

Finite difference schemes for linear PDE

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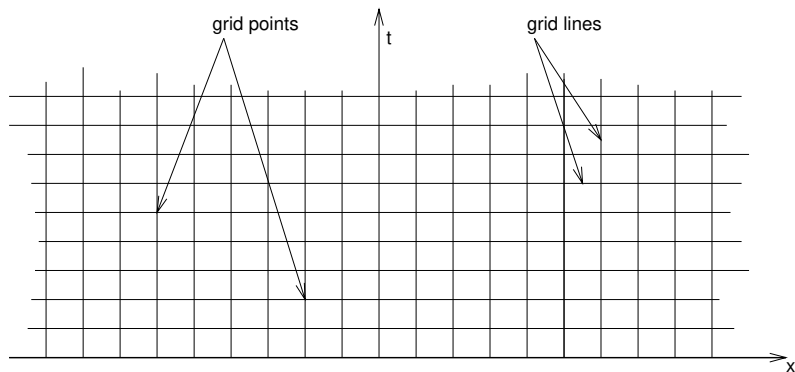
We consider

$$Pu = u_t + au_x = 0, \quad -\infty < x < \infty, t > 0, \quad u = u(x, t)$$

with initial condition

$$u(x, 0) = u_0(x)$$

First we define the grid points in the (x, t) plane by drawing vertical and horizontal lines through the points (x_i, t_n)



$$t_n = n\Delta t, \quad n = 0, 1, 2, \dots$$

$$x_j = jh, \quad j = 0, \pm 1, \pm 2, \dots$$

The lines $x = x_i$ and $t = t_n$ are called grid lines and their intersections are called mesh points of the grid.

The basic idea of **finite difference method** is to replace derivatives by **finite differences**. This can be done in many ways;

By replacing the derivatives by finite differences and neglecting the error terms we have list of difference equations. For example

$$P_{\Delta t, h} v = \frac{v_j^{n+1} - v_j^n}{\Delta t} + a \frac{(v_{j+1}^n - v_j^n)}{h} = 0 \text{ (forward time - forward space)}$$

$$P_{\Delta t, h} v = \frac{v_i^{n+1} - v_j^n}{\Delta t} + a \frac{(v_j^n - v_{j-1}^n)}{h} = 0 \text{ (forward time - backward space)}$$

$$P_{\Delta t, h} v = \frac{v_j^{n+1} - v_j^n}{\Delta t} + a \frac{(v_{j+1}^n - v_{j-1}^n)}{2h} = 0 \text{ (forward time - central space)}$$

$$P_{\Delta t, h} v = \frac{v_j^n - v_j^{n-1}}{\Delta t} + a \frac{(v_{j+1}^n - v_j^n)}{h} = 0 \text{ (backward time - forward space)}$$

$$P_{\Delta t, h} v = \frac{v_j^n - v_j^{n-1}}{\Delta t} + a \frac{(v_j^n - v_{j-1}^n)}{h} = 0 \text{ (backward time - backward space)}$$

Cosistency, Stability and convergence

Solution need not converge always!

$$u_t + u_x = 0$$

$$u(x, 0) = u_0(x) = \begin{cases} 1 & \text{if } x \leq 0 \\ 2x^3 - 3x^2 + 1 & \text{if } 0 \leq x \leq 1 \\ 0 & \text{if } x \geq 1 \end{cases}$$

$$u(x, t) = u_0(x - t) = \begin{cases} 1 & x \leq t \\ 2(x - t)^3 - 3(x - t)^2 + 1 & 0 \leq x - t \leq 1 \\ 0 & x \geq t + 1 \end{cases}$$

$$v_i^{n+1} = v_j^n - \frac{\Delta t}{h}(v_{j+1}^n - v_j^n) \text{ (forward time - forward space).}$$

Definition

$$\|u\|_2 = \left(h \sum_j |u(x_j)|^2 \right)^{1/2} = \left(h \sum_j |u_j|^2 \right)^{1/2}$$

$$\|u\|_\infty = \sup_j |u(x_j)| = \sup_j |u_j|.$$

Definition : Given a partial differential equation $Pu = 0$ and a finite difference scheme $P_{\Delta t, h}v = 0$ we say that the finite difference scheme is **consistent** with the partial differential equation in norm $\|\cdot\|$, if for the actual solution u of $Pu = 0$,

$$\|P_{\Delta t, h}u\| \rightarrow 0 \quad \text{as } \Delta t, h \rightarrow 0.$$

Definition : The finite difference method is accurate of order (p, q) in $\|\cdot\|$ if for the actual solution u of $Pu = 0$,

$$\|P_{\Delta t, h} u\| = O(h^p) + O(\Delta t^q).$$

We can write

$$v_j^{n+1} = \sum_{l=-k}^k \alpha_l v_{j+l}^n = \alpha_{-k} v_{j-k}^n + \dots \alpha_0 v_j^n + \dots + \alpha_k v_{j+k}^n .$$

Shift operator: S_+ and S_- $S_+ v_j = v_{j+1}, \quad S_- v_j = v_{j-1}$

$$v_j^{n+1} = \alpha_{-k} S_-^k v_j^n + \dots \alpha_{-1} S_- v_j^n + \alpha_0 v_j^n + \alpha_1 S_+ v_j^n + \dots + \alpha_k S_+^k v_j^n$$

Definition : The finite difference method is called **stable** in $\|\cdot\|$, if there exist constants K and β such that

$$\|v^n\| \leq Ke^{\beta t} \|v^0\|$$

where $t = n\Delta t$, K and β are independent of h and Δt .

Definition : The finite difference method is called **strongly stable** in $\|\cdot\|$, if $\|v^n\| \leq \|v^{n-1}\|$.

Definition: A finite difference method is **unconditionally stable** if it is stable for any time step Δt and space step h .

Example: $v_j^{n+1} = v_j^n - a \frac{\Delta t}{h} (v_j^n - v_{j-1}^n)$ (FTBS) for $u_t + au_x = 0$

$$v_j^{n+1} = v_j^n (1 - a\lambda) + a\lambda v_{j-1}^n, \quad \lambda = \frac{\Delta t}{h}$$

$$\begin{aligned} \|v^{n+1}\|_\infty &= \sup_j |v_j^{n+1}| = \sup_j |v_j^n (1 - a\lambda) + a\lambda v_{j-1}^n| \\ &\leq \sup_j \{|1 - a\lambda| |v_j^n| + a\lambda |v_{j-1}^n|\} \leq |1 - a\lambda| \|v^n\|_\infty + |a\lambda| \|v^n\|_\infty \end{aligned}$$

If $0 < a\lambda \leq 1$, then $\|v^{n+1}\|_\infty \leq \|v^n\|_\infty \leq \dots \leq \|v^0\|_\infty$. Therefore this scheme is l_∞ -stable if $a\lambda \leq 1$ (conditionally stable).

Solution of $u_t + u_x = 0$, $u(x, 0) = \sin(2\pi x)$

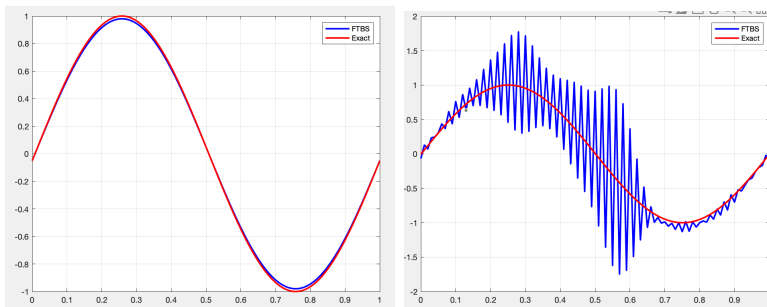


Figure: (Left) solution at $t = 1$ with $\Delta t = 0.9h$. (Right) solution at $t = 1$ with $\Delta t = 1.3h$.

Example: $v_j^n = v_j^{n-1} - \lambda(v_j^n - v_{j-1}^n) \quad n \geq 1$ (BTBS)

$$-\lambda v_{j-1}^n + v_j^n(1 + \lambda) = v_j^{n-1}$$

This can be written in the matrix form, $Av^n = v^{n-1}$ where $A = (a_{ij})$ with $a_{ii} = (1 + \lambda)$ and $a_{ii-1} = -\lambda$ and $a_{ij} = 0$ if $j \neq i, i - 1$.

Definition: A difference scheme $\mathbf{v}^{n+1} = Q\mathbf{v}^n$ approximating the PDE $Pu = 0$ is a convergent scheme at time t in $\|\cdot\|$ if, as $(n+1)\Delta t$ converges to t

$$\left\| \mathbf{u}^{n+1} - \mathbf{v}^{n+1} \right\| \rightarrow 0$$

as h and Δt converges to 0.

Definition: A difference scheme $\mathbf{v}^{n+1} = Q\mathbf{v}^n$ approximating the PDE $Pu = 0$ is a convergent scheme of order (p, q) in $\|\cdot\|$ if for any time t , as $(n+1)\Delta t$ converges to t

$$\left\| \mathbf{u}^{n+1} - \mathbf{v}^{n+1} \right\| = \mathcal{O}(h^p) + \mathcal{O}(\Delta t^q)$$

as h and Δt converges to 0.

Definition : A finite difference method is said to be **linear** if it is of the form

$$v_j^{n+1} = \sum_{l=-m_1}^{m_2} c_l v_{l+j}^n \text{ where } c_l \text{'s are constants}$$

m_1, m_2 are non-negative integers.

Theorem (Lax): If a finite difference method is linear, stable and accurate of order (p, q) in $\|\cdot\|$, then it is convergent of order (p, q) in $\|\cdot\|$.

Proof:

Von-Neumann Analysis

Define the discrete Fourier transform of $v = (v_j)_{j=-\infty}^{\infty}$ be a sequence by

$$\widehat{v}(\xi) = \sum_{j=-\infty}^{\infty} v_j e^{ij\xi} \quad i = \sqrt{-1}, \quad \xi \in [0, 2\pi].$$

$$\begin{aligned} \widehat{S_+ v} &= \sum_j (S_+ v_j) e^{ij\xi} = \sum_j v_{j+1} e^{ij\xi} \\ &= \sum_j v_j e^{i(j-1)\xi} = e^{-i\xi} \sum_j v_j e^{ij\xi} = e^{-i\xi} \widehat{v}(\xi). \end{aligned}$$

Similarly $\widehat{S_- v} = e^{i\xi} \widehat{v}(\xi).$

Example: (FTBS)

$$\begin{aligned}v_j^{n+1} &= v_j^n - \frac{\Delta t}{h}(v_j^n - v_{j-1}^n) \\&= (1 - \lambda)v_j^n + \lambda v_{j-1}^n, \quad \lambda = \frac{\Delta t}{h} \\&= (1 - \lambda)v_j^n + \lambda S_- v_j^n \\&= ((1 - \lambda) + \lambda S_-)v_j^n\end{aligned}$$

$$\begin{aligned}\Rightarrow v^{n+1} &= Q(S_+, S_-)v^n, \quad Q(S_+, S_-) = (1 - \lambda)I + \lambda S_- \\ \Rightarrow \widehat{v}^{n+1} &= (1 - \lambda)\widehat{v}^n + \lambda \widehat{S_-} v^n \\ &= (1 - \lambda + \lambda e^{i\xi})\widehat{v}^n\end{aligned}$$

In general

$$\begin{aligned}\widehat{v}^{n+1} &= Q(e^{-i\xi}, e^{i\xi})\widehat{v}^n \\ \rho(\xi) &= Q(e^{-i\xi}, e^{i\xi}) \text{ is called } \mathbf{\text{amplification factor}}\end{aligned}$$

Definition: A symbol $\rho(\xi)$ is said to satisfy the Von Neumann condition if there exists a constant $C > 0$ (independent of $\Delta t, h, n$ and ξ) such that

$$|\rho(\xi)| \leq 1 + C\Delta t \quad \text{for } \xi \in [0, 2\pi]$$

Necessary and **sufficient** condition for stability

Theorem : A finite difference method $v^{n+1} = Qv^n$ is stable in the l_2 norm iff the Von-Neumann condition is satisfied.

Proof:

Examples: $(u_t + au_x = 0)$

1. Godunov Scheme :

$$\begin{aligned}v_j^{n+1} &= v_j^n - \lambda \frac{(1 + \operatorname{sgn} a)}{2} a (v_j^n - v_{j-1}^n) - \lambda \frac{(1 - \operatorname{sgn} a)}{2} a (v_{j+1}^n - v_j^n) \\&= \max(0, -a\lambda) v_{j+1}^n + (1 - |\lambda a|) v_j^n + \max(0, a\lambda) v_{j-1}^n\end{aligned}$$

2. FTCS

$$v_j^{n+1} = v_j^n - \frac{a\Delta t}{2h}(v_{j+1}^n - v_{j-1}^n)$$

$$v^{n+1} = (1 - a\frac{\lambda}{2}S_+ + a\frac{\lambda}{2}S_-)v^n$$

$$\rho(\xi) = 1 - a\frac{\lambda}{2}(e^{-i\xi} - e^{i\xi}) = 1 + ia\lambda \sin \xi$$

$$|\rho(\xi)|^2 = 1 + a^2\lambda^2 \sin^2 \xi > 1 \text{ if } \xi \neq 0, \pi$$

This scheme is not strongly stable in $\|\cdot\|_2$ It is accurate of order $(p, q) = (2, 1)$

This scheme is stable in $\|\cdot\|_2$ with restriction $\Delta t \leq \frac{h^2}{a^2}$ (which is more restrictive than CFL)

2. Lax-Friedrichs Scheme :

$$v_j^{n+1} = \frac{v_{j+1}^n + v_{j-1}^n}{2} - \frac{\Delta t a}{2h} (v_{j+1}^n - v_{j-1}^n)$$

$$v^{n+1} = \left(\frac{1}{2}(1 - a\lambda)S_+ + \frac{1}{2}(1 + a\lambda)S_- \right) v^n$$

$$\rho(\xi) = \frac{1}{2}(1 - a\lambda)e^{-i\xi} + \frac{1}{2}(1 + a\lambda)e^{i\xi}$$

$$|\rho(\xi)| \leq \frac{1}{2}|1 - a\lambda| + \frac{1}{2}|1 + a\lambda| \leq 1 \quad \text{if } |a\lambda| \leq 1$$

The **LF** scheme is $\|\cdot\|_2$ if $|a\lambda| \leq 1$.

Note:

The **LF** scheme is convergent in $\|\cdot\|_2$ and $\|\cdot\|_\infty$ if $|a\lambda| \leq 1$

The **LF** Scheme is first order accurate i.e. $p = 1, q = 1$

3. Lax-Wendroff scheme

$$\begin{aligned}u(x, t + \Delta t) &= u(x, t) + \Delta t u_t(x, t) + \frac{(\Delta t)^2}{2} u_{tt}(x, t) + O(\Delta t^3) \\&= u(x, t) - \Delta t a u_x + \frac{(\Delta t)^2}{2} a^2 u_{xx} + O(\Delta t)^3 \\v_j^{n+1} &= v_j^n - \frac{\Delta t a}{2h} (v_{j+1}^n - v_{j-1}^n) + \frac{a^2 (\Delta t)^2}{2h^2} (v_{j+1}^n - 2v_j^n + v_{j-1}^n)\end{aligned}$$

This scheme is second order accurate i.e, $p = q = 2$

$$\begin{aligned}
 \rho(\xi) &= 1 + \frac{\lambda a}{2}(e^{i\xi} - e^{-i\xi}) + \frac{a^2 \lambda^2}{2}(e^{i\xi} + e^{-i\xi} - 2) \\
 &= 1 - a^2 \lambda^2 (1 - \cos \xi) + i \lambda a \sin \xi \\
 &= 1 - 2a^2 \lambda^2 \sin^2 \frac{\xi}{2} + i \lambda a \sin \xi \quad (\text{because } 1 - \cos \xi = 2 \sin^2 \frac{\xi}{2})
 \end{aligned}$$

$$|\rho(\xi)|^2 = 1 - 4a^2 \lambda^2 (1 - a^2 \lambda^2) \sin^4 \frac{\xi}{2}$$

$$|\rho(\xi)| \leq 1 \quad \text{if} \quad |a\lambda| \leq 1$$

Scheme is $\|\cdot\|_2$ stable. Hence converges in $\|\cdot\|_2$ norm

4. Crank-Nicolson Scheme

$$\begin{aligned}\frac{u(x, t + \Delta t) - u(x, t)}{\Delta t} &= \frac{1}{\Delta t} \int_t^{t+\Delta t} u_t(x, \xi) d\xi \\&= \frac{u_t(x, t + \Delta t) + u_t(x, t)}{2} + O(\Delta t^2) \\&= -a \frac{u_x(x, t + \Delta t) + u_x(x, t)}{2} + O(\Delta t^2) \\&= -\frac{a}{2} \frac{(u(x + h, t + \Delta t) - u(x - h, t + \Delta t))}{2h} \\&\quad - \frac{a}{2} \frac{(u(x + h, t) - u(x - h, t))}{2h} + O(\Delta t^2) + O(h^2)\end{aligned}$$

The CN scheme is given by

$$\frac{v_i^{n+1} - v_i^n}{\Delta t} = -\frac{a}{2} \frac{(v_{i+1}^{n+1} - v_{i-1}^{n+1})}{2h} - \frac{a}{2} \frac{(v_{i+1}^n - v_{i-1}^n)}{2h}$$

This scheme is second order accurate i.e., $p = q = 2$

$$\begin{aligned}
-\frac{a\lambda}{4}v_{j-1}^{n+1} + v_j^{n+1} + \frac{a\lambda}{4}v_{j+1}^{n+1} &= v_j^n - \frac{a\lambda}{4}(v_{j+1}^n - v_{j-1}^n) \\
\left(-\frac{a\lambda}{4}S_- + I + \frac{a\lambda}{4}S_+\right)v^{n+1} &= \left(I - \frac{a\lambda}{4}(S_+ - S_-)\right)v^n \\
\left(-\frac{a\lambda}{4}e^{i\xi} + 1 + \frac{a\lambda}{4}e^{-i\xi}\right)\widehat{v}^{n+1} &= \left(1 - \frac{a\lambda}{4}(e^{-i\xi} - e^{i\xi})\right)\widehat{v}^n \\
\widehat{v}^{n+1} &= \left(\frac{1 + \frac{a\lambda}{2}i \sin \xi}{1 - \frac{a\lambda}{2}i \sin \xi}\right)\widehat{v}^n \\
\rho(\xi) &= \frac{1 + \frac{a\lambda}{2}i \sin \xi}{1 - \frac{a\lambda}{2}i \sin \xi} = \frac{z}{\bar{z}} \\
|\rho(\xi)| &= 1
\end{aligned}$$

The CN scheme is unconditionally stable in $\|\cdot\|_2$ and hence converges in the same norm.

Scheme	Stable	Strongly stable	CFL
FTCS	Yes	No	$\Delta t \leq \frac{h^2}{a^2}$
BTBS* ($a > 0$)	Yes	Yes	-
Upwind	Yes	Yes	$ a \lambda \leq 1$
Lax-Friedrichs	Yes	Yes	$ a \lambda \leq 1$
Lax-Wendroff	Yes	Yes	$ a \lambda \leq 1$

Parabolic equation

$$u_t = bu_{xx}, \quad -\infty < x < \infty, \quad t > 0, \quad b > 0$$
$$u(x, 0) = u_0(x)$$

$$u_t = \frac{u(x, t + \Delta t) - u(x, t)}{\Delta t} + O(\Delta t)$$
$$u_{xx} = \frac{u(x + h, t) - 2u(x, t) + u(x - h, t)}{h^2} + O(h^2)$$

$$\frac{v_i^{n+1} - v_i^n}{\Delta t} = \frac{b}{h^2}(v_{i+1}^n - 2v_i^n + v_{i-1}^n) \text{ is of order } (p, q) = (2, 1)$$
$$v_i^{n+1} = v_i^n(1 - 2\lambda b) + \lambda b v_{i+1}^n + \lambda b v_{i-1}^n$$

Crank-Nicolson scheme

$$v_i^{n+1} = v^n + \frac{b\Delta t}{2h^2}(v_{i+1}^{n+1} - 2v_i^{n+1} + v_{i-1}^{n+1}) + \frac{b\Delta t}{2h^2}(v_{i+1}^n - 2v_i^n + v_{i-1}^n)$$

This scheme is second order accurate i.e. $p = q = 2$.

θ -Scheme: ($0 \leq \theta \leq 1$)

$$v_i^{n+1} = v_i^n + \theta b \lambda (v_{i+1}^{n+1} - 2v_i^{n+1} + v_{i-1}^{n+1}) + (1 - \theta) \lambda b (v_{i+1}^n - 2v_i^n + v_{i-1}^n)$$

- If $\theta = 1/2$, θ - scheme is nothing but Crank-Nicolson Scheme.
- The order of accuracy is $(p, q) = (2, 1)$ if $\theta \neq 1/2$.

l_2 stability: θ -Scheme

$$-\theta b \lambda v_{i+1}^{n+1} + (1 + 2\theta b \lambda) v_i^{n+1} - \theta b \lambda v_{i-1}^{n+1} = (1 - \theta) \lambda b v_{i-1}^n + (1 - 2(1 - \theta) \lambda b) v_i^n + (1 - \theta) \lambda b v_{i+1}^n.$$

$$(-\theta b \lambda e^{-i\xi} + (1 + 2\theta b \lambda) - \theta b \lambda e^{i\xi}) \widehat{v}^{n+1} = ((1 - \theta) \lambda b e^{i\xi} + (1 - 2(1 - \theta) \lambda b) + (1 - \theta) \lambda b e^{-i\xi}) \widehat{v}^n$$

$$\rho(\xi) = \frac{1 - 4(1 - \theta) \lambda b \sin^2 \frac{\xi}{2}}{1 + 4\theta b \lambda \sin^2 \frac{\xi}{2}}$$

$$|\rho(\xi)| \leq 1 \quad \text{if} \quad (1 - 2\theta)w \leq 2, \quad w = 4\lambda b \sin^2 \frac{\xi}{2}$$

- Unconditionally stable in $\|\cdot\|_2$ if $\theta \geq 1/2$
- Conditionally stable $\|\cdot\|_2$ if $\theta < 1/2$, $\lambda b \leq \frac{1}{2(1-2\theta)}$

l_∞ **stability:** θ -Scheme

$$Av^{n+1} = Bv^n$$

$$a_{ij} = \begin{cases} 1 + 2\theta\lambda b & \text{if } j = i \\ -\theta\lambda b & \text{if } j = i - 1 \\ & \text{or } j = i + 1 \\ 0 & \text{otherwise,} \end{cases} \quad b_{ij} = \begin{cases} 1 - 2(1 - \theta)b\lambda & \text{if } j = i \\ (1 - \theta)\lambda b & \text{if } j = i - 1 \\ & \text{or } j = i + 1 \\ 0 & \text{otherwise} \end{cases}$$

References I