

# Score Matching Based Generative Model and Diffusion Model

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**Computer Vision Core**

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- Score-Based Generative Model(NCSN)
- Diffusion Model(DDPM)
- Score-Based Generative Model through SDE

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## Generative Modeling by Estimating Gradients of the Data Distribution

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## SCORE-BASED GENERATIVE MODELING THROUGH STOCHASTIC DIFFERENTIAL EQUATIONS

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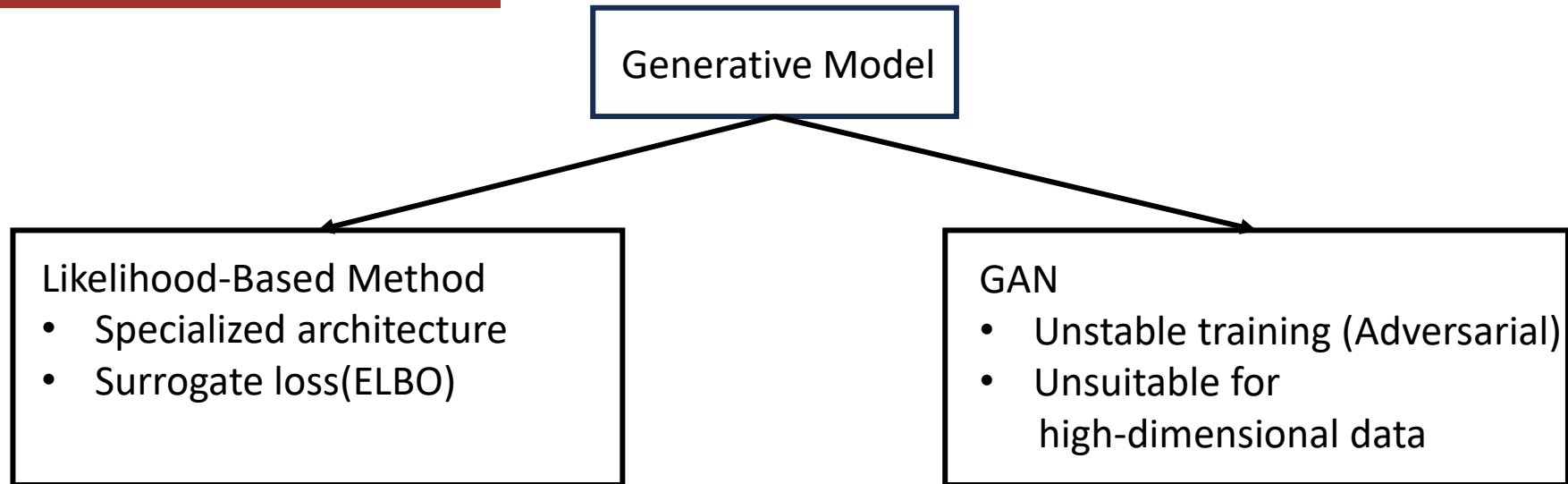
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# Score-Based Generative Model

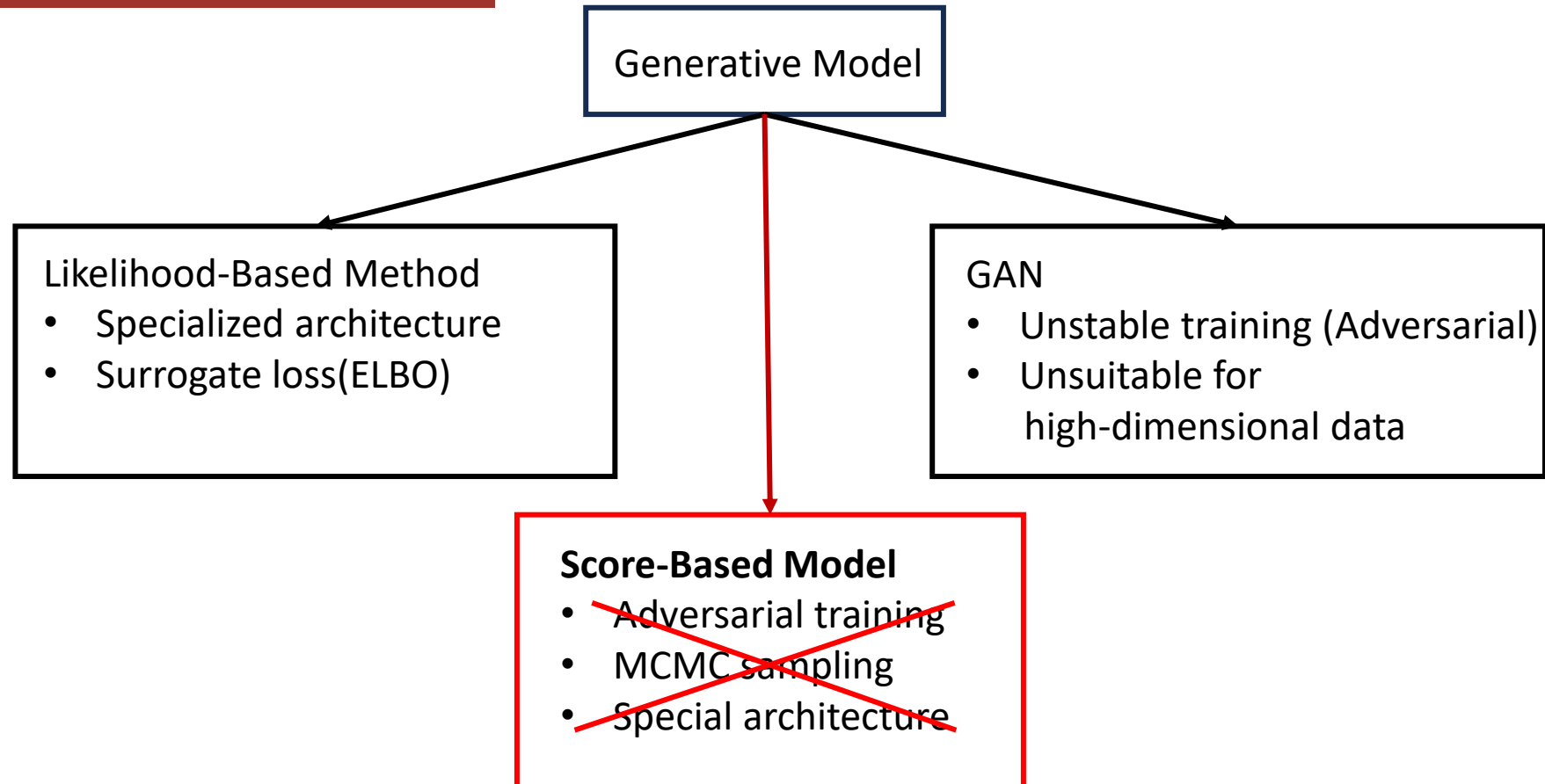
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## Introduction



# Score-Based Generative Model

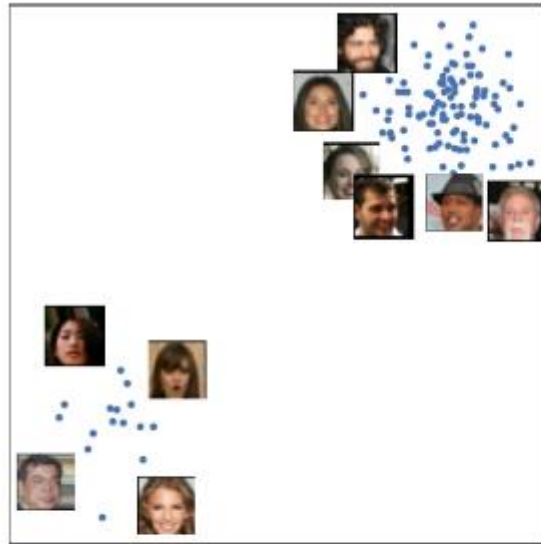
## Introduction



# Score-Based Generative Model

## Overview

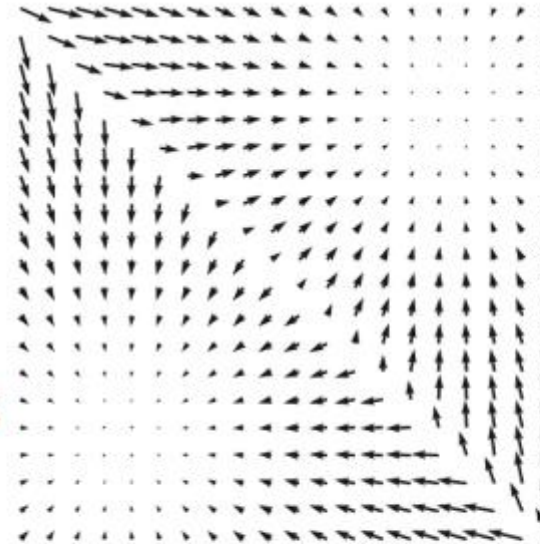
$$\begin{aligned}\text{Score} &= \text{Gradient of } \log(\text{pdf}) \\ &= \nabla_x \log p(x)\end{aligned}$$



Data samples

$$\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N\} \stackrel{\text{i.i.d.}}{\sim} p(\mathbf{x})$$

score  
matching



Scores

$$\mathbf{s}_\theta(\mathbf{x}) \approx \nabla_{\mathbf{x}} \log p(\mathbf{x})$$

Langevin  
dynamics

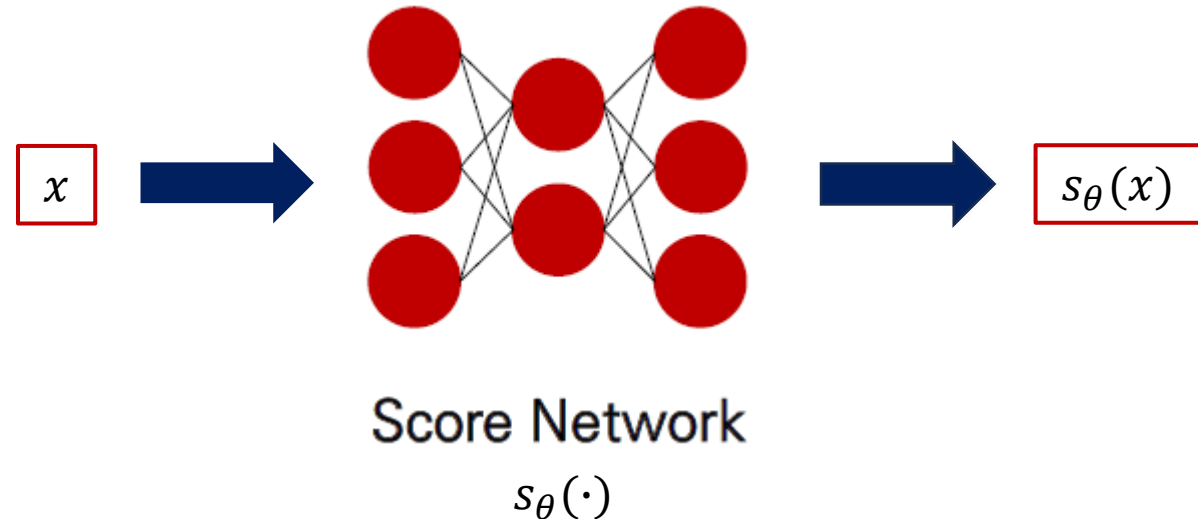


New samples

# Score-Based Generative Model

## Score-Matching

- Score Network  $s_\theta(\cdot) : R^D \rightarrow R^D$ 
  - U-Net in paper
- Training objective:
  - MSE between network output and score
  - Network estimates score



Training objective

$$\text{MSE}(s_\theta(x), \nabla_x \log(p(x)))$$

# Score-Based Generative Model

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## Score-Matching

Training objective

$$\text{MSE}(s_{\theta}(x), \nabla_x \log(p(x)))$$



# Score-Based Generative Model

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## Score-Matching

Training objective

$$\text{MSE}(s_{\theta}(x), \nabla_x \log(p(x)))$$

$$\frac{1}{2} \mathbb{E}_{p_{\text{data}}} [\|\mathbf{s}_{\theta}(\mathbf{x}) - \nabla_{\mathbf{x}} \log p_{\text{data}}(\mathbf{x})\|_2^2]$$



# Score-Based Generative Model

## Score-Matching

Training objective

$$\text{MSE}(s_{\theta}(x), \nabla_x \log(p(x)))$$

$$\frac{1}{2} \mathbb{E}_{p_{\text{data}}} [\|\mathbf{s}_{\theta}(\mathbf{x}) - \nabla_{\mathbf{x}} \log p_{\text{data}}(\mathbf{x})\|_2^2]$$

$$\mathbb{E}_{p_{\text{data}}(\mathbf{x})} \left[ \text{tr}(\nabla_{\mathbf{x}} \mathbf{s}_{\theta}(\mathbf{x})) + \frac{1}{2} \|\mathbf{s}_{\theta}(\mathbf{x})\|_2^2 \right]$$

Score-Matching

Using score matching, we can directly train a score network  $\mathbf{s}_{\theta}(\mathbf{x})$  to estimate  $\nabla_{\mathbf{x}} \log p_{\text{data}}(\mathbf{x})$  training a model to estimate  $p_{\text{data}}(\mathbf{x})$  first.

# Score-Based Generative Model

## Score-Matching

Training objective

$$\text{MSE}(s_{\theta}(x), \nabla_x \log(p(x)))$$

$$\frac{1}{2} \mathbb{E}_{p_{\text{data}}} [\|\mathbf{s}_{\theta}(\mathbf{x}) - \nabla_{\mathbf{x}} \log p_{\text{data}}(\mathbf{x})\|_2^2]$$

$$\mathbb{E}_{p_{\text{data}}(\mathbf{x})} \left[ \text{tr}(\nabla_{\mathbf{x}} \mathbf{s}_{\theta}(\mathbf{x})) + \frac{1}{2} \|\mathbf{s}_{\theta}(\mathbf{x})\|_2^2 \right]$$

Jacobian Matrix(d\*d)

Complex computation  
in high-dimension

Score-Matching

# Score-Based Generative Model

## Score-Matching

Training objective

$$\text{MSE}(s_{\theta}(x), \nabla_x \log(p(x)))$$

$$\frac{1}{2} \mathbb{E}_{p_{\text{data}}} [\|\mathbf{s}_{\theta}(\mathbf{x}) - \nabla_{\mathbf{x}} \log p_{\text{data}}(\mathbf{x})\|_2^2]$$

Score-Matching

$$\mathbb{E}_{p_{\text{data}}(\mathbf{x})} \left[ \text{tr}(\nabla_{\mathbf{x}} \mathbf{s}_{\theta}(\mathbf{x})) + \frac{1}{2} \|\mathbf{s}_{\theta}(\mathbf{x})\|_2^2 \right]$$

Denoising Score Matching

$$\frac{1}{2} \mathbb{E}_{q_{\sigma}(\tilde{\mathbf{x}}|\mathbf{x})p_{\text{data}}(\mathbf{x})} [\|\mathbf{s}_{\theta}(\tilde{\mathbf{x}}) - \nabla_{\tilde{\mathbf{x}}} \log q_{\sigma}(\tilde{\mathbf{x}} | \mathbf{x})\|_2^2]$$

Sliced score matching

$$\mathbb{E}_{p_{\mathbf{v}}} \mathbb{E}_{p_{\text{data}}} \left[ \mathbf{v}^{\top} \nabla_{\mathbf{x}} \mathbf{s}_{\theta}(\mathbf{x}) \mathbf{v} + \frac{1}{2} \|\mathbf{s}_{\theta}(\mathbf{x})\|_2^2 \right]$$

# Score-Based Generative Model

## Score-Matching

Training objective

$$\text{MSE}(s_{\theta}(x), \nabla_x \log(p(x)))$$

$$\frac{1}{2} \mathbb{E}_{p_{\text{data}}} [\|\mathbf{s}_{\theta}(\mathbf{x}) - \nabla_{\mathbf{x}} \log p_{\text{data}}(\mathbf{x})\|_2^2]$$

Score-Matching

$$\mathbb{E}_{p_{\text{data}}(\mathbf{x})} \left[ \text{tr}(\nabla_{\mathbf{x}} \mathbf{s}_{\theta}(\mathbf{x})) + \frac{1}{2} \|\mathbf{s}_{\theta}(\mathbf{x})\|_2^2 \right]$$

Denoising Score Matching

$$\frac{1}{2} \mathbb{E}_{q_{\sigma}(\tilde{\mathbf{x}}|\mathbf{x}) p_{\text{data}}(\mathbf{x})} [\|\mathbf{s}_{\theta}(\tilde{\mathbf{x}}) - \nabla_{\tilde{\mathbf{x}}} \log q_{\sigma}(\tilde{\mathbf{x}} | \mathbf{x})\|_2^2]$$

Sliced score matching

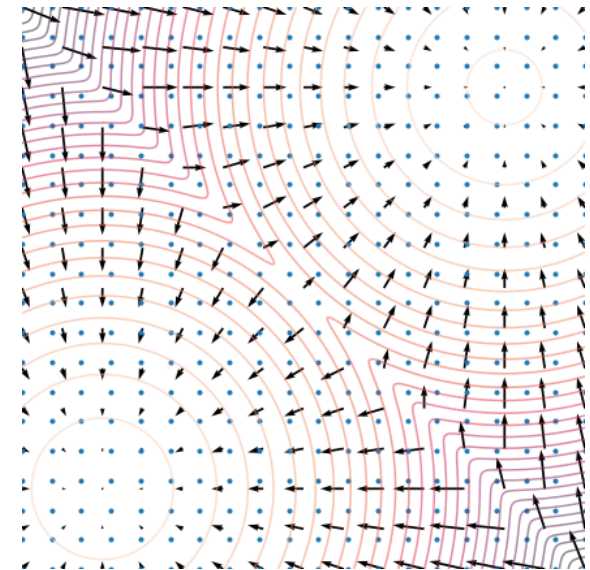
$$\mathbb{E}_{p_{\mathbf{v}}} \mathbb{E}_{p_{\text{data}}} \left[ \mathbf{v}^{\top} \nabla_{\mathbf{x}} \mathbf{s}_{\theta}(\mathbf{x}) \mathbf{v} + \frac{1}{2} \|\mathbf{s}_{\theta}(\mathbf{x})\|_2^2 \right]$$

# Score-Based Generative Model

## Langevin dynamics

- Using only **score function**
- Trained score network :  $\mathbf{s}_\theta(\mathbf{x}) \approx \nabla_{\mathbf{x}} \log p(\mathbf{x})$
- $\epsilon$  : fixed step size
- $\mathbf{z}_t$ : noise  $\sim N(0, I)$
- $\mathbf{x}_0$ = random noise
- Some error is negligible  
when  $\epsilon$  is sufficiently small and  $T$  is sufficiently large

$$\tilde{\mathbf{x}}_t = \tilde{\mathbf{x}}_{t-1} + \frac{\epsilon}{2} \nabla_{\mathbf{x}} \log p(\tilde{\mathbf{x}}_{t-1}) + \sqrt{\epsilon} \mathbf{z}_t, \quad t = 0, 1, \dots, T$$



# Challenges of Score-Based Generative Model

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## Manifold Hypothesis

The manifold hypothesis states that data in the real world tend to concentrate on low dimensional manifolds embedded in a high dimensional space (a.k.a., the ambient space).

### Difficulty

1. Since the score  $\nabla_x \log(p(x))$  is a gradient taken in the ambient space, it is undefined when  $x$  is confined to a low dimensional manifold.
2. The score matching objective provides a consistent score estimator only when the support of the data distribution is the whole space.

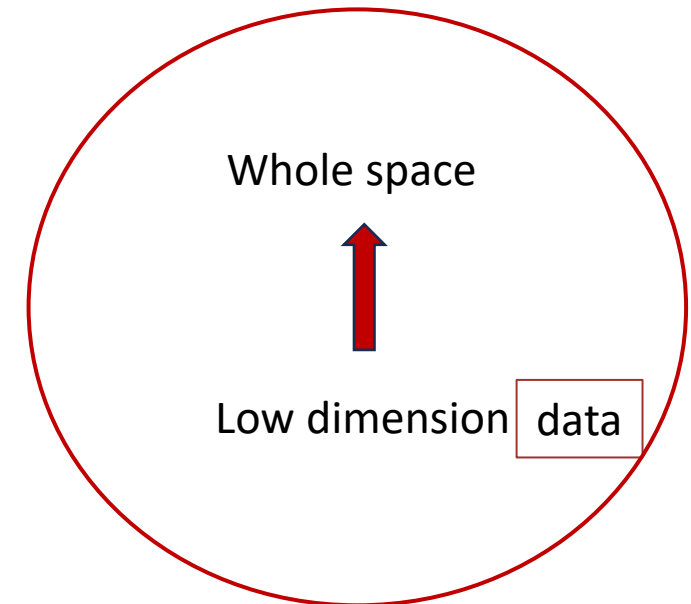
# Challenges of Score-Based Generative Model

## Manifold Hypothesis

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### Difficulty

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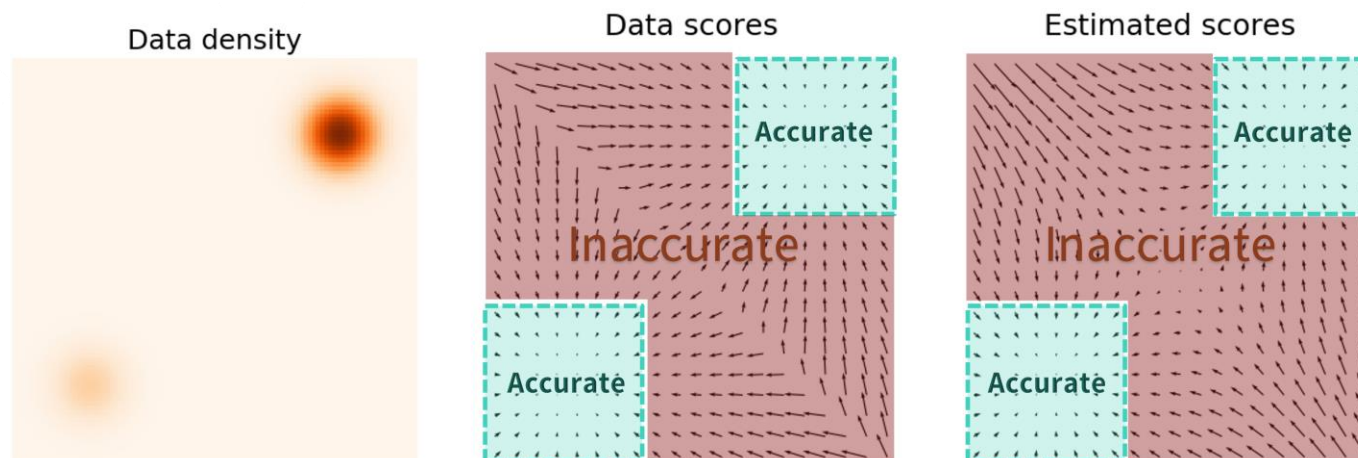
# Challenges of Score-Based Generative Model

## Low data density regions

Difficulty

Due to lack of data samples

1. Inaccurate score estimation with score matching  
lack of data samples
2. Slow mixing of Langevin dynamics



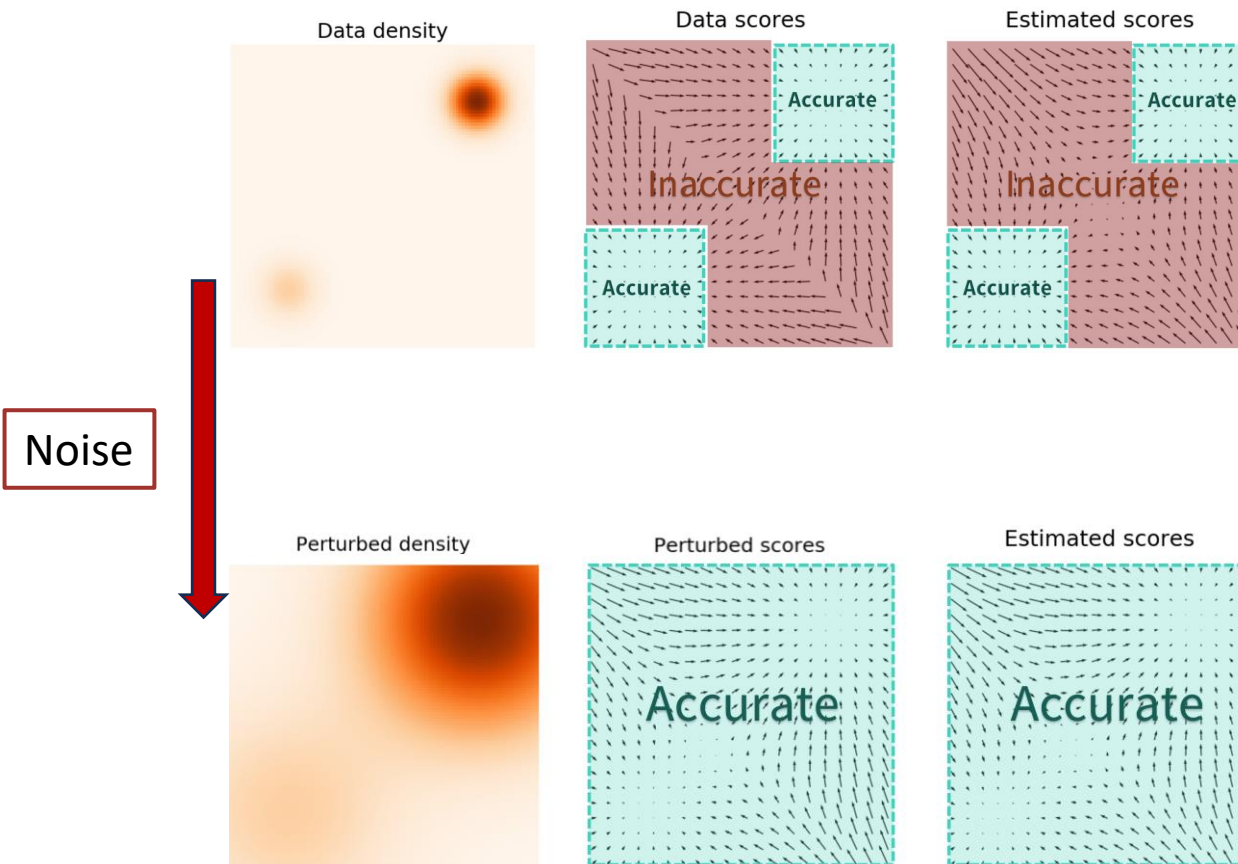
$$p_{data} = \frac{1}{5}N((-5, -5), I) + \frac{4}{5}N((5, 5), I)$$

# Noise Conditional Score Networks(NCSN)

## Problem-Solving

Adding multiple-level gaussian noise

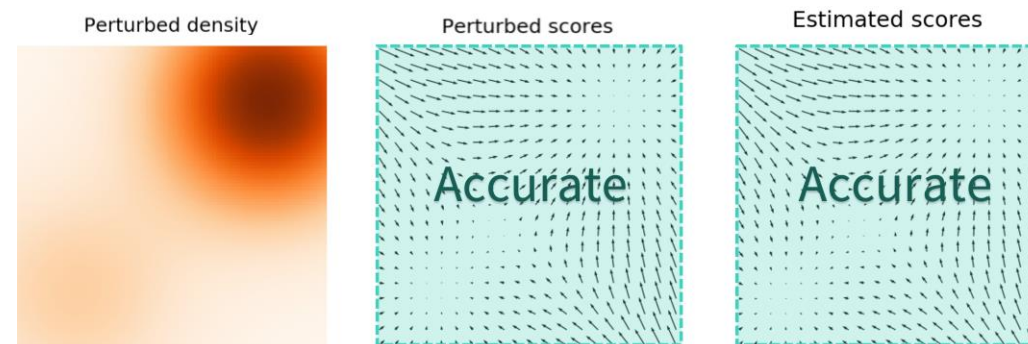
- Global – Distributing data to whole space
- Large – Filling low density regions
- Multiple level – improving mixing rate



# Noise Conditional Score Networks(NCSN)

## Denoising score-matching

- $q_{\sigma}(\tilde{x}|x)$  : Gaussian noise
- $\tilde{x}$  : data added noise (perturbing data)
- $q_{\sigma}(\tilde{\mathbf{x}}) \triangleq \int q_{\sigma}(\tilde{\mathbf{x}} | \mathbf{x})p_{\text{data}}(\mathbf{x})d\mathbf{x}$  : perturbed data distribution
- Small noise  $\rightarrow \mathbf{s}_{\theta^*}(\mathbf{x}) = \nabla_{\mathbf{x}} \log q_{\sigma}(\mathbf{x}) \approx \nabla_{\mathbf{x}} \log p_{\text{data}}(\mathbf{x})$



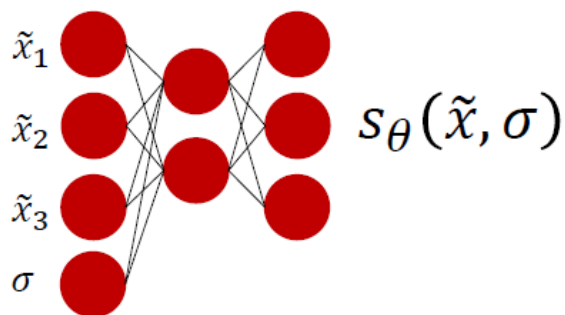
Perturbing an image with multiple scales of Gaussian noise

# Noise Conditional Score Networks(NCSN)

## Denoising score-matching

Multiple-level gaussian noise

- Large  $\sigma_1$   $\rightarrow$  small  $\sigma_L$  (like Fine-tuning)
- $q_\sigma(\tilde{\mathbf{x}} \mid \mathbf{x}) = \mathcal{N}(\tilde{\mathbf{x}} \mid \mathbf{x}, \sigma^2 I)$



Noise Conditional Score Network  
(NCSN)

$$\frac{1}{2} \mathbb{E}_{q_\sigma(\tilde{\mathbf{x}}|\mathbf{x})p_{\text{data}}(\mathbf{x})} [\|s_\theta(\tilde{\mathbf{x}}) - \nabla_{\tilde{\mathbf{x}}} \log q_\sigma(\tilde{\mathbf{x}} \mid \mathbf{x})\|_2^2]$$



$$\frac{1}{2} \mathbb{E}_{p_{\text{data}}(\mathbf{x})} \mathbb{E}_{\tilde{\mathbf{x}} \sim \mathcal{N}(\mathbf{x}, \sigma^2 I)} \left[ \left\| s_\theta(\tilde{\mathbf{x}}, \underline{\sigma}) + \frac{\tilde{\mathbf{x}} - \mathbf{x}}{\underline{\sigma}^2} \right\|_2^2 \right]$$

# Noise Conditional Score Networks(NCSN)

## Annealed Langevin dynamics

$$\tilde{\mathbf{x}}_t = \tilde{\mathbf{x}}_{t-1} + \frac{\epsilon}{2} \nabla_{\mathbf{x}} \log p(\tilde{\mathbf{x}}_{t-1}) + \sqrt{\epsilon} \mathbf{z}_t$$

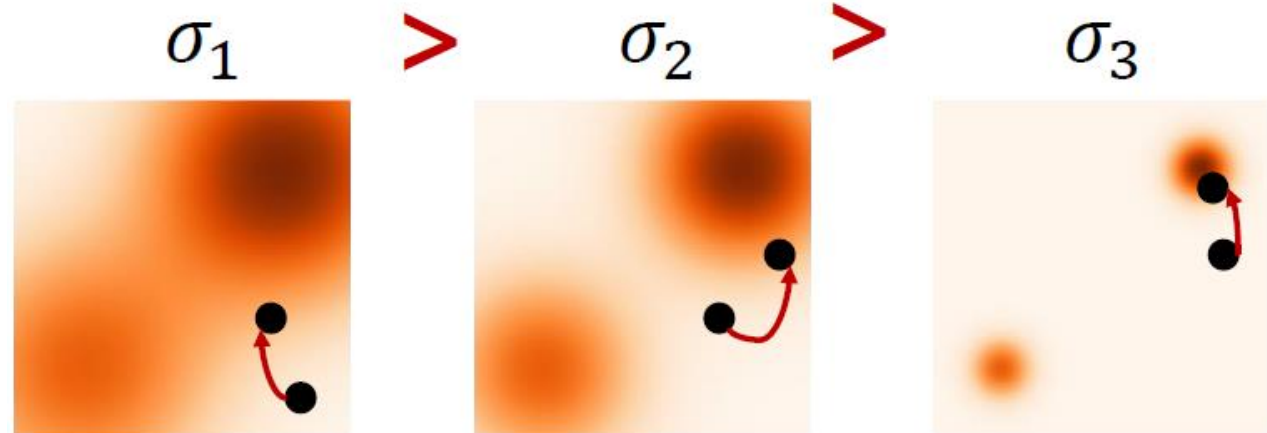


$$\tilde{\mathbf{x}}_t \leftarrow \tilde{\mathbf{x}}_{t-1} + \frac{\alpha_i}{2} \mathbf{s}_{\theta}(\tilde{\mathbf{x}}_{t-1}, \underline{\sigma}_i) + \sqrt{\alpha_i} \mathbf{z}_t$$

**Algorithm 1** Annealed Langevin dynamics.

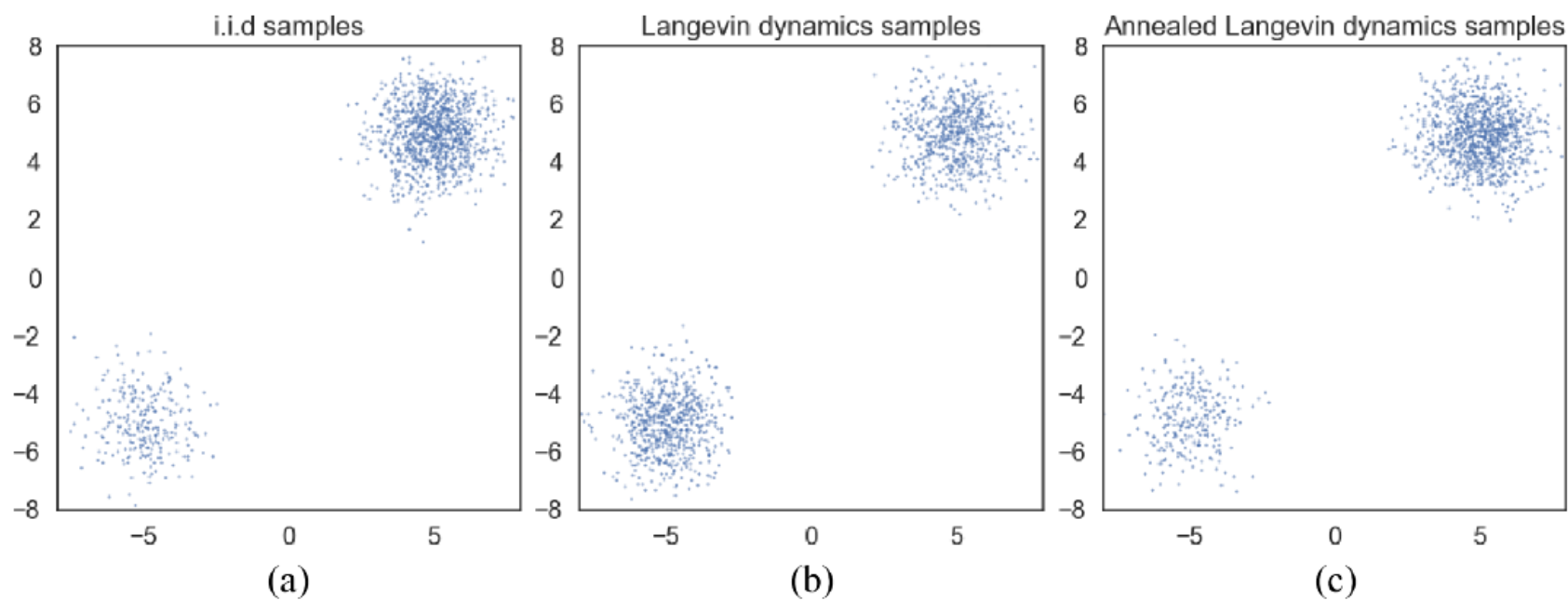
**Require:**  $\{\sigma_i\}_{i=1}^L, \epsilon, T$ .

- 1: Initialize  $\tilde{\mathbf{x}}_0$
- 2: **for**  $i \leftarrow 1$  to  $L$  **do**
- 3:    $\alpha_i \leftarrow \epsilon \cdot \sigma_i^2 / \sigma_L^2$     $\triangleright \alpha_i$  is the step size.
- 4:   **for**  $t \leftarrow 1$  to  $T$  **do**
- 5:     Draw  $\mathbf{z}_t \sim \mathcal{N}(0, I)$
- 6:      $\tilde{\mathbf{x}}_t \leftarrow \tilde{\mathbf{x}}_{t-1} + \frac{\alpha_i}{2} \mathbf{s}_{\theta}(\tilde{\mathbf{x}}_{t-1}, \sigma_i) + \sqrt{\alpha_i} \mathbf{z}_t$
- 7:   **end for**
- 8:  $\tilde{\mathbf{x}}_0 \leftarrow \tilde{\mathbf{x}}_T$
- 9: **end for**
- return**  $\tilde{\mathbf{x}}_T$



# Noise Conditional Score Networks(NCSN)

## Annealed Langevin dynamics





# Noise Conditional Score Networks(NCSN)

## Experiment

| Model                         | Inception                        | FID          |
|-------------------------------|----------------------------------|--------------|
| <b>CIFAR-10 Unconditional</b> |                                  |              |
| PixelCNN [59]                 | 4.60                             | 65.93        |
| PixelIQN [42]                 | 5.29                             | 49.46        |
| EBM [12]                      | 6.02                             | 40.58        |
| WGAN-GP [18]                  | $7.86 \pm .07$                   | 36.4         |
| MoLM [45]                     | $7.90 \pm .10$                   | <b>18.9</b>  |
| SNGAN [36]                    | $8.22 \pm .05$                   | 21.7         |
| ProgressiveGAN [25]           | $8.80 \pm .05$                   | -            |
| <b>NCSN (Ours)</b>            | <b><math>8.87 \pm .12</math></b> | 25.32        |
| <b>CIFAR-10 Conditional</b>   |                                  |              |
| EBM [12]                      | 8.30                             | 37.9         |
| SNGAN [36]                    | $8.60 \pm .08$                   | 25.5         |
| BigGAN [6]                    | <b>9.22</b>                      | <b>14.73</b> |

Table 1: Inception and FID scores for CIFAR-10

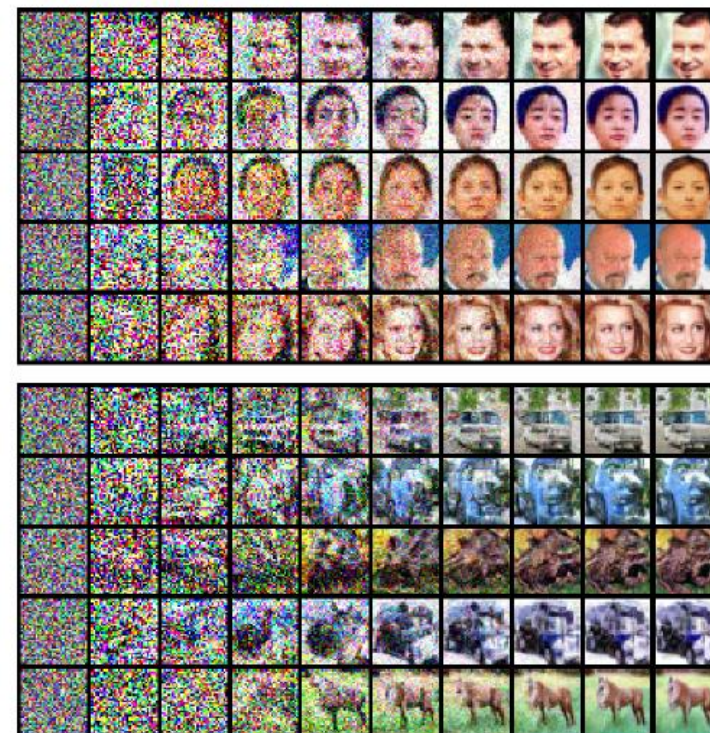


Figure 4: Intermediate samples of annealed Langevin dynamics.

# Noise Conditional Score Networks(NCSN)

## Experiment

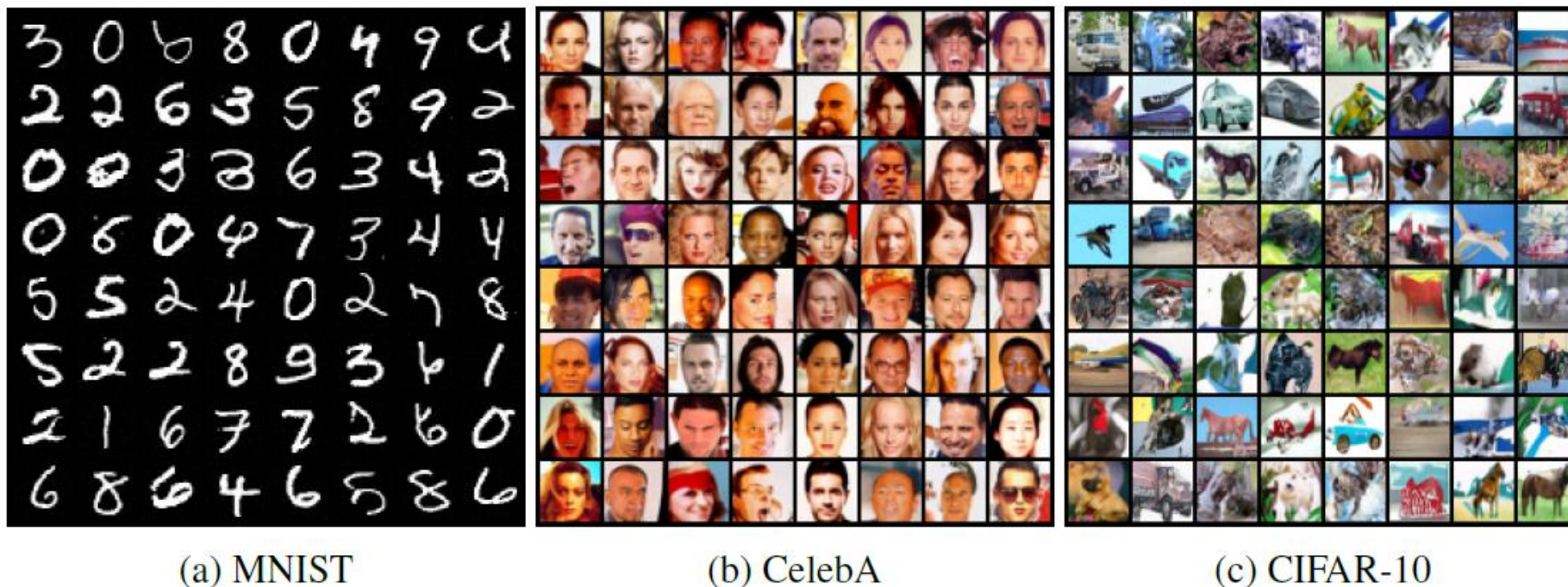


Figure 5: Uncurated samples on MNIST, CelebA, and CIFAR-10 datasets.



# Noise Conditional Score Networks(NCSN)

## Experiment

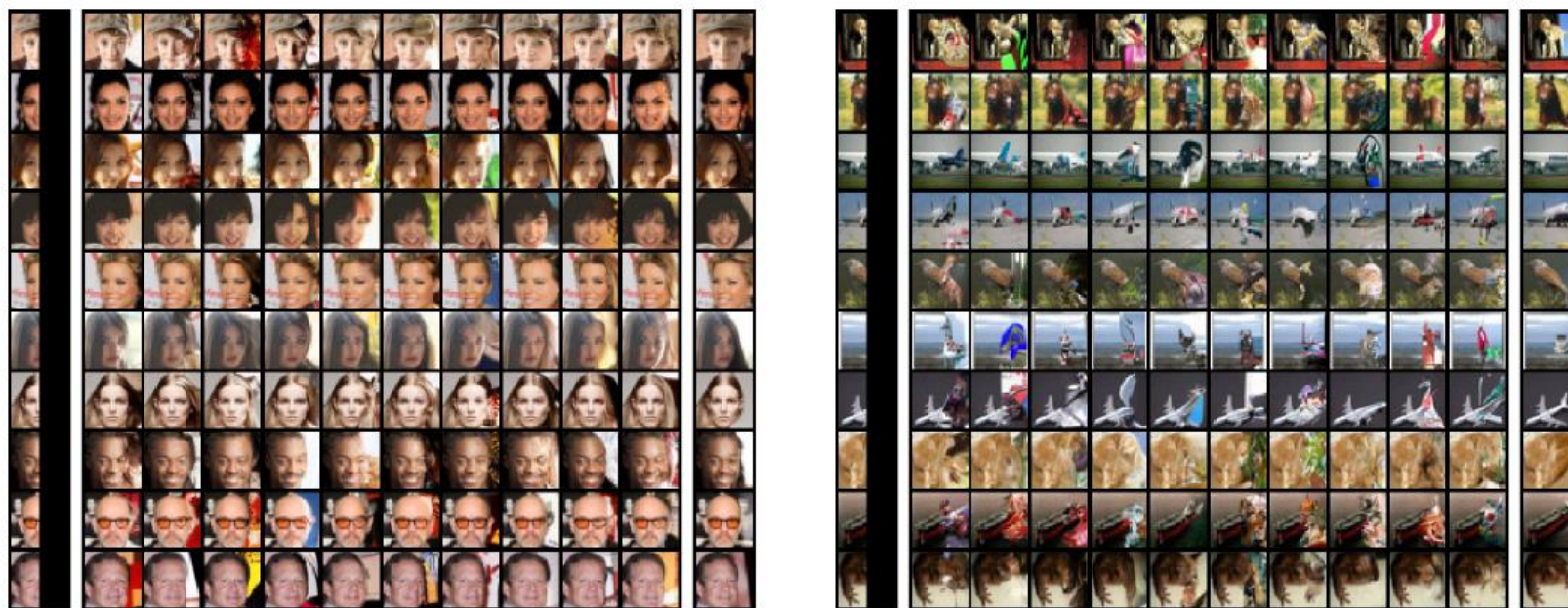


Figure 6: Image inpainting on CelebA (**left**) and CIFAR-10 (**right**). The leftmost column of each figure shows the occluded images, while the rightmost column shows the original images.

# Denoising Diffusion Probability Model(DDPM)

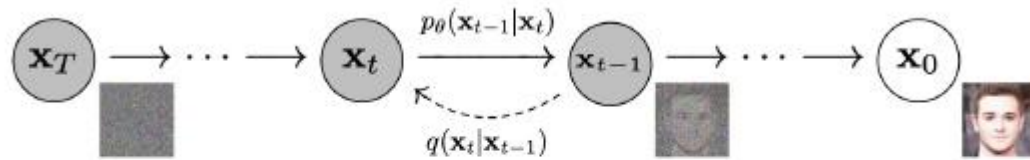


Figure 2: The directed graphical model considered in this work.

$$q(\mathbf{x}_t|\mathbf{x}_{t-1}) = \mathcal{N}(\mathbf{x}_t; \sqrt{1 - \beta_t}\mathbf{x}_{t-1}, \beta_t\mathbf{I})$$

Data



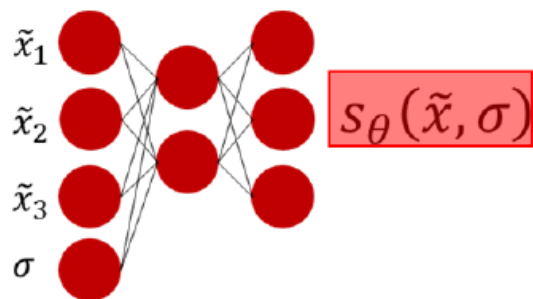
Noise

$$p_\theta(\mathbf{x}_{t-1}|\mathbf{x}_t) = \mathcal{N}(\mathbf{x}_{t-1}; \mu_\theta(\mathbf{x}_t, t), \sigma_t^2\mathbf{I})$$

# NCSN & DDPM

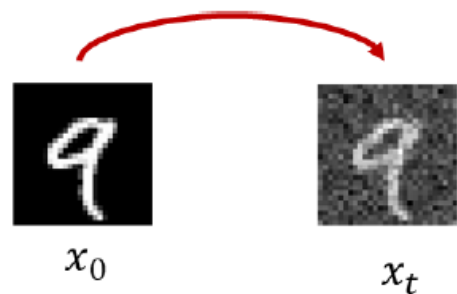
- Similar training objective

## NCSN

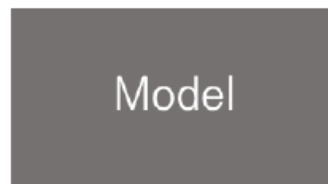


$$\frac{1}{2} E_{q_{\sigma}(\tilde{x}|x)p_{data}(x)} \left[ \left\| s_{\theta}(\tilde{x}, \sigma) - \frac{\tilde{x} - x}{\sigma^2} \right\|_2^2 \right]$$

## DDPM



$x_t$   
 $t$



$z_{\theta}(x_t, t)$

$$E_{x_0, z} [\|z_t - z_{\theta}(x_t, t)\|^2]$$

# NCSN & DDPM

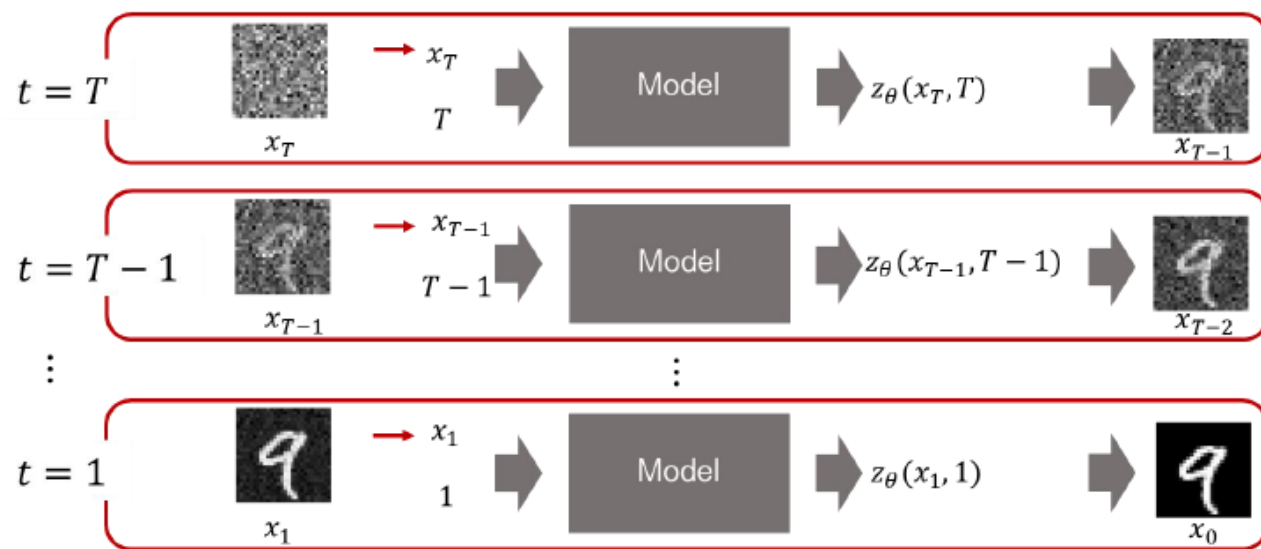
- Similar new sampling

$$\tilde{\mathbf{x}}_t \leftarrow \tilde{\mathbf{x}}_{t-1} + \frac{\alpha_i}{2} \mathbf{s}_\theta(\tilde{\mathbf{x}}_{t-1}, \sigma_i) + \sqrt{\alpha_i} \mathbf{z}_t$$



Figure 4: Intermediate samples of annealed Langevin dynamics.

NCSN



DDPM



# Score-Based Generative Modeling Through SDEs

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## SCORE-BASED GENERATIVE MODELING THROUGH STOCHASTIC DIFFERENTIAL EQUATIONS

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# Score-Based Generative Modeling Through SDEs

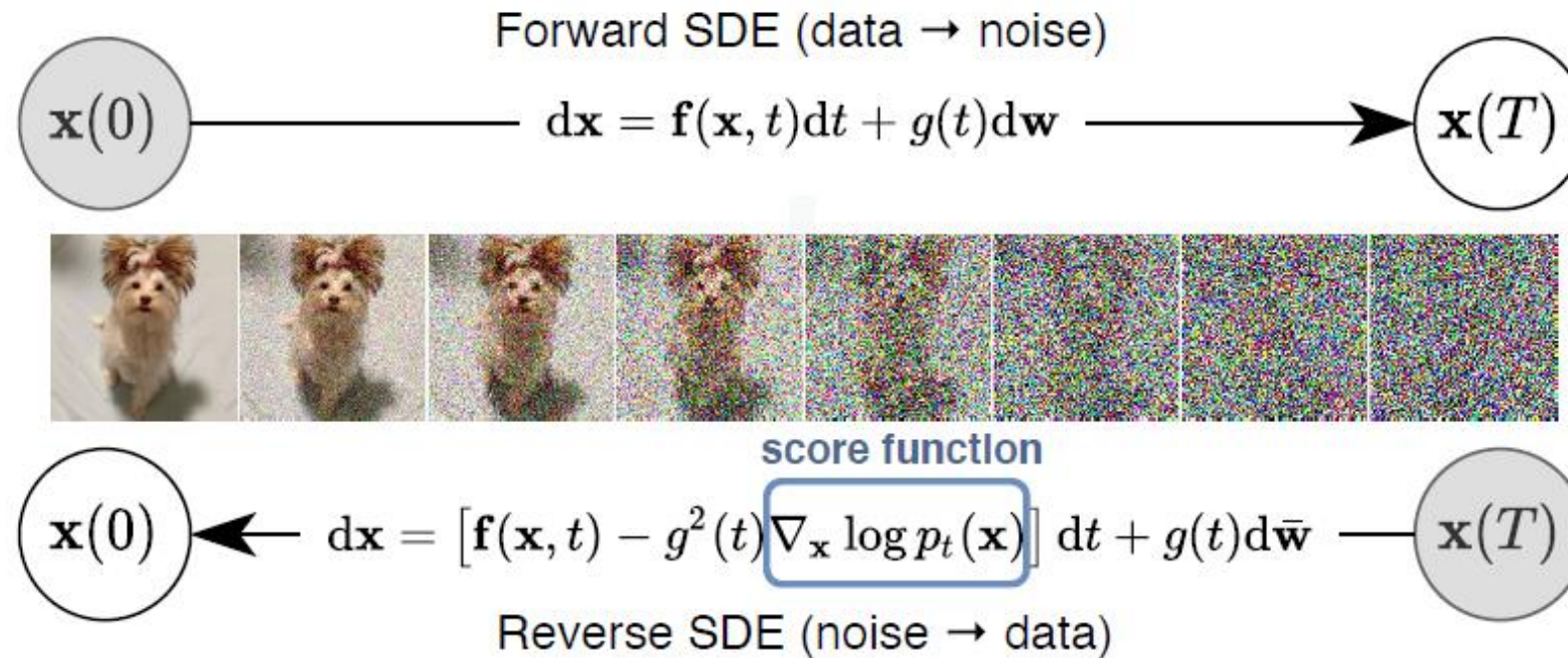
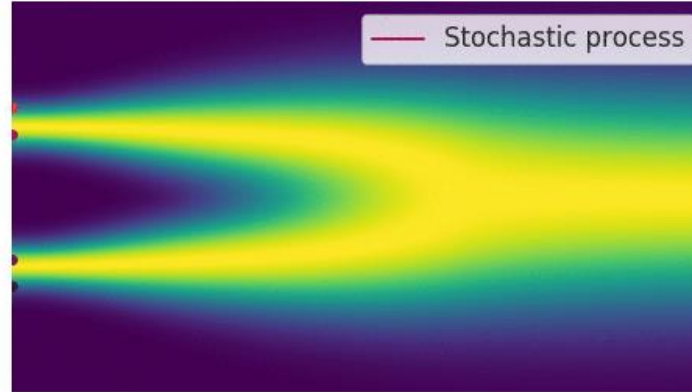
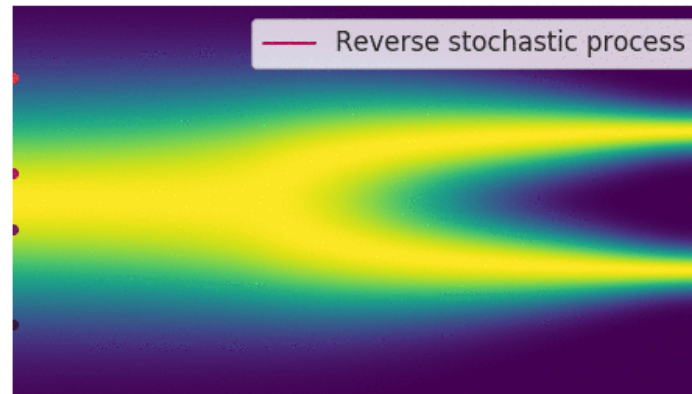


Figure 1: **Solving a reverse-time SDE yields a score-based generative model.** Transforming data to a simple noise distribution can be accomplished with a continuous-time SDE. This SDE can be reversed if we know the score of the distribution at each intermediate time step,  $\nabla_{\mathbf{x}} \log p_t(\mathbf{x})$ .

# Score-Based Generative Modeling Through SDEs



Perturbing data to noise with a continuous-time stochastic process.



Generate data from noise by reversing the perturbation procedure.

# Reference

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TRAIN AND TEST