = |F(n+k) - F(k)| |\tau(u(j)^*u(n)u(k))| \quad (6.16)$$

$$= |F(n+k) - F(k)| \delta_{j,n+k} \quad (6.17)$$

$$(6.18)$$

So therefore

$$\|[F(D), u(n)]\|_2^2 = \sum_{j,k \in \mathbb{Z}^d} |F(n+k) - F(k)|^2 \delta_{j,n+k} \quad (6.19)$$

$$= \sum_{k \in \mathbb{Z}^d} |F(n+k) - F(k)|^2. \quad (6.20)$$

So we have necessary and sufficient conditions for $[F(D), u(n)] \in \mathcal{L}^2$.

6.4 Membership of \mathcal{L}^p

We can see that since $F(D)$ and $F(n+D)$ are self adjoint,

$$[F(D), u(n)]^* = (F(n+D) - F(D))u(n)^* \quad (6.21)$$

Hence,

$$[F(D), u(n)]^*[F(D), u(n)] = (F(n+D) - F(D))^2. \quad (6.22)$$

Hence,

$$|[F(D), u(n)]| = |F(n+D) - F(D)|. \quad (6.23)$$

Now,

$$\text{Tr}(|[F(D), u(n)]|^p) = \sum_{k \in \mathbb{Z}^d} \tau(u(k)^* |F(D+n) - F(D)|^p u(k)) \quad (6.24)$$

$$= \sum_{k \in \mathbb{Z}^d} \tau(u(k)^* |F(k+n) - F(k)|^p u(k)) \quad (6.25)$$

$$= \sum_{k \in \mathbb{Z}^d} |F(k+n) - F(k)|^p. \quad (6.26)$$

Hence, for any $p > 0$, we have $[F(D), u(n)] \in \mathcal{L}^p$ if and only if $\{F(k+n) - F(k)\} \in \ell^p(\mathbb{Z}^d)$ with an equality of (quasi-)norms.

6.5 Double commutators

We are also interested in the properties of the double commutators,.

$$[[F(D), u(n)], u(n)]$$

for $n \in \mathbb{Z}^d$. By equation 6.11, this is

$$[[F(D), u(n)], u(n)] = [F(D), u(n)]u(n) - u(n)[F(D), u(n)] \quad (6.27)$$

$$= u(n)(F(n+D) - F(D))u(n) - u(n)u(n)(F(D+n) - F(D)) \quad (6.28)$$

$$= (F(D) - F(D-n))u(n)^2 - (F(D-n) - F(D-2n))u(n)^2 \quad (6.29)$$

$$= (F(D-2n) - 2F(D-n) + F(D))u(n)^2 \quad (6.30)$$

$$= u(n)(F(D+n) - 2F(D) + F(D-n))u(n). \quad (6.31)$$

Hence,

$$|[[F(D), u(n)], u(n)]| = |F(D+2n) - 2F(D+n) + F(D)|.$$

So we have $[[F(D), u(n)], u(n)] \in \mathcal{L}^p$ if and only if $\{F(k+n) - 2F(k) + F(k-n)\}_{k \in \mathbb{Z}^d} \in \ell^p(\mathbb{Z}^d)$.

Appendix A

Classical Harmonic Analysis

A.1 Introduction

Given a function $f : \mathbb{T} \rightarrow \mathbb{C}$, we have an associated Fourier series,

$$f \sim \sum_{n \in \mathbb{Z}} \hat{f}(n) z^n \tag{A.1}$$

where $z : \mathbb{T} \rightarrow \mathbb{T}$ is the identity function, and

$$\hat{f}(n) = \int_{\mathbb{T}} z^{-n} f \, d\mathbf{m} \tag{A.2}$$

where \mathbf{m} is the normalised Haar (or arc length) measure on \mathbb{T} . Implicitly f is sufficiently regular so that these Fourier coefficients exist.

I have used the symbol “ \sim ” rather than an equals sign, since in general we do not have equality. In general, for $f \in L^1(\mathbb{T}, \mathbf{m})$, the Fourier series might diverge almost everywhere if it is interpreted as a sum.

However, if one turns to alternative methods of summation, it is possible to interpret \sim as an equality.

Here we consider Abel summation.

A.2 Abel summation

Abel summation is inspired by Abel’s theorem, which we prove now.

Proposition A.1. *Suppose that*

$$f(z) = \sum_{n=0}^{\infty} a_n z^n$$

is a power series converging in $\{z \in \mathbb{C} : |z| < 1\}$ such that the coefficients come from a Banach space $(X, \|\cdot\|)$. Suppose further that the sum

$$\sum_{n=0}^{\infty} a_n$$

converges. Then,

$$\lim_{z \rightarrow 1^-} f(z) = \sum_{n=0}^{\infty} a_n.$$

where by $z \rightarrow 1^-$, we mean that z is restricted to the subset of the unit disc where $|1 - z| \leq M(1 - |z|)$ for some constant M .

Proof. Assume without loss of generality that

$$\sum_{n=0}^{\infty} a_n = 0.$$

Now define

$$s_k = \sum_{n=0}^k a_n$$

and $s_{-1} = 0$. Then we have

$$f(z) = \sum_{n=0}^{\infty} (s_n - s_{n-1})z^n.$$

so

$$f(z) = (1 - z) \sum_{k=0}^{\infty} s_k z^k.$$

Let $\varepsilon > 0$, and choose n large enough such that $\|s_k\| < \varepsilon$ for $k > n$. Then we have

$$\left\| (1 - z) \sum_{k=n}^{\infty} s_k z^k \right\| \leq \varepsilon |1 - z| \sum_{k=n}^{\infty} |z|^k = \varepsilon |1 - z| \frac{|z|^n}{1 - |z|} \leq M\varepsilon.$$

When z is sufficiently close to 1, we have

$$\left\| (1 - z) \sum_{k=0}^{n-1} s_k z^k \right\| < \varepsilon.$$

Hence, for z sufficiently close to 1, we have

$$\|f(z)\| < (M + 1)\varepsilon.$$

□

With this in mind, we define the Abel summation method.

Definition A.2. Let $\{a_k\}_{k=0}^{\infty} \subset X$ be a sequence in a Banach space $(X, \|\cdot\|)$. Suppose that for all $r \in (1 - \varepsilon, 1)$, for some $\varepsilon > 0$ we have

$$\sum_{k=0}^{\infty} a_k r^k$$

exists. Then we define the Abel sum, denoted by,

$$A - \sum_{k=0}^{\infty} a_k$$

as

$$A - \sum_{k=0}^{\infty} a_k := \lim_{r \rightarrow 1^-} \sum_{k=0}^{\infty} a_k r^k.$$

if this limit exists.

Abel's theorem automatically implies that the Abel sum of a series agrees with the usual sum, however there are series which are summable in the Abel sense but not the classical sense. It is easy to see that,

$$A - \sum_{n=0}^{\infty} (-1)^n = \lim_{r \rightarrow 1^-} \sum_{n=0}^{\infty} (-r)^n = \lim_{r \rightarrow 1^-} \frac{1}{1+r} = \frac{1}{2}.$$

A.3 The Poisson Kernel

To sum a Fourier series in the Abel sense, an important technical tool is the Poisson Kernel, which we introduce in this section.

Given $f \in L^1(\mathbb{T}, \mathbf{m})$, define

$$A_r f := \sum_{n \in \mathbb{Z}} r^{|n|} \hat{f}(n) z^n.$$

with $r \in (0, 1)$. $A_r f$ exists since the Fourier coefficients of f are bounded. By definition,

$$A - \sum_{n \in \mathbb{Z}} \hat{f}(n) z^n = \lim_{r \rightarrow 1^-} A_r f.$$

where the limit is taken in an appropriate Banach space.

Like with classical and Cesàro sums, Abel sums can be constructed with a convolution.

Proposition A.3. *We can write,*

$$A_r f = P_r * f.$$

where

$$P_r = 1 + \frac{rz}{1-rz} + \frac{r}{z-r}$$

Proof. The Fourier coefficients of $A_r f$ are the Fourier coefficients of f multiplied by the coefficients of

$$\sum_{n \in \mathbb{Z}} r^{|n|} z^n.$$

Hence define

$$P_r = \sum_{n \in \mathbb{Z}} r^{|n|} z^n.$$

The result follows from summing this geometric series. \square

The reason for the superiority of Abel summation over classical summation is that the Poisson kernels form an approximate identity.

Proposition A.4. *The Poisson kernels $\{P_r\}_{r \in (0,1)}$ form an approximate identity.*

Proof. By the formula,

$$P_r = \sum_{n \in \mathbb{Z}} r^{|n|} z^n,$$

we have

$$\int_{\mathbb{T}} P_r d\mathbf{m} = 1.$$

To complete the proof, we convert to coordinates. Let $z = \exp(2\pi i\theta)$, for $\theta \in (-1/2, 1/2)$, and we can regard P_r as a function of θ .

Then we have

$$\begin{aligned} P_r(\theta) &= 1 + \frac{re^{2\pi i\theta}}{1-re^{2\pi i\theta}} + \frac{re^{-2\pi i\theta}}{1-re^{-2\pi i\theta}} \\ &= 1 + \frac{re^{2\pi i\theta}(1-re^{-2\pi i\theta}) + re^{-2\pi i\theta}(1-re^{2\pi i\theta})}{(1-re^{2\pi i\theta})(1-re^{-2\pi i\theta})} \\ &= 1 + \frac{2r \cos(2\pi\theta) - 2r^2}{1+r^2-2r \cos(2\pi\theta)} \\ &= \frac{1-r^2}{1-2r \cos(2\pi\theta) + r^2} \end{aligned}$$

Let $\delta > 0$. Now we estimate,

$$\int_{\delta}^{1/2} P_r(\theta) d\theta \leq \int_{\delta}^{1/2} \frac{1-r^2}{1-2r \cos(2\pi\delta) + r^2} d\theta \leq \frac{1-r^2}{1-2r \cos(2\pi\delta) + r^2}$$

Hence this integral vanishes as $r \rightarrow \infty$.

Moreover, we have

$$1-2r \cos(2\pi\theta) + r^2 \geq (1-r)^2.$$

Hence $P_r \geq 0$. Therefore, $\|P_r\|_1 = 1$.

Thus the Poisson kernels form an approximate identity. \square

As a consequence of this, we have

1. If $f \in C(\mathbb{T})$, then $A_r f \rightarrow f$ uniformly.
2. If $f \in L^p(\mathbb{T}, \mathbf{m})$, for $1 \leq p < \infty$, we have $A_r f \rightarrow f$ in the L^p sense.

Hence, if $f \in L^1(\mathbb{T}, \mathbf{m})$, we have

$$f(\zeta) = A - \sum_{n \in \mathbb{Z}} \hat{f}(n) \zeta^n$$

for almost all $\zeta \in \mathbb{T}$.

A.4 Fourier Series of Measures

Suppose μ is a complex Borel regular measure on \mathbb{T} . Associated to μ is a Fourier series,

$$\mu \sim \sum_{n \in \mathbb{Z}} \hat{\mu}(n) z^n$$

where

$$\hat{\mu}(n) = \int_{\mathbb{T}} z^{-n} d\mu.$$

It was proved in ‘‘Cesàro convergence of Fourier series’’ that this series can be interpreted as a sequence of measures converging in the Cesàro sense and the weak* topology to μ . Here we wish to analyse the Abel sums of the Fourier series of μ . Define for $r \in (0, 1)$,

$$A_r \mu = \sum_{n \in \mathbb{Z}} r^{|n|} \hat{\mu}(n) z^n.$$

This series converges because μ is bounded, so the Fourier coefficients are bounded.

Recall that if $f \in C(\mathbb{T})$, we define $f * \mu$ as the function

$$(f * \mu)(\zeta) := \int_{\mathbb{T}} f(\zeta \tau^{-1}) d\mu(\tau).$$

This allows us to compute $A_r \mu$ for a measure μ :

Proposition A.5. *If μ is a complex Borel regular measure on \mathbb{T} , then*

$$A_r \mu = P_r * \mu.$$

Proof. We compute,

$$\begin{aligned} (P_r * \mu)(\zeta) &= \int_{\mathbb{T}} \sum_{n \in \mathbb{Z}} r^{|n|} \zeta^n \tau^{-n} d\mu(\tau) \\ &= \sum_{n \in \mathbb{Z}} \zeta^n r^{|n|} \int_{\mathbb{T}} \tau^{-n} d\mu(\tau). \end{aligned}$$

The interchange of the integral and summation is justified by the uniform convergence of the sum defining P_r . Hence we have $A_r \mu = P_r * \mu$. \square

Recall that a sequence of measures $\{\mu_n\}_{n=0}^{\infty}$ converges in the weak* sense if for any $f \in C(\mathbb{T})$, we have $\int_{\mathbb{T}} f d\mu_n \rightarrow \int_{\mathbb{T}} f d\mu$. Any $f \in L^1(\mathbb{T})$ can be interpreted as a measure μ_f , by $d\mu_f = f d\mathbf{m}$.

Proposition A.6. *Let μ be a complex Borel regular measure on \mathbb{T} . The functions $\{A_r \mu\}_{r \in (0,1)}$, interpreted as measures, converge in the weak* sense to μ as $r \rightarrow 1^-$.*

Proof. Let $f \in C(\mathbb{T})$. We compute,

$$\begin{aligned} \int_{\mathbb{T}} f d\mu_{A_r \mu} &= \int_{\mathbb{T}} f P_r * \mu d\mathbf{m} \\ &= \int_{\mathbb{T}} \int_{\mathbb{T}} f(\zeta) P_r(\zeta \tau^{-1}) d\mu(\tau) d\mathbf{m}(\zeta). \end{aligned}$$

However note that $P_r(\tau) = P_r(\tau^{-1})$, so by Fubini's theorem,

$$\begin{aligned} \int_{\mathbb{T}} f d\mu_{A_r \mu} &= \int_{\mathbb{T}} \int_{\mathbb{T}} P_r(\tau \zeta^{-1}) f(\zeta) d\mathbf{m}(\zeta) d\mu(\tau) \\ &= \int_{\mathbb{T}} P_r * f d\mu. \end{aligned}$$

However, since f is continuous, we have that $P_r * f \rightarrow f$ uniformly as $r \rightarrow 1^-$. Hence

$$\lim_{r \rightarrow 1^-} \int_{\mathbb{T}} f d\mu_{A_r \mu} = \int_{\mathbb{T}} f d\mu$$

So $A_r \mu$ converges in the weak* sense to μ . \square

A.5 Harmonic functions on \mathbb{D}

Abel summation is much more heavily studied than Cesàro summation. The reason for this is that there is a close connection between the Abel sums $A_r f$ for a function f on \mathbb{T} , and functions on $\mathbb{D} := \{z \in \mathbb{C} : |z| < 1\}$ which are *harmonic*.

Given $f \in L^1(\mathbb{T})$, define $\tilde{f} : \mathbb{D} \rightarrow \mathbb{C}$ by

$$\tilde{f}(r\zeta) = A_r f(\zeta) = (P_r * f)(\zeta)$$

for $r \in [0, 1]$ and $\zeta \in \mathbb{T}$.

Note that, by Young's convolution inequality,

$$\left(\int_{\mathbb{T}} |\tilde{f}(r\zeta)|^p d\mathbf{m}(\zeta) \right)^{1/p} \leq \|P_r\|_1 \|f\|_p.$$

Hence,

$$\sup_{r \in [0, 1]} \left(\int_{\mathbb{T}} |\tilde{f}(r\zeta)|^p d\mathbf{m}(\zeta) \right)^{1/p} \leq \|f\|_p.$$

This motivates the definition of the *Hardy spaces*:

Definition A.7 (Hardy Spaces). Let $p \in (0, \infty]$. For $p < \infty$, let $H^p(\mathbb{T})$ denote the space of complex valued functions f which are complex differentiable in the open unit disc such that

$$\|f\|_{H^p} := \sup_{r \in [0, 1)} \left(\int_{\mathbb{T}} |f(r\zeta)|^p d\mathbf{m}(\zeta) \right)^{1/p} < \infty. \quad (\text{A.3})$$

For $p = \infty$, instead we require

$$\|f\|_{H^\infty} := \sup_{\zeta \in \mathbb{D}} |f(\zeta)| < \infty.$$

The link between Abel summation and Hardy spaces is provided by the following theorems, proved in [9]:

Theorem A.8. Let $f \in L^p(\mathbb{T})$, for $p \in [1, \infty]$. Then $\tilde{f} \in H^p(\mathbb{T})$ if and only if $\hat{f}(n) = 0$ for $n < 0$.

Theorem A.9. Let $f \in H^p(\mathbb{T})$, for $p \in [1, \infty]$. Then, for almost all $\zeta \in \mathbb{T}$, the limit

$$\lim_{r \rightarrow 1^-} f(r\zeta)$$

exists, and defines a function in $L^p(\mathbb{T})$.

Combining theorems A.8 and A.9, we have the following result, also proved in [9]

Theorem A.10. Let $p \in [1, \infty]$. The space $H^p(\mathbb{T})$ embeds isometrically into the subspace of $L^p(\mathbb{T})$ consisting of those f with $\hat{f}(n) = 0$ for $n < 0$. The embedding ι is given by, for $f \in H^p(\mathbb{T})$

$$\iota(f)(\zeta) = \lim_{r \rightarrow 1^-} f(r\zeta) \quad (\text{A.4})$$

for almost all $\zeta \in \mathbb{T}$.

The map $f \mapsto \tilde{f}$, when restricted to the subspace of f with $\hat{f}(n) = 0$ for $n < 0$, is the inverse of ι .

Appendix B

Lorentz Spaces

B.1 Introduction

Lorentz spaces form a broad generalisation of L^p spaces and weak L^p spaces. These notes cover the basic definitions.

B.2 Weak L^p -spaces

Let (X, \mathcal{A}, μ) be a σ -finite measure space. Given a measurable function $f : X \rightarrow \mathbb{C}$, we may define the distribution function

$$d_f(\alpha) = \mu\{x \in X : |f(x)| \geq \alpha\}.$$

for $\alpha \geq 0$.

By Markov's inequality, for $p > 0$,

$$d_f(\alpha) \leq \frac{\|f\|_p^p}{\alpha^p}.$$

The linear span of the class of functions f for which

$$d_f(\alpha) \leq \frac{C^p}{\alpha^p}$$

for some constant C is called the weak L^p space or $L^{p,w}(X)$. Given $f \in L^{p,w}(X)$, define

$$\|f\|_{p,w} := \sup_{\alpha > 0} \alpha d_f(\alpha)^{1/p}.$$

B.3 Non-increasing Rearrangements

Again let (X, \mathcal{A}, μ) be a σ -finite measure space, and $f : X \rightarrow \mathbb{C}$ is measurable. Then define, for $t \geq 0$,

$$f^*(t) = \inf\{s \geq 0 : d_f(s) \leq t\}.$$

f^* is called the non-increasing rearrangement of f .

Lemma B.1.

$$\left(\int_X |f|^p d\mu \right)^{1/p} = \left(\int_0^\infty (f^*)^p d\mu \right)^{1/p}$$

Lemma B.2.

$$\sup_{t>0} t^q f^*(t) = \sup_{\alpha>0} \alpha d_f(\alpha)^{1/p}.$$

Inspired by the above two results is the following definition,

Definition B.3 (Lorentz spaces). Let $p, q > 0$. For a σ -finite measure space (X, \mathcal{A}, μ) , and a measurable function $f : X \rightarrow \mathbb{C}$, define

$$\|f\|_{p,q} = \left(\int_0^\infty (t^{1/p} f^*(t))^q \frac{dt}{t} \right)^{1/q}$$

and

$$\|f\|_{p,\infty} = \sup_{t \geq 0} t^{1/p} f^*(t).$$

B.4 Discrete spaces

When X is a set with counting measure, the $L^{p,q}$ spaces are denoted $\ell^{p,q}(X)$.

Appendix C

Interpolation

C.1 Introduction

The method of interpolation is a very powerful one in analysis, and it allows many results to be obtained from “edge” cases.

Historically, interpolation is motivated by the Riesz-Thorin theorem, which we state here.

Theorem C.1. *Let $p_0, q_0 \in [1, \infty]$ and $p_1, q_1 \in [1, \infty]$ with $p_0 \neq p_1$ and $q_0 \neq q_1$. Suppose that (U, μ) and (V, ν) are measure spaces. Let T be an operator such that*

$$T : L^{p_0}(U) \rightarrow L^{q_0}(V)$$

with norm M_0 and

$$T : L^{p_1}(U) \rightarrow L^{q_1}(V)$$

with norm M_1 .

Let $\theta \in (0, 1)$, and $p_\theta^{-1} = \theta p_0^{-1} + (1 - \theta)p_1^{-1}$, and $q_\theta^{-1} = \theta q_0^{-1} + (1 - \theta)q_1^{-1}$.

Then,

$$T : L^{p_\theta}(U) \rightarrow L^{q_\theta}(V)$$

with norm $M \leq M_0^\theta M_1^{1-\theta}$.

This theorem can be proved directly, however it is more insightful to prove it using abstract interpolation theory. The purpose of these notes is to introduce this theory.

C.2 Abstract Interpolation Theory

Let \mathbf{NLS} be the category of normed linear spaces with morphisms given by bounded linear maps.

Definition C.2. A pair $X, Y \in \mathbf{NLS}$ is called a compatible pair if X and Y are both subspaces of a topological vector space U .

Definition C.3. The category \mathbf{NLS}_1 is the category of compatible pairs (X, Y) of normed spaces, where a morphism $T : (X_1, Y_1) \rightarrow (X_2, Y_2)$ is a linear map $T : X_1 + Y_1 \rightarrow X_2 + Y_2$ such that $T : X_1 \rightarrow X_2$ and $T : Y_1 \rightarrow Y_2$ is bounded.

Proposition C.4. Let $\Delta : \mathbf{NLS}_1 \rightarrow \mathbf{NLS}$ be the function that maps (X, Y) to $X \cap Y$, where $X \cap Y$ is given the norm,

$$\|x\|_{X \cap Y} = \max\{\|x\|_X, \|x\|_Y\}.$$

Let $\Sigma : \mathbf{NLS}_1 \rightarrow \mathbf{NLS}$ be given by $\Sigma((X, Y)) = X + Y$, where $X + Y$ is given the norm,

$$\|x\|_{X+Y} = \inf\{\|x_1\|_X + \|x_2\|_Y : x = x_1 + x_2, x_1 \in X, x_2 \in Y\}.$$

Then Δ and Σ are functors.

Definition C.5. An interpolation functor is a functor $\mathcal{F} : \mathbf{NLS}_1 \rightarrow \mathbf{NLS}$ such that for $(X, Y) \in \mathbf{NLS}_1$, we have

$$\Delta((X, Y)) \subseteq \mathcal{F}((X, Y)) \subseteq \Sigma((X, Y))$$

We say that an interpolation functor \mathcal{F} is *uniform* if for any morphism $T : (X_1, Y_1) \rightarrow (X_2, Y_2)$ in \mathbf{NLS}_1 , we have

$$\|\mathcal{F}(T)\| \leq C \max\{\|T\|_{X_1 \rightarrow X_2}, \|T\|_{Y_1 \rightarrow Y_2}\}.$$

for some constant $C > 0$. If $C = 1$, we say that \mathcal{F} is *exact*.

We say that an interpolation functor \mathcal{F} is of exponent $\theta \in (0, 1)$ if

$$\|\mathcal{F}(T)\| \leq C \|T\|_{X_1 \rightarrow X_2}^\theta \|T\|_{Y_1 \rightarrow Y_2}^{1-\theta}.$$

for some constant $C > 0$. If $C = 1$, we say that \mathcal{F} is *exact of exponent θ* .

C.3 Real Interpolation: The K Method

Definition C.6. Let $(X_0, X_1) \in \mathbf{NLS}_1$. For $x \in X_0 + X_1$ and $t > 0$, define

$$K(x, t; X_0, X_1) = \inf \{ \|x_0\| + t\|x_1\| : x_0 \in X_0, x_1 \in X_1, x = x_0 + x_1 \}.$$

Then for $\theta \in (0, 1)$ and $q \in [1, \infty)$, define

$$\|x\|_{\theta, q; K} := \left(\int_0^\infty (t^{-\theta} K(x, t; X_0, X_1))^q \frac{dt}{t} \right)^{1/q}$$

and for $\theta \in [0, 1]$,

$$\|x\|_{\theta, \infty; K} := \sup_{t>0} t^{-\theta} K(x, t; X_0, X_1).$$

The space $K_{\theta, q}(X_0, X_1)$ is the set of $x \in X_0 + X_1$ such that $\|x\|_{\theta, q; K} < \infty$.

Proposition C.7. *The function $(X, Y) \mapsto K_{\theta, q}(X, Y)$ is an exact interpolation functor of order θ .*

C.4 Complex Interpolation

Definition C.8. Let (X_0, X_1) be a compatible pair of Banach spaces. Let $\mathcal{S} := \{z \in \mathbb{C} : \Re(z) \in (0, 1)\}$.

Define the set $\mathcal{F}(X_0, X_1)$ to be the space of functions $f : \overline{\mathcal{S}} \rightarrow X_0 + X_1$ which are complex differentiable in \mathcal{S} , continuous on $\overline{\mathcal{S}}$ and bounded on $\partial\mathcal{S}$.

It is true that $\mathcal{F}(X_0, X_1)$ is a Banach space under the norm,

$$\|f\|_{\mathcal{F}(X_0, X_1)} = \max \left\{ \sup_{t \in \mathbb{R}} \|f(it)\|, \sup_{t \in \mathbb{R}} \|f(1+it)\| \right\}.$$

Let $\theta \in (0, 1)$. Then, define

$$(X_0, X_1)_\theta = \{f(\theta) : f \in \mathcal{F}(X_0, X_1)\}.$$

We define the norm,

$$\|x\|_{(X_0, X_1)_\theta} = \inf \{ \|f\|_{\mathcal{F}(X_0, X_1)} : x = f(\theta) \}.$$

Proposition C.9. *The mapping $(X_0, X_1) \rightarrow (X_0, X_1)_\theta$ is an interpolation functor, which is exact of exponent θ .*

C.5 Using interpolation

Once we know how to describe certain interpolation spaces, results such as the Riesz-Thorin theorem become immediate.

Proposition C.10. *Let X be a measure space. Let $p_0, p_1 \in [1, \infty]$, and $p_\theta^{-1} = \theta p_0^{-1} + (1 - \theta)p_1^{-1}$ for $\theta \in (0, 1)$. Then*

$$(L^{p_0}(X), L^{p_1}(X))_\theta = L^{p_\theta}(X).$$

Another immediate corollary:

Proposition C.11. *Let G be a locally compact group abelian group equipped with bi-variant Haar measure μ , and $p \in [1, \infty]$. For $\varphi \in L^1(G, \mu)$, the map $Tf = \varphi * f$ is bounded on $L^p(G, \mu)$, with norm less than or equal to $\|\varphi\|_1$.*

Proof. To prove the case $p = 1$, we let $f \in L^p(G)$, and compute,

$$\begin{aligned} \|\varphi * f\|_1 &= \int_G \left| \int_G \varphi(x - y) f(y) d\mu(y) \right| d\mu(x) \\ &\leq \int_G \int_G |\varphi(x - y)| |f(y)| d\mu(y) d\mu(x) \\ &= \|\varphi\|_1 \|f\|_1 \end{aligned}$$

where the interchange of integrals is justified by Tonelli's theorem.

Now for $p = \infty$, we compute,

$$\|\varphi * f\|_\infty = \text{ess-sup}_{x \in G} \left| \int_G \varphi(x - y) f(y) d\mu(y) \right|$$

By Hölder's inequality, this can be bounded by $\|\varphi\|_1 \|f\|_\infty$.

The rest of the cases follow from complex interpolation of the pair $(L^1(G, \mu), L^\infty(G, \mu))$. □

Appendix D

Dirac Operators

D.1 Introduction

This chapter is intended to give an introduction to the relationship between the Dirac operator and the exterior algebra. The general philosophy is that any expressions involving coordinates are to be avoided.

Throughout these notes, (M, g) is a Riemannian manifold.

D.2 Music, Clifford bundles and Modules

A metric g on a manifold M gives us a canonical isomorphism between T^*M and TM , called \sharp , pronounced “sharp”. For $x \in M$, given a linear functional $\omega \in T_x^*M$ we define $\sharp\omega$ to be the unique vector such that $\omega(v) = g(\sharp\omega, v)$ for all $v \in T_xM$. This is called the “musical isomorphism”.

The Clifford bundle of (M, g) is a vector bundle on M defined as follows.

Definition D.1. Let $x \in M$. The clifford algebra at x , $\text{Cliff}_x(M, g)$ is defined as the free associative unital algebra generated by T_xM modulo the relation

$$uv + vu = -2g(u, v)1 \tag{D.1}$$

where $u, v \in \text{Cliff}_x(M, g)$, and 1 is the identity in $\text{Cliff}_x(M, g)$.

The clifford bundle $\text{Cliff}(M, g)$ is the vector bundle on M whose fibres are $\text{Cliff}_x(M, g)$.

Let's not care about the topology on $\text{Cliff}(M, g)$ at the moment.

There is clearly an embedding $TM \hookrightarrow \text{Cliff}(M, g)$.

Now for a vector bundle V on M , we say that V is a clifford module if there is a right multiplication map $\gamma : \text{Cliff}(M, g) \otimes V \rightarrow V$.

A *connection* on V is a linear map

$$\nabla : V \rightarrow T^*M \otimes V. \quad (\text{D.2})$$

satisfying the Leibniz rule, for $f \in C^\infty(M)$ and $v \in V$,

$$\nabla(fv) = df \otimes v + f\nabla(v). \quad (\text{D.3})$$

Now we may define a *Dirac operator*. Suppose V is a clifford bundle with connection ∇ . Then the composition of linear maps,

$$V \xrightarrow{\nabla} T^*M \otimes V \xrightarrow{\sharp \otimes I} TM \otimes V \xrightarrow{\gamma} V \quad (\text{D.4})$$

is called the Dirac operator associated with V and ∇ .

D.3 Relationship with differentials

Suppose we have a clifford bundle V with connection ∇ .

Via the musical isomorphism, we may regard any differential form $\omega \in \Gamma(T^*M)$ as an operator on $\Gamma(V)$, since $\sharp(\omega)$ is an element of $\Gamma(\text{Cliff}(M, g))$, it may act on V .

Similarly, by pointwise multiplication, any $f \in C^\infty(M)$ is an operator on $\Gamma(V)$.

Theorem D.2. *We have an equality of operators on $\Gamma(V)$,*

$$[D, f] = df. \quad (\text{D.5})$$

for any $f \in C^\infty(M)$.

Proof. Let $f \in C^\infty(M)$ and $v \in \Gamma(V)$. Let us compute $D(fv)$.

By definition,

$$D(fv) = (\gamma \circ (\sharp \otimes I) \circ \nabla)(fv). \quad (\text{D.6})$$

By the Leibniz rule,

$$(\sharp \otimes I)\nabla(fv) = \sharp(df) \otimes v + (I \otimes f)(\sharp \otimes 1)\nabla(v). \quad (\text{D.7})$$

Hence,

$$D(fv) = \gamma(\sharp(df))v + fD(v). \quad (\text{D.8})$$

Therefore, $[D, f]v = df(v)$. \square

Appendix E

Ideals Of Compact Operators

E.1 Two-sided Ideals

In what follows, let \mathcal{H} be a separable complex infinite dimensional Hilbert space.

Definition E.1. A linear subspace \mathcal{J} of $\mathcal{B}(\mathcal{H})$ is called a two sided ideal if for any $A \in \mathcal{J}$ and $B \in \mathcal{B}(\mathcal{H})$, we have $AB, BA \in \mathcal{J}$.

In this thesis we have been majorly concerned with ideals of compact operators. Recall that for a compact operator $T \in \mathcal{K}(\mathcal{H})$, the sequence $\{\mu_n(T)\}_{n=0}^{\infty}$ of singular values is a sequence of positive numbers vanishing towards zero. Let $\mu : \mathcal{K}(\mathcal{H}) \rightarrow c_0(\mathbb{N})$ denote the mapping $T \mapsto \{\mu_n(T)\}$.

If we regard compact operators as infinitesimals, we determine the “size” of an infinitesimal T (i.e. a compact operator) in terms of the rate of decay of $\mu(T)$.

It turns out that there is an extremely useful description of ideals of compact operators in terms of sequences of singular values.

E.2 The Calkin Correspondence

Definition E.2. For a sequence $x \in c_0(\mathbb{N})$, let x^* denote the non-increasing rearrangement (see Appendix B for details).

A subspace $J \subseteq c_0(\mathbb{N})$ is called a *calkin space* if for any positive sequences $x, y \in c_0(\mathbb{N})$, with $x^* \leq y^*$ (componentwise), and $y \in J$, then $x \in J$.

The following is proved in [10].

Proposition E.3 (The Calkin Correspondence). *Let \mathcal{J} be a two-sided ideal of compact operators on \mathcal{H} . Associate to \mathcal{J} the following subset of $c_0(\mathbb{N})$,*

$$J_+ = \{\mu(T) : T \in \mathcal{J}\}. \quad (\text{E.1})$$

Denote by J the linear subspace of $c_0(\mathbb{N})$ generated by J_+ .

Then J is a Calkin space.

Conversely, given a Calkin space J , we construct an ideal \mathcal{J} as follows. For a sequence $x \in c_0(\mathbb{N})$, let $\text{Diag}(x)$ denote the operator on \mathcal{H} that is a diagonal matrix with n th diagonal entry x_n with respect to a given fixed orthonormal basis $\{e_n\}_{n=0}^\infty$ of \mathcal{H} . Let \mathcal{S} be the subset of $\mathcal{K}(\mathcal{H})$ given by

$$\mathcal{S} = \{\text{Diag}(x) : x \in J\}. \quad (\text{E.2})$$

Let \mathcal{J} be the ideal generated by \mathcal{S} .

The correspondence $J \leftrightarrow \mathcal{J}$ is a bijection between Calkin spaces and ideals of compact operators.

E.3 Lorentz and Macaev Ideals

The Calkin correspondence inspires the definitions of a vast array of ideals:

Definition E.4. The space $\mathcal{L}^{p,q} \subseteq \mathcal{K}(\mathcal{H})$ is the linear span of all positive operators T such that $\mu(T) \in \ell^{p,q}$ (see appendix B for the definition of $\ell^{p,q}$).

Definition E.5. The space $m_{1,\infty} \subseteq c_0(\mathbb{N})$ is defined to be the set formed by the linear span of all positive sequences x such that

$$\sup_{N \geq 0} \left\{ \frac{1}{\log(N+1)} \sum_{n=0}^N x_n \right\} < \infty. \quad (\text{E.3})$$

The ideal $\mathcal{M}_{1,\infty}$ is defined to be the linear span of the set of positive operators T such that $\mu(T) \in m_{1,\infty}$.

Since it is easily verified (as is done in [10]) that the spaces $\ell^{p,q}$ and $m_{1,\infty}$ are Calkin spaces, it follows that $\mathcal{L}^{p,q}$ and $\mathcal{M}_{1,\infty}$ are two-sided ideals.

For our purposes, the following description of $\mathcal{M}_{1,\infty}$ will be useful:

Proposition E.6. *Let $x \in \mathcal{M}_{1,\infty}$. Then there is an equivalence of norms,*

$$\|x\|_{\mathcal{M}_{1,\infty}} \cong \sup_{s \in (0,1)} s \|x\|_{\mathcal{L}^{s+1}}. \quad (\text{E.4})$$

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